

INTRODUZIONE AL CORSO DI STATICA

24/2/22

RIPASSO : GRANDEZZE FISICHE

- scalari : massa $[M]$, lunghezze $[L]$, temperature $[T]$, pressione $[FL^{-2}]$
- vettoriali : forze $[F]$, spostamento $[L]$

UNITA' DI MISURA

massa : Kg

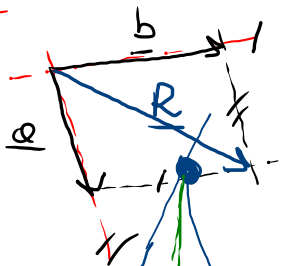
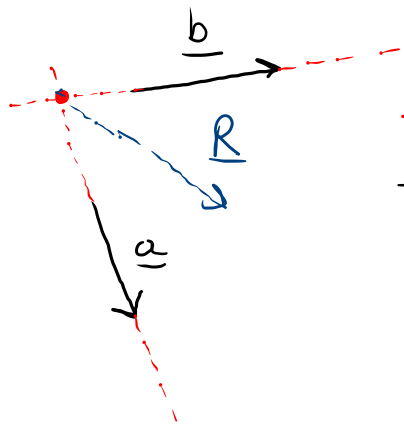
$$\text{Peso} = M \cdot g$$

lunghezze : m

forze : N

pressione : $\text{Pa} = \frac{\text{N}}{\text{m}^2} \Rightarrow$ grado di sollecitazione dei materiali
 $\sim \text{MPa} = \text{N}/\text{mm}^2$; $\text{GPa} \sim 10^9 \text{Pa}$
 10^6Pa

ALCUNE CONSIDERAZ- SUI VETTORI



Regole del
parallelogramma

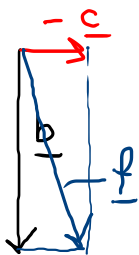
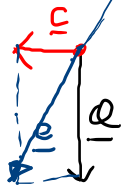


$$l_1 > l_2$$

$$\{\underline{a}, \underline{b}\}$$



$$\{\underline{e}, \underline{f}\}$$

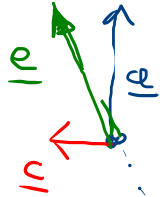


VETTORI //
CONCORDI

STESSA RISULTANTE

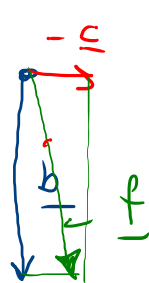
$$|\underline{R}| = 5$$

VEITORI //
DISCORDI



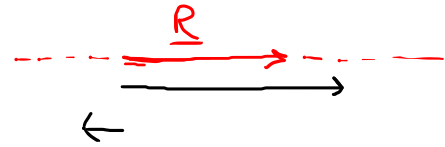
$$|a| \neq |b|$$

Aggiungere ad un sistema di
vettori 2 vettori uguali ed
opposti $\{c, -c\}$ NON CAMBIA
R e la sua posizione.

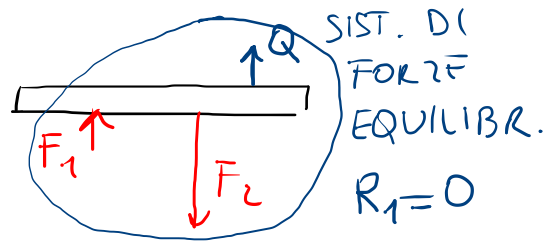
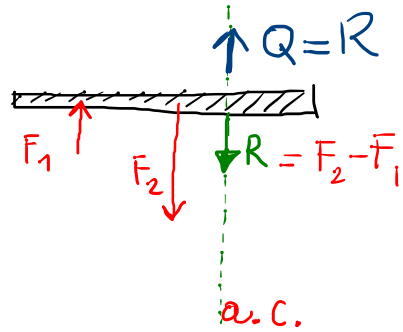


RETTA D'AZIONE DELLA RESULT.
=
ASSE CENTRALE

$$\underline{R} \sim |\underline{R}| = 1$$



RAGIONIAMO:

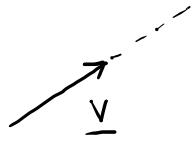


Problema: assegnato $\{F_1, F_2\}$

come posso metterlo in equilibrio?

