



UNIVERSITÀ
DEGLI STUDI DI TRIESTE



09 – Resolved signals

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Resolved signals

- The VHDL language requires the designer to specify precisely which values are obtained from the interconnection of multiple outputs (i.e., drivers) on the same signal.
- This is done with the *resolved signals*, which are an extension of the normal signals studied in the previous lessons.
- The resolved signals include in their definition a function, called *resolution function*, that is used for computing the final value of the signal from the contributions of all drivers.

Example: tri-state logic

- We want to write a resolved signal of the type:

```
type tri_state_logic is ('0', '1', 'Z');
```

- The resolution function must be capable to accept any number of contributions of type *tri_state_logic* and must return a *tri_state_logic*.
- We write a resolution function that has a single parameter, which is an unconstrained array of elements *tri_state_logic*.

```
type tri_state_logic_array is array (integer range <>) of tri_state_logic;
```

Example: tri-state logic

```
function resolve_tri_state_logic ( values : in tri_state_logic_array )
    return tri_state_logic is
    variable result : tri_state_logic := 'Z';
begin
    for index in values'range loop
        if values(index) /= 'Z' then
            result := values(index);
        end if;
    end loop;
    return result;
end function resolve_tri_state_logic;
```

```
signal s1 : resolve_tri_state_logic tri_state_logic;
```

Resolved signal

```
signal s1 : resolve_tri_state_logic tri_state_logic;
```

- The resolution function indicates that the signal is a *resolved signal*, with the resolution function there given.
- Since the signal is a resolved signal, it can have different drivers.
- When a transaction for the signal becomes active, the novel value is not applied directly to the signal.
- On the contrary, the contributions of all sources connected to the signal are grouped together in an array, which is passed to the resolution function.
- The result of the resolution function is the new value applied to the signal.

Resolved signal

- The syntax behind the *resolve signals*:

```
subtype_indication ←  
    [ resolution_function_name ]  
    type_mark [ range ( range_attribute_name  
        [ simple_expression ( to [ downto ] simple_expression )  
        [ ( discrete_range { , ... } ) ] ) ]
```

- Also *resolved subtypes* and types:

```
subtype resolved_logic is  
    resolve_tri_state_logic tri_state_logic;  
  
signal s2, s3 : resolved_logic;
```

Example: a four value logic

```
package MVL4 is
  type MVL4_ulogic is ('X', '0', '1', 'Z');  -- unresolved logic type
  type MVL4_ulogic_vector is array (natural range <>) of MVL4_ulogic;
  function resolve_MVL4 ( contribution : MVL4_ulogic_vector )
    return MVL4_ulogic;

  subtype MVL4_logic is resolve_MVL4 MVL4_ulogic;
end package MVL4;

-----

package body MVL4 is
  type table is array (MVL4_ulogic, MVL4_ulogic) of MVL4_ulogic;
  constant resolution_table : table :=
    -- 'X'  '0'  '1'  'Z'
    -----
    ( ( 'X',  'X',  'X',  'X' ),    -- 'X'
      ( 'X',  '0',  'X',  '0' ),    -- '0'
      ( 'X',  'X',  '1',  '1' ),    -- '1'
      ( 'X',  '0',  '1',  'Z' ) );  -- 'Z'

  function resolve_MVL4 ( contribution : MVL4_ulogic_vector )
    return MVL4_ulogic is
    variable result : MVL4_ulogic := 'Z';
  begin
    for index in contribution'range loop
      result := resolution_table(result, contribution(index));
    end loop;
    return result;
  end function resolve_MVL4;
end package body MVL4;
```

Example: a tri-state buffer

```
use work.MVL4.all;

entity tri_state_buffer is
    port ( a, enable : in MVL4_ulogic; y : out MVL4_ulogic );
end entity tri_state_buffer;

-----

architecture behavioral of tri_state_buffer is
begin
    y <= 'Z' when enable = '0' else
        a when enable = '1' and (a = '0' or a = '1') else
        'X';
end architecture behavioral;
```


