



UNIVERSITÀ  
DEGLI STUDI DI TRIESTE



Dipartimento di scienze economiche,  
aziendali, matematiche e statistiche  
"Bruno de Finetti"

# Bayesian Statistics

## Introduction to Monte Carlo methods

Leonardo Egidi

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# Motivations

The entire goal of Bayesian analysis is to compute and extract summaries from the **posterior distribution** for the parameter  $\theta$ :

$$\pi(\theta|y) = \frac{\pi(\theta)p(y|\theta)}{\int_{\Theta} \pi(\theta)p(y|\theta)} \quad (1)$$



This is easy for conjugate models: normal likelihood + normal prior, beta+binomial, Poisson+gamma, multinomial+Dirichlet

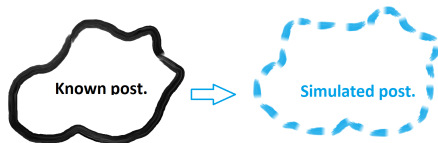


However, in real applications and complex models there is not usually a closed and analytical form for the posterior. The problem is represented by the denominator of (1).

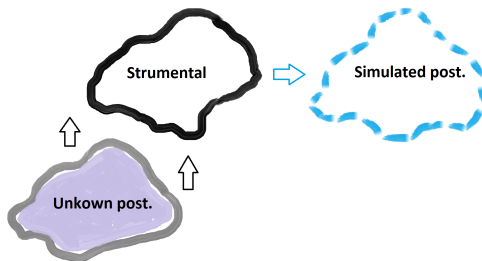
# Motivations

The Bayesian idea is to use simulation to generate values from the posterior distribution:

- *directly* when the posterior is entirely/partially known



- via some suitable *instrumental* distributions when the posterior is unknown/not analytically available.



# Motivations

In what follows, we will refer to the evaluation of the general integral:

$$E_f[h(X)] = \int_{\mathcal{X}} h(x)f(x)dx, \quad (2)$$

where  $f(\cdot)$  is referred as the **target** distribution, generally untractable/partially tractable. Possible solutions:

- Numerical integrations
- Asymptotic approximations
- **Accept-reject methods**
- **Monte Carlo methods**: i.i.d. draws from the posterior (or similar) distributions
- **Markov Chain Monte Carlo (MCMC) methods**: dependent draws from a Markov chain whose limiting distribution is the posterior distribution (Metropolis-Hastings, Gibbs sampling, Hamiltonian Monte Carlo).

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# Numerical integration

Numerical integration methods often fails to spot the region of importance for the function to be integrated.



For example, consider a sample of ten Cauchy rv's  $y_i$  ( $1 \leq y_i \leq 10$ ) with location parameter  $\theta = 350$ . The marginal distribution of the sample under a flat prior is:

$$m(y) = \int_{-\infty}^{+\infty} \prod_{i=1}^{10} \frac{1}{\pi} \frac{1}{1 + (y_i - \theta)^2} d\theta$$



The R function `integrate` does not work well! In fact, it returns a wrong numerical output (see next slide) and fails to signal the difficulty since the error evaluation is absurdly small. Function `area` may work better.

## Numerical integration: Cauchy example

```
set.seed(12345)
rc = rcauchy(10) + 350
lik = function(the) {
  u = dcauchy(rc[1] - the)
  for (i in 2:10) u = u * dcauchy(rc[i] - the)
  return(u)}
integrate(lik, -Inf, Inf)

[1] 3.728903e-44 with absolute error < 7.4e-44
integrate(lik, 200, 400)

[1] 1.79671e-11 with absolute error < 3.3e-11
```

We need to know the range where the likelihood is not negligible.  
Moreover, numerical integration cannot easily face multidimensional integrals.



