

TENSORI

$$g_{ij}, du^i, du^j$$

$$u^i (i=1,2,\dots) \Rightarrow u^j (j=1,2,\dots,n)$$

$$du^j = \sum_i \frac{\partial u^j}{\partial u^i} du^i \quad (i,j=1,2,\dots,n)$$

$$V^j$$

TENSORI

CONTRAVARIANTE

$$V^j = \sum_i \frac{\partial u^j}{\partial u^i} V^i$$

ANCHE du^i e $\tilde{u}^i$ SONO CONTRAVARIANTI

VETTORI SONO TENSORI DI ORDINE 1

$$\phi(u^i) = \phi(u'^j)$$

$$\frac{\partial \phi}{\partial u'^j} = \sum_i \frac{\partial \phi}{\partial u^i} \cdot \frac{\partial u^i}{\partial u'^j} = \sum_i \frac{\partial u^i}{\partial u'^j} \frac{\partial \phi}{\partial u^i}$$

$$\frac{\partial \phi}{\partial u^i} \equiv \text{VETTORE COVARIANTE}$$

$$\Rightarrow \partial_i \phi = \frac{\partial \phi}{\partial u^i}$$

$$V'^j = \frac{\partial V'^j}{\partial V^i} V^i$$

$$\frac{\partial \phi}{\partial V'^j} = \frac{\partial V^i}{\partial V'^j} \frac{\partial \phi}{\partial V^i}$$

$$ds^2 = g_{ij} dV^i dV^j$$

$$ds^2 = g'_{kl} dV'^k dV'^l = g_{ij} dV^i dV^j = g_{ij} \frac{\partial V^i}{\partial V'^k} \frac{\partial V^j}{\partial V'^l} dV'^k dV'^l$$

$$g'_{kl} = \frac{\partial V^i}{\partial V'^k} \frac{\partial V^j}{\partial V'^l} g_{ij}$$

