

Esercizi sull'integrale e sulla somma di convoluzione

1. Si determini la risposta del sistema di figura 1 quando $x(t)$ e $h(t)$ sono:

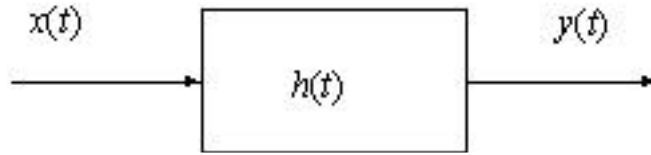


Fig. 1

a) $x(t) = e^{-at}u(t)$
 $h(t) = e^{-bt}u(t)$ (considera re sia $a \neq b$ sia $a = b$)

b) $x(t) = u(t) - 2u(t-2) + u(t-5)$
 $h(t) = e^{2t}u(1-t)$

c) $x(t) = e^{-3t}u(t)$
 $h(t) = u(t-1)$

d) $x(t) = e^{-2t}u(t+2) + e^{3t}u(-t+2)$
 $h(t) = e^t u(t-1)$

e) $x(t) = \begin{cases} e^t & t < 0 \\ e^{5t} - 2e^{-t} & t > 0 \end{cases}$
 $h(t)$ come in fig. 2

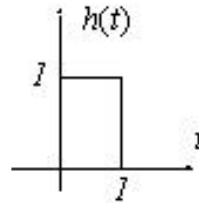


Fig. 2

f) $x(t)$ e $h(t)$ come in figura 3

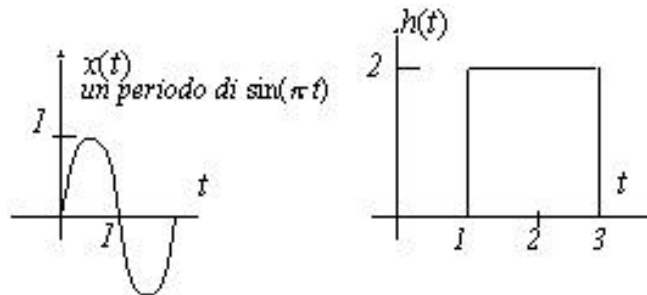


Fig. 3

g) $x(t)$ come in figura 4
 $h(t) = u(-2-t)$

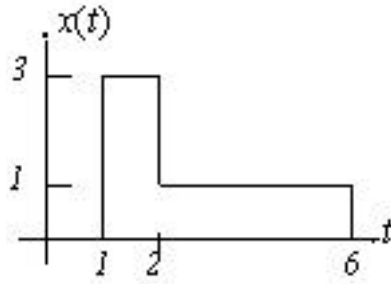


Fig.4

- h) $x(t) = \mathbf{d}(t) - 2\mathbf{\ddot{a}}(t-1) + \mathbf{\ddot{a}}(t-2)$
 $h(t)$ come in figura 5

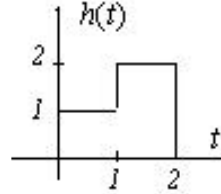


Fig. 5

- i) $x(t)$ e $h(t)$ come in figura 6
 j) $x(t)$ e $h(t)$ come in figura 7
 k) $x(t)$ e $h(t)$ come in figura 8
 l) $x(t)$ e $h(t)$ come in figura 9

