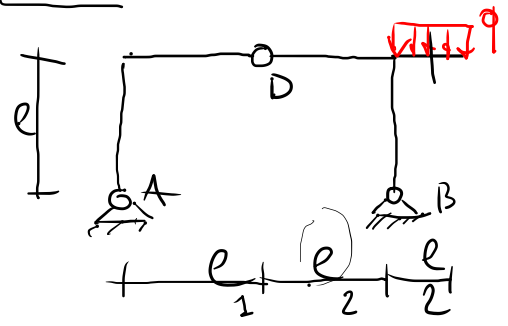


19/5/22

ES PLV

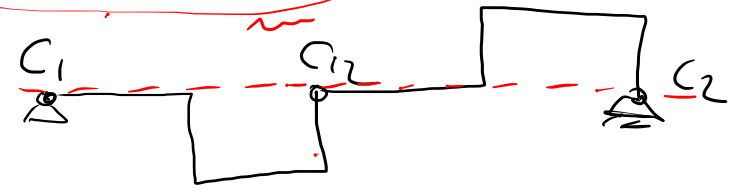


C. REATIVO

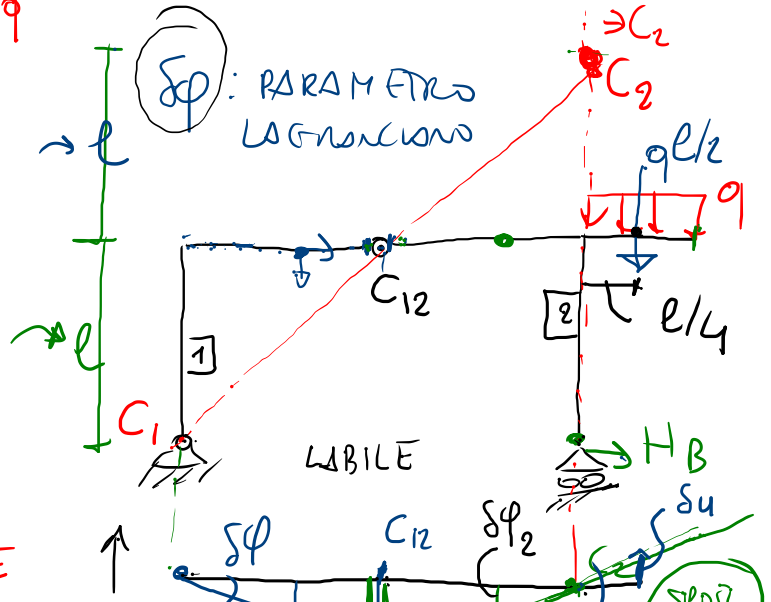
C_1, C_2, C_{12}

IL TEOREMA DELLE COORDINATE CINEMATICHE

$C_1 \leftrightarrow C_{12} \leftrightarrow C_2$



H_B CON IL PLV



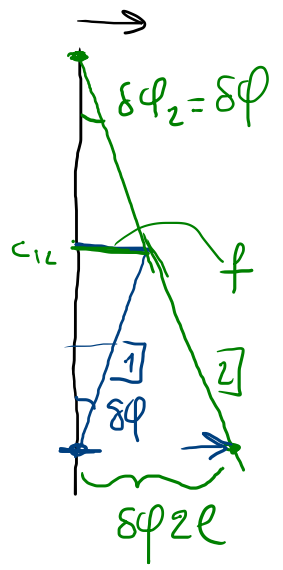
$\delta\phi$: PARAMETRO LOGNOMICO

LABILE

$d = \delta\phi l_1 = \delta\phi_2 l_2$

$\delta\phi_2 = f / \delta\phi$

$\delta\phi_2 = \delta\phi$



SPOST. ORIZZ.

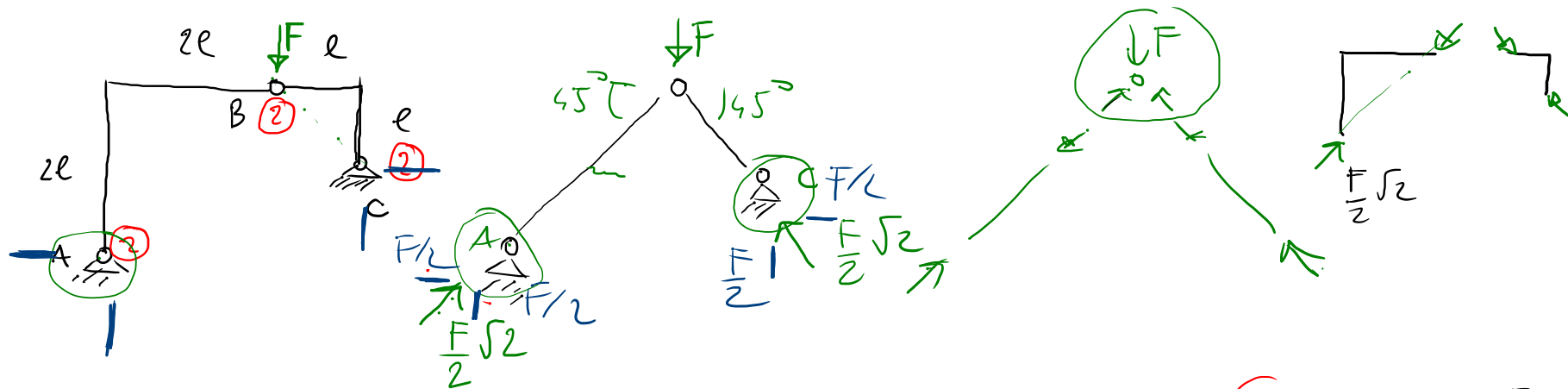
$f = \delta\phi l$
 $\delta\phi l$
 $\delta\phi$

