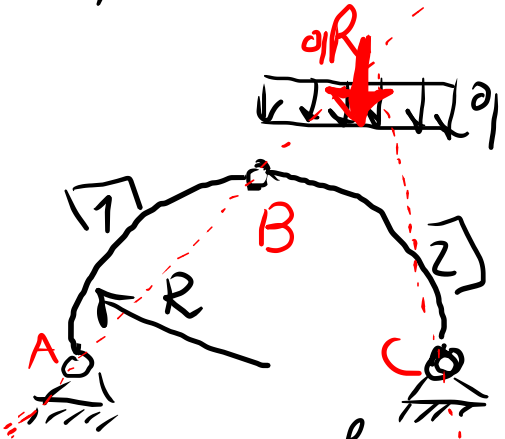
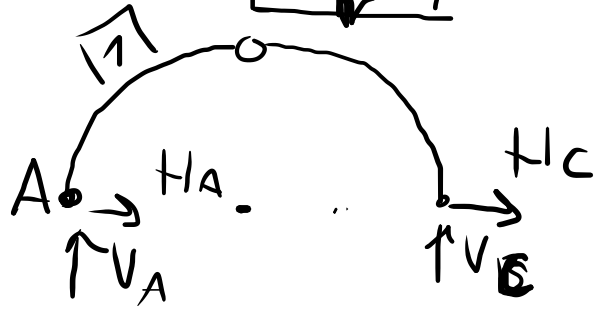


# ES, STUDIO C.D.S. IN UNA STR. AD ARCO



RICERCA REAZ. VINCORI

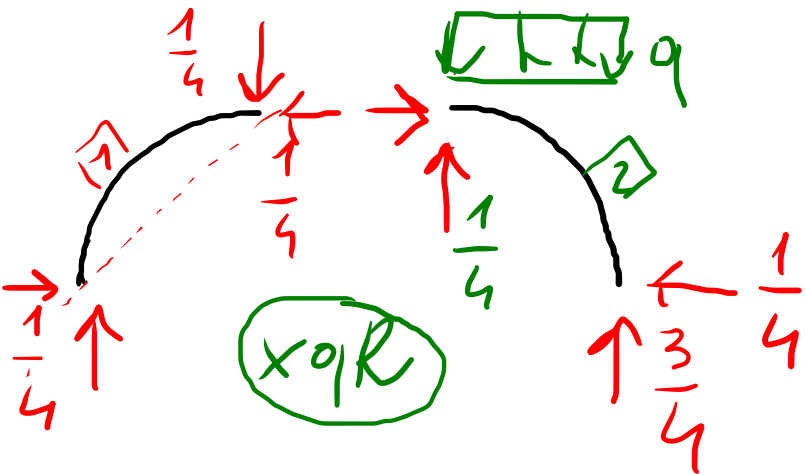
$$\left. \begin{aligned} \rightarrow : H_A + H_C &= 0 \\ +\uparrow : V_A - qR + V_C &= 0 \\ \curvearrowright : -qR \cdot \frac{3R}{2} + V_C \cdot 2R &= 0 \end{aligned} \right\} \begin{array}{l} \text{EQ. EQUIL.} \\ \text{GLOBALE [1] + [2]} \end{array}$$

