Deterministic chaos

- Determinism and predictability
- Deterministic chaos and absolute chaos
- Logistic map
- Fractals
- Measuring chaos
- Chaos in classical billiards

M. Peressi - UniTS - Laurea Magistrale in Physics Laboratory of Computational Physics - Unit XIII Determinism and predictability Deterministic chaos and absolute chaos

Determinism

Determinism indicates that every event is determined by a chain of prior occurrences.

Pierre Simon de Laplace (1749-1827) strongly believed in **causal determinism**:

"We ought to regard the present state of the universe as the effect of its antecedent state and as the cause of the state that is to follow. An intelligence knowing all the forces acting in nature at a given instant, as well as the momentary positions of all things in the universe, would be able to comprehend in one single formula the motions of the largest bodies as well as the lightest atoms in the world, provided that its intellect were sufficiently powerful to subject all data to analysis; to it nothing would be uncertain, the future as well as the past would be present to its eyes."

(from: "Essai philosophique sur les probabilites")

Predictability

Determinism ≠ predictability

The world could be highly predictable, in some senses, and yet not deterministic; and it could be deterministic yet highly unpredictable...

Determinism: related to the nature of the physical system

<u>Predictability</u>: related to what we can do (observe, analyze, calculate); to predict something we need:

- knowledge of initial conditions
- capability of solving exactly the equation of evolution

Chaos and determinism

a system is **chaotic** if its trajectory through the configuration space is sensitively dependent on the initial conditions, that is, if very small causes can produce large effects

(in meteorology: "butterfly effect")



Chaos and determinism





In the last few decades, physicists have become aware that even the systems studied by classical mechanics can behave in an intrinsically unpredictable manner. Although such a system may be perfectly deterministic in principle, its behavior is completely unpredictable in practice. This phenomenon was called **deterministic chaos.**

Deterministic chaos is not randomness

Deterministic chaos is not the same as <u>absolute</u> chaos. Absolute chaos or randomness is when you don't know nothing at all of what will be the next value: it can be any value!

Another important difference is that for deterministic chaos we have a <u>simple law</u> that will produce all the values in the "attractor". Instead for randomness there is no known recipe to produce past and future values. Chaos and determinism: logistic map; Mandelbrot function and fractals

Chaos and determinism

Deterministic chaos described by intrinsically NON LINEAR equations. E.g., dynamics of population:

$$x_{n+1} = 4rx_n(1 - x_n)$$

 x_n is the ratio of the population in the *n*th generation to a reference population.

WHICH DYNAMICAL BEHAVIOR?

The logistic map

realistic model in which the population is bounded

$$P_{n+1} = P_n(a - bP_n)$$

rescale the population by letting $P_n = (a/b)x_n$

$$x_{n+1} = ax_n(1 - x_n)$$

define the parameter r = a/4 and obtain

$$x_{n+1} = f(x_n) = 4rx_n(1 - x_n)$$

- f is called a one-dimensional map
- The sequence of values x_0, x_1, x_2, \cdots is called the *trajectory* or the *orbit*.
- x^* is a fixed point if $x_{n+1} = x_n = x^*$, i.e., $f(x^*) = x^*$

The logistic map

$$x_{n+1} = 4rx_n(1 - x_n)$$

 $0 \le x \le 1; \quad 0 < r \le 1$ (*)

(*): condition $(f(x))_{max} \leq 1 \Rightarrow r \leq 1$; $x^*=$ fixed point $\leq 1 \Rightarrow r > 0$



Fixed points

fixed-point condition is given by $f(x^*) = x^*$

$$x_{n+1} = 4rx_n(1-x_n)$$

$$x_{1}^{*} = 0$$
 and $x_{2}^{*} = 1 - \frac{1}{4\eta}$

stable fixed point:

for sufficiently small r, the iterated values of x converge to x = 0 independently of the value of x_0

unstable if for almost all x_0 near the fixed point, the trajectories diverge from it

It can be demonstrated that:

$$x_{1}^{*} = 0 \text{ is stable for } 0 < r < 1/4$$

$$x_{2}^{*} = 1 - \frac{1}{4r} \text{ is stable for } \frac{1}{4} < r < \dots? \quad (< 1)$$

$$(\text{condition } x_{2}^{*} > 0)$$





Figure 6.2: Bifurcation diagram of the logistic map. For each value of r, the iterated values of x_n are plotted after the first 1000 iterations are discarded. Note the transition from periodic to chaotic behavior and the narrow windows of periodic behavior within the region of chaos.



