

Reali Hartbe:

dai FdT di ordine 1

ad eventuali di stato

\mathcal{B}

approccio relativo

SOLO

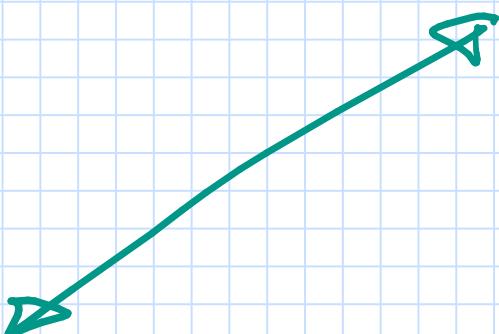
tu s'facci LTI SISO

di ordine $M=1$

LTI, $n=1$, SISO, tempo continuo

$$\begin{cases} \dot{x} = ax + bu \\ y = cx + du \end{cases} \quad a, b, c, d \in \mathbb{R}$$

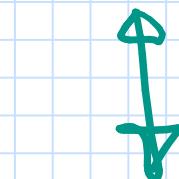
$d=0 \Leftrightarrow$ sistema
direttamente proprio



$d \neq 0 \Leftrightarrow$ sistema con
direttamente proprio

FAT $D(s)$ grado 1

$N(s)$ grado 0



FAT

$D(s)$ grado 1
 $A(s)$ grado 1

$$\left\{ \begin{array}{l} \dot{x} = ax + bu \\ y = cx + du \end{array} \right. \xrightarrow{\text{d}} \left\{ \begin{array}{l} sX - x(0) = ax + bu \\ y = cx + du \end{array} \right. \stackrel{=0}{=}$$

$$\left\{ \begin{array}{l} X(s) = \frac{b}{s-a} U(s) \\ Y(s) = \frac{cb}{s-a} U(s) + dU(s) \end{array} \right.$$

$$T_{u,y}(s) = \frac{cb}{s-a} + d = \frac{ds + (cb - da)}{(s-a)}$$

$$T(s) = \frac{ds + (cb - da)}{(s-a)}$$

$d=0$
sistema strettamente
proprio

$$T(s) = \frac{cb}{s-a} \quad M=0$$

$$M=1$$

$\downarrow d \neq 0$

$$T(s) = \frac{ds + (cb - da)}{s-a} \quad M=1$$

$$M=1$$

ordine $M=1$

SISO

Voglio utilizzare questo information per risolvere P
Problema inverso:

dare una FolT di ordine 1, SISO, facendo uso realizzazioni in es.
di fatto

$$f_0 T \quad M=1 \\ u=0$$

$$G(s) = \frac{f}{ps - q}$$

$$f, p, q \in \mathbb{R} \\ p \neq 0$$

Per confronto

$$\frac{f}{ps - q} = \frac{f/p}{s - (q/p)} \quad \leftrightarrow \quad \frac{cb}{s - a}$$

divido Numer
e Den per p

$$\begin{cases} cb = f/p \\ a = q/p \end{cases} \quad \text{infinito solut.}$$

scelto come dc

$$b=1 \rightarrow c=f/p \\ c=1 \rightarrow b=f/p$$

2 formule soluzioni equivalenti

(2 fra le infinite possibili \rightarrow scegliete $x \in (\mathbb{R}) \rightarrow$
 \rightarrow calcolate b [ogni volta user]

1^a scelte

$$\left\{ \begin{array}{l} \dot{x} = \left(\frac{g}{\rho}\right)x + u \\ y = \left(\frac{f}{\rho}\right)x \end{array} \right.$$

2^a scelte

$$\left\{ \begin{array}{l} \dot{x} = \left(\frac{g}{\rho}\right)x + \left(\frac{f}{\rho}\right)u \\ y = x \end{array} \right.$$