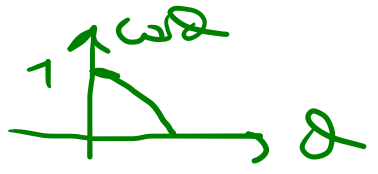
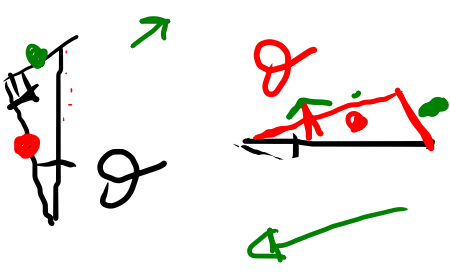
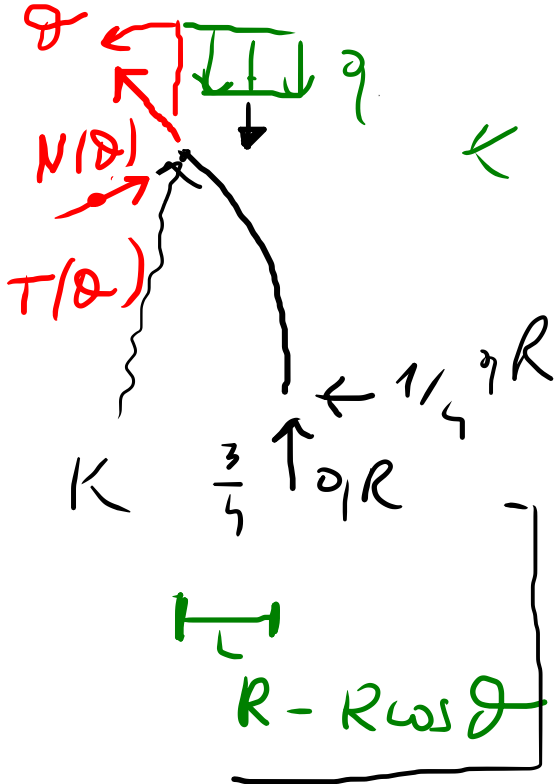
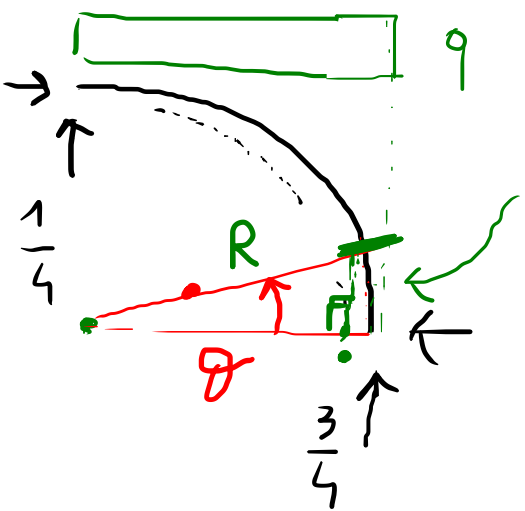


$$[1] \curvearrowright : H_A R - V_A R = 0 \quad \text{EQ. AUS.}$$

$$V_C = \frac{3}{4} qR ; \quad V_A = +\frac{1}{4} qR ; \quad H_A = +\frac{1}{4} qR$$

$$H_C = -H_A = -\frac{1}{4} qR$$





$N(\theta), T(\theta), M(\theta)$   
 $\theta \in [0, \pi/2]$

CALCOLO DI  $N(\theta)$

$$+ \uparrow : +N(\theta) - qR(1 - \cos\theta) + \frac{3}{4}qR + \frac{1}{4}qR \sin\theta = 0$$



$$M(\theta) = qR(1 - \cos\theta) - \frac{3}{4}qR \cos\theta - \frac{1}{4}qR \sin\theta$$

$$M(0) = -\frac{3}{4}qR \sim M(0) = qR(1-1) - \frac{3}{4}qR \cdot 1 - 0 = -\frac{3}{4}qR \quad \text{OK}$$