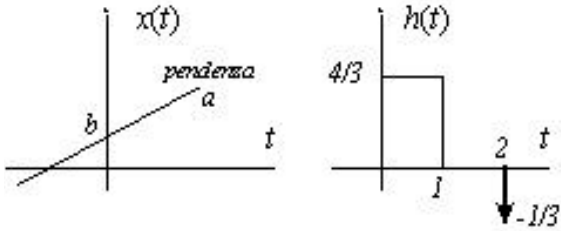


Fig. 6

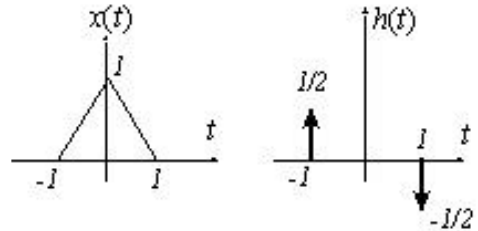


Fig. 7

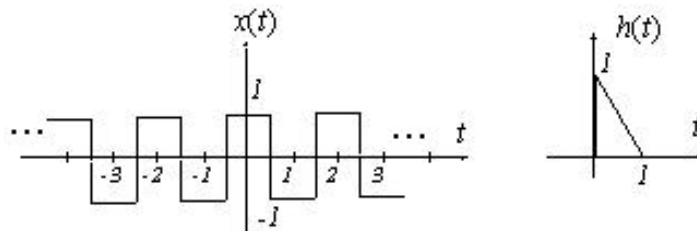


Fig. 8

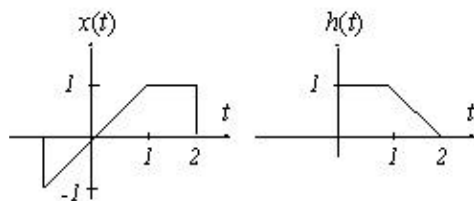


Fig. 9

2. Si determini la risposta del sistema di figura 10 quando $x[n]$ e $h[n]$ sono:

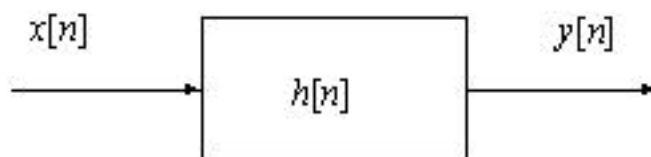


Fig. 10

- $x[n] = \mathbf{a}^n u[n]$
 $h[n] = \mathbf{b}^n u[n]$ ($\mathbf{a} \neq \mathbf{b}$)
- $x[n] = h[n] = \mathbf{a}^n u[n]$
- $x[n] = 2^n u[-n]$
 $h[n] = u[n]$
- $x[n] = (-1)^n \{u[-n] - u[-n-8]\}$
 $h[n] = u[n] - u[n-8]$
- $x[n]$ e $h[n]$ come in figura 11.
- $x[n]$ e $h[n]$ come in figura 12.
- $x[n]$ e $h[n]$ come in figura 13

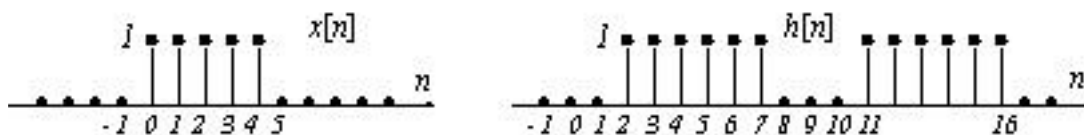


Fig. 11

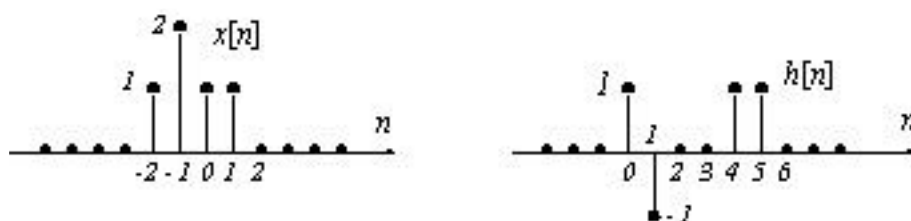


Fig. 12

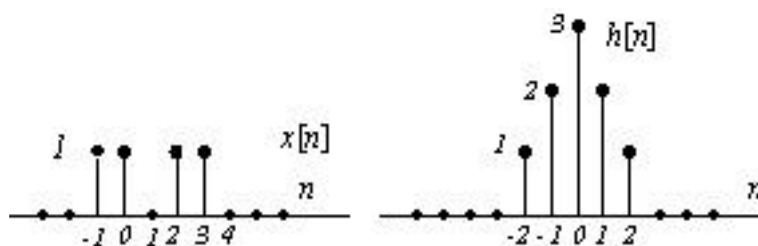


Fig. 13

$$x[n] = 1 \text{ per tutti i valori di } n$$

h)
$$h[n] = \left(\frac{1}{2}\right)^n u[n] + 4^n u[-n-1]$$

$$x[n] = u[n] - u[-n]$$

i)
$$h[n] = \left(\frac{1}{2}\right)^n u[n] + 4^n u[-n-1]$$

j)
$$x[n] = \left(-\frac{1}{2}\right)^n u[n-4]$$

$$h[n] = 4^n u[2-n]$$

3. In un sistema LTI tempo continuo il segnale di ingresso $x(t)$ e quello di uscita $y(t)$ sono legati dalla relazione:

$$y(t) = \int_{-\infty}^t e^{-(t-\tau)} x(\tau-2) d\tau$$

Determinare la risposta impulsiva del sistema e la risposta al segnale di ingresso di figura 14

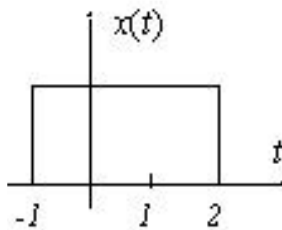


Fig. 14

4. Un sistema lineare, ma non tempo invariante, è caratterizzato dalla risposta $h[k, n]$ all'impulso unitario centrato in $n=k$, vale a dire a $\mathbf{d}[n-k]$. Per ognuna delle seguenti espressioni di $h[k, n]$ individuare una relazione esplicita tra l'uscita $y[n]$ e l'ingresso $x[n]$ del relativo sistema.

a)
$$h[k, n] = \begin{cases} \mathbf{d}[n-k] & \text{per } k \text{ pari} \\ 0 & \text{per } k \text{ dispari} \end{cases}$$

b)
$$h[k, n] = \mathbf{d}[2n-k]$$

c)
$$h[k, n] = ku[n-k]$$

d)
$$h[k, n] = k\mathbf{d}[n-2k] + 3k\mathbf{d}[n-k]$$

e)
$$h[k, n] = \begin{cases} \mathbf{d}[n-k+1] & \text{per } k \text{ pari} \\ 5u[n-k] & \text{per } k \text{ dispari} \end{cases}$$