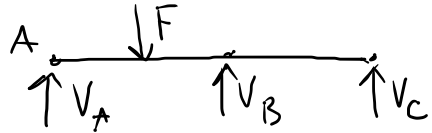
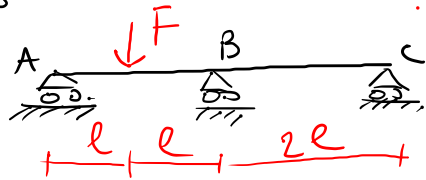


LES



$g=3, v=3, d=2$: STRUTTURAZIONE

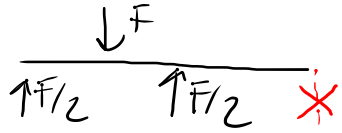
7/4/22

AFFRONTO IL PROBLEMA STATICO

$$\begin{aligned} \rightarrow : 0 &= 0 \quad (\text{IDENTITA'}) \\ +\uparrow : V_A + V_B + V_C - F &= 0 \\ +\curvearrowleft : -F \cdot l + V_B \cdot 2l + V_C \cdot 4l &= 0 \end{aligned}$$

STATICAMENTE
INDETERMINATO

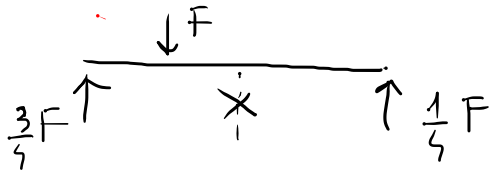
2 EQ. IN 3 INCOGNITE
 \Rightarrow INFINITE SOLUZIONI.



PRIMA SOLUZIONE PROPOSTA

$V_A = \frac{F}{2}, V_B = \frac{F}{2}, V_C = 0$

$$\begin{cases} F + 0 - F = 0 & \text{OK} \\ -F \cdot l + F \cdot l + 0 = 0 & \text{OK} \end{cases}$$



SECONDA SOLUZIONE PROPOSTA

$V_A = \frac{3}{4} F, V_B = 0, V_C = \frac{1}{4} F$

$$\begin{cases} \frac{3}{4} F + 0 + \frac{1}{4} F - F = 0 & \text{OK} \\ -F \cdot l + 0 + \frac{1}{4} F \cdot 4l = 0 & \text{OK} \end{cases}$$

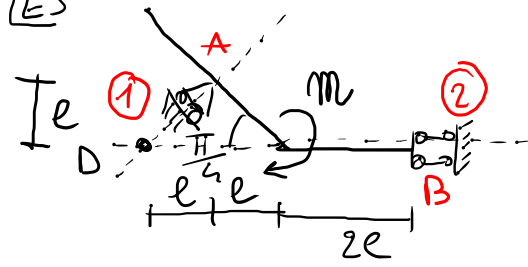
CLASSIFICAZIONE DEI PROBLEMI STATICI (P.S.)

- P.S. STATICAMENTE IMPOSSIBILE : LE EQ. DEL SISTEMA NON SONO SODDISFATTE ; NON ESISTE UNA SOLUZ.
- P.S. " DETERMINATO : \exists UNA SOLUZ. UNICA DEL SIST. DI EQ. DI EQUILIBRIO
- P.S. " INDETERMINATO : \exists INFINITE SOLUZIONI

RELAZIONE TRA P.S. E STRUTTURA

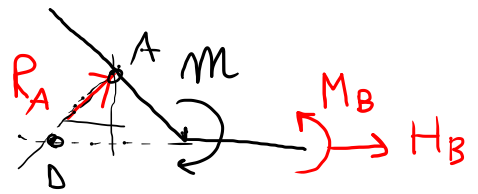
- STR. ISOSTATICA ($q = v = s$) \Rightarrow P.S. STAT. DETERMINATO
- STR. IPERSTATICA ($q = s < v$) \Rightarrow P.S. STAT. INDETERMINATO

LES



$g=3$
 $v=3$
 $s=3$

STR I SOST.