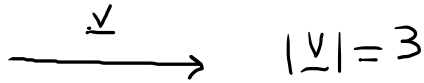
Risposta: applico una Q sull'asse
centrale tale che $Q=R$

VETTORI, LORO RAPPRESENTAZIONE E OPERAZIONI

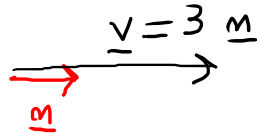


INTENSITA' o MODULO : $|\underline{v}|$, v : LUNGHEZZA DEL SEGMENTO

VERSORE : VETTORE UNITARIO : $|\underline{m}| = 1$



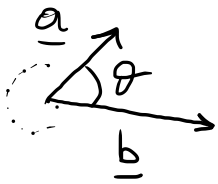
$$|\underline{v}| = 3$$



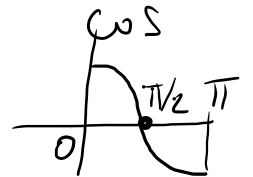
← INTENSITA'

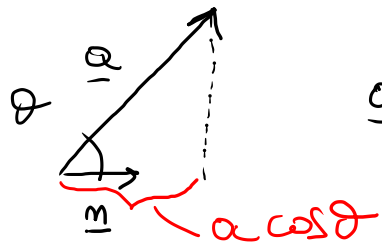
• DUE OPERAZIONI SUI VETTORI

1) PRODOTTO SCALARE $\underline{a} \cdot \underline{b} \Rightarrow$ NUMERO REALE



$$\underline{a} \cdot \underline{b} = ab \cos \theta \begin{cases} > 0 \\ = 0 \\ < 0 \end{cases}$$



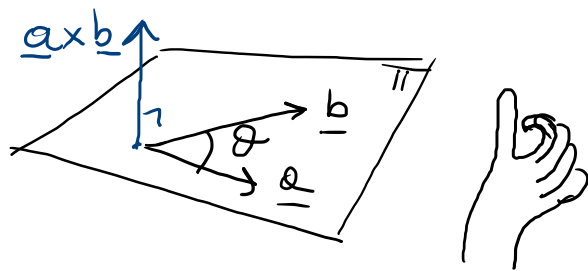


\underline{m} : VERSORE

$$\underline{a} \cdot \underline{m} = a \cdot 1 \cos \theta = a \cos \theta \quad ; \quad \text{PROIEZ. DEL VETTORE } \underline{a} \text{ NELLA DIREZ. DI } \underline{m}$$

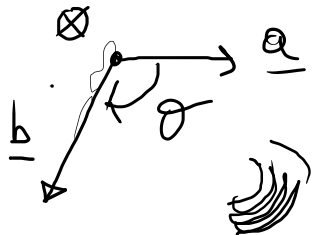
2) PRODOTTO VETTORIALE

$\underline{a}, \underline{b} \rightarrow \underline{a} \times \underline{b}$ è un vettore
 $\hookrightarrow \perp \underline{a}, \perp \underline{b}$

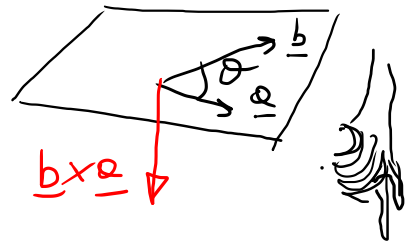


$$|\underline{a} \times \underline{b}| = ab \sin \theta \rightarrow \text{se } \theta = 0 \Rightarrow |\underline{a} \times \underline{b}| = 0$$

ES.

