



Università di Trieste Corso di Laurea in Geologia

Anno accademico 2017 - 2018

Geologia Marina

Parte II

Modulo 2.4 Perforazione Oceanica

Docente Angelo Camerlenghi





Scientific ocean drilling is one of Earth sciences' longest running and most successful international collaborations.













In 1961 scientific drilling took root as a feasible technology to study Earth's subseafloor geology. **Project Mohole**, a concept developed by the American Miscellaneous Society with funding from the National Science Foundation, considered the feasibility of **drilling through the Mohorovičić seismic discontinuity**



Harry Hess, a founding father of the theory of plate tectonics, explains Project Mohole Damon Teagle and Benoît Ildefonse, Nature, 2011.



UNIVERSITÀ DEGLI STUDI DITRIESTE Dipartimento di Matematica e Geoscienze

DRILLING SITES



Drill ship CUSS 1







Five holes were drilled off the coast of **Guadalupe Island**, **Mexico**, the deepest to 601 ft (183 m) below the sea floor in 11,700 ft (3,600 m) of water. This was unprecedented: not in the hole's depth but because of the depth of the ocean and because it was drilled from an untethered platform. Also, the core sample proved to be valuable; penetrating through Miocene-age sediments for the first time to reveal the lowest 13 m (44 ft) consisting of basalt.







The next phase of scientific ocean drilling, the **Deep Sea Drilling Project (DSDP),** began in 1966 using the Drilling Vessel *Glomar Challenger*. This pioneer vessel for DSDP conducted drilling and coring operations in the Atlantic, Pacific and Indian oceans as well as the Mediterranean and Red Seas. The *Glomar Challenger* also advanced the technology of deep-ocean drilling.







DSDP drillsites in the Mediterranean and North Atlantic







In 1985, *JOIDES Resolution* replaced the *Glomar Challenger* at the start of a new program, the **Ocean Drilling Program (ODP)**. ODP was truly an international cooperative effort to explore and study the composition and structure of the Earth's subseafloors. The *JOIDES Resolution* conducted 110 expeditions for ODP at 2000 drill holes located throughout the world's ocean basins.













The Integrated Ocean Drilling Program (IODP 2003-2013) built upon the

international partnerships and scientific success of the DSDP and ODP by employing multiple drilling platforms financed by the contributions from 26 participating nations. These platforms - a refurbished *JOIDES Resolution*, the new marine-riser equipped Japanese Deep Sea Drilling Vessl *Chikyu*, and specialized Mission-Specific-Platforms - were used to reach new areas of the global subsurface during 52 expeditions.













Fundamental principles of IODP

- science driven project
- science plan: The Deep Biosphere and the Sub-seafloor Ocean Environmental Change, Processes and Effects Solid Earth Cycles and Geodynamics
- multiple platform approach to drilling





IODP Funding Model

- Each platform operated independently by respective country or consortia
- Science Support Office funded by NSF



Dipartimento di Matematica e Geoscienze

Corso di Geologia Marina 2017-18











HOW MUCH DOES IT COST? Example from end of IODP phase

- **NSF** and **MEXT** Total program costs (75 M USD / anno) Platform operation costs Science operation costs
- ECORD 7 M USD / year (2003-2006) 16.8 M USD (2006)
- **MOST** 5.5 M USD 2003-2008 (1.0 1.5 M USD / year)

http://www.iodp.org

Riserless Drilling

Riser Drilling

Mission-Specific







THE 'RISER' DRILLING SYSTEM







https://www.youtube.com/watch?v=yuu0QcnOVbo











CORE ON DECK

http://www.youtube.com/watch?feature=player_embedd ed&v=wC9IDPvvze0

http://www.iodp.org/images/stories/swf/jamstec_english_1_deepsea_drilling.swf http://www.iodp.org/images/stories/swf/jamstec_english_2_rotary_drilling.swf http://www.iodp.org/images/stories/swf/jamstec_english_3_riser_system.swf http://www.iodp.org/images/stories/swf/4core_procedure_eng.swf http://www.iodp.org/core-analyzing-process/2/





