

Equilibrio

- 1) a) Eq stabile $\rightarrow \frac{d^2U}{dx^2} > 0$ (assumo σ
 Eq instabile \rightarrow " < 0 e $\epsilon > 0$)
 Eq indiffer. \rightarrow " $= 0$

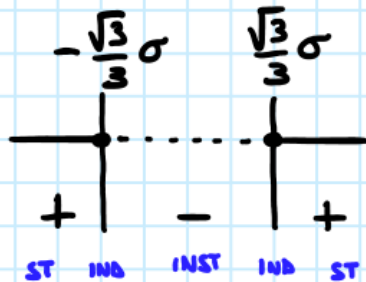
$$\rightarrow U(x) = \epsilon \left(1 - \left(\frac{x}{\sigma} \right)^2 \right)^2 = \epsilon \left(1 + \left(\frac{x}{\sigma} \right)^4 - 2 \left(\frac{x}{\sigma} \right)^2 \right)$$

$$\frac{dU}{dx} = \epsilon \left(\frac{4x^3}{\sigma^2} - \frac{4x}{\sigma^2} \right) = \frac{4\epsilon}{\sigma^2} x \left(\frac{x}{\sigma^2} - 1 \right) = 0$$

$\Rightarrow x_1 = 0, x_{2,3} = \pm \sigma$

$$\frac{d^2U}{dx^2} = \epsilon \left(\frac{12x^2}{\sigma^2} - \frac{4}{\sigma^2} \right)$$

$$\frac{\epsilon}{\sigma^2} \left(\frac{12x^2}{\sigma^2} - 4 \right) > 0 \rightarrow \left(\frac{12x^2}{\sigma^2} - 4 > 0 \right)$$



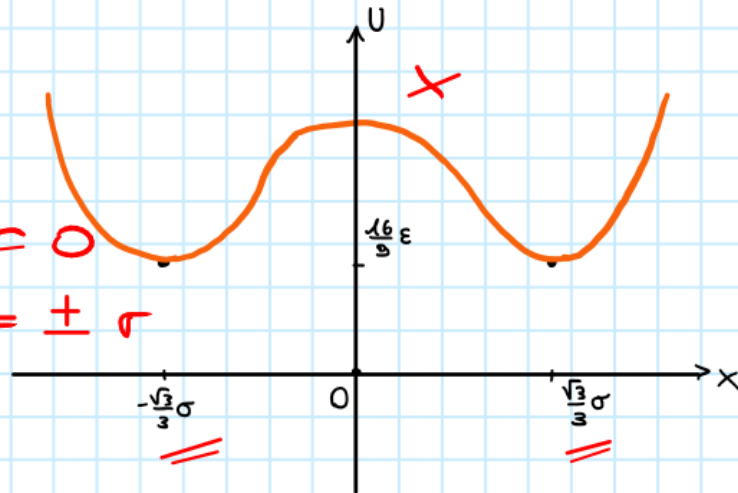
$$\rightarrow x_{1,2} = 0 \pm \sqrt{\frac{12}{\sigma^2} \cdot \frac{4}{\sigma^2}} = \pm \frac{2\sqrt{3}}{\sigma}$$

$$\left\{ \begin{array}{l} + \frac{2\sqrt{3}}{24} \sigma = \frac{\sqrt{3}}{3} \sigma \\ - \frac{2\sqrt{3}}{24} \sigma = -\frac{\sqrt{3}}{3} \sigma \end{array} \right.$$

$$U(x_1) = \frac{16}{9} \epsilon$$

$$U(x_2) = \frac{16}{9} \epsilon$$

⚠ bisogna cercare gli annullamenti di U'' !