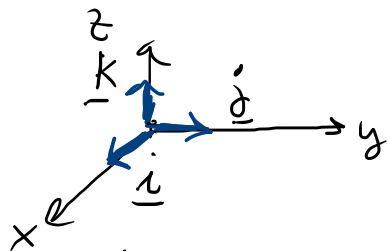


$\underline{a} \times \underline{b}$ entra o esce dal foglio?
ENTRA!



$$\underline{b} \times \underline{a} = -\underline{a} \times \underline{b}$$

RAPPRESENTAZ. COORDINATA DEI VETTORI



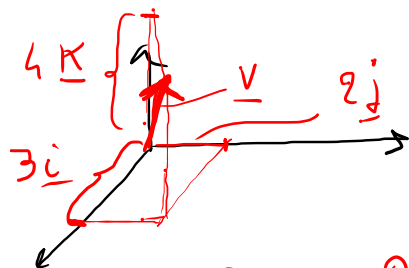
$\underline{i}, \underline{j}, \underline{k}$: 3 vettori \perp Tra di loro

$$|\underline{i}| = |\underline{j}| = |\underline{k}| = 1 \quad ; \quad \underline{i} \cdot \underline{i} = 1 \quad (\underline{j} \cdot \underline{j} = 1 = \underline{k} \cdot \underline{k})$$

$$\underline{i} \times \underline{j} = \underline{k} \dots \dots$$

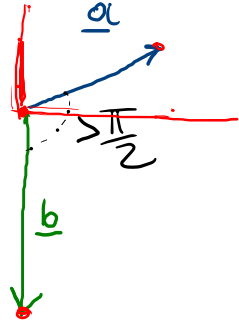
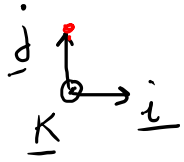
$\{\underline{i}, \underline{j}, \underline{k}\}$: BASE DEI VETTORI NELLO SPAZIO

$$\underline{v} = \underline{(3)} \underline{i} + 2 \underline{j} + 4 \underline{k} \quad ; \quad \text{RAPPRES. COORD. DI } \underline{v}$$



$$\underline{v} \cdot \underline{i} : \text{COMP DI } \underline{v} \text{ lungo } \underline{i} = \Delta (3 \underline{i} + 2 \underline{j} + 4 \underline{k}) \cdot \underline{i} = 3 \overset{1}{\underline{i} \cdot \underline{i}} + 2 \cancel{\underline{j} \cdot \underline{i}} + 4 \cancel{\underline{k} \cdot \underline{i}} = 3 + \dots = 3$$

LES



$$\underline{a} = 2\underline{i} + \underline{j} \quad ; \quad \underline{b} = -3\underline{j}$$

RAPPR. VERT. DI \underline{a} E \underline{b}

$$\begin{aligned} \underline{a} \cdot \underline{b} &= (2\underline{i} + \underline{j}) \cdot (-3\underline{j}) = 2\underline{i} \cdot (-3\underline{j}) + \underline{j} \cdot (-3\underline{j}) \\ &= -6 \underbrace{\underline{i} \cdot \underline{j}}_0 - 3 \underbrace{\underline{j} \cdot \underline{j}}_1 = -3 \end{aligned}$$

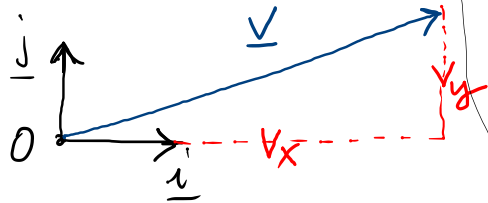
$$\begin{aligned} \underline{a} &= a_x \underline{i} + a_y \underline{j} \\ \underline{b} &= b_x \underline{i} + b_y \underline{j} \end{aligned}$$

$$\Rightarrow \underline{a} \cdot \underline{b} = a_x b_x + a_y b_y (+ a_z b_z)$$

SOMMA PRODOTTO
COMPONENTI OMOLOGHE

LES : \underline{a} E \underline{b} ORTOGONALI PER COSTRUZIONE $\Rightarrow \underline{a} \cdot \underline{b} = 0$

