Exercises Lecture XIII

Chaos and determinism

1. **Logistic map**
   The program `map.f90` calculates the values x_n of the terms of a sequence obtained from the starting point x_0 by applying iteratively the logistic application:

   $$x_{n+1} = 4rx_n(1 - x_n)$$

   with a chosen parameter r up to a given index $n = n_{max}$.

   (a) Calculate the terms of the series up to $n = 15$ with the parameter $r_1 = 1/3$ and starting from $x_0 = 1/4$, and those for the parameter $r_2 = 0.5$ starting from $x_0 = 1/2$. Verify that the two values are *stable equilibrium points* for the corresponding parameters r.

   (b) For $r = 0.875$, calculate up to $n = 50$ the terms of the sequence starting from $x_0 = 0.3$, then from $x_0 = 0.6$ and from $x_0 = 0.9$. Determine the period of the trajectory and calculate the fixed points with 5 significant digits.

   (c) Calculate the Lyapunov exponent for some values of r.

2. **Regular and chaotic billiards**
   Consider a two-dimensional planar geometry in which a particle moves with constant velocity along straight line orbits until it elastically reflects off the boundary. This straight line motion occurs in various "billiard" systems. A simple example of such a system is a particle moving with fixed speed within a circle. Suppose that we divide the circle into two equal parts and connect them by straight lines of length L. This geometry is called a *stadium billiard*. It has a similar geometry to that known as the *Sinai billiard model*. The program `billiard.f90` produces the trajectory for a particle moving in a circular or stadium billiard accoridng to the choice of L. Use the radius of the circular parts as unit length.
   The algorithm for determining the path of the particle is as follows:

   (a) Begin with an initial position (x_0, y_0) and momentum (p_{x0}, p_{y0}) of the particle such that $|p_0|$ =1.

   (b) Determine which of the four sides the particle will hit. The possibilities are:
   (1) top line segment
   (2) bottom line segment
   (3) right semicircle
   (4) left semicircle.

   (c) Determine the next position of the particle from the intersection of the straight line defined by the current position and momentum, and the equation for the segment where the next reflection occurs.

(d) Determine the new momentum, (p'_x, p'_y), of the particle after reflection such that the angle of incidence equals the angle of reflection. For reflection off the line segments we have $(p'_x, p'_y) = (P_x, -p_y)$. For reflection off a circle we have:

$$p'_x = (y^2 - (x - x_c)^2)p_x - 2(x - x_c)yp_y$$

$$p'_y = -2(x - x_c)yp_x + ((x - x_c)^2) - y^2)p_y$$

where $(x_c, 0)$ is the center of the circle.

(e) Repeat steps (b)-(d).

3. Observe qualitatively that the dynamics is chaotic if $L \neq 0$.

4. The divergence of the trajectories even with slightly different initial conditions can be described by the Lyapunov exponent, defined by the relation:

$$|\Delta s| = |\Delta s_0| e^{\lambda n}$$

where n is the number of reflections and Δs is the difference of the two phase space trajectories defined by

$$\Delta s = \sqrt{|\mathbf{r}_1 - \mathbf{r}_2|^2 + |\mathbf{p}_1 - \mathbf{p}_2|^2}.$$

Estimate the largest Lyapunov exponent for L=1. One way to do it, is to consider two particles starting with almost identical positions and/or momenta (varying by say 10^{-5}) and make a *semilog* plot of Δs versus n. Why does the exponential growth in Δs stop for sufficiently large n? Repeat your calculation for different initial conditions and average your values of Δs before plotting. Repeat the calculation for $L = 0.1$, 0.5, and 2.0 and determine if your results depend on L.

5. Another test for the existence of chaos is the reversibility of the motion. Do this simulation for $L = 1$ and $L = 0$. Reverse the momentum after the particle has made n reflections, and let the drawing color equal the background color so that the path can be erased. What limitation does roundoff error place on your results? Hint: use single and double precision.

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!ccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
! LOGISTIC MAP
!  map.f90
!  x'= m*x*(1-x) with fixed points and bifurcations
!ccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
program map
  implicit none
  real :: r_min=0.25, r_max=1.0, r, step=0.0025, x
  integer :: n
  open(unit=7,file="map.dat",status="replace",action="write")
  ! calculate the sequences for different values of the parameter
  ! starts from r=r_min, then increase by step=0.0025.
  ! Starting point x=0.5
  r = r_min
  do
     r = r + step
     if (r > r_max) exit
     x = 0.5
     ! through away the first 200 points...
     Do  n=0, 200
        x = 4 * r * x * (1 - x)
     end do
     ! ...save other 200 points for each value of the parameter.
     Do  n=201, 401
        x = 4* r * x * (1 - x)
        Write (unit=7,fmt="(f6.6,f10.6)") r,x
     end do
  end do
  close(unit=7)
end program map
```

