

#### Diversità degli studi ditrieste Dipartimento di Matematica e Geoscienze

### Corso di Geologia Marina 2020-21



## Illuminating Earth's Past, Present, and Future



THE INTERNATIONAL OCEAN DISCOVERY PROGRAM EXPLORING THE EARTH UNDER THE SEA

SCIENCE PLAN FOR 2013-2023

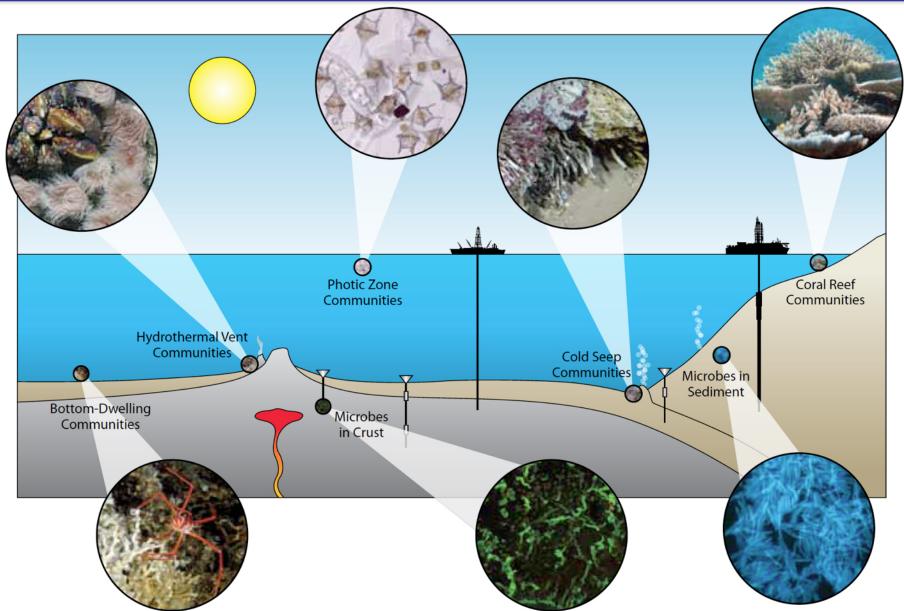
### **Research Themes**

- Climate and Ocean Change: Reading the Past, Informing the Future
- Biosphere Frontiers: Deep Life, Biodiversity, and Environmental Forcing of Ecosystems
- Earth Connections: Deep Processes and Their Impact on Earth's Surface Environment
- Earth in Motion: Processes and Hazards on Human Time Scales

### Education AND OUTREACH







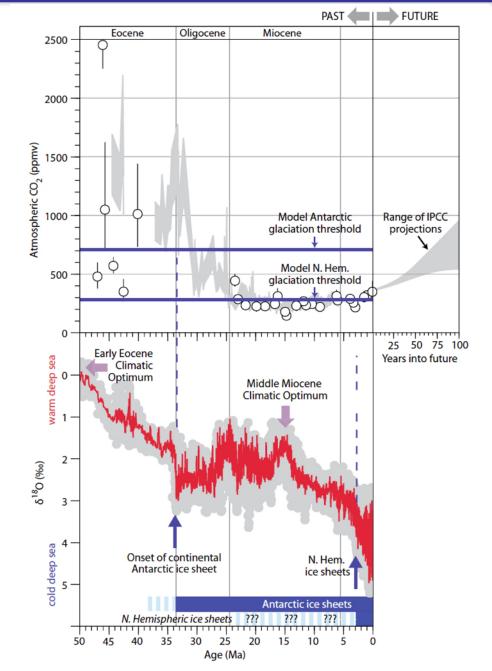
New Science Plan and as follows:

Bottom Dwelling: Ross (2007; Figure 3), Hydrothermal Vents: Devey at al. (2007, Figure 2), Microbes in Crust: Orcutt et al. (2010), Photic Zone: M. Montresor, SZN/Alfred Wegener Institute, Cold Seep Communities: Vanreusel et al. (2009, Figure 6A), Microbes in Sediment: Figure 3. 2B, Coral Reef: Coral Disease Working Group (2007; Figure 2)





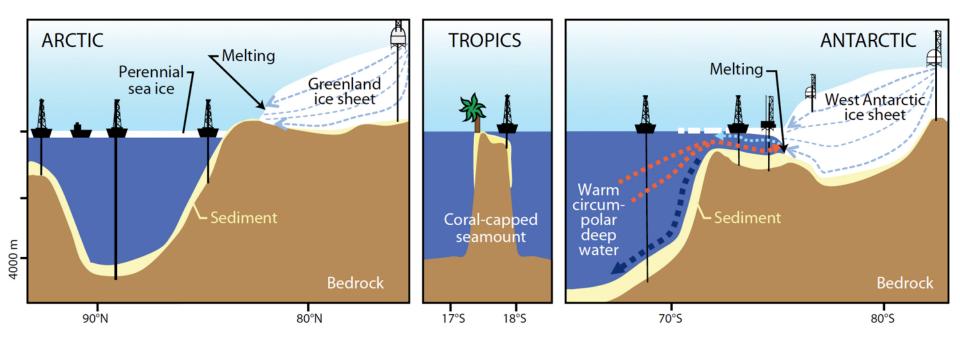
### Climate and Ocean Change: Reading the Past, Informing the Future







