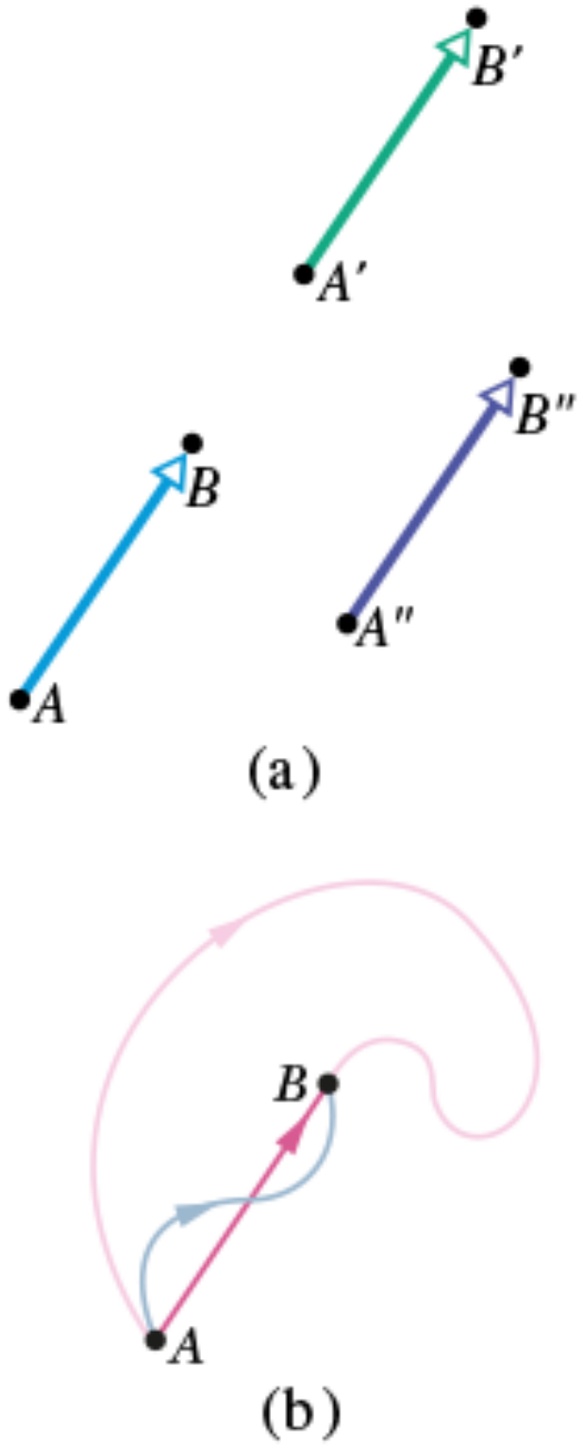
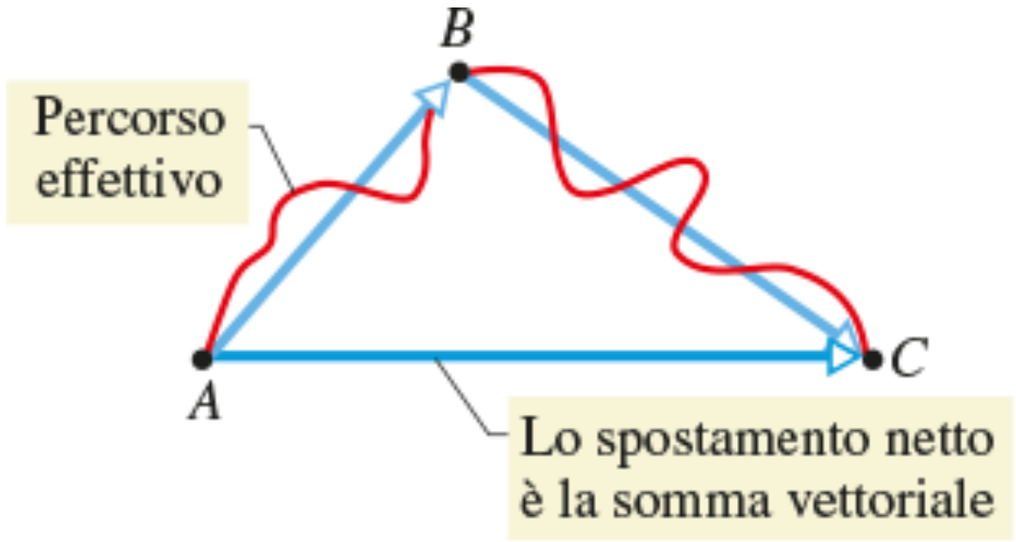
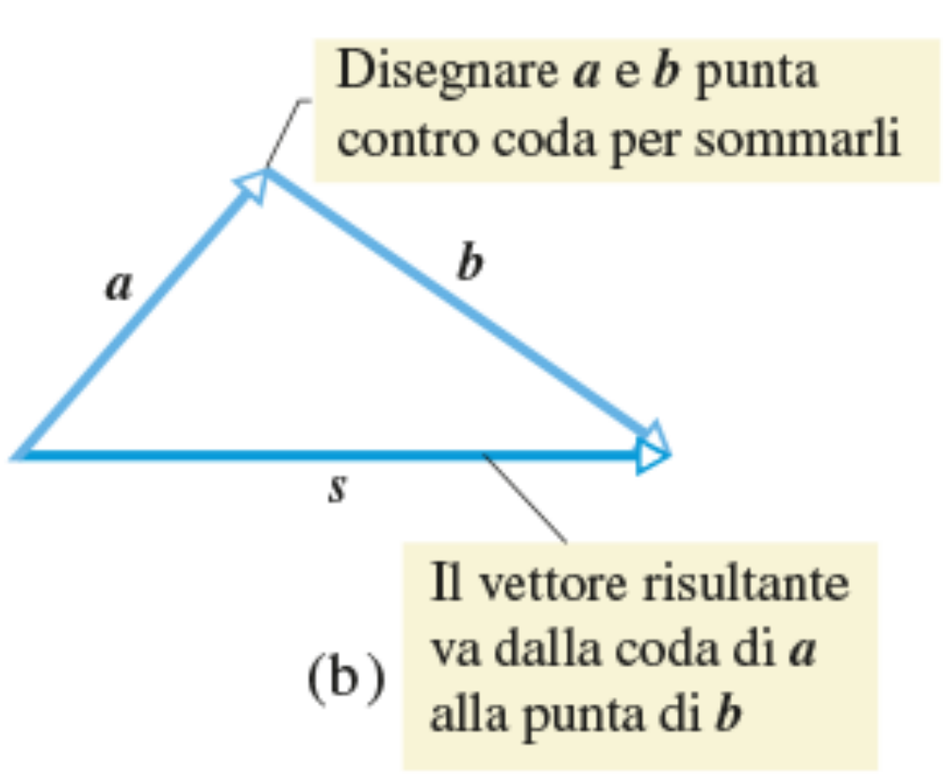


(a)

(b)



(a)



