

ESTIMATION OF STEADY STATE MEANS

$(X_t)_{t \geq 0}$ $[X_{0:T}] \cdot X_\infty$: steady state distribution, $X_\infty = \lim_{t \rightarrow \infty} X_t$

$E[f(X_\infty)]$? \rightarrow

$X_T \approx X_\infty$ for T very large

ERGONIC THEOREM

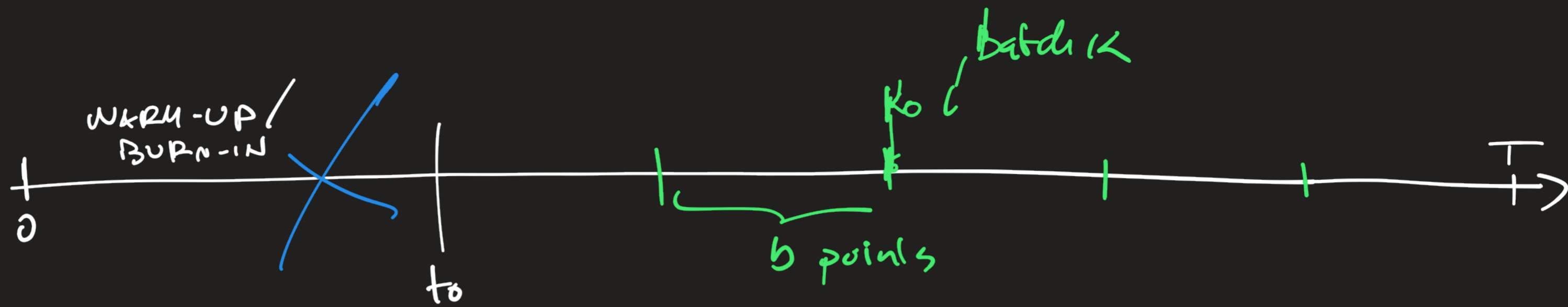
$$E[f(X_\infty)] = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T f(X_t) dt \quad (\text{ERGONIC } X_t)$$

STATE
AVERAGE

TIME AVERAGE

We simulate a SINGLE TRAJECTORY for a very long time and use ergodic theorem

$$Y_j = f(X_j) \quad y_i = f(x_i)$$



"time to reach stationarity"

$$\hat{Y} = \left(\sum_{i=t_0}^T y_i \right) \cdot \frac{1}{T-t_0} \quad T-t_0 = n \quad \Rightarrow \quad \hat{Y} = \frac{1}{n} \sum_{i=0}^n y_{t_0+i}$$

BATCH MEANS: FIX $b > 0$ BATCH SIZE,
 split the n points in K batches of size b ($K = \frac{n}{b}$)

for batch k , we compute $\hat{Y}_k = \frac{1}{b} \sum_{i=0}^{b-1} y_{k \cdot b + i}$
FIRST INDEX IN BATCH k .