FdT

$$M = 1$$

SISO

$$M = 1$$

$$G(s) = \frac{ps - q}{rs - w}$$

$$p, q \in \mathbb{R}$$

$$r, w \in \mathbb{R}$$

Per confronto

$$G(s) = \frac{ps - q}{rs - w} \rightleftharpoons \begin{array}{l} \text{componere} \\ \text{le fettine in 2 parti} \\ 1^{\circ} \text{ parte sferica} \\ 2^{\circ} \text{ parte FdT strutt.-propria} \end{array}$$

$$\begin{array}{c|c} ps - q & rs - w \\ \hline -ps + \frac{wP}{r} & P/r \\ \hline \frac{wp - qr}{r} & \cong M \end{array}$$

$$G(s) = \left(\frac{P}{r} \right) + \frac{M}{rs - w}$$

$$G(s) = \left(\frac{P}{r}\right) + \frac{m}{rs - w}$$

\Rightarrow

$$G(s) = d + \frac{cb}{s - \alpha}$$

Come il caso
precedente

$$\begin{cases} c=1 \\ b=w/r \\ \alpha=\omega/r \end{cases}$$

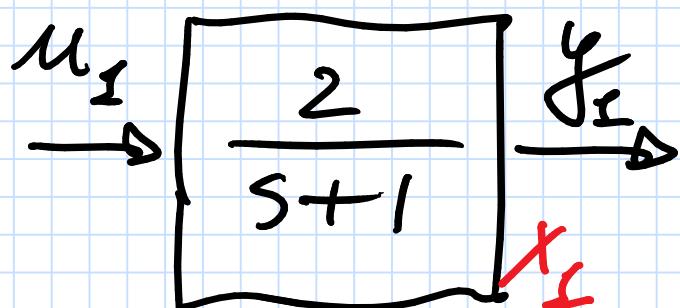
$$\begin{cases} b=1 \\ c=w/r \\ \alpha=\omega/r \end{cases}$$

Esenyi

$$\textcircled{1} \quad T(s) = \frac{2}{s+1} \quad \xrightarrow{\quad} \quad \frac{cb}{s-a}$$

$$G(s) = \frac{cb}{s-a}$$

$$G(s) = \omega l + \frac{\tau b}{s-a}$$



$$R = -1$$

$$b=1$$

$$c=2$$

$$\tau=1$$

$$b=2$$

$$\left\{ \begin{array}{l} \dot{x}_1(t) = -x_1(t) + 2u_1(t) \\ y_1(t) = x_1(t) \end{array} \right.$$

$$\left\{ \begin{array}{l} \dot{x}_1(t) = -x_1(t) + a_1(t) \\ y_1(t) = 2x_1(t) \end{array} \right.$$

$$\textcircled{2} \quad T(s) = \frac{2s+3}{s+5}$$

$$M=1$$
$$M=1$$

$$\begin{array}{r} 2s+3 \\ \hline -2 \quad -10 \\ \hline 1 \quad -7 \end{array} \quad \left| \begin{array}{c} s+5 \\ 2 \end{array} \right.$$

