# Unit 7 <br> Recursion, Dynamic Programming, and <br> Abstract vs Concrete Data Types 

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## The Factorial Number

## Definition (The Factorial Number of $n$ )

Is the product of all the positive natural numbers $\leq n$.

$$
n!=n *(n-1) *(n-2) * \ldots * 1
$$

How to compute it?

## The Factorial Number

Use a variable to represent the product, initialize it to 1 , and multiply its value to that of all the integer between 1 and $n$ by using a loop.

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Easy? No!

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Easy? No!

Any simplier idea?

A Derivative

$$
\frac{d}{d x}(\ln x+1)^{2}=?
$$

## A Derivative

$$
\frac{d}{d x}(\ln x+1)^{2}=\frac{2 *(\ln x+1)}{x}
$$

Why?

## Eating Pizza



## Eating Pizza



How do you eat pizza?

## Tower of Hanoi

A game for children

- 3 rods
- $n$ disks having different width stacked in the first rod
- only one disk can be moved at a time
- a disk can be placed only on either the floor or widther disks
- the disk tower should be moved from the first rod to the last one


## Tower of Hanoi - 1 Disk



## Tower of Hanoi - 1 Disk



Disk moved from rod 1 to rod 3.

## Tower of Hanoi - 1 Disk



## Tower of Hanoi - 2 Disks



## Tower of Hanoi - 2 Disks



Disk moved from rod 1 to rod 2.

## Tower of Hanoi - 2 Disks



Disk moved from rod 1 to rod 3.

## Tower of Hanoi - 2 Disks



Disk moved from rod 2 to rod 3.

## Tower of Hanoi - 2 Disks



## Tower of Hanoi - 6 Disks



## What have

(1) the factorial number
(2) the computation of $\frac{d}{d x}(\ln x+1)^{2}$
(3) eating pizza
(9) the tower of Hanoi
in common?

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Nothing!

A solution technique!

## Computing the Factorial

Whenever $n>1$ :

$$
\begin{aligned}
n! & =n *(n-1) *(n-2) * \ldots * 1 \\
& =n *((n-1) *(n-2) * \ldots * 1) \\
& =n *(n-1)!
\end{aligned}
$$

Thus, we can define $n!$ as:

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Thus, we can define $n!$ as:

$$
n!= \begin{cases}1 & \text { if } n=0 \\ n *(n-1)! & \text { othewise }\end{cases}
$$

## Deriving Composited Functions

$$
\frac{d}{d x}(f \circ g)(x)=\left(\frac{d}{d x}(f)(g(x))\right) *\left(\frac{d}{d x}(g)(x)\right)
$$

$(\ln x+1)^{2}$ is the composited function $(f \circ g \circ h)(x)$ where:

- $h(x)=\ln x$
- $g(x)=x+1$
- $f(x)=x^{2}$


## Deriving Composited Functions

Thus:

$$
\begin{aligned}
\frac{d}{d x}(\ln x+1)^{2} & =\frac{d}{d x}(f \circ g \circ h)(x) \\
& =\frac{d}{d x}(f)((g \circ h)(x)) * \frac{d}{d x}(g \circ h)(x)
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& =2 *(\ln x+1) * 1 * \frac{1}{x} \\
& =\frac{2 *(\ln x+1)}{x}
\end{aligned}
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## Eating Pizza

If I can eat what's left in a single bite, I do it. Otherwise, I cut a small piece of it, I eat the piece and reduce the original problem to eating a smaller quantity of pizza.

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## A Solution for the Tower of Hanoi with 6 Disks



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## Recursion

All the previous problem solutions share the same technique:
(1) identify some "easy" cases
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This technique is called recursion and is based on:
(1) one or more base cases
(2) one or more recursive steps

## Recursively Computing the Factorial

Extremely simple and elegant

```
unsigned int fact(unsigned int n) {
    // Base case
    if (n<=1) return 1;
    // Recursive step
    return n*fact(n-1);
```


## The Recursive Solution to Hanoi

Have you tried to write an iterative (no recursion, only loops) code to solve Hanoi tower problem?

How much difficult is it?

