

TEORIA DELLA RISPOSTA LINEARE

Caso statico

Hamiltoniana: $H + \Delta H$ $\Delta H = -\phi A$ $A(\{\vec{r}_i\}) \rightarrow$ osservabile $\phi = \phi(\vec{r})$

Regime risposta lineare: $\Delta H \ll k_B T$

$$\langle \dots \rangle_p \rightarrow e^{-\beta(H + \Delta H)}$$

$$\langle \dots \rangle \rightarrow e^{-\beta H}$$

$$Z = \text{Tr}[e^{-\beta H}]$$

$$\langle A \rangle_p = \frac{\text{Tr}[e^{-\beta(H + \Delta H)} A]}{\text{Tr}[e^{-\beta(H + \Delta H)}]} = \frac{\text{Tr}[e^{-\beta H} (1 - \beta \Delta H) A]}{\text{Tr}[e^{-\beta H} (1 - \beta \Delta H)]} + O[(\beta \Delta H)^2]$$

$$= \frac{\text{Tr}[e^{-\beta H} (1 - \beta \Delta H) A]}{Z} \cdot \left(1 + \frac{\text{Tr}[e^{-\beta H} \beta \Delta H]}{Z} \right)$$

$$= (\langle A \rangle - \beta \langle \Delta H A \rangle) \cdot (1 + \beta \langle \Delta H \rangle) = \langle A \rangle - \beta \langle \Delta H A \rangle + \beta \langle \Delta H \rangle \langle A \rangle$$

$$= \langle A \rangle - \beta (\langle \Delta H A \rangle - \langle \Delta H \rangle \langle A \rangle) = \langle A \rangle - \beta \underbrace{\langle (A - \langle A \rangle)(\Delta H - \langle \Delta H \rangle) \rangle}_{\langle \delta A \delta \Delta H \rangle}$$

↳ covarianza ΔH e A

$$\Delta H = -\phi A \quad \phi = \omega \sin t$$

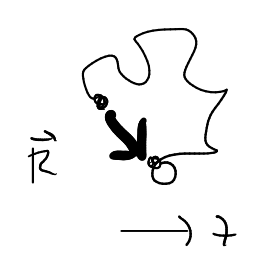
$$\delta \langle A \rangle \equiv \langle A \rangle_p - \langle A \rangle = +\phi \beta \langle (A - \langle A \rangle)^2 \rangle = \phi \beta \langle \delta A^2 \rangle$$

↑
risposta
lineare
↑
fluttuazioni
equilibrio

Funzione di risposta:

$$\chi \equiv \frac{\delta \langle A \rangle}{\phi} = \beta \langle \delta A^2 \rangle$$

Esempio: catena polimerica ideale $N+1$ monomeri, distanza legame A



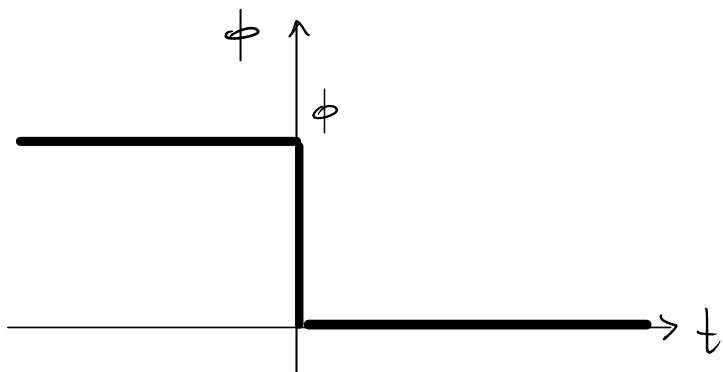
$$\vec{R} = \vec{r}_{N+1} - \vec{r}_1 \quad \langle \vec{R} \rangle = \vec{0} \quad \langle |\vec{R}|^2 \rangle = a^2 N \quad \langle R_z^2 \rangle = \frac{1}{3} a^2 N$$

$$\phi = f \quad \Rightarrow \quad \Delta H = -f R_z \quad \Rightarrow \quad \delta l \equiv \langle R_z \rangle_p - \underbrace{\langle R_z \rangle}_{=0} = f \beta \frac{a^2 N}{3} \quad \Rightarrow \quad f = \frac{3 k_B T}{a^2 N} \delta l$$