Example: a tri-state buffer

```
use work.MVL4.all;
architecture gate_level of misc_logic is
    signal src1, src1_enable : MVL4_ulogic;
    signal src2, src2_enable : MVL4_ulogic;
    signal selected_val : MVL4_logic;
    ...
begin
    src1_buffer : entity work.tri_state_buffer(behavioral)
        port map ( a => src1, enable => src1_enable, y => selected_val );
    src2_buffer : entity work.tri_state_buffer(behavioral)
        port map ( a => src2, enable => src2_enable, y => selected_val );
    ...
end architecture gate_level;
```

Composite resolved subtype

```
package words is
  type X01Z is ('X', '0', '1', 'Z');
  type uword is array (0 to 31) of X01Z;
  type uword_vector is array (natural range <>) of uword;
  function resolve_word ( contribution : uword_vector ) return uword;
  subtype word is resolve_word uword;
end package words;
```

Composite resolved subtype

```
package body words is
  type table is array (X01Z, X01Z) of X01Z;
  constant resolution_table : table :=
    -- 'X'  '0'  '1'  'Z'
    -----
    ( ( 'X',  'X',  'X',  'X' ),    -- 'X'
      ( 'X',  '0',  'X',  '0' ),    -- '0'
      ( 'X',  'X',  '1',  '1' ),    -- '1'
      ( 'X',  '0',  '1',  'Z' ) );  -- 'Z'

  function resolve_word ( contribution : uword_vector ) return uword is
    variable result : uword := (others => 'Z');
  begin
    for index in contribution'range loop
      for element in uword'range loop
        result(element) :=
          resolution_table( result(element), contribution(index)(element) );
      end loop;
    end loop;
    return result;
  end function resolve_word;
end package body words;
```

Example: data port inout

```
use work.words.all;  
entity cpu is  
  port ( address : out uword; data : inout uword; ... );  
end entity cpu;
```

```
use work.words.all;  
entity memory is  
  port ( address : in uword; data : inout uword; ... );  
end entity memory;
```

```
architecture top_level of computer_system is  
  use work.words.all;  
  signal address : uword;  
  signal data : word;  
  ...  
begin  
  the_cpu : entity work.cpu(behavioral)  
    port map ( address, data, ... );  
  the_memory : entity work.memory(behavioral)  
    port map ( address, data, ... );  
  ...  
end architecture top_level;
```

Problem

- It is illegal to do this kind of partial assignment:

```
boot_rom : entity work.ROM(behavioral)
  port map ( a => address, d => data(24 to 31), ... );  -- illegal
```

- In the data signal we would have 2 sources for bits 0 to 23, 3 sources for bits 24 to 31.
- Solution: declare a composite type composed by elements of a resolved type:

```
type MVL4_logic_vector is array (natural range <>) of MVL4_logic;
```

Example

```
use work.MVL4.all;
entity ROM is
    port ( a : in MVL4_ulogic_vector(15 downto 0);
          d : inout MVL4_logic_vector(7 downto 0);
          rd : in MVL4_ulogic );
end entity ROM;
-----
use work.MVL4.all;
entity SIMM is
    port ( a : in MVL4_ulogic_vector(9 downto 0);
          d : inout MVL4_logic_vector(31 downto 0);
          ras, cas, we, cs : in MVL4_ulogic );
end entity SIMM;
-----
architecture detailed of memory_subsystem is
    signal internal_data : MVL4_logic_vector(31 downto 0);
    ...
begin
    boot_ROM : entity work.ROM(behavioral)
        port map ( a => internal_addr(15 downto 0),
                  d => internal_data(7 downto 0),
                  rd => ROM_select );

    main_mem : entity work.SIMM(behavioral)
        port map ( a => main_mem_addr, d => internal_data, ... );
    ...
end architecture detailed;
```