## The Recursive Solution to Hanoi (Cont'd)

```
void Hanoi(char from_rod, char tmp_rod,
char to_rod, unsigned int disks) {
// Base case if (disks = 0) return;
// Recursive step
```

Hanoi(from_rod, to_rod, tmp_rod, disks -1);
 disks, from_rod, to_rod);

Hanoi(tmp_rod, from_rod, to_rod, disks -1);

## Computing Fibonacci Number By Recursion

Let us have a look to our iterative code
unsigned long int Fib(unsigned int $n$ ) \{ unsigned long int $\mathrm{F} 0=1, \mathrm{~F} 1=1, \mathrm{~F} 2=1$;
for (unsigned int $\mathrm{i}=1$; $\mathrm{i}<\mathrm{n} ; \mathrm{i}++$ ) $\{$

$$
F 2=F 1+F 0 ;
$$

$\mathrm{F} 0=\mathrm{F} 1 ; \quad / *$ this part is not
F1 $=$ F2; really easy to understand */
return F2;

## Computing Fibonacci Number By Recursion

The recursive version is shorter, more readable, and elegant (?!?!?!)

```
unsigned long int Fib(unsigned int n) {
    // Base cases
    if (n<2) return 1;
    //Recursive step
    return Fib(n-1) + Fib(n-2);
```


## What About Their "Execution Time"?

Roughtly extimable by counting instructions to be executed

- iterative solution: 3 initializations +3 instructions per iteration +1 return. In total, $3+3 * n+1$ instructions.
- recursive solution: 2 instructions per call and the number of calls depends on the input parameter


## Follow the Function Calls. . .

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Fib(4)

## Follow the Function Calls...



## Follow the Function Calls. . .



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Fib(2)

## Follow the Function Calls...



## Follow the Function Calls...



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## Follow the Function Calls...



## Follow the Function Calls. . .



## Follow the Function Calls. . .



## . . . and Count Them

A generic call to Fib(n) produces:

$$
C(n) \stackrel{\text { def }}{=} \begin{cases}1 & \text { if } n \text { is either } 0 \text { or } 1 \\ C(n-1)+C(n-2)+1 & \text { otherwise }\end{cases}
$$

total calls.

## . . . and Count Them



## . . . and Count Them



It is exponential!!!

Any possible solution?

## . . . and Count Them



It is exponential!!!

Any possible solution? Back to the calls tree ...

## Calls Tree



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## Calls Tree

The function performs the very same calls many times.

The computation has two main features:

- evaluates sub-problems i.e., Fib(n-1), Fib(n-2), ...
- its sub-problems are overlapping e.g., Fib(3) is evaluated many times


## Calls Tree

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The computation has two main features:

- evaluates sub-problems i.e., Fib(n-1), Fib(n-2), ...
- its sub-problems are overlapping e.g., Fib(3) is evaluated many times

Under such conditions we can use dynamic programming

## Dynamic Programming

Is a solution technique that:

- reduces the original problems to sub-problems
- avoid overlapping by memoizing sub-problem solutions
E.g., Use an array to store the results of Fib calls and do not recompute them.


## Fibonacci and Dynamic Programming

```
unsigned int Fib(unsigned int n) { unsigned int *F;
\(\mathrm{F}=(\) unsigned int *) calloc(n, sizeof(unsigned int));
```

unsigned int result $=F \operatorname{Dyn}(\mathrm{n}, \mathrm{F})$;
free (F);
return result;

## Fibonacci and Dynamic Programming (Cont'd)

```
unsigned int FDyn(unsigned int \(n\),
                                    unsigned int *F) \{
    if \((F[n]!=0)\)
        return \(F[n]\);
    if \((\mathrm{n}<2)\)
    \(F[n]=1\);
    else
        \(F[n]=F \operatorname{Dyn}(n-1, F)+F \operatorname{Dyn}(n-2, F) ;\)
```

    return F[n];
    In this case, stay with the iterative solution.

## Abstract vs Concrete Data Types

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- Abstract Data Types: data type models that specify domains and primitives
- Concrete Data Types: implementations for ADT
is fundamental.

Replacing a CDT by another CDT is almost immediate if they implement the same ADT.

## Some Abstract Data Types

Some of the most used abstract data types are:

- arrays
- lists
- queues
- stacks


## ADT: Arrays

Can store a set of values and provide the following functions:

- get ( $n$ ) gets the value from position $n$
- set ( $n, v$ ) sets value $v$ in position $n$
- size() returns the array size

In the $C$ programming language it is implemented by the array.

