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335 211609

INDUSTRIAL PLANTS II

Chapter one ó part 2:

Lean manufacturing

KAIZEN

DOUBLE DEGREE MASTER IN

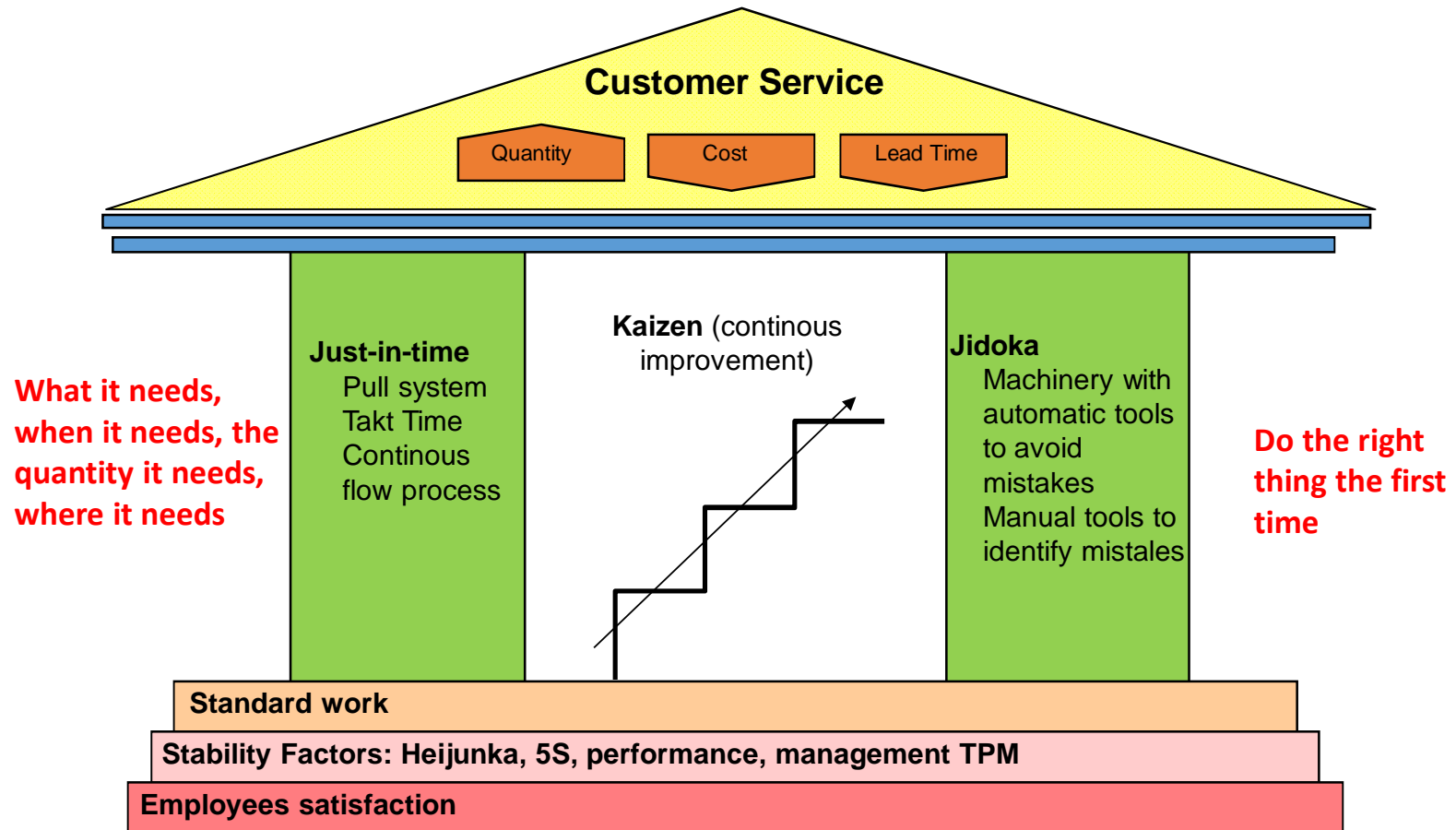
òPRODUCTION ENGINEERING AND MANAGEMENTö

CAMPUS OF PORDENONE

UNIVERSITY OF TRIESTE



Il Toyota Production System





TECHNIQUES AND TOOLS				7 TOOLS	CORRELATION	
					PARETO'S DIAGRAM	
					ISTOGRAMS	
					CONTROL CHARTS	
					ISHIKAWA DIAGRAM	
				ONE POINT LESSON		
				A3	5 WHYS	
				KEY PERFORMANCE INDICATORS		
				5 S		
				YAMAZUMI	ANDON	FLASH MEETINGS
				TAKT TIME	VISUAL MANAGEMENT	GROUP WORK
			ERGONOMY	KANBAN	STANDARDIZATION	EMPOWERMENT
			TPM	KAIKAKU	PDCA	INVOLVEMENT
			SMED	JIT	POKAYOKE	AGREEMENT
	QUALITY FUNCTION DEPLOYMENT	SPAGHETTI CHART	OEE	HEIJUNKA	KAIZEN	INFORMATION
	WASTES	LABOUR TIMES STUDY	ONE PIECE FLOW	FROM PUSH TO PULL	SIX SIGMA	COMMUNICATION
	HOSHIN KANRI	CURRENT VMS	FUTURE VSM	PULL	JIDOKA	MOTIVATION RESEARCH
PRINCIPLES	DEFINE THE VALUE	IDENTIFY THE VALUE FLOW	SET UP FLOW ACTIVITIES	MANUFACTURE PULLING THE PRODUCTION	RESEARCH PERFECTION	ATTENTION TO PEOPLE
FOCUS	CUSTOMER			QUALITY	EMPLOYEES	

FLOW

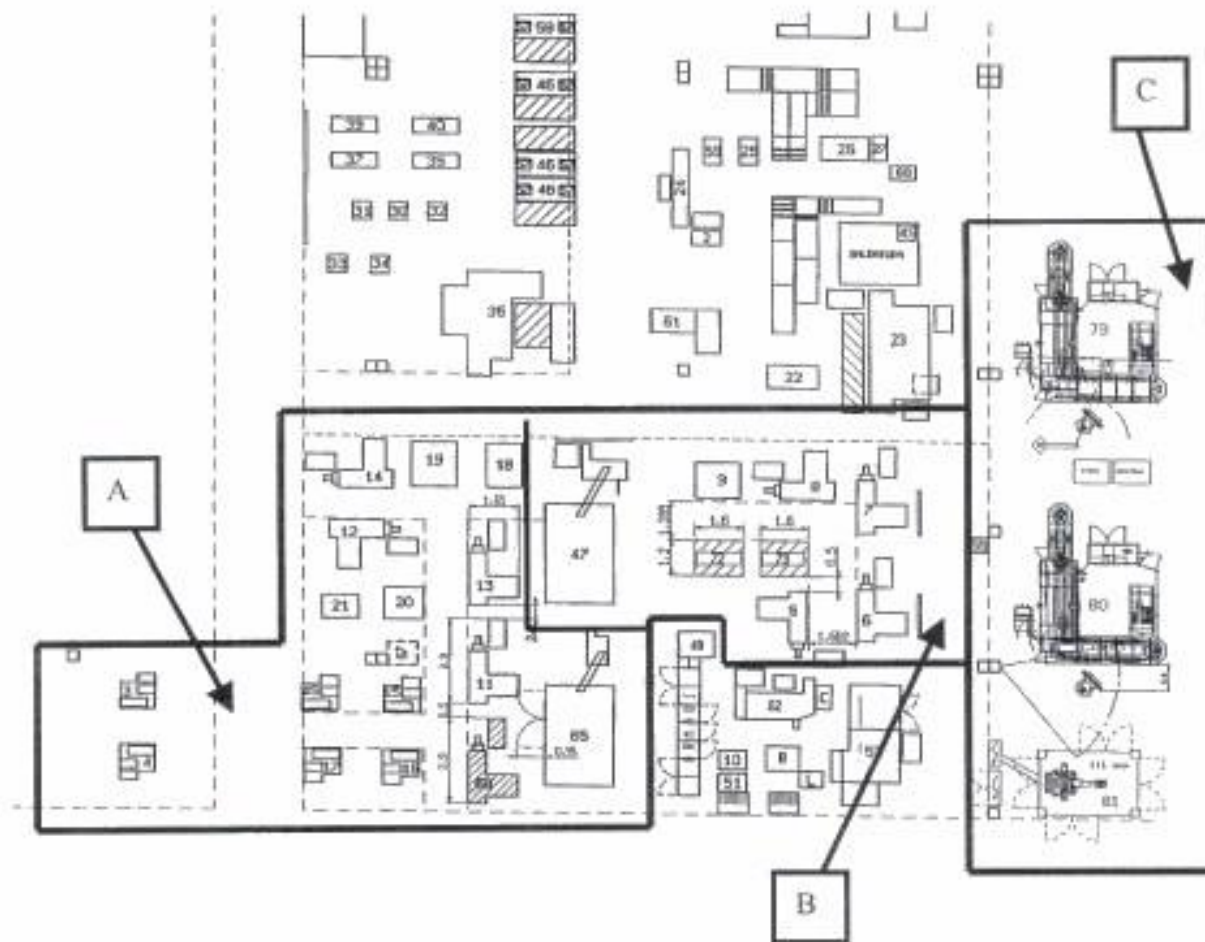
It is the set of activities / information related to the transformation of materials that are necessary to get the final products, in the way that the company decide suitable for achieving its goals.



“Simplify, and the products will flow like water”

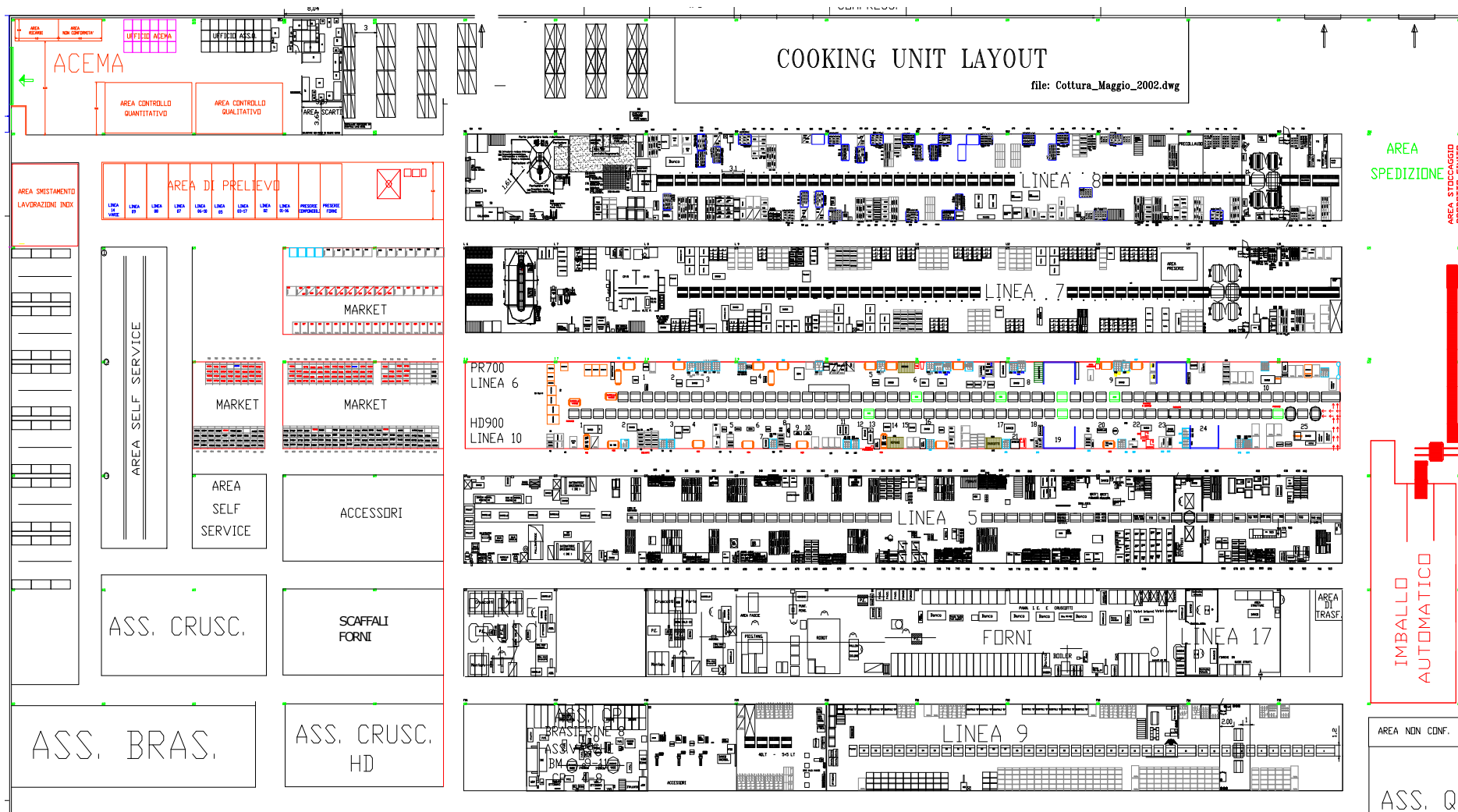


LAY-OUT TYPE A



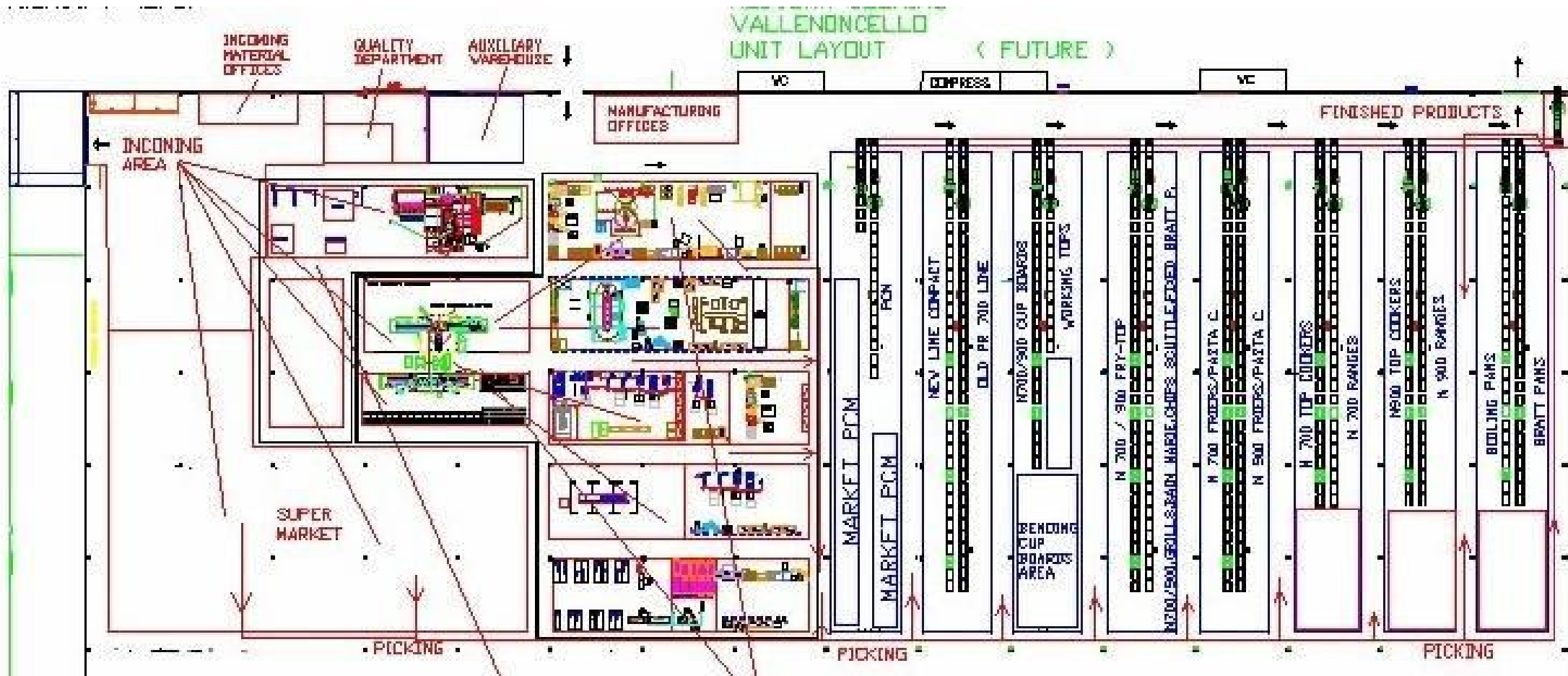


LAY-OUT TYPE B

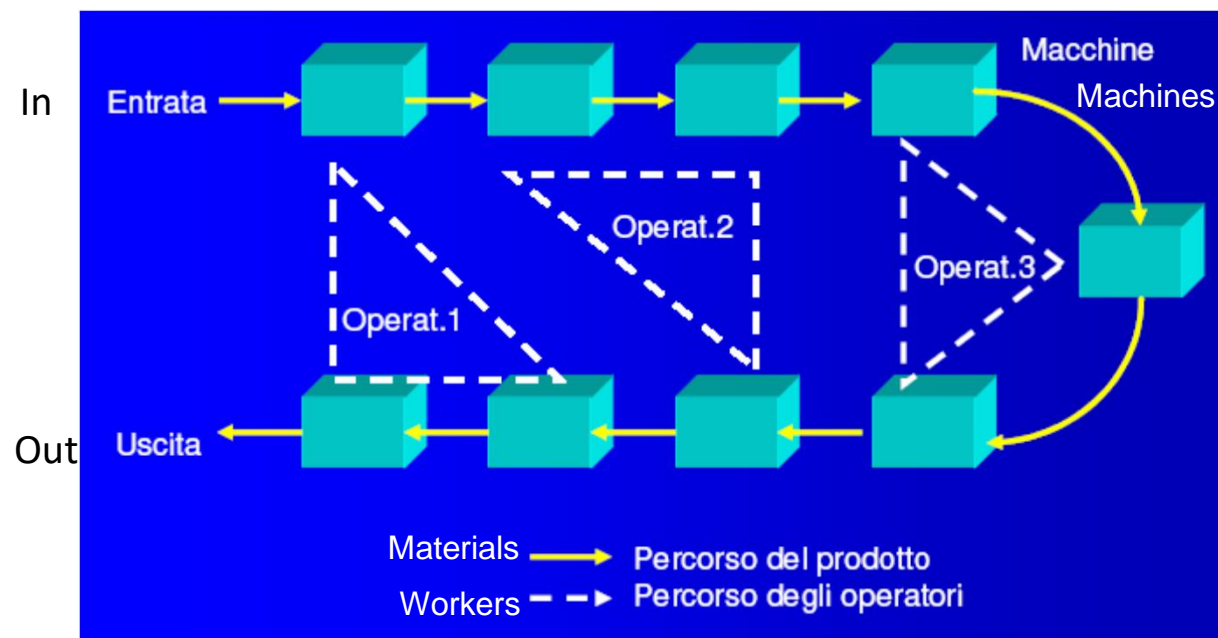


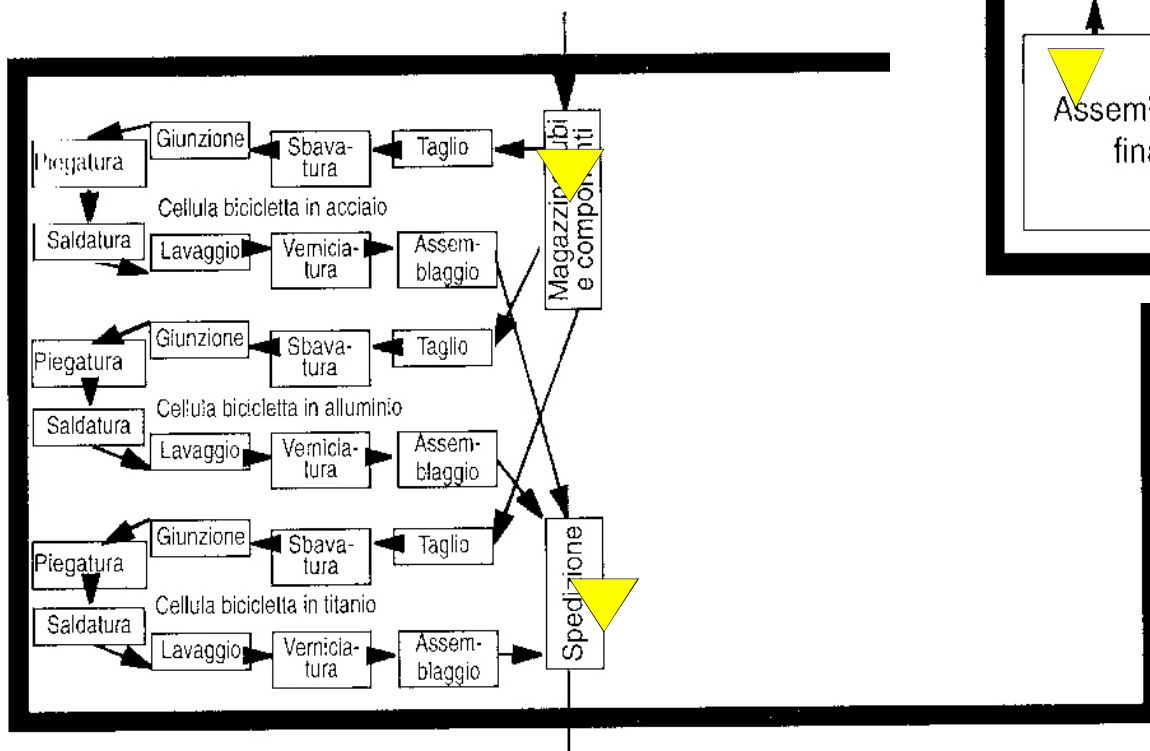
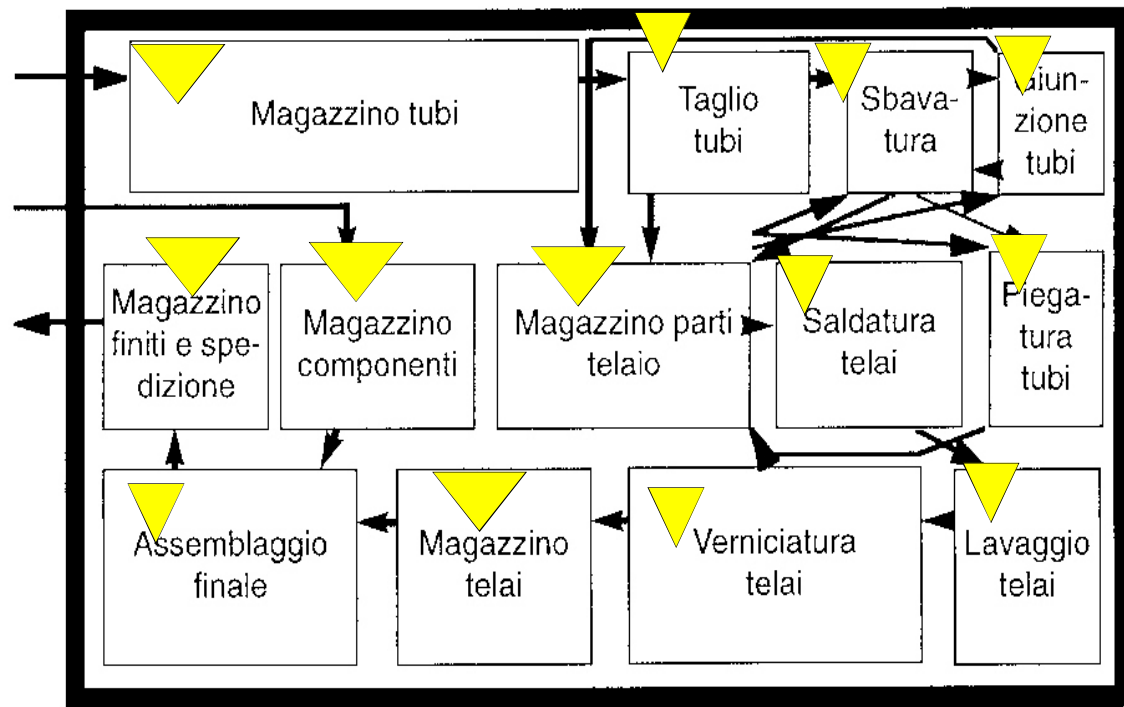


LAY-OUT TYPE B



Flow line or U-shaped





VALUE STREAM MAPPING

VSM is a graphical tool ideal for complete process mapping

It is used to identify and mark the processes, material flows and information of certain products

The VSM is very useful in gathering information and viewing problems and possible improvements

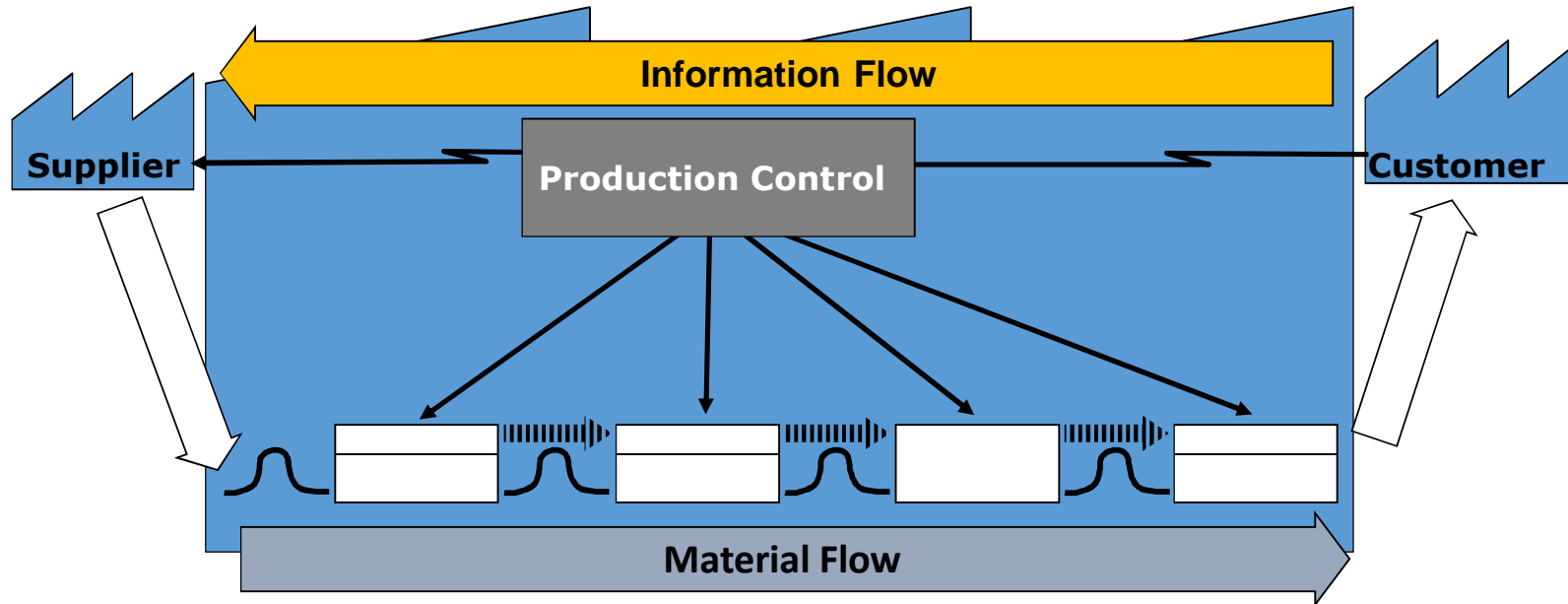
The VSM of the Current State is used to provide an overall representation of the process as it is and to identify possible improvements

The VSM of the Future State helps to understand what the target final state should be and how to implement it

The VSM is a diagram represented on a single page

The VSM is made by using standard symbols

VALUE STREAM MAPPING

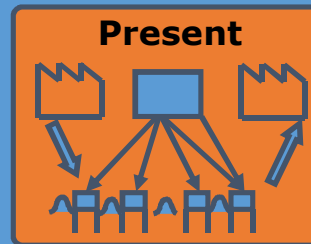


It provide a representation of the present process «from the beginning to the end» and its performance levels
A set of symbols are used to represent all the element ofthe present process

VALUE STREAM MAP: PRESENT AND FUTURE

Present state: AS IT IS (value stream analysis)

Analysis
thorough and
fact-based



Reason

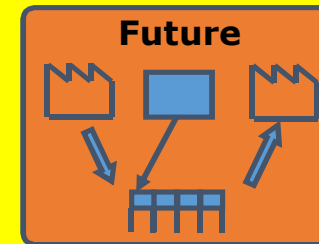
- It provides a visual description of the present value stream

Objectives

- Show the current system as a whole
- Highlight wastes and their sources throughout the process
- Identify opportunities for improvement
- Provide a common picture to discuss problems and changes

Future State: AS TO BE (value stream design)