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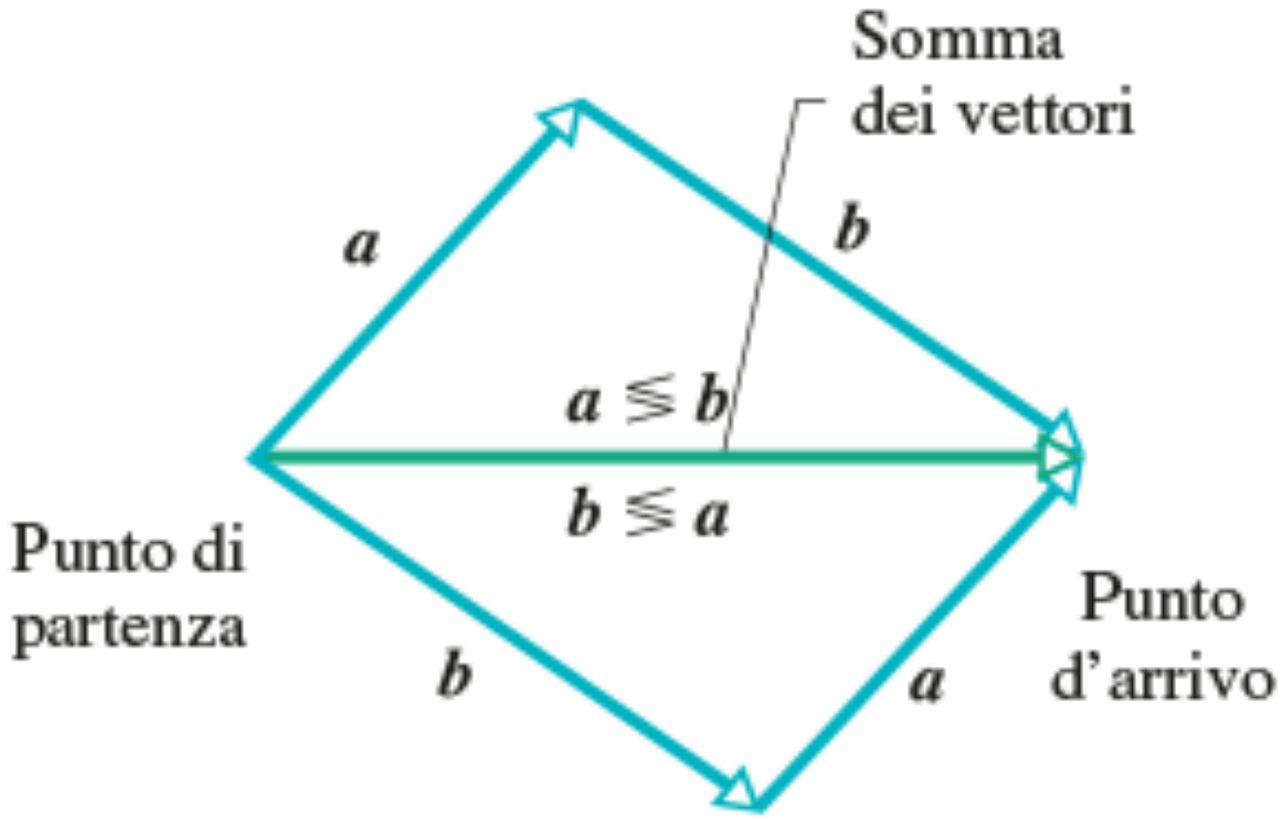
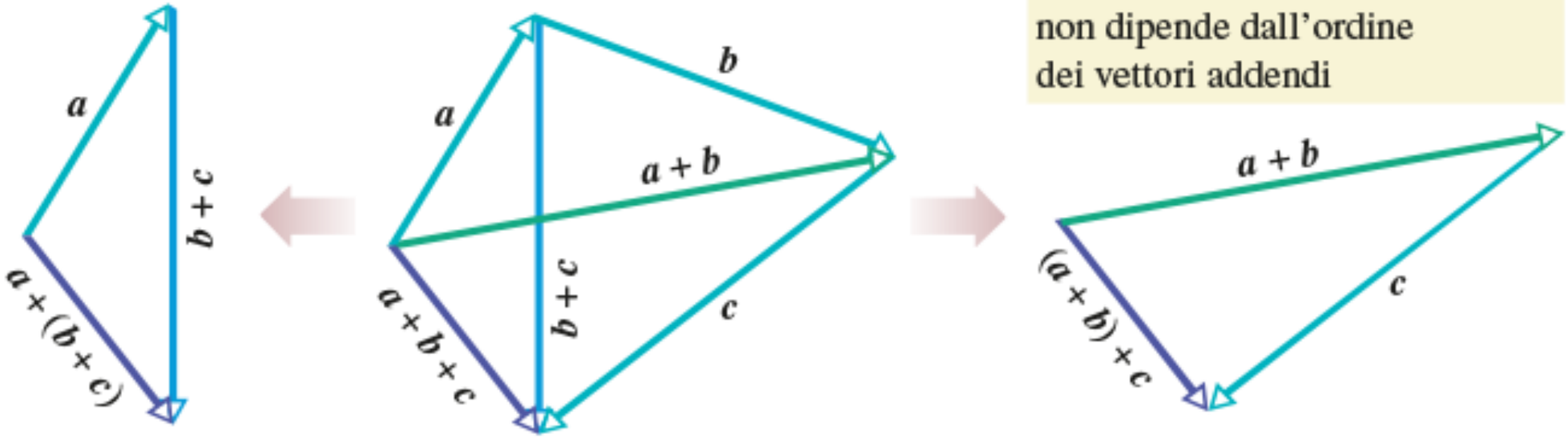
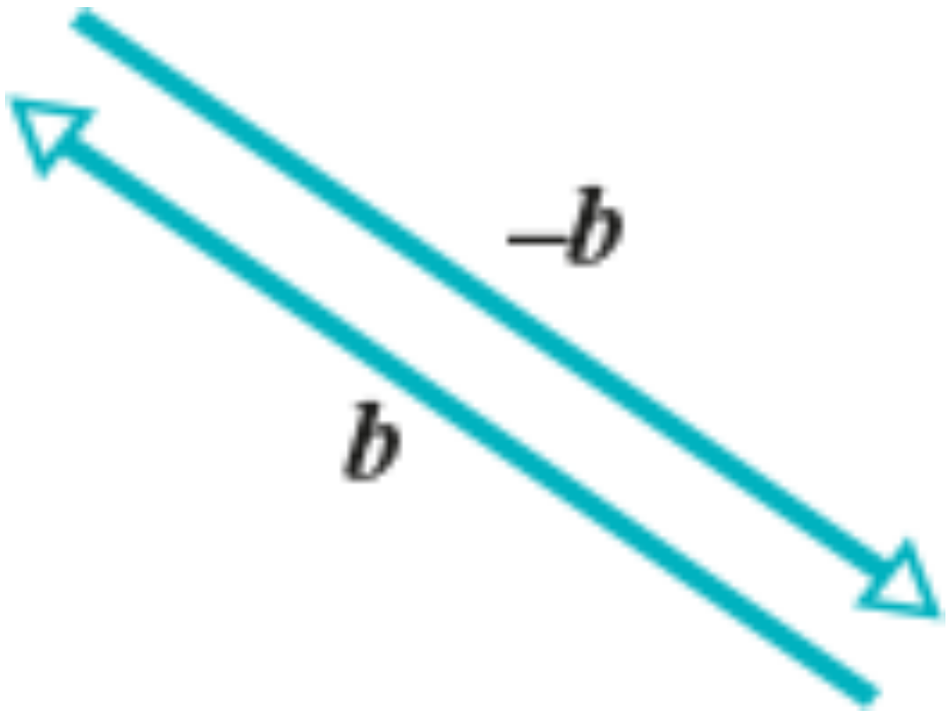
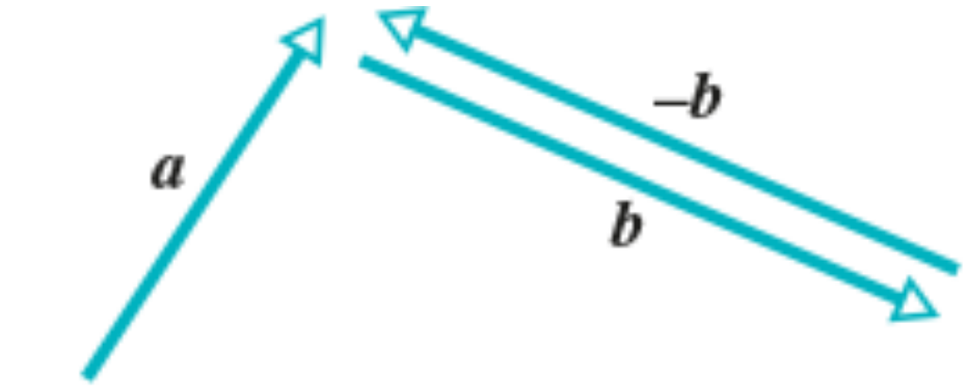


Il vettore risultante dalla somma
non dipende dall'ordine dei vettori addendi

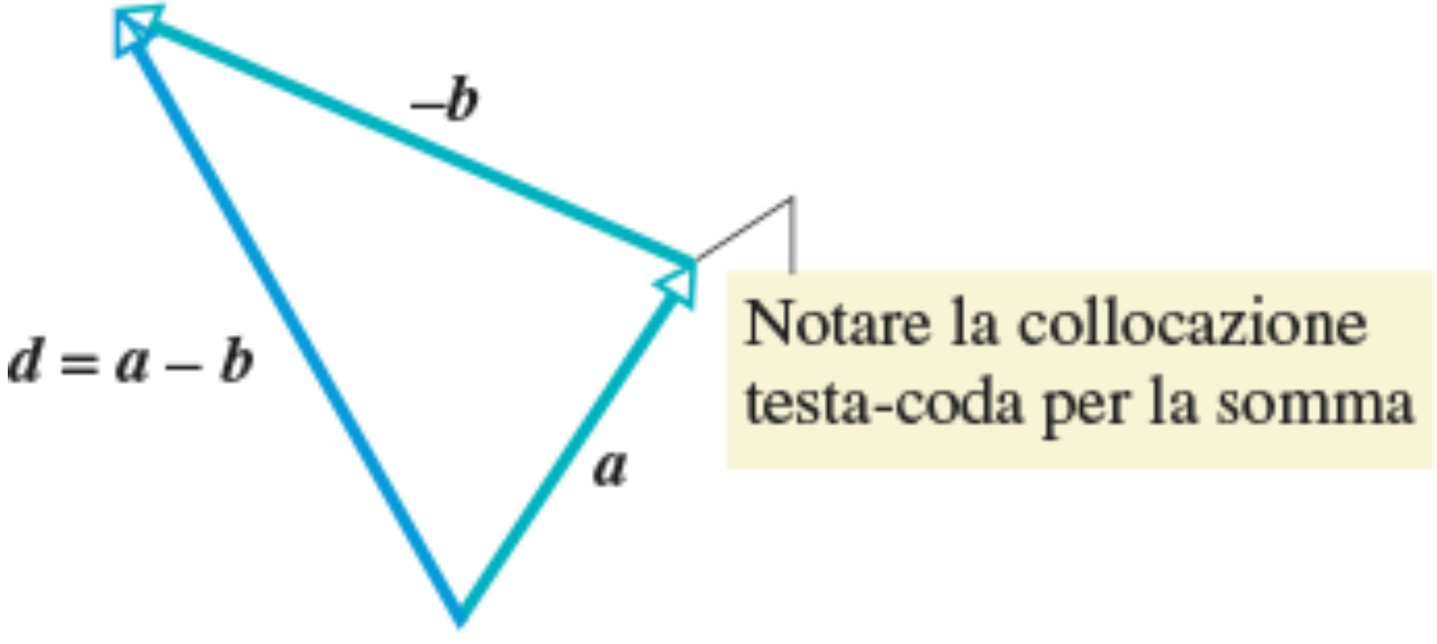
Il vettore risultante dalla somma non dipende dall'ordine dei vettori addendi







(a)