$$T(s) = 2 - \frac{7}{s+5}$$

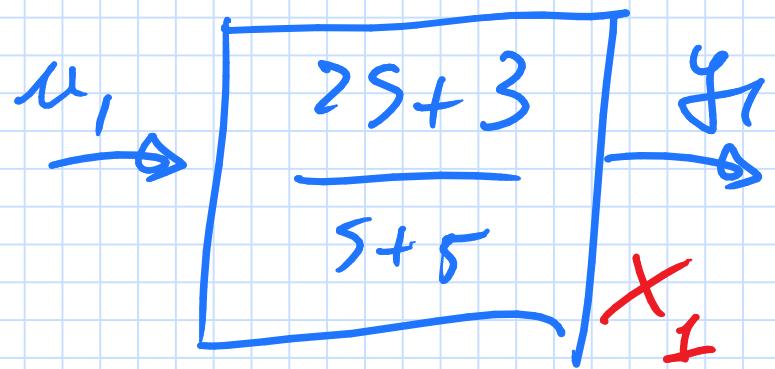
$$G(s) = d + \frac{cb}{s-\varrho}$$

$$d=2$$

$$\varrho = -5$$

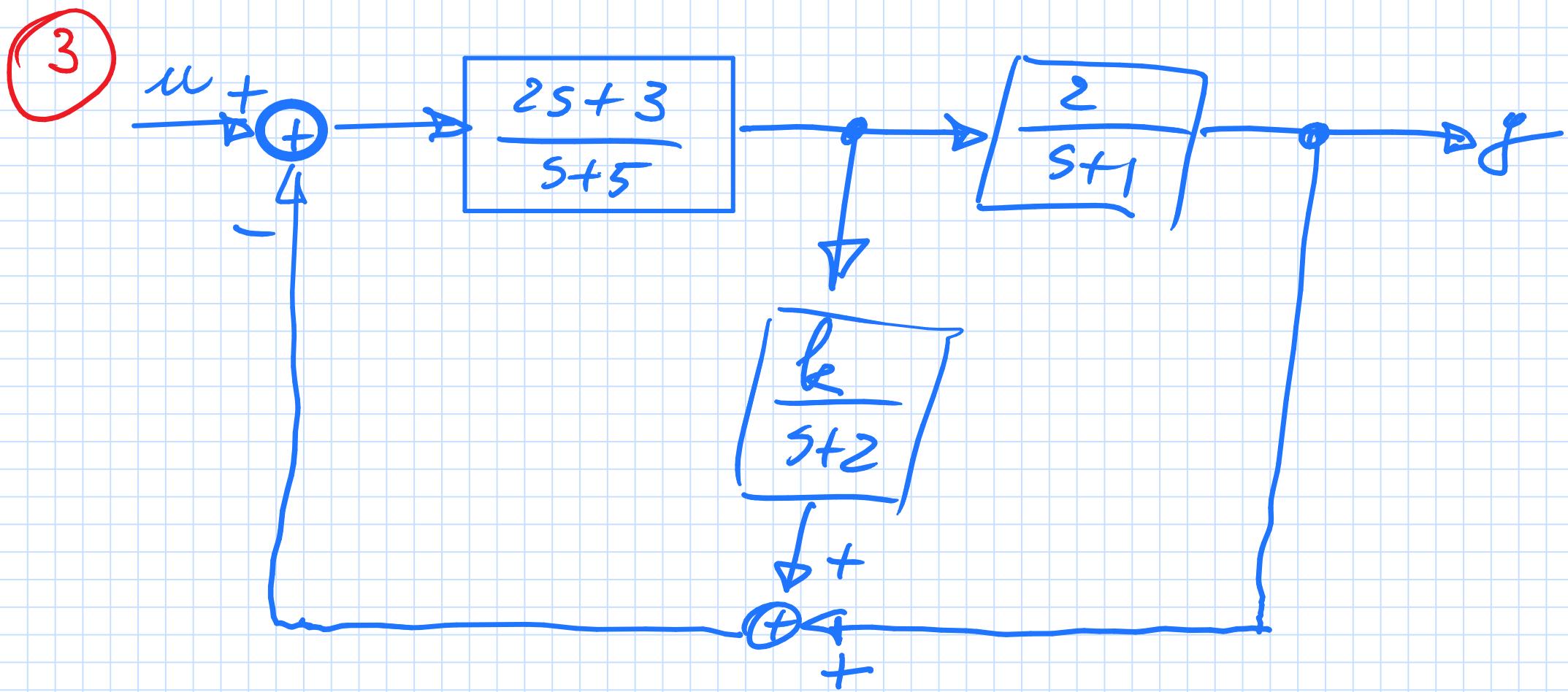
$$b=1$$
$$c=-7$$

$$\tau=1$$
$$b=-7$$