ES: MODULO o INTENSITA' DI UN VETTORE IN RAPPR. CARTESIANA

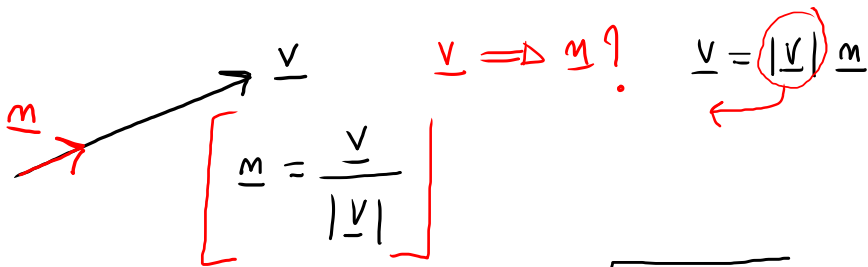


$$\underline{v} = v_x \underline{i} + v_y \underline{j}$$

$$|\underline{v}|? \quad |\underline{v}|^2 = v_x^2 + v_y^2 \Rightarrow |\underline{v}| = \sqrt{v_x^2 + v_y^2} \quad \text{---} + v_z^2$$

COME POSSO SCRIVERE $v_x^2 + v_y^2$? $v_x v_x + v_y v_y = \underline{v} \cdot \underline{v} \Rightarrow |\underline{v}| = \sqrt{\underline{v} \cdot \underline{v}}$

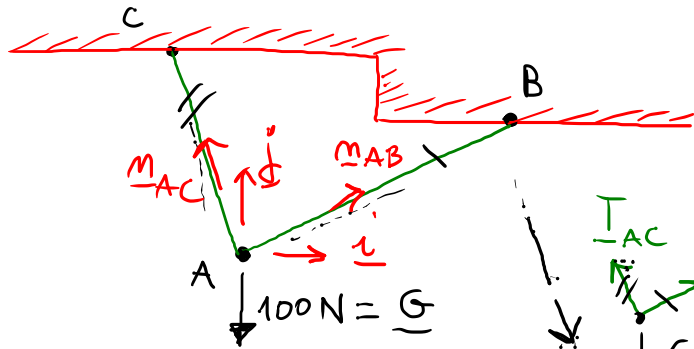
COME CALCOLARE IL VERSORE ASSOCIATO AD UN VETTORE ASSEGNATO



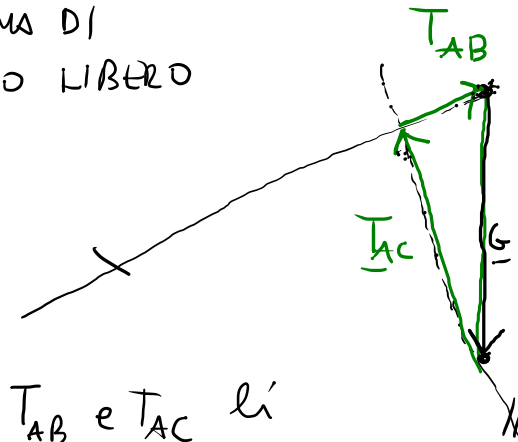
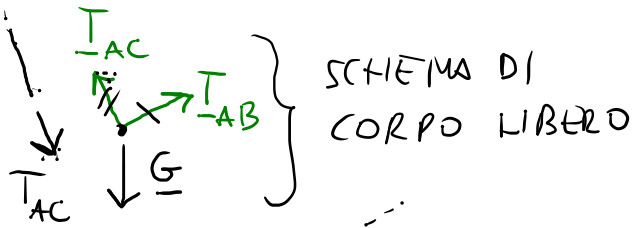
ES: $\underline{v} = 3\underline{i} + 4\underline{j} \Rightarrow |\underline{v}| = \sqrt{v_x^2 + v_y^2} = \sqrt{9 + 16} = \sqrt{25} = 5$
 $\underline{m} = \frac{1}{5} (3\underline{i} + 4\underline{j}) = \frac{3}{5}\underline{i} + \frac{4}{5}\underline{j}$ VERIF. $|\underline{m}| = 1$

ES. EQUILIBRIO DI UN PUNTO MATERIALE "PESANTE"

1) CALCOLE LE TENSIONI NEI FILI ($\sum \vec{F}_i = \vec{0}$)



1) METODO GRAFICO: SOMMA DI \underline{G} , \underline{T}_{AB} , \underline{T}_{AC} È UGUALE A ZERO.



