

## Funzione di autocorrelazione della velocità

$$C_v(t', t'') = \langle (v(t') - \langle v \rangle)(v(t'') - \langle v \rangle) \rangle$$

Equilibrio:

- $\langle v \rangle = 0$

- $C_v$  dipende da  $t'' - t' = t$

$$C_v|t| = \langle v(t') v(t'+t) \rangle$$

In 3d:

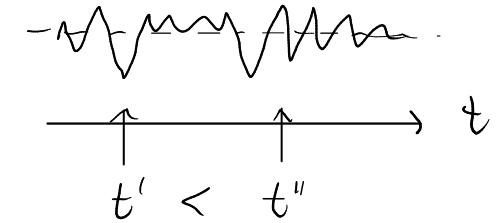
$$C_v(t) = \frac{1}{3} \langle \vec{v}(t') \cdot \vec{v}(t'+t) \rangle \stackrel{\substack{t'=0 \\ \downarrow}}{=} \frac{1}{3} \langle \vec{v}(t) \cdot \vec{v}(0) \rangle$$

Langevin:

$$\vec{v}(t) = \vec{v}_0 e^{-\xi/m t} + \frac{1}{m} \int_0^t ds e^{-\xi/m(t-s)} \vec{\theta}(s)$$

$$\begin{aligned} \vec{v}(t) &= \vec{v}(t_0) e^{-\xi/m(t-t_0)} + \frac{1}{m} \int_{t_0}^t ds e^{-\xi/m(t-s)} \vec{\theta}(s) \quad t_0 \rightarrow -\infty \\ &= \int_{-\infty}^t ds e^{-\xi/m(t-s)} \vec{\theta}(s) \end{aligned}$$

(es.) ...  $\langle \vec{v}(t) \cdot \vec{v}(0) \rangle$



$$\frac{d\vec{v}}{dt} = -\frac{\varepsilon}{m}\vec{v} + \frac{1}{m}\vec{\theta}(t)$$

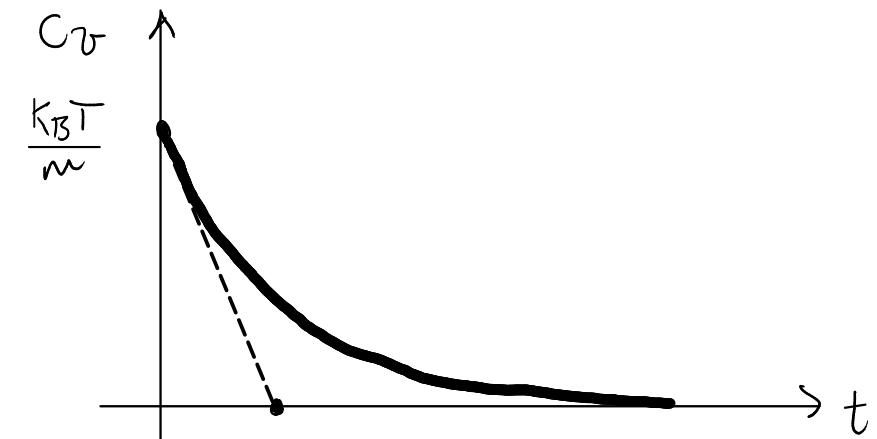
$$\langle \frac{d\vec{v}}{dt} \cdot \vec{v}(0) \rangle = -\frac{\varepsilon}{m} \langle \vec{v}(t) \cdot \vec{v}(0) \rangle + \frac{1}{m} \langle \vec{\theta}(t) \cdot \vec{v}(0) \rangle = 0$$

$$\frac{d}{dt} \langle \vec{v}(t) \cdot \vec{v}(0) \rangle = -\frac{\varepsilon}{m} \langle \vec{v}(t) \cdot \vec{v}(0) \rangle$$

$$\langle \vec{v}(t) \cdot \vec{v}(0) \rangle = \langle |\vec{v}|^2 \rangle e^{-\frac{\varepsilon}{m}t}$$

$$\langle v^2 \rangle = \frac{3k_B T}{m}$$

$$C_v = \frac{1}{3} \langle \vec{v}(t) \cdot \vec{v}(0) \rangle = \frac{k_B T}{m} e^{-\frac{\varepsilon}{m}t}$$