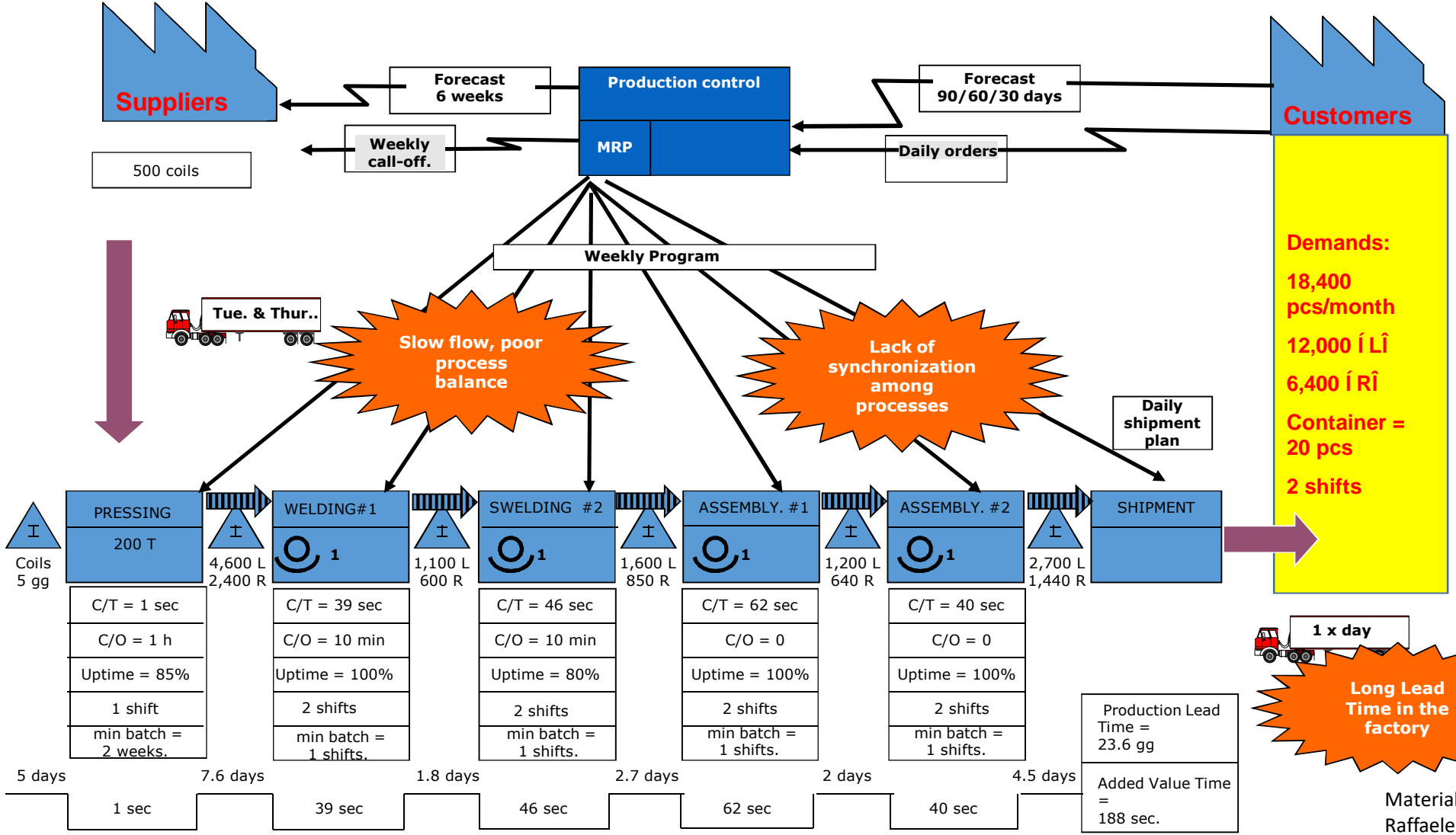
Design
creative and
synthetic



- It provides a visual description of the future redesigned value stream

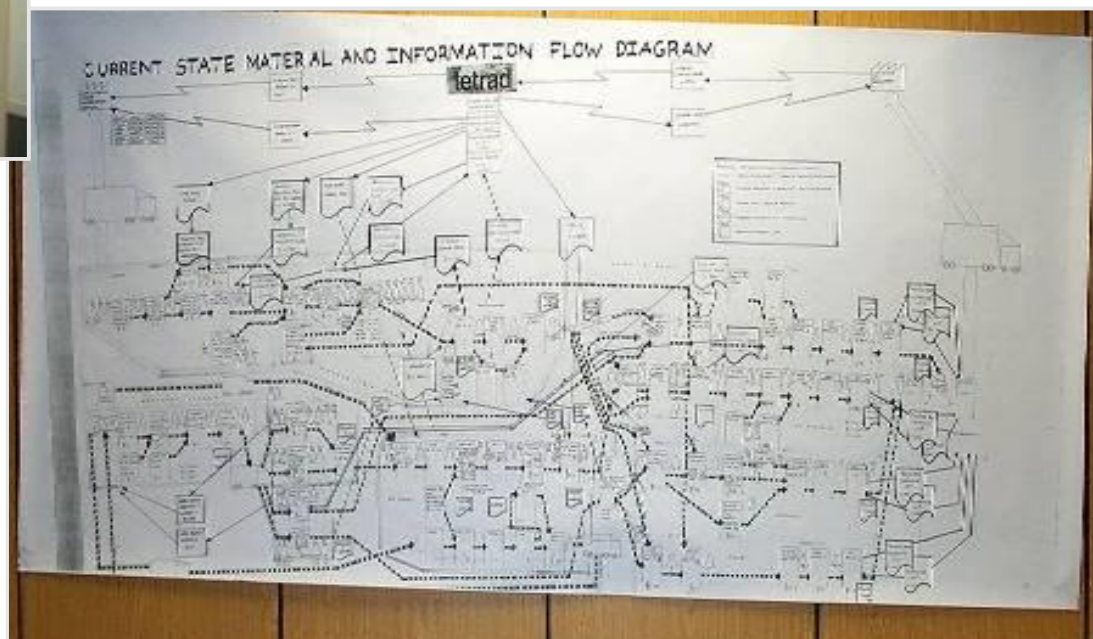
- Push for the use of best practices to create the vision of the ideal value flow in "Lean" terms
- Be helpful in quantifying the potential improvement
- Be used as a communication tool of the Future Situation

CURRENT VALUE STREAM MAPPING

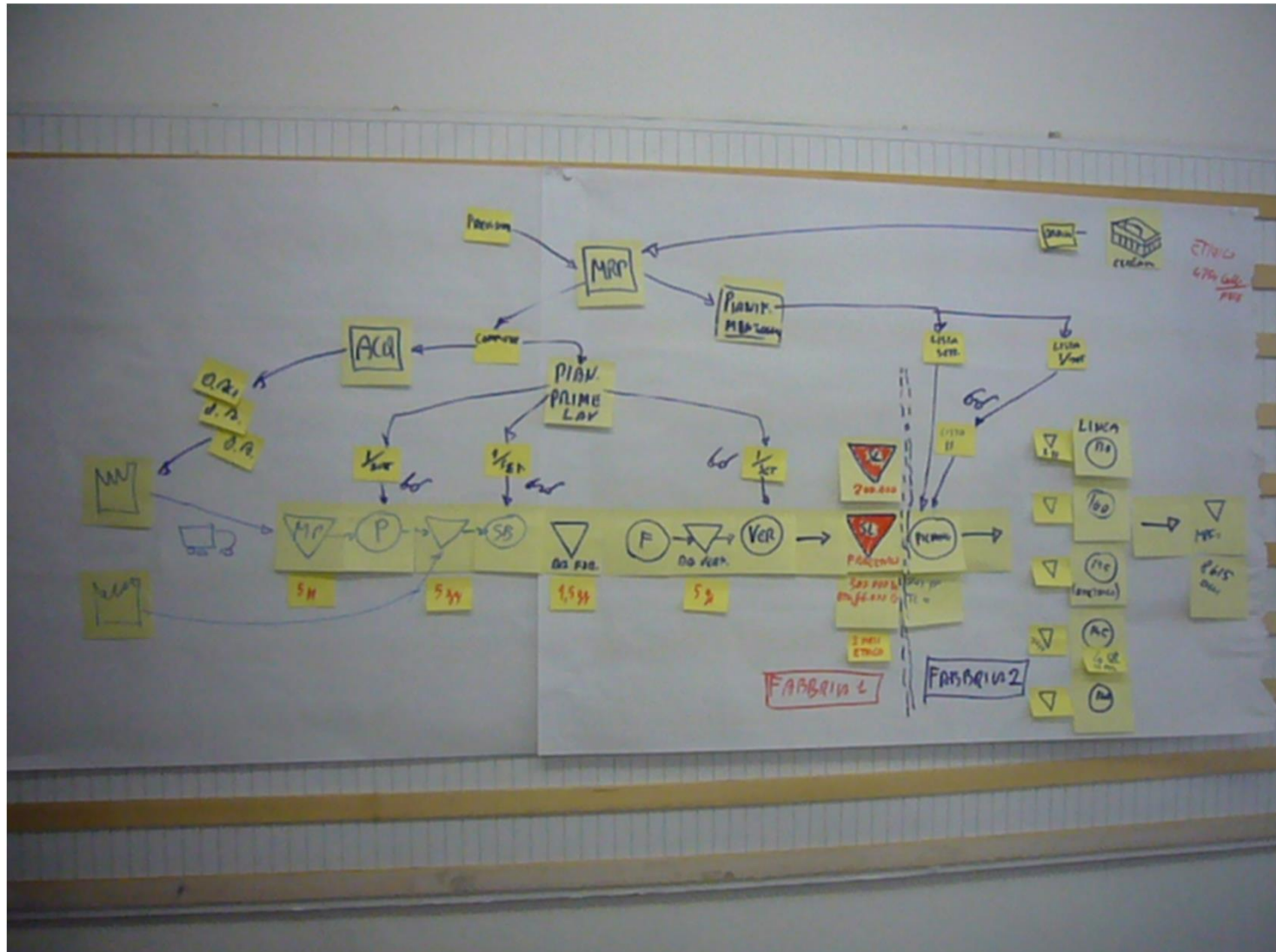




VALUE STREAM MAPPING



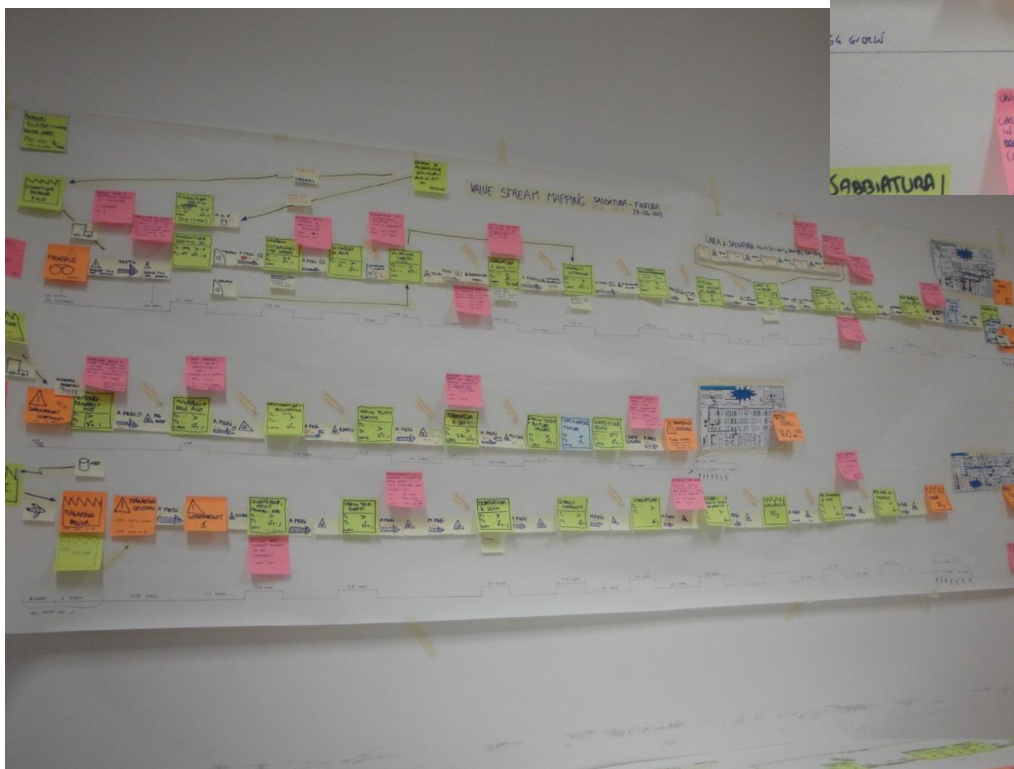
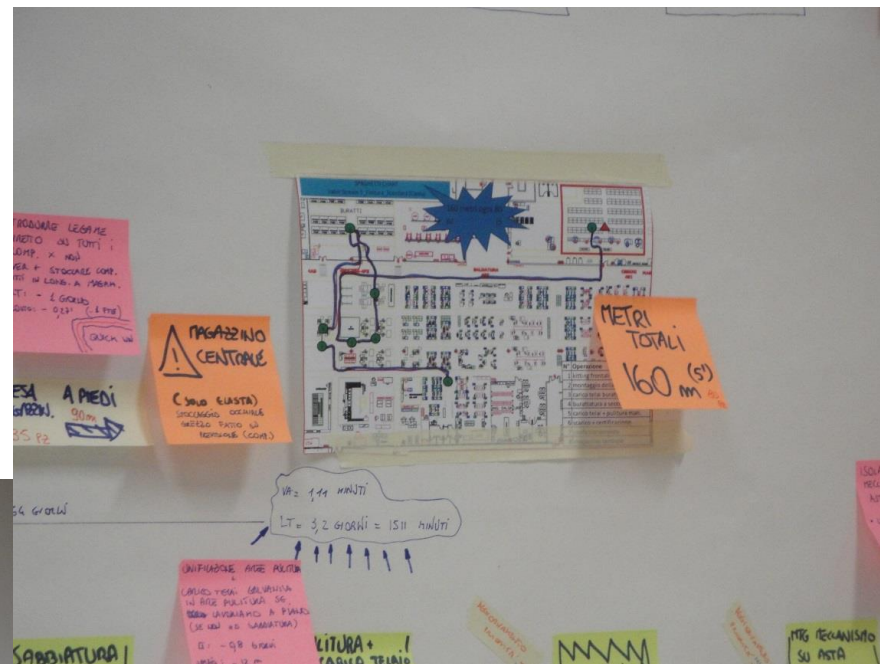
IDENTIFY THE VALUE STREAM



Aif 2

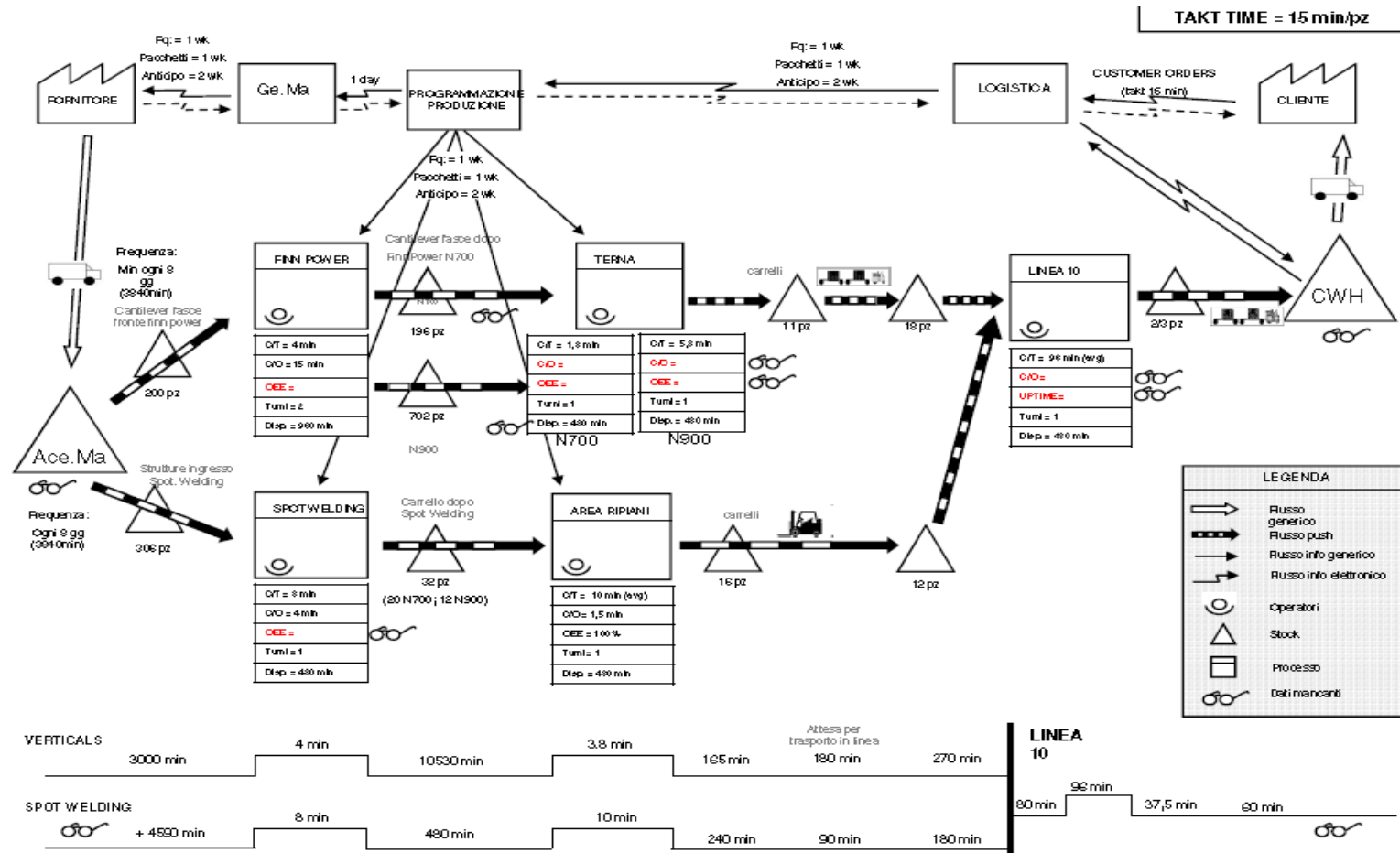


EXAMPLES OF VSM



Safilo - Longarone

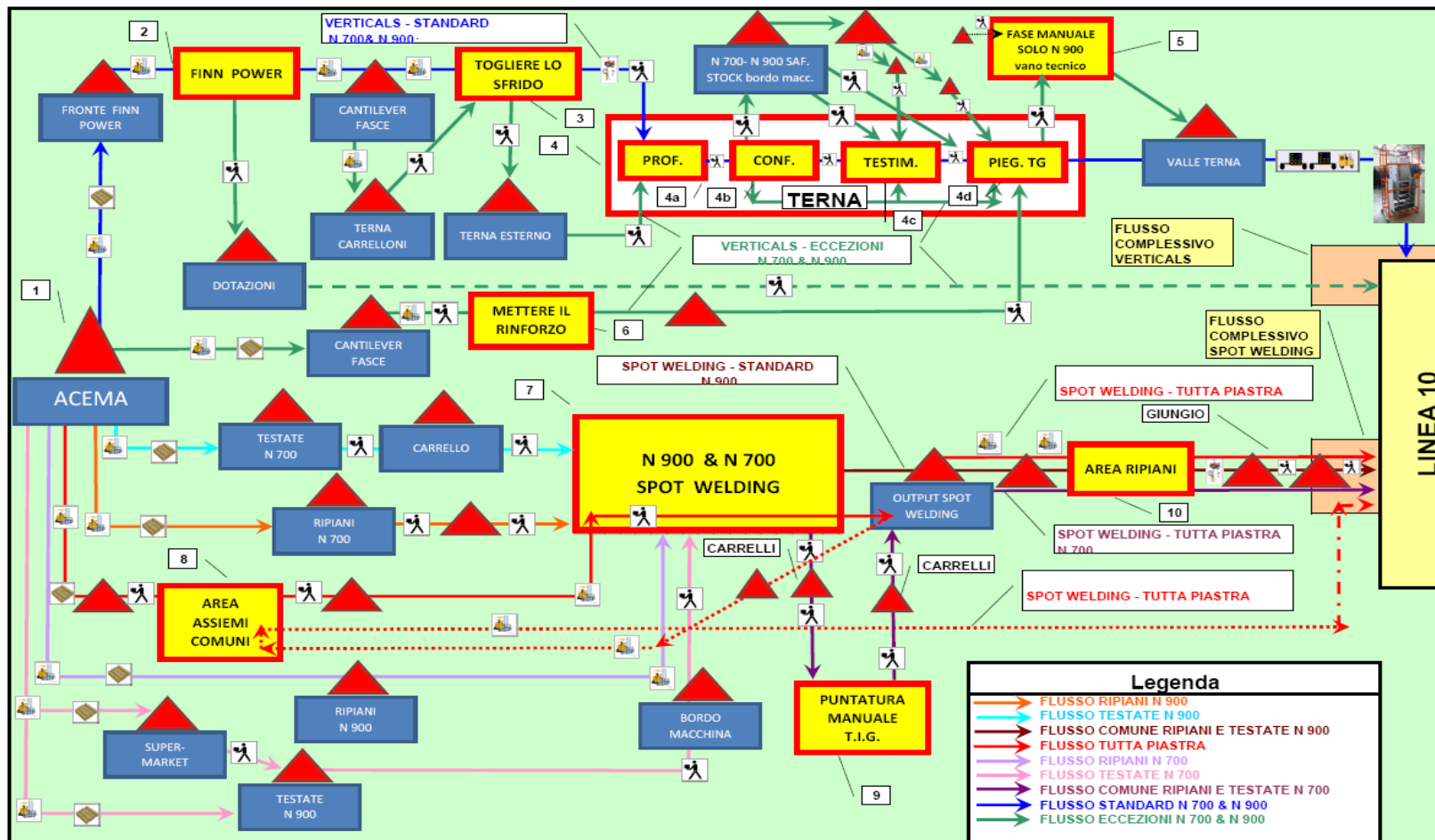
EXAMPLES OF VSM



Electrolux Prof. – Modular Cooking

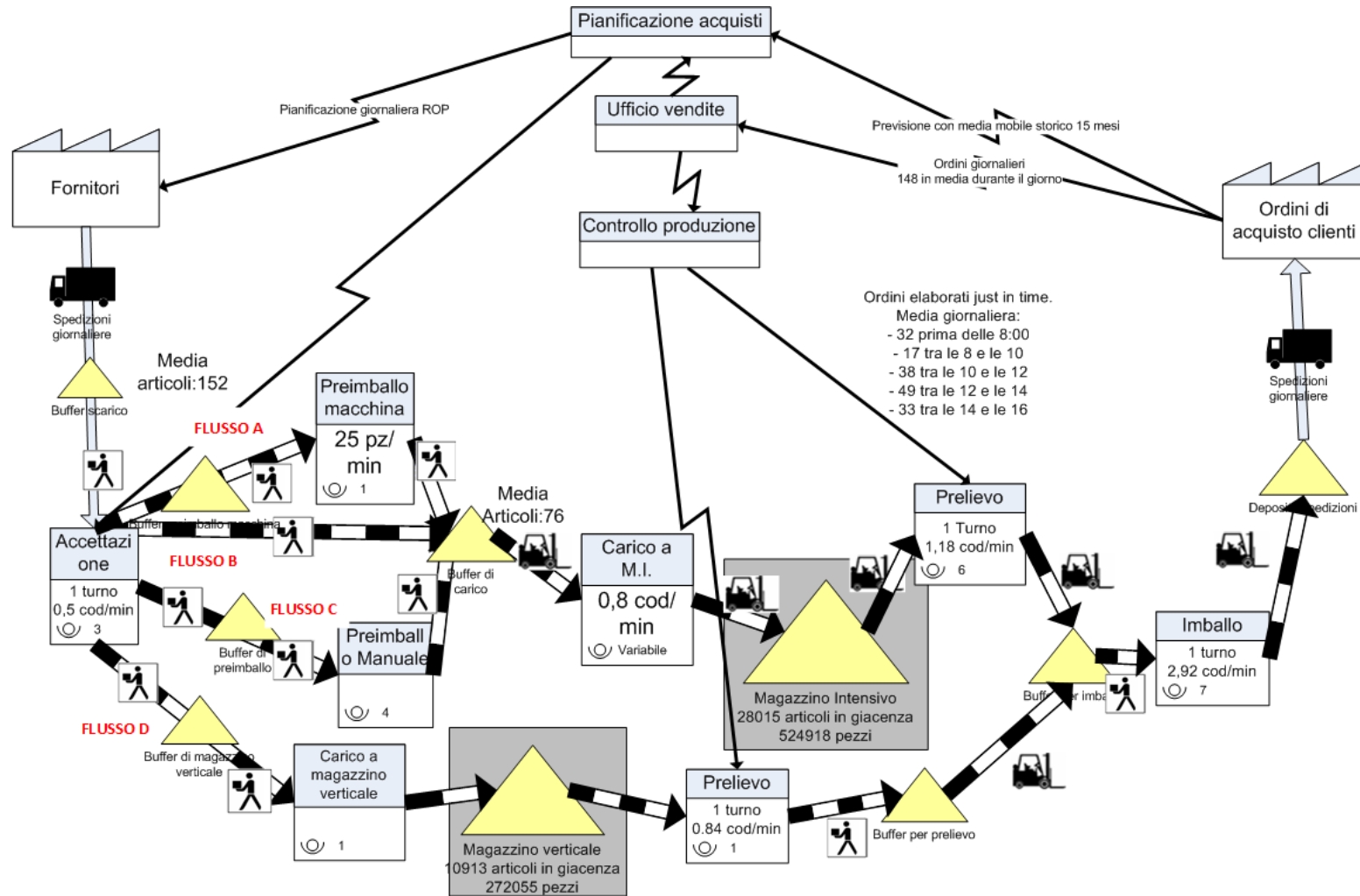


EXAMPLES OF VSM



Electrolux Prof. – Modular Cooking

EXAMPLES OF VSM



Electrolux Prof. – After Sales Service



IMPORTANCE OF THE VALUE STREAM MAPPING

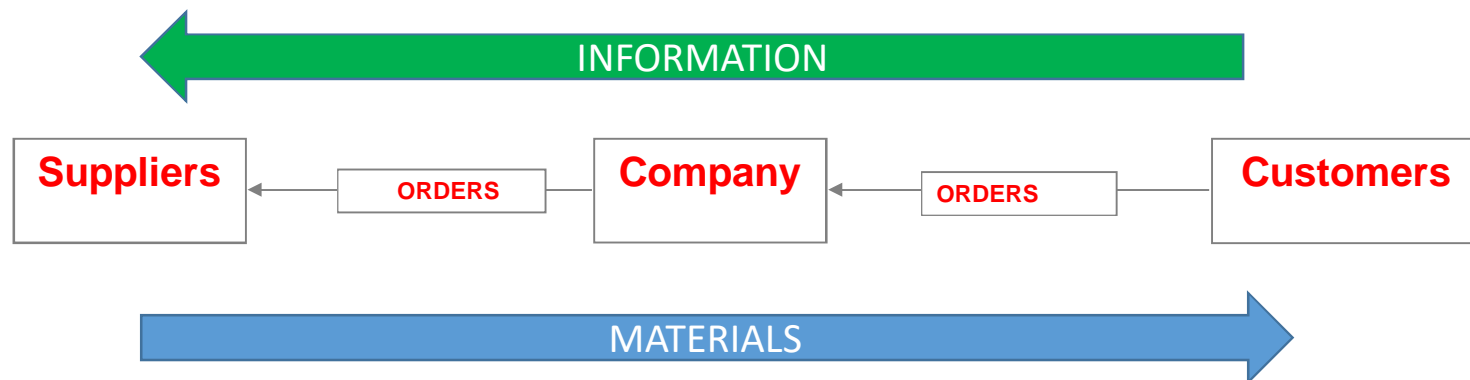
- It allows to develop a "consistent" picture of the production system, "from start to end"
- It allows to consider the complete supply chain



- It allows to analytically link system-level performance to the adopted layout choices
- It is an effective tool:
 - for promoting open dialogue between staff and for aligning on the solutions to strive for
 - for tracking continuous improvement over time and prioritizing areas for further improvement
- It pushes to frequent and do problem solving activity (PDCA), sharing the results
- It make familiar work as a cross-functional teams
- It makes easy to rotate the task among the team members

BEFORE STARTING VSMÅ

- “ **IDENTITY A PRODUCT FAMILY (GROUP)**
- “ **IDENTIFY A UNIQUE RESPONSIBLE FOR THE VALUE STREAM (VALUE STREAM MANAGER)**
- “ **DEFINE THE TEAM**
- “ **START BY MAPPING ONLY THE INTERNAL PROCESSES (WITHIN OUR FACTORY)**
- “ **CONSIDER BOTH MATERIAL AND INFORMATION FLOWS**



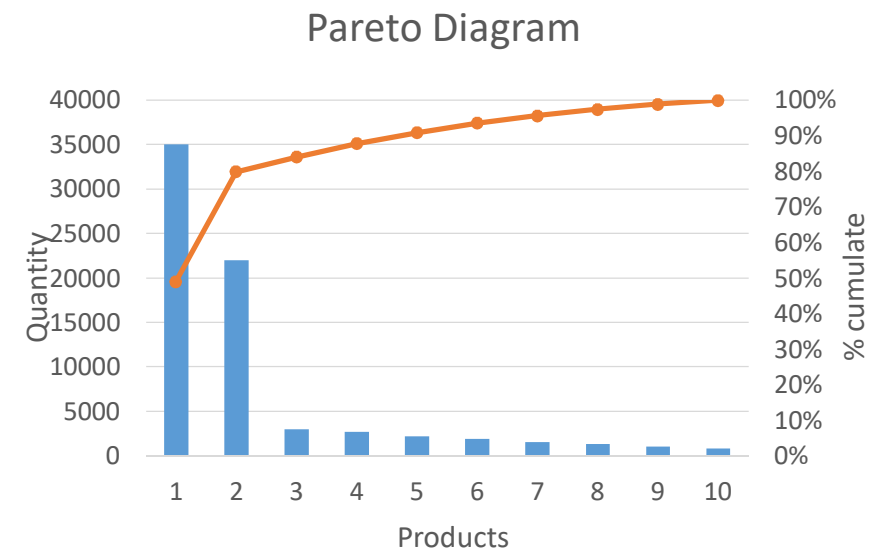


BEFORE STARTING VSMÅ

“ IDENTIFY A PRODUCT FAMILY (GROUP)

- “ The PQ (Product-Quantity) analysis is based on the assumption that the first production processes to be analyzed are those related to products made in large quantities.
- “ The PQ analysis requires that the production mix of the plant has to be reported on a Pareto diagram.

Product	Q	Q. Cumulate	%	% Cumulate
#1	35000	35000	49,02%	49,02%
#2	22000	57000	30,81%	79,83%
#3	3000	60000	4,20%	84,03%
#4	2700	62700	3,78%	87,82%
#5	2200	64900	3,08%	90,90%
#6	1900	66800	2,66%	93,56%
#7	1500	68300	2,10%	95,66%
#8	1300	69600	1,82%	97,48%
#9	1000	70600	1,40%	98,88%
#10	800	71400	1,12%	100,00%





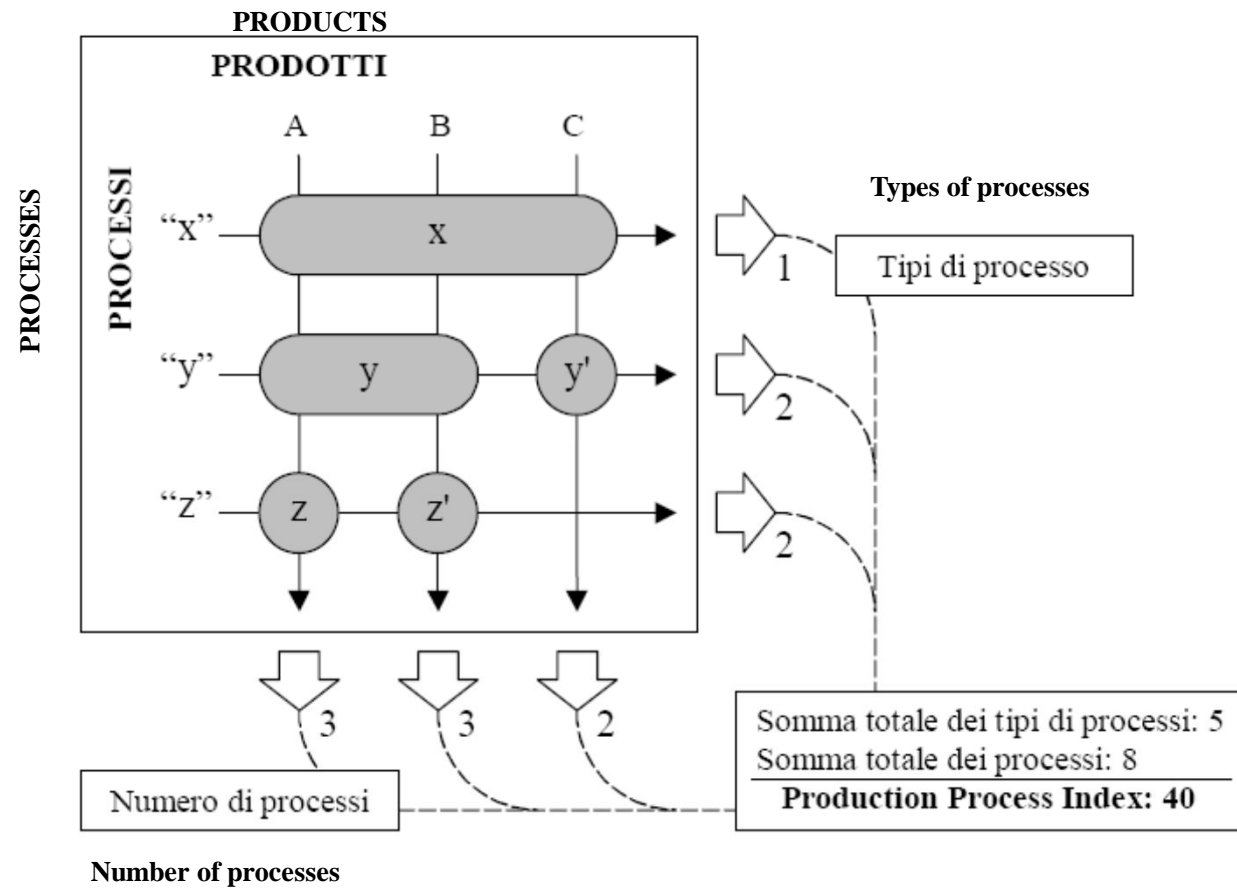
IDENTITY A PRODUCT FAMILY (GROUP): PRODUCT-PROCESS ANALYSIS

		Macchine							
		M#1	M#2	M#3	M#4	M#5	M#6	M#7	M#8
Prodotti e Quantità	1500	P#1	x	x	x		x	x	
	12000	P#2		x		x		x	x
	10000	P#3		x		x		x	x
	5400	P#4	x	x	x	x	x		
	3000	P#5			x		x	x	x
	2800	P#6	x	x	x		x	x	
	2700	P#7	x		x			x	x
	1500	P#8	x		x			x	x

Famiglia	Prodotti	Quantità totale
F#1	P#1,P#4,P#6	9700
F#2	P#2,P#3	22000
F#3	P#5,P#7,P#8	7200

QUANTITY: PIECES OR HOURS OR EUROS?