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# Accept-reject method

Suppose we need to evaluate the following integral, but we cannot directly sample from the target density:

$$E_f[h(\theta)] = \int_{\Theta} h(\theta)f(\theta)d\theta, \quad (3)$$

where  $h(\cdot)$  is a parameter function and  $f(\cdot)$  is the **target** distribution (in Bayesian inference, this is usually the posterior).



Assume that

- ❶  $f(\theta)$  is continuous and such that  $f(\theta) = d(\theta)/K$ , and we know how to evaluate  $d(\theta) \Rightarrow$  we know the functional form of  $f$ .
- ❷ There exists another density  $g(\theta)$ , an **instrumental** density, such that, for some big  $c$ ,  $d(\theta) \leq c \times g(\theta), \forall \theta$ .

# Accept-reject method

It is possible to show that the following algorithm will generate values from the target density  $f(\theta)$ :

## A-R algorithm

- 1 draw a candidate  $W = w \sim g(w)$  and a value  $Y = y \sim \text{Unif}(0, 1)$ .
- 2 if

$$y \leq \frac{d(w)}{c \times g(w)},$$

set  $\theta = w$ , otherwise reject the candidate  $w$  and go back to step 1.

# Accept-reject method

## Theorem

- (a) The distribution of the accepted value is exactly the target density  $f(\theta)$ .*
- (b) The marginal probability that a single candidate is accepted is  $K/c$ .*

# Accept-reject method

## Proof.

(a) The cdf of  $W|Y \leq \frac{d(w)}{c \times g(w)}$  can be written as:

$$\begin{aligned} F_W(\theta) &= \frac{\Pr(W \leq \theta, Y \leq \frac{d(w)}{c \times g(w)})}{\Pr(Y \leq \frac{d(w)}{c \times g(w)})} = \frac{\int_W \Pr(W \leq \theta, Y \leq \frac{d(w)}{c \times g(w)} | w) g(w) dw}{\int_W \Pr(Y \leq \frac{d(w)}{c \times g(w)} | w) g(w) dw} = \\ &= \frac{\int_{-\infty}^{\theta} \Pr(Y \leq \frac{d(w)}{c \times g(w)} | w) g(w) dw}{\int_{-\infty}^{+\infty} \Pr(Y \leq \frac{d(w)}{c \times g(w)} | w) g(w) dw} = \frac{\int_{-\infty}^{\theta} \frac{d(w)}{c} dw}{\int_{-\infty}^{+\infty} \frac{d(w)}{c} dw} = \\ &= \frac{\int_{-\infty}^{\theta} \frac{Kf(w)}{c} dw}{\int_{-\infty}^{+\infty} \frac{Kf(w)}{c} dw} = \int_{-\infty}^{\theta} f(w) dw. \end{aligned}$$

(b) The probability that a single candidate  $W = w$  will be accepted is

$$\begin{aligned} \Pr(W \text{ accepted}) &= \Pr(Y \leq \frac{d(W)}{c \times g(W)}) = \\ &= \int_W \Pr(Y \leq \frac{d(W)}{c \times g(W)} | W = w) g(w) dw = \\ &= \int_W \frac{d(w)}{c} dw = \int_W \frac{K}{c} f(w) dw = \frac{K}{c} \end{aligned}$$

# A-R algorithm: simulation from a Beta distribution

Suppose we need to draw values from a  $\text{Beta}(a, b)$ , our  $f$ , but we only have a random number generator for the interval  $(0, 1)$ , a  $\text{Unif}(0, 1)$ , or instrumental distribution  $g$ . Both the distribution have support  $(0, 1)$ , then we have:

$$f(\theta) = \frac{d(\theta)}{K} = \frac{\theta^{a-1}(1-\theta)^{b-1}}{B(a,b)},$$

where  $B(a,b)$  is the Beta function with arguments  $a$  and  $b$ .