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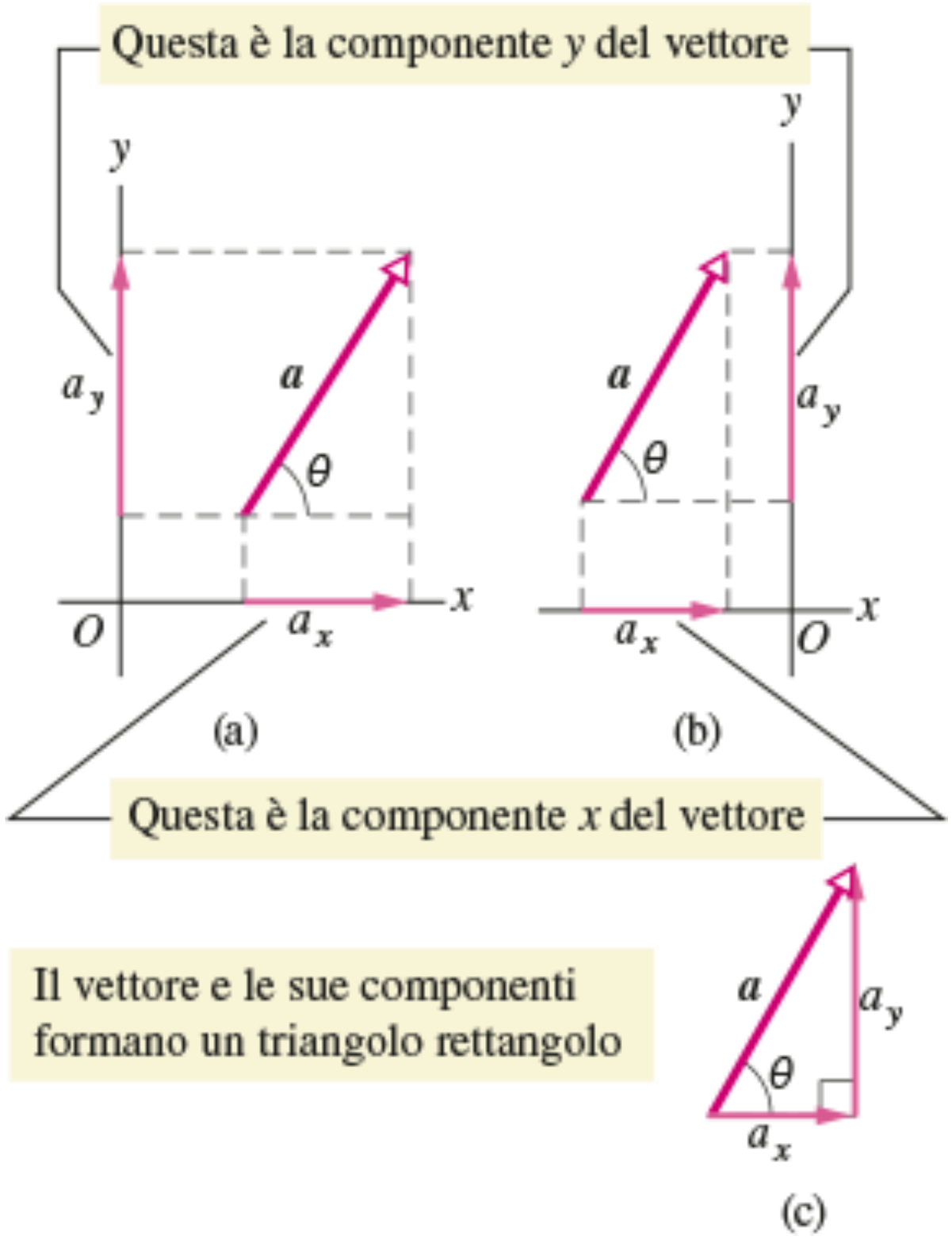
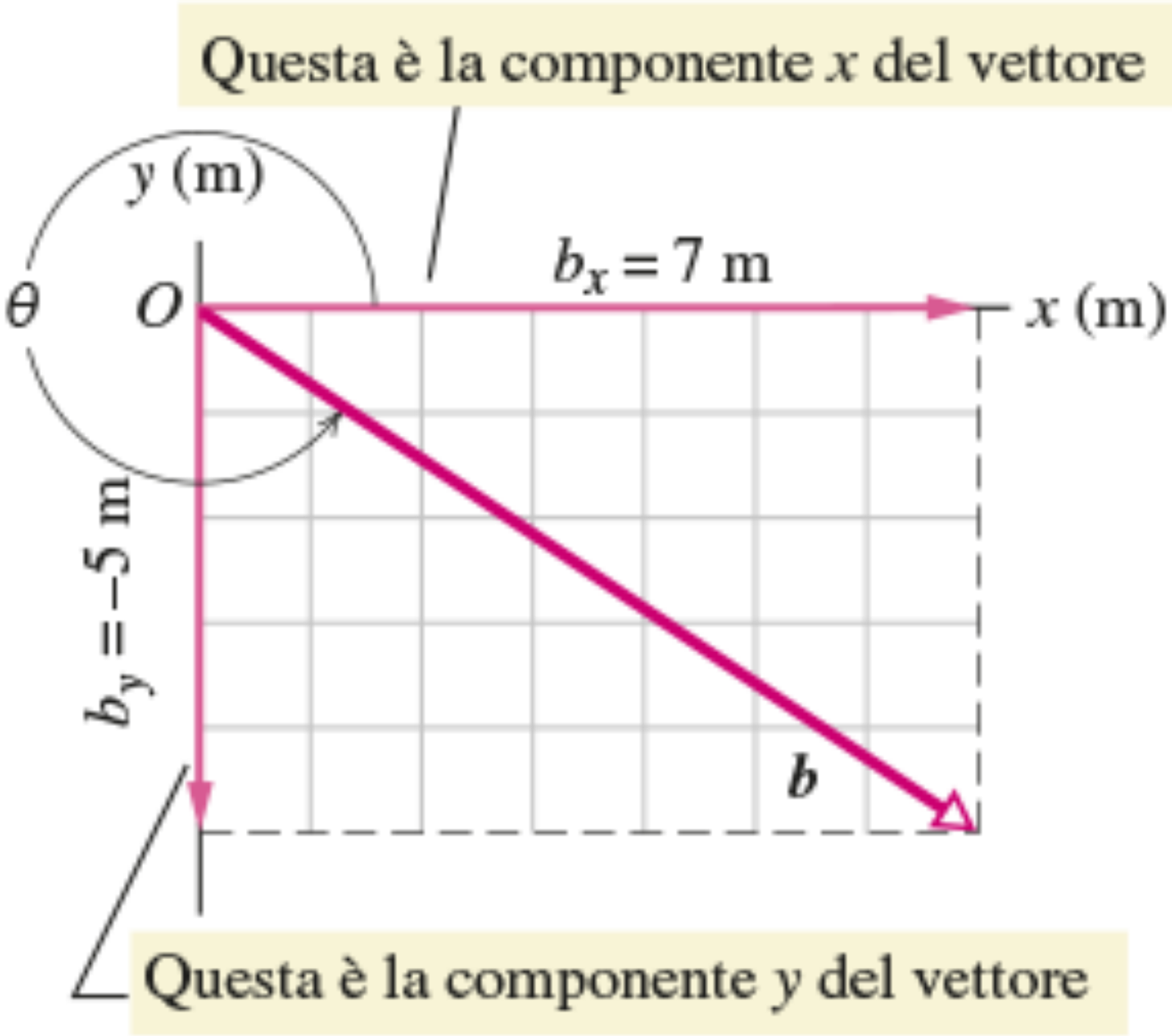
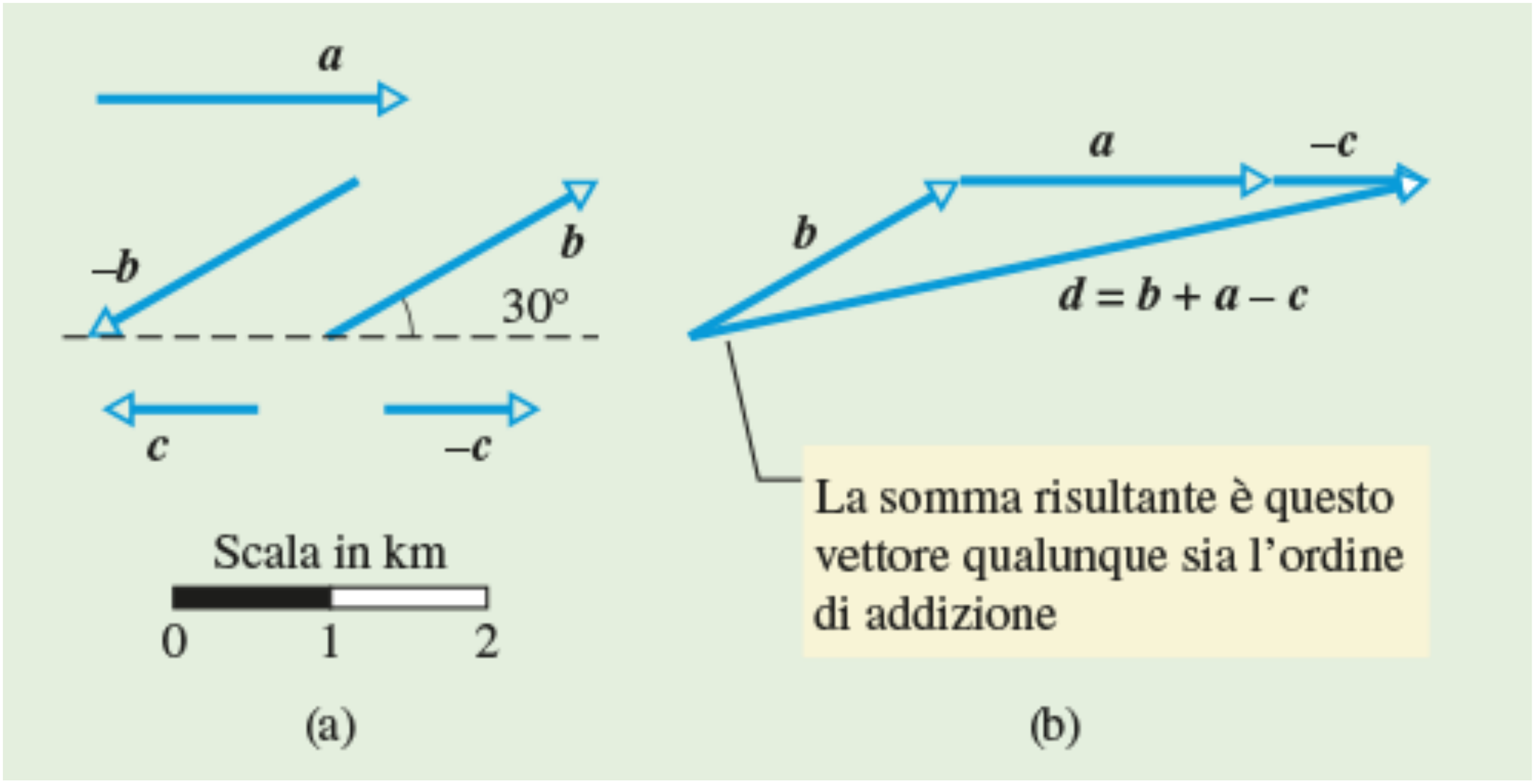
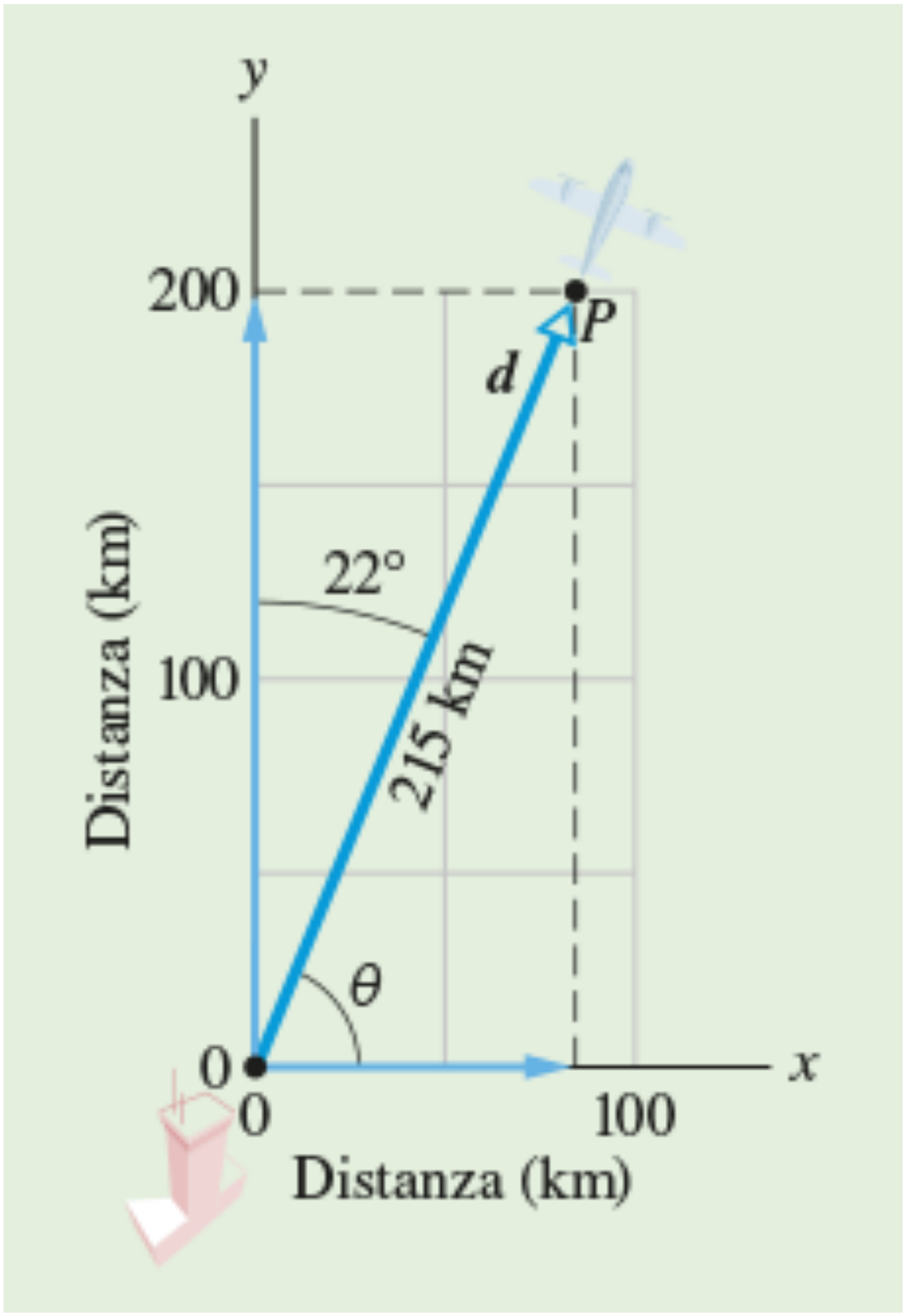