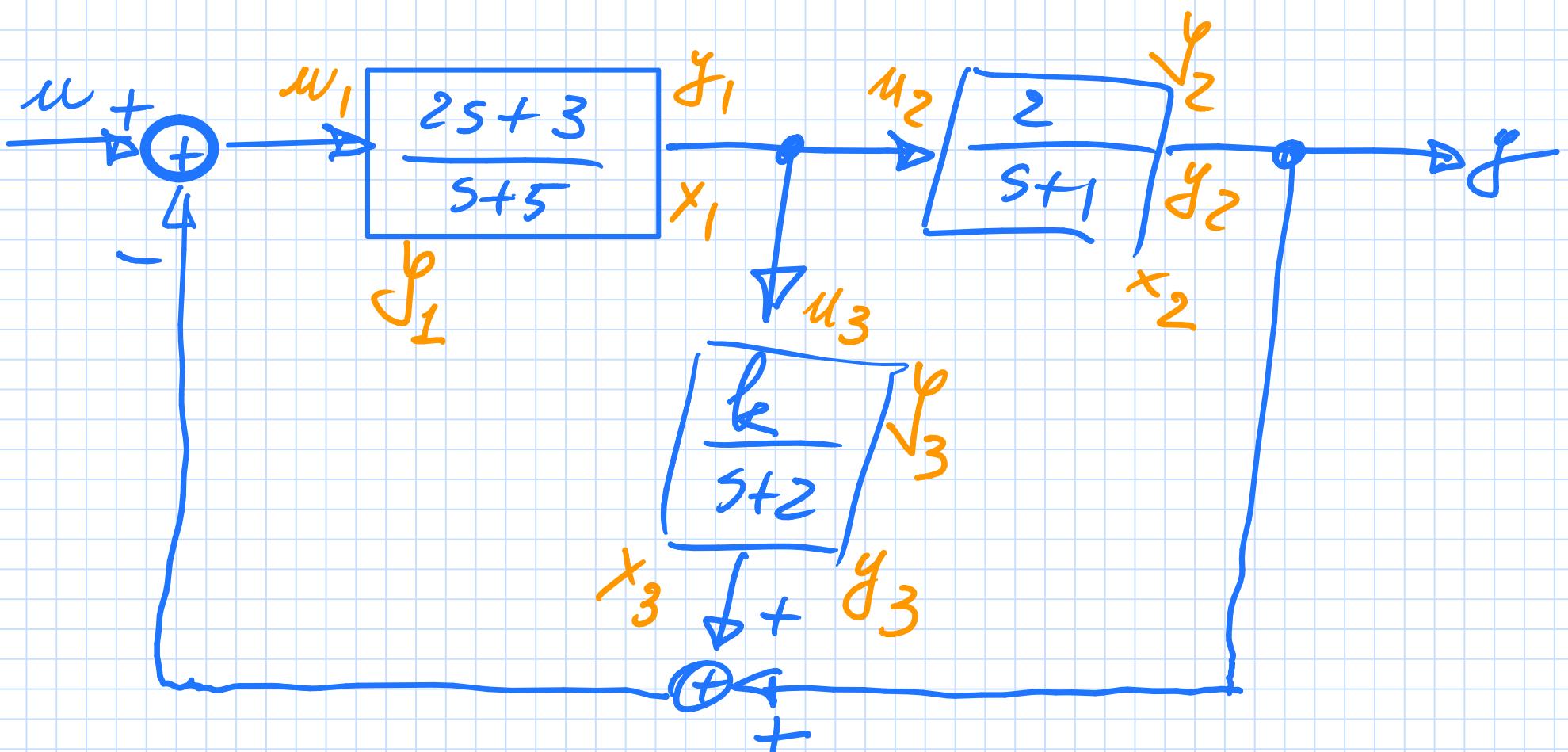


$$\begin{cases} \dot{x}_1(t) = -5x_1(t) + u_1(t) \\ y_1(t) = -7x_1(t) + 2u_1(t) \end{cases}$$

$$\begin{cases} \dot{x}_1(t) = -5x_1(t) - 7u_1(t) \\ y(t) = x_1(t) + 2u_1(t) \end{cases}$$