The AR steps are:

- draw  $\theta^* \sim g = \text{Unif}(0, 1)$ ,  $U \sim \text{Unif}(0, 1)$ .
- we accept  $\theta = \theta^*$  iff  $U \leq \frac{d(\theta^*)}{c \times g(\theta^*)}$ .
- otherwise, go back to step 1

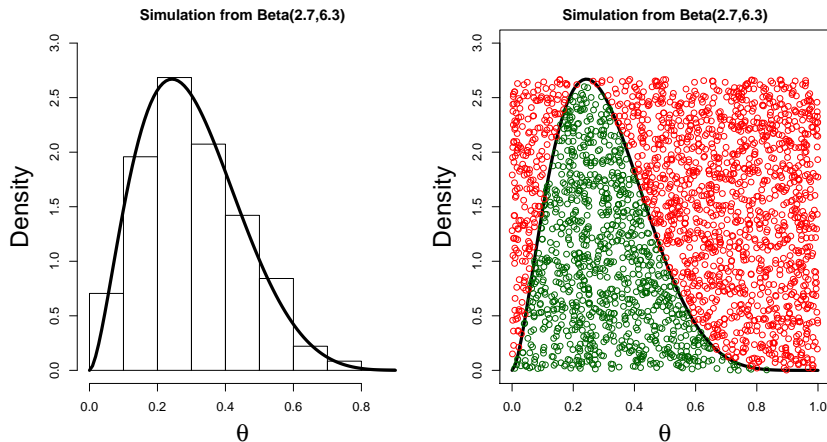
## A-R algorithm: simulation from a Beta distribution

```

Nsims=2500
#parameters
a=2.7; b=6.3
#find optimal c
c=optimise(f=function(x) {dbeta(x,a,b)},
           interval=c(0,1), maximum=TRUE)$objective
u=runif(Nsims, max=c)
theta_star=runif(Nsims)
theta=theta_star[u<dbeta(theta_star,a,b)]
# accept prob
1/c

[1] 0.3745677
    
```

# A-R algorithm: simulation from a Beta distribution



**Figure:** On the left plot, the true Beta(2.7, 6.3), and the histogram of the simulated distribution. On the right plot, the pairs  $(\theta^*, U)$ : the accepted (green) and the discarded (red).  $K = 1$ .

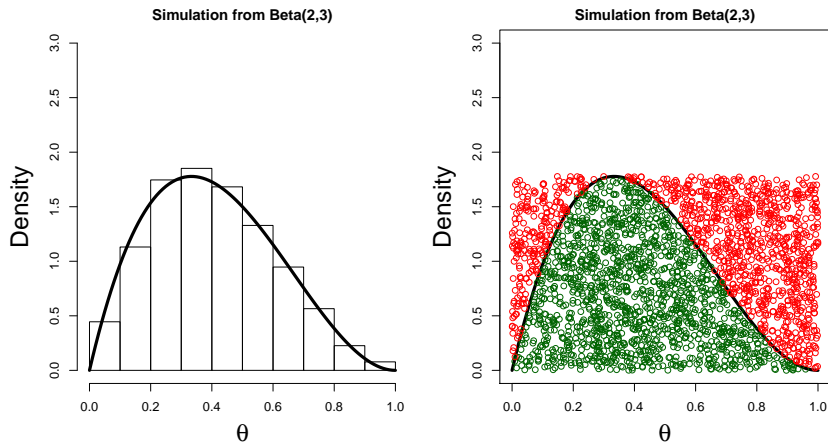


## A-R algorithm: simulation from a Beta distribution

```

Nsim=2500
#beta parameters
a=2; b=3
#find optimal c
c=optimise(f=function(x) {dbeta(x,a,b)},
           interval=c(0,1), maximum=TRUE)$objective
u=runif(Nsim, max=c)
theta_star=runif(Nsim)
theta=theta_star[u<dbeta(theta_star,a,b)]
#accept prob
1/c
[1] 0.5625
    
```

# A-R algorithm: simulation from a Beta distribution



**Figure:** On the left plot, the true Beta(2,3), and the histogram of the simulated distribution. On the right plot, the pairs  $(\theta^*, U)$ : the accepted (green) and the discarded (red).  $K = 1$ .