POLIGONO DELLE FORZE CHIUSO!
 $\underline{R} = \underline{0}$

T_{AB} e T_{AC} li ottengo da una misura in scala del POLIGONO

2) METODO ANALITICO

$\underline{G} + \underline{T}_{AB} + \underline{T}_{AC} = \underline{0}$ EQ. DI EQUILIBRIO

$\underline{G} = -100 \underline{j}$ N

$\underline{T}_{AB} = T_{AB} (4\underline{i} + 2\underline{j}) \frac{1}{\sqrt{20}}$

$\underline{T}_{AC} = T_{AC} (-\underline{i} + 3\underline{j}) \frac{1}{\sqrt{10}}$

25 N

SCRIVO LE COMPONENTI LUNGO \underline{i} e \underline{j} DELL'EQ. DI EQUILIBRIO

$$\underline{i} : \frac{4}{\sqrt{20}} T_{AB} - \frac{1}{\sqrt{10}} T_{AC} = 0$$

$$\underline{j} : -100 + \frac{2}{\sqrt{20}} T_{AB} + \frac{3}{\sqrt{10}} T_{AC} = 0$$

2 EQUAZ. IN 2 INCOGNITE

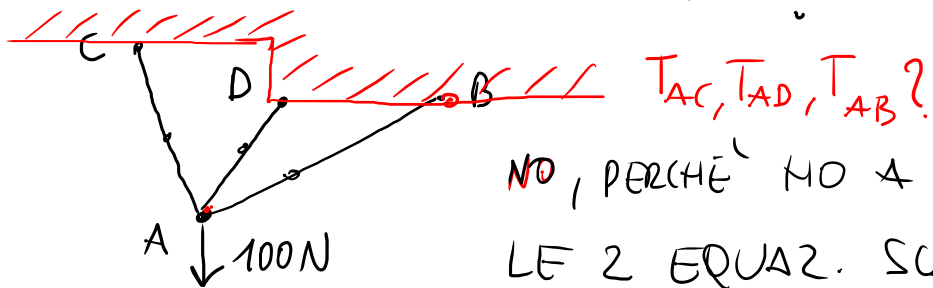
\Rightarrow 1 SOLUZ. UNICA CON

$$T_{AC}, T_{AB} \neq 0$$

RAGIONIAMO!

RIVSCIREMMO A QUALCUNO LE TENSIONI
NEL FILI DI QUESTO PROBLEMA?

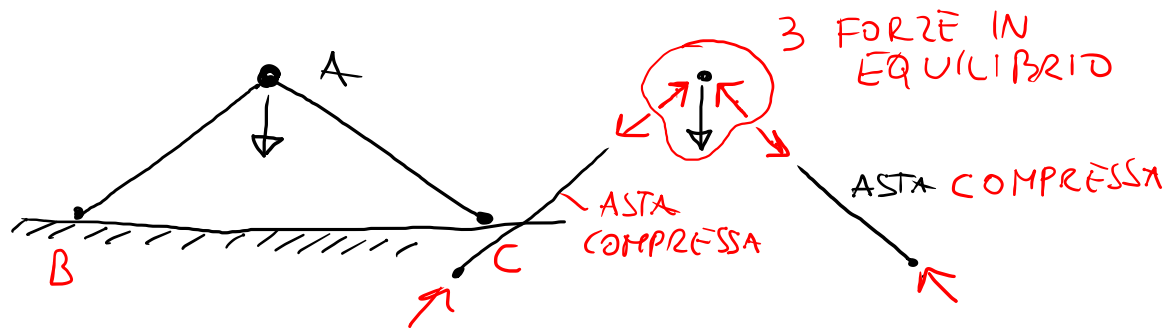
$$\left. \begin{aligned} T_{AB} &= \frac{100\sqrt{5}}{7} \text{ N} \\ T_{AC} &= \frac{200\sqrt{10}}{7} \text{ N} \end{aligned} \right\}$$



NO, PERCHÉ HO A DISPOSIZ. SEMPRE SOLO

LE 2 EQUAZ. SCALARI LUNGO \underline{i} e LUNGO \underline{j} .

