

3/13 Trovare $S \in SO(2)$ t.c. ${}^t S A S = D$ diagonale con $A = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$

$$\boxed{{}^t S = S^{-1}}$$

$\underline{{}^t \bar{S} A S}$ (Componente compl.)

$\underline{{}^t S A S}$ (Componente)
su \mathbb{Q}

Autovaleori di A $P_A = \det(A - x I_2) = \begin{vmatrix} 1-x & 2 \\ 2 & 1-x \end{vmatrix} =$

$$= (1-x)^2 - 4 = (1-x+2)(1-x-2) = (3-x)(-1-x) = \underline{(x+1)(x-3)}$$

$x_1 = -1, x_2 = 3$

$$\boxed{P_A(x) = 0}$$

$m_a(-1) = 1, m_a(3) = 1 \Rightarrow \underline{m_f(-1) = m_f(3) = 1}$

$$\boxed{x_1 = -1}$$

$$\begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$x + y = 0$$

$$\underline{v_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}}$$

$$\|v_1\| = 1$$

$$\boxed{x_2 = 3} \quad \begin{pmatrix} -2 & 2 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad -x + y = 0 \quad v_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \|v_2\| = 1$$

(v_1, v_2) base ortogonale de \mathbb{R}^2

$$\frac{1}{2} \begin{vmatrix} 1 & 1 \\ -1 & 1 \end{vmatrix} = 1 \quad S = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$$

$$S^{-1} = {}^t S = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$

$$\boxed{{}^t S A S = D} = \begin{pmatrix} -1 & 0 \\ 0 & 3 \end{pmatrix}$$

4/13 Trovare $T \in SO(3)$ t.c. ${}^t T B T = D$ diag. $\hookrightarrow B = \begin{pmatrix} -1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \end{pmatrix}$

$\boxed{{}^t T = T^{-1}}$

Autovaleori

$$\begin{aligned}
 P_B &= \det \begin{pmatrix} -1-x & 1 & 1 \\ 1 & -1-x & 1 \\ 1 & 1 & -1-x \end{pmatrix} = -(1+x) \begin{vmatrix} -1-x & 1 \\ 1 & -1-x \end{vmatrix} - 2 \begin{vmatrix} 1 & 1 \\ 1 & -1-x \end{vmatrix} + \\
 &+ \begin{vmatrix} 1 & -1-x \\ 1 & 1 \end{vmatrix} = \\
 &= -(1+x) \left((1+x)^2 - 1 \right) - 2(-1-x-1) = \\
 &= -(1+x) \left((2+x)x \right) + 2(2+x) = (2+x) \left(-x - x^2 + 2 \right) = \\
 &= -(x+2) \left(x^2 + x - 2 \right) = -(x+2) \left(x-1 \right) \left(x+2 \right) = \underline{\underline{-(x+2)^2(x-1)}}
 \end{aligned}$$

$$P_B = -(x+2)^2(x-1)$$

$$\lambda_1 = -2, \lambda_2 = 1$$

$$m_a(-2) = 2, m_a(1) = 1$$

$$m_g(-2) = 2$$

$$m_g(1) = 1$$

$$1 \leq m_g(\lambda) \leq m_a(\lambda)$$

$$\boxed{\lambda_1 = -2}$$

$$(B + 2I_3)X = 0$$

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$x + y + z = 0$$

$$\begin{cases} x = -u - t \\ y = u \\ z = t \end{cases}$$

$$u, t \in \mathbb{R}$$

$$v_1 = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, v_2 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