Graphical interpretation of the logistic map: intersection with the diagonal (non trivial solution) for $1/4 \le r \le 1$



Note: the graphical intersection between y(x) and the diagonal gives the **fixed point**, but it is not sufficient to determine whether it is **stable or unstable**

The logistic map

Numerics:

for a given parameter r:

- for a given $x_{0,i}$ iterate the map and plot the trajectory (n, x_n);
- verify whether it converges and, in case, to which value(s)

- verify numerically if the analytically predicted fixed points x_1^* , x_2^* are stable or unstable fixed points

Another famous example

other equations intrinsically NON LINEAR can show a chaotic behavior for certain values of the parameters.

E.g.

quadratic recurrence equation Mandelbrot function (in general in the complex field):

 $Z(n+I) = Z(n)^2 + C$

with C constant (also negative) and n = 0, 1, 2, ...

Start with an initial value Z(0), then calculate: $Z(1) = Z(0)^2 + C$ then: $Z(2) = Z(1)^2 + C$ etc etc ...

Some examples in the real field

$I(n+I) = Z(n)^2 + C$	n	Z1 (n)
	0	0.0000
	1	0.2000
	2	0.2400
	3	0.2576
	4	0.2664
	5	0.2709
	6	0.2734
	7	0.2748
	8	0.2755
	9	0.2759
	10	0.2761
	11	0.2762
	12	0.2763
	13	0.2763
	14	0.2764
	15	0.2764
	16	0.2764

Some examples in the real field $Z(n+1) = Z(n)^2 + C$

Previous example: C = 0.2 and Z(0) = 0 => Convergence to $Z^*= 0.2764$

In general: Fixing Z(0) = 0:

For 0 < C <= 0.25: convergence to a fixed point, solution of $Z = Z^2 + C$ (**attractor**)

For C< \sim -0.75 : convergence with damped oscillation

For C~-0.76 : bifurcation (two-values attractor)

Decreasing C: further bifurcations

Further decreasing, at C~-1.42: chaotic behavior (infinite points of attraction; and very small change of Z(0)=> very different behavior of the sequence - "butterfly effect")

Some examples in the real field

$Z(n+I) = Z(n)^2 + C$

Chaotic sequence at C = -1.7:

The values of the sequence do not repeat However they are within a certain range

Range including all points of the series: chaotic attractor or strange attractor

n	Z1(n)	
0	0.0000	
1	-1.7000	
2	1.1900	
3	-0.2839	
4	-1.6194	
5	0.9225	
6	-0.8491	
7	-0.9791	
8	-0.7414	
9	-1.1503	
10	-0.3768	
11	- <mark>1.558</mark> 1	
12	0.7275	
13	-1.1707	
14	-0.3295	
15	-1.5914	
16	0.8326	



"The" Mandelbrot set

the set of those points C in the **complex plane** for which the "evolution" of Z(0)=0 under iteration of Z(n) remains "bounded", i.e., |Z(n)| never diverges as n grows.

The Mandelbrot set can be plotted: in practice, a maximum number of iterations n_{max} and a maximum value of $|Z|=r_{max}=2$ is considered (it can be demonstrated that if there is a $|Z_n|>2$, then the sequence diverges)

one-color plots: black pixel: C is in the Mandelbrot set (|Z| remains limited)/ white: C is NOT

=> FRACTAL CHARACTERISTICS

http://mathworld.wolfram.com/MandelbrotSet.html



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multicolor plots: C points are colored according to the number of iterations $n < n_{max}$ required to have $|Z_n| > r_{max}$ (here: see the animation)

=> FRACTAL CHARACTERISTICS

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important characteristic of chaos

sensitivity to initial conditions

our ability to make numerical predictions is limited

The difference between two trajectories may diverge exponentially :

$$|\Delta x_n| = |\Delta x_0| e^{\lambda n}$$

Lyapunov exponent



The Lyapunov exponent as a function of the control parameter rfor the logistic map

 $x_{n+1} = 4rx_n(1 - x_n)$



A PROBLEM in a numerical approach:

ROUNDOFF:

small initial errors are exponentially amplified in time; after some (?) iterations the trajectories can diverge!