# A-R algorithm: simulation from a Beta distribution

## Comments:

- The probability of accepting the candidate  $\theta^*$  is higher in the second case, since a  $\text{Beta}(2, 3)$  is more similar to a  $\text{Unif}(0, 1)$  than a  $\text{Beta}(2.7, 6.3)$ .
- $c$  must be chosen in such a way that the condition  $d(\theta) \leq c \times g(\theta)$  is verified for all  $\theta$ .
- $K$  has been fixed to 1, since all the distribution  $\pi$  to be sampled from is completely known.
- In general,  $g$  needs to have thicker tail than  $d$  for  $d/g$  to remain bounded for all  $\theta$ . For instance, normal  $g$  cannot be used to sample from a Cauchy  $d$ . You can do the opposite of course.
- One criticism of the A-R method is that it generates *useless* simulations from the proposal  $g$  when rejecting, even those necessary to validate the output as being generated from the target  $f$ .

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# Classical Monte Carlo integration

Two major classes of numerical problems that arise in statistical inference are *optimization* problems and *integration* problems.



Suppose we need to calculate:

$$E_f[h(X)] = \int_{\mathcal{X}} h(x)f(x)dx, \quad (4)$$

where  $f(\cdot)$  is a probability density and  $h(\cdot)$  is a function of  $x$ . When an analytical solution is not possible, how do we approximate this integral?



If  $|I| < \infty$  and  $X_1, X_2, \dots, X_S$  are i.i.d  $\sim f$ , then the Strong Law of Large Numbers implies that the empirical mean is **consistent** for  $E_f[h(X)]$

$$\widehat{E_f[h(X)]} = \frac{1}{S} \sum_{s=1}^S h(X_s) \rightarrow E_f[h(X)] \text{ in probability, as } S \rightarrow \infty \quad (5)$$

# Classical Monte Carlo integration

The variance of  $\widehat{E_f[h(X)]}$  is

$$\text{Var}(\widehat{E_f[h(X)]}) = \frac{1}{S} \int_{\mathcal{X}} [h(x) - E_f[h(x)]]^2 f(x) dx$$

and it can be approximated by

$$\hat{V} = \frac{1}{S} \sum_{s=1}^S [h(x_s) - \widehat{E_f[h(X)]}]^2.$$

When  $S$  is large (approximately) for the Central Limit Theorem we have that:

$$\frac{\widehat{E_f[h(X)]} - E_f[h(X)]}{\sqrt{\hat{V}}} \sim \mathcal{N}(0, 1).$$

## Example: Normal mean with Cauchy prior

Consider:

$$y|\theta \sim \mathcal{N}(\theta, 1), \quad \theta \sim \text{Cauchy}(0, 1).$$

The posterior mean for a single observation  $y$  is:

$$E(\theta|y) = \frac{\int_{-\infty}^{+\infty} \frac{\theta}{1+\theta^2} e^{-(y-\theta)^2/2} d\theta}{\int_{-\infty}^{+\infty} \frac{1}{1+\theta^2} e^{-(y-\theta)^2/2} d\theta}.$$

We could draw  $\theta_1, \dots, \theta_S$  from  $\mathcal{N}(y, 1)$  and compute:

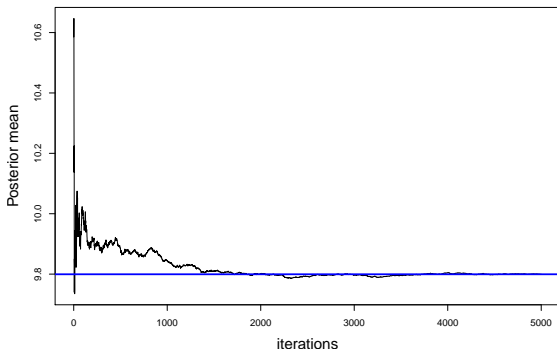
$$\hat{E}(\theta|y) = \frac{\sum_{s=1}^S \frac{\theta_s}{1+\theta_s^2}}{\sum_{s=1}^S \frac{1}{1+\theta_s^2}}$$

The effect of the prior is to pull a little bit the estimate of  $\theta$  toward 0.