$\delta L = 0 \Rightarrow H_B$

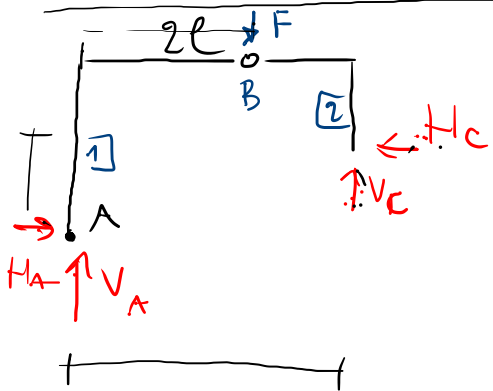
$-\frac{q l}{2} (\delta\phi \frac{l}{4}) + H_B \delta\phi_2 l_2 = 0$

$-\frac{q l}{8} = -2 H_B \Rightarrow H_B = + \frac{q l}{16}$

ARCO A TRE CARNIERE CON CARNIERA INTERNA CORICATA

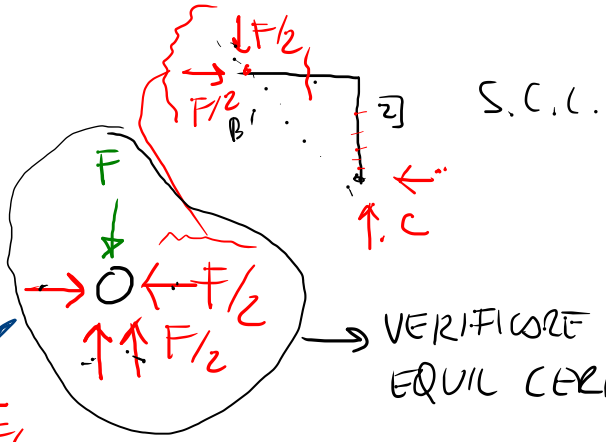
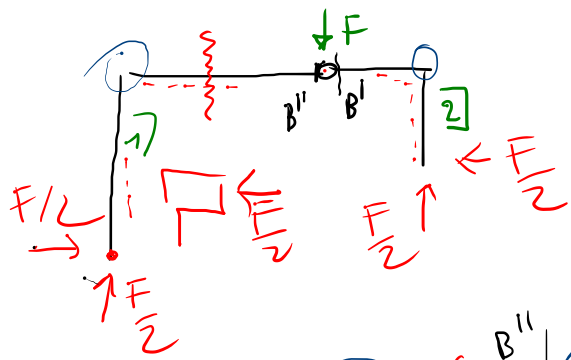


STUDIO CON EQ' AUSILIARIA



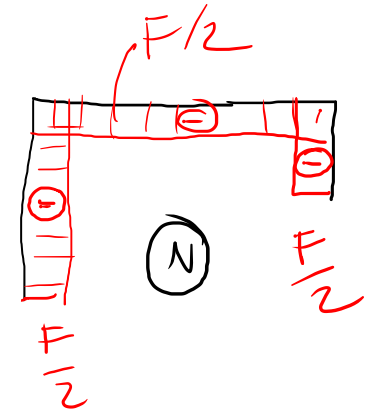
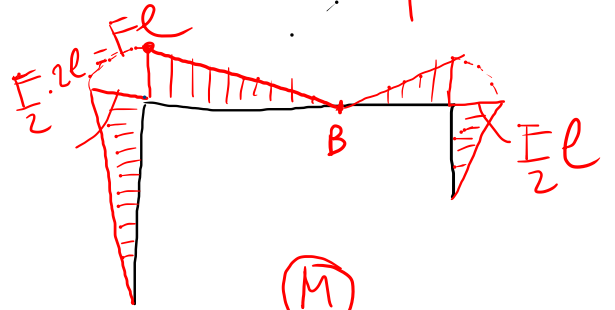
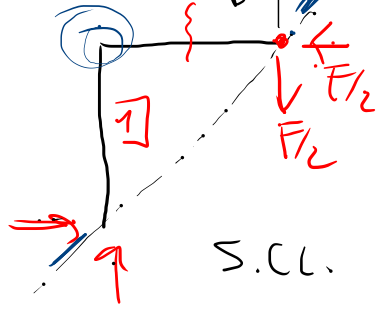
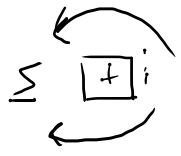
$$\left. \begin{aligned}
 +\rightarrow : +H_A - H_C &= 0 \\
 +\uparrow : +V_A - F + V_C &= 0 \\
 +\curvearrowright : -F \cdot 2l + H_C \cdot l + V_C \cdot 3l &= 0 \\
 +\leftarrow : V_C \cdot l - H_C \cdot l &= 0
 \end{aligned} \right\} \begin{array}{l} \text{[1] + [2]} \\ \text{EQ AUSIL.} \end{array}$$