How to calculate λ ? FIT over several trajectories

Chaos in classical billiards



MODEL BILLIARDS (conservation of energy law, reflection law of geometric optics)

> calculate trajectories (which depend on: shape of the billiard; initial position and velocity)



Circular billiards support regular (periodic or non - periodic) trajectories, but in any case **non - ergodic**. (note also:

conservation of angular momentum, incidence angle constant)

In phase space (q(t),p(t)): limited region (a line: q(t) varies, p(t) constant)

Also elliptical billiards support regular trajectories:



The convolution of a trajectory can be: ellipse, hyperbole, regular polygon

Rectangular billiards also support regular (periodic or non - periodic) trajectories, which in this case can be also ergodic





In a rectangular/square/elliptic billiards the trajectories are **regular** but also **stable**, i.e. changing the initial conditions, they remain close each other



In a rectangular/square/elliptic billiards the trajectories are **regular** but also **stable**, i.e. changing the initial conditions, they remain close each other

By inserting a circle in a rectangular or square billiard, chaotic trajectories, strongly dependent on the initial conditions, are generated ("dynamical billiard" or "Sinai billiard", 1963)

2014 Abel Prize

from the Norwegian Academy of Science and Letters awarded to the mathematical physicist Yakov Sinai (now Princeton University, New Jersey). for his "fundamental contributions to dynamical systems, ergodic theory, and mathematical physics"

http://www.abelprize.no/



Stadium (Bunimovich) billiard has a geometry simpler than Sinai billiard, also resulting in chaotic trajectories



: (a) Geometry of the stadium billiard model. (b) Geometry of the Sinai billiard model.

NON Ergodicity of circular billiards

Ergodicity of chaotic billiards





Conservation of the energy,

but in one case (stable trajectories): - another physical constant (e.g. angular momentum in case of circular billiards)

- no other physical constant for stadium billiards

our model

point-like spheres

no friction: forces normal to the boundaries => v'// = v // => v' = - v

perfectly elastic collisions: energy conservation: |v'| = |v|





the algorithm

given x, y, v_x, v_y at time t

calculate : time to the next collision the position of collision velocity after the collision (reflection)

Iterate N times (N collisions)

collision time

Calculation of time to the next collision:

 $x(t) = x_0 + v_x t$ $y(t) = y_0 + v_y t$

boundaries: f(x,y)=0 : (e.g.: $y_0 + v_y t_c = 0$)

at the collision time t_c:

$$f(x(t_c),y(t_c))=f(x_0 + v_x t_c, y_0 + v_y t_c)=0$$

collision point

(half) circular boundary: equation: $[x(t_c) - x_c]^2 + [y(t_c) - y_c]^2 = 1$

i.e.:
$$(x_0 + v_x t_c - x_c)^2 + (y_0 + v_y t_c - y_c)^2 = 1$$

- => 0, 1 o 2 solutions:
- (0 sol.) no collision
- (1 sol.) collision (tangent line)
- (2 sol.) collision (consider only the larger t_c)

velocity after collision

For reflection off of a circular boundary: $(x - x_c)^2 + y^2 = 1$

$$v'_x = (y^2 - (x - x_c)^2) v_x - 2 (x - x_c)y v_y$$

 $v'_y = -2 (x - x_c) y v_x + ((x - x_c)^2 - y^2) v_y$

(valid if $v_x^2 + v_y^2 = 1$)

Lyapunov exponent

Dynamics is chaotic:

start with two particles with almost identical positions and/or momenta (varying by say 10^{-5}); compute the difference Δs of the two phase space trajectories as a function of the number of reflections n, where:

$$\Delta s_n = \sqrt{|\mathbf{r}_{1,n} - \mathbf{r}_{2,n}|^2 + |\mathbf{p}_{1,n} - \mathbf{p}_{2,n}|^2}$$

Lyapunov exponent can be calculated by a semilog plot of Δs versus n

- L dependence?
- role of single/double precision?



on \$/home/peressi/comp-phys/XIII-chaos/ or on moodle2

map.f90 billiard.f90

and

biliardi2.zip (material in java, from the Lab activity with High School students, with G. Pastore)

possibility of observing "Quantum Chaos": delocalization of the wavefunction in chaotic billiards



possibility of observing "Quantum Chaos"



Iron on Copper (111)