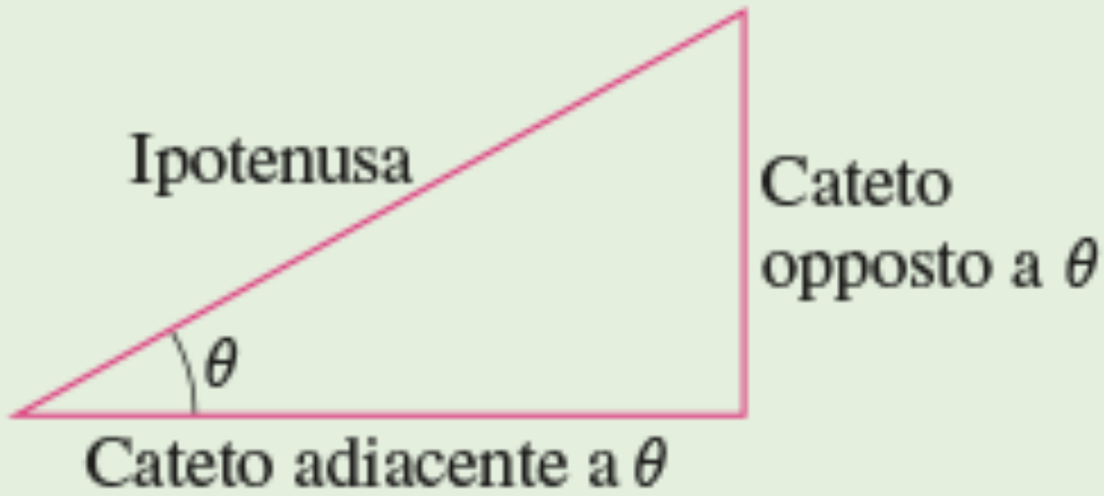


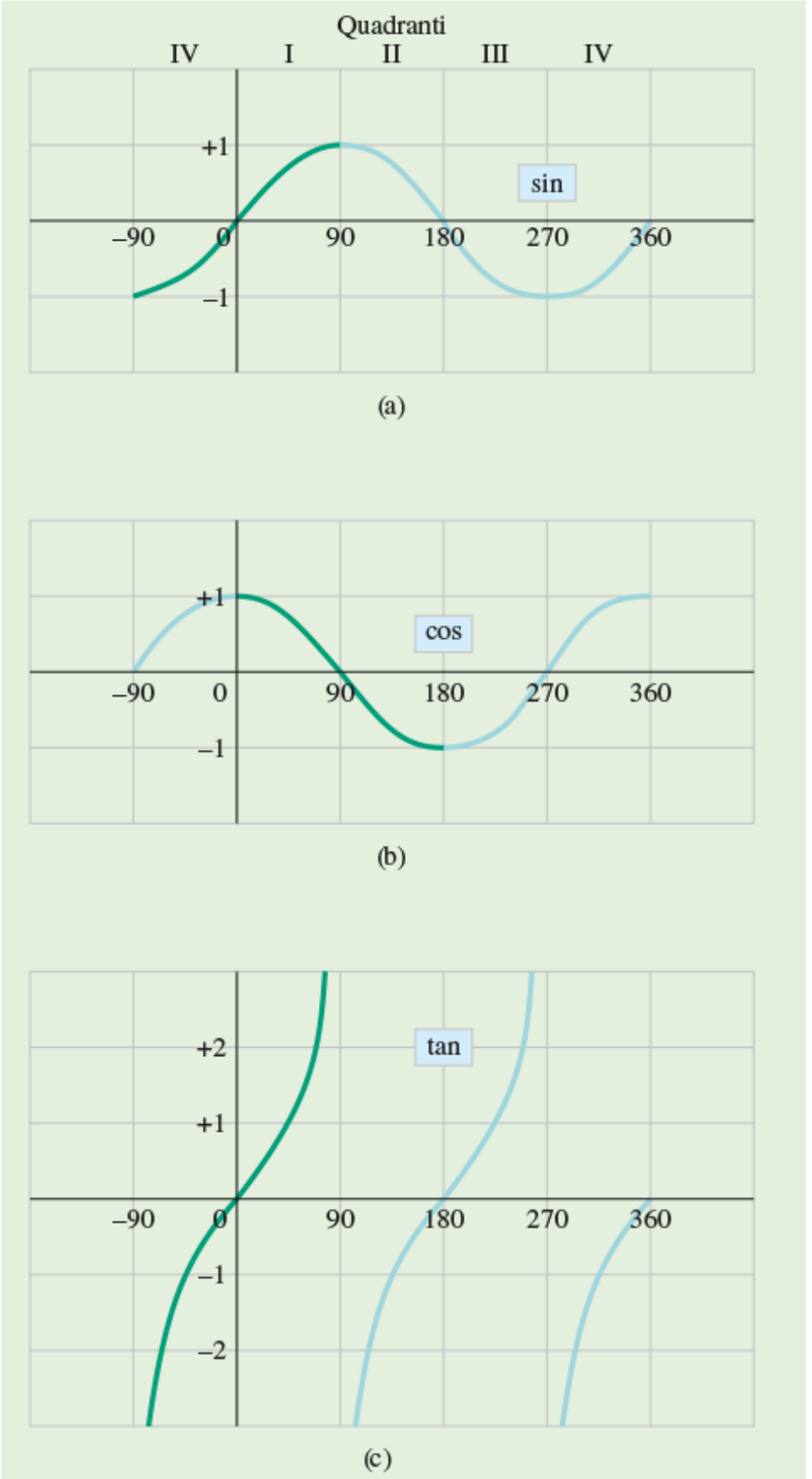


$$\sin\theta = \frac{\text{cateto opposto a } \theta}{\text{ipotenusa}}$$

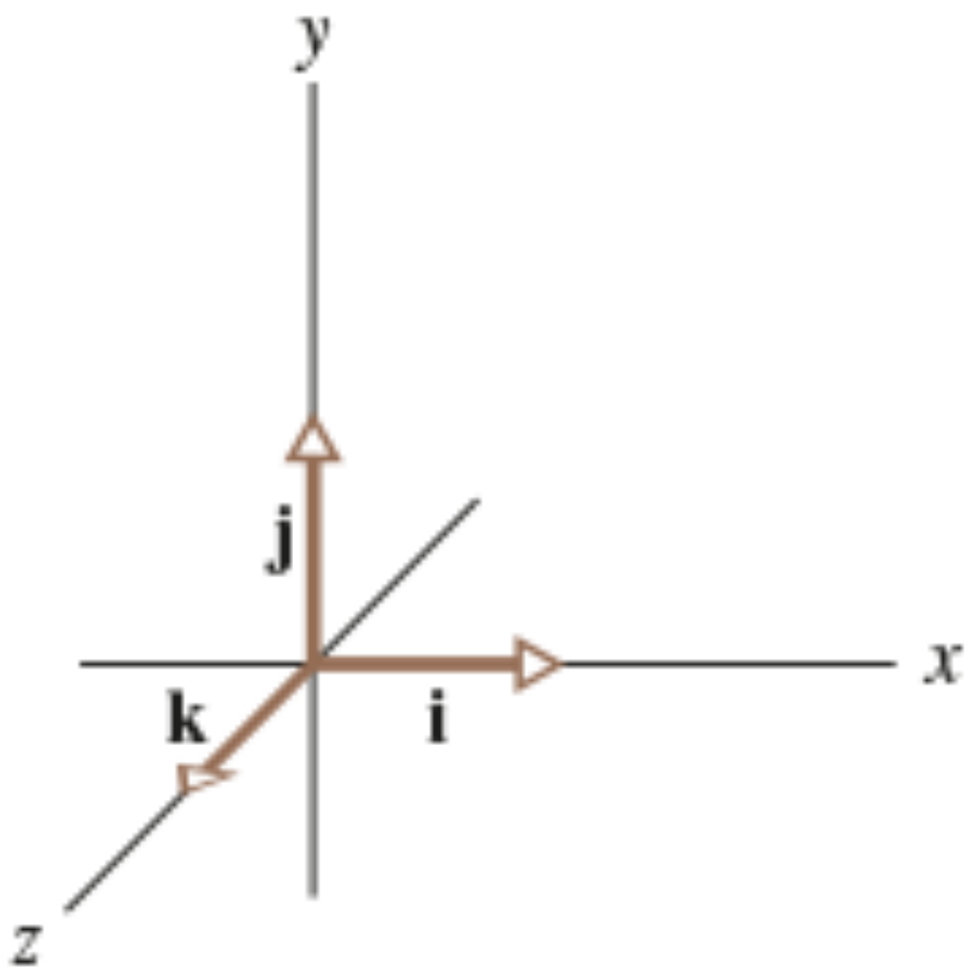
$$\cos\theta = \frac{\text{cateto adiacente a } \theta}{\text{ipotenusa}}$$