$$\left. \begin{aligned}
 V_C &= \frac{2Fl}{4l} = \frac{+F}{2} = H_C \\
 H_A = H_C &= \frac{+F}{2} \\
 V_A = F - V_C &= \frac{+F}{2}
 \end{aligned} \right\}$$

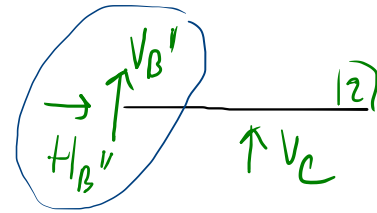
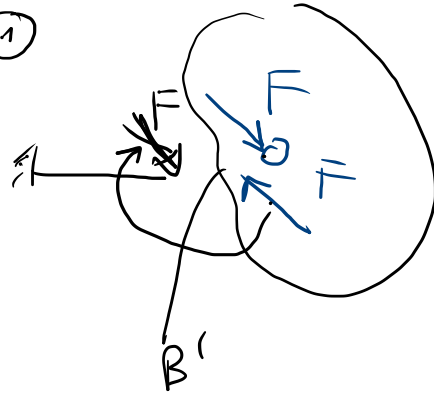
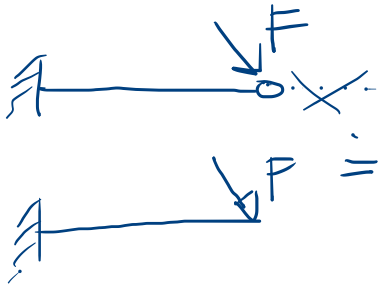
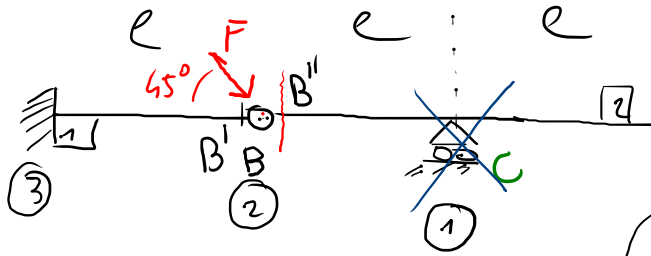


VERIFICARE
EQUIL CARNIERA

OK!

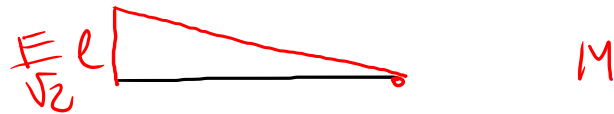
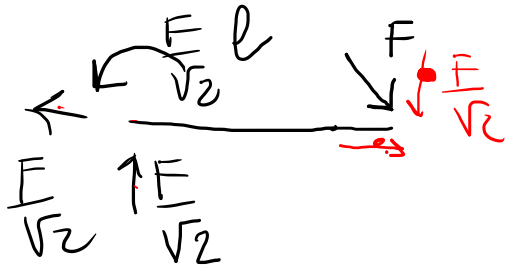


LES

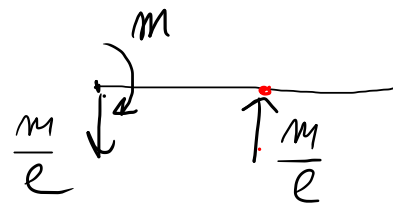
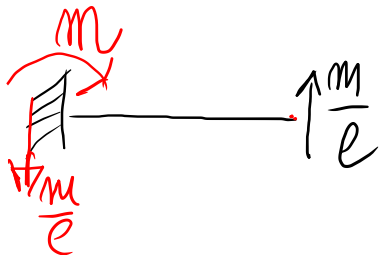
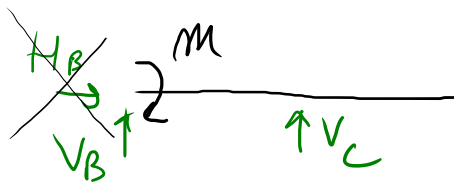
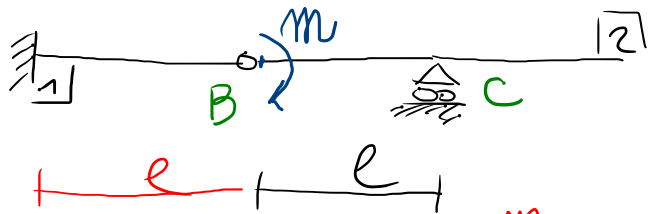