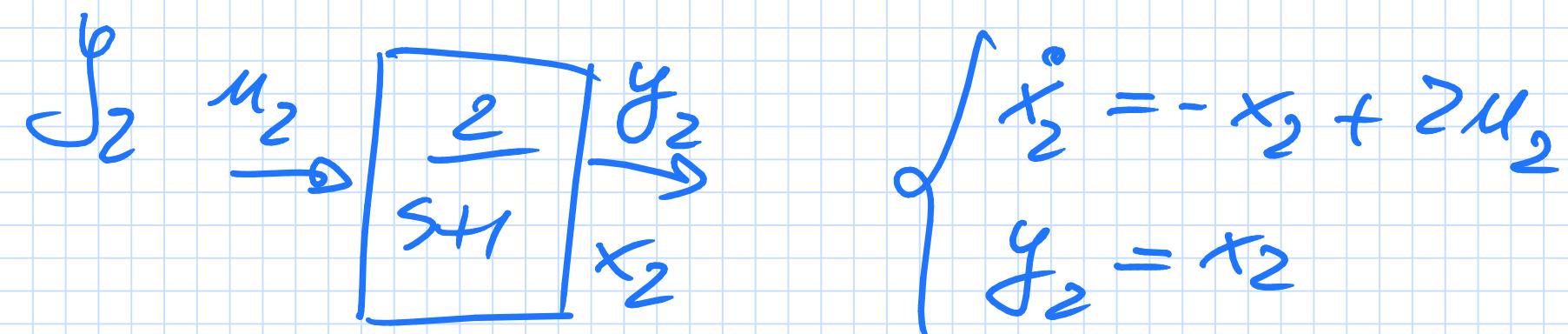
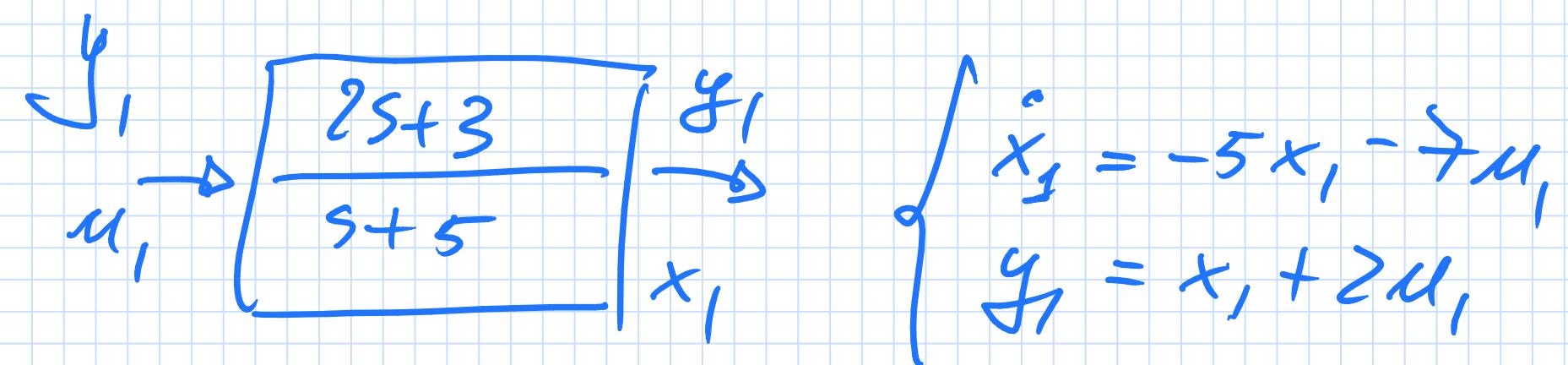
Trovare una realizzazione in eq. di stato
 NON modificare lo schema!