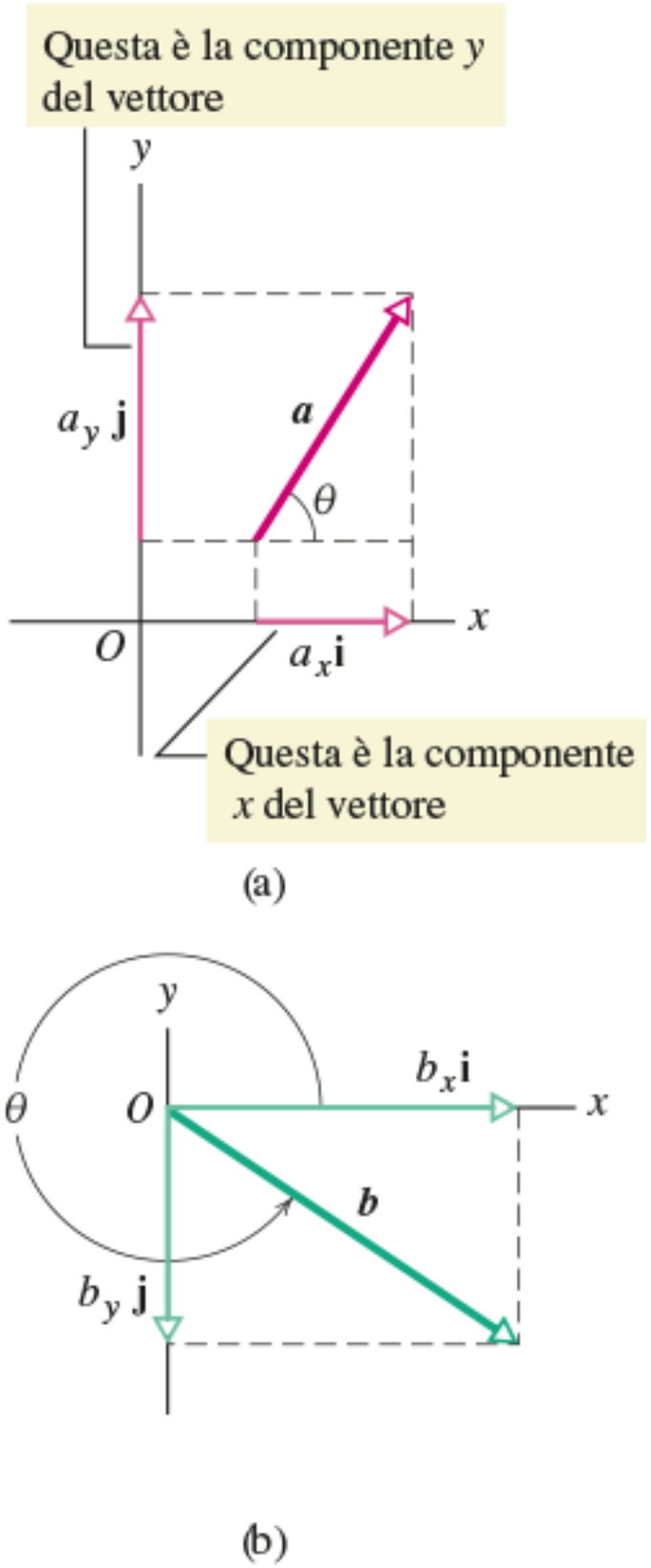
$$\tan\theta = \frac{\text{cateto opposto a } \theta}{\text{cateto adiacente a } \theta}$$

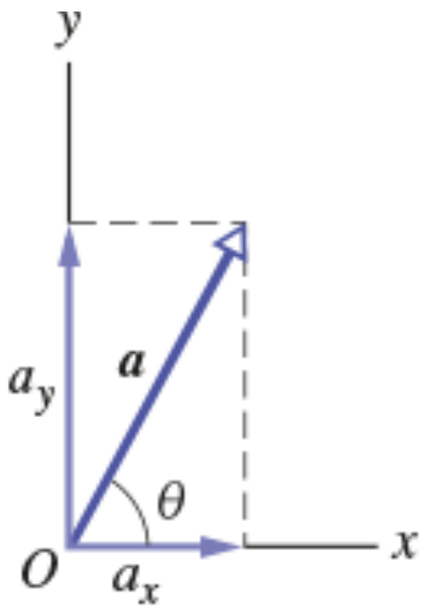




I versori sono diretti come gli assi

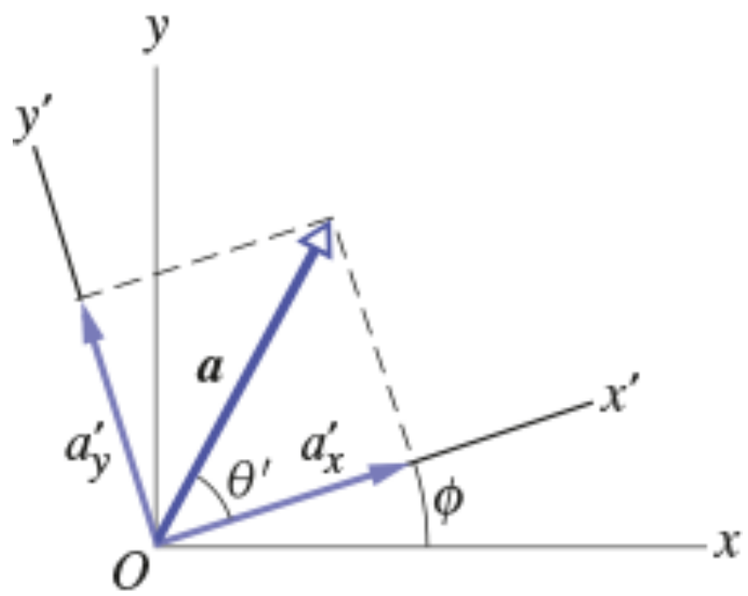




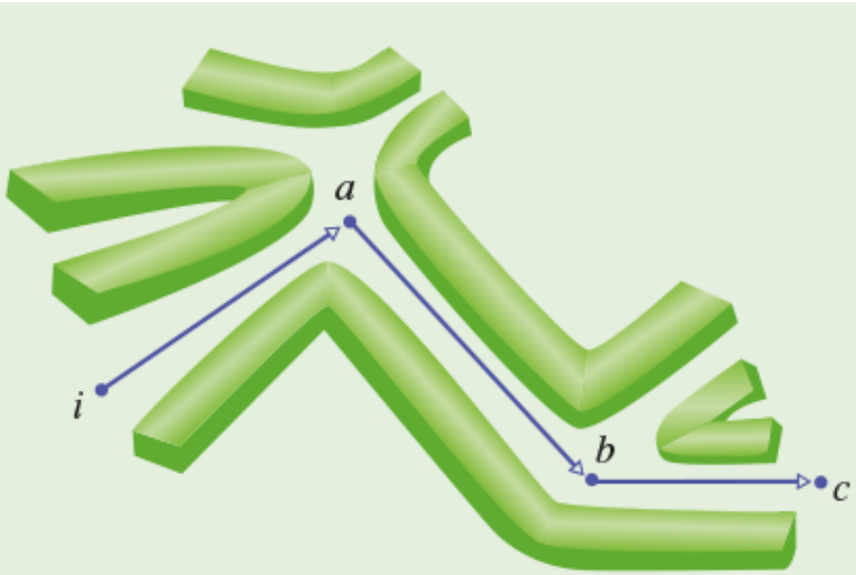


(a)

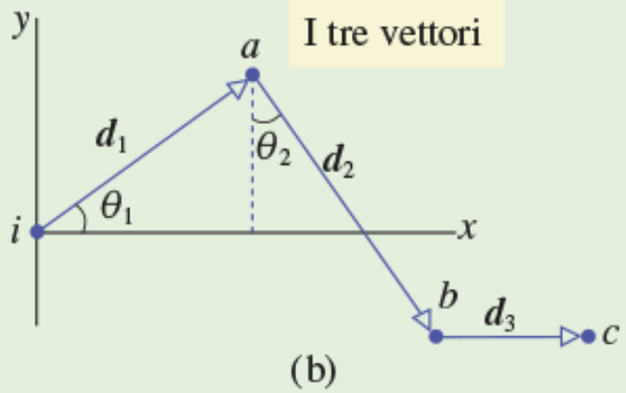
La rotazione degli assi modifica le componenti a vettore invariato



(b)



(a)