↓
forza estensione

Caso dinamico

Regime lineare : $\Delta H \ll k_B T$

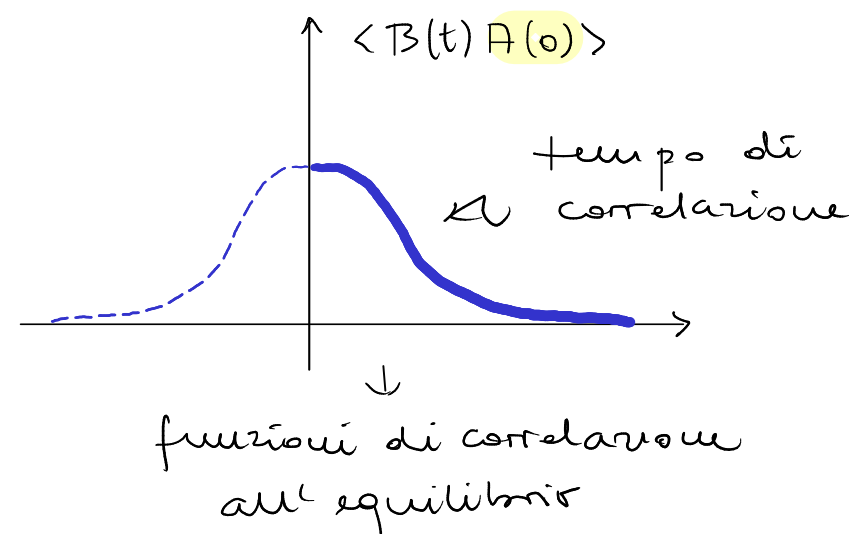
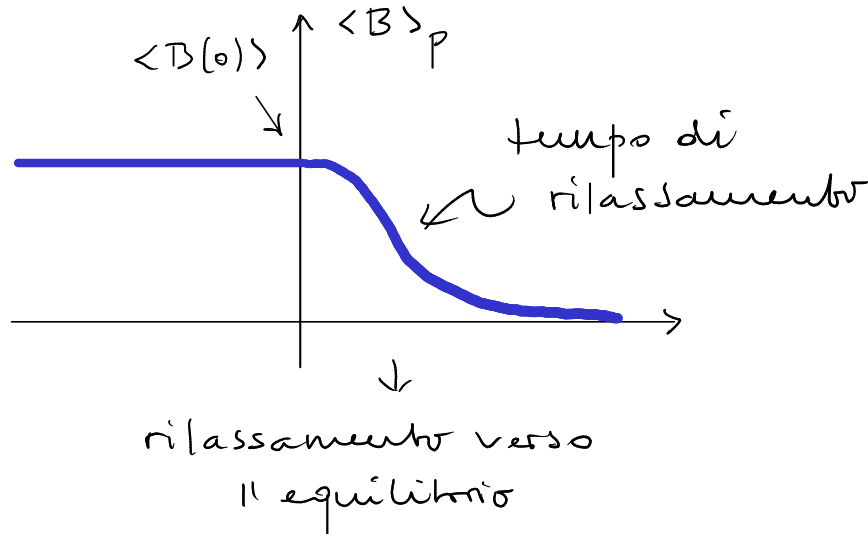
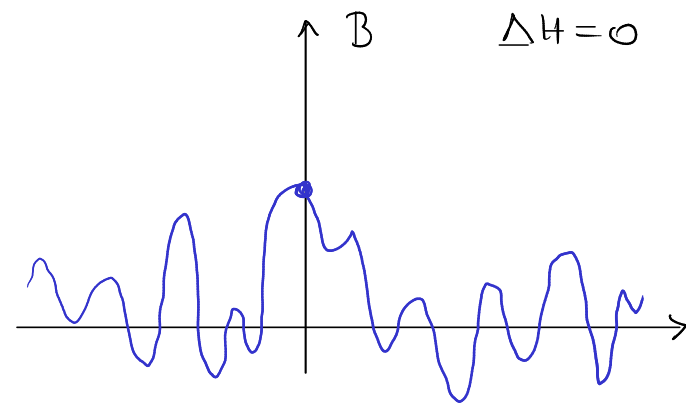
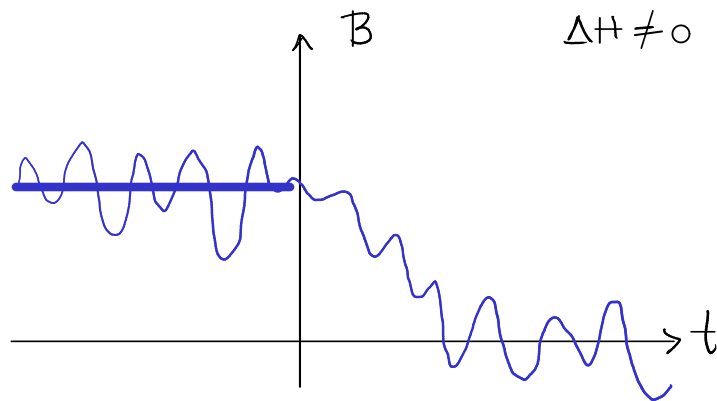