IDENTITY A PRODUCT FAMILY (GROUP): PRODUCT-PROCESS ANALYSIS (indexes)



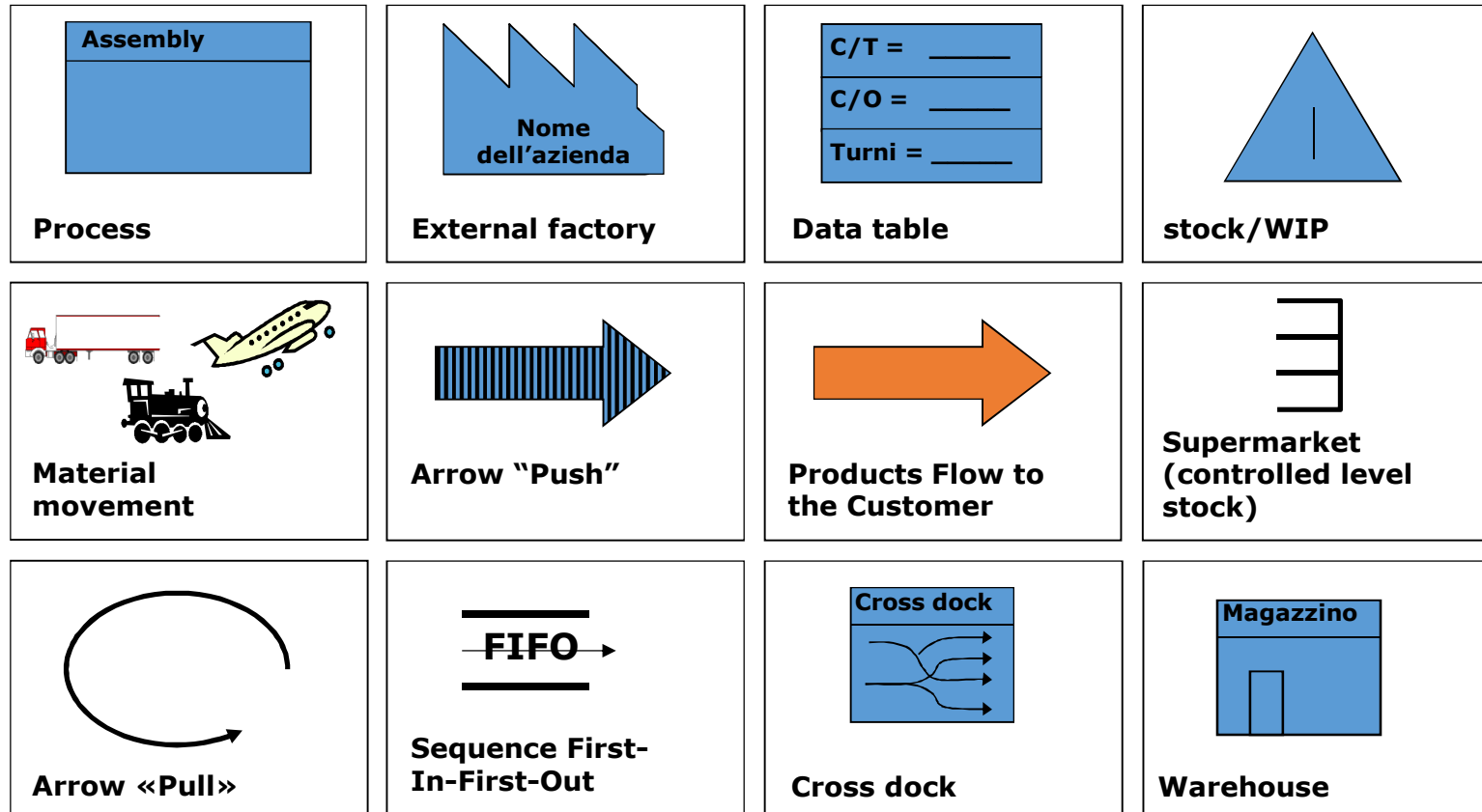


SUGGESTIONS FOR MAPPING

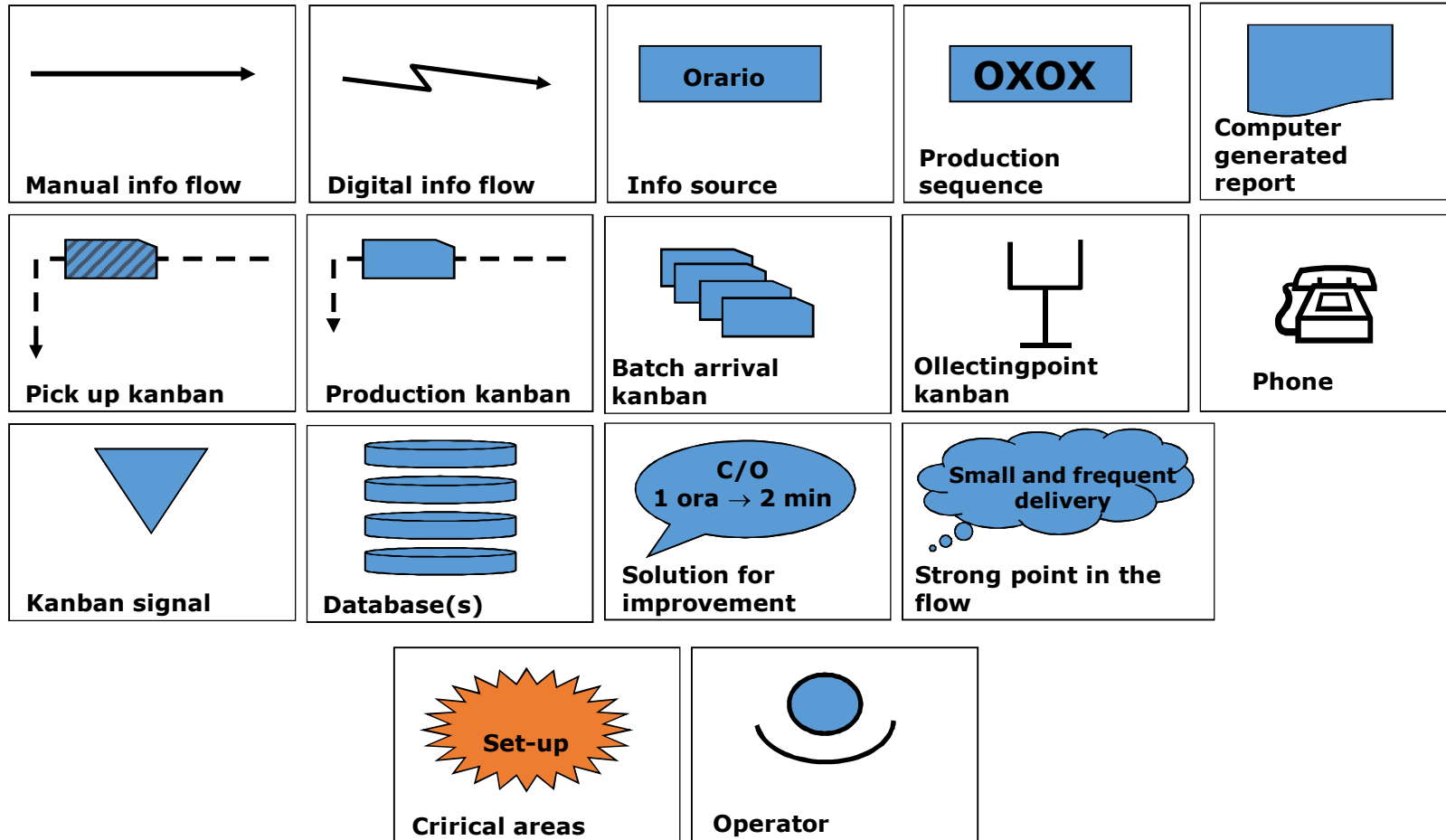
- “ COLLECT INFORMATION BY WALKING THE REAL FLOW OF MATERIALS AND INFORMATION (GEMBA)
- “ START FIRST WITH A QUICK WALK ALONG THE ENTIRE STREAM TO GET AN IDEA OF THE SEQUENCE OF THE PROCESSES
- “ START THE REAL MAPPING FROM THE CUSTOMER AND HIS REQUESTS BACKWARDS
- “ ALWAYS HAVE A STOPWATCH AND CAMERA AVAILABLE (CONSIDER BUT PLS DON'T TRUST COMPLETELY STANDARD TIMES, MAYBE OBSOLETE)
- “ MAP THE ENTIRE CHAIN PERSONALLY (LET THE TEAM PARTICIPATE)
- “ USE AN A4 PAPER, A PENCIL AND AN ERASER
- “ CARRY OVER ON A BILLBOARD AND DISCUSS WITHIN YOUR GROUP
- “ USE THE VSM SYMBOLS



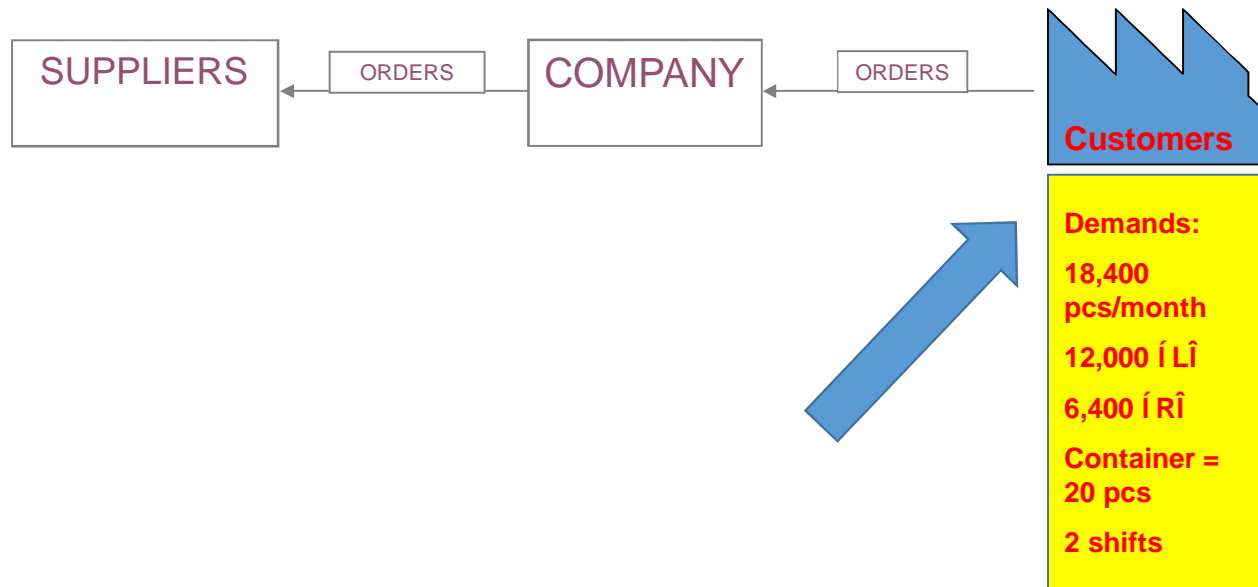
SIMBOLI PER LA MAPPATURA



SIMBOLI PER LA MAPPATURA

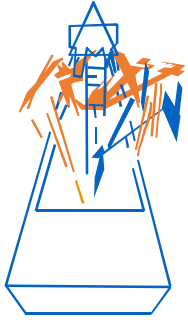


1) FIRST STEP FOR VSM





TAKT TIME

$$\text{Takt time} = \frac{\text{Hours planned for production}}{\text{Customer's demand}}$$


In the considered example:

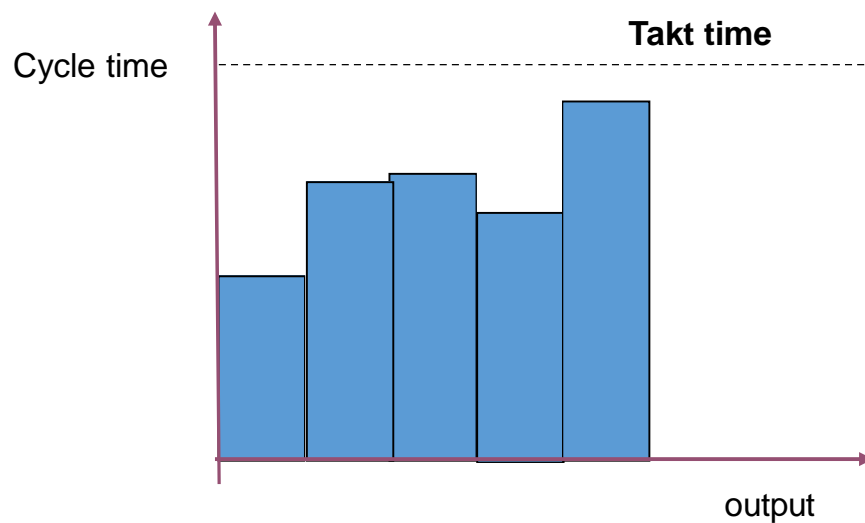
18400 pcs/months

4600 pcs/week

450 min/day=2250 min/week

$2250/4600 = 0,49$ min/pc

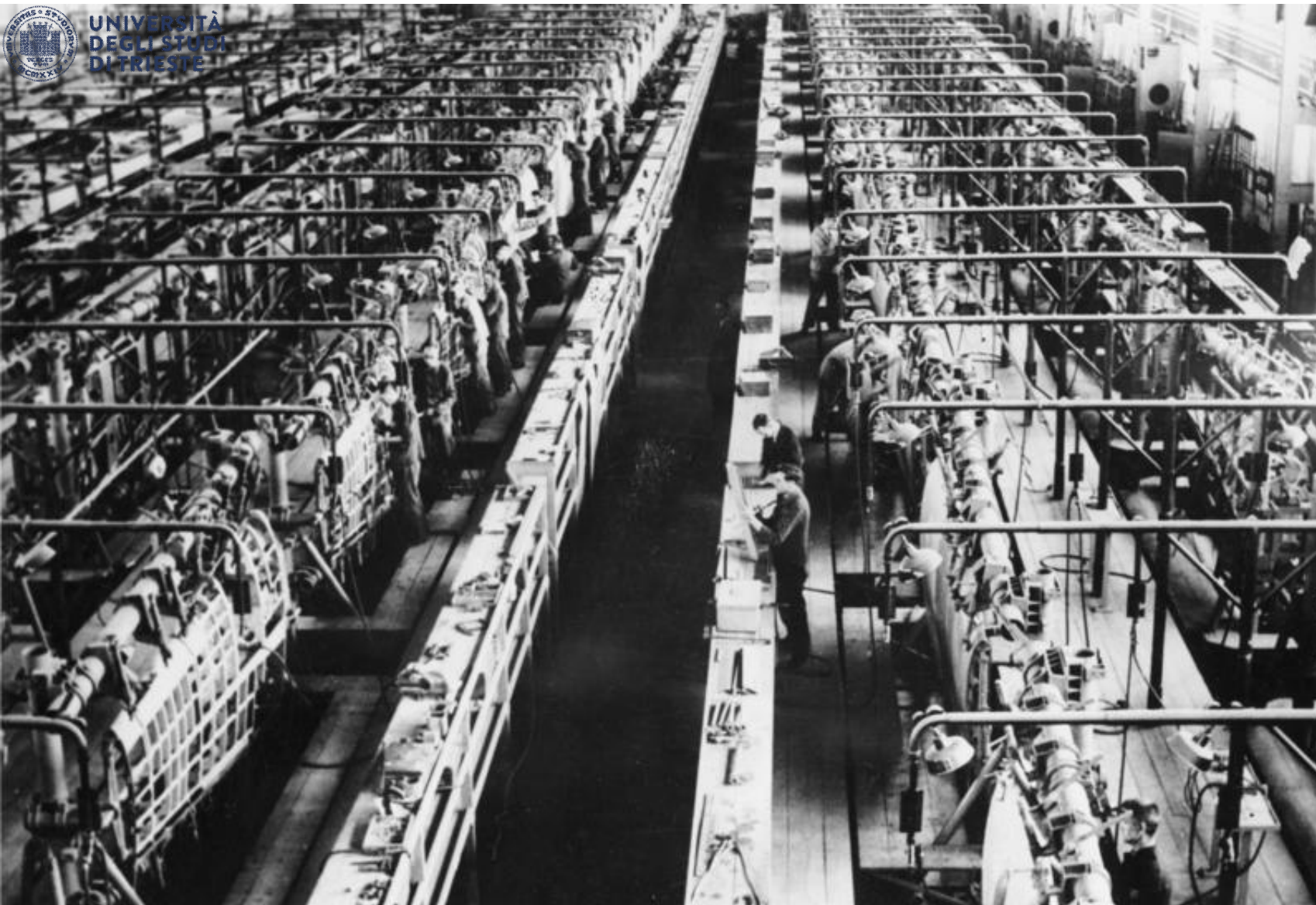
Takt time= 0,49 min/pc



CABCACC CABCACC ...



UNIVERSITÀ
DEGLI STUDI
DI TRIESTE



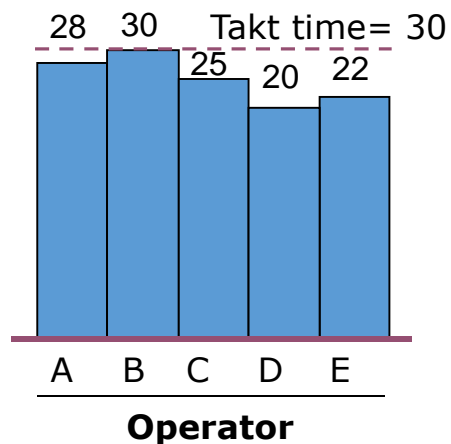
An assembly line
inside a Messerschmitt
factory in Germany
just before the WWII.



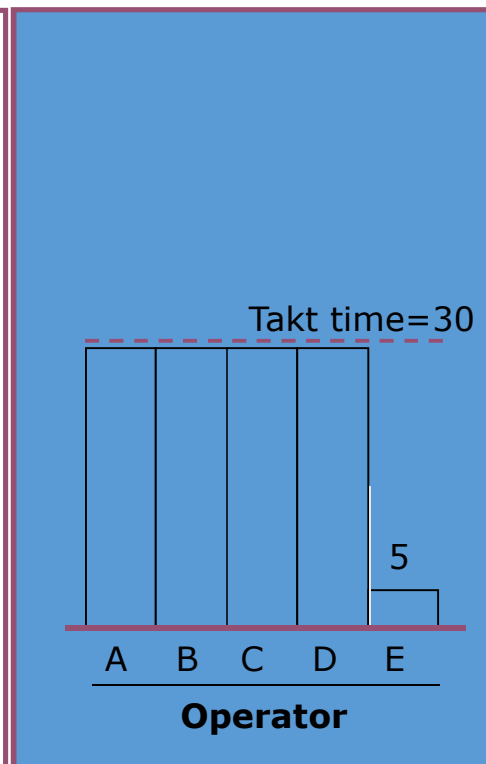
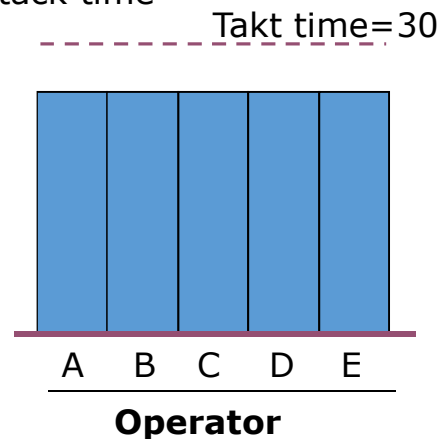
Materiale riservato
Raffaele Campanella

TAKT TIME: BALANCE AMONG OPERATORS

Normally the work activities are not equally distributed among the operators



In some cases, the work activities are equally distributed among the operators but with a time levelling significantly lower than takt time



How many workers will be necessary?

$$\text{Number of operators} = \frac{\text{Total workload}}{\text{"Takt time"}}$$

Example

$$\text{Number of operators} = \frac{125s}{30s (TT)} = 4.1$$

TAKT TIME: IF VARIABLEÅ

If the Customers demand increase
the Takt time decrease

If the Customers demand decrease
the Takt time increase

Cycle times have to be reduced eg by:

Increasing the number of work places
Introducing overtime
Outsourcing
Utilising all the available time
.....

Competences
and flexibility
of the
operators

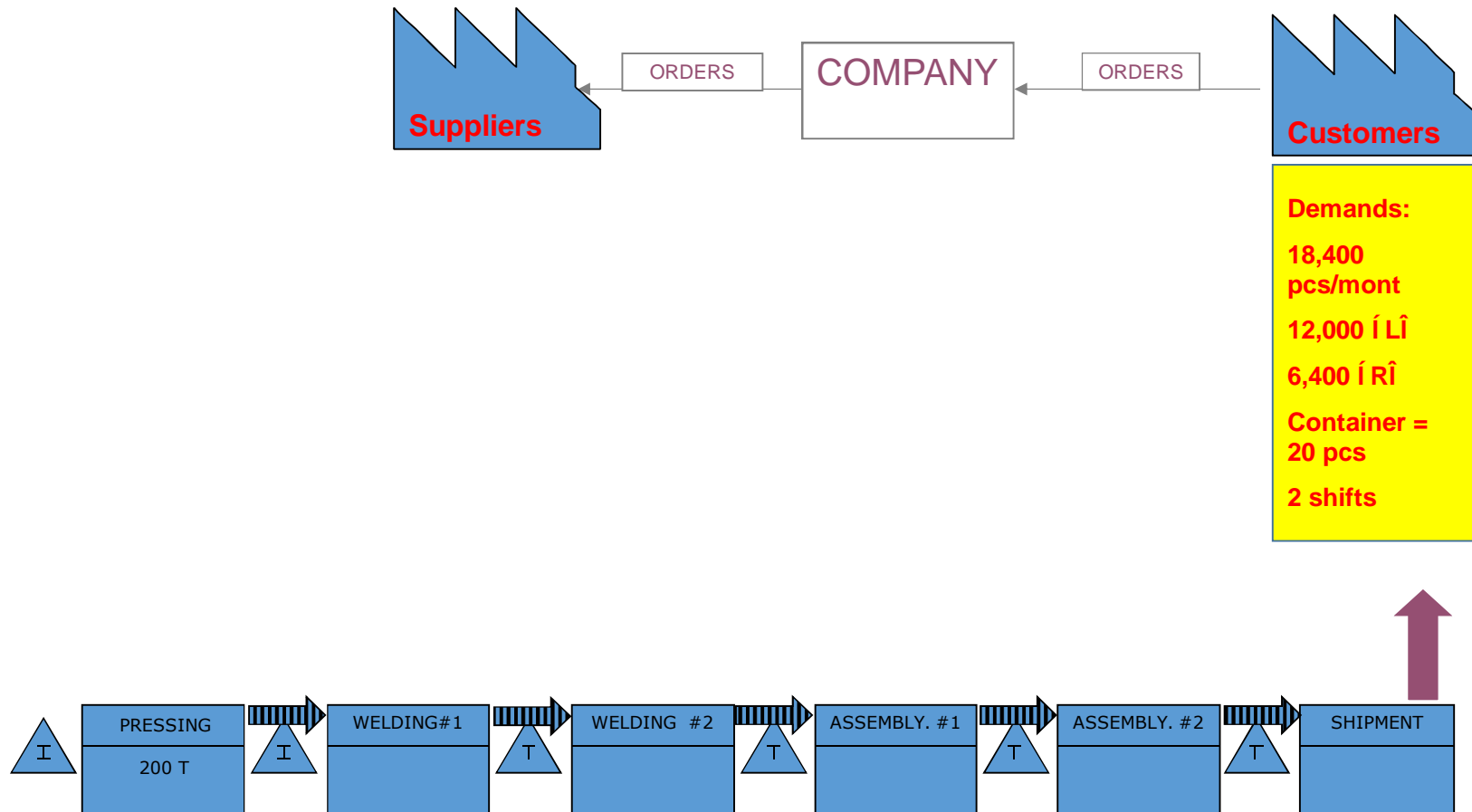
Cycle times have to be increased eg, by:

Decreasing the number of operators
insourcing external activities
Utilising the workers in diferent activities
Permissions, holidays
.....