NO CARICHI
NO REAZIONI

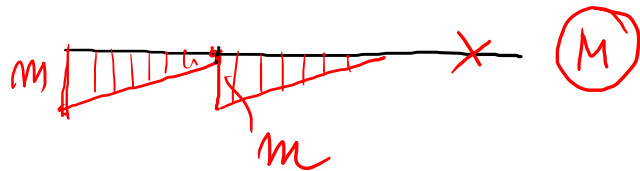
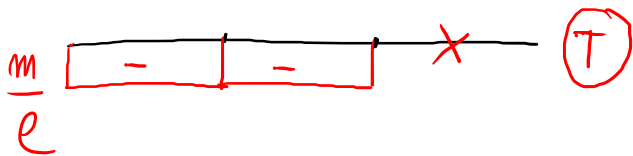
$$\begin{cases} H_{B''} = 0 \\ V_C + V_{B''} = 0 \\ V_C = 0 \end{cases}$$



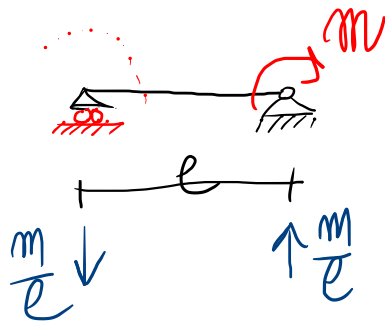
ES



B



UN ULTERIORE SCHEMA DA SAPERE A MEMORIA

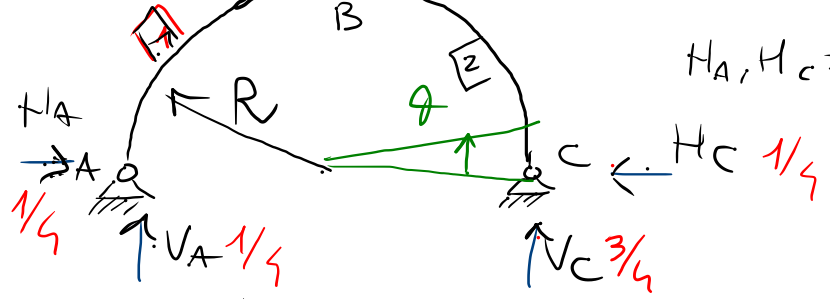


ES.



EQUIL. e DIAGR CDS

$H_A, H_C \Rightarrow$ SPINTA



$$\rightarrow +H_A - H_C = 0$$

$$\uparrow + V_A - qR + V_C = 0$$

$$A) \uparrow - qR \cdot \frac{3}{2}R + V_C \cdot 2R = 0$$

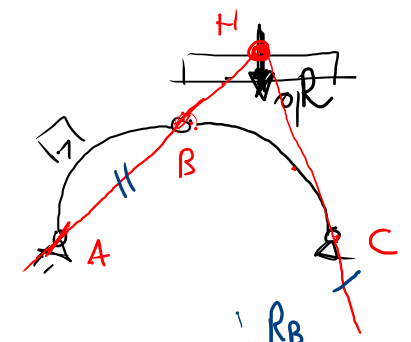
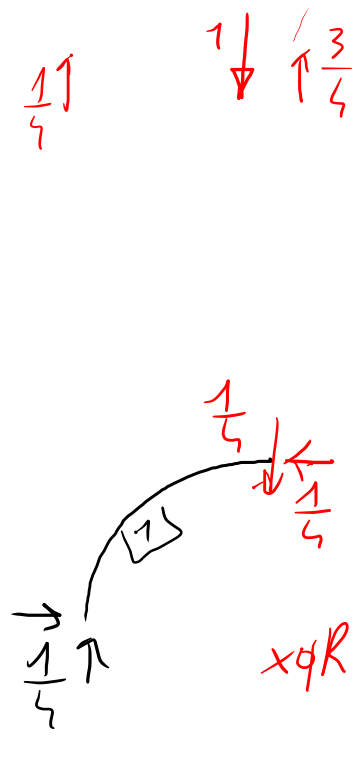
$$\uparrow B) : -V_A R + H_A R = 0 \quad \text{eq. AUSIL.}$$