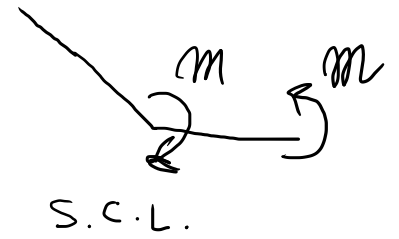
$\rightarrow : + \frac{R_A}{\sqrt{2}} + H_B = 0$

$+\uparrow : + \frac{R_A}{\sqrt{2}} = 0$

$+\curvearrowleft : -M + M_B + H_B e = 0$

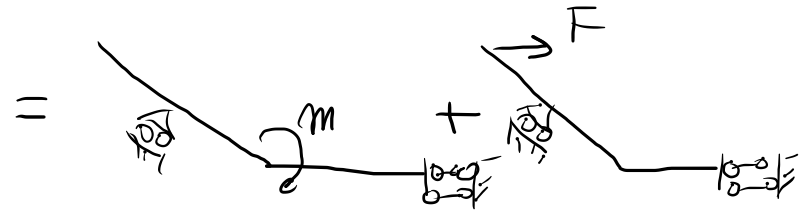
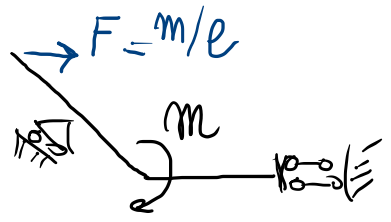
$H_B = 0$
 $R_A = 0$
 $M_B = M$

P.S.
STAT-
DETERM.

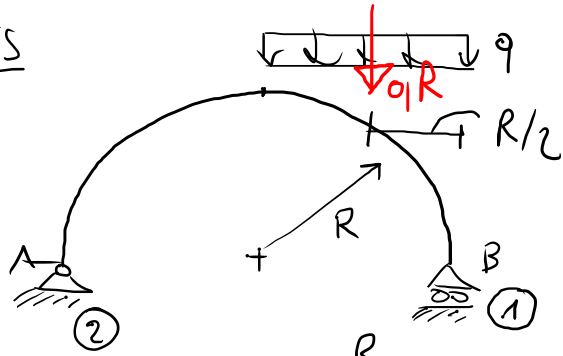


(PROVARE A SOST. QUESTA EQ CON \curvearrowleft)

UNA VARIANTE:



LES

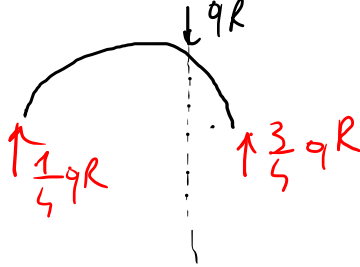
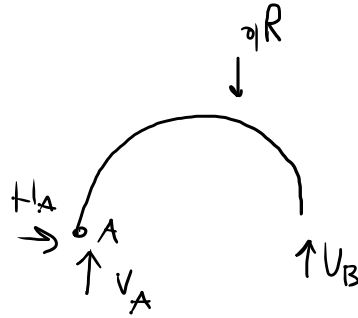


$$q = v = \Delta = 3 \quad \text{---} \quad R$$

$$H_A = 0$$

$$V_B = \frac{3}{2} q R^2 \frac{1}{2R} = \frac{3}{4} q R$$

$$V_A = qR - V_B = \frac{1}{4} q R$$



$$\begin{aligned} \rightarrow & : H_A = 0 \\ \uparrow & : V_A - qR + V_B = 0 \\ \leftarrow & : -qR \frac{3}{2} R + V_B 2R = 0 \end{aligned}$$

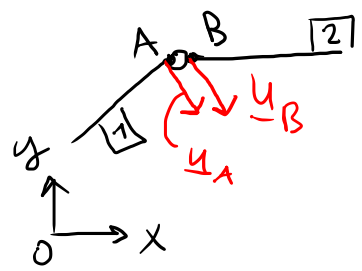
S.C.L.

