

Hilbert's 10th problem and how to 'flatten' its instances

D. Cantone, E. G. Omodeo Unsolvable cases of the Entscheidungsproblem for ZF 3/39

HILBERT'S 10th PROBLEM (1900)



Scheme of a *hypothetical* solver for the $10^{\underline{th}}$ problem. The answer:

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Scheme of a hypothetical solver for the $10^{\underline{th}}$ problem. The answer:

"yes" should indicate that the equation has at least one solution

$$\begin{cases} x_1 = \mathbf{v}_1 \\ \vdots \vdots \vdots \\ x_m = \mathbf{v}_m \end{cases}$$

where each \mathbf{v}_i is an integer (positive, negative, or null).

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Establishing whether or not, any given equation

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D(x_1,\ldots,x_m) = 0,
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(where D is a polynomial with coefficients in $\mathbb Z$),

admits a solution



are problems translatable into each other.

This presentation will refer H10 to \mathbb{N}

THEOREM DPRM (1970)

Hilbert's problem H10 is algorithmically unsolvable

Consider a polynomial Diophantine equation

 $D(x_1,\ldots,x_m) = 0$

to be solved in \mathbb{N} . By pulling out subterms of the polynomial D, we can *flatten* this equation into a system (=conjunction) of equations of the forms

x = y + z, $x = y \cdot z$, x = 1, x = y

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x = y+z, $x = y \cdot z$, x = 1, x = y,

where x, y, z stand for variables, to be regarded—the new ones as well as the original ones, x_1, \ldots, x_m —as unknowns in N. We will manage that x, y, z are *distinct* when they appear in the same equation $x = y \star z$. The *equisolvability* between the system Δ thus obtained and the equation given at the outset will be obvious.

The equation $\ensuremath{\$}$

$$4 x_1^3 x_2 - 2 x_1^2 x_3^3 - 3 x_2^2 x_1 + 5 x_3 = 0$$

in 3 unknowns can be flattened into the following system in 22 unknowns (19 are 'temporaries'):

$$o = 1, o_1 = o , u_2 = o + o_1,$$

$$p_1 = u_2 \cdot x_1, p_2 = p_1 \cdot x_1, p_3 = p_2 \cdot x_1,$$

$$q_1 = u_2 \cdot x_2, q_2 = q_1 + x_2, q_3 = q_2 \cdot x_2,$$

$$s_1 = x_3 , s_2 = s_1 \cdot x_3, s_3 = s_2 \cdot x_3,$$

$$r_1 = s_1 + x_3, r_2 = r_1 + x_3, r_3 = r_1 + r_2,$$

$$t_1 = p_3 \cdot q_1, t_2 = p_2 \cdot s_3, t_3 = q_3 \cdot x_1,$$

$$w = t_1 + r_3, w = t_2 + t_3.$$

[§]Cf. [Mat93, p. 4]

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The equation $\ensuremath{\$}$

$$4 x_1^3 x_2 - 2 x_1^2 x_3^3 - 3 x_2^2 x_1 + 5 x_3 = 0$$

in 3 unknowns can be flattened into the following system in 25 unknowns (22 are 'temporaries'):

ζ	=	$\zeta_1+\zeta_2\ ,$	ζ_1	=	$\zeta_2+\zeta,$	ζ_2	=	$\zeta + \zeta_1$,
			o_1	=	$o+\zeta$,	<i>u</i> ₂	=	$o + o_1$,
0	\neq	ζ,	o_1'	=	$o+\zeta$,	0	=	$o_1\cdot o_1',$
p_1	—	$u_2 \cdot x_1$,	p 2	=	$p_1 \cdot x_1$,	p_3	=	$p_2 \cdot x_1$,
q_1	=	$u_2 \cdot x_2$,	q_2	=	$q_1 + x_2$,	q 3	=	$q_2 \cdot x_2$,
S_1	=	$x_3 + \zeta$,	<i>s</i> ₂	=	$s_1 \cdot x_3$,	<i>s</i> ₃	=	$s_2 \cdot x_3$,
r_1	=	$s_1 + x_3$,	r_2	=	$r_1 + x_3$,	<i>r</i> ₃	=	$r_1 + r_2$,
t_1	=	$p_3 \cdot q_1$,	t_2	=	$p_2 \cdot s_3$,	t ₃	=	$q_3 \cdot x_1$,
			W	=	$t_1 + r_3$,	W	=	$t_2 + t_3$.

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We have just seen how to eliminate equations of the form x = y (with x, y distinct var's) during flattening, thanks to a new var. ζ which (in concert with others) gets the value **0**. To enforce this, three constraints suffice:

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FIGURE: The three variables ζ , ζ_1 , ζ_2 are thus forced to take the value **0**

HOW TO EMPLOY SQUARING INSTEAD OF PRODUCT

We can also rewrite each equation of the form

 $x = y \cdot z$

as a system involving only squaring and addition. In fact we can replace it, in light of the identity



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HOW TO EMPLOY SQUARING INSTEAD OF PRODUCT

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where f, g, h, k, p, q and x' are new and, as before, $\zeta = 0$.

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