## Example: Normal mean with Cauchy prior

```
set.seed(12345)
theta = rnorm(5000, 10, 1)
I = sum(theta/(1 + theta^2))/sum(1/(1 + theta^2))
I
[1] 9.793254
```



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  - Classical MC
  - Importance sampling

# Importance sampling

Importance sampling is based on the following representation:

$$\begin{aligned} E_f[h(X)] &= \int_{\mathcal{X}} h(x)f(x)dx = \\ &= \int_{\mathcal{X}} h(x)\frac{f(x)}{g(x)}g(x)dx = E_g \left[ h(X)\frac{f(X)}{g(X)}, \right] \end{aligned} \quad (6)$$

where  $g$  is an arbitrary density function, called **instrumental** distribution, whose support is greater than  $\mathcal{X}$ .



Given a sequence  $X_1, \dots, X_S$  i.i.d. from  $g$  we can estimate the integral above by

$$E_f^{is}[h(X)] = \frac{1}{S} \sum_{s=1}^S h(x_s) \frac{f(x_s)}{g(x_s)} = \frac{1}{S} \sum_{s=1}^S h(x_s) w(x_s), \quad (7)$$

where  $w(x) = f(x)/g(x)$  is called **importance function**.

# Importance sampling

Note that classical Monte Carlo and importance sampling both produce unbiased estimator for the integral (4), but:

$$\text{Var}(\widehat{E_f[h(X)]}) = \frac{1}{S} \int_{\mathcal{X}} [h(x) - E_f[h(x)]]^2 f(x) dx$$

$$\text{Var}(E_f^{is}[h(X)]) = \frac{1}{S} \int_{\mathcal{X}} [h(x) \frac{f(x)}{g(x)} - E_f[h(x)]]^2 g(x) dx$$



We can work on  $g$  in order to minimize the variance of (7). The constraint that  $\text{supp}(h \times f) \subset \text{supp}(g)$  is absolute in that using a smaller support truncates the integral (4) and thus produces a biased result.



It puts very little restriction on the choice of the instrumental distribution  $g$ , which can be chosen from distributions that are either easy to simulate or efficient in the approximation of the integral.

# Importance sampling

- IS variance is finite only when

$$E \left[ h(X)^2 \frac{f(X)^2}{g(X)^2} \right] = \int_{\mathcal{X}} h(x)^2 \frac{f(x)^2}{g(x)^2} dx < \infty$$

- Densities  $g$  with lighter tails than  $f$ , ( $\sup f/g = \infty$ ) are not good proposals because they can lead to infinite variance.
- When  $\sup f/g = \infty$  the weights  $f(x_i)/g(x_i)$  may take very high values and few values  $x_i$  influence the estimate of (4).
- Note also that

$$E_g \left[ h(X)^2 \frac{f(X)^2}{g(X)^2} \right] = \int_{\mathcal{X}} h(x)^2 \frac{f(x)^2}{g(x)^2} dx$$

the ratio  $f(x)/g(x)$  should be bounded when  $f(x)$  is not negligible...hence the modes of  $f(x)$  and  $g(x)$  should be close each other.

# Importance sampling for Bayesian inference

In Bayesian inference we need to compute quantities coming from the posterior distribution, such as::

$$E_{\pi(\theta|y)}[h(\theta)] = \frac{\int_{\Theta} h(\theta) p(y|\theta) \pi(\theta) d\theta}{\int_{\Theta} p(y|\theta) \pi(\theta) d\theta} = \int_{\Theta} h(\theta) \frac{p(y|\theta) \pi(\theta)}{p(y)} d\theta, \quad (8)$$

where  $\pi(\theta)$  is the prior,  $p(y|\theta)$  is the likelihood function and  $p(y) = \int_{\Theta} p(y|\theta) \pi(\theta) d\theta$ , the marginal likelihood, is often *unknown*.