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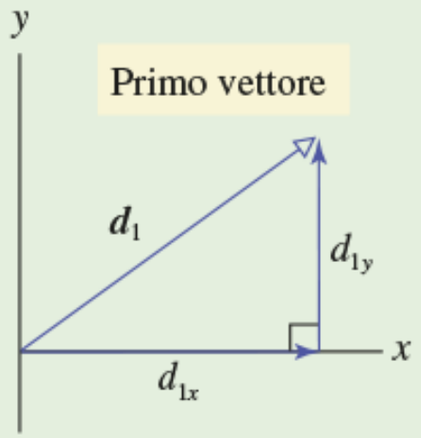
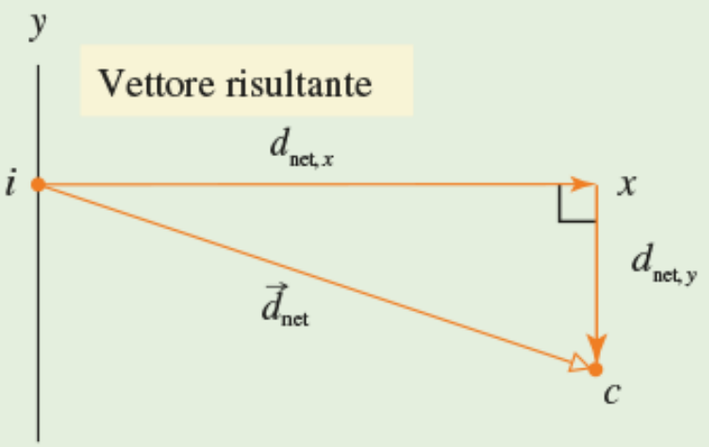
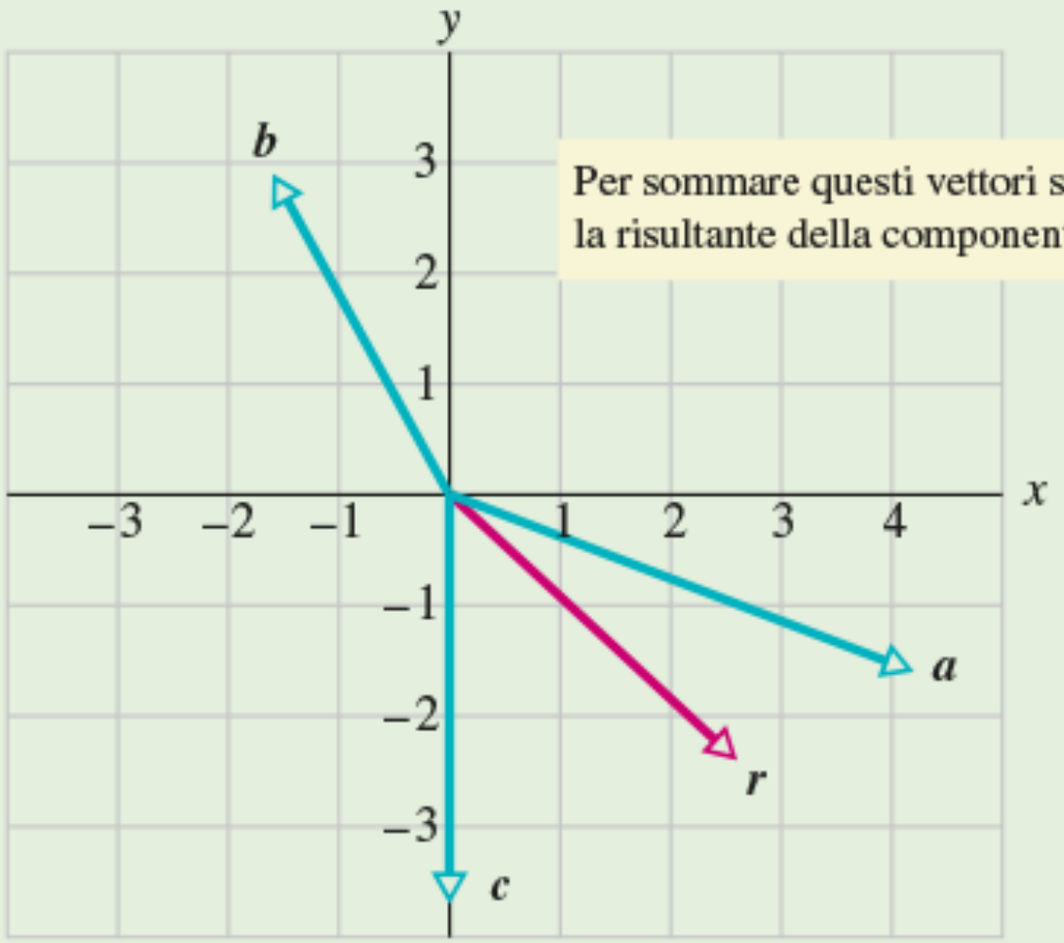


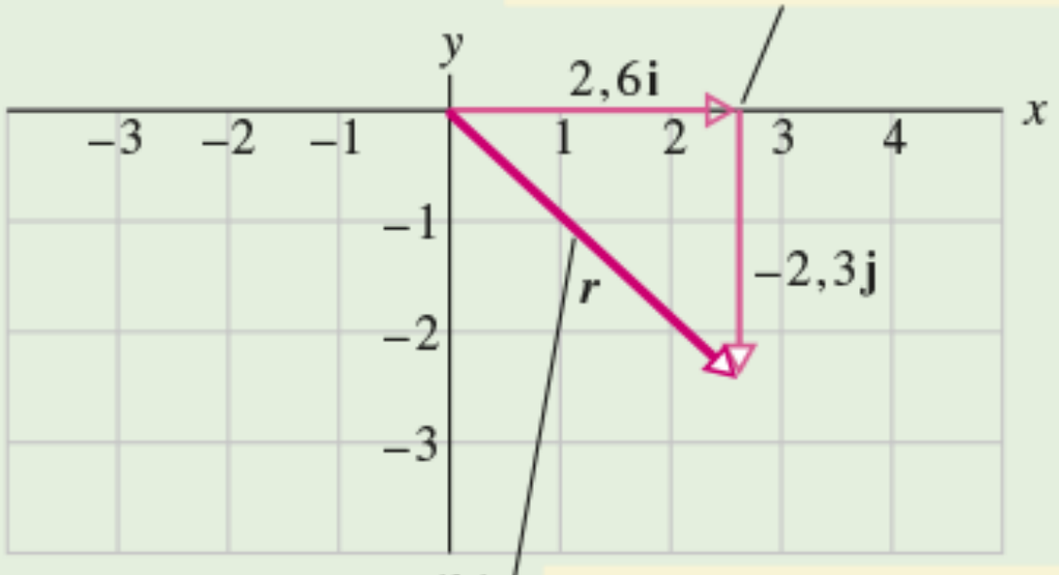
(c)



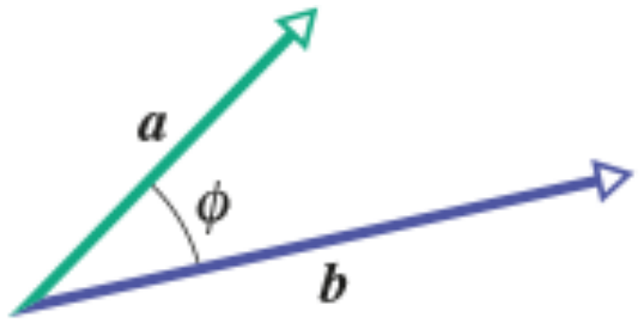
(d)



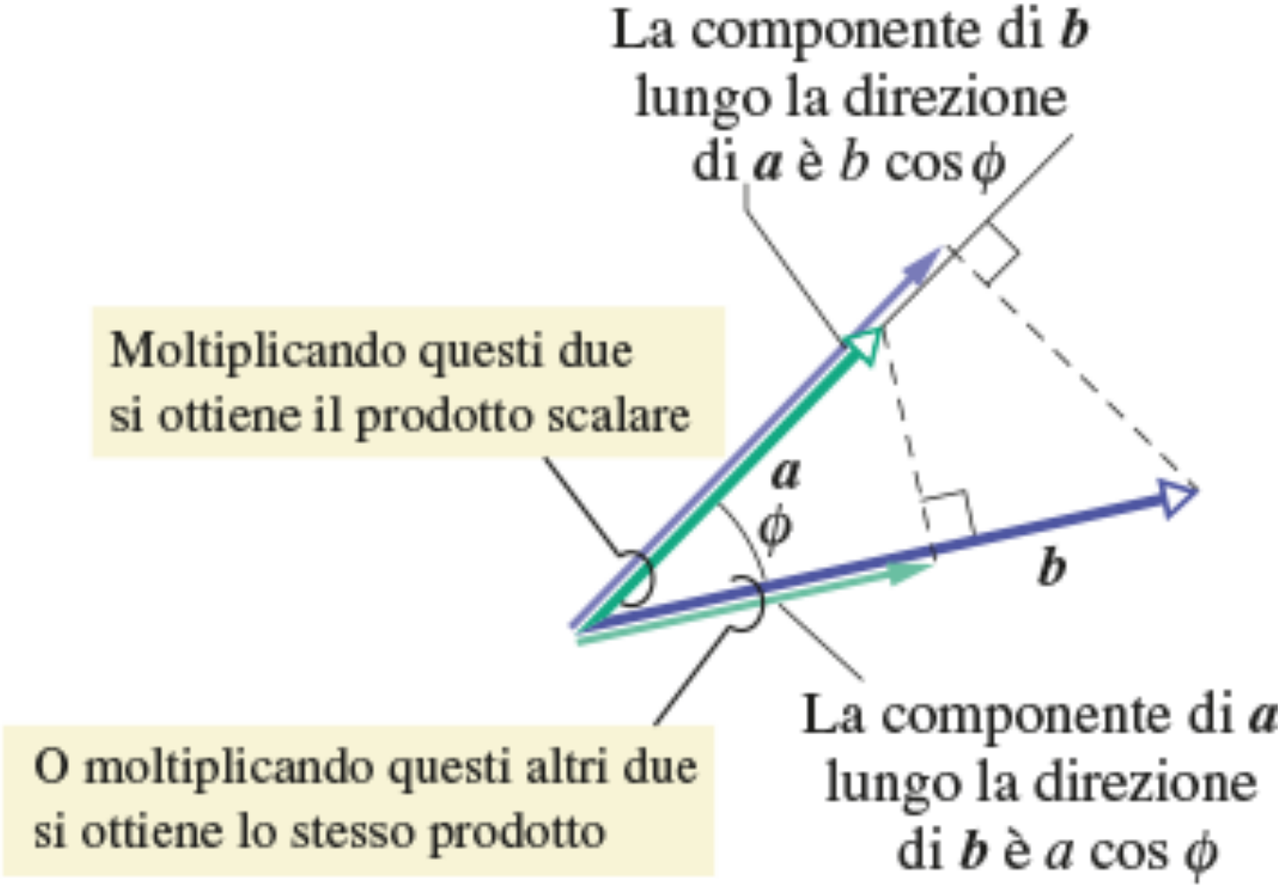
(a) Poi si dispongono le due risultanti una in coda all'altra



(b) Questo è infine il risultato della somma vettoriale



(a)