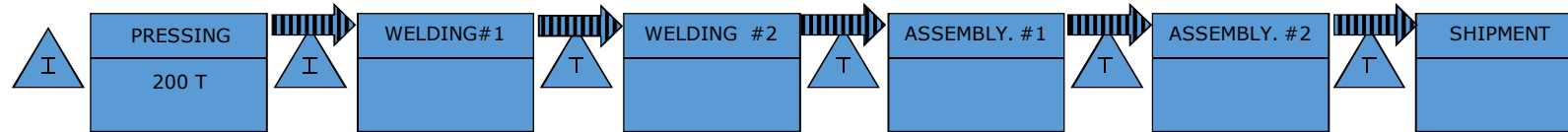
Kaizen activities in order to reduce movements o machinery times have to be done in all the cases

2) IDENTIFY THE PROCESSES

Tempo di processo/
lead time di lavoro

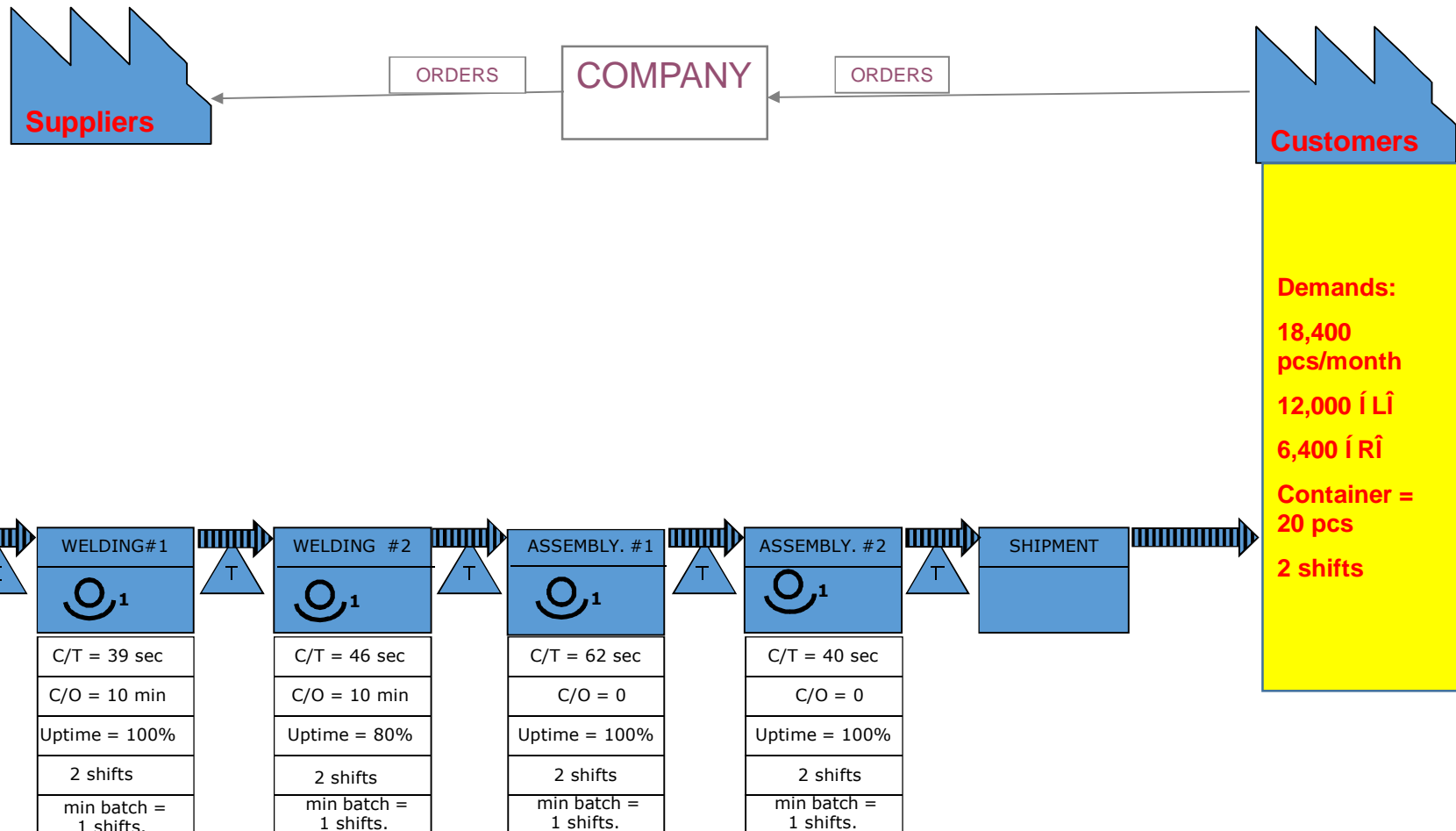


PROCESSES TYPICAL DATA



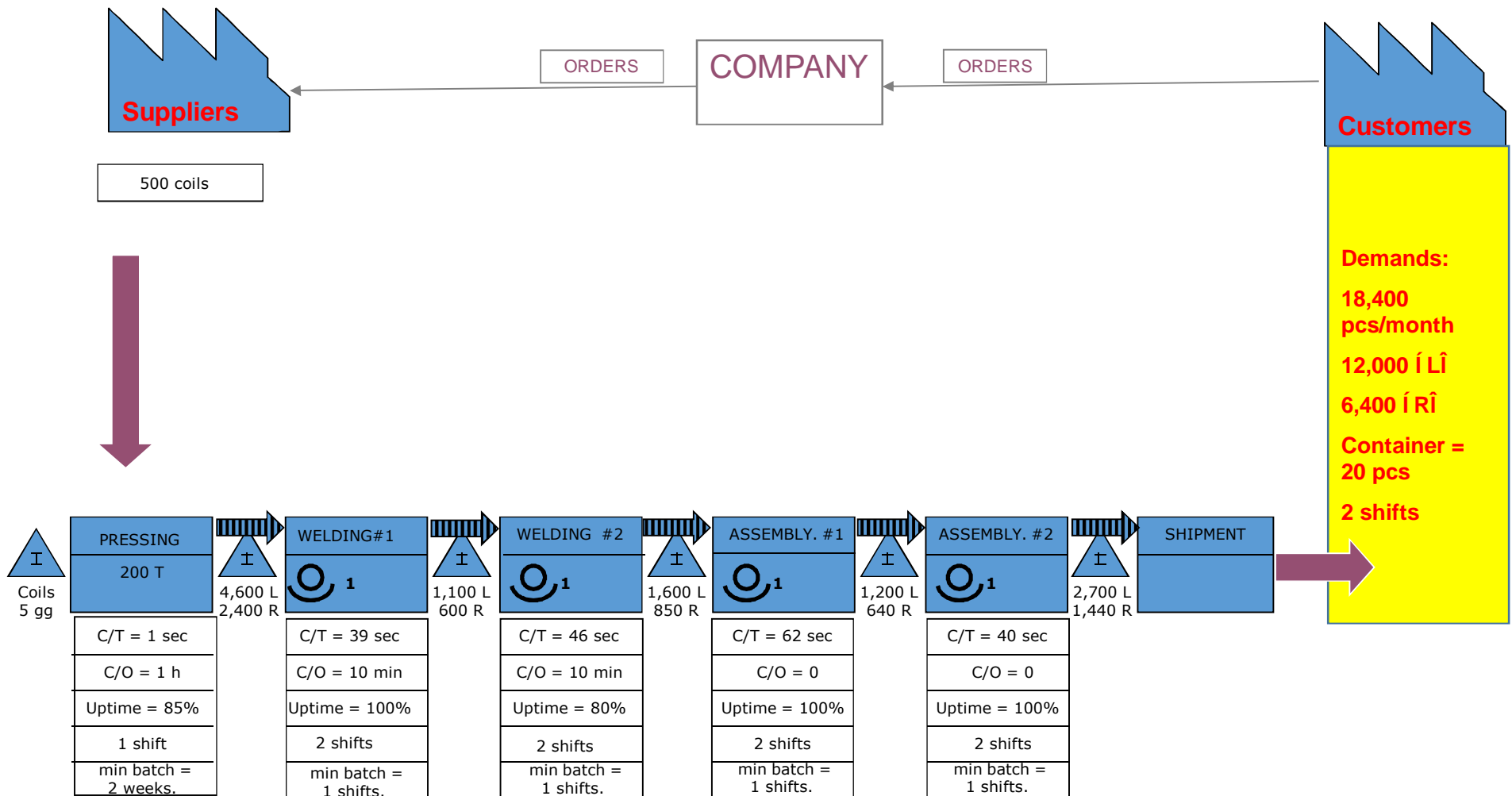
- “ **C/T: Cycle Time** È **VA: Time with Add Value** È **L/T Lead Time (sec)**
- “ **C/O: Set-up time** È **Time to change model (sec/h)**
- “ **UPTIME: Availability of the Machinery when necessary (%)**
- “ **EPE (Every Part Every): Dimension of the production batch**
- “ **Number of operator in the specific process**
- “ **Number of variants produced**
- “ **Number of scraps (%)**
- “ **À ..**

3) COLLECT PROCESS DATA

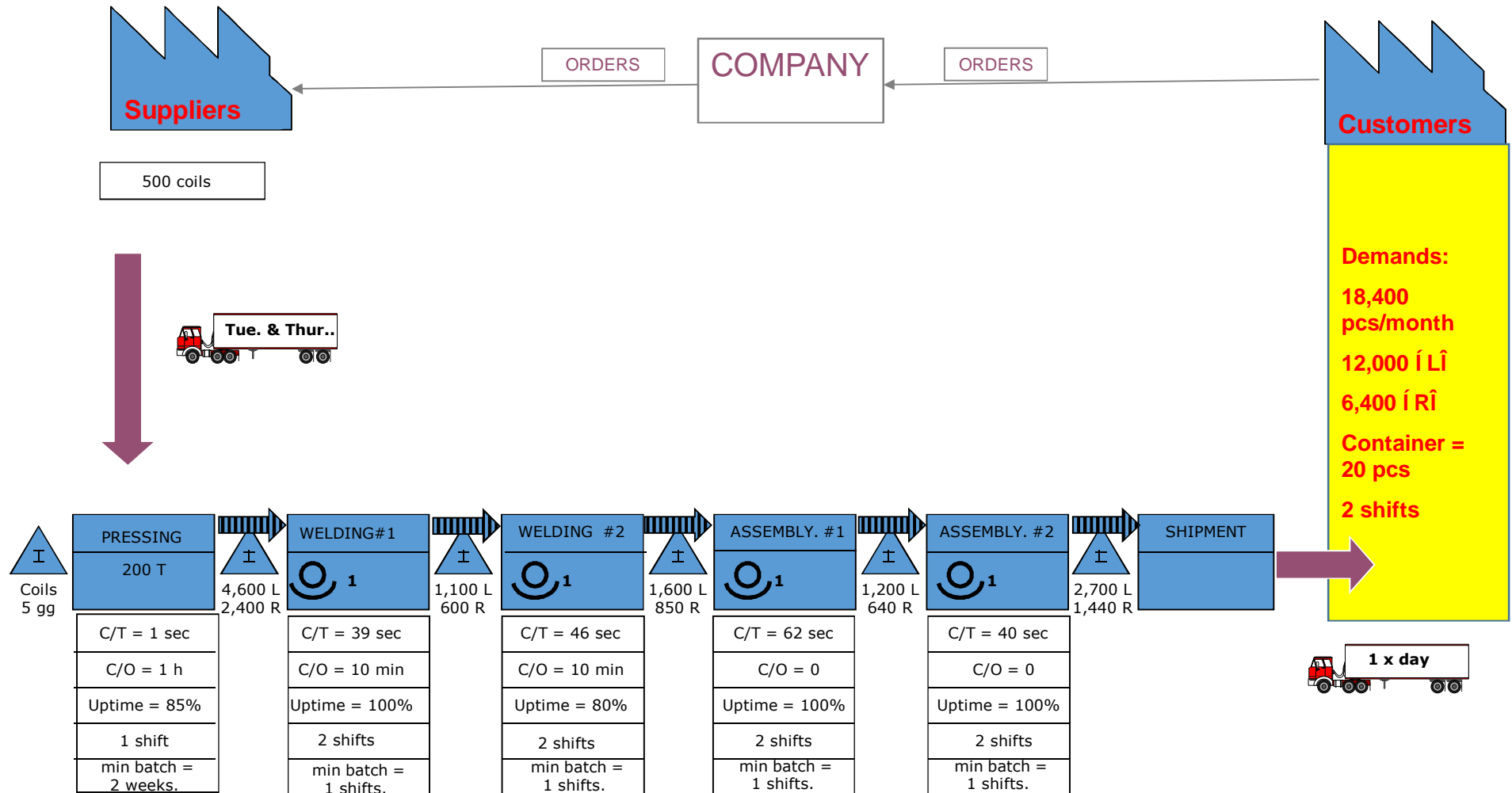




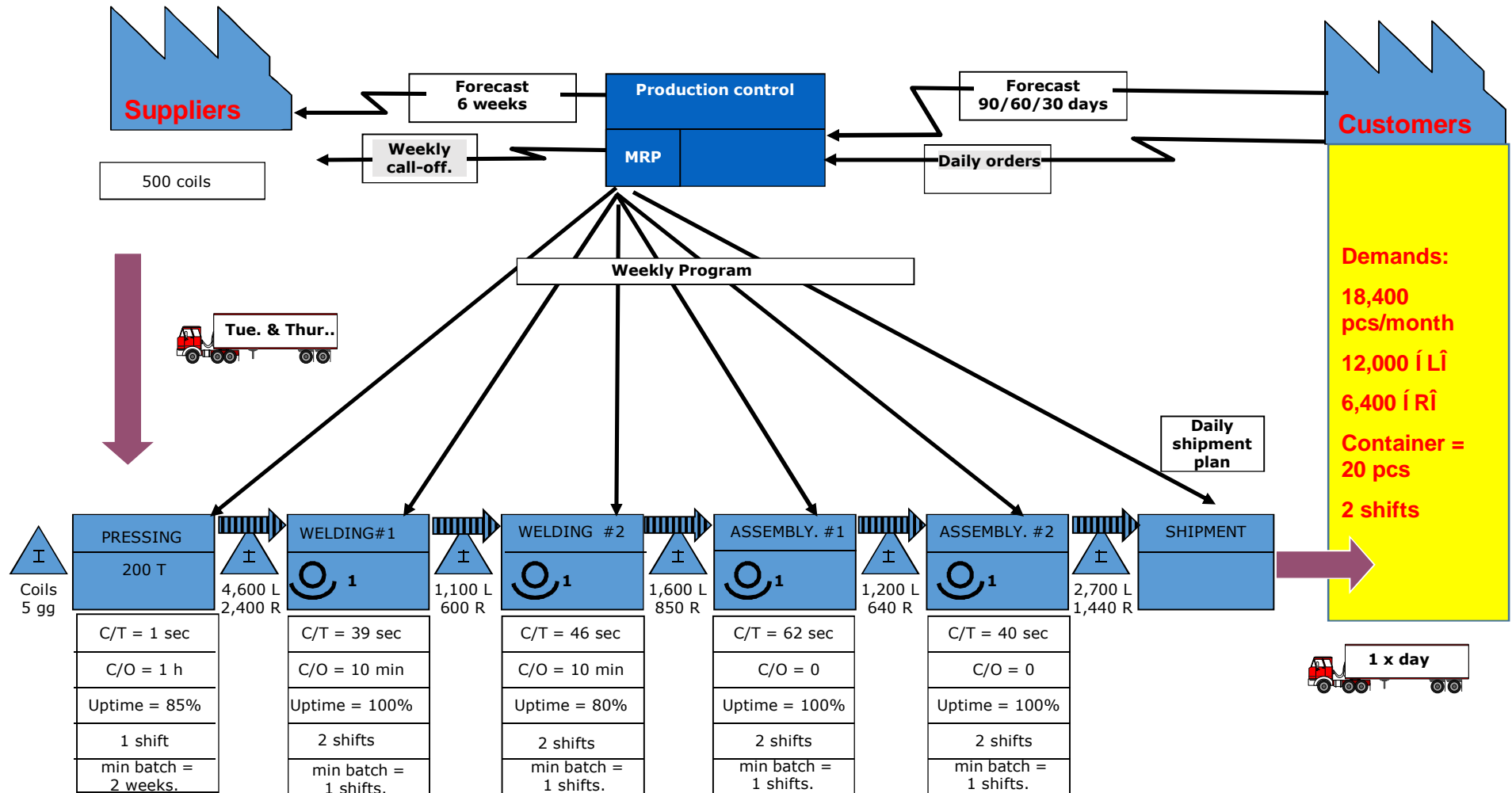
4) COLLECT STOCK DATA



5) COLLECT DATA ON MATERIALS FLOW

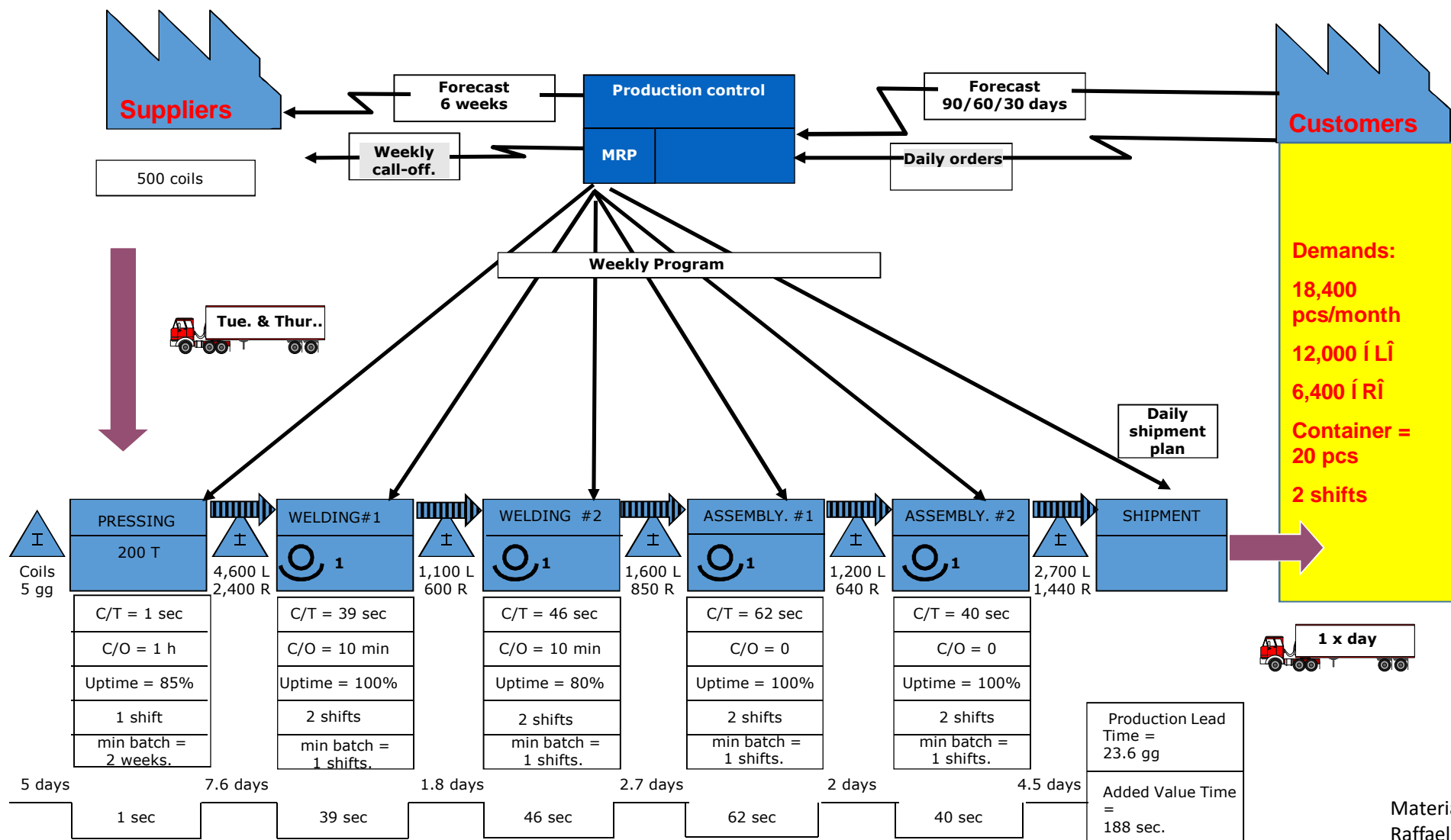


6) COLLECT DATA ON INFORMATION FLOW

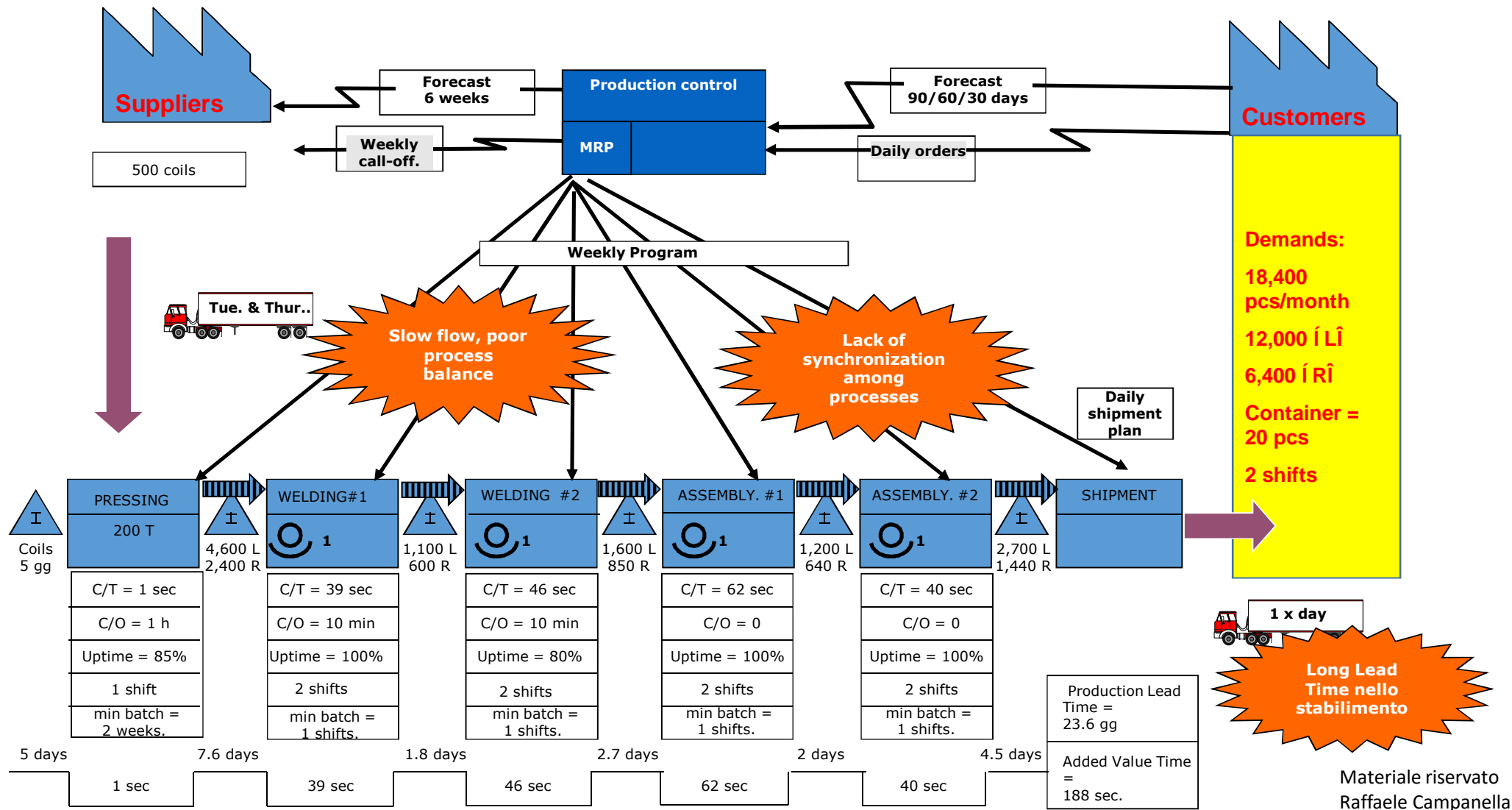




7) LEAD TIME CALCULATION



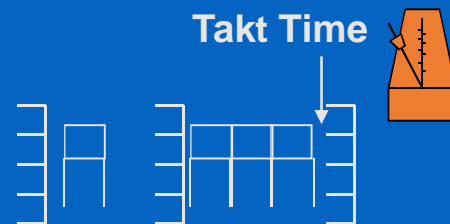
CURRENT VALUE STREAM MAPPING



6) COLLECT DATA ON INFORMATION FLOW

Considerations on pull vs. push

Pull System



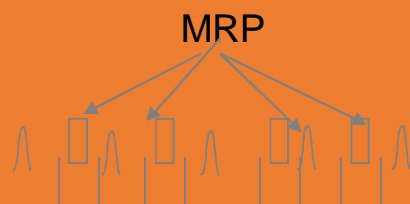
Pull System works when the production information (based on Customer's orders) is sent to the process upstream

Push System



The most common push system is the one where takt time is not known and the materials are pushed by upstream processes

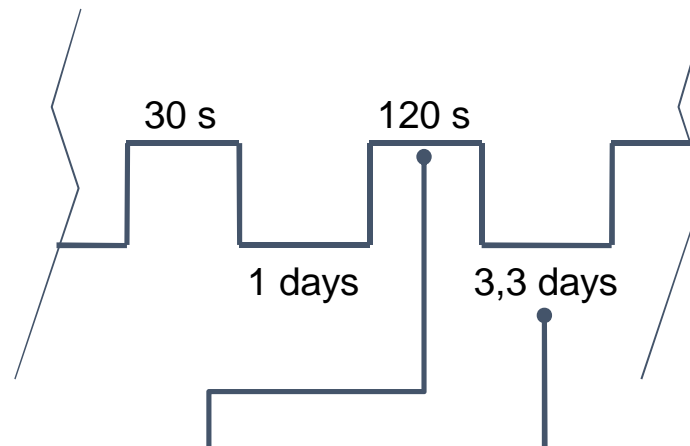
MRP System



When MRP System is used, the system remains "push" type, gives its own inputs to all the processes. The result is production with different rhythm due to uncertainty of the assumptions



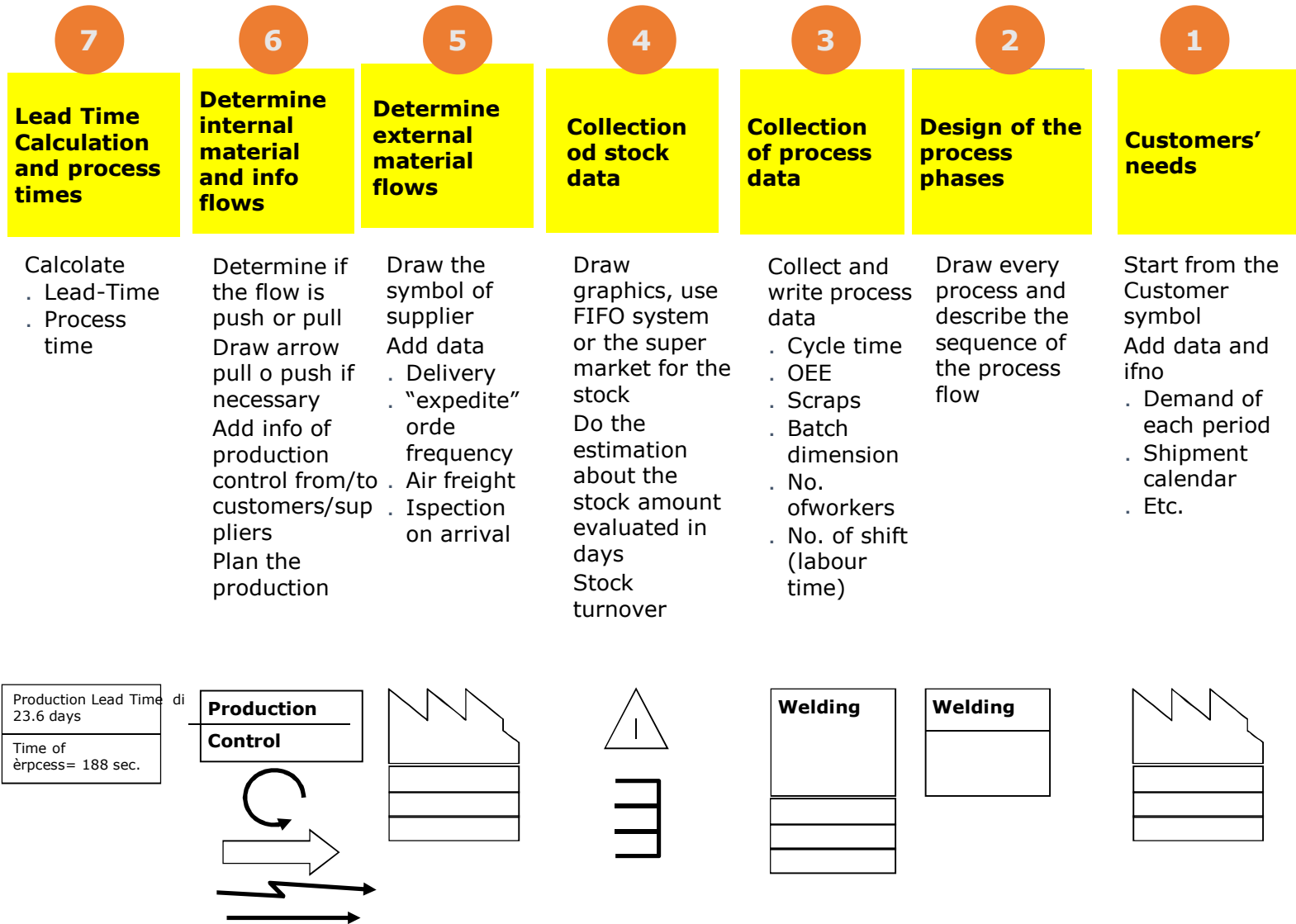
7) LEAD TIME CALCULATION Considerations on the time line



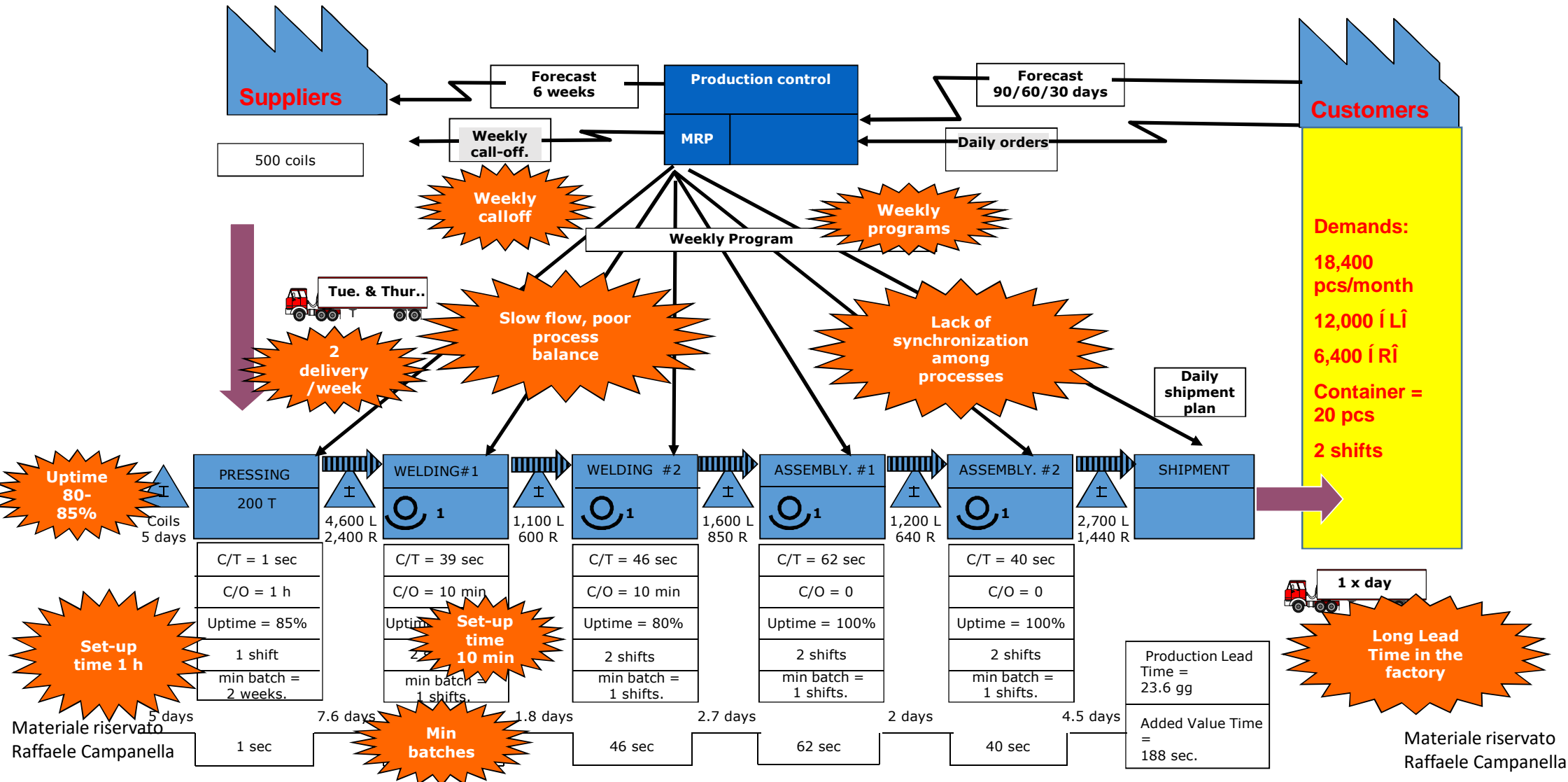
- “ The upper part of the line is the average of the present working times of the process
- “ Process time is defined as the sum of workers and machine cycle times
- “ The labour times are referred to the present job organization (actual efficiency and losses)

- “ The low part of the line show the waiting time between two consecutive processes
- “ This time is linked to the average WIP between two consecutive processes
- “ Cases related to specific orders are not considered

SYNTHESIS OF THE 7 STEPS FOR VSM



CURRENT VALUE STREAM MAPPING



ORGANIZE ACTIVITIES ACCORDING PULL SYSTEM

- The value added activities have to flow without interruption, like the water.
- The interruptions of the productive activities are:
 - A warehouse
 - A buffer
 - A waiting time
 - Å Å .
- The concept of flow is not familiar with our way of thinking, that instead prefers working by batches. It is easier to approach the production completing the first operation for all the available pieces, then completing the second operation for all the pieces and so on. Very often this is due to the fact that the passage from the first to the second operation is linked to a machine (and brain) set-up that takes time.