$(u, t) = (1, 0)$ $(u, t) = (0, 1)$

$$\underline{V_{-2}} = \text{Span}(v_1, v_2)$$

Gram - Schmidt v_1, v_2

$$\|t_1\|^2 = 2$$

$$\langle v_1, v_2 \rangle = 1$$

$$t_1 = v_1 = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$

$$t_2 = v_2 - \frac{\langle v_2, t_1 \rangle}{\langle t_1, t_1 \rangle} t_1 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{pmatrix}$$

$$V_{-2} = \text{Span}(t_1, t_2)$$

$$\|t_2\|^2 = \frac{1}{2} + 1 = \frac{3}{2}$$

$$\begin{cases} u_1 = \frac{t_1}{\|t_1\|} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \\ u_2 = \frac{t_2}{\|t_2\|} = \sqrt{\frac{2}{3}} \begin{pmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{pmatrix} = -\frac{1}{2} \sqrt{\frac{2}{3}} \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} \end{cases}$$

$$V_{-2} = \text{Span}(u_1, u_2)$$

base ortonormale de V_{-2} .

$$\boxed{\lambda_2 = 1}$$

$$(B - I_3) X = 0$$

$$\begin{pmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -2 & 1 \\ -2 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -2 & 1 \\ 0 & -3 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -2 & 1 \\ 0 & -1 & 1 \end{pmatrix}$$

$$\begin{cases} -y + z = 0 \\ x - 2y + z = 0 \end{cases}$$

$$\begin{cases} z = u \\ y = u \\ x = u \end{cases}$$

$$v_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$u_3 = \frac{v_3}{\|v_3\|} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$S = (u_1 \quad u_2 \quad u_3)$$

$$\det = \frac{1}{\sqrt{2}} \left(-\frac{1}{2} \sqrt{\frac{2}{3}} \right) \frac{1}{\sqrt{3}}$$

$$\begin{vmatrix} -1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & -2 & 1 \end{vmatrix}$$

$$a < 0$$

$$= a (-1 \cdot 3 - 1 \cdot 3) \geq 0$$

$$\boxed{T = S}$$

8/13

$$S_\theta = \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix}, \quad \theta \in \mathbb{R}$$

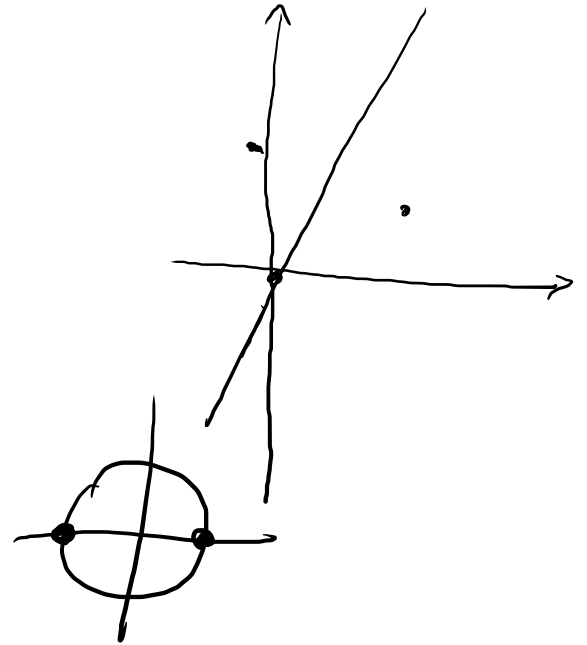
$$S_\theta \in O(2) - SO(2) \quad \det S_\theta = -1$$

$${}^t S_\theta = S_\theta$$

$$\text{Se } \sin \theta = 0 \Leftrightarrow \theta = k\pi, \quad k \in \mathbb{Z}$$

$$\Rightarrow S_{k\pi} = \begin{pmatrix} \pm 1 & 0 \\ 0 & \mp 1 \end{pmatrix}$$

Assumiamo $\theta \neq k\pi, \forall k \in \mathbb{Z}$.