JOIDES Resolution Riserless Drillship



Minimum water depth according to specifications: 75 m

http://www.iodp-usio.org/



Dipartimento di Matematica e Geoscienze

Corso di Geologia Marina 2017-18









Site Surveys

Dynamic Positioning

Drilling



Hole Re-entry

http://www.iodp-usio.org/





Core Logging Core Handling

http://www.iodp-usio.org/





Geomagnetic logging



Micropaleontology







http://www.iodp-usio.org/

Microbiology







Downhole Logging

http://www.iodp-usio.org/





Chikyu Riser Drillship





Japan invests in the new deep sea riser drilling vessel Chikyu. The vessel will then be offered to IODP as drilling platform.





http://www.mext.go.jp





Chikyu Riser Drillship



ength	210 m
Vidth	38 m
Draft	9.2 m
Veight	57000 Ton
Crew	150 people
Pipes	10 km
Riser length	4 km



The ship is built and operated by JAMSTEC, The Japan Agency for Marine-Earth Science and Technology









http://www.jamstec.go.jp/chikyu/ (c)JAMSTEC/CDEX









The **U.S.A**. (trough the National Science Foundation, NSF) will re-fit and improve the drilling and laboratory capability of the JOIDES RESOLUTION, and will cover manage the operations of the **non-riser deep water drilling**.



http://www.iodp-usio.org/





Europe + Canada (ECORD) manages drilling operations that neither the JOIDES Resolution nor the Chikyu can do (ice-covered seas, shallow water).



http://www.ecord.org/

ACEX (Arctic Coring Expedition) IODP Exp. 203 (year 2004)

ttp://www.secord.org/







ACEX (Arctic Coring Expedition) IODP Exp. 203 (year 2004)

VIDAR VIKING

Vidar Viking: the drill ship

http://www.ecord.org/

Sweedish Ice Breaker Oden

ACEX (Arctic Coring Expedition) IODP Exp. 203 (year 2004)

http://www.ecord.org

Russian Ice breaker Sovietsky Soyuz ACEX (Arctic Coring Expedition) IODP Exp. 203 (year 2004)



Советский союз





DP Hunter, IODP Tahiti Sea Level Expedition (IODP Expedition- 310)



http://www.ecord.org/





DP Hunter, IODP Tahiti Sea Level Expedition (IODP Expedition- 310, year 2005)





http://www.ecord.org/



NIVERSITÀ DEGLI STUDI DITRIESTE Dipartimento di Matematica e Geoscienze

Corso di Geologia Marina 2017-18



Illuminating Earth's Past, Present, and Future



THE INTERNATIONAL OCEAN DISCOVERY PROGRAM EXPLORING THE EARTH UNDER THE SEA

Research Themes

- Climate and Ocean Change: Reading the Past, Informing the Future
- Biosphere Frontiers: Deep Life, Biodiversity, and Environmental Forcing of Ecosystems
- Earth Connections: Deep Processes and Their Impact on Earth's Surface Environment
- Earth in Motion: Processes and Hazards on Human Time Scales

Education AND OUTREACH

SCIENCE PLAN FOR 2013-2023



New Science Plan and as follows:

Bottom Dwelling: Ross (2007; Figure 3), Hydrothermal Vents: Devey at al. (2007, Figure 2), Microbes in Crust: Orcutt et al. (2010), Photic Zone: M. Montresor, SZN/Alfred Wegener Institute, Cold Seep Communities: Vanreusel et al. (2009, Figure 6A), Microbes in Sediment: Figure 3. 2B, Coral Reef: Coral Disease Working Group (2007; Figure 2)





Climate and Ocean Change: Reading the Past, Informing the Future







Climate and Ocean Change: Reading the Past, Informing the Future



Elements of this figure were adapted from Schoof (2010)





Biosphere Frontiers: Deep Life, Biodiversity, and Environmental Forcing of Ecosystems







Earth Connections: Deep Processes and Their Impact on Earth's Surface Environment



New Science Plan





Earth in Motion: Processes and Hazards on Human Time Scales



Inset from Expedition 319 Scientists (2010)





ECORD (European Consortium for Ocean research Drilling).



