

FOGLIO 2

ESERCIZIO 1

$A = \begin{pmatrix} 1 & 2 & -1 \\ 1 & 1 & 2 \\ -1 & -2 & 1 \end{pmatrix}$ . Trovare  $\text{Sat}$  invertibile t.c.  $\text{SAT} = \begin{pmatrix} E_1 & 0 \\ 0 & B \end{pmatrix}$ .

$A$  è la matrice associata a  $L_A: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  alle basi canoniche  $C$  e  $C$ .

Il  $\text{SAT}$  è la matrice di  $L_A$  rispetto alle basi  $\beta^C$  e  $\beta^C$  t.c.  $M_{\beta^C}^{\beta^C}(L_A) = \begin{pmatrix} E_1 & 0 \\ 0 & B \end{pmatrix}$ .

Inoltre,  $M_{\beta^C}^{\beta^C}(L_A) = M_C^{\beta^C} \cdot M_C^{\beta^C}(L_A) \cdot M_{\beta^C}^C$ .

STEP 1: Calcolo  $\text{rg}(A)$ .

$$\begin{pmatrix} 1 & 2 & -1 \\ 1 & 1 & 2 \\ -1 & -2 & 1 \end{pmatrix} \xrightarrow{\substack{R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 + R_1}} \begin{pmatrix} 1 & 2 & -1 \\ 0 & -1 & 3 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow \text{rg}(A) = 2.$$

(Divisione SAT in  $\begin{pmatrix} E_1 & 0 \\ 0 & B \end{pmatrix}$ )

STEP 2: Trovare una base di  $\ker A$ .

$$Ax = 0 \Leftrightarrow \begin{cases} x_1 + 2x_2 - x_3 = 0 \\ -x_2 + 3x_3 = 0 \\ x_3 = 0 \end{cases} \Leftrightarrow \begin{cases} x_1 = -3x_3 \\ x_2 = 3x_3 \\ x_3 = 0 \end{cases}$$

$\Rightarrow \ker A = \{(-3, 3, 0) \mid \alpha \in \mathbb{R}\} = \langle (-3, 3, 0) \rangle$

$= V$ , dimensione

STEP 3: Completare a una base di  $\mathbb{R}^3$ .

$\beta = \{e_1, e_2, e_3, v\}$  base di  $\mathbb{R}^3 \vee$ .

STEP 4: sono in base di  $\mathbb{R}^3$  data  $\alpha \beta$

$$L_A(e_1) = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, L_A(e_2) = \begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix}, L_A(e_3) = \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix}, L_A(v) = \begin{pmatrix} -3 \\ 3 \\ 0 \end{pmatrix}$$

$\Rightarrow \left\{ \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix}, \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} -3 \\ 3 \\ 0 \end{pmatrix} \right\}$  base di  $\mathbb{R}^3$

STEP 5: Completare a una base di  $\mathbb{R}^3$ .

da  $\ker A = \langle v \rangle \Rightarrow \beta^1 = \left\{ \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix}, \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix} \right\}$  base di  $\mathbb{R}^3$ .

STEP 6: Verifica  $M_{\beta^1}^{\beta^1}(L_A) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ .

$\beta = \{e_1, e_2, e_3, v\}$ .

$$L_A(e_1) = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} \xrightarrow{\text{matrice di cambio di base}} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad L_A(e_2) = \begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix} \xrightarrow{\text{matrice di cambio di base}} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$L_A(e_3) = \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix} \xrightarrow{\text{matrice di cambio di base}} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad L_A(v) = \begin{pmatrix} -3 \\ 3 \\ 0 \end{pmatrix} \xrightarrow{\text{matrice di cambio di base}} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

STEP 7: Trovare  $T = M_{\beta^1}^C$ ,  $S = M_C^{\beta^1}$ .

$$T = M_{\beta^1}^C = M_C^{\beta^1}(L_A) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{\text{cambio di base}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$S = M_C^{\beta^1} = (M_{\beta^1}^C)^{-1} = \begin{pmatrix} 1 & 2 & 1 \\ 1 & 1 & 2 \\ -1 & -2 & 1 \end{pmatrix}^{-1} = \frac{1}{\det(S)} \begin{pmatrix} -2 & 2 & -1 \\ 2 & -1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \checkmark$$

$$\textcircled{1} : \begin{pmatrix} 1 & 2 & 1 & | & 1 & 0 & 0 \\ 1 & 1 & 2 & | & 0 & 1 & 0 \\ -1 & -2 & 1 & | & 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & 1 & | & 1 & 0 & 0 \\ 0 & -1 & 1 & | & -1 & 1 & 0 \\ 0 & 0 & 2 & | & 1 & 0 & 1 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & 2 & 1 & | & 1 & 0 & 0 \\ 0 & -1 & 1 & | & -1 & 1 & 0 \\ 0 & 0 & 2 & | & 1 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 & | & -2 & -1 & -1 \\ 0 & -1 & 1 & | & -1 & 1 & 0 \\ 0 & 0 & 2 & | & 1 & 0 & 1 \end{pmatrix}$$