ENVELOPES GAME

POSSIBLE ACTIONS



Long Lead
Time in the
factory

- See the difference between lead time and value added time:

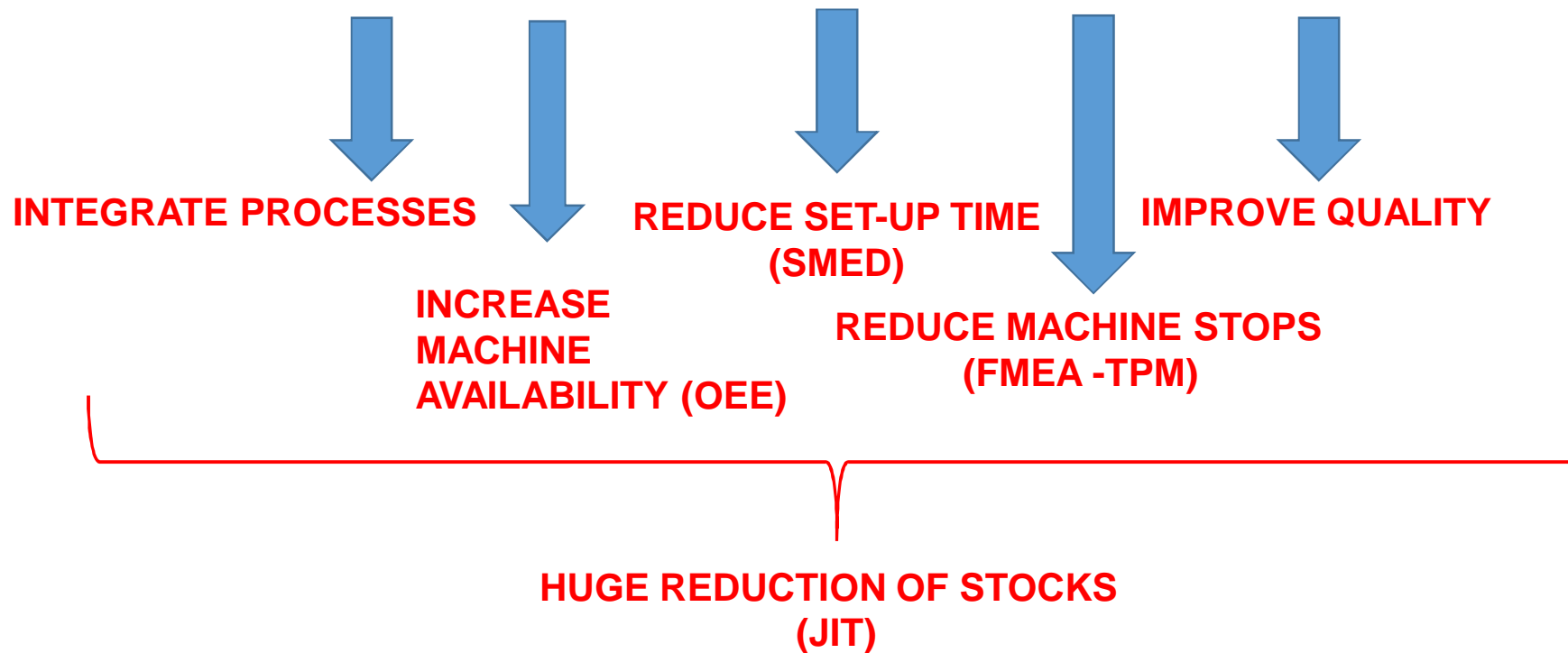
Production Lead Time = 23.6 gg
Added Value Time = 188 sec.

- Why this so huge difference?
- What are the reasons?

- “ The long lead time is due to the stock along the processes
- “ The processes are too many and separate
- “ The processes production capacities are unbalanced
- “ The production organization is «push»

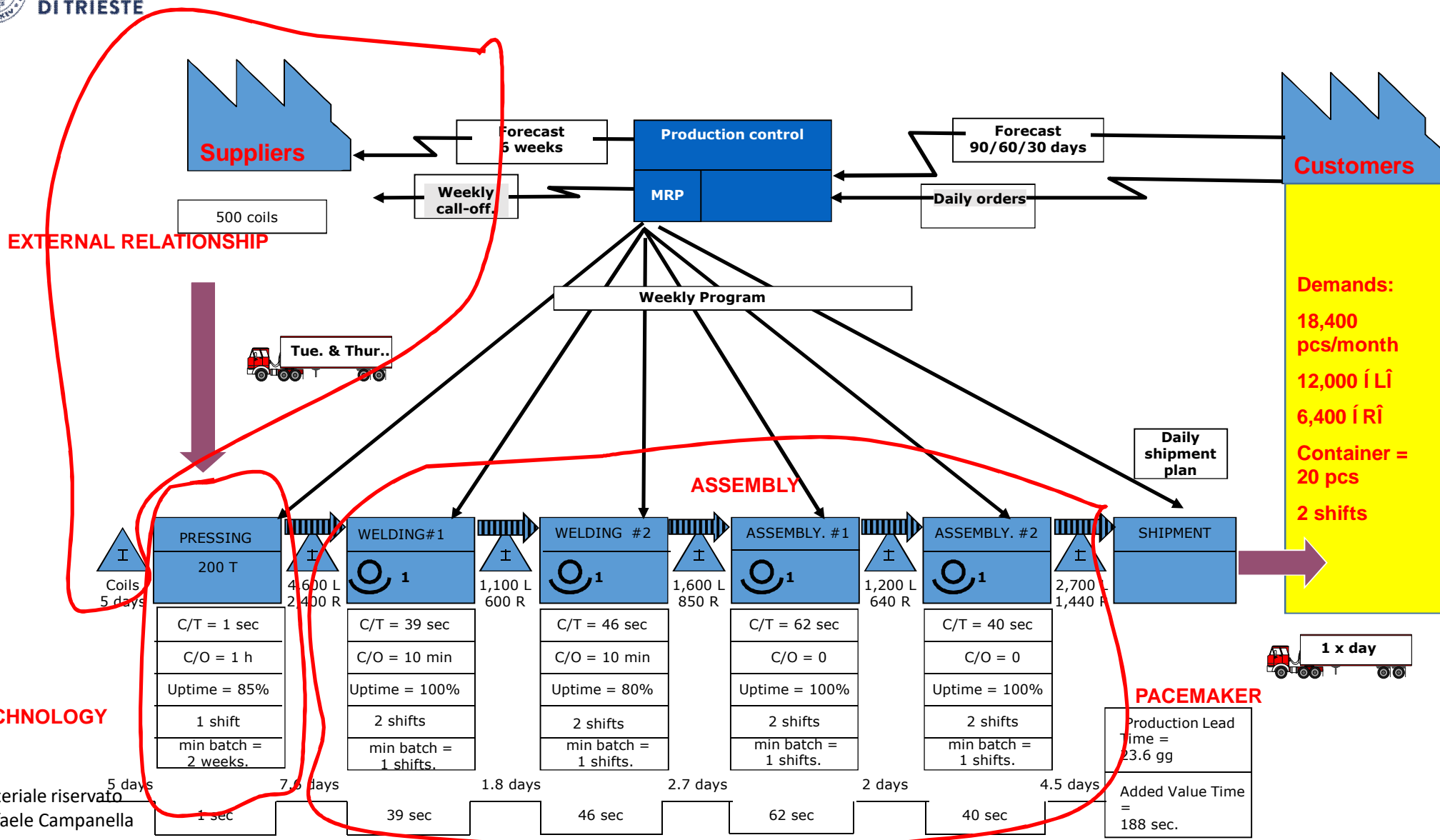
POSSIBLE ACTIONS

- “ The long lead time is due to the stock along the processes
- “ The processes are too many and separate
- “ The processes production capacities are unbalanced
- “ The production organization is «push»





TOWARD THE FUTURE STREAM MAP



TOWARD THE FUTURE STREAM MAP

OBJECTIVES

ASSEMBLY = PACEMAKER

- “ ONLY A UNIQUE CELL FOR WELDING AND ASSEMBLY
- “ KAIZEN WORK TO REDUCE TOTAL CYCLE TIME TO 168 SEC OR LESS
- “ ELIMINATE CHANGE-OVER (SET-UP) TIME
- “ IMPROVE UPTIME WELDER UO TO 100%
- “ PULL SYSTEM WITH KANBAN CARDS IN THE ASSEMBLY AREA

TECHNOLOGY:

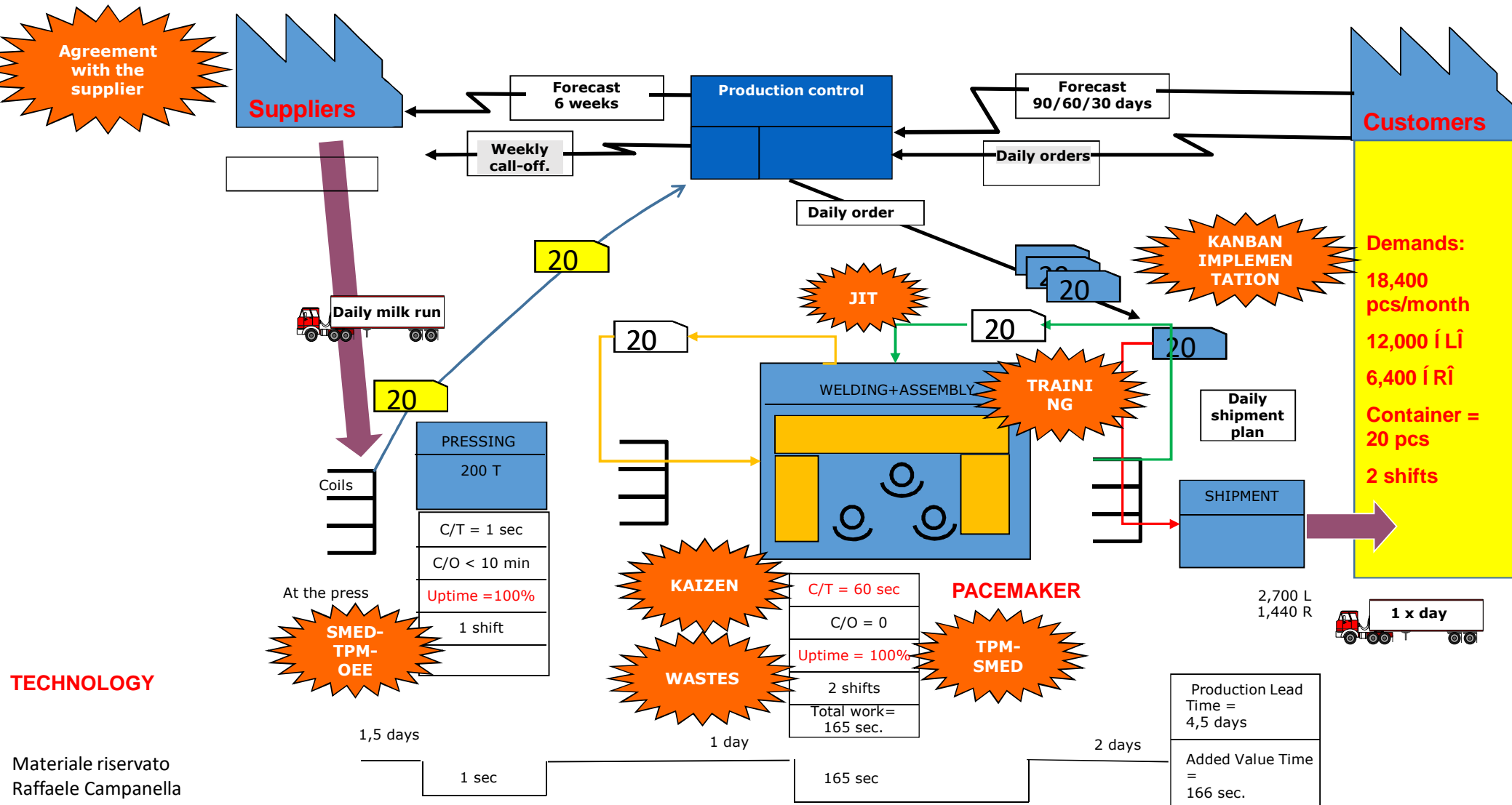
- “ PULL SYSTEM WITH STAMPED PARTS SUPERMARKET
- “ REDUCE BATCHES SIZE TO 300 (LH) AND 160 (RH)
- “ REDUCE STAMPINGCHANGE-OVER TO LESS THAN 10 MIN.

EXTERNAL RELATIONSHIP:

- “ AGREEMENT WITH COIL SUPPLIER
- “ PULL SYSTEM WITH STEEL COILS SUPERMARKET
- “ DAILY COIL DELIVERY



TOWARD THE FUTURE STREAM MAP



TECHNOLOGY

KEY MESSAGES

VSM is the olistic map of the production system and show grafically (visually) processes, material and information flows

It is used to describe the present status of the production system in order to develop its future status

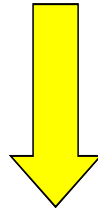
It is built according a solid method (eg. Process phases, symbols,...)

It is built by skilled technicians able to identify correctly the working logics of the system

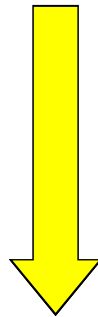
It is a fondamentale tool to support the transformation of the Productive System and the pertinent organization

THE LABOUR TIMES STUDY

LABOUR TIMES STUDY



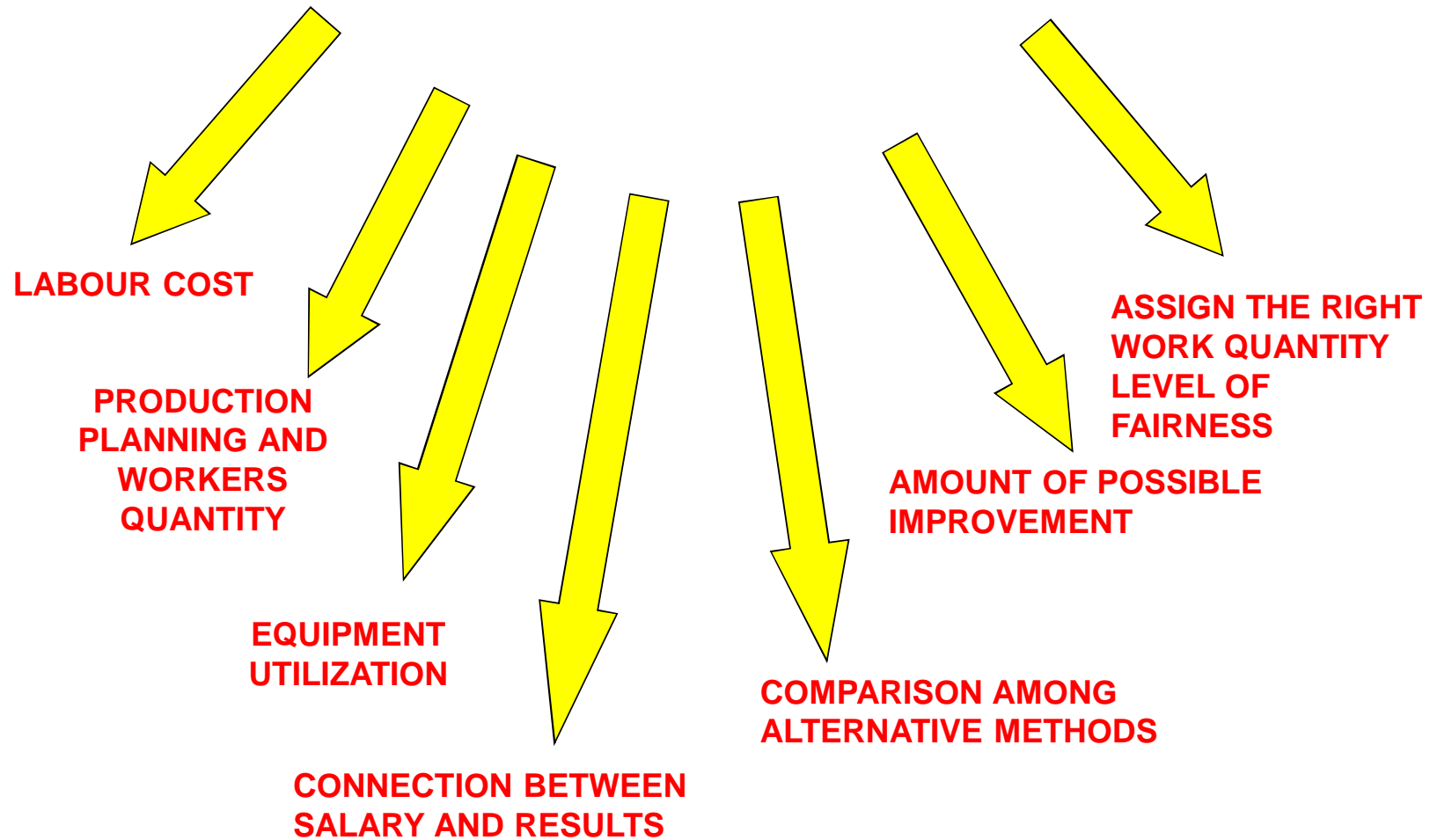
MEASURE THE WORK QUANTITY



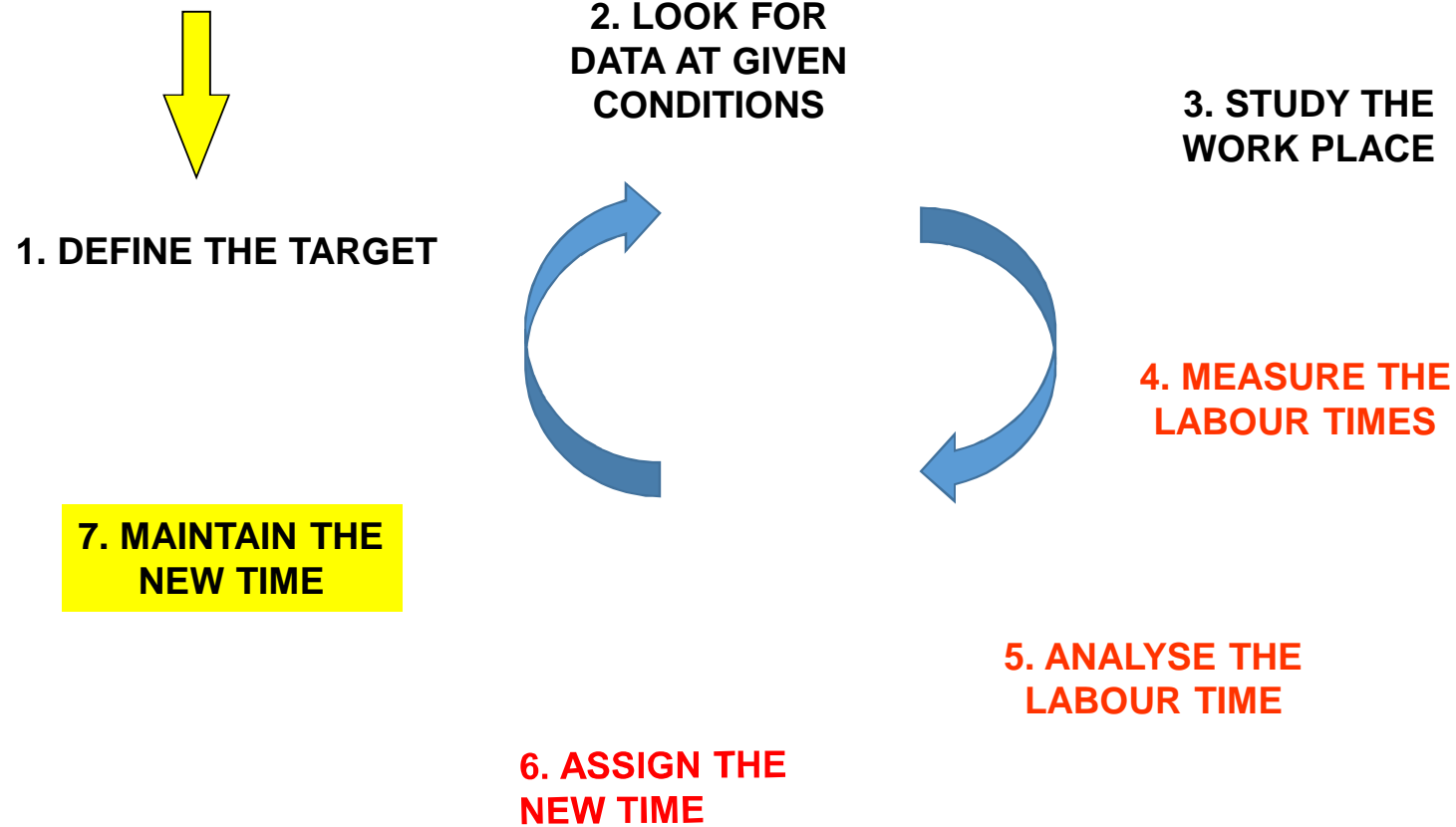


LABOUR TIME

WHY DO WE HAVE TO MEASURE IT?

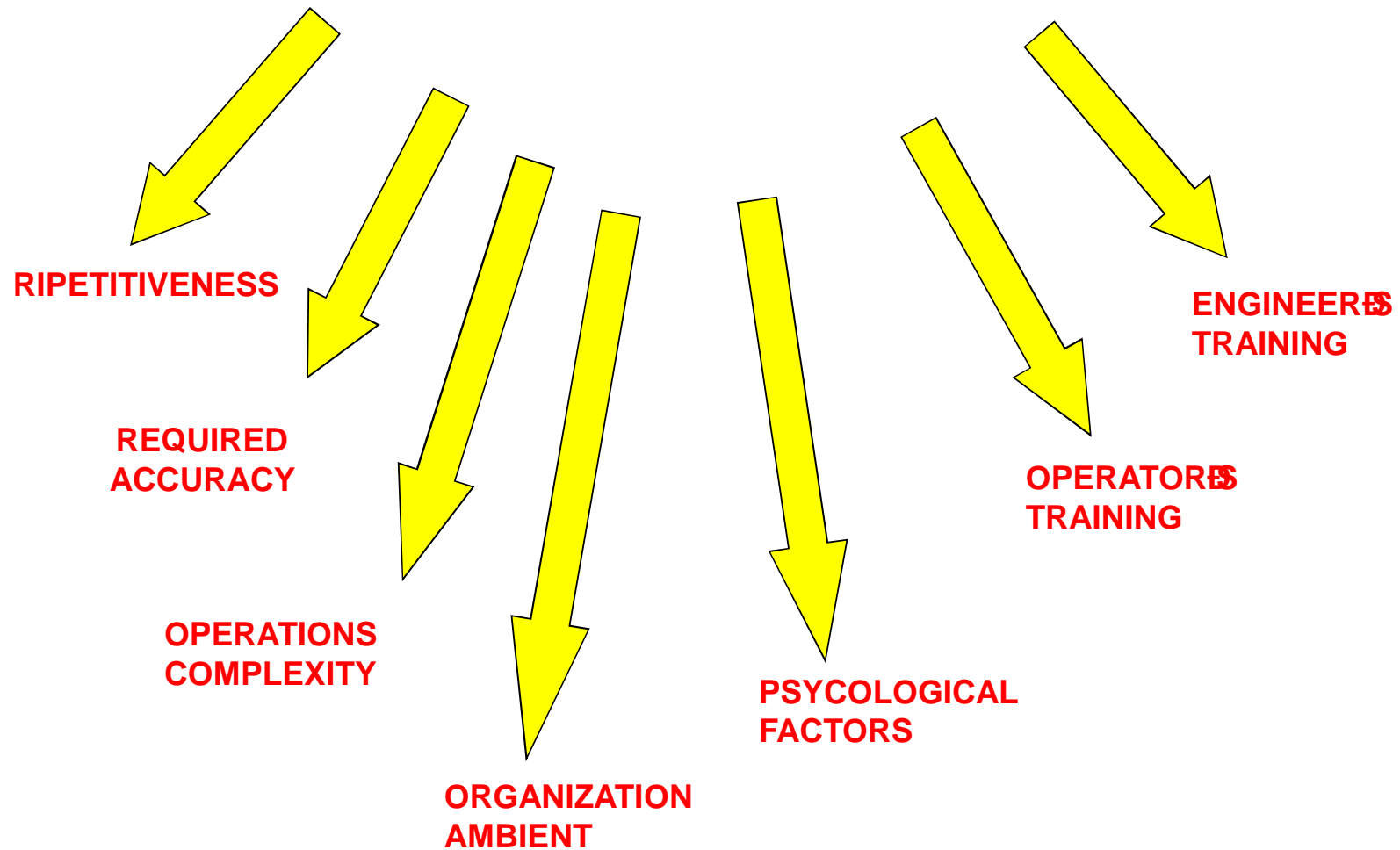


LABOUR TIME PROCEDURE

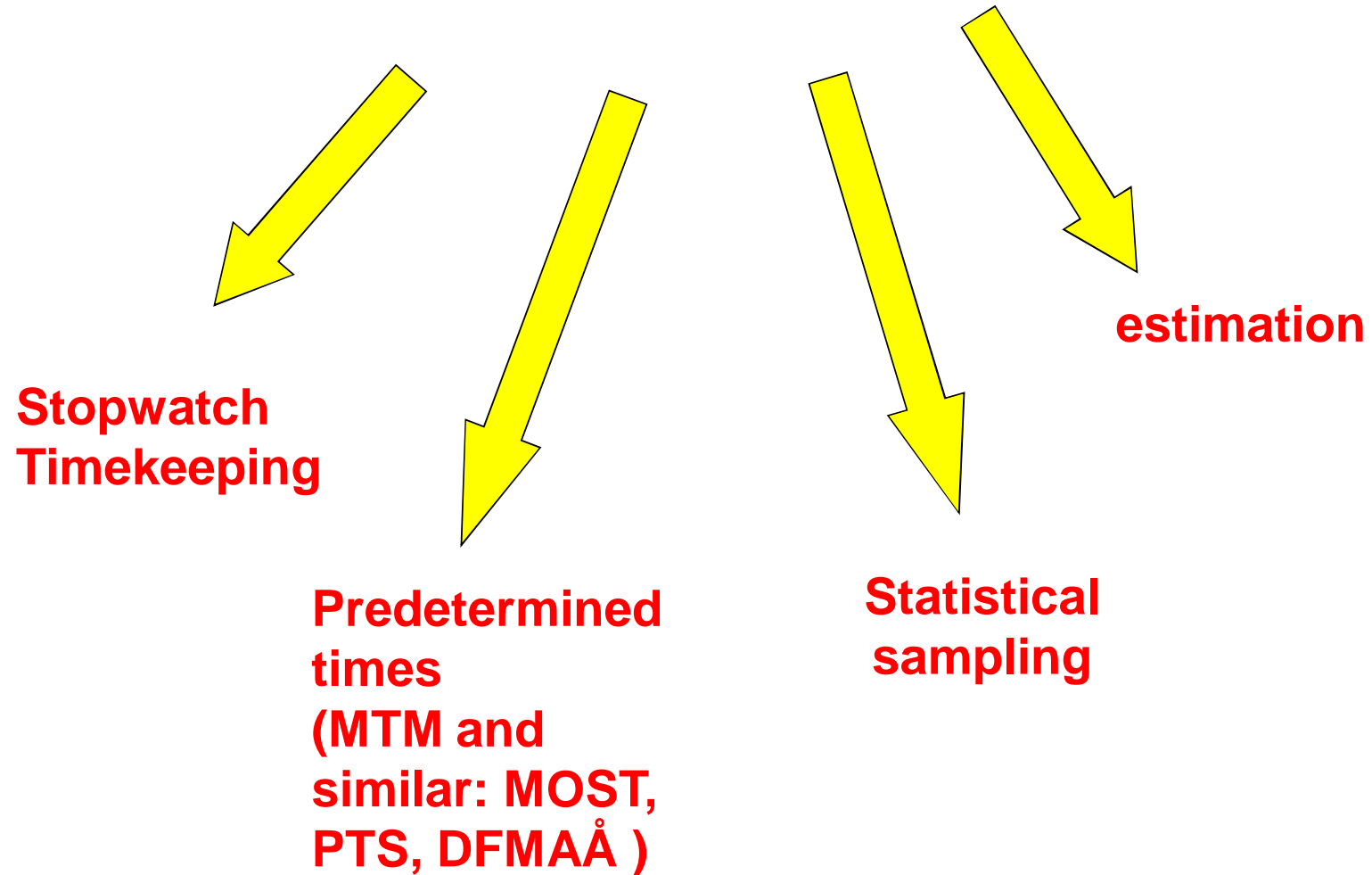




LABOUR TIME INFLUENCING FACTORS



HOW TO ASSIGN LABOUR TIME





LABOUR TIME

TIME-KEEPING

Working Cycle: It is the rational sequence, according with a pre-assigned method, of the work activities, in order to get a certain material transformation.

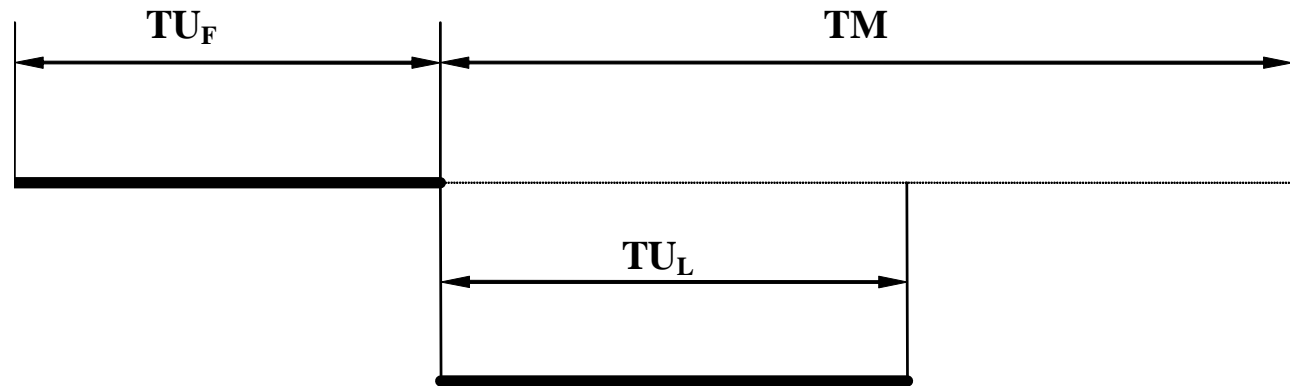
Operation : It is a part of a working cycle grouping together the activities done by the operator, by the machine separately or together in the same working place.

Phase: They are the parts which compose an operation.