$$V_C = qR \frac{3}{4}$$

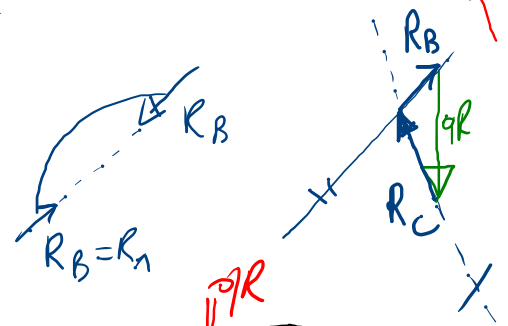
$$H_A = \frac{1}{4} qR$$

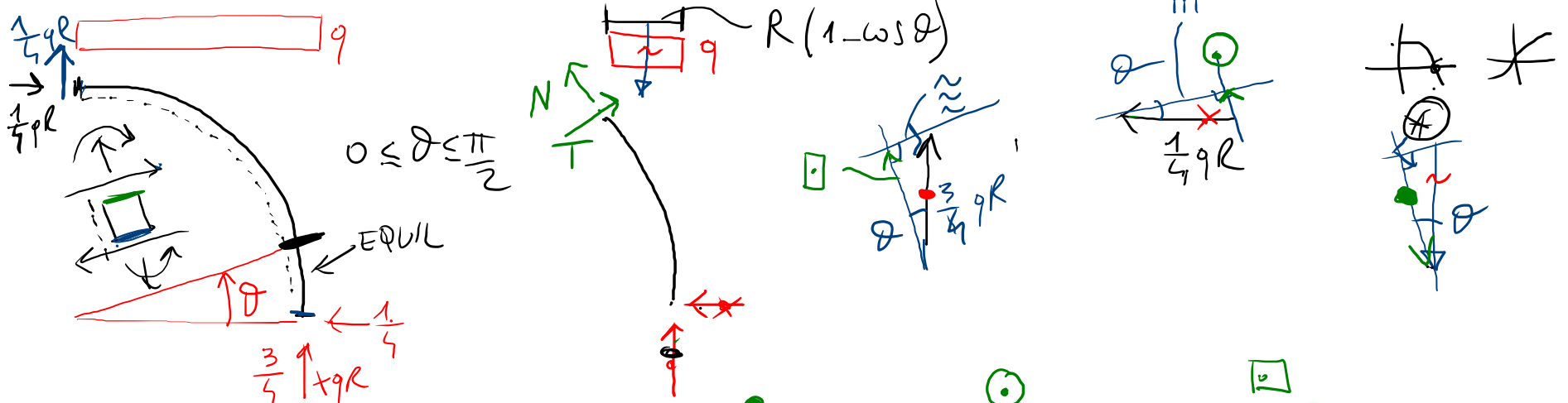
$$V_A = \frac{1}{4} qR$$

$$H_C = \frac{1}{4} qR$$



P. FORTE CORPO [2]





$\uparrow (N) : +N - qR(1-\cos\theta)\cos\theta + \frac{1}{4}qR\sin\theta + \frac{3}{5}qR\cos\theta = 0$

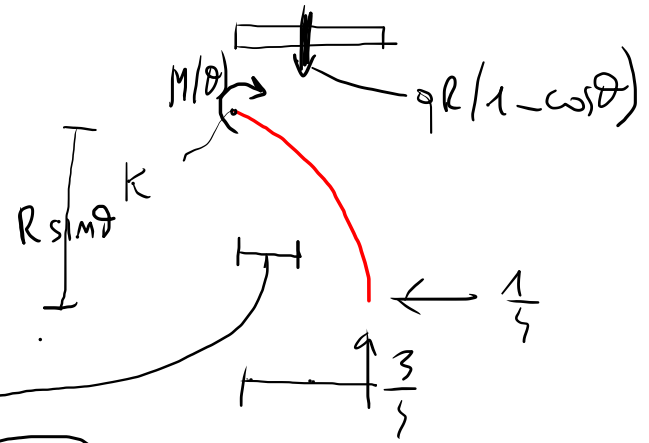
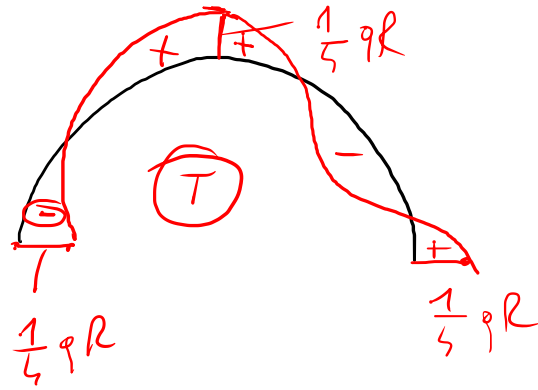
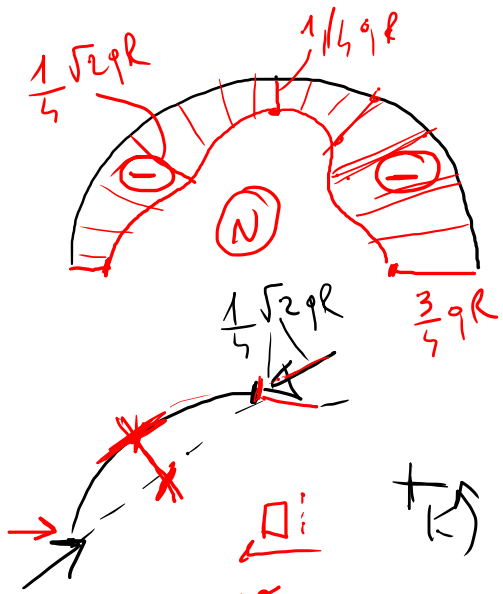
$N(\theta) = qR(1-\cos\theta)\cos\theta - \frac{1}{4}qR\sin\theta - \frac{3}{5}qR\cos\theta ; N(0) = -\frac{3}{4}qR \text{ [OK]}$