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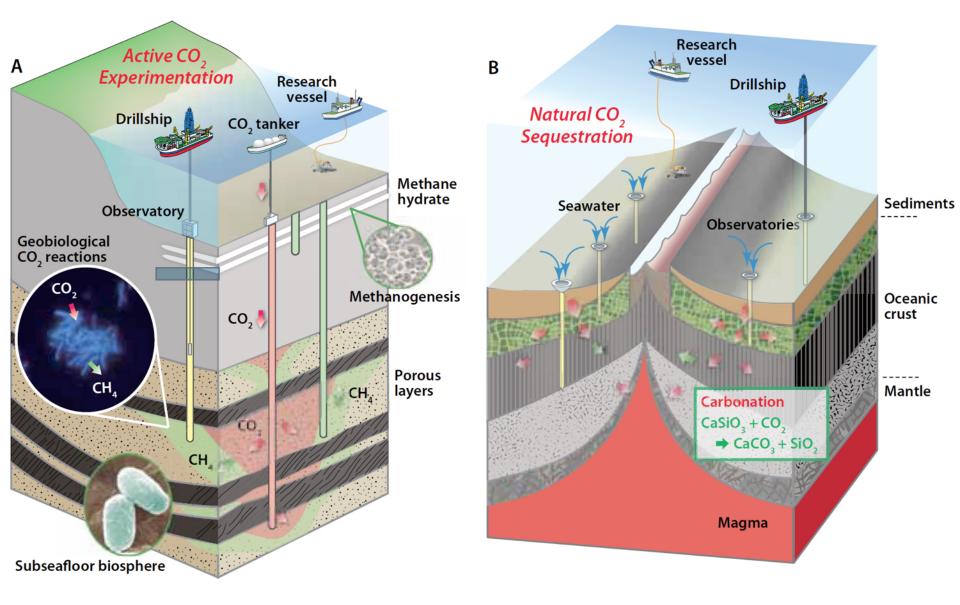


#### Elements of this figure were adapted from Schoof (2010)





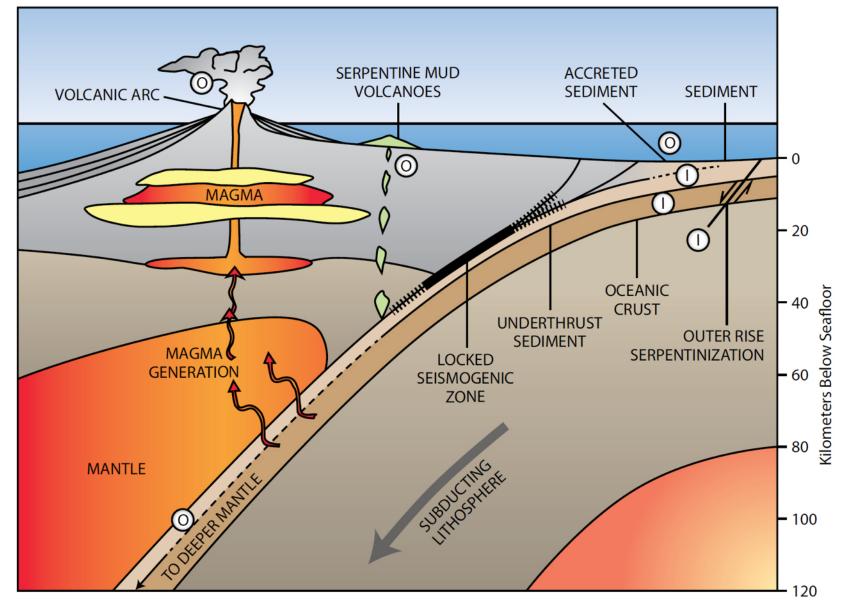
### Biosphere Frontiers: Deep Life, Biodiversity, and Environmental Forcing of Ecosystems