```
!ccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
! THE CHAOTIC MOTION OF DYNAMICAL SYSTEMS: stadium billiard
!  billiard.f90    (reference system: origin in the middle point)
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module bill
  implicit none
  public:: start,move,hit,output,reflect
  real,public::z,w,c,L,m,q,xr1,xr2,a,b,xrmax,xrmin
  !integer,public::i
  integer,public::n,ro
  real,dimension(:),public,allocatable::x,y,px,py
  real,dimension(4),public::xr

contains

  subroutine start()
    ! gives pos., mom., geometry, numbers of steps
    print*," number of steps >"
    read(unit=5,fmt=*)n
    allocate (x(n))
    allocate (y(n))
    allocate (px(n))
    allocate (py(n))
    print*,"length of the straight side (i nunits of r) >"
    read(unit=5,fmt=*)L
    print*,"initial position (x0,y0) >"
    read(unit=5,fmt=*)x(1),y(1)
    print*,"initial momentum (px0,py0) >"
    read(unit=5,fmt=*)px(1),py(1)
    if((px(1)**2+py(1)**2)/=1.0) then        ! renormalize to 1:
       px(1)=px(1)/sqrt(px(1)**2+py(1)**2)
       py(1)=py(1)/sqrt(px(1)**2+py(1)**2)
    end if
    return
  end subroutine start

  subroutine hit(i)
    !     given position and momentum of the particles, determine where
    !     it will reflect:
    !     1) top line (y=1,ro=1)
    !     2) bottom line (y=-1,ro=2)
    !     3) right semicircle with center in (L/2,0)(ro=3),
    !     4) left semicircle with center in (-L/2,0)(ro=4)

    integer,intent(in) :: i
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```
!       real,dimension(n+1)::x,y,px,py

if(px(i)/=0.0) then
   ! case px(i)/=0
   m=py(i)/px(i)
   q =y(i)-m*x(i)  ! line through (x,y) and with
   ! the direction of the momentum
   if(m>0.0) then
      ! subcase m>0
      if(py(i)>0.0) then
         if(((1.0-q)/m)>L/2) then
            ro=3
         else
            if(((1.0-q)/m)>(-L/2)) then
               ro=1
            else
               ro=4
            end if
         end if
      else
         if(((-1.0-q)/m)<(-L/2)) then
            ro=4
         else
            if(((-1.0-q)/m)<L/2) then
               ro=2
            else
               ro=3
            end if
         end if
      end if
   end if

   if(m<0.0)then
      ! subcase m<0
      if(py(i)>0.0) then
         if(((1-q)/m)<(-L/2)) then
            ro=4
         else
            if(((1.0-q)/m)<L/2) then
               ro=1
            else
               ro=3
            end if
         end if
      else
         if(((-1.0-q)/m)>L/2) then
```

```
            ro=3
         else
            if(((-1.0-q)/m)>(-L/2)) then
               ro=2
            else
               ro=4
            end if
         end if
      end if

      ! subcase m=0 (within the case px(i)=/0)
      if(m==0.0) then
         if(px(i)>0.0) then
            ro=3
         else
            ro=4
         end if
      end if

   else

      ! case px(i)=0
      if(py(i)>0.0) then
         if(abs(x(i))<L/2) then
            ro=1
         else
            if(x(i)>=L/2)ro=3
            if(x(i)<=(-L/2))ro=4
         end if
      else
         if(abs(x(i))<L/2) then
            ro=2
         else
            if(x(i)>=L/2)ro=3
            if(x(i)<=(-L/2))ro=4
         end if
      end if

   end if

   return
end subroutine hit

subroutine reflect(i)
   ! calc. the abscissa of the reflection point, x(i+1), here called xr
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```
  integer,intent(in) :: i

  if(px(i)==0.0) then
     xr(ro)=x(i)
  else
     if((ro==1.0).or.(ro==2.0)) then
        xr(ro)=((-1)**(ro+1) - q)/m
     end if
     if((ro==3.0).or.(ro==4.0)) then
        b=(1.0+m**2)*(q**2+(L**2)/4.0 -1.0)
        a=((m*q+((-1)**ro)*L/2)**2)-b
        xr1=(-(m*q+((-1)**ro)*L/2)+sqrt(a))/(1+m**2)
        xr2=(-(m*q+((-1)**ro)*L/2)-sqrt(a))/(1+m**2)
        xrmin=min(xr1,xr2)
        xrmax=max(xr1,xr2)
     end if
     if(ro==3.0) then
        if((m*py(i))<0.0) then
           xr(ro)=xrmin
        else
           xr(ro)=xrmax
        end if
     end if
     if(ro==4.0) then
        if((m*py(i))<=0.0) then
           xr(ro)=xrmin
        else
           xr(ro)=xrmax
        end if
     end if
  end if

  return
end subroutine reflect

subroutine move(i)
  !     determine the position of reflection and momenta after reflection
  integer,intent(in) :: i

  x(i+1)=xr(ro)
  if((ro==1.0).or.(ro==2.0)) then
     px(i+1)=px(i)
     py(i+1)= - py(i)
     y(i+1)= (-1)**(ro+1.0)
  end if
```

```
    if((ro==3.0).or.(ro==4.0)) then
       if(px(i)/=0.0) then
          y(i+1)= m*x(i+1)+q
       else
          y(i+1)=sign(1.,py(i))*sqrt(1-(x(i+1)+((-1)**ro)*L/2)**2)
       end if
       a=(y(i+1)**2-(x(i+1)+((-1)**ro)*L/2)**2)*px(i)
       b=2*(x(i+1)+((-1)**ro)*L/2)*y(i+1)*py(i)
       px(i+1)=a-b
       a=-2*(x(i+1)+((-1)**ro)*L/2)*y(i+1)*px(i)
       b=((x(i+1)+((-1)**ro)*L/2)**2-y(i+1)**2)*py(i)
       py(i+1)=a+b
    end if

    return
  end subroutine move

  subroutine output(i)
    !     write positions and momenta on a file
    integer,intent(in) :: i
    write(unit=3,fmt=*)i,x(i),y(i),px(i),py(i)
    return
  end subroutine output

end module bill


program billiard
  use bill
  integer::j
  call start()
  open(unit=3,file="dati",status="replace",action="write")

  do j=1,n-1
     call hit(j)
     call reflect(j)
     call move(j)
     call output(j)
  end do

  deallocate (x)
  deallocate (y)
  deallocate (px)
  deallocate (py)
  close(3)
end program billiard
```