g_{ij} = TENSORE METRICO = TENSORE
COVARIANTE
DI RANGO
2

g^{ij} = TENSORE CONTRAVARIANTE DI RANGO
2

$$C^T$$

$$D_i = g_{ij} C^j \quad / \quad D^i = g^{ij} D_j$$

SCALAR

$$C, D$$

$$\bar{C} \equiv \bar{D}$$

$$D_i = g_{ij} D^j$$

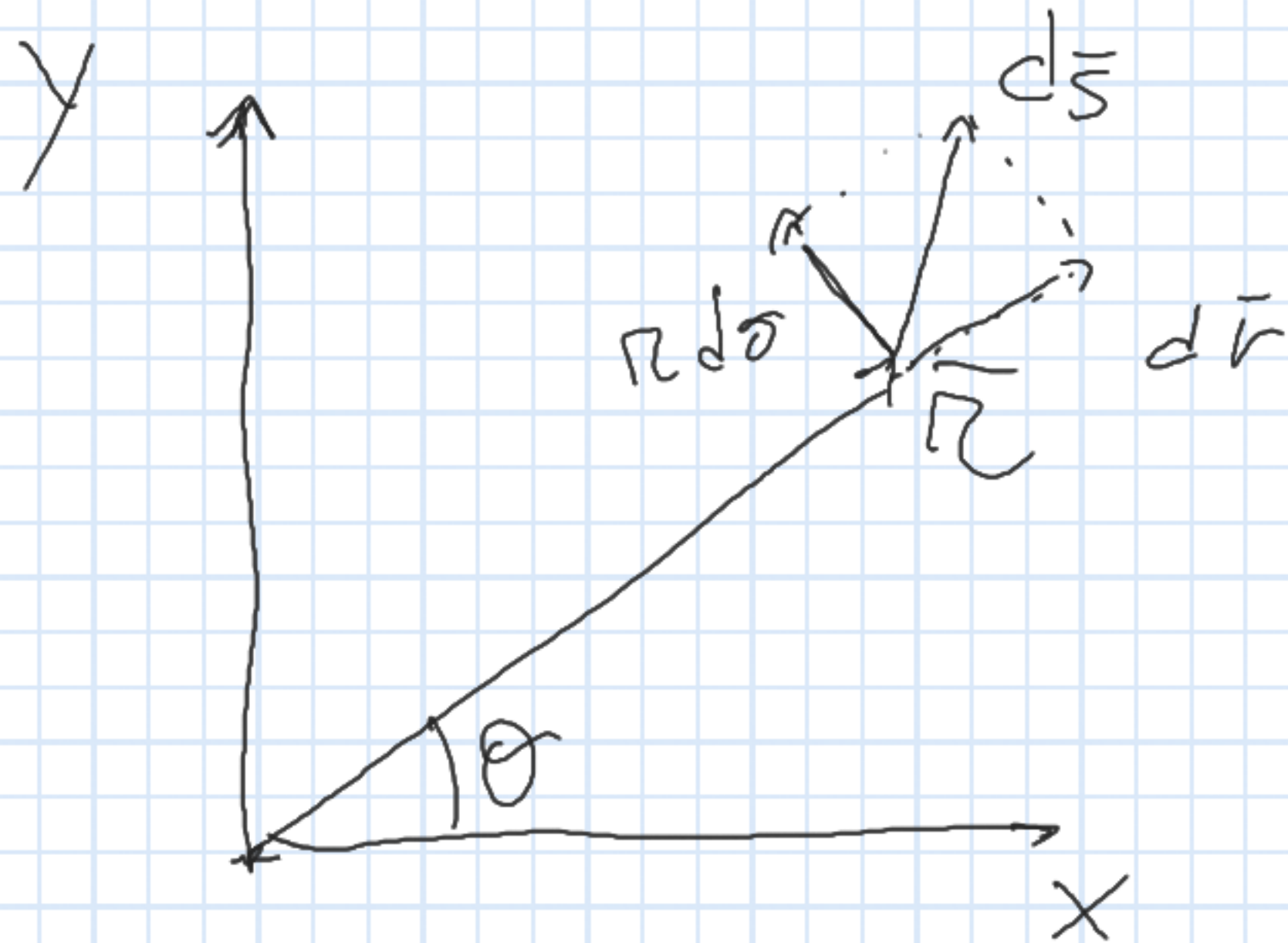
$$D^i = g^{ij} D_j$$

CONTRAVARIANT

COVARIANT

IL TENSORE METRICO g_{ij} SERVE A

TRASFORMARE
IN COVARIANTI
(E
LE COMPONENTI CONTRAVARIANTI
VICEVERSA



$$(x, y) = (r \cos \theta, r \sin \theta)$$

$$v^1 = r \quad v^2 = \theta$$

$$\begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix}$$

ds

$$g_{11} = \overline{x_1} \cdot \overline{x_1}$$

$$g_{22} = \overline{x_2} \cdot \overline{x_2}$$

$$g_{12} = g_{21} = \overline{x_1} \cdot \overline{x_2}$$

$$\vec{x}_1 = (\cos \theta, \sin \theta)$$

$$\vec{x}_2 = (r \sin \theta, -r \cos \theta)$$

$$g_{11} = \cos^2 \theta + \sin^2 \theta = 1$$

$$g_{22} = r^2 \sin^2 \theta + r^2 \cos^2 \theta = r^2$$

$$g_{12} = r \sin \theta \cos \theta - r \cos \theta \sin \theta = 0$$

$$g_{ij} = \begin{pmatrix} 1 & 0 \\ 0 & r^2 \end{pmatrix}$$

$$g^{ij} = \begin{pmatrix} 1 & 0 \\ 0 & 1/r^2 \end{pmatrix}$$

$$g = r^2 \Rightarrow \sqrt{g} = r \Rightarrow \boxed{dS^2 = \sqrt{g} du^1 du^2 = r dr d\theta}$$

$$A_i = (5, 9) \quad B^i = (3, 7) \quad g_{is} = \begin{pmatrix} 1 & 0 \\ 0 & r^2 \end{pmatrix}$$

$$A, B^i = A_1 B^1 + A_2 B^2 = 5 \cdot 3 + 7 \cdot 9 = 78 \quad g^{is} = \begin{pmatrix} 1 & 0 \\ 0 & \frac{1}{r^2} \end{pmatrix}$$

$$A^i = g_{is} A_s \Rightarrow A^1 = g^{11} A_1 + g^{12} A_2 = 1 \cdot 5 + 0 \cdot 9 = 5$$

$$A^2 = g^{21} A_1 + g^{22} A_2 = 0 \cdot 5 + \frac{9}{r^2} = 9/r^2$$

$$B_i = g_{is} B^i \rightarrow B_1 = g_{11} B^1 + g_{12} B^2 = 3 + 0 = 3$$

$$B_2 = g_{21} B^1 + g_{22} B^2 = 7r^2$$

$$\boxed{A^i B_i} = A^1 B_1 + A^2 B_2 = 5 \cdot 3 + \frac{9}{k^2} \cdot 7k^2 = 78 = A_i B^i$$

$$A^i B_i = \underbrace{g_{is}}_{\sim} A^i B^s = g^{is} A_s B_i = A_i B^i = \text{INVARIANT}$$

$$\bar{v} = v^i \bar{x}_i$$

$$\bar{v}_k = \bar{v} \cdot \bar{x}_k = v^i \bar{x}_i \cdot \bar{x}_k =$$

$$= v^i g_{ik} = g_{ik} v^i = \underbrace{g_{ki}}_{\text{symmetric}} \underbrace{v^i}_{\text{covector}}$$