ESERCIZIO 2

$\textcircled{a}$   $A = \begin{pmatrix} 1 & 1 & 2 \\ 1 & 3 & -2 \\ 0 & 1 & 3 \\ 1 & 3 & 3 \end{pmatrix}$ .  $A$  invertibile? Trovare l'inversa di  $A$  in  $\mathbb{R}$  e  $\mathbb{Z}_7$ .

$$\det(A) = \begin{vmatrix} 1 & 1 & 2 \\ 1 & 3 & -2 \\ 0 & 1 & 3 \\ 1 & 3 & 3 \end{vmatrix} = \begin{vmatrix} 1 & 1 & 2 \\ 0 & 2 & -6 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{vmatrix} = \begin{vmatrix} 2 & -6 \\ 1 & 3 \end{vmatrix} = 2 \cdot 3 - (-6) = 12 \neq 0$$

$\Rightarrow A$  invertibile in  $\mathbb{R}$  e  $\mathbb{Z}_7$ .

INVERSA DI A?

Trovare l'inversa in  $\mathbb{R}$ , con i gruppi addizionali. Trovare l'inversa in  $\mathbb{Z}_7$  a partire da questa.

$$\begin{pmatrix} 1 & 1 & 2 & | & 1 & 0 & 0 \\ 1 & 3 & -2 & | & 0 & 1 & 0 \\ 0 & 1 & 3 & | & 0 & 0 & 1 \\ 1 & 3 & 3 & | & 0 & 0 & 0 \end{pmatrix} \xrightarrow{R_1 \rightarrow R_1 - R_2} \begin{pmatrix} 1 & 1 & 2 & | & 1 & 0 & 0 \\ 1 & 3 & -2 & | & 0 & 1 & 0 \\ 0 & 1 & 3 & | & 0 & 0 & 1 \\ 0 & 2 & 1 & | & -1 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{R_2 \rightarrow R_2 - R_1} \begin{pmatrix} 1 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & 2 & -4 & | & -1 & 1 & 0 \\ 0 & 1 & 3 & | & 0 & 0 & 1 \\ 0 & 2 & 1 & | & -1 & 0 & 0 \end{pmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{pmatrix} 1 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & 1 & 3 & | & 0 & 0 & 1 \\ 0 & 2 & -4 & | & -1 & 1 & 0 \\ 0 & 2 & 1 & | & -1 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{R_3 \rightarrow R_3 - R_2} \begin{pmatrix} 1 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & 1 & 3 & | & 0 & 0 & 1 \\ 0 & 0 & -7 & | & -1 & 1 & -1 \\ 0 & 2 & 1 & | & -1 & 0 & 0 \end{pmatrix} \xrightarrow{R_4 \rightarrow R_4 - R_2} \begin{pmatrix} 1 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & 1 & 3 & | & 0 & 0 & 1 \\ 0 & 0 & -7 & | & -1 & 1 & -1 \\ 0 & 1 & -2 & | & -1 & 0 & -1 \end{pmatrix}$$

$$\xrightarrow{R_1 \rightarrow R_1 - R_2} \begin{pmatrix} 1 & 0 & -1 & | & 1 & 0 & -1 \\ 0 & 1 & 3 & | & 0 & 0 & 1 \\ 0 & 0 & -7 & | & -1 & 1 & -1 \\ 0 & 1 & -2 & | & -1 & 0 & -1 \end{pmatrix} \xrightarrow{R_4 \leftrightarrow R_2} \begin{pmatrix} 1 & 0 & -1 & | & 1 & 0 & -1 \\ 0 & 1 & -2 & | & -1 & 0 & -1 \\ 0 & 0 & -7 & | & -1 & 1 & -1 \\ 0 & 1 & 3 & | & 0 & 0 & 1 \end{pmatrix}$$

$\textcircled{b}$ . DA QUESTO PASSAGGIO IN POI USANDO DIFFERENZIALE  $\mathbb{Z}_7$  DA  $\mathbb{R}$ .

Tutte i passaggi, in un certo senso, sono validi in  $\mathbb{Z}_7$ .

Risparmi però ricordare che dividere per 4 (o per qualsiasi altro numero) significa moltiplicare per  $4^{-1}$ .