$N(\pi/2) = -\frac{1}{4}qR \text{ [OK]}$

$\rightarrow (T) : +T - qR(1-\cos\theta)\sin\theta - \frac{1}{4}qR\cos\theta + \frac{3}{4}qR\sin\theta = 0$

$T(\theta) = qR(1-\cos\theta)\sin\theta + \frac{1}{4}qR\cos\theta - \frac{3}{5}qR\sin\theta \rightarrow T(0) = +\frac{1}{4}qR$
 $\rightarrow T(\pi/2) = qR - \frac{3}{4}qR = +\frac{1}{4}qR$

[OK] [OK]

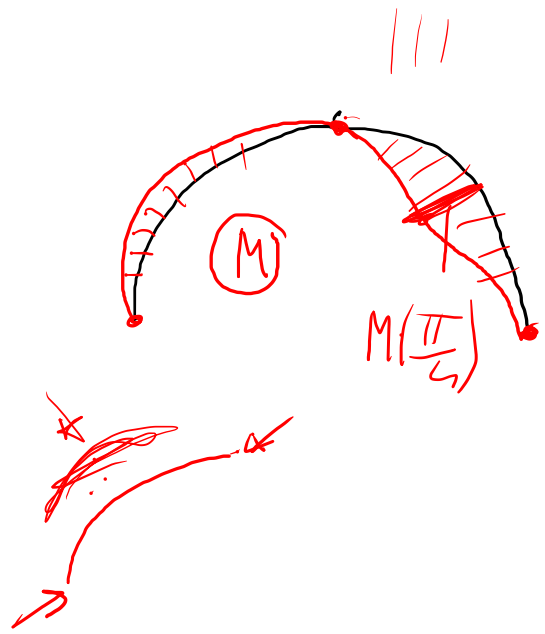


$$\begin{aligned}
 \uparrow (+) : -M(\theta) - qR(1-\cos\theta) \cdot \frac{R}{2}(1-\cos\theta) - \frac{1}{4}qR \cdot R \sin\theta \\
 + \frac{3}{4}qR \cdot R(1-\cos\theta) = 0
 \end{aligned}$$

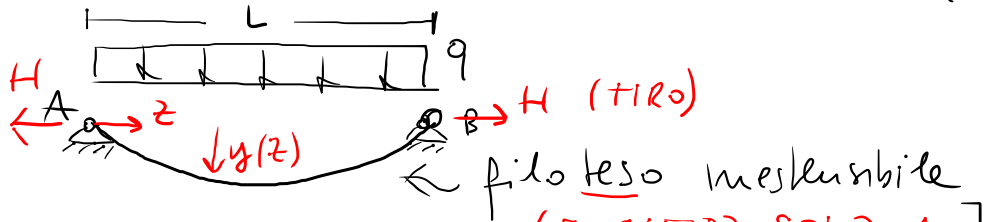
$$M(\theta) = -\frac{qR^2}{2}(1-\cos\theta)^2 - \frac{1}{4}qR^2 \sin\theta + \frac{3}{4}qR^2(1-\cos\theta)$$

$$M(0) = 0 \rightarrow 0 \quad \text{OK}$$

$$M\left(\frac{\pi}{2}\right) = 0 \rightarrow -\frac{2}{4}qR^2 - \frac{1}{4}qR^2 + \frac{3}{4}qR^2 = 0$$