VHDL 2008: resolved composite subtypes

- In the previous examples, `MLV4_ulogic_vector` and `MLV4_logic_vector` are different types, and their values are incompatible.
- To solve this problem, since VHDL 2008 it is possible to define a subtype of a composite type, in which we introduce a resolution function for the elements:

```
subtype MVL4_logic_vector is (resolve_MVL4) std_ulogic_vector;
```

- The syntax rule that is applied is:

```
resolution_indication  $\leftarrow$   
  resolution_function_name  
  [ ( resolution_indication  
    [ ( record_element_identifier resolution_indication ) { , ... } ] )
```

VHDL 2008: resolved composite subtypes

```
type unresolved_RAM_content_type is  
    array (natural range <>) of MVL4_ulogic_vector;
```

```
subtype RAM_content_type is  
    ((resolve_MVL4)) unresolved_RAM_content_type;
```

```
type unresolved_status_type is record  
    valid : MVL4_ulogic;  
    dirty : MVL4_ulogic;  
    tag : MVL4_ulogic_vector;  
end record unresolved_status_type;
```

```
subtype status_resolved_valid is  
    (valid wired_and) unresolved_status_type;
```


Summarizing

- The *resolved signal* and the *resolved types* are the only way we can connect together multiple drivers for a signal.
- We need a *resolution function* for determining the final value of the signal.
- The *resolution function* must have a single parameter, which is an *unconstrained array* with value of the type of the signal, and must return a value of the type of the signal.
- The type of the array's index does not matter, provided that it is capable to enumerate the largest collection of sources for the *resolved signal*.
- The *resolution function* must be a **pure** function, i.e., must not have side effects.
- Since the order of the contributions passed to the function is unknown, it must be a *commutative* function.

Summarizing

- During simulation, the *resolution function* is called every time one of the *resolved signal* sources is active.
- During synthesis, the *resolution function* specifies how the synthesized hardware shall combine the values of the different sources of the *resolved signal*.

IEEE Std_Logic_1164 resolved subtypes

```
type std_ulogic is ('U', 'X', '0', '1', 'Z', 'W', 'L', 'H', '-');
```

```
type std_ulogic_vector is array ( natural range <> ) of std_ulogic;
```

- ulogic means unresolved logic
- The resolved types are:

```
function resolved ( s : std_ulogic_vector ) return std_ulogic;
```

```
subtype std_logic is resolved std_ulogic;
```

```
type std_logic_vector is array ( natural range <>) of std_logic;
```

- VHDL 2008:

```
                is  
subtype std_logic_vector (resolved) std_ulogic_vector;
```

The resolution function

```
type stdlogic_table is array (std_ulogic, std_ulogic) of std_ulogic;
constant resolution_table : stdlogic_table :=
    -----
    -- 'U', 'X', '0', '1', 'Z', 'W', 'L', 'H', '-'
    -----
    ( ( 'U', 'U', 'U', 'U', 'U', 'U', 'U', 'U', 'U', 'U' ), -- 'U'
      ( 'U', 'X', 'X', 'X', 'X', 'X', 'X', 'X', 'X', 'X' ), -- 'X'
      ( 'U', 'X', '0', 'X', '0', '0', '0', '0', 'X' ), -- '0'
      ( 'U', 'X', 'X', '1', '1', '1', '1', '1', 'X' ), -- '1'
      ( 'U', 'X', '0', '1', 'Z', 'W', 'L', 'H', 'X' ), -- 'Z'
      ( 'U', 'X', '0', '1', 'W', 'W', 'W', 'W', 'X' ), -- 'W'
      ( 'U', 'X', '0', '1', 'L', 'W', 'L', 'W', 'X' ), -- 'L'
      ( 'U', 'X', '0', '1', 'H', 'W', 'W', 'H', 'X' ), -- 'H'
      ( 'U', 'X', 'X', 'X', 'X', 'X', 'X', 'X', 'X' ) -- '-'
    );

function resolved ( s : std_ulogic_vector ) return std_ulogic is
    variable result : std_ulogic := 'Z'; -- weakest state default
begin
    if s'length = 1 then
        return s(s'low);
    else
        for i in s'range loop
            result := resolution_table(result, s(i));
        end loop;
    end if;
    return result;
end function resolved;
```