Elementary movements: they are the fundamental activities that compose each phase



LABOUR TIME



- TU_F = ELEMENTO DI MACCHINA FERMA OPERATOR TIME WITH IDLE MACHINE
 TM = ELEMENTO DI TEMPO MACCHINA OPERATING MACHINE TIME
 TU_L = ELEMENTI DI MACCHINA LAVORA OPERATOR TIME DURING MACHINE OPERATION TIME



**UNIVERSITÀ
DEGLI STUDI
DI TRIESTE**

LABOUR TIME

**Video tramezzino: Tesi Bianchetti MVI 1133 Video clip
ALF 195 Foto production systems
ALF 201**



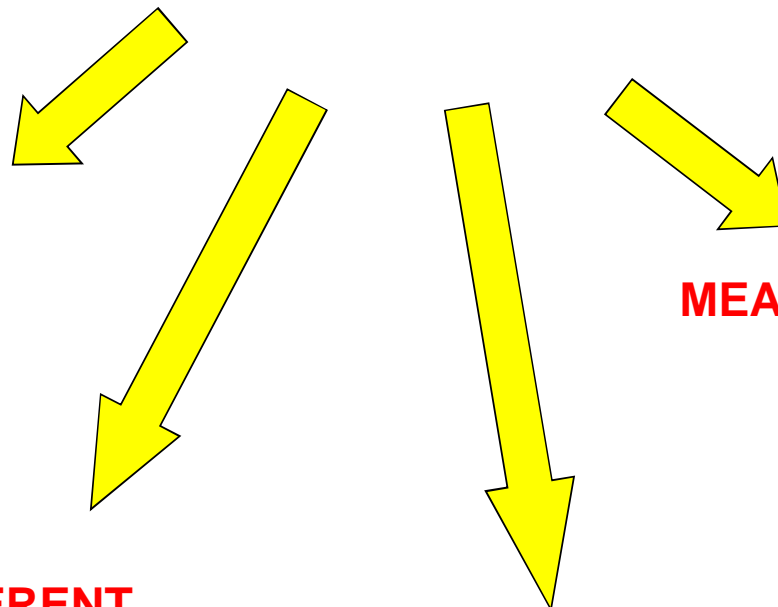
LABOUR TIME *PHASES*

RECOGNIZABLE
(detach point)

MEASURABLE

COHERENT

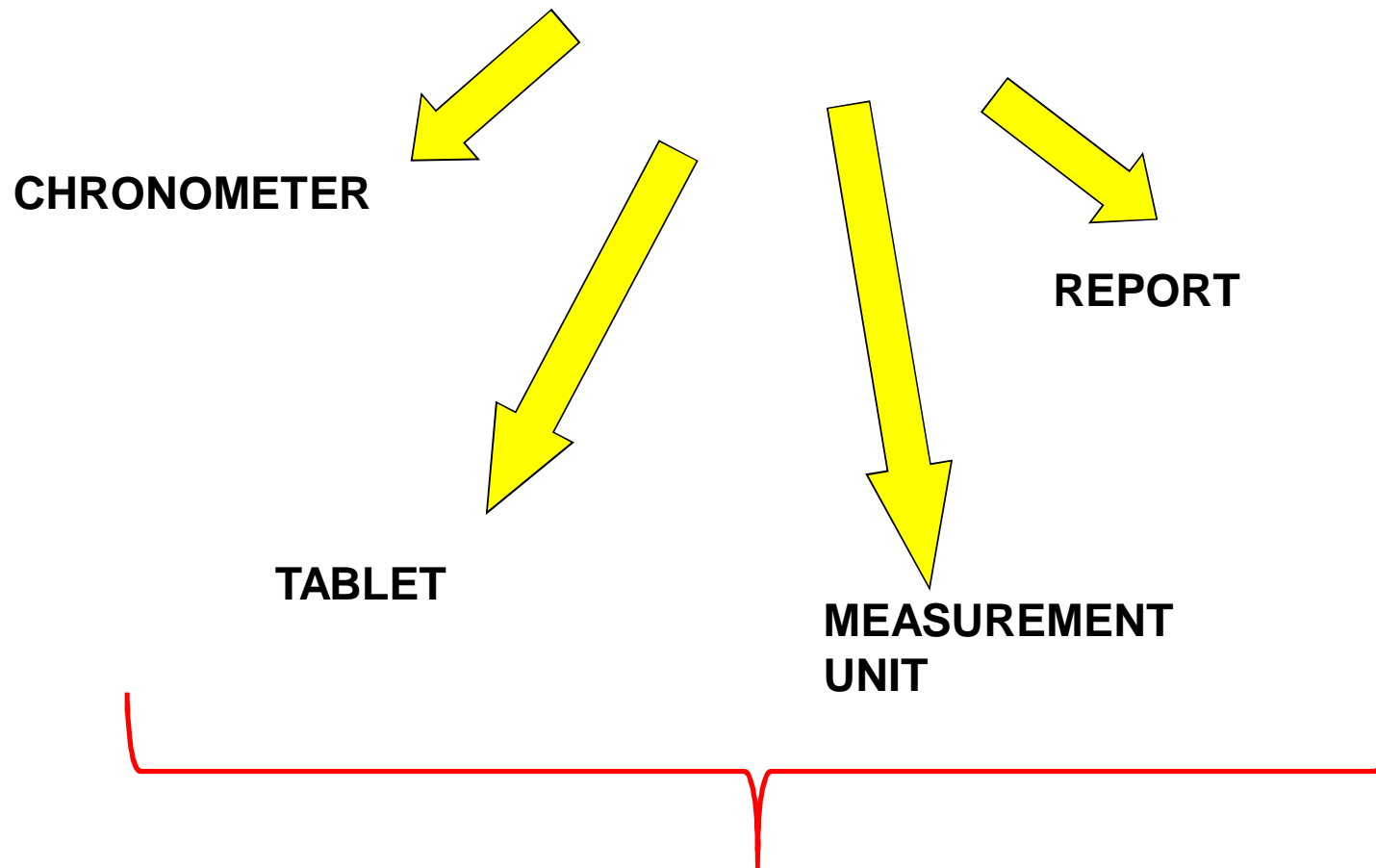
COMPLETE





LABOUR TIME

TIME KEEPING



CHRONOMETER

REPORT

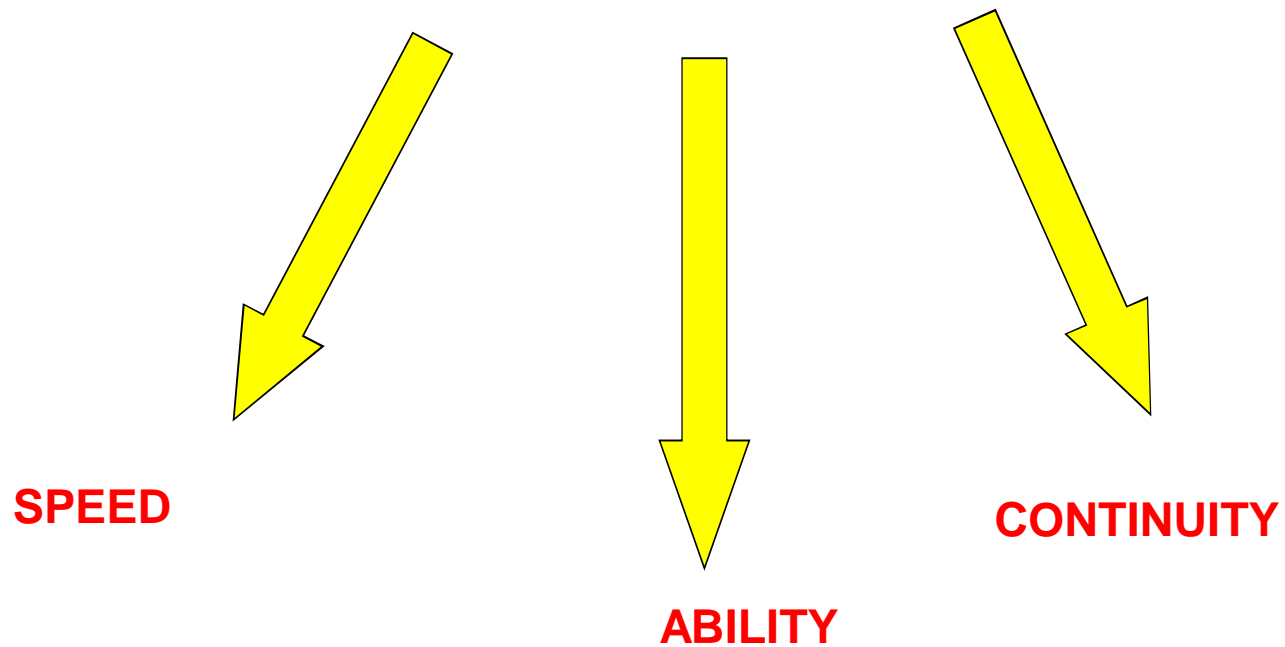
TABLET

MEASUREMENT
UNIT

$T_m = \text{MEASURED TIME}$



LABOUR TIME RITHM EVALUATION



Video productions systems -foto -Alf P1200195 ó testa linea
P1200201 - casseti



LABOUR TIME

RITHM EVALUATION

(INTERNATIONAL LABOUR OFFICE)

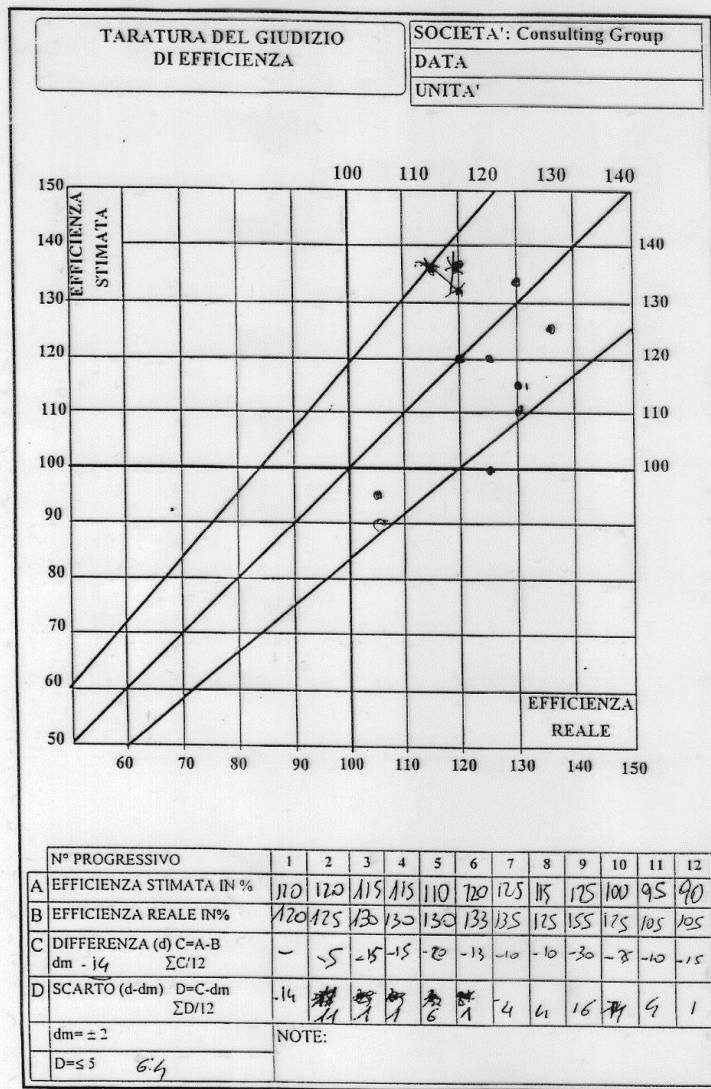
Normal pace: it is the rithm of a normal operator when he works under a good supervision without incentive. This pace can be easily kept day by day without particular mental and phisical stress, and it is characterized by a reasonable level of effort.

The normal performance generally accepted is equivalent to the speed of a man normally built, when he walk without weights and along a straight and plan line at 3 miles/hour (4, 8 Km/h) .



LABOUR TIME RITHM EVALUATION (INTERNATIONAL LABOUR OFFICE)

Rythm	Description		compared speed at miles/h
100/133			
67	Low performance	Very slow, clumsy, lazy movements. The operator looks half asleep, does not show interest in the job.	2
100	Medium performance	Constant performance deliberate, unhurried, a worker who does not work with an incentive, but under good supervision. It seems slow, but the time is not wasted intentionally	3
133	High performance	Performance fast, active, well-trained average worker, who works with incentive. The required standard of quality and precision is achieved without effort.	4
167	Over the average performance	The operator is very fast and reveals a high degree of self-control, skill and coordination of movements much more than an average well-trained operator.	5
200		Operator exceptionally fast, with a capacity of intense concentration and effort. It is unlikely that this rate should be retained for a long time: a "virtuous" performance, reachable only by a few workers champion.	6



LABOUR TIME STUDY

NORMAL TIME

Measured Time T_M

measured keeping into account all the correct executions, not considering those where the operator for any reason could not work with the forecasted method

Judgement on the medium pace G

weighted by the judgements noted for that phase during the time keeping

$$T_N = T_M \times G$$

LABOUR TIME STUDY

NORMAL TIME

$$T_N = \frac{\sum_{i=1}^n T_{Mi} \times G_i}{n}$$

LABOUR TIME STUDY

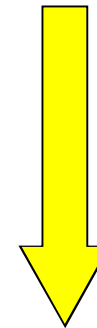
TIME INCREASE



**Physiological
factors**



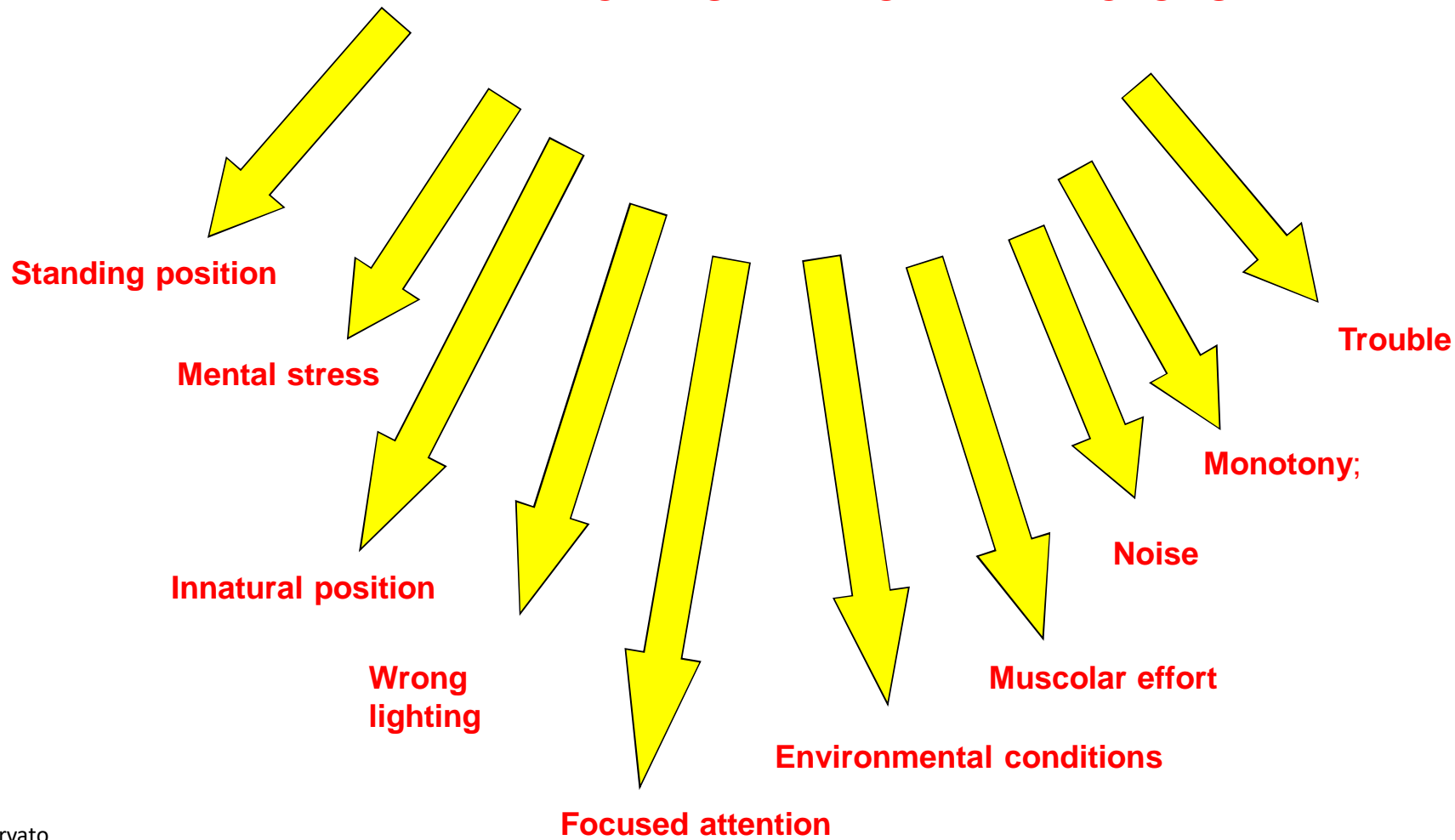
Stress factors





LABOUR TIMES STUDY

TIME INCREASE È IMPORTANT FACTORS



LABOUR TIMES STUDY

TIME INCREASE È IMPORTANT FACTORS

WEIGHT: 2-25% DEPENDING OF THE KGS

EYE STRESS: 1-6% DEPENDING OF DIMENSIONS

MENTAL STRESS: 1-2% DEPENDING ON COMPLEXITY

MONOTONY: 1-5% DEPENDING OF THE WORKING CYCLE

NOISE: 1-3% DEPENDING ON THE LEVEL

HEATING: 1-3% DEPENDING ON THE TEMPERATURE AND HUMIDITY

SMOKE, DUST : 1-3% DEPENDING TO THE QUANTITY

LABOUR TIME STUDY ASSIGNED TIME

Normal Time : $T_N = T_M \times G$

Assigned Time (pace = 100): $T_A = T_N \times (1 + M)$

Assigned Time (pace = 133): $T_A = (T_N \times (1 + M))/1.33$

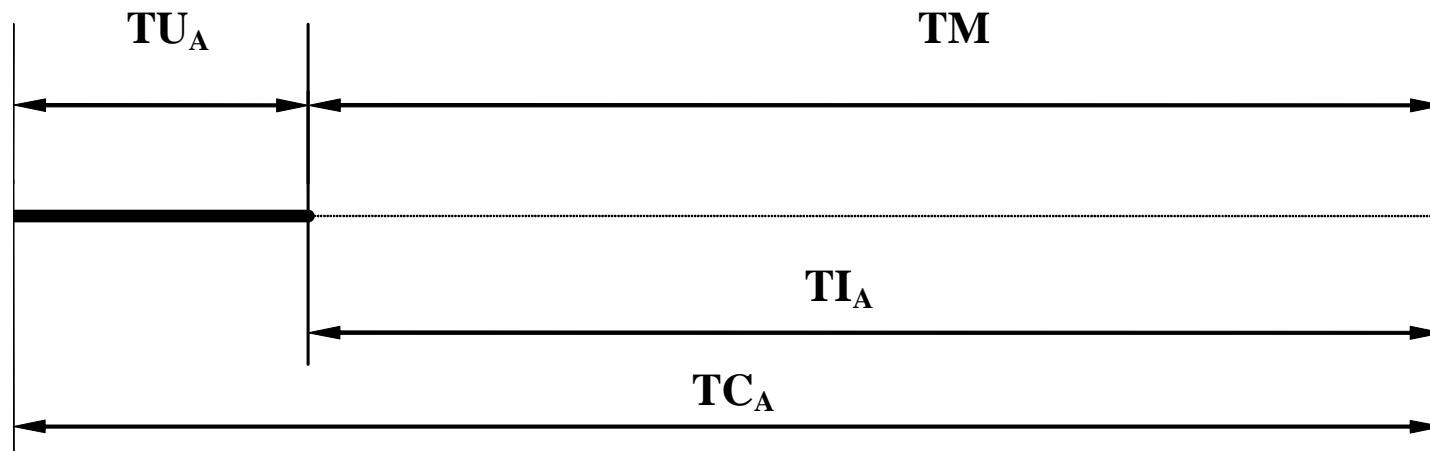
where M is the increase factor

Production per hour : $P_h = \frac{60}{T_{A(133)}}$

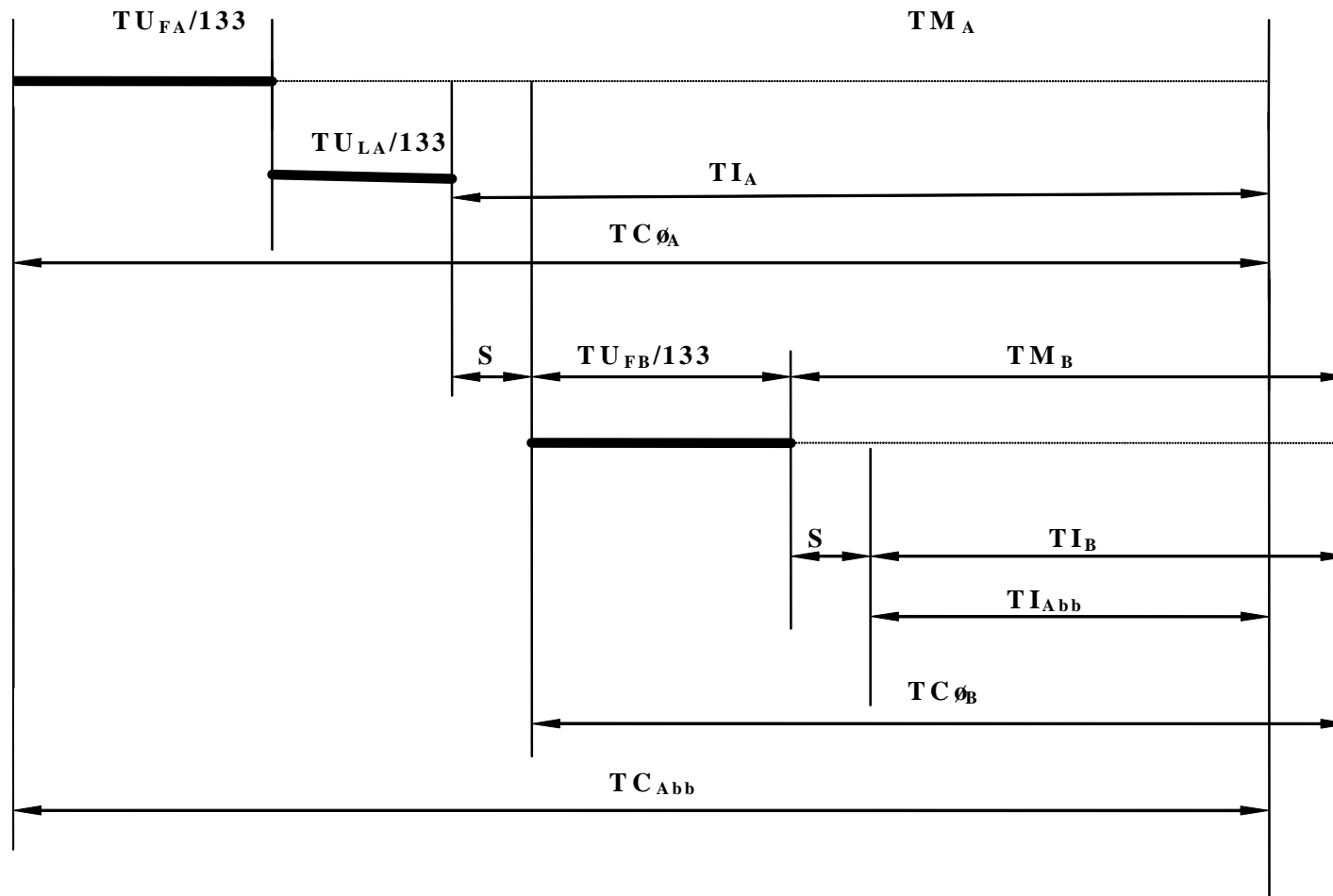


		CRONOMETRAGGIO																Data		Giro N.			
																		11.05.1994		1			
Particolare		ASSIEME MOBILE																					
Operazione N.		1 di 20		Descrizione																SALDARE SQUADRETTA ANTIGOCCE TUBO CARICO			
E DISCO PER FORO A SCHIENALE - ASSIEME MOBILE -																							
Stabilimento		Sezione LB		C. di costo		Reparto		Linea-Gruppo		Codice N.		Modello											
DIST/VPN		186.00		186.03		186.03.03		03		37068.5530		LAVABIANCHERIA CO 210											
Cronometrista		Ora inizio:		Esecutore		Matricola		uomo		donna		IP		S									
		10:20				10642		<input checked="" type="checkbox"/>		<input type="checkbox"/>		<input checked="" type="checkbox"/>		<input type="checkbox"/>									
		Ora fine:																					
		10:50																					
N.	Fasi	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	TR G	TN
1	Prelevare schienali da cont. dist. mt.5 e deporre vicino al banco di lavoro.				306/60						270/40						170/20				1/40	2,487	8,078
					105						120						110					112	
2	Prelevare schienali in prossimità banco di lav. e posizionare su bancate saldabrice.	9	7	7	7	7	8	7	7	8	8	8	9	7	8	8	7	9	9	8	7	0,078	8,183
		130	140	140	140	140	140	140	140	130	130	130	130	135	130	130	135	125	125	125	135	134	
3	Prelevare da cont. pratic-system 1 disco per foro, posizionare e saldare allo schienale con 2 punti.	12	12	15*	11	13	10	10	16	12	15*	10	15	11	11	14	13	12	14	15*	13	0,124	8,155
		125	125	125	125	120	135	135		125	125	135	120	125	125	120	125	120	120	120		125	
4	Prelevare da cont. pratic-system 1 sq. antigocce, posizionare e saldare allo schienale con 3 punti.	18	18	19	16	15	18	17	15	17	18	18	17	17	18	19	18	17	15	16	15	0,171	8,225
		130	130	130	135	135	130	130	135	130	130	130	130	130	130	130	135	135	135	135		132	
5	Togliere schienale da bancate e deporre su carrello distante mt 1	15	17	18	18	17	19	22	19	18	19	15	16	14	15	15	15	19	18	19	18	0,172	8,194
		120	110	110	110	110	110	100	105	115	105	120	120	125	120	120	120	110	110	110	110	113	
6	Rifornimento sq. antigocce davanti mt.5, deporre in cont. pratic-system su banco di lavoro.				80/60				60/40					93/50				80/50			1/50	0,782	8,018
					120				120					105				115				115	
7	Rifornimento dischi per fon. davanti mt.5, deporre in cont. pratic-system su banco di lavoro				40/150						62/300						90/800				1/350	0,640	8,062
					120						125						115					120	
8	Con lima togliere bave da punte elettrodi.										170/350										1/350	0,170	8,061
											120											120	

LABOUR TIME STUDY

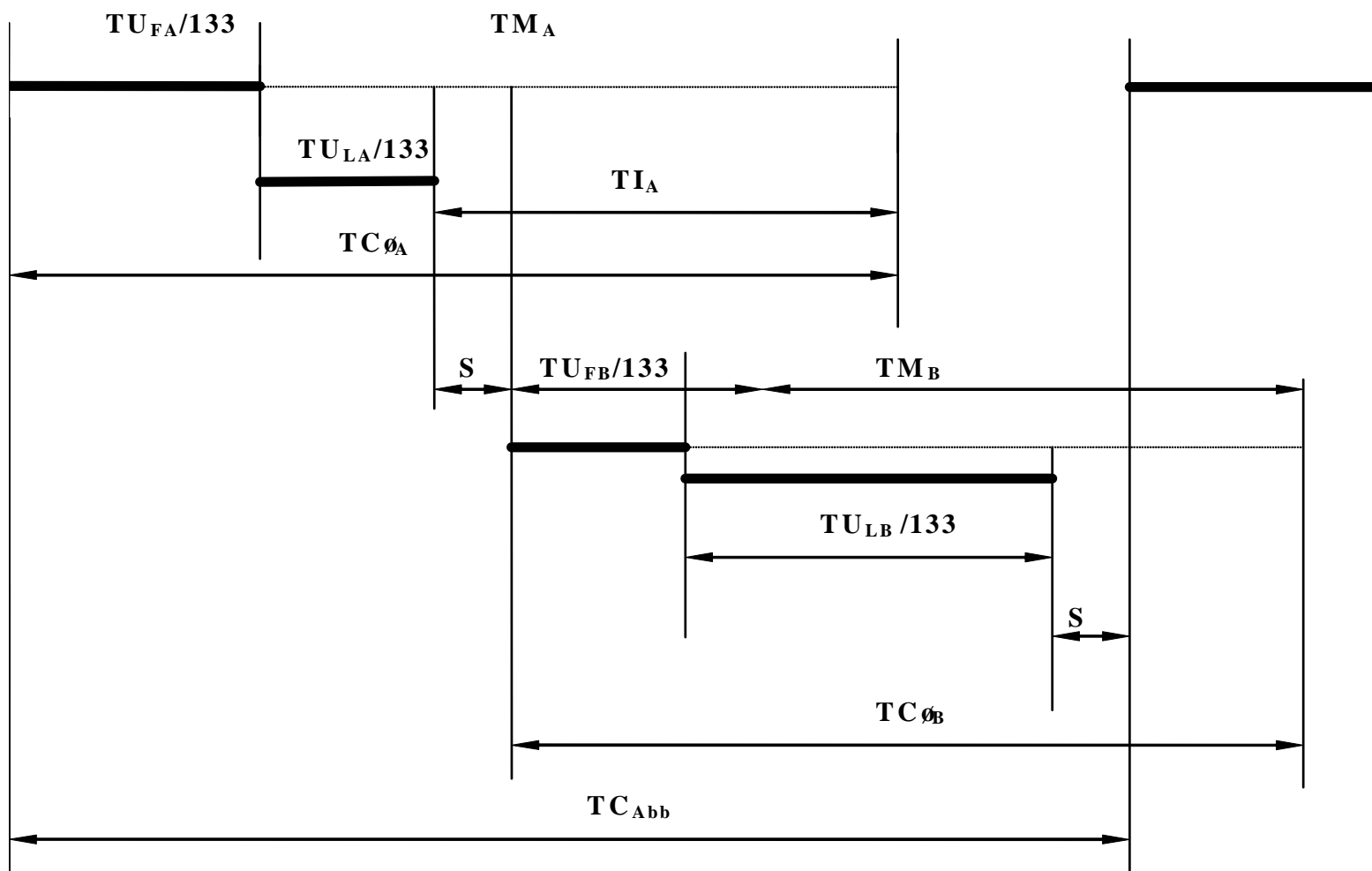


LABOUR TIME STUDY





LABOUR TIME STUDY



LABOUR TIME STUDY

ASSEMBLY LINE

Leveling: it is the activity of distribution of the labour times between the various operators in an assembly line or product flow, in order to assign to each one approximately the same amount of work content

Pilot Time: it is the longest time assigned among the different operators of an assembly line. It corresponds to the time interval between a product and another.

Individual Assigned Time : it is the time strictly necessary to perform the assigned operations

Percentage of leveling: it is the ratio between the sum of individual assigned times and the product of the pilot time and the number of operators along the line.