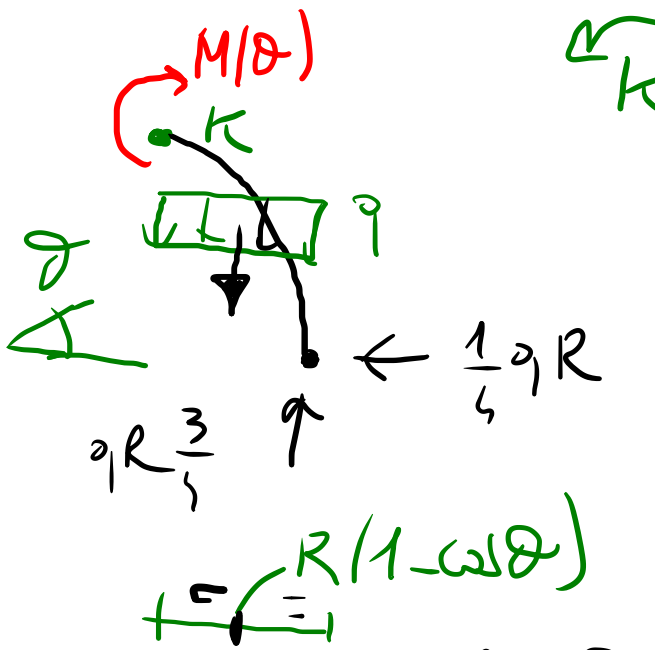
$$M(\frac{\pi}{2}) = -\frac{1}{4}qR \sim M(\frac{\pi}{2}) = \dots \text{ESERCIZIO}$$

$$+ \rightarrow : +T(\theta) - qR(1 - \cos\theta) \sin\theta + \frac{3}{4}qR \sin\theta - \frac{1}{4}qR \cos\theta = 0$$

$$T(\theta) = qR(1 - \cos\theta) \sin\theta - \frac{3}{4}qR \sin\theta + \frac{1}{4}qR \cos\theta$$

$$T(\frac{\pi}{2}) \stackrel{ES.}{=} +\frac{1}{4}qR$$

$$T(0) = \frac{1}{4}qR \sim T(0) = qR(0) - \frac{3}{4}qR \cdot 0 + \frac{1}{4}qR \cdot 1 = \frac{1}{4}qR \quad \text{OK}$$



$$\sum \overset{\curvearrowright}{K}^+ : -M(\theta) - \underbrace{q(R(1-\cos\theta))}_{\text{FORZA}} \cdot \frac{R(1-\cos\theta)}{2}$$

$$+ \frac{3}{4} qR \cdot R(1-\cos\theta) - qR \cdot \frac{1}{4} \cdot R \sin\theta = 0$$

$$M(\theta) = -\frac{qR^2}{2} (1-\cos\theta)^2 + \frac{3}{4} qR^2 (1-\cos\theta)$$