Given  $\theta_1, \dots, \theta_S$  i.i.d. from  $g(\theta)$  an IS estimator for (8) is given by:

$$E_{\pi(\theta|y)}^{is}[h(\theta)] = \frac{S^{-1} \sum_{s=1}^S h(\theta_s) \frac{p(y|\theta_s) \pi(\theta_s)}{p(y) g(\theta_s)}}{S^{-1} \sum_{s=1}^S \frac{p(y|\theta_s) \pi(\theta_s)}{p(y) g(\theta_s)}} \quad (9)$$

## IS for Bayesian inference: location of a $t$ -distribution

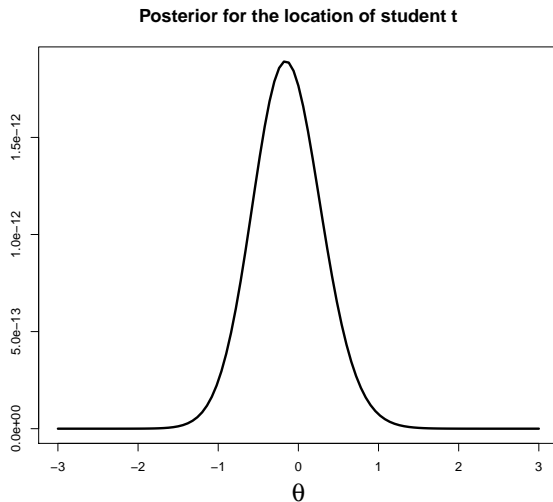
Let  $y_1, \dots, y_n$  be an i.i.d. sample from a student- $t$  with fixed degrees of freedom:

```
y.t <- rt(n=9, df =3)
```

Let be  $\theta$  the location parameter (in the simulation  $\theta = 0$ ) and take  $\pi(\theta) \propto 1$ . Then the posterior for  $\theta$  is:

$$\pi(\theta|y) \propto \prod_{i=1}^n [3 + (y_i - \theta)^2]^{-2}$$

# IS for Bayesian inference: location of a $t$ -distribution





# IS for Bayesian inference: location of a $t$ -distribution

Consider the posterior mean:

$$E(\theta|y) = \frac{\int_{\Theta} \theta \prod_{i=1}^n [3 + (y_i - \theta)^2]^{-2} d\theta}{\int_{\Theta} \prod_{i=1}^n [3 + (y_i - \theta)^2]^{-2} d\theta}$$

Possible strategies for computation:

- draws from the prior are not proper (the prior is improper)
- draws from the posterior are not possible (we are not able to do them)
- draws from the components  $g(\theta) \propto p(y_i|\theta)$ ? maybe...

## IS for Bayesian inference: location of a $t$ -distribution

For example take:

$$g(\theta) \propto p(y_i|\theta) \propto [3 + (y_i - \theta)^2]^{-2}.$$

Given  $S$  draws from  $g(\theta)$ , estimate the posterior mean by:

$$E^{is}(\theta|y) = \frac{\sum_{s=1}^S \theta_s \frac{\prod_{i=1}^n [3 + (y_i - \theta)^2]^{-2}}{[3 + (y_i - \theta)^2]^{-2}}}{\sum_{s=1}^S \frac{\prod_{i=1}^n [3 + (y_i - \theta)^2]^{-2}}{[3 + (y_i - \theta)^2]^{-2}}} = \frac{\sum_{s=1}^S \theta_s \prod_{i=1}^n [3 + (y_i - \theta)^2]^{-2}}{\sum_{s=1}^S \prod_{i=1}^n [3 + (y_i - \theta)^2]^{-2}}$$