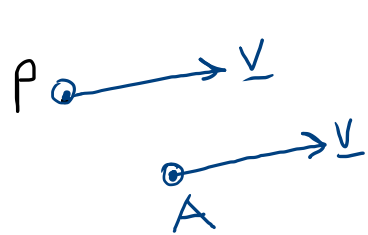
LE SOLUZ. SONO $\infty^1 = \infty^{3-2}$



POSSO RISOLVERE IL PROBLEMA PERCHÉ HO 2 INCOGNITE CON 2 EQ. SCALARI

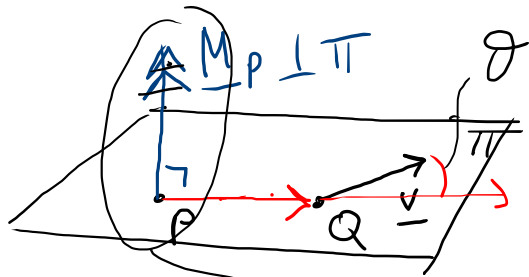
CENNI ALLA TEORIA DEI VETTORI APPLICATI

VETTORE APPLICATO: UNA COPPIA (P, \underline{v}) dove P è un pto nello spazio



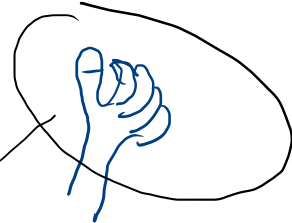
$$P \xrightarrow{\underline{v}} Q \quad (P, \underline{v}) \doteq PQ \quad , \quad |\underline{v}| = \overline{PQ} = |PQ|$$

DEFINIZIONE DI MOMENTO DI UN VETTORE APPLICATO



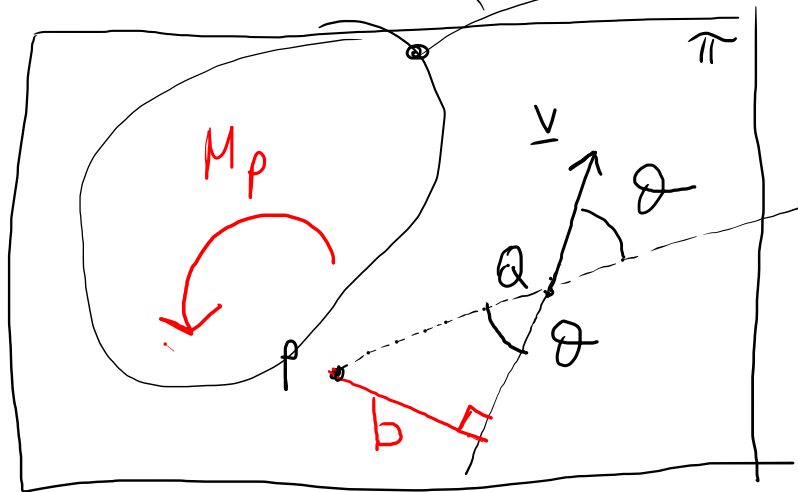
CHIAMO MOMENTO DEL VETTORE (Q, \underline{v})
RISPETTO A P: P: POLO o PUNTO DI RIDUZIONE

$$\underline{M}_{(P)} = \underline{PQ} \times \underline{v}$$



$$|\underline{M}_p| = |\underline{PQ}| |\underline{v}| \sin \theta = |\underline{v}| \cdot b$$

↳ braccio



DISEGNO \underline{M}_p NEL PIANO CON
UNA FRECCIA RICURVA

(ES .

$M_A ? \Rightarrow$



$$M_A = +3 \cdot 2 = 6 \text{ Nm}$$