1) Autovektoren

$$P_{S_\theta} = \det \begin{pmatrix} \cos \theta - x & \sin \theta \\ \sin \theta & -\cos \theta - x \end{pmatrix} = (x - \cos \theta)(x + \cos \theta) - \sin^2 \theta =$$
$$= x^2 - \cos^2 \theta - \sin^2 \theta = x^2 - 1$$

$$\lambda_1 = 1, \quad \lambda_2 = -1$$

$$m_a(1) = m_a(-1) = 1 = m_g(1) = m_g(-1).$$

$$\boxed{(\sin \theta \neq 0)}$$

$$(\lambda_1 = 1) \quad (S_\theta - I_2) \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} \cos \theta - 1 & \sin \theta \\ \sin \theta & -\cos \theta - 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$(\cos \theta - 1)x + \sin \theta y = 0$$

$$\begin{cases} x = u \\ y = \frac{1 - \cos \theta}{\sin \theta} u \end{cases}$$

$$u = \sin \theta$$

$$v_1 = \begin{pmatrix} \sin \theta \\ 1 - \cos \theta \end{pmatrix}$$

$$\|v_1\|^2 = \sin^2 \theta + (1 - \cos \theta)^2 = \sin^2 \theta + 1 - 2 \cos \theta + \cos^2 \theta = 2(1 - \cos \theta)$$

$$u_1 = \frac{v_1}{\|v_1\|} = \frac{1}{\sqrt{2(1 - \cos \theta)}} \begin{pmatrix} \sin \theta \\ 1 - \cos \theta \end{pmatrix}$$

$$\begin{matrix} > 0 \\ (\sin \theta \neq 0) \end{matrix}$$

$$(d_2 = -1) \quad (S_\theta + T_2) X = 0 \quad \begin{pmatrix} \cos \theta + 1 & \sin \theta \\ \sin \theta & -\cos \theta + 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 0$$

$$\sin \theta \neq 0 \quad \rightsquigarrow \quad (\cos \theta + 1)x + \sin \theta y = 0$$

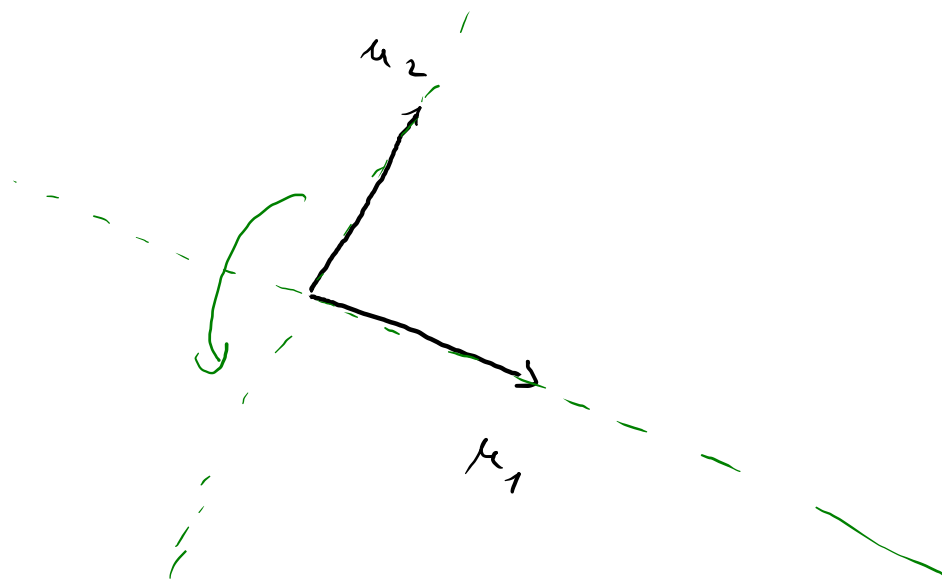
$$\begin{cases} x = u \\ y = -\frac{\cos \theta + 1}{\sin \theta} u \end{cases} \quad u \in \mathbb{R} \quad u = \sin \theta \rightsquigarrow v_2 = \begin{pmatrix} \sin \theta \\ -(1 + \cos \theta) \end{pmatrix}$$

$$\begin{aligned} \|v_2\|^2 &= \sin^2 \theta + (1 + \cos \theta)^2 = \sin^2 \theta + 1 + 2\cos \theta + \cos^2 \theta = \\ &= 2(1 + \cos \theta) > 0 \quad (\sin \theta \neq 0) \end{aligned}$$