Dunque  $A^{-1} = \begin{pmatrix} 2^{-1} \cdot 5 & 2^{-1} \cdot 7 & -2 & -5 \\ -2^{-1} \cdot 9 & -2^{-1} \cdot 21 & -8 & -15 \\ -2^{-1} \cdot 5 & 2^{-1} \cdot 13 & 5 & -9 \\ -2^{-1} \cdot 3 & -2^{-1} \cdot 3 & -1 & 2 \end{pmatrix} = \begin{pmatrix} 6 & 0 & 5 & 2 \\ 6 & 0 & 6 & 1 \\ 3 & 3 & 5 & 5 \\ 3 & 2 & 6 & 2 \end{pmatrix}$

$\textcircled{b}$   $A(x) = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & x \end{pmatrix}$ ,  $x \in \mathbb{R}$ .  $A(x)$  invertibile?  $(A(x))^{-1}$ .

$$\det(A(x)) = \begin{vmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & x \end{vmatrix} = \begin{vmatrix} 1 & 1 \\ 1 & x \end{vmatrix} = 2x - 1 - x = x - 1.$$

Quindi  $A(x)$  invertibile  $\Leftrightarrow x - 1 \neq 0 \Leftrightarrow x \neq 1$ .

IN TAL CASO:

Calcoliamo l'inversa di  $A$  tramite la matrice trasposta.

$$A_{11}^{-1} = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 1 & x \end{vmatrix} = \begin{vmatrix} 2 & 1 \\ 1 & x \end{vmatrix} = 2x - 1 \quad A_{22}^{-1} = \begin{vmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{vmatrix} = -x \quad A_{33}^{-1} = \begin{vmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 0 \end{vmatrix} = 1$$

$$A_{21}^{-1} = \begin{vmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{vmatrix} = -x \quad A_{12}^{-1} = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{vmatrix} = -1 \quad A_{32}^{-1} = \begin{vmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 0 & 1 \end{vmatrix} = 1$$

$$\Rightarrow \tilde{A} = \begin{pmatrix} 2x-1 & -x & 1 \\ -x & x & -1 \\ 1 & -1 & 1 \end{pmatrix} \Rightarrow A^{-1} = \frac{1}{x-1} \tilde{A} \checkmark \checkmark$$

Visto che  $A$  è simmetrica, anche  $\tilde{A}$  lo è!

Avremo potuto calcolare solo gli  $A_{ii}^{-1}$  con i  $2 \times 2$ .

$\textcircled{c}$   $V = \mathbb{R}[t]_{\leq 2}$ .  $A = \left\{ \begin{pmatrix} t^2 - 2t \\ p_2(t) \end{pmatrix}, \begin{pmatrix} 1 + 2t \\ p_2(t) \end{pmatrix}, \begin{pmatrix} 2 - t^2 \\ p_3(t) \end{pmatrix} \right\}$

$$B = \left\{ \begin{pmatrix} -2 + t \\ q_1(t) \end{pmatrix}, \begin{pmatrix} 1 + t + t^2 \\ q_2(t) \end{pmatrix}, \begin{pmatrix} 2t + 2t^2 \\ q_3(t) \end{pmatrix} \right\}$$

$A, B$  basi?  $M_A^B$ ?

$$A \text{ base} \Leftrightarrow \text{rg} \left( \begin{pmatrix} t^2 - 2t \\ p_2(t) \end{pmatrix}, \begin{pmatrix} 1 + 2t \\ p_2(t) \end{pmatrix}, \begin{pmatrix} 2 - t^2 \\ p_3(t) \end{pmatrix} \right) = 3 \Leftrightarrow \text{rg} \begin{pmatrix} 0 & 1 & 2 \\ -2 & 2 & 0 \\ 2 & 0 & -1 \end{pmatrix} = 3$$

$= M_A^A$

$$\begin{vmatrix} 0 & 1 & 2 \\ -2 & 2 & 0 \\ 2 & 0 & -1 \end{vmatrix} = \begin{vmatrix} 1 & 2 \\ 2 & 0 \end{vmatrix} = -2 \neq 0 \checkmark$$

Analizziamo,  $B$  base  $\Leftrightarrow \text{rg} \begin{pmatrix} -1 & 1 & 0 \\ 0 & 1 & 2 \\ 1 & 1 & 2 \end{pmatrix} = 3$ .