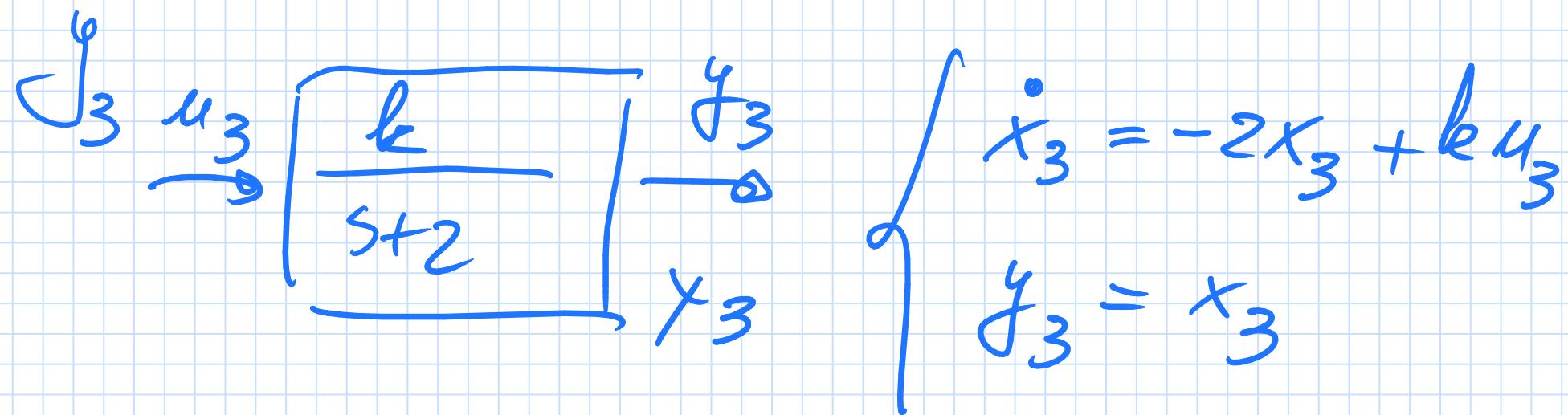


- (*) chiedetere: blocchi $y_1, y_2, y_3 \dots$
- (*) chiedetere i parametri, quale e quando si ottiene uno blocco
- (*) trovare una soluz. in esp. dato k per

(*) descrivere con un diagramma le interconnessioni tra i blocchi y_i

(*) eliminare variabili sistemiche $(u_1, y_1, u_2, u_3, y_2, y_3)$





$$\dot{x}_1 = -5x_1 - y_1 + u_1$$

$$\dot{x}_2 = -x_2 + 2u_2$$

$$\dot{x}_3 = -2x_3 + k u_3$$

$$y = y_1 = x_2$$

$$u_1 = u - y_2 - y_3 = u - x_2 - x_3$$

$$u_2 = y_1 = x_1 + 2u_1 = x_1 - 2x_2 - 2x_3 + 2u$$

$$u_3 = y_1 = x_1 + 2u_1 = x_1 - 2x_2 - 2x_3 + 2u$$

$$y_1 = x_1 + 2u_1$$

$$y_2 = x_2$$

$$y_3 = x_3$$

Dopo aver sostituito le variabili a caccia
 sfruttando le relazioni algebriche che legano
 le var. ausiliarie alle variabili di stato (x_1, x_2, x_3)
 di ingresso e uscita del sistema totale (u, y)

$$\left\{ \begin{array}{l} \dot{x}_1 = -5x_1 + 7x_2 + 7x_3 - 7u \quad \text{ordine 3} \\ \dot{x}_2 = +2x_1 - 5x_2 - 4x_3 + 4u \\ \dot{x}_3 = kx_1 - 2kx_2 - 2(1+k)x_3 + 2bu \\ y = x_2 \end{array} \right.$$

LTI, SISO, M=1, Tiempo discreto

$$\begin{cases} x(k+1) = a x(k) + b u(k) & a, b, c, d \in \mathbb{R} \\ y(k) = c x(k) + d u(k) & c \neq 0 \end{cases}$$

$$T(z) = C (zI - A)^{-1} B + D$$

$$= \frac{c b}{z - a} + d$$

← struttura
mostra el
caso "a tiempo
continuo"

$$G_1(z) = \frac{f}{pz - q}$$

$$M=0$$

$$n=1$$

$$P \neq 0$$

Sistema
strettamente
proposto

Più confronto

$$G_1(z) = \frac{f/p}{z - q/p} \leftrightarrow T(A) = \frac{c_b}{z - \alpha}$$

$$\alpha = q/p$$

$$b=1$$

$$c=f/p$$

$$c=1$$

$$b=f/p$$

$$\begin{cases} x(k+1) = \left(\frac{q}{p}\right)x(k) + u(k) \\ y(k) = \left(\frac{f}{p}\right)x(k) \end{cases}$$

$$\begin{cases} x(k+1) = \frac{q}{p}x(k) + \frac{f}{p}u(k) \\ y(k) = x(k) \end{cases}$$

$$G_1(z) = \frac{e^z + f}{pz + g}$$

$e, f, p, g \in \mathbb{R}$

$$M=1$$

$$M=1$$

El modo similar al caso "en tiempo continuo"

$$\frac{e^z + f}{-pz - \frac{eg}{p}} \quad \left| \begin{array}{l} pz + g \\ \frac{e}{p} \end{array} \right.$$

$$\frac{1}{f - \frac{ep}{g}}$$

$$f(z) = \frac{e}{p} + \frac{\left(f - \frac{ep}{g}\right)}{z + g/p}$$

$$T(z) = \alpha + \frac{rb}{z - \alpha}$$