## ADT: Lists

Can store a set of values and provides the following functions:

- get( $n$ ) gets the element in position $n$
- insert ( $n, v$ ) inserts the element $v$ in position $n$
- replace ( $n, v$ ) replaces the element in position $n$ by $v$
- remove( $n$ ) removes the element in position $n$ from the list
- size() returns the number of elements in the list


## Possible Implementations for Lists

```
typedef struct int_list {
    size_t size;
    int *list;
} int_list;
int_list create_empty() {
    int_list L = {0, NULL};
    return L;
```

\}
void destroy(int_list L) \{
free(L.list);

## Possible Implementations for Lists

> void insert (int_list $L$, const size_t $n$, const int $v)\{$
> $L$. isst=realloc $(\mathrm{L} . \operatorname{list}$, $(++L . \operatorname{size}) * \operatorname{sizeof}($ int $)) ;$
for (int $\mathrm{i}=\mathrm{L} . \operatorname{size}-1$; $\mathrm{i}>\mathrm{n}$; $\mathrm{i}++$ )
L. list [i] $=$ L. Iist [ $\mathrm{i}-1$ ];
L. list $[\mathrm{n}]=\mathrm{v}$;

## Possible Implementations for Lists (Cont'd)

```
typedef struct list_el {
    struct list_el *next;
    int value;
    list_el;
typedef struct list_el * int_list2;
int_list2 create_empty() {
    return NULL;
```


## Possible Implementations for Lists (Cont'd)

void insert (int_list 2 L , constr size _t n , const int v) \{
if $(\mathrm{n}==0)$ \{
list_el next=(list_el *)
malloc (sizeof (list_el))
next. value $=L->$ value;
next. next=L->next;
$L \rightarrow$ next $=$ next;
L $->$ value $=v$;
\} else if $(L->$ next $=$ NULL $)$ $\{\ldots\}$
else
insert(L->next, $n-1, v)$;

## ADT: Queues

store a set of values and use the First In First Out policy

- enqueue (v) inserts $v$ at the end of the queue
- dequeue() removes the first element of the queue and returns it
- head() returns the first element of the queue without removing it
- size() returns the number of elements in the queue


## Possible Implementations for Queues

Circular arrays

## typedef struct \{

size_t max_size; size_t size;
size_t front; int *queue;
\} int_queue;
int_queue create_empty() \{
int_queue $\mathrm{Q}=\{\mathrm{DEFAULT}$ _MAX_SIZE, 0 , 0 , NULL\};
Q. queue $=($ int *) calloc (DEFAULT_MAX_SIZE, sizeof(int));
return $Q$;

## Possible Implementations for Queues

$$
\begin{aligned}
& \text { void enqueue(int_queue } Q \text {, const int v) \{ } \\
& \text { if (Q.size }=\text { Q. max_size) \{ } \\
& \text { Q.max_size *= 2; } \\
& \text { Q. queue }=(\text { int *) realloc (Q.queue, } \\
& \text { Q. max_size*sizeof (int)); } \\
& \text { \} } \\
& \text { size_t idx=((Q.size++)+Q.front)\%Q.max_size; } \\
& \text { Q.queue[idx] = v; }
\end{aligned}
$$

## ADT: Stacks

store a set of values and use the First In Last Out policy

- push(v) inserts $v$ on the top of the stack
- pop() removes the element at the top of the stack and returns it
- top () returns the element at the top of the stack without removing it
- is_empty () returns true if and only if the stack is empty


## Possible Implementations for Stacks

```
typedef struct {
    size_t max_size; size_t size;
    int *stack;
} int_stack;
```

int_stack create_empty () \{
int_stack $S=\left\{D E F A U L T \_M A X \_S I Z E, 0\right.$,
0 , NULL\};
S.stack $=($ int $*)$ calloc (DEFAULT_MAX_SIZE ,
sizeof (int)) ;
return $S$;

## Possible Implementations for Stacks

$$
\begin{aligned}
& \text { void push(int_stack } S \text {, const int } v)\{ \\
& \text { if }(S . \operatorname{size}=S . m a x \text { size })\{ \\
& \text { S.max_size } *=2 ; \\
& \text { S. queue }=(\text { int } *) \text { realloc }(S \text {. queue, } \\
& \text { S.max_size } * \text { sizeof }(\text { int })) ;
\end{aligned}
$$

\}
S.queue[S.size ++ ] = v;

## Coming soon...

- Exercises!