VINCOLI INTERNI

$\nu=3$: VINCOLO TRIPLO (INCASTRO INTERNO) : È LA CONTINUITÀ MATERIALE TRA DUE SEZIONI UNA TRAVE



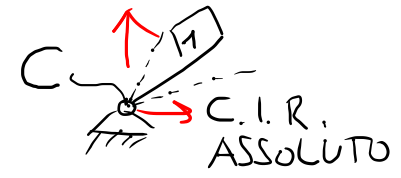
$\nu=2$: CERNIERA INTERNA



$u_A = u_B$

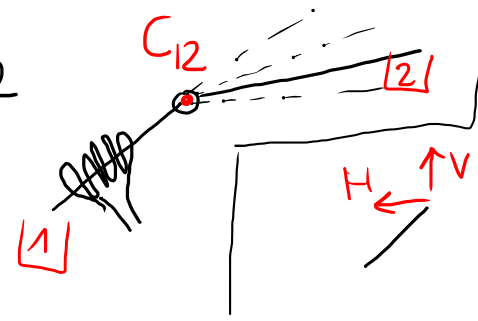
EQ. CINEMATICA
(σ DI VINCOLO)

$$\begin{cases} u_{Ax} = u_{Bx} \\ u_{Ay} = u_{By} \end{cases}$$



$\theta_1 \neq \theta_2$

C.I.R. RELATIVO C_{12}
È IL PUNTO CERNIERA

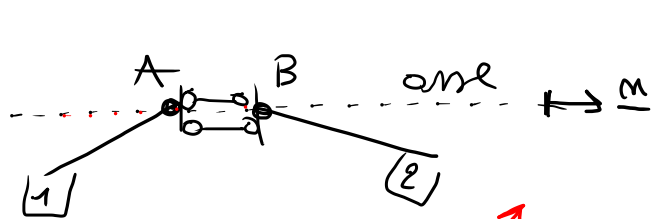


DAL PUNTO STATICO:

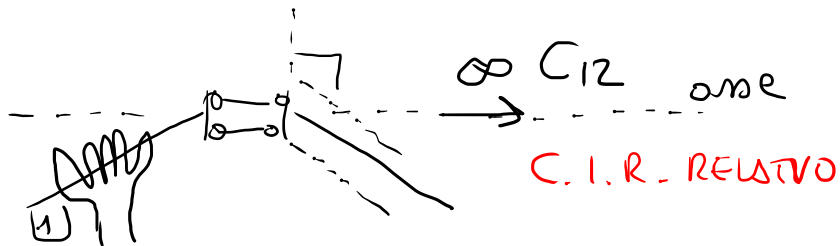
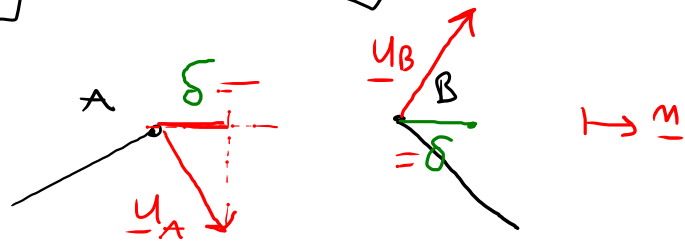
REAZ - INTERNE



$v=2$; DOPPIO-PENDOLO INTERNO



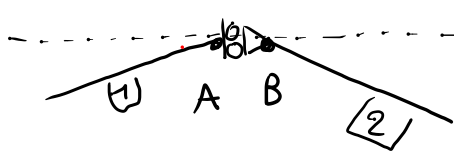
$$\begin{cases} u_A \cdot M = u_B \cdot M \\ \theta_1 = \theta_2 \end{cases}$$