$$- \frac{1}{4} qR^2 \sin\theta$$

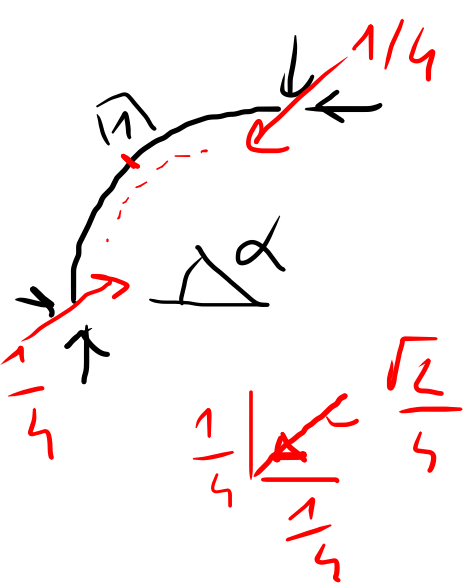
$$Q = qR^2$$



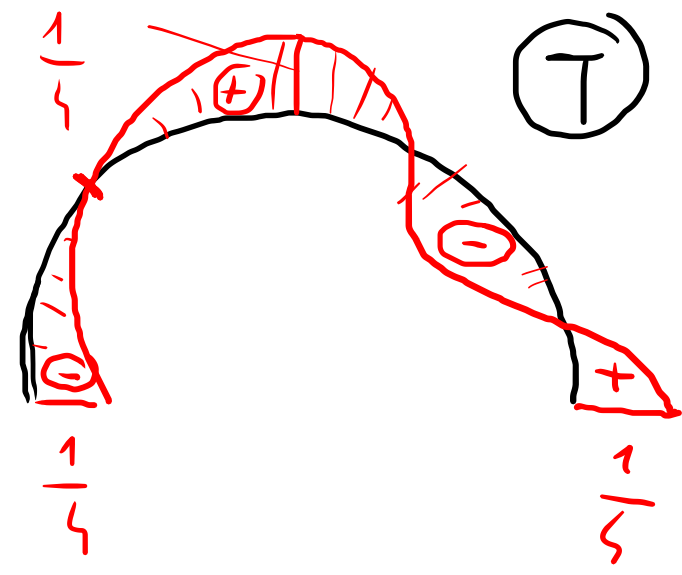
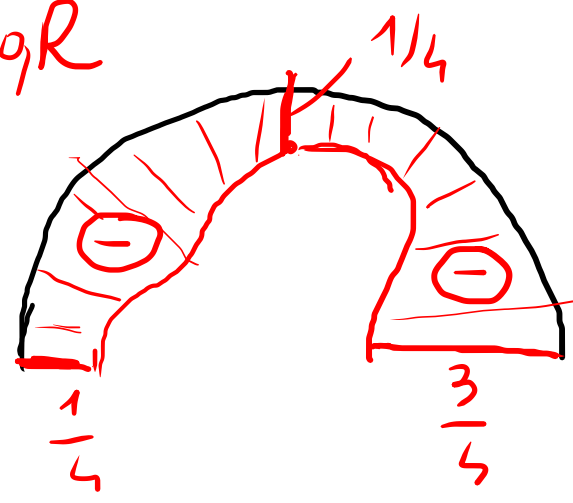
$$M(0) \stackrel{!}{=} 0 \rightarrow M(0) = 0$$

$$M\left(\frac{\pi}{2}\right) \stackrel{!}{=} 0 \rightarrow M\left(\frac{\pi}{2}\right) = -\frac{q}{2} (1)^2 + \frac{3}{4} q \cdot 1 - \frac{1}{4} q \cdot 1 =$$

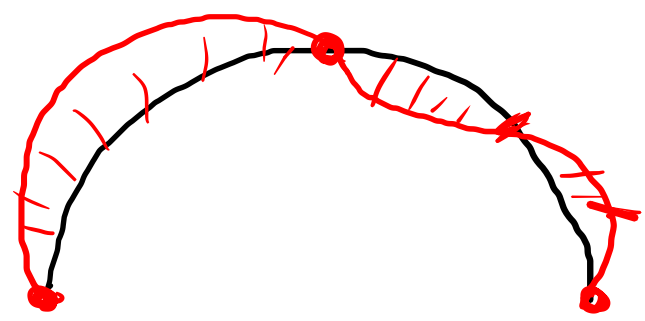
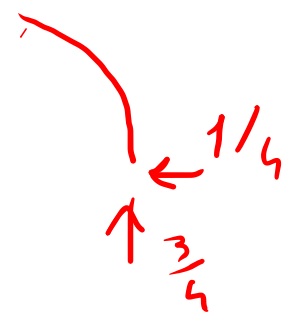
$$= \left(-\frac{1}{2} + \frac{3}{4} - \frac{1}{4}\right) q = 0 \quad \text{OK!}$$