### Earth Connections: Deep Processes and Their Impact on Earth's Surface Environment

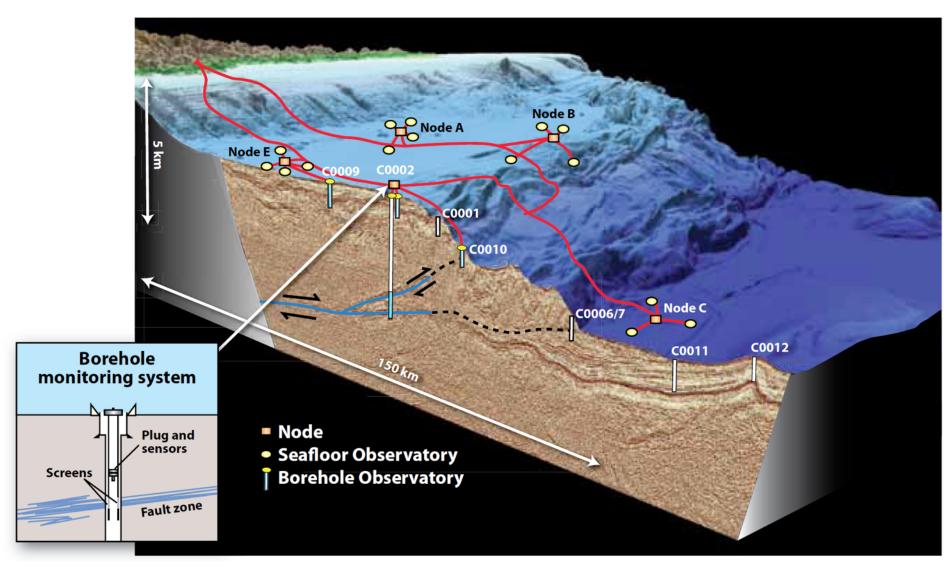


New Science Plan



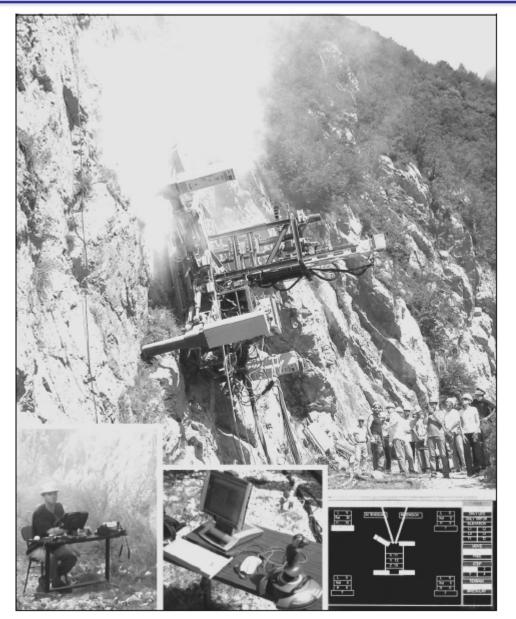


### Earth in Motion: Processes and Hazards on Human Time Scales









## Why robotic drilling ?

### Disadvantage

• Less control on drill process

### Advantage

- Safety
- Access to extreme environments (steep walls, extraterrestrial environments, sea floor)

Picture: Roboclimber (Molfino, 2005)





## Advantages of sea bed drill rigs

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- Stable platform optimal drill bit control
- No need for drill pipe through the water column
- Operation from multipurpose research vessels



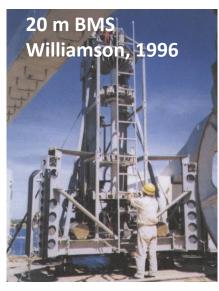
Seabed Rig AS











## Existing seabed drill rigs





3-m rockdrill University of Washington, 1990

Courtesy Time Freudenthal, MARUM, Bremen









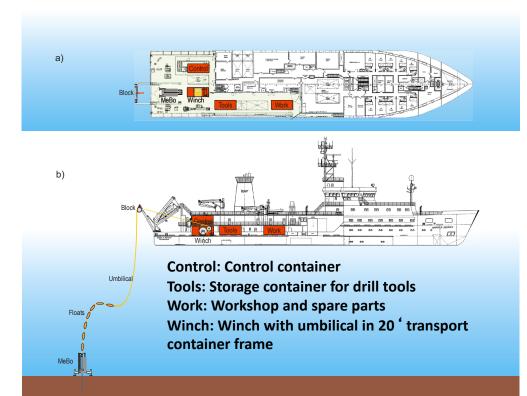
## MeBo specifications

- Drilling depth 70 m
- Coring of soft sediments and hard rocks
- Core diameter 55 84 mm
- Deployment depth 0 2000 m
- MeBo weight about 10 tonnes
- Total system weight about 75 tonnes
- Transport within six 20<sup>+</sup> containers









## **Concept of MeBo**

- Umbilical is used to lower the drill rig to the sea floor
- Umbilical is used for energy supply and remote control from the vessel

 Transport of the System within 20<sup>+</sup> shipping containers, that are mounted on the working deck of the research vessel