$$\phi = \begin{cases} \phi & t \leq 0 \\ 0 & t > 0 \end{cases}$$

$$\Delta H = -\phi(t) A$$

$$A = A(\{F_i\})$$

$$B = B(\{F_i\})$$



$$\langle B(0) \rangle_p = \frac{\text{Tr} [e^{-\beta(H+\Delta H)} B(0)]}{\text{Tr} [e^{-\beta(H+\Delta H)}]}$$

$$\langle B(t) \rangle_p = \frac{\text{Tr} [e^{-\beta(H+\Delta H)} B(t)]}{\text{Tr} [e^{-\beta(H+\Delta H)}]}$$

evoluto al tempo t
 $\Gamma(0) \rightarrow \Gamma(t)$

Regime lineare : $\Delta H \ll k_B T$

$$\langle B(t) \rangle_p = \frac{\text{Tr} [e^{-\beta(H+\Delta H)} B(t)]}{\text{Tr} [e^{-\beta(H+\Delta H)}]} = \dots = \underbrace{\langle B(t) \rangle}_{\langle B \rangle} - \beta \left(\underbrace{\langle B(t) \Delta H \rangle}_{\langle B \rangle \langle \Delta H \rangle} - \underbrace{\langle B(t) \rangle \langle \Delta H \rangle}_{\langle B \rangle \langle \Delta H \rangle} \right) + O[(\beta \Delta H)^2]$$

$$\langle B(t) \rangle_p - \langle B \rangle = \beta \phi \left(\langle B(t) A(0) \rangle - \langle B \rangle \langle A \rangle \right) = \beta \phi C_{BA}(t)$$

$$\delta \bar{B}(t) \equiv \langle B(t) \rangle_p - \langle B \rangle = \beta \phi C_{BA}(t) \qquad \delta \bar{B}(0) = \beta \phi C_{BA}(0)$$

↑
risposta
fuori equilibrio

↑
correlazione
all'equilibrio

$$\frac{\delta \bar{B}(t)}{\delta \bar{B}(0)} = \frac{C_{BA}(t)}{C_{BA}(0)} \rightarrow \text{principio di regressione di Onsager}$$

↑
funzione correlazione normalizzata

$$A = B \rightarrow \frac{\delta \bar{A}(t)}{\delta \bar{A}(0)} = \frac{C_{AA}(t)}{C_{AA}(0)}$$