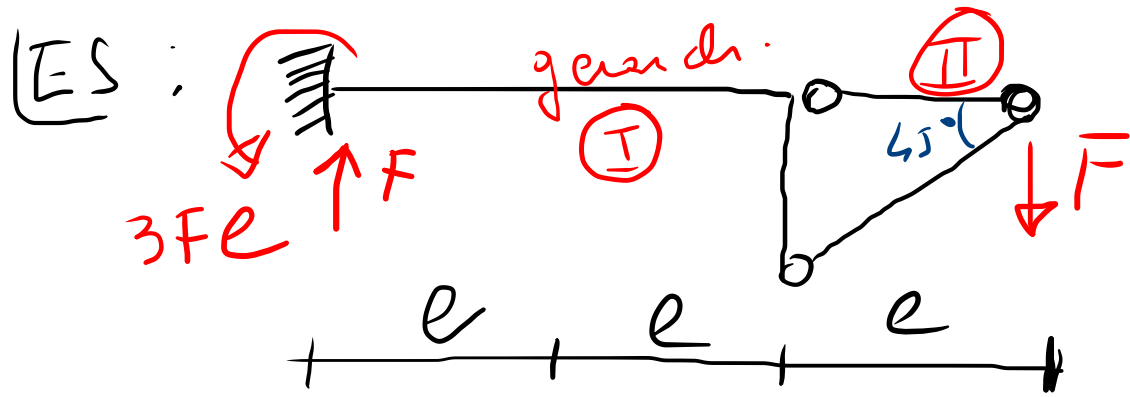
(H)  $\times qR$



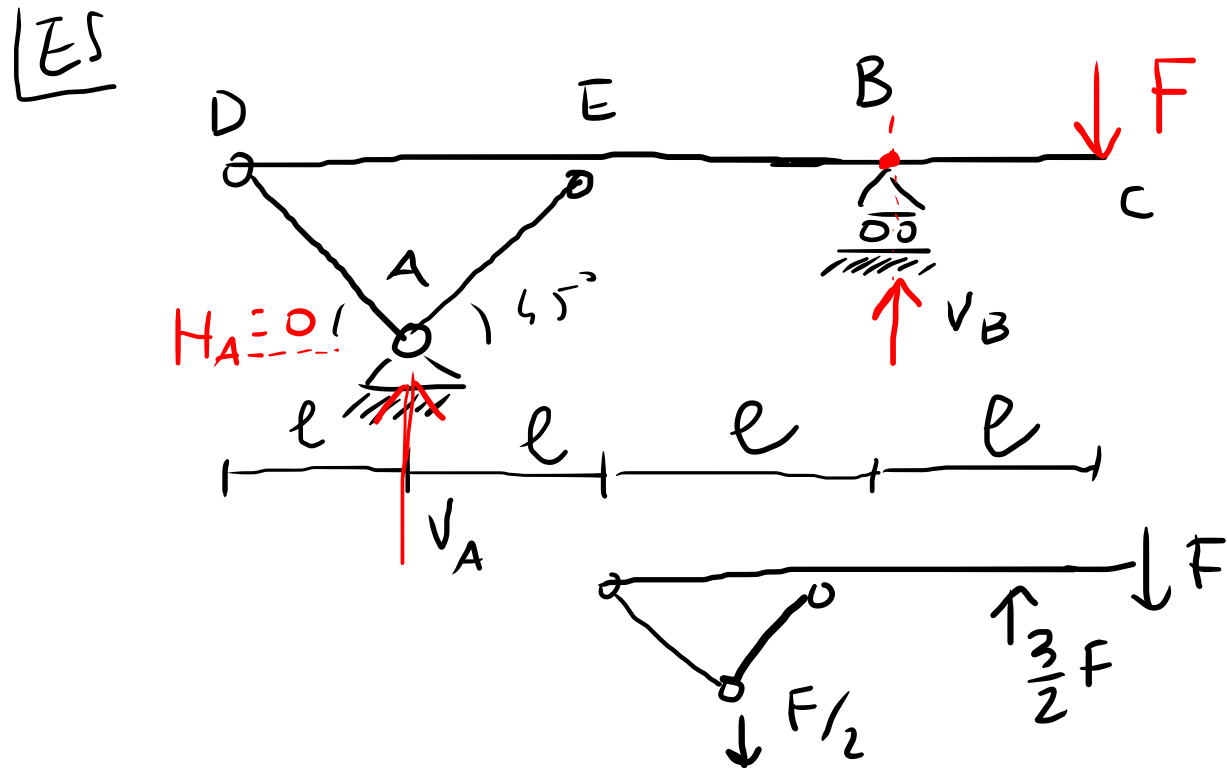