$$u_2 = \frac{v_2}{\|v_2\|} = \frac{1}{\sqrt{2(1 + \cos \theta)}} \begin{pmatrix} \sin \theta \\ -(1 + \cos \theta) \end{pmatrix} \quad (u_1, u_2) \text{ base ortonormal} \\ \text{di } \mathbb{R}^2 \text{ ortonormalitate.}$$

$$S_{\partial} u_1 = u_1$$

$$S_{\partial} u_2 = -u_2$$



S_{∂} riflessione lineare

di \mathbb{R}^2

rispetto a $r = \text{span}(u_1)$

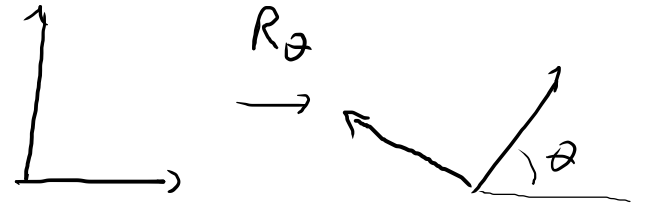
7/13

$$R_\theta = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

matrice di rotazione di angolo $\theta \in \mathbb{R}$

$$R_\theta \in SO(2) \Rightarrow R_\theta \in SU(2)$$

(teorema spettrale unitario)



$$\text{Se } \sin \theta = 0 \quad R_{k\pi} = \begin{pmatrix} \pm 1 & 0 \\ 0 & \pm 1 \end{pmatrix}$$

$\theta = k\pi, k \in \mathbb{Z}$

Possiamo assumere $\sin \theta \neq 0$

Autovale

$$P_{R_\theta} = \det \left(R_\theta - \lambda I_2 \right) = \begin{vmatrix} \cos \theta - \lambda & -\sin \theta \\ \sin \theta & \cos \theta - \lambda \end{vmatrix} =$$
$$= (\cos \theta - \lambda)^2 + \sin^2 \theta = \lambda^2 - 2\lambda \cos \theta + 1$$

$$x^2 - 2\cos\theta x + 1 = 0$$

$$x = \cos\theta \pm \sqrt{\cos^2\theta - 1} = \cos\theta \pm \sqrt{-(1 - \cos^2\theta)} = \cos\theta \pm \underline{\underline{i \sin\theta}}$$

$$= e^{\pm i\theta} \in \mathbb{C} - \mathbb{R} \text{ w. } \sin\theta \neq 0$$

$$m_a(\lambda_1) = m_a(\lambda_2) = 1$$

$$\Rightarrow m_g(\lambda_1) = m_g(\lambda_2) = 1$$

(sin θ ≠ 0)

Autovektoren: (sin θ ≠ 0)

$$\lambda_1 = \cos\theta + i \sin\theta$$

$$(R_\theta - \lambda_1 I_2) X = 0 \quad \begin{pmatrix} -i \sin\theta & -\sin\theta \\ \sin\theta & -i \sin\theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 0$$

$$\sin\theta x - i \sin\theta y = 0 \Rightarrow x - i y = 0$$

$$v_1 = \begin{pmatrix} i \\ 1 \end{pmatrix} \rightarrow u_1 = \frac{v_1}{\|v_1\|} = \frac{1}{\sqrt{2}} \begin{pmatrix} i \\ 1 \end{pmatrix}$$

$$\lambda_2 = \cos \theta - i \sin \theta$$

$$(R_\theta - \lambda_2 I_2) X = 0$$

$$\begin{pmatrix} i \sin \theta & -\sin \theta \\ \sin \theta & i \sin \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 0$$

$$x + iy = 0 \quad v_2 = \begin{pmatrix} 1 \\ +i \end{pmatrix} \quad \|v_2\| = \sqrt{2} \quad u_2 = \frac{v_2}{\|v_2\|} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}$$

(u_1, u_2) base ortogonale di \mathbb{C}^2 che diagonalizza R_θ