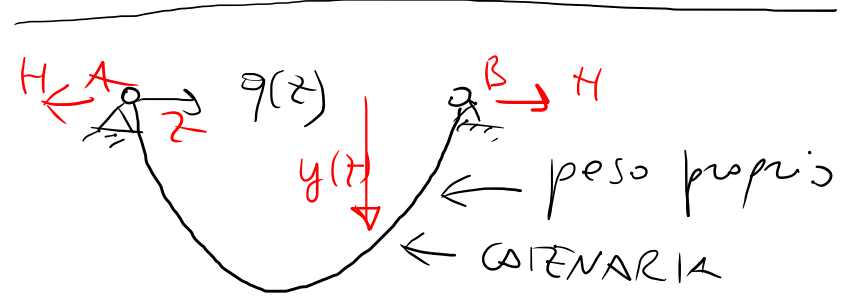
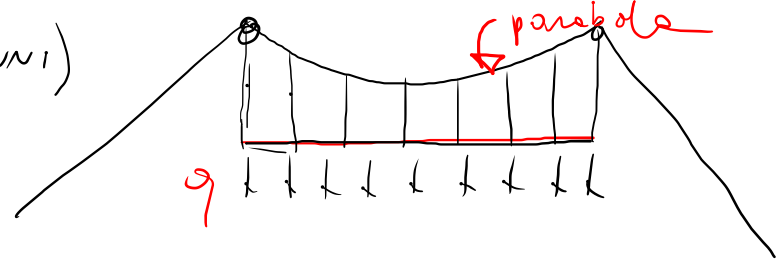
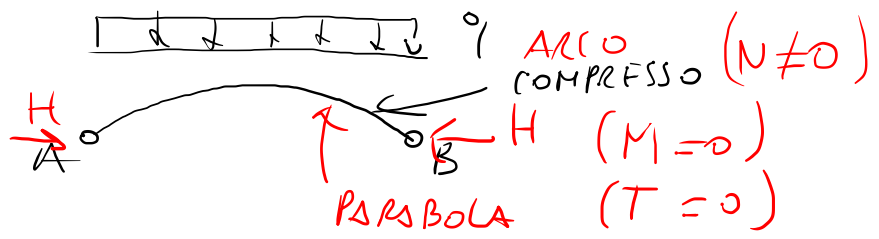
STRUTTURE FUNICOLARI DEL CARICO (CENNI)



$$y''(z) = \frac{q}{H} \left. \begin{array}{l} \text{cost.} \end{array} \right\}$$

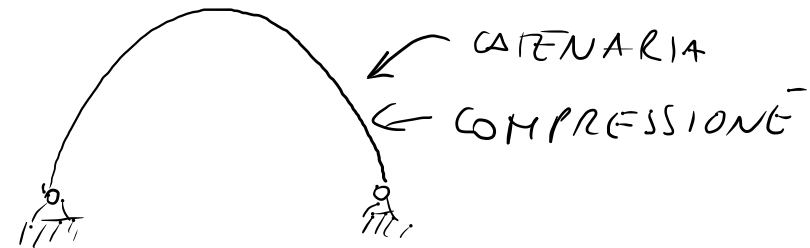
$$y(0) = 0; y(L) = 0$$

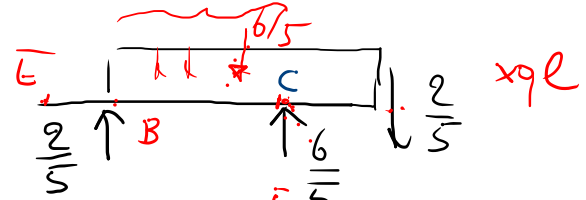
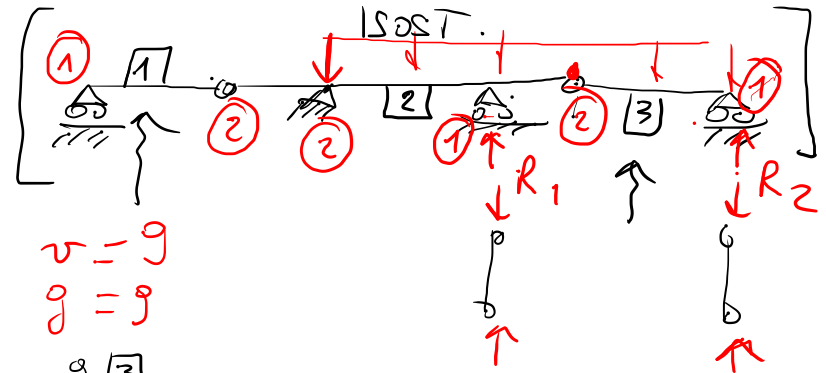
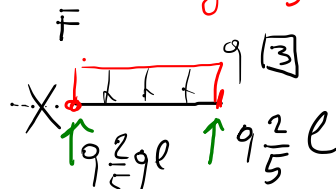
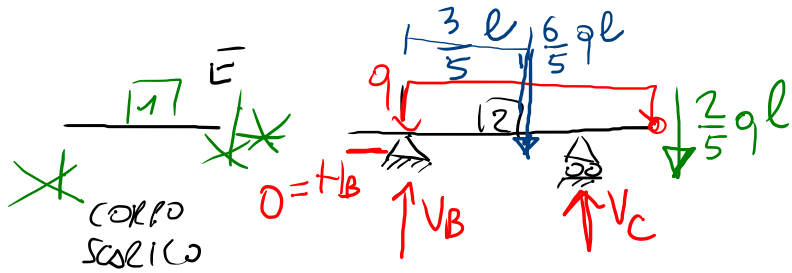
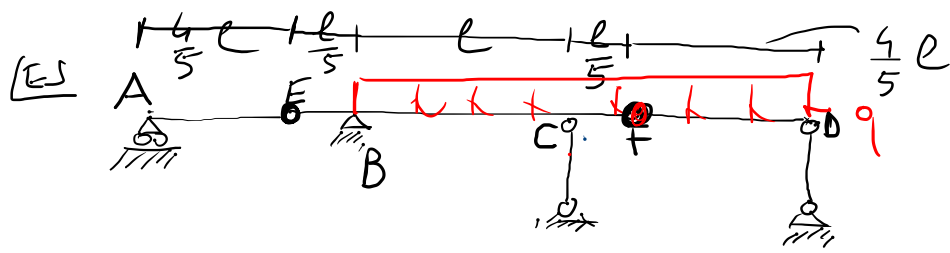
$y(z) \Rightarrow$ PARABOLA