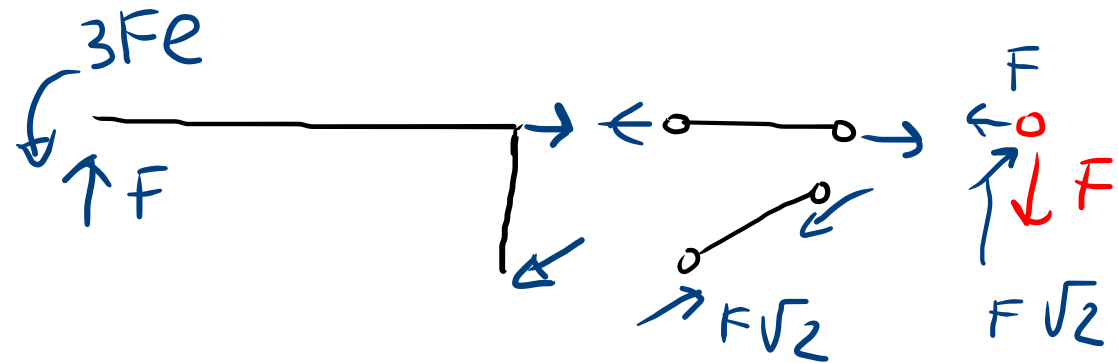
(T)  $\times qR$