PRESTA? - STATICA

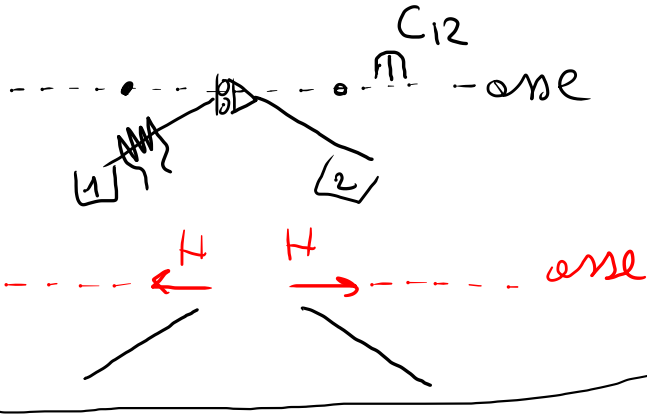
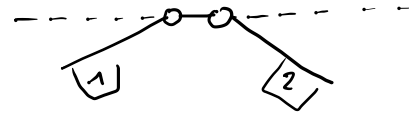


$v=1$: CORRELLIO INTERNO (PENDELO / BIELLA INTERNO(A))



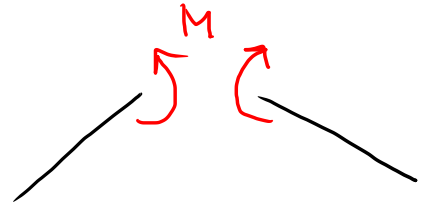
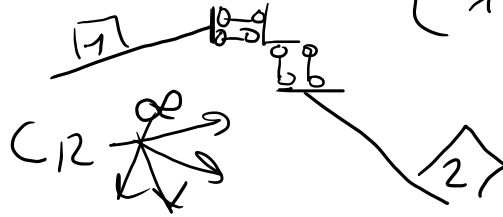
asse $\rightarrow \omega$

$$\left\{ \begin{aligned} \underline{u}_A \cdot \underline{M} &= \underline{u}_B \cdot \underline{M} \end{aligned} \right.$$



$v=1$: DOPPIO-DOPPIO PENDELO INTERNO

$$\left\{ \theta_1 = \theta_2 \right.$$

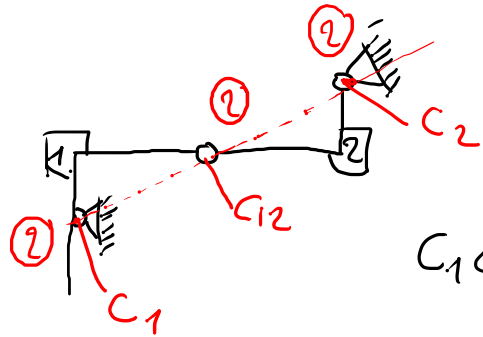


Lo studio della cinematica di 2 C.R. mutuamente vincolati coinvolge 3 CENTRI DI ROTAZIONE: i 2 CENTRI ASSOLUTI (C_1, C_2) e QUELLO RELATIVO (C_{12}).

PROPRIETA': Condiz. Necessarie affinché avvenga un moto relativo tra 2 C.R. è che i CENTRI C_1, C_2 siano allineati con C_{12} .

$$\underline{C_1} \Leftrightarrow \underline{C_{12}} \Leftrightarrow \underline{C_2}$$

ES. IL CASO DI 3 CERNIERE ALLINEATE



$$q = 3 \cdot 2 = 6$$

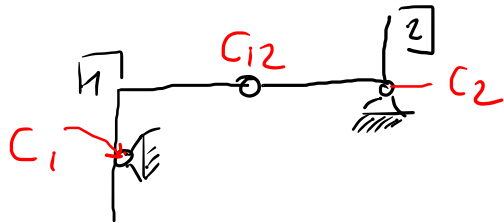
$$v = 6$$

$$\Delta = 5$$

VINCOLI MAL DISPOSTI

$C_1 \leftrightarrow C_{12} \leftrightarrow C_2 \Rightarrow$ c'è moto relativo
e la STR. È LABILE ($\Delta = 5$)

Prima veduto le possibilità di esistenza dei centri osservando i vincoli interni ed esterni. Poi verifico l'eventuale allineamento.



NON C'È L'ALLINEAMENTO

$\Rightarrow \Delta = 6$ (VINCOLI BEN DISPOSTI)

STR ISOST.