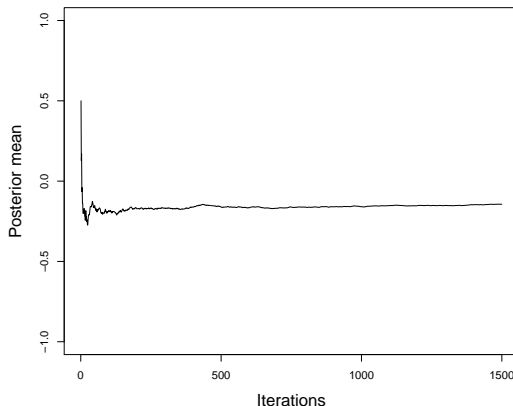
## IS for Bayesian inference: location of a $t$ -distribution

```
t.medpost = function(nsim, data, l) {
  sim <- data[l] + rt(nsim, 3)
  n <- length(data)
  s <- c(1:n)[-l]
  num <- cumsum(sim * sapply(sim,
    function(theta) t.lik(theta, data[s]))))
  den <- cumsum(sapply(sim,
    function(theta) t.lik(theta, data[s]))))
  num/den
}

media.post <- t.medpost(nsim = 1500, data = y.t,
  l = which(y.t == median(y.t)))

media.post[1500]
[1]-0.1440603
```

# IS for Bayesian inference: location of a $t$ -distribution



The convergence seems to be reached even after a few observations. What if we sample from other  $g$ 's?

# IS for Bayesian inference: location of a $t$ -distribution

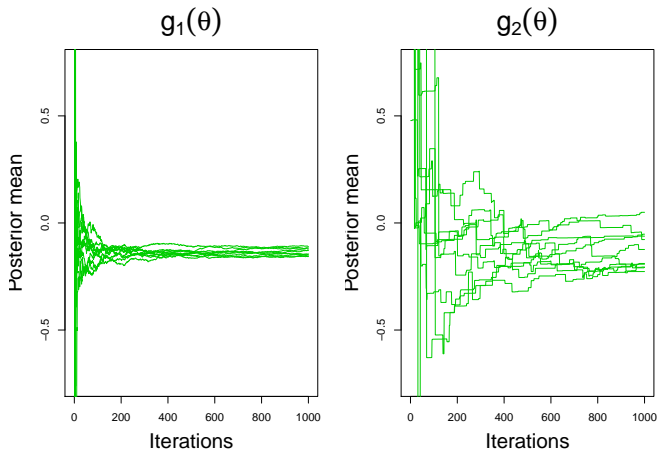
$$g_1(\theta) \propto p(y_{(n/2)}|\theta)$$

```
par(mfrow = c(1, 2))
plot(c(0, 0), xlim = c(0, 1000),
     ylim = c(-0.75, 0.75), type = "n", ylab = "Posterior mean",
     xlab="Iterations", main =)
for (i in 1:10) {
  lines(x = c(1:1000), y = t.medpost(nsim = 1000,
    data = y.t, l = which(y.t == median(y.t))), col = 3)}
```

$$g_2(\theta) \propto p(y_{(n)}|\theta)$$

```
plot(c(0, 0), xlim = c(0, 1000), ylim = c(-0.75, 0.75),
     type = "n", ylab = "Posterior mean",
     xlab="Iterations")
for (i in 1:10) {
  lines(x = c(1:1000), y = t.medpost(nsim = 1000,
    data = y.t, l = which(y.t == max(y.t))), col = 3)}
```

# IS for Bayesian inference: location of a $t$ -distribution



There is greater variability and slower convergence if we sample from the distribution of the maximum.

## Further reading

Further reading:

- Chapter 5 from *Bayesian computation with R*, J. Albert
- Chapter 3 and 5 from *Introducing Monte Carlo Methods with R*, C. Robert and G. Casella.