(M)  $\times qR$



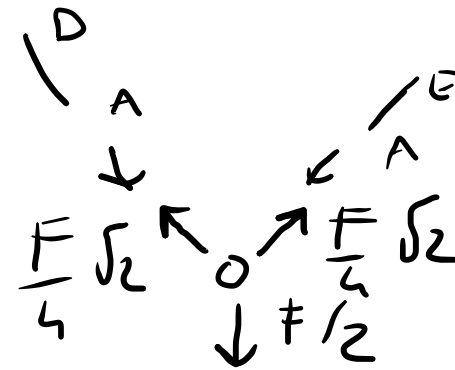
3  $g$  nel piano



$V_A?$  :  $\curvearrowright B$  :  $-V_A 2e + Fe = 0$   $V_A = \frac{F}{2}$

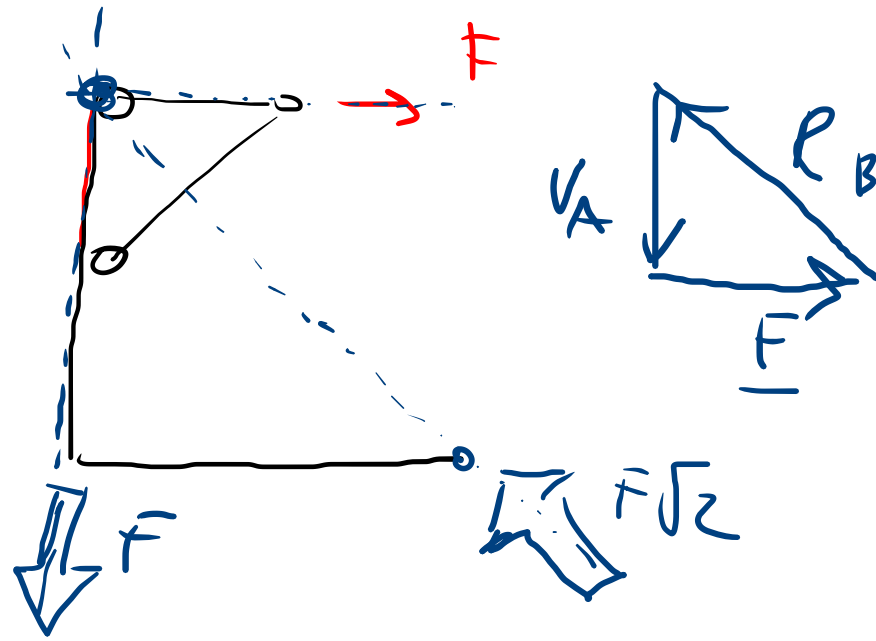
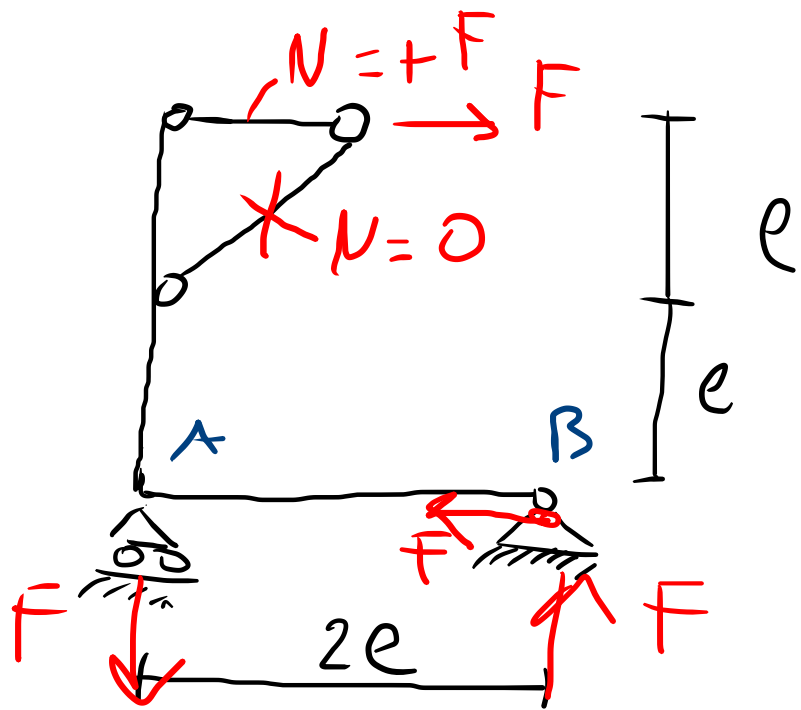
$V_B?$  :  $\curvearrowleft A$  :  $V_B 2e - F 3e = 0$