16 European nations + Canada

Austria Belgium Canada Denmark Finland France Germany Ireland Iceland Italy
The Netherlands
Norway
Portugal
United Kingdom
Spain
Sweden
Sweden
Switzerland



Prevision 2005: ECORD 12.5 Million USD, ~ 17 % of IODP

http://www.ecord.org/





ECORD Science Operation (ESO)

ESO is a consortium of European scientific institutions created to manage the operations of the **Mission Specific Platforms-MSP** on behalf of ECORD in the framework of the <u>Integrated Ocean Drilling Program-IODP</u>.

ESO is composed by:

- The **<u>British Geological Survey - BGS</u>**, (co-ordinator) responsibile of the overall management, under contract with EMA as indicated by the ECORD Council;

- The **University of Bremen**, sub-contracted by BGS to manage the core repository and the data management with the WDC-MARE/PANGAEA (<u>IODP-MSP</u> <u>data portal</u>). GFZ Potsdam contributes with by supporting ESO with the Drilling Information System (DIS) for offshore data acquisition;

-The **European Petrophysical Consortium**, sub-contracted by BGS to manage the Wireline Logging operations and petrophysical activities. The Consortium is composed by:

- University of Leicester (co-ordinator), U.K,
- the Université de Montpellier 2, France,
- RWTH Aachen, Germany and Vrije Universiteit of Amsterdam, Netherlands.

http://www.ecord.org/







Why robotic drilling ?

Disadvantage

 Less control on drill process

Advantage

- Safety
- Access to extreme environments (steep walls, extraterrestrial environments, sea floor)

Picture: Roboclimber (Molfino, 2005)







Advantages of sea bed drill rigs

- Stable platform optimal drill bit control
- No need for drill pipe through the water column
- Operation from multipurpose research vessels



Seabed Rig AS













Existing seabed drill rigs





3-m rockdrill University of Washington, 1990

Courtesy Time Freudenthal, MARUM, Bremen









MeBo specifications

- Drilling depth 70 m
- Coring of soft sediments and hard rocks
- Core diameter 55 84 mm
- Deployment depth 0 2000 m
- MeBo weight about 10 tonnes
- Total system weight about 75 tonnes
- Transport within six 20 ' containers









Concept of MeBo

- Umbilical is used to lower the drill rig to the sea floor
- Umbilical is used for energy supply and remote control from the vessel

 Transport of the System within 20 ' shipping containers, that are mounted on the working deck of the research vessel







Concept

- Mast, drill head and flush water pump form the central drilling unit
- Drill rig has access to drilling tools stored within two magazines
- The drill string is built up and down using a loading arm and two chucks
- Stability on the sea floor is increased by movable legs











Drill rig For maintenance work between deployments the MeBo lies horizontally on deck. The movable legs are armed in. The rig weighs about 10 tonnes.











Winch

The winch stores 2500 m of the umbilical. The pull force of the winch in the upper layer is 12 tonnes.









Control Unit

The drill rig is remotely controlled from the control container. All actions are surveyed by video cameras and sensors.









Workshop

A mechanical workshop and spareparts are transported within a workshop container for maintenance and repair on sea









Drill tools

2.35m rods are used to build up the drill string. 30 core barrels and 29 rods are required for core drilling down to 70 m below the sea floor.







MeBo 2004/2005 (HBFG)

allon

Prakla Bohrtec

NSW, STA ...

Schilling Robotics



Pressure Core Barrel 2008/2010 (BMBF, SUGAR)

Borehole Logging (2010)