Resolved subtypes

```
subtype X01 is resolved std_ulogic range 'X' to '1';      -- ('X','0','1')
subtype X01Z is resolved std_ulogic range 'X' to 'Z';    -- ('X','0','1','Z')
subtype UX01 is resolved std_ulogic range 'U' to '1';    -- ('U','X','0','1')
subtype UX01Z is resolved std_ulogic range 'U' to 'Z';  -- ('U','X','0','1','Z')
```

Port *inout* with a resolved signal

- Let us consider a port with mode ***inout*** connected to a resolved signal.
- Which is the value at the port's input: the value driven by the port or the value of the resolved signal?
- The value of the resolved signal.
- A port with mode ***inout*** is modeled at the output as a driver that contributes to the signal value and at the input as a sensor that monitors the actual value of the signal.

Example: wired-and synchronization

```
library ieee; use ieee.std_logic_1164.all;
entity bus_module is
    port ( synch : inout std_ulogic; ... );
end entity bus_module;

-----

architecture top_level of bus_based_system is
    signal synch_control : std_logic;
    ...
begin
    synch_control_pull_up : synch_control <= 'H';
    bus_module_1 : entity work.bus_module(behavioral)
        port map ( synch => synch_control, ... );
    bus_module_2 : entity work.bus_module(behavioral)
        port map ( synch => synch_control, ... );
    ...
end architecture top_level;
```

Example: wired-and synchronization

```
architecture behavioral of bus_module is
begin
  behavior : process is
    ...
  begin
    synch <= '0' after Tdelay_synch;
    ...
    -- ready to start operation
    synch <= 'Z' after Tdelay_synch;
    wait until synch = 'H';
    -- proceed with operation
    ...
  end process behavior;
end architecture behavioral;
```


Resolved ports

- The ports of an entity can also be declared of a *resolved subtype*.
- Example: when an architecture comprises a certain number of processes that drive a port or a certain number of *component instances* whose outputs are connected to the same port.
- The final value of the *resolved port* will be determined by resolving all sources inside the architecture body.