LABOUR TIME STUDY

ASSEMBLY LINE

Percentage of leveling: it is the ratio between the sum of individual assigned times and the product of the pilot time and the number of operators along the line..

$$L = \frac{\sum_{i=1}^n T a_i}{T_p \times n} \times 100$$

Dove:

L	=	percentuale di livellamento	Percentage of leveling
T _{ai}	=	Tempo assegnato dell'operazione i-esima	Assigned time to the i-operation
T _p	=	Tempo pilota della linea	Pilot time of the assembly line
n	=	numero di operatori	Number of operators along the assembly line

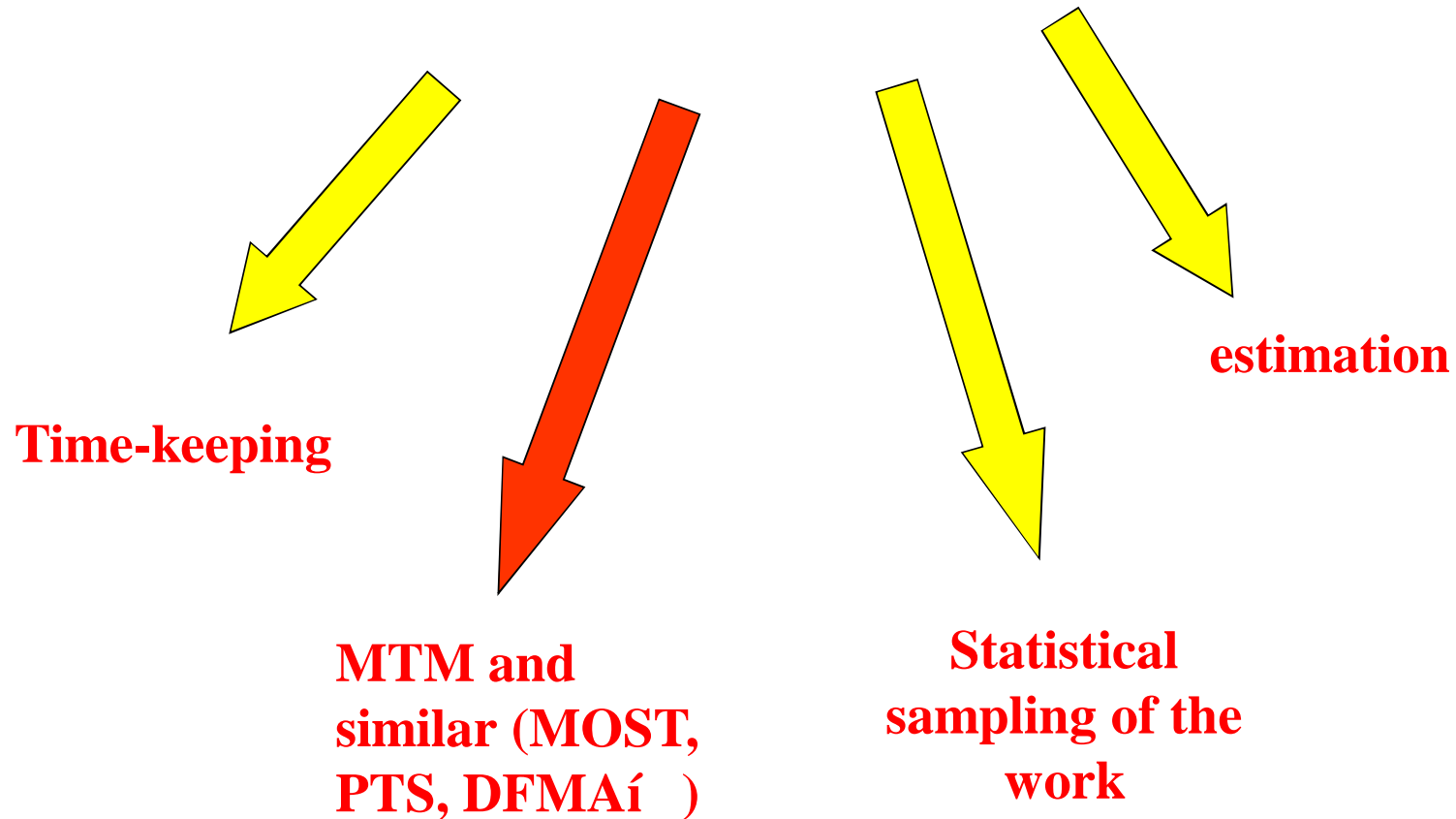
LABOUR TIME STUDY

ASSEMBLY LINE

Number of Workers calculation:

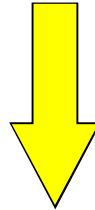
$$W = \frac{T_{a_{TOT}} \times n}{T_P \times (1 - \epsilon_i)}$$

WAYS TO DEFINE THE LABOUR TIMES



LABOUR TIMES
MICRO-MOVEMENTS

FRANK & LILIAN GILBRETH (1920)



THERBLIGS: 17 ELEMENTARY MOVEMENTS

THERBLIGS

1) Movements allowing an efficient work:

Prendere	Grasp	G
Sostenere	Hold	H
Lasciare	Release Load	RL
Accoppiare	Assemble	A
Usare	Use	U
Disaccoppiare	Disassemble	DA
Posizionare	Position	P
Esaminare	Inspect	I

2) Movements limiting an efficient work:

Raggiungere	Transport Empty	TE
Trasportare	Transport Load	TL
Cercare	Search	Sh
Scegliere	Select	St
Preposizionare	Preposition	PP
Decidere	Plan	Pn

3) Movements that are not generating any work:

Riposo per affaticamento	Rest	R
Attesa evitabile	Avoidable delay	AD
Attesa non evitabile	Unavoidable delay	UD

METHODS TIME MEASUREMENT - MTM

“ Maynard, Stegermertens e Schwab,

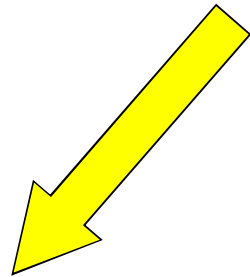
“ Westinghouse 1940 - 1948

“ MTM 1

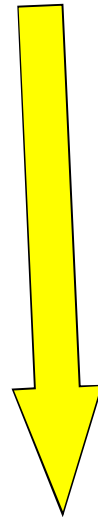
“ MTM 2

“ MTM 3

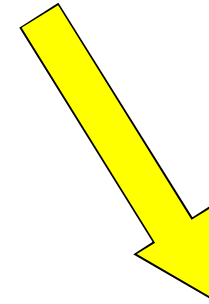
MTM 1



**Movements of the
arms, hands and
fingers**



**Movements of
the eyes**



**Movements of
the body, legs
and feet**

MTM 1

1) Movements of the arms, hands and fingers

<u>Movements</u>	symbol	meaning
Raggiungere	R	Reach
Muovere	M	Move
Ruotare	T	Turn
Girare volantino	C	Crank
Applicare Press.	AP	Apply pressure
Prendere	G	Grasp

3) Movements of the body, legs and feet:

<u>Movements</u>	symbol	meaning
Muovere il piede	FM	foot motion
Muovere la gamba	LM	leg motion
Passo laterale	SS	side step
Ruotare il corpo	TB	turn body
Abbassarsi	B	Bend
Inginocchiarsi	K	Kneel
Sedersi	SIT	Sit
Alzarsi da seduto	STD	Stand
Camminare	W	Walk

2) Movements of the eyes:

<u>Movements</u>	symbol	meaning
Fissare lo sguardo	EF	Eye focus
Muovere gli occhi	ET	Eye turn



MTM Units

$$\begin{aligned} 1 \text{ TMU} &= 1/100.000 \text{ h} \\ &= 6/10.000 \text{ minute} \\ &= 36/1000 \text{ second} \\ &= 0.06 \text{ hundredth of minute} \end{aligned}$$

100.000 TMU	to have	1 hour
1.666 TMU	to have	1 minute
28 TMU	to have	1 second
16.7 TMU	to have	1 hundredth of minute



MTM 1 - R

Distance Moved (in.)	Time TMU				Wt. Allowance			Case and Description
	A	B	C	Hand in Motion B	Wt. (lb) Up to	Dynamic Factor	Static Constant (TMU)	
¼ or less	2.0	2.0	2.0	1.7				A Move object to other hand or against stop.
1	2.5	2.9	3.4	2.3	2.5	1.00	0	
2	3.6	4.6	5.2	2.9				
3	4.9	5.7	6.7	3.6	7.5	1.06	2.2	
4	6.1	6.9	8.0	4.3				
5	7.3	8.0	9.2	5.0	12.5	1.11	3.9	
6	8.1	8.9	10.3	5.7				
7	8.9	9.7	11.1	6.5	17.5	1.17	5.6	B Move object to approximate or indefinite location.
8	9.7	10.6	11.8	7.2				
9	10.5	11.5	12.7	7.9	22.5	1.22	7.4	
10	11.3	12.2	13.5	8.6				
12	12.9	13.4	15.2	10.0	27.5	1.28	9.1	
14	14.4	14.6	16.9	11.4				
16	16.0	15.8	18.7	12.8	32.5	1.33	10.8	
18	17.6	17.0	20.4	14.2				C Move object to exact location.
20	19.2	18.2	22.1	15.6	37.5	1.39	12.5	
22	20.8	19.4	23.8	17.0				
24	22.4	20.6	25.5	18.4	42.5	1.44	14.3	
26	24.0	21.8	27.3	19.8				
28	25.5	23.1	29.0	21.2	47.5	1.50	16.0	
30	27.1	24.3	30.7	22.7				
Additional	0.8	0.6	0.85		TMU per inch over 30 inches			

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MTM 1

Left hand description	F	Left hand movement	TMU	Right hand movement	F	Right hand description
SCREW 2 BOLTS						
Reach the bolt		R24C	12.5	R24C		Reach the bolt
Grasp		G4B	9.1	-		Grasp
		-	9.1	G4B		
Bolt to assembly		M24C	13.0	M24C		Bolt to assembly
Position 1 st bolt		P2SE	16.2	-		
Search thread	2	M2B	4.0	-	2	Position 1 st bolt Search thread
		-	16.2	P2SE		
		-	4.0	M2B		
Release		RL1	2.0	RL1		Release
fastening cycle	8	R2A	16.0	R2A	8	fastening cycle
		G1A	16.0	G1A		
		M2B	16.0	M2B		
		RL1	16.0	RL1		
		Total	150.1			
TIGHTEN 2 BOLTS WITH A WRENCH						
Reach the assembly		R-A	12.8	R30B		Reach the wrench
Grasp		G1A	3.5	G1B		Grasp Wrench to assembly Position Static component Screw Recovery with wrench Reposition wrench Static component Screw Tighten Recovery with wrench Release
			15.1	M30C		
			14.7	P1SSD		
			1.6	SC2		
			10.9	M20B2		
			11.7	M20C		
			14.7	P1SSD		
			1.6	SC2		
			9.6	M16B2		
			10.6	APA		
			13.3	M30B		
			2.0	RL1		
			Total	122.1		



MTM - 3

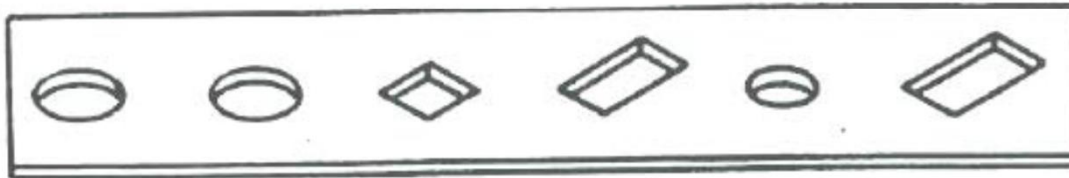
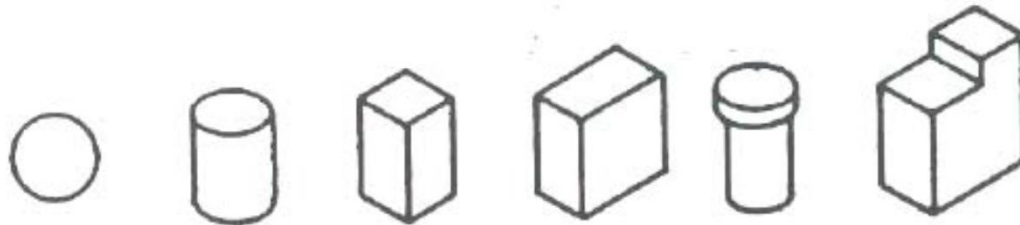
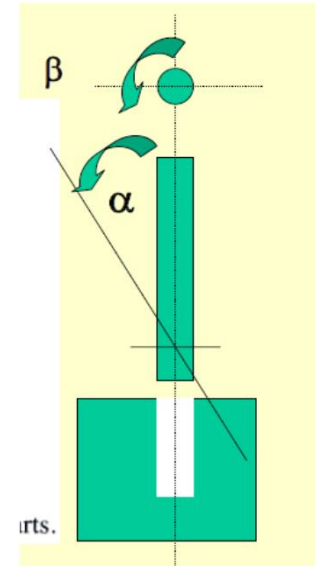
MILL. : 0.06
 SEC. X 0.036 (3600 : 100000)
 TMU : 0.036
 SEC. X 0.036 (3600 : 100000)
 TMU : 0.036
 MILL. : 0.06
 SEC. X 0.036 (3600 : 100000)
 TMU : 0.036

TABELLA PER LA DETERMINAZIONE DEI TEMPI STD DI ASSEMBLAGGIO		DATA AGGIORNAMENTO	22.01.87	11.03.87				
OTTENERE		STIMOLA	5	15	30	45	60	75
OGGETTO CON 1-2 MANI 1-2 OGGETTI		OG	5	8	10	13	15	18
CONTROLLATO	1 MANI 1-2 OGGETTI	OGLU	10	13	15	18	20	23
		OGLD	18	20	23	25	28	30
	2 MANI 1-2 OGGETTI	OCPU	13	15	17	20	22	25
		OCPD	22	25	28	30	32	35
RACIATA DI OGGETTI		OM	19	22	25	27	29	32
VALORI SOPPLEMENTARI PER	OTTENERE OGGETTO CON 2 MANI	DM	18					
	SCROLLARE OGGETTI	SO	5					
	OTTENERE PER SCORRIENTO	DS	10					
PIAZZARE		STIMOLA	5	15	30	45	60	75
OGGETTO CON 1-2 MANI 1-2 OGGETTI		PG	4	6	8	11	13	15
LARGO	1-2 MANI 1-2 OGGETTI	PLU	7	10	13	16	19	22
	2-3 MANI 1-2 OGGETTI	PLD	16	19	22	25	28	31
STRETTO	1-2 MANI 1-2 OGGETTI	PSU	13	16	19	22	25	28
	2-3 MANI 1-2 OGGETTI	PSD	26	31	34	37	40	43
VALORI SOPPLEMENTARI PER	TENUTA SPECIFICHE	TD	4					
	AS	AS	3					
	PESO (ogni mano 10-15 ogni 20-25 kg max. ogni)	P	1					
	OGGETTI RIPORTAMENTO CICLO	RCL	6					
	OGGETTI RIPORTO	RCS	16					
	CONTROLO VISIVO ACQUETRIZIA	CVA	8					
INTEGRATIVI		STIMOLA	TEMPI					
OGNI PIAZZARE CICLO DI ATTREZZI O PARTI		IPC	16					
APPLICARE FORZA		IAF	7					
MUDERE DIST. RIPRODURRE		IDR	4					
RUBARE		DESTA	11					
		PIERD	12					
MOVIMENTI ALTERNATIVI		OGGETTI OG CH	IAC					
		OGGETTI 610 CH	IAM					
		LUNDE 610 CH	IAL					
RIPRODURRE AL PAS- SAGGIO DI PARTI ATTREZZI, PARTI, DESTA		OGGETTI TPO, M13 OG	IIN					
		OGGETTI TPO, S OG	IIS					
RIPRODURRE DISTANZA (OGGETTI 18 CH DI PERI)		OTTENERE PIAZZARE, OGGETTI	IMD					
		PIAZZARE SUCCESSIVO	IMDS					
MOVIMENTI DEL CORPO		CARRIAGE	IMC					
		FORNIRE O SOLLICITARE OGGETTI O OGGETTI	IMP					
		OGGETTI O PIAZZARE	IMS					
USO OGGETTI		SPORTARE OGGETTO OGGETTI	IOS					
		LUNDE OGGETTI O LETTERE	IOL					
		PIAZZARE OGGETTO	IOF					
AZIONARE		STIMOLA	DISTANZE PER OTTENERE CH					
ALLAVITE O LEVETTA DI CORNIO		OGGETTI OGGETTI	0	25	45	65	85	105
		OGGETTI OGGETTI	AP	1	6	9	11	14
RIPAZZARE DI CORNIO		OGGETTI OGGETTI	APF	8	13	16	18	21
		OGGETTI OGGETTI	AMS	9	14	17	19	22
PEDALE DI CORNIO		OGGETTI OGGETTI	AMG	13	17	20	23	25
		OGGETTI OGGETTI	APE	5	10	14	19	23
VALANTINO O RONDINELLA		OGGETTI OGGETTI	AVP	10	15	18	20	23
		OGGETTI OGGETTI	AVP	10	15	18	20	23
USO ATTREZZI		STIMOLA	50	27	17			
OGGETTI		UAG	50	27	17			
LUNDE		UAL	31	10	15			
OGGETTI		UAC	31	10	15			
OGGETTI		UAM	31	10	15			
OGGETTI (OGGETTI METALLICI)		UAPC	34	7	16			
OGGETTI A MOLLA (OGGETTI, TRONCHI)		UAPG	38	14	15	29		
OGGETTI		UAF	67	20	15			
USO PER TENERE O TRASPORTARE								
USO PER PIEDARE, TORCERE TRANCARE, COMPORRE								
* NEL TABULATO SOTTO SU OGNETTO ASSIEME UN VALORE DI PIU' VARIABILE * PUU' UN APPLICARE FORZA (IAF-7) PER LA LUNGHEZZA TOTALE DI OGNETTO TABULATO								
FISSARE		STIMOLA	80	43				
VITI-DADI-RONDELLE		OGGETTI	80	43				
CON CACCIAVITE GENERICI O CHIAVE A TUBO		OGGETTI OGGETTI	FVGM	80	43			
		OGGETTI OGGETTI	FVGS	67	59		22	
		OGGETTI OGGETTI	FVGI	44	26			
CON CACCIAVITE PNEUMATICI		OGGETTI OGGETTI	FVPM	87	50			
		OGGETTI OGGETTI	FVPS	74	66		0,6	
		OGGETTI OGGETTI	FVPA	44	26		2,4	
OGNETTI FISSAVITI GIU' (OGNETTI) (2) (1/4 DI GIRO 90°)		OGGETTI OGGETTI	FVPI	48	30			
		OGNETTI OGNETTI	FVFI	45	22		24	
A MANO E PRESA		OGNETTI OGNETTI	FVMM	76	35			
		OGNETTI OGNETTI	FVMS	40			22	
RONDINELLA SU VITE E PRESA		OGNETTI OGNETTI	FRVM	73	32			
		OGNETTI OGNETTI	FRVM	78	37			
		OGNETTI OGNETTI	FRVSR	59				
		OGNETTI OGNETTI	FRVSO	64				
		OGNETTI OGNETTI	FRSS	24				
PER VITI METRICHE O AUTOFILET- TANTI (CON BARILE SPRECTORI)								
PER VITI AUTOFILETANTI CON SPRECTORI DI LARGHEZZA OGNETTI E OLTRA O VITI CON OGNETTI								
FASTON		STIMOLA	60					
A MANO		FFM	60					
A MANO CON USO PINZA		PRIMO	FFMP	108				
		SUCCESSIVO	FFMP/S	84				
ANELLO ELASTICO		OGNETTI PIAZZARE (1) USARE E OGNETTI (1,5-30 CH)	PS					
SEEGER		FAS	204	169				
STAFFA		OGNETTI OGNETTI	FSC	74	63			
		OGNETTI OGNETTI	FSM	134	116			
ELASTICO IN GOMMA (1) CON UN GIRO O 2 AGGANCI (2) OGNETTI SUCCESSIVO		FEG	55	119				
RIFORMIMENTI		STIMOLA						
TAGLIARE								
NASTRO ADESIVO SCATOLE								
APERTURE FALDE SCATOLE		OGNETTI OGNETTI	RAFS/P	128				
OGNETTI (FORMATO 1)		OGNETTI OGNETTI	RAFS/S	250				
STACCARE ZONA PUNTATA		RTPS	65					
SACCHETTO PROTEZIONE		APPLICARE	RASP	197				

BOOTHROYD-DEWHURST METHOD

Experience shows there are two distinct operations in this:

1. Alignment of the axis of the part that corresponds to the axis of insertion
 - called alpha rotation, α .
2. Rotation of the part about its axis of insertion
 - called beta rotation, β .



α	0	180	180	90	360	360
β	0	0	90	180	0	360

Source: Motorola



Estimated Handling Time Table

Total axis of symmetry

Size of Part

Time used later

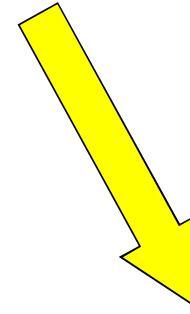
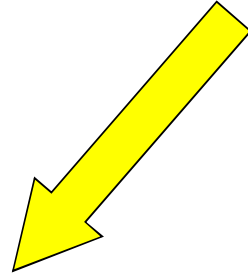
How handled

Source: Design for Assembly, © Boothroyd & Dewhurst 1983

Key: ■ ONE HAND

	parts are easy to grasp and manipulate					parts present handling difficulties (1)																																																																																																															
	thickness > 2 mm		thickness ≤ 2 mm			thickness > 2 mm		thickness ≤ 2 mm																																																																																																													
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	0	1	2	3	4	5	6	7	8	9																																																																																																											
parts can be grasped and manipulated by one hand without the aid of grasping tools	<table border="1"> <tr> <td>$(\alpha + \beta) < 360^\circ$</td> <td>0</td><td>1.13</td><td>1.43</td><td>1.88</td><td>1.69</td><td>2.10</td><td>1.84</td><td>2.17</td><td>2.65</td><td>2.45</td><td>2.98</td> </tr> <tr> <td>$360^\circ \leq (\alpha + \beta) < 540^\circ$</td> <td>1</td><td>1.5</td><td>1.8</td><td>2.25</td><td>2.06</td><td>2.55</td><td>2.25</td><td>2.57</td><td>3.06</td><td>3</td><td>3.38</td> </tr> <tr> <td>$540^\circ \leq (\alpha + \beta) < 720^\circ$</td> <td>2</td><td>1.8</td><td>2.1</td><td>2.55</td><td>2.36</td><td>2.85</td><td>2.57</td><td>2.9</td><td>3.38</td><td>3.18</td><td>3.7</td> </tr> <tr> <td>$(\alpha + \beta) = 720^\circ$</td> <td>3</td><td>1.95</td><td>2.25</td><td>2.7</td><td>2.51</td><td>3</td><td>2.73</td><td>3.06</td><td>3.55</td><td>3.34</td><td>4</td> </tr> </table>											$(\alpha + \beta) < 360^\circ$	0	1.13	1.43	1.88	1.69	2.10	1.84	2.17	2.65	2.45	2.98	$360^\circ \leq (\alpha + \beta) < 540^\circ$	1	1.5	1.8	2.25	2.06	2.55	2.25	2.57	3.06	3	3.38	$540^\circ \leq (\alpha + \beta) < 720^\circ$	2	1.8	2.1	2.55	2.36	2.85	2.57	2.9	3.38	3.18	3.7	$(\alpha + \beta) = 720^\circ$	3	1.95	2.25	2.7	2.51	3	2.73	3.06	3.55	3.34	4																																																										
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ONE HAND with GRASPING AIDS	<table border="1"> <tr> <th colspan="10">parts need tweezers for grasping and manipulation</th> <th rowspan="2">parts need standard tools other than tweezers</th> <th rowspan="2">parts need special tools for grasping and manipulation</th> </tr> <tr> <th colspan="5">parts can be manipulated without optical magnification</th> <th colspan="5">parts require optical magnification for manipulation</th> </tr> <tr> <th colspan="2">parts are easy to grasp and manipulate</th> <th colspan="3">parts present handling difficulties (1)</th> <th colspan="2">parts are easy to grasp and manipulate</th> <th colspan="3">parts present handling difficulties (1)</th> <th colspan="2"></th> </tr> <tr> <th>thickness > 0.25mm</th> <th>thickness ≤ 0.25mm</th> <th>thickness > 0.25mm</th> <th>thickness ≤ 0.25mm</th> <th>thickness > 0.25mm</th> <th>thickness ≤ 0.25mm</th> <th>thickness > 0.25mm</th> <th>thickness ≤ 0.25mm</th> <th>thickness > 0.25mm</th> <th>thickness ≤ 0.25mm</th> <th colspan="2"></th> </tr> <tr> <th>0</th><th>1</th><th>2</th><th>3</th><th>4</th><th>5</th><th>6</th><th>7</th><th>8</th><th>9</th><th colspan="2"></th> </tr> <tr> <td>4</td><td>3.6</td><td>6.85</td><td>4.35</td><td>7.6</td><td>5.6</td><td>8.35</td><td>6.35</td><td>8.6</td><td>7</td><td>7</td><td></td> </tr> <tr> <td>5</td><td>4</td><td>7.25</td><td>4.75</td><td>8</td><td>6</td><td>8.75</td><td>6.75</td><td>9</td><td>8</td><td>8</td><td></td> </tr> <tr> <td>6</td><td>4.8</td><td>8.05</td><td>5.55</td><td>8.8</td><td>6.8</td><td>9.55</td><td>7.55</td><td>9.8</td><td>8</td><td>9</td><td></td> </tr> <tr> <td>7</td><td>5.1</td><td>8.35</td><td>5.85</td><td>9.1</td><td>7.1</td><td>9.55</td><td>7.85</td><td>10.1</td><td>9</td><td>10</td><td></td> </tr> </table>											parts need tweezers for grasping and manipulation										parts need standard tools other than tweezers	parts need special tools for grasping and manipulation	parts can be manipulated without optical magnification					parts require optical magnification for manipulation					parts are easy to grasp and manipulate		parts present handling difficulties (1)			parts are easy to grasp and manipulate		parts present handling difficulties (1)					thickness > 0.25mm	thickness ≤ 0.25mm	thickness > 0.25mm	thickness ≤ 0.25mm	thickness > 0.25mm	thickness ≤ 0.25mm	thickness > 0.25mm	thickness ≤ 0.25mm	thickness > 0.25mm	thickness ≤ 0.25mm			0	1	2	3	4	5	6	7	8	9			4	3.6	6.85	4.35	7.6	5.6	8.35	6.35	8.6	7	7		5	4	7.25	4.75	8	6	8.75	6.75	9	8	8		6	4.8	8.05	5.55	8.8	6.8	9.55	7.55	9.8	8	9		7	5.1	8.35	5.85	9.1	7.1	9.55	7.85	10.1	9	10	
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TWO HANDS for MANIPULATION	<table border="1"> <tr> <th colspan="11">TWO HANDS or assistance required for LARGE SIZE</th> </tr> <tr> <td>two hands, two persons or mechanical assistance required for grasping and transporting parts</td> <td colspan="11"></td> </tr> </table>											TWO HANDS or assistance required for LARGE SIZE											two hands, two persons or mechanical assistance required for grasping and transporting parts																																																																																														
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Further system using predetermined labour times



MOST
Maynard Operations Sequence
Technique
(Ziell Zandin -1980)

PTS ó Predetermined
times system (Cegos 1990)



MOST

Maynard Operations Sequence Technique

Activity	Sequence model	Parameter
General Move	ABG ABP A	A- Action distance
		B- Body Motion
		C - Gain control
		P - Placement
Controlled Move	ABG MXI A	M - Move controlled
		X - Process Time
		I - Alignment
Tool use	ABG ABP*ABP A	F7L - fasten/loosen
		C- cut
		S - surface treat
		M - measure
		R - Record
		T - Think

MOST

Maynard Operations Sequence Technique

General Move. The General Move sequence is applicable when an object is moved through the air from one location to another. There are four parameters (actions) in the General Move, symbolized by letters of the alphabet:

A — Action distance, usually horizontal. This parameter is used to describe movements of the fingers, hands, or feet (e.g., walking). The movement can be performed either loaded or unloaded.

B — Body motion, usually vertical. This parameter defines vertical body motions and actions (e.g., sitting, standing up).

G — Gain control. This parameter is used for any manual actions involving the fingers, hands, or feet to gain physical control of one or more objects. It is closely related to the grasp motion element in MTM (e.g., grasp the object).

P — Placement. The placement parameter is used to describe the action involved to lay aside, position, orient, or align an object after it has been moved to the new location (e.g., position the object).

MOST

Maynard Operations Sequence Technique

TABLE 14.6 MOST Parameters and Index Values for the General Move Activity Sequence Model

General Move activity sequence model = A B G A B P A				
Index	A = Action distance	B = Body motion	G = Gain control	P = Placement
0	Close \leq 5 cm (2 in.)			Hold, Toss
1	Within reach (but $>$ 2 in.)		Grasp light object using one or two hands	Lay aside Loose fit
3	1 or 2 steps	Bend and arise with 50% occurrence	Grasp object that is heavy, or obstructed, or hidden, or interlocked	Adjustments, light pressure, double placement
6	3 or 4 steps	Bend and arise with 100% occurrence		Position with care, or precision, of blind, or obstructed, or heavy pressure
10	5, 6, or 7 steps	Sit or stand		
16	8, 9, or 10 steps	Through door, or Climb on or off, or Stand and bend, or Bend and sit		

MOST

Maynard Operations Sequence Technique

Example: General Move Develop the activity sequence model and determine the normal time for the following work activity: A worker walks 5 steps, picks up a small part from the floor, returns to his original position, and places the part on his worktable.

Solution: Referring to Table 14.6, the indexed activity sequence model for this work activity would be the following:

$A_{10} B_6 G_1 A_{10} B_0 P_1 A_0$

where A_{10} = walk 5 steps, B_6 = bend and arise, G_1 = control of small part, A_{10} = walk back to original position, B_0 = no body motion, P_1 = lay aside part on table, and A_0 = no motion. The sum of the index values is 28. Multiplying by 10, we have 280 TMUs (about 17 sec).