$V_B = \frac{3}{2} F$

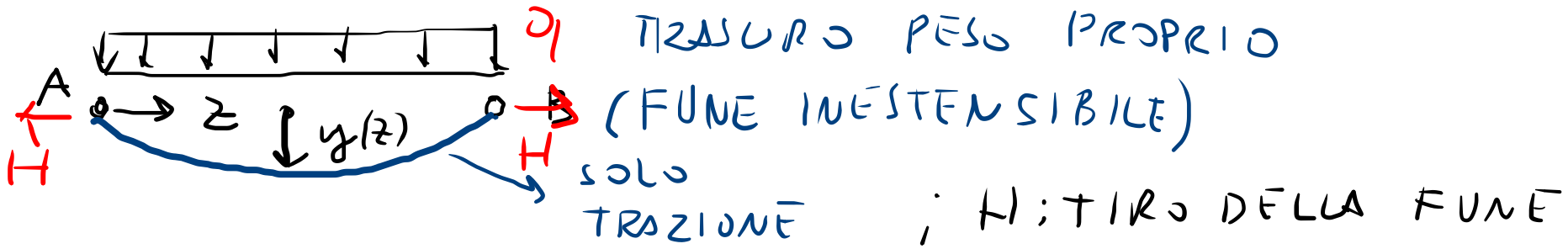


$N_{AD} = + \frac{F}{4} \sqrt{2}$

$N_{AE} = + \frac{F}{4} \sqrt{2}$

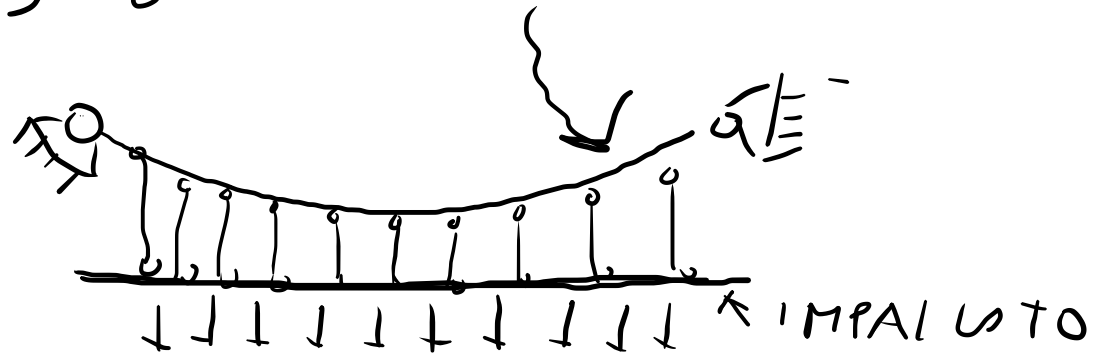


# STRUTTURE FUNICOLARI DEL CARICO

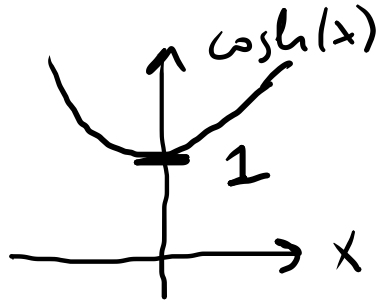


$$y''(z) = \frac{q}{H} \left. \vphantom{y''(z)} \right\} \text{const.} \longrightarrow y(z) : \text{PARABOLA}$$

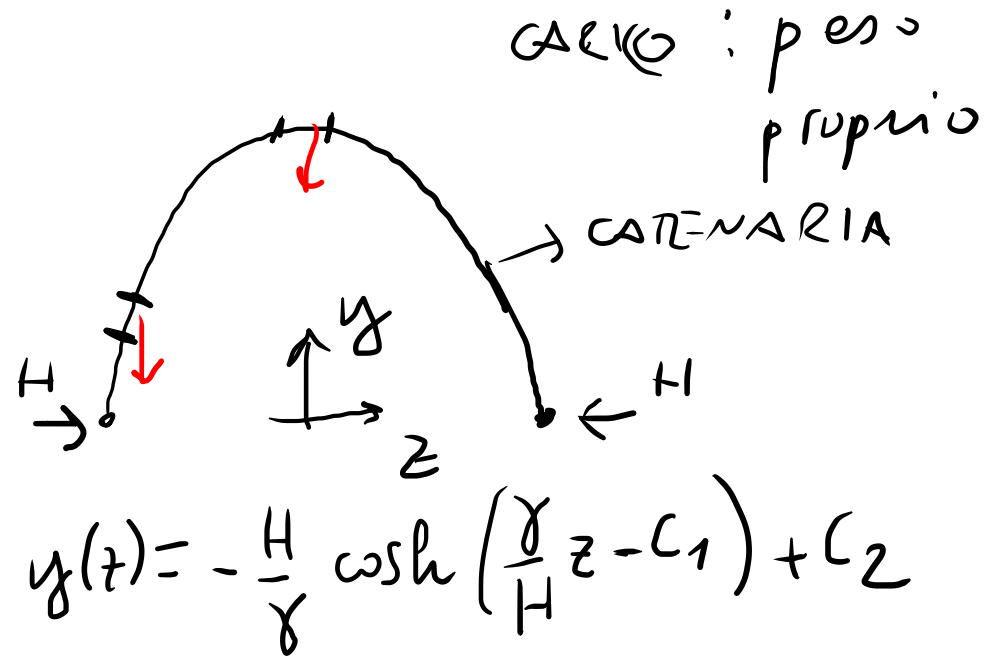
→ PONTI SOSPESI



SF NORM.  
⊖ { T, M = 0



$\gamma$ : peso per unità di lunghezza



$$y(z) = -\frac{H}{\gamma} \cosh\left(\frac{\gamma}{H}z - C_1\right) + C_2$$