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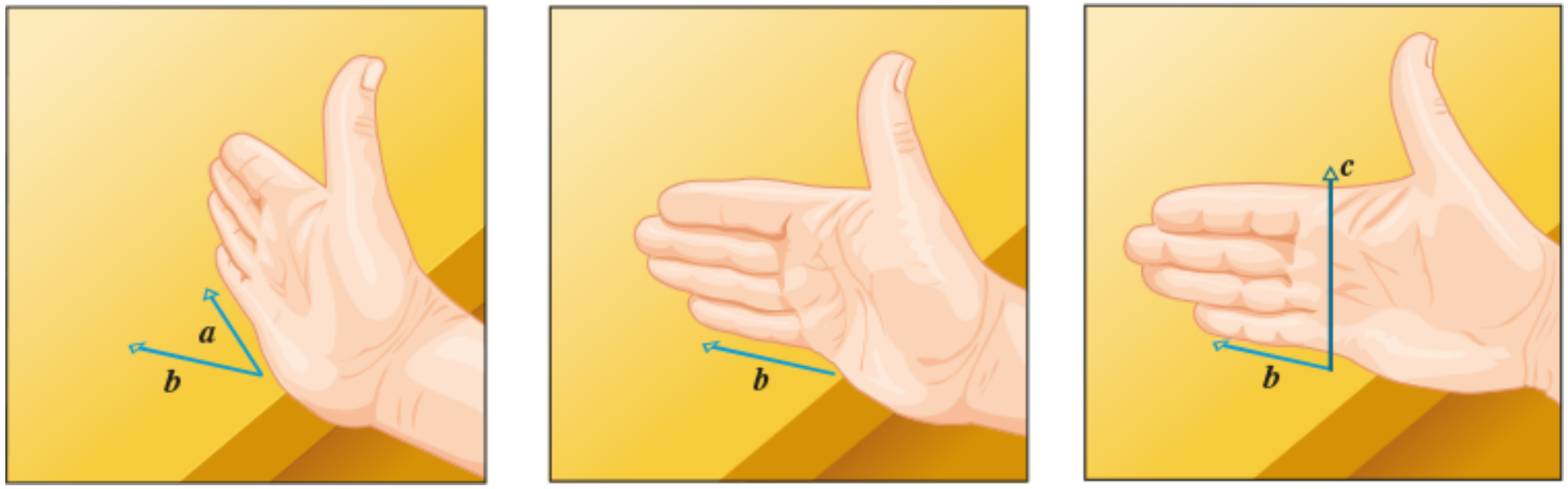
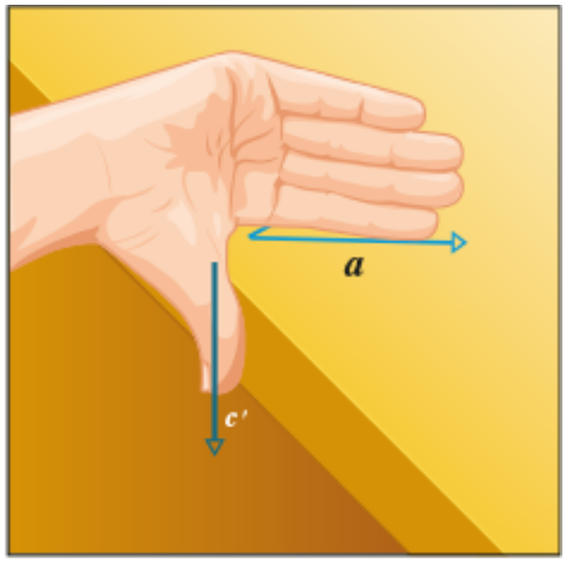
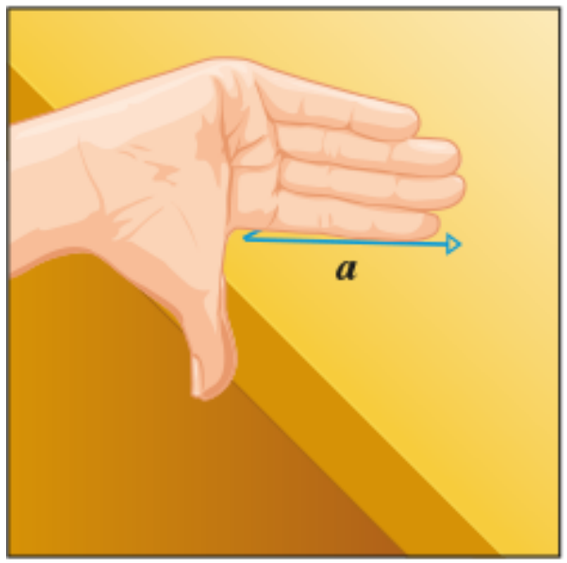
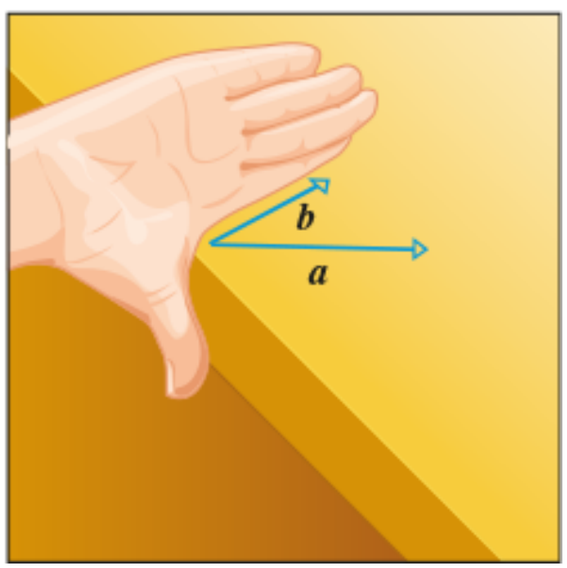
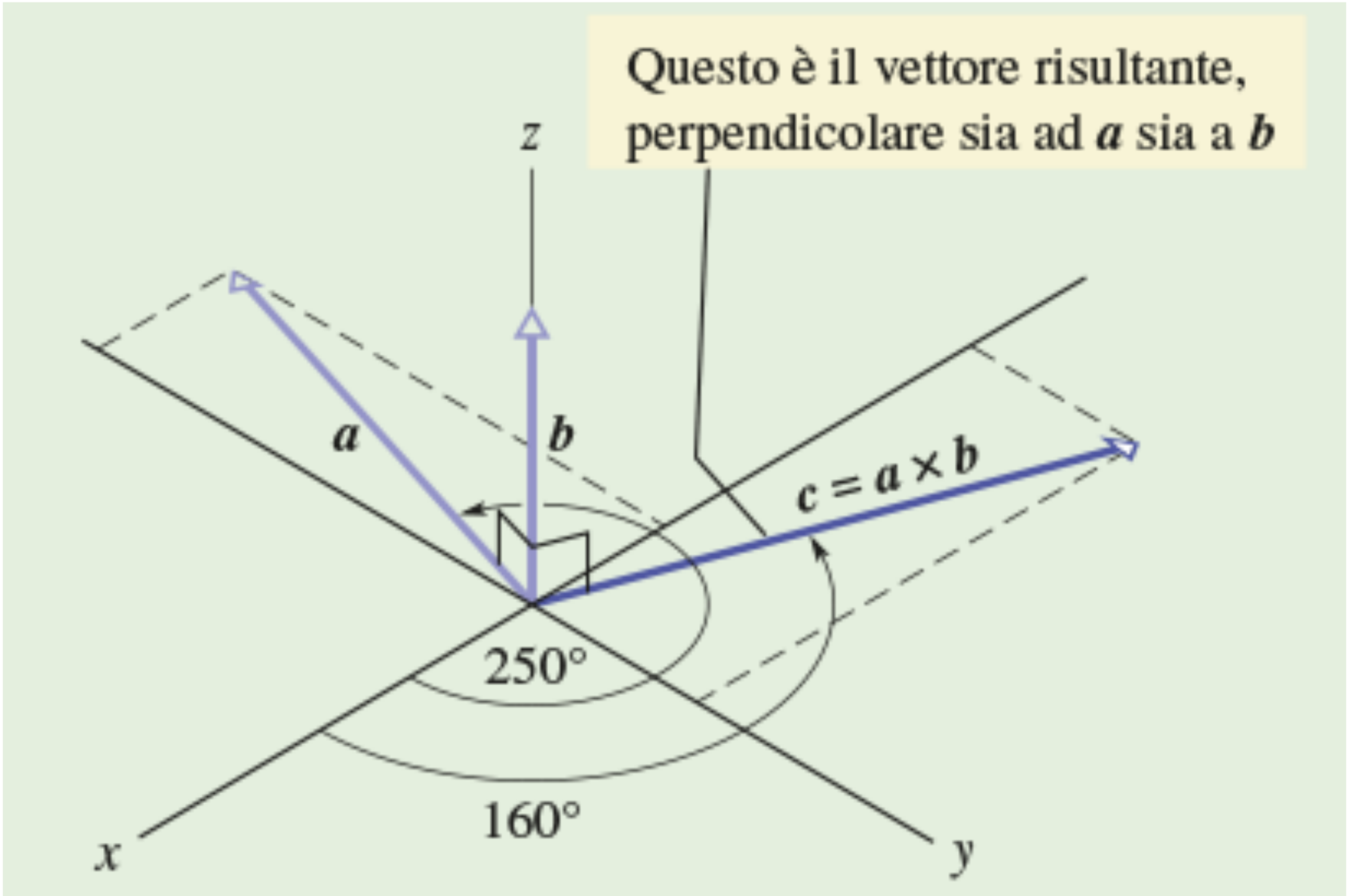
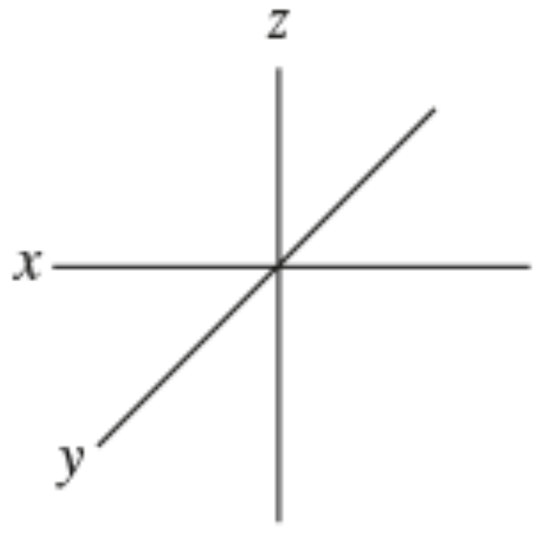




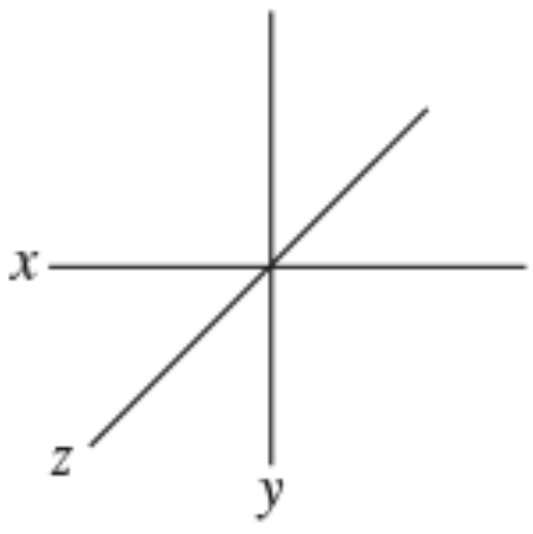








(a)