γ : PESO PER UNITA' DI LUNGHEZZA

$$y(z) = \frac{H}{\gamma} \cosh\left(\frac{\gamma}{H} z - c_1\right) + c_2$$



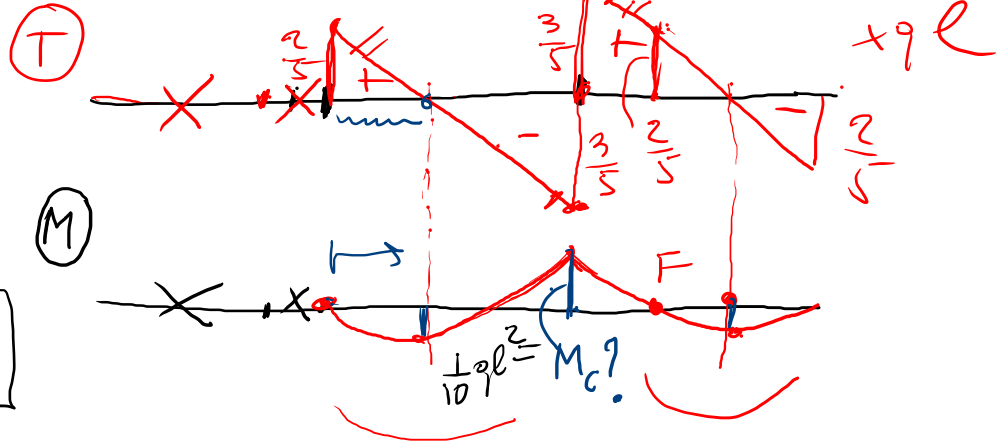


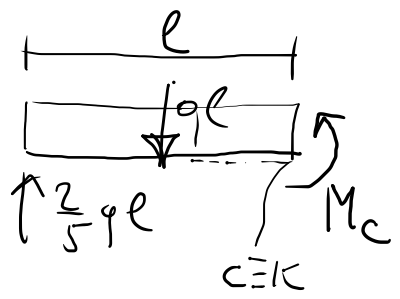
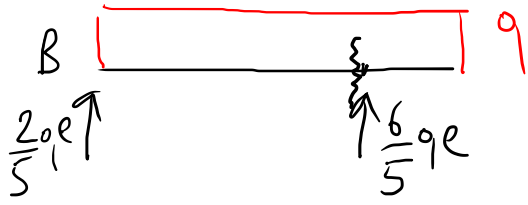
EQUIL. CORPO [2]

$$\uparrow + : V_B - \frac{6}{5}ql + V_C - \frac{2}{5}ql = 0$$

$$\curvearrowright B : -\frac{6}{5}ql \cdot \frac{3}{5}l + V_C l - \frac{2}{5}ql \cdot \frac{6}{5}l = 0$$

$$\boxed{V_C = \frac{6}{5}ql} \quad V_B = \frac{8}{5}ql - V_C = \frac{2}{5}ql$$





$$\sum \uparrow^+ : -\frac{2}{5}ql \cdot l + ql \frac{l}{2} + M_c = 0$$

$$M_c = \left(\frac{2}{5} - \frac{1}{2} \right) ql^2 = \frac{4-5}{10} = -\frac{1}{10} ql^2$$