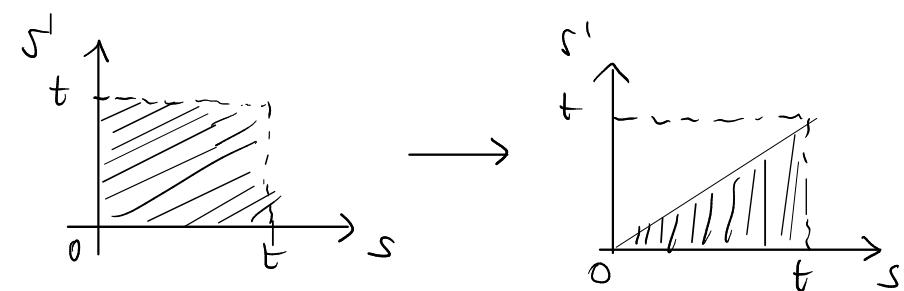


## Spostamento quadratico medio

→ moto diffusivo

$$\Delta \vec{r} = \vec{r}(t) - \vec{r}(0) = \int_0^t \vec{v}(s) ds$$

$$\langle |\Delta \vec{r}|^2 \rangle = \left\langle \int_0^t \vec{v}(s) ds \cdot \int_0^t \vec{v}(s') ds' \right\rangle = \int_0^t ds \int_0^t ds' \langle \vec{v}(s) \cdot \vec{v}(s') \rangle$$



$$= 2 \int_0^t ds \int_0^s ds' \langle \vec{v}(s) \cdot \vec{v}(s') \rangle$$

$$\langle \vec{v}(s) \cdot \vec{v}(s') \rangle = 3 C_v(s-s')$$

↙ Equilibrio  
 $t' = s - s'$   
 cambio variabile

$$= 6 \int_0^t ds \underbrace{\int_0^s dt' C_v(t')}_{= 6 \left\{ [s \int_0^s dt' C_v(t')] \right\}_0^t} - \int_0^t ds s C_v(s) = 6 \left\{ t \int_0^t ds C_v(s) - \int_0^t ds s C_v(s) \right\}$$

$$\langle |\Delta \vec{r}|^2 \rangle = 6t \int_0^t \left( 1 - \frac{s}{t} \right) C_v(s) ds$$

Langevin:

$$C_v(t) = \frac{k_B T}{m} e^{-\frac{\epsilon}{m} t} \xrightarrow{\text{es.}} \langle |\Delta \vec{r}|^2 \rangle = 6 \frac{k_B T}{\epsilon} \left[ t + \frac{m}{\epsilon} (e^{-\frac{\epsilon}{m} t} - 1) \right]$$

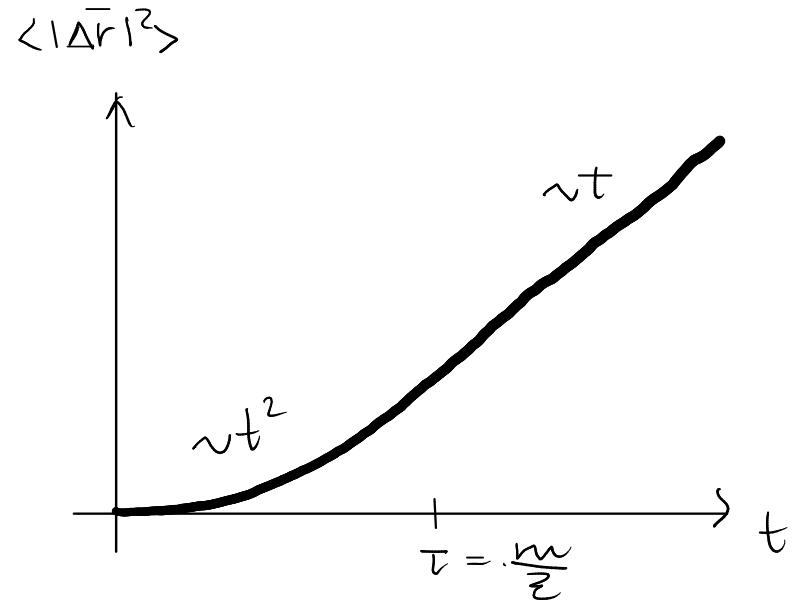
- $t \ll \frac{m}{\zeta} : \langle |\Delta \bar{r}|^2 \rangle \approx 6 \frac{k_B T}{\zeta} \left[ t + \frac{m}{\zeta} \left( -\frac{\zeta}{m} t + \frac{1}{2} \frac{\zeta^2}{m^2} t^2 \right) \right] = 3 \frac{k_B T}{\zeta} \cdot \frac{\zeta}{m} t^2 = \frac{3 k_B T}{m} t^2$

