

$$y(t) = z + v_2(t)$$

$$\text{or } v_2 = V_2$$

$$v_2(\cdot) \sim \text{NWG}(0, V_2)$$

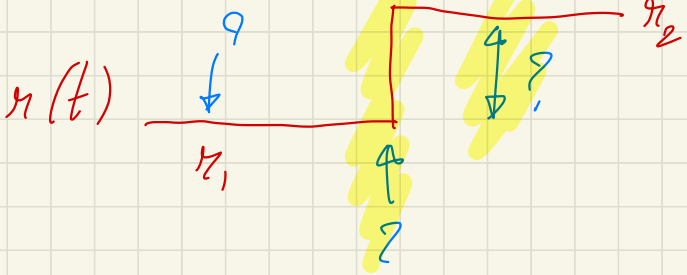
$$x_1(t) = z$$

$$\begin{cases} x_1(t+1) = x_1(t) + \cancel{v_1(t)} \\ y(t) = x_1(t) + \underline{v_2(t)} \end{cases}$$

$$P(t+1) = F \left[P(t) - P(t) H^T \left(V_2 + H P(t) H^T \right)^{-1} H P(t) \right] F^T + V_1$$

$$p(t+1) = p(t) - \frac{\hat{p}^2(t)}{\hat{\sigma}^2 + p(t)}$$

$$k(t) = \frac{\hat{p}(t)}{\hat{p}(t) + \hat{\sigma}^2}$$



.