Resolved port *inout*

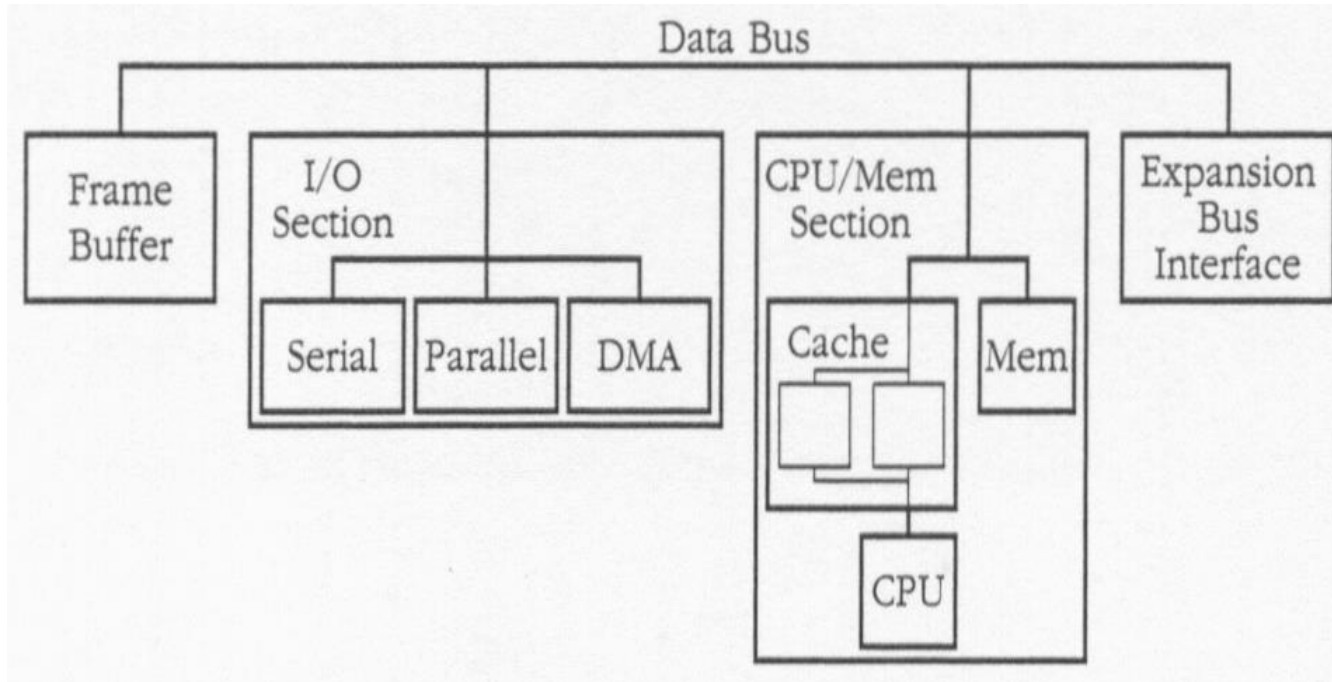
```
library ieee; use ieee.std_logic_1164.all;  
entity IO_section is  
    port ( data_ack : inout std_logic; ... );  
end entity IO_section;
```

- We could have different I/O controllers connected to the same port of *data_ack*.
- At the top level this port could be connected to a resolved signal.
- The value of the signal will be resolved after the value driven by the *resolved port* is resolved.
- The *resolution function* of the signal could be different from that of the port.

Resolved port hierarchy

- We could consider different levels of port hierarchy with a process nested at the lowest level that drives a value to be passed through some *resolved ports* up to a signal at the top level.
- The value of the signal at the highest level is called *effective value* of the signal.
- The *effective value* is returned down the port hierarchy for determining the actual value of each port with mode *in* or *inout*.

Example



'driving_value' attribute

- Allows a process to find the value it is presently contributing to a *resolved signal*.
- It cannot be used for determining the value contributed from other processes.

Resolved signal parameters

- In case of signal parameters in subprograms with mode **out** : no signal resolution is executed inside the subprogram.
- In case of signal parameters with mode **in** : the subprogram sees the effective value of the signal.
- In case of signal parameters with mode **inout** : the subprogram sees the effective value of the signal and no internal resolution is performed.

Example

```
procedure init_synchronize ( signal synch : out std_logic ) is  
begin  
    synch <= '0';  
end procedure init_synchronize;  
procedure begin_synchronize ( signal synch : inout std_logic;  
                             Tdelay : in delay_length := 0 fs ) is  
begin  
    synch <= 'Z' after Tdelay;  
    wait until synch = 'H';  
end procedure begin_synchronize;  
procedure end_synchronize ( signal synch : inout std_logic;  
                             Tdelay : in delay_length := 0 fs ) is  
begin  
    synch <= '0' after Tdelay;  
    wait until synch = '0';  
end procedure end_synchronize;
```

Example

```
synchronized_module : process is
    ...
begin
    init_synchronize(barrier);
    ...
    loop
        ...
        begin_synchronize(barrier);
        ...    -- perform operation, synchronized with other processes
        end_synchronize(barrier);
        ...
    end loop;
end process synchronized_module;
```


See:

- Peter Ashenden, «The designers' guide to VHDL» Morgan Kaufmann,
 - Chapter 8