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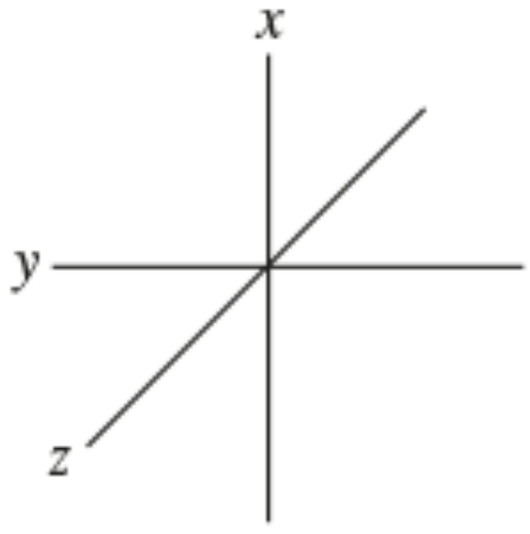

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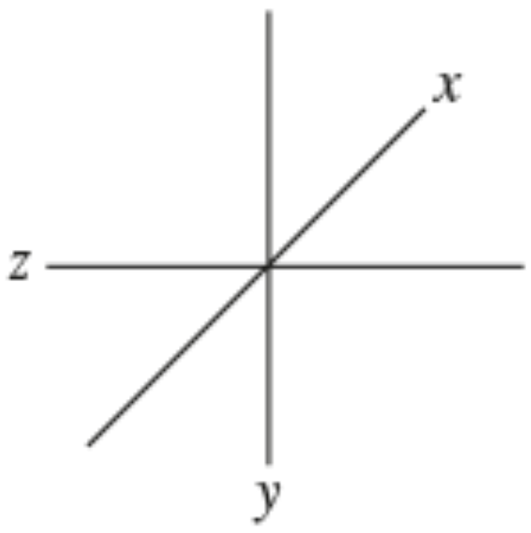

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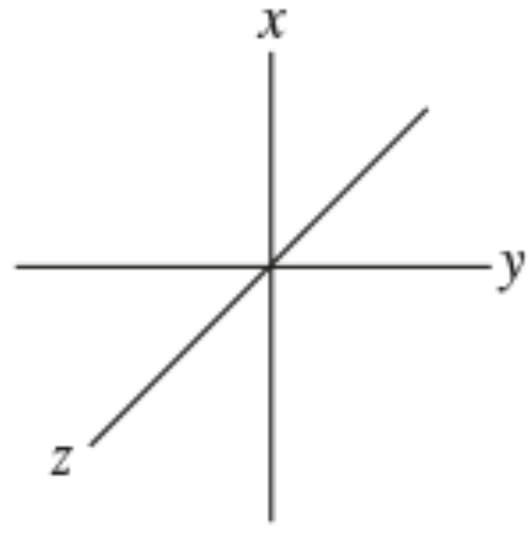
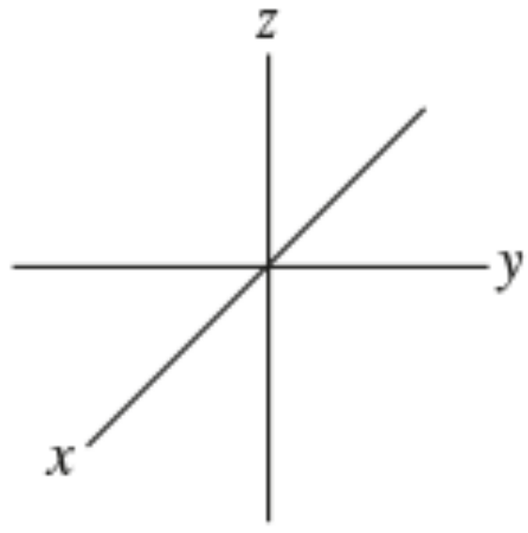
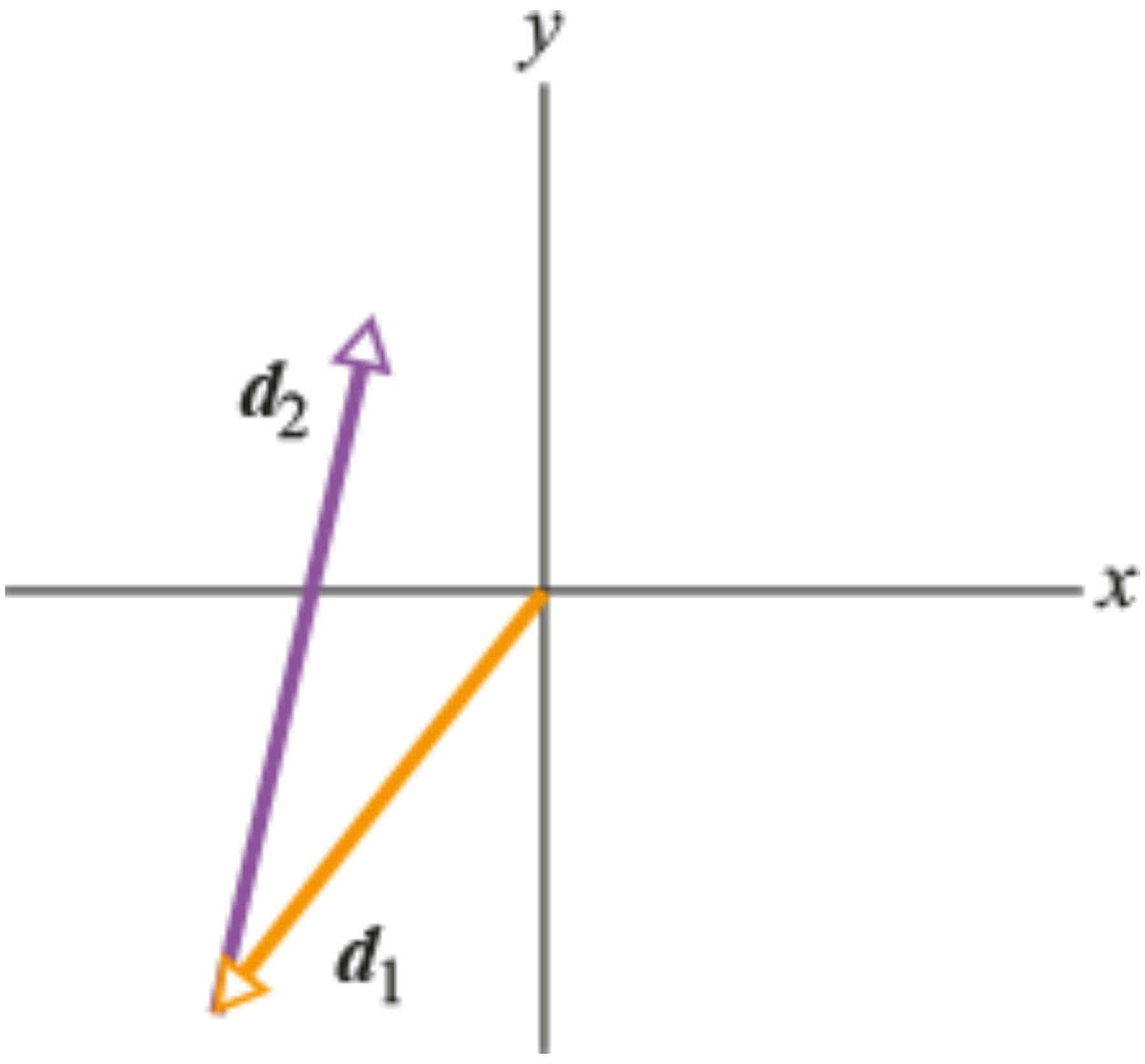
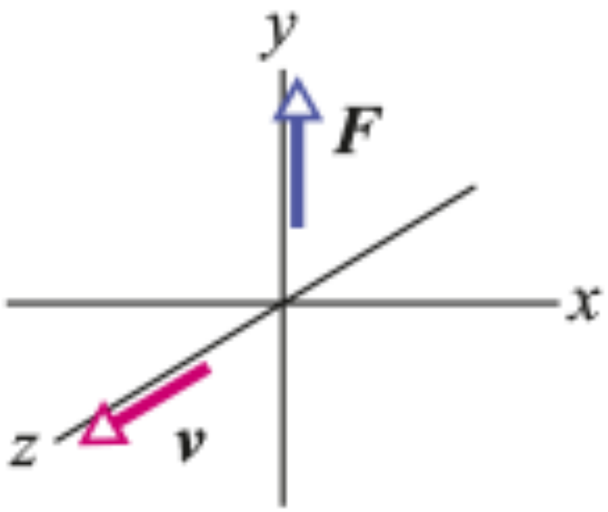


(e)

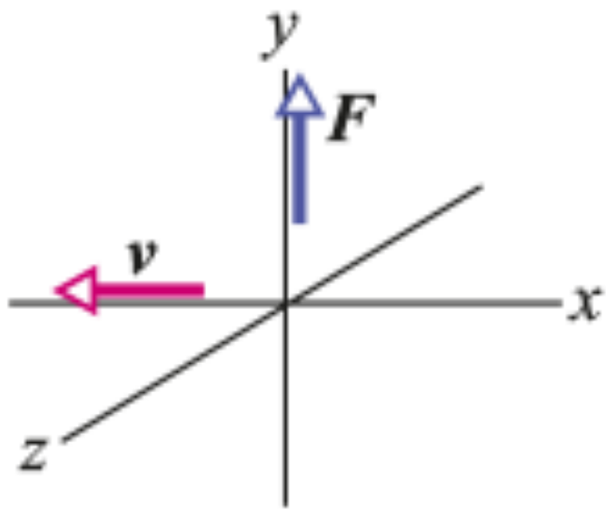


(f)

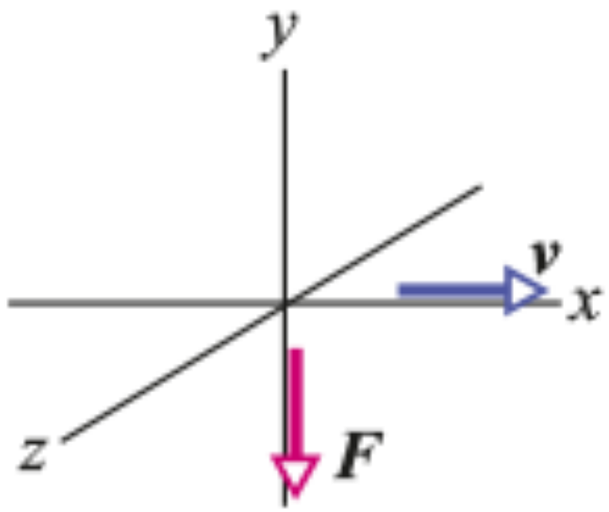




(1)



(2)



(3)