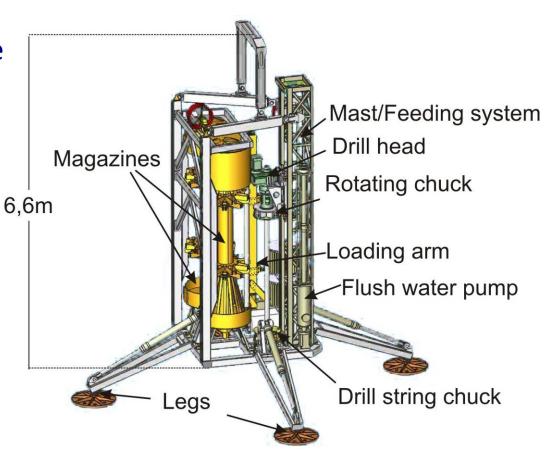






## Concept

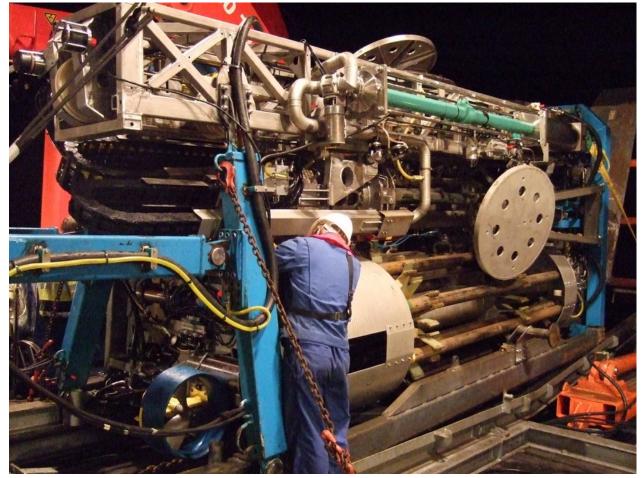
- Mast, drill head and flush water pump form the central drilling unit
- Drill rig has access to drilling tools stored within two magazines
- The drill string is built up and down using a loading arm and two chucks
- Stability on the sea floor is increased by movable legs











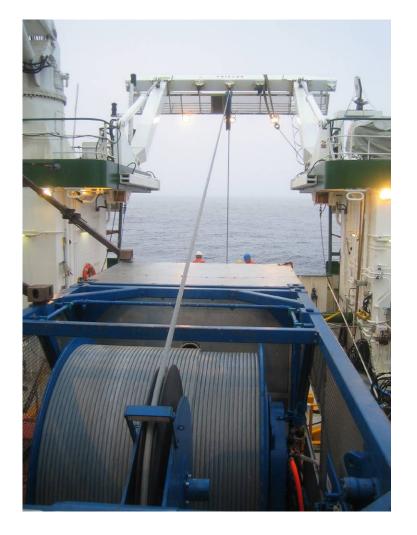
## Drill rig

For maintenance work between deployments the MeBo lies horizontally on deck. The movable legs are armed in. The rig weighs about 10 tonnes.









## Winch

The winch stores 2500 m of the umbilical. The pull force of the winch in the upper layer is 12 tonnes.









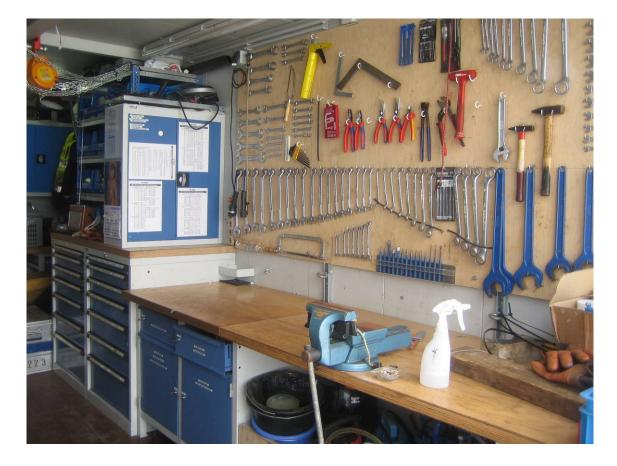
## **Control Unit**

The drill rig is remotely controlled from the control container. All actions are surveyed by video cameras and sensors.









## Workshop

A mechanical workshop and spareparts are transported within a workshop container for maintenance and repair on sea









## **Drill tools**

2.35m rods are used to build up the drill string. 30 core barrels and 29 rods are required for core drilling down to 70 m below the sea floor.







MeBo 2004/2005 (HBFG)

Prakla Bohrtec

**Schilling Robot** 

NSW, STA ...

nik

### Wire-line 2007/2008 (HBFG)

### Pressure Core Barrel 2008/2010 (BMBF, SUGAR)

# Borehole Logging (2010)