$\sim t^2$  balistico

- $t \gg \frac{m}{\zeta} : \langle |\Delta r|^2 \rangle \approx 6 \frac{k_B T}{\zeta} t$  coefficiente di diffusione  $D$

$\sim t$  diffusivo

$$= 2 \cdot d \cdot D \cdot t$$



## EQUAZIONE DI LANGEVIN SOVRA-AMORTITA

$$m \frac{d\vec{r}}{dt} = -\zeta \vec{v} + \vec{F}_{\text{est}} + \vec{\theta}(t) \quad \vec{F}_{\text{est}} = \vec{F}_{\text{est}}(\vec{r}, t)$$

$\checkmark$  trascurabile rispetto agli altri se  $\zeta \rightarrow \infty$ ,  $\zeta \sim \theta_0$

$$\zeta \frac{d\vec{r}}{dt} = \vec{F}_{\text{est}} + \vec{\theta}(t). \quad \text{eq. Langevin sovra-ammortita} \rightarrow \text{dinamica Browniana}$$

### Caso libero

$$\vec{r}(t) = \vec{r}(0) + \frac{1}{\zeta} \int_0^t ds \vec{\theta}(s) \quad \Delta \vec{r} = \vec{r}(t) - \vec{r}(0) \quad \theta_0 = k_B T \cdot \zeta$$

$$\langle |\Delta \vec{r}|^2 \rangle = \frac{1}{\zeta^2} \int_0^t ds \int_0^t ds' \langle \vec{\theta}(s) \cdot \vec{\theta}(s') \rangle = \frac{6\theta_0}{\zeta^2} \int_0^t ds = 6 \frac{\theta_0}{\zeta^2} t = 6 \frac{k_B T}{\zeta} t$$

$$D = \frac{\theta_0}{\zeta^2}$$

coff. diffusione

### Esempi

- forza costante
- potenziale armonico
- forzante sinusoidale
- particella attiva

## Algoritmo di Ernak : potenziale generico

$$\varepsilon \frac{dx}{dt} = F(x) + \theta(t) \quad \langle \theta(t) \rangle = 0 \quad \langle \theta(t') \theta(t'') \rangle = 2\theta_0 \delta(t' - t'') \quad \theta_0 = k_B T \cdot \varepsilon$$

Euler I ordine : intervallo  $\Delta t$

$$x(t + \Delta t) = x(t) + \frac{1}{\varepsilon} \int_t^{t+\Delta t} F(x) dt + \frac{1}{\varepsilon} \int_t^{t+\Delta t} \theta(t) dt \approx x(t) + \frac{F(x)}{\varepsilon} \Delta t + \underbrace{\frac{1}{\varepsilon} \int_t^{t+\Delta t} \theta(t) dt}_{\tilde{\theta}}$$

$$\tilde{\theta}(t; \Delta t) = \frac{1}{\varepsilon} \int_t^{t+\Delta t} \theta(t) dt$$

$$\left\{ \begin{array}{l} \langle \tilde{\theta}(t; \Delta t) \rangle = 0 \\ \langle \tilde{\theta}^2(t; \Delta t) \rangle = \frac{1}{\varepsilon^2} \int_t^{t+\Delta t} ds \int_t^{t+\Delta t} ds' \langle \theta(s) \theta(s') \rangle = \frac{2\theta_0}{\varepsilon^2} \int_t^{t+\Delta t} ds = 2 \frac{\theta_0}{\varepsilon^2} \Delta t = 2 \frac{k_B T}{\varepsilon} \Delta t \end{array} \right. = D$$

Teor. limite centrale  $\Rightarrow \tilde{\theta}$  ha distribuzione gaussiana

$$p(\tilde{\theta}) = \frac{1}{\sqrt{4\pi D \Delta t}} e^{-\frac{\tilde{\theta}^2}{4D\Delta t}} \xrightarrow{3d} p(\vec{\tilde{\theta}}) = \frac{1}{(4\pi D \Delta t)^{3/2}} e^{-\frac{|\vec{\tilde{\theta}}|^2}{4D\Delta t}}$$

## APPROCCIO DI FOKKER - PLANCK