Funzione di risposta

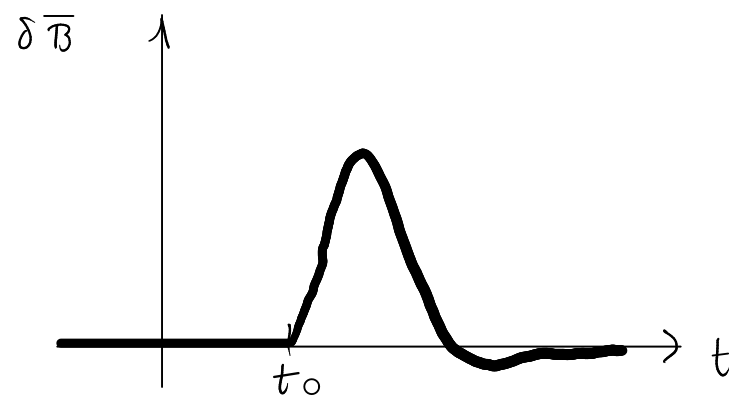
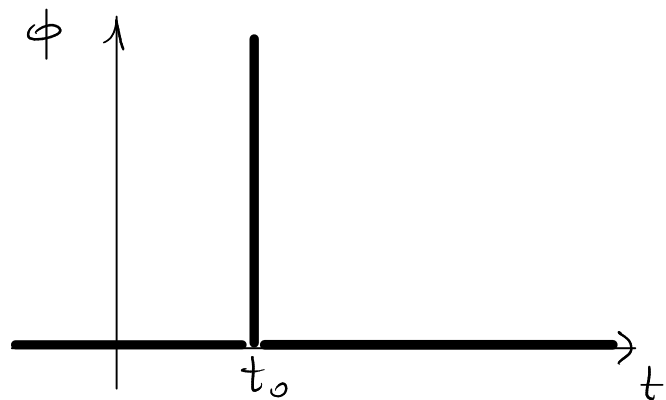
$$\Delta H = -\phi(t) A$$

regime lineare

$$\delta \bar{B}(t) = \int_{-\infty}^{\infty} dt' \phi(t') \chi_{BA}(t', t) \underset{\substack{\uparrow \\ t' < t \\ \text{causalità}}}{=} \int_{-\infty}^t dt' \phi(t') \chi_{BA}(t', t) \underset{\uparrow}{=} \int_{-\infty}^t dt' \phi(t') \chi_{BA}(t-t')$$

χ_{BA} è una proprietà all'equilibrio

ES.: campo impulsivo $\phi(t) = \phi_0 \delta(t-t_0) \rightarrow \delta \bar{B}(t) = \phi_0 \chi_{BA}(t-t_0)$



Caso particolare:

$$\phi(t) = \begin{cases} \phi & t \leq 0 \\ 0 & t > 0 \end{cases}$$

$$\delta \bar{B}(t) = \beta \phi C_{BA}(t) \text{ (4)}$$

$$= \int_{-\infty}^t dt' \phi(t') \chi_{BA}(t-t') = \phi \int_{-\infty}^0 dt' \chi_{BA}(t-t')$$

$$= \underset{s = t - t'}{\uparrow} \phi \int_t^{\infty} ds \chi_{BA}(s) = \underset{*}{\uparrow} \phi \beta C_{BA}(t)$$

Teorema di fluttuazione-dissipazione

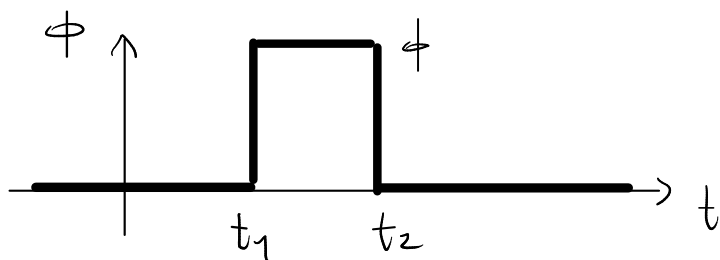
$$\chi_{BA}(t) = -\beta \frac{dC_{BA}}{dt}$$

\uparrow
risposta

\uparrow
funzione di
correlazione

$$A=B \quad : \quad \chi(t) = -\beta \frac{dC}{dt}$$

Esercizio : $\Delta H = \sim \phi(t) A$



$$C_{BA}(t) = C_{AB}(0) \exp(-t/\tau)$$

$$\phi(t) = \begin{cases} 0 & t < t_1 \\ \phi & t_1 \leq t \leq t_2 \\ 0 & t > t_2 \end{cases} \Rightarrow \begin{cases} \chi_{BA} = ? \\ \delta \bar{B}(t) = ? \end{cases}$$