$$\begin{vmatrix} -1 & 1 & 0 \\ 0 & 1 & 2 \\ 1 & 1 & 2 \end{vmatrix} = - \begin{vmatrix} 1 & 2 \\ 1 & 2 \end{vmatrix} = -2 \neq 0 \checkmark$$

$$M_A^B = M_C^B M_A^C = \begin{pmatrix} 0 & 1 & 1 \\ -1 & 1 & 2 \\ 1 & 1 & 2 \end{pmatrix}^{-1} \cdot M_A^C$$

$$\begin{pmatrix} -1 & 1 & 1 \\ 0 & 2 & 0 \\ 1 & 1 & 1 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} 0 & 2 & 0 \\ -1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \xrightarrow{R_3 \rightarrow R_3 + R_2} \begin{pmatrix} 0 & 2 & 0 \\ -1 & 1 & 1 \\ 0 & 2 & 2 \end{pmatrix} \xrightarrow{R_3 \rightarrow R_3 - R_2} \begin{pmatrix} 0 & 2 & 0 \\ -1 & 1 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\xrightarrow{R_1 \leftrightarrow R_3} \begin{pmatrix} 0 & 1 & 1 \\ -1 & 1 & 1 \\ 0 & 2 & 0 \end{pmatrix} \xrightarrow{R_2 \rightarrow R_2 + R_1} \begin{pmatrix} 0 & 1 & 1 \\ 0 & 2 & 2 \\ 0 & 2 & 0 \end{pmatrix} \xrightarrow{R_2 \rightarrow R_2 - R_1} \begin{pmatrix} 0 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 2 & 0 \end{pmatrix} \xrightarrow{R_2 \rightarrow R_2 - R_1} \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 2 & 0 \end{pmatrix}$$

$(M_A^B)^{-1} = M_B^A$

$$\Rightarrow M_A^B = M_B^C M_C^A = \begin{pmatrix} 0 & 1 & 1 \\ -1 & 1 & 2 \\ 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 1 \\ -1 & 2 & 2 \\ 2 & 1 & 3 \end{pmatrix} \checkmark$$

$\textcircled{d}$   $B = \left\{ \begin{pmatrix} 1 & 0 & 2 \\ v_1 \end{pmatrix}, \begin{pmatrix} 0 & 1 & -1 \\ v_2 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 2 \\ v_3 \end{pmatrix} \right\} \subseteq \mathbb{Q}^3$

$$B^1 = \left\{ \begin{pmatrix} 3 & 1 & 0 \\ w_1 \end{pmatrix}, \begin{pmatrix} -1 & 1 & 2 \\ w_2 \end{pmatrix}, \begin{pmatrix} 0 & 2 & 0 \\ w_3 \end{pmatrix} \right\} \subseteq \mathbb{Q}^3$$

$\exists T: \mathbb{Q}^3 \rightarrow \mathbb{Q}^3$  t.c.  $T(v_i) = w_i, \forall i=1,2,3$ ?  $M_{\beta^1}^{\beta^0}(T)$ ?  $M_C^C(T)$ ?

$\exists T \Leftrightarrow B$  base di  $\mathbb{Q}^3 \Leftrightarrow \text{rg} M_{\beta^1}^{\beta^0} = 3$ .

$$M_{\beta^1}^{\beta^0} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 2 \end{pmatrix} \Rightarrow \text{rg} = 3 \checkmark$$

$\nabla$  ALLO STESSO MODO, NOTIAMO  $B$  BASE DI  $\mathbb{Q}^3$ .

$$M_{\beta^1}^{\beta^0}(T) = I \Rightarrow M_{\beta^1}^{\beta^0}(T) = M_{\beta^1}^{\beta^0} M_{\beta^0}^{\beta^1}(T) = M_{\beta^0}^{\beta^1} M_{\beta^1}^{\beta^0} = M_{\beta^0}^{\beta^1} \cdot I = M_{\beta^0}^{\beta^1}$$

$$\Rightarrow M_{\beta^0}^{\beta^1}(T) = M_{\beta^0}^{\beta^1} = M_{\beta^0}^{\beta^1} M_{\beta^1}^{\beta^0} = (M_{\beta^1}^{\beta^0})^{-1} \cdot M_{\beta^0}^{\beta^0}$$

$$M_{\beta^0}^{\beta^1}(T) = M_{\beta^0}^{\beta^1} M_{\beta^1}^{\beta^0}(T) = M_{\beta^0}^{\beta^1} M_{\beta^1}^{\beta^0} = M_{\beta^0}^{\beta^1} \cdot (M_{\beta^1}^{\beta^0})^{-1}$$

$$M_{\beta^0}^{\beta^1} = \begin{pmatrix} 3 & -1 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 0 \end{pmatrix} \quad \left( M_{\beta^1}^{\beta^0} \right)^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & -1 & 2 \end{pmatrix}^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

$$\textcircled{e} : \begin{pmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & -1 & 2 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_2 \leftrightarrow R_1} \begin{pmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & -1 & 2 & 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow M_{\beta^1}^{\beta^0}(T) = \begin{pmatrix} 3 & -1 & 0 \\ 0 & 1 & 0 \\ 1 & 3 & 1 \end{pmatrix} \checkmark \checkmark$$