Analysis Time of one standard hour

PTS : **1 hour**

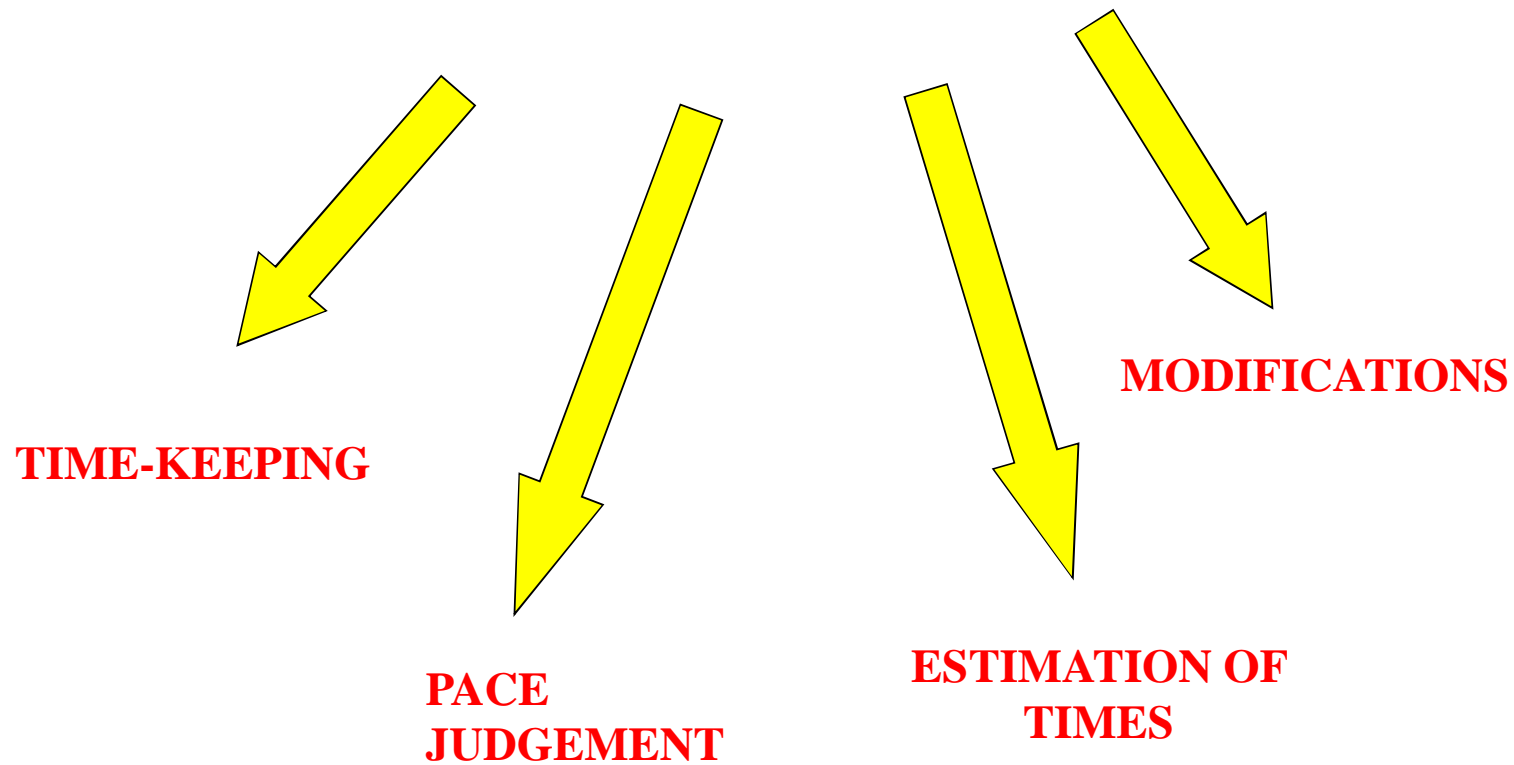
MOST: **5 hours**

TIME-KEEPING: **15 hours**

MTM: **40 hours**



MTM - ADVANTAGES



MTM - DISADVANTAGES



ANALYSIS TIME



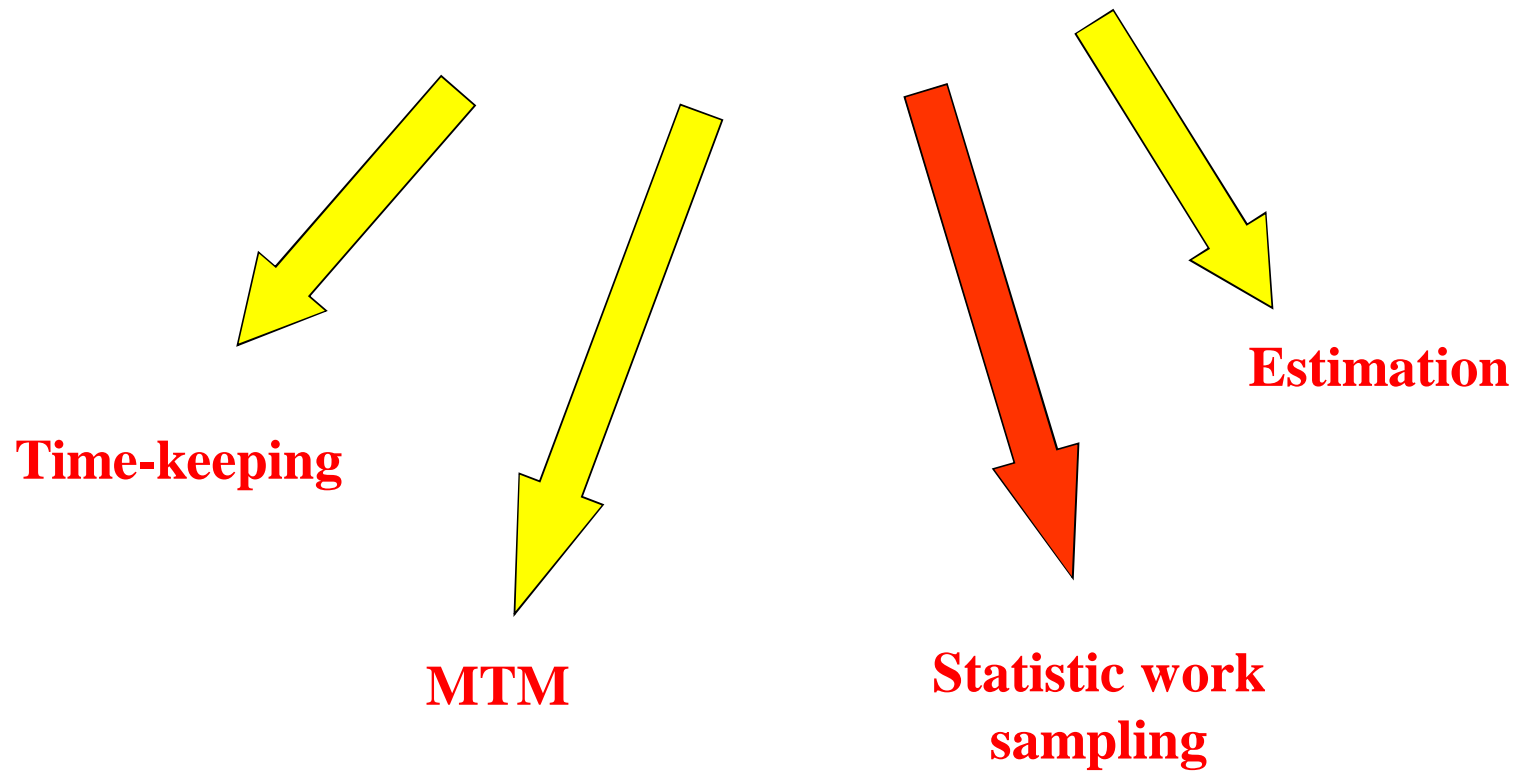
**RIPETITIVE
OPERATIONS**



**SPECIFIC LONG
TRAINING**



WAY TO ASSIGN LABOUR TIMES



STATISTICAL WORK SAMPLING

ÉL.H.C. Tippett
É1935
ÉTextile industry

the number of observations recorded over the entire field of investigation is related to the number of observations to each work as the total time of the analysis is related to the time necessary to perform each of them.

$$\mathbf{N : n = T : t}$$

STATISTICAL WORK SAMPLING

“ **Statistical** technique for determining the proportions of time spent by **subjects** in various defined **categories of activity**

“ **Subjects = workers** labour, machines

“ **Categories of activity = setting up a machine, producing parts, wasted times, etc.**

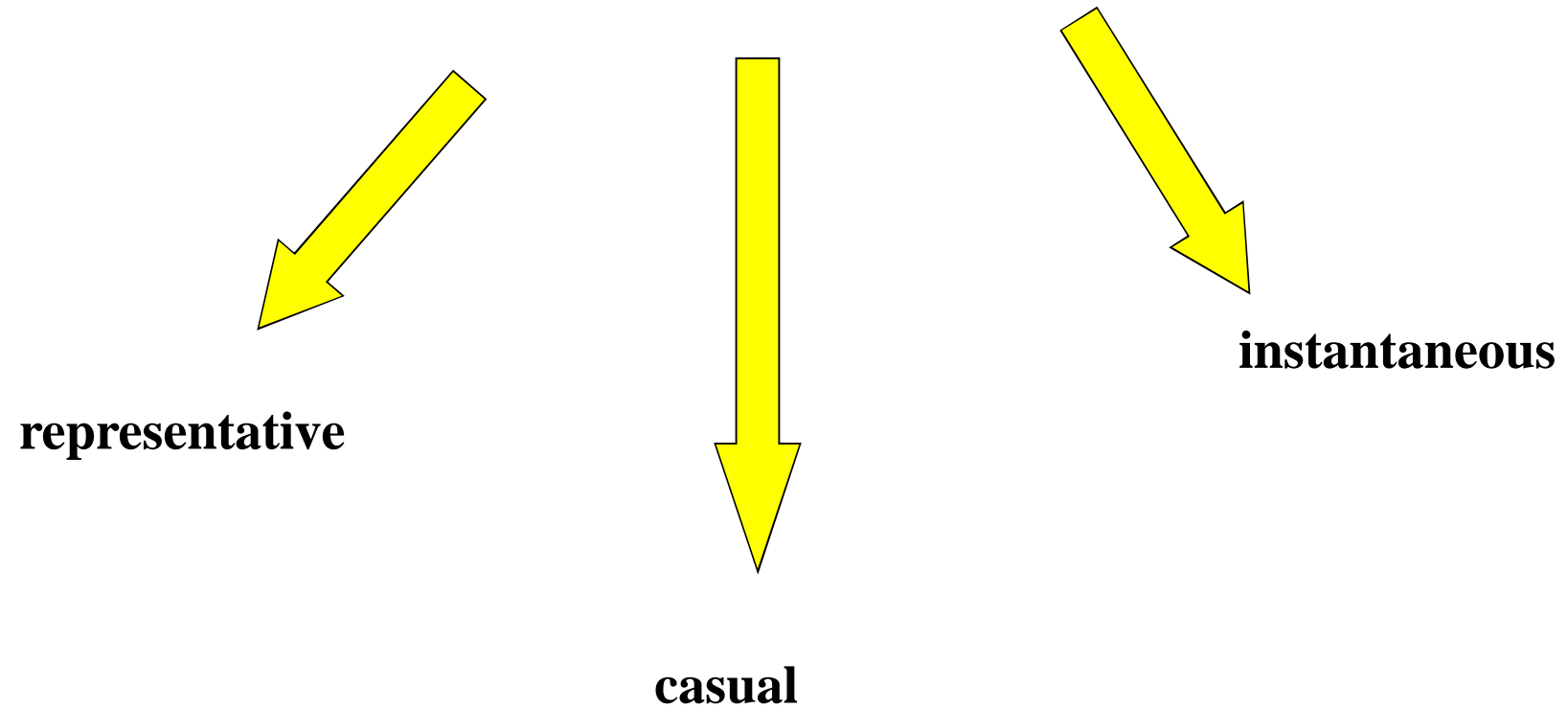
“ **For statistical accuracy:**

“ **Observations must be taken at random times**

“ **Period of the study must be representative of the types of activities performed by the subjects**



OBSERVATIONS



WHEN IS WORK SAMPLING APPROPRIATE?

- “ **Sufficient time** should be available to perform the study. Eg. several weeks usually required for a work sampling study
- “ **Multiple subjects**
- “ **Long cycle times** for the jobs covered by the study
- “ **Non-repetitive work cycles** (Jobs consist of various tasks rather than a single repetitive task)

Example: How Work Sampling Works?

A total of 500 observations taken at random times during a one-week period (40 hours) on 10 machines with results shown below.

Category	No. of observations
(1) set up:	75
(2) Running production:	300
(3) Machine idle:	125
TOTAL	500

How many hours per week did an average machine spend in each category?

Example: Solution

Proportions of time determined as number of observations in each category divided by 500

Time in each category determined by multiplying proportion by total weekly hours (40 hr)

Hrs per category

(1) Set up $75/500 = 0.15$	$0.15 \times 40 = 6$
(2) Running production $300/500 = 0.60$	$0.60 \times 40 = 24$
(3) Machine idle $125/500 = 0.25$	$0.25 \times 40 = 10$
	1.00 40

Work Sampling Applications

- “ **Machine utilization**: how much time is spent by machines in various categories of activity
- “ **Worker utilization**: how workers spend their time
- “ **Allowances for time standards**
- “ **Average unit time**: determining an average time on each work unit
- “ **Time standards**: limited statistical accuracy when standards set by work sampling

Work sampling conditions

- 1. The moment and the time extension should be valid for all the observations**
- 2. the number of observations is sufficient**
- 3. activities are qualified clearly**
- 4. the time between two sequential observations is not too short**
- 5. the observer follows strictly the procedures**
- 6. the operators under observation work in a normal way**

Procedure

- 1) Define the area to be investigated**
- 2) Define how much time cumulatively you need**
- 3) Define the categories to be studied**
- 4) Define the statistical parameters of the sampling :**
 - a) max. error accepted for our categories (eg. 2%).**
 - b) probability which reality should statistically represented with (eg. 95,5%).**
- 6) Calculate the number of observation**
- 7) define the numer of observations per day**
- 8) define the number of technicians performing the study**

Procedure

- 9) Prepare the report where the data will be collected
- 10) Inform the responsables and the workers
- 11) Do some brief tests
- 12) **Do the work sampling**
- 15) Analyse the collected datas
- 16) define the direct times, the indirect times, the workers losses

73735	45963	78134	63873
02965	58303	90708	20025
98859	23851	27965	62394
33666	62570	64775	78428
81666	26440	20422	05720
15838	47174	76866	14330
89793	34378	08730	56522
78155	22466	81978	57323
16381	66207	11698	99314
75002	80827	53867	37797
99982	27601	62686	44711
84543	87442	50033	14021
77757	54043	46176	42391
80871	32792	87989	72248
30500	28220	12444	71840

SAMPLE DIMENSION

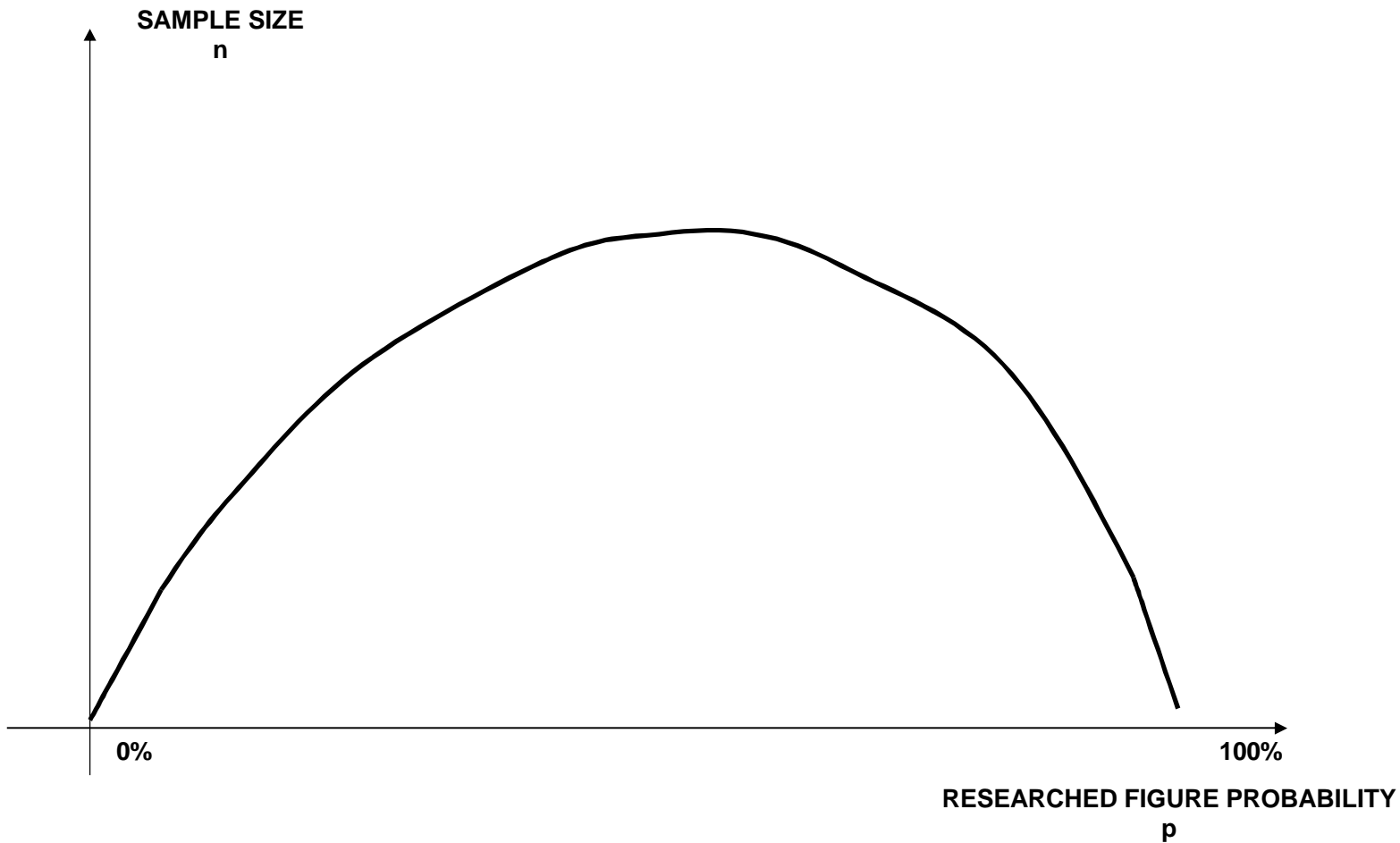
**IT DEPENDS ON THE PROBABILITY OF THE FIGURE
YOU ARE LOOKING FOR.**

**EG.: IF THE BATCH SIZES ARE VERY BIG, THE
PROBABILITY TO ASSIST TO A PRESS SET-UP IS VERY
LOW.**

**EG.: IF THE WORKSHOP HAS TO CHANGE CODE TO
BE PRODUCED EVERY 30 ϕ THE PROBABILITY TO
ASSIST TO A SET-UP IS VERY HIGH.**



SAMPLE DIMENSION





SAMPLE DIMENSION

$$n = \frac{a^2 * p (100 \ddot{E} p)}{Z^2}$$

a: is the confidence level that the actual value of p probability is included in the range p+/- Z

“ a = 1 means that there are 68% of probability that the researched figure is included in the range p+/- Z

“ a = 2 means that there are 95,5% of probability that the researched figure is included in the range p+/- Z

“ a = 3 means that there are 99,5% of probability that the researched figure is included in the range p+/- Z

Z = relative error accepted for the phenomenon knowledge

p = percentage of the phenomenon to be studied

n = number of observations



SAMPLE DIMENSION

$$n = \frac{a^2 * p (100 \ddot{E} p)}{Z^2}$$

p%	25
a	2
Z%	2
n	1875

p%	25
a	2
Z%	5
n	300

p%	20
a	2
Z%	10
n	64

p%	10
a	2
Z%	15
n	16



Example

	CAMPIONAMENTO STATISTICO DEL LAVORO Foglio raccolta dati	Data:		Macchina: Saldatrice		Caso: 1	
		Ora inizio: Ora fine:		Ore tot. pres.: 8		Turno: primo	
		1	2	3	4	5	Oss.
	MACCHINA O POSTO DI LAVORO	A	B	C	D	E	Totali
TEMPI DIRETTI PRODUTTIVI	Deporre i pezzi da banco a contenitore						12
	Riforn. Pezzi da contenitore a banco						12
	prendere e posizionare pezzo in attrezzo						22
	Smontare pezzo da attrezzo e deporre						19
	Puntare						
	Saldare continuo						58
	Lavori manuali diversi						35
	Attesa durante TM						28
	Attività durante TM						23
	Pulire pezzi						9
	SOMMA TEMPI DIRETTI PRODUTTIVI	36	45	44	43	50	218
TEMPI PREPARAZIONE	Tempi diretti						11
	Tempi perduti necessari						12
	Attese diverse						13
	Tempi perduti personali e diversi						19
		SOMMA TEMPI PREPARAZIONE	12	9	13	10	11
TEMPI PERDUTI NECESSARI	Affilatura e sostituzione utensili						8
	Cambio contenitore						8
	Attese per cambio contenitori						17
	Trasporto materiali						4
	Ricerca materiali e contenitori						4
	Attesa per rifornimento materiali						11
	Dare, ricevere istruzioni...						
	Ricerca attrezzature e utensili						3
	Pulizia posti di lavoro						9
	Controlli dimensionali e visivi						
	Registrazioni scritte						2
	Spostamento a vuoto						8
	SOMMA TEMPI PERDUTI NECESSARI	15	16	13	19	11	74
TEMPI PERDUTI PERSONALI	Inattività personali varie						3
	Necessità fisiologiche						15
	Inizio ritardato/fine anticipata						7
	SOMMA TEMPI PERDUTI PERSONALI	9	5	5	3	3	25
	Operatore fuori reparto						3
TOTALE		75	75	75	75	75	375
	Giudizio del passo di lavoro	60	80	100	120	140	
		70	90	110	130	150	
Note							



Esempio

	SEGRETERIA COMMERCIALE	A	B	C	D	E	F	G	TOTALE	Caso: 1 Analista:	CAMPIONAMENTO STATISTICO DEL LAVORO Foglio raccolta dati	Data:	Ora inizio : Ora fine:
Lavori specifici della funzione	Controllo fatture Segr. Commerc.								30				
	Controllo fatture Vendite Industr..								21				
	Controllo ordini Segr. Commerc.								20				
	Controllo ordini Vendite Industr..								13				
	Registrazione fatture-ordini								24				
	Archiviazione fatture-ordini								13				
	Pratiche di addebito								23				
	Pratiche di accredito								42				
Lavori Vari	Versamento IVA								103				
	Archiviazione bolle di consegna								57				
	Attività varie di commessa								53				
Tempi perduti necessari	Dare-ricevere istruzioni								116				
	Dare-ricevere aiuto/assistenza								116				
	Personali								139				
TOTALE		110	110	110	110	110	110	110	770				



Example

Data		15/1	16/1	17/1	18/1	19/1	22/1	23/1	24/1									totali	AI 95%			
Ore parziali di presenza		48	48	48	48	48	48	48	48													
Ore progress. di presenza		48	96	144	192	240	288	336	384										p	+/- Z	+/- Y	
Tempi diretti	Oss. parz.	169	218	195	238	176	182	184	187													
	Oss. progress	169	387	582	820	996	1178	1362	1549	a								1549	62,6	1,9	3,0	
Tempi prepar. Lavor.	Oss. parz.	89	0	0	0	0	0	0	0													
	Oss. progress	89	89	89	89	89	89	89	89	b								89	3,6	0,8	2,2	
Tempi perduti necessari	Oss. parz.	46	74	78	87	86	48	94	51													
	Oss. progress	46	120	198	285	371	419	513	564	c								564	22,8	1,7	7,5	
Tempi personali	Oss. parz.	8	5	40	27	21	7	20	2													
	Oss. progress	8	13	53	80	101	108	128	130	d								130	5,3	0,9	17,3	
Tempi perduti non necess.	Oss. parz.	6	3	0	0	0	0	0	0													
	Oss. progress	6	9	9	9	9	9	9	9	e								9	0,4	0,1	33,3	
Operatore ad altro centro	Oss. parz.	0	0	47	8	17	63	0	0													
	Oss. progress	0	0	47	55	72	135	135	135	f								135	5,5	1,0	18,2	
N° Osserv. totali	PARZIALI	318	300	360	360	300	300	298	240													
	PROGRESSIVI	318	618	978	1338	1638	1938	2236	2476	TOT.								2476	100,0			

Curva di stabilità	%																					
	90																					
	80																					
	70																					
	60																					
	50																					
	40																					
	30																					
	20																					
	10																					
0																						

Note:	Reparto:	
	Analista:	
Visto:	Costo:	
	Centro di	

Campo:	
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Example

Data	15/1	16/1	17/1	18/1	19/1	22/1	23/1	24/1							totali	AI 95%		
Ore parziali di presenza	48	48	48	48	48	48	48	48										
Ore progress. di	48	96	144	192	240	288	336	384								p	+/- Z	+/- Y
Cambio lavorazione	Oss. parz.	89	0	0	0	0	0	0										
	Oss. prog	89	89	89	89	89	89	89	a						89	3,6	0,8	22,2
Attesa servomezzi e materiali	Oss. parz.	0	0	0	0	0	0	0										
	Oss. prog	0	0	0	0	0	0	0										
Riparazioni	Oss. parz.	0	0	0	0	0	0	0										
	Oss. prog	0	0	0	0	0	0	0										
Inattività diverse	Oss. parz.	60	82	165	122	124	118	114	53									
	Oss. prog	60	142	307	429	553	671	785	838	b					838	33,8	1,9	5,6
Macchina inattiva	Oss. parz.	149	82	165	122	124	118	114	53									
	Oss. prog	149	231	396	518	642	760	874	927	c					927	37,4	1,8	4,8
Macchina attiva	Oss. parz.	169	218	195	238	176	182	184	187									
	Oss. prog	169	387	582	820	996	1178	1362	1549	d					1549	62,6	2,0	3,2
N° Osserv. totali	PARZIALI	318	300	360	360	300	300	298	240									
	PROGRES	318	618	978	1338	1638	1938	2236	2476	TOT.					2476	100,0		

Curva di stabilità	%																	
	90																	
	80																	
	70																	
	60																	
	50																	
	40																	
	30																	
	20																	
	10																	
0																		

Note:	Reparto:	
	Analista:	
	Visto:	

Campionamento statistico del Lavoro Analisi impiego macchina	Caso:	
	Centro di costo:	

Active Machine
Inactive Machine
Various Inactivities
Set-up

Macchina attiva= 100*d/TOT
 Macchina inatt. = 100 c/TOT
 inattività div. = 100 b/TOT
 Cambio lav. =100*a/TOT



STATISTICAL WORK SAMPLING ADVANTAGES

Can be used to measure activities that are very difficult to measure by direct observation

“ Multiple subjects can be studied in the same time

“ Requires less time and lower cost than continuous direct Observation

“ Training requirements less than Time keeping and MTM

“ Less tiresome and tedious on observer than continuous Observation

“ Fewer mistakes than short-run observations

“ Being a subject in work sampling is more acceptable than being watched continuously for a long time

STATISTICAL WORK SAMPLING DISADVANTAGES & LIMITATIONS

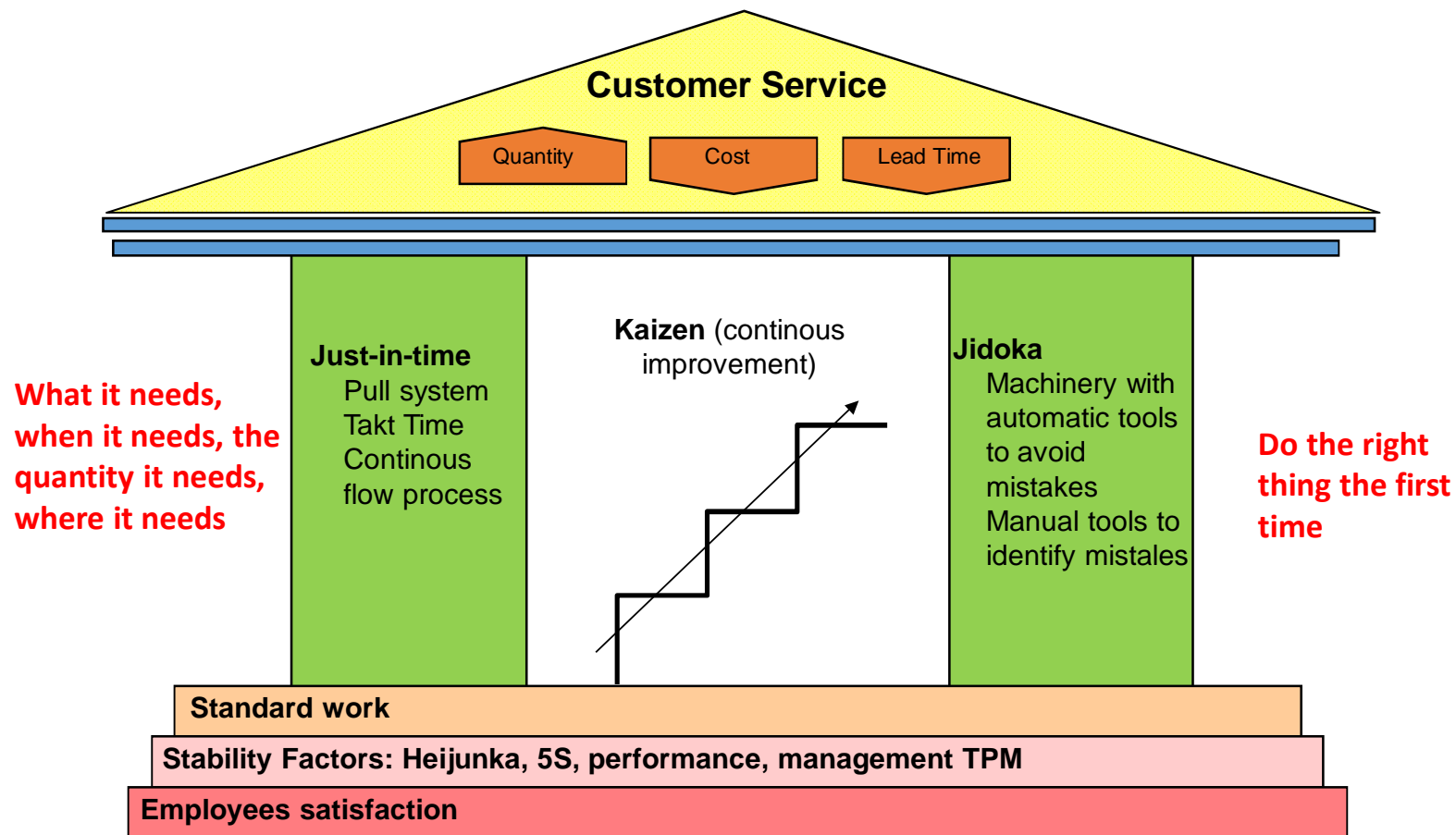
- “ Not as accurate for setting time standards as other work measurement techniques**
- “ Work sampling provides less detailed information about work elements than TK and MTM**
- “ Not proper to set standards for incentive pay systems**
- “ Usually not practical to study a single subject doing repetitive work**
- “ Since work sampling deals with multiple subjects, individual differences will be missed**
- “ Workers may be suspicious because they do not understand the statistical basis of work sampling**
- “ Behavior of subjects may be influenced by the act of observing them**

LESSON LEARNT

- “ LABOUR TIMES HAVE TO BE MEASURED**
- “ ALL THE WORK TYPES CAN BE MEASURED**
- “ THERE ARE MANY METHODS TO MEASURE LABOUR TIMES**
- “ THEY ARE SUITABLE TO THE DIFFERENT SITUATIONS**



Il Toyota Production System





TECHNIQUES
AND TOOLS

				7 TOOLS	CORRELATION	
					PARETO'S DIAGRAM	
					ISTOGRAMS	
					CONTROL CHARTS	
					ISHIKAWA DIAGRAM	
				ONE POINT LESSON		
				A3	5 WHYS	
				KEY PERFORMANCE INDICATORS		
				5 S		
			YAMAZUMI	ANDON		FLAS
			TAKT TIME	VISUAL MANAGEMENT		GRO
		ERGONOMY	KANBAN	STANDARDIZATION		EMP
		TPM	KAIKAKU	PDCA		IN
		SMED	JIT	POKAYOKE		AGR
QUALITY FUNCTION DEPLOYMENT	SPAGHETTI CHART	OEE	HEIJUNKA	KAIZEN		INFO
WASTES	LABOUR TIMES STUDY	ONE PIECE FLOW	FROM PUSH TO PULL	SIX SIGMA		COM
HOSHIN KANRI	CURRENT VSM	FUTURE VSM	PULL	JIDOKA		MOT RESI
DEFINE THE	IDENTIFY THE	SET UP FLOW	E PULLING THE			ATTE