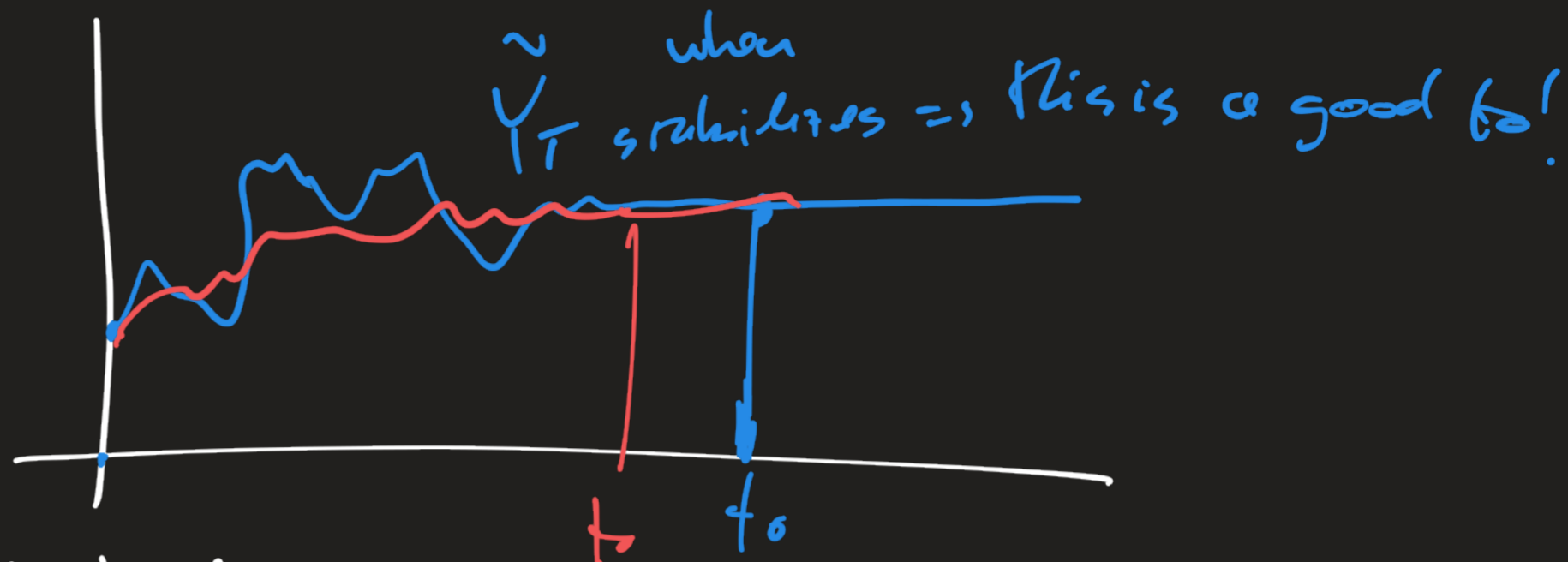
$$\hat{Y} = \frac{1}{K} \sum_{j=1}^K \hat{Y}_j$$

$$\text{VAR}[\hat{Y}_j] = \frac{1}{K-1} \sum_{j=1}^K (\hat{Y}_j - \hat{Y})^2$$

$$\text{VAR}[\hat{Y}] \approx \frac{\text{VAR}[\hat{Y}_j]}{K} \quad (\text{true in the limit of } n \rightarrow \infty, b \rightarrow \infty)$$

• How to choose t_0 ?

$$y_{0:T} \quad \bar{Y}_T = \frac{1}{(T+1)} \sum_{i=0}^T y_i$$



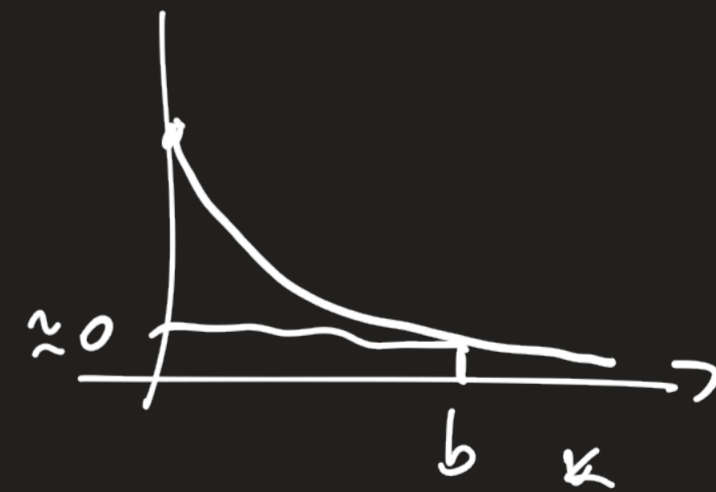
better strategy: simulate m (few) draws ($m=5$ or $m=10$)

take at each time $\bar{y}_j = \frac{1}{m} \sum_{i=1}^m y_{j,i}$

• How to choose b ?

AUTO COVARIANCE X_t

$$\rho_k = \text{cov} \left[\bar{y}_i, \bar{y}_{i+k} \right]$$



$$\hat{\rho}_k = \frac{1}{T-k} \sum_{i=1}^{T-k} \left[\bar{y}_i - \bar{Y} \right] \left[\bar{y}_{i+k} - \bar{Y} \right] \quad \left(\hat{\rho}_k \text{ becomes bad for large } k \right)$$