$$\frac{dE_p}{dx} = -F_x = 0$$

$$\frac{d^2E_p}{dx^2}$$

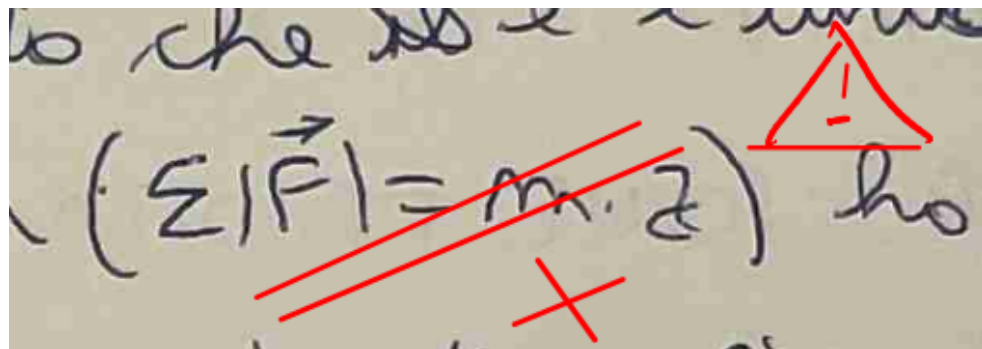
• II Newton

$$\sum |\vec{F}| = m \cdot a \quad \text{X}$$

$$|\sum \vec{F}| = m |\vec{a}|$$

ERRORE

$$\sum |\vec{F}| = ma$$



• UNITA' DI MISURA :

$$M = \frac{|\vec{g}| |\vec{r}|^2}{G} = \frac{(9.81 \frac{m}{s^2})(6 \times 10^6)^2 m}{6.674 \times 10^{-11} N m^2 / kg^2} = 5.29 \times 10^{24} \approx 10^{25} \quad \text{X UNITA' DI MISURA}$$

$$M \approx 10^{25}$$

• Vettori - scalari :

$$\vec{v}_1 = \frac{\rho_b \cdot V_b \cdot g}{\xi}$$

$$\vec{v} = \frac{\rho_b V_b g}{\xi}$$

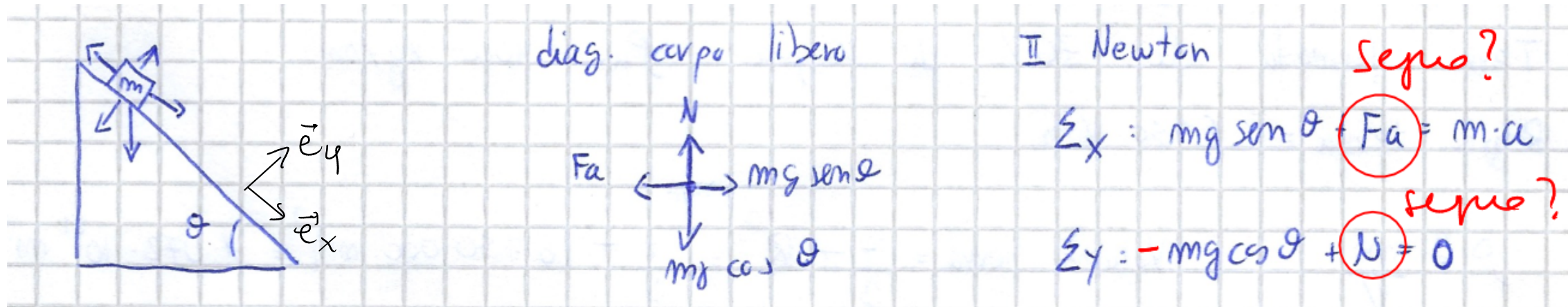
$-kx = m \cdot \vec{a} \rightarrow \frac{d^2x}{dt^2} = -\frac{k}{m}x$ non puoi uguagliare un vettore e uno scalare x diagramma

$$-kx = m\vec{a}$$

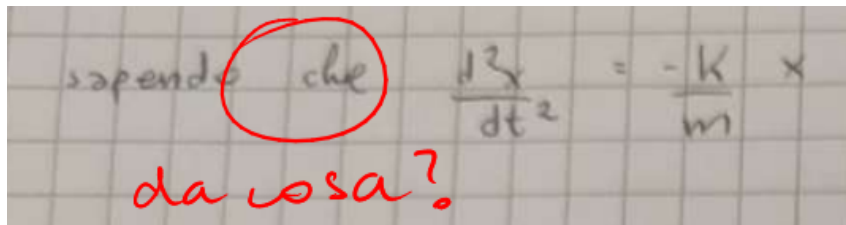
$\frac{F_1}{F_2} = \mu_s$ che cosa è il rapporto tra 2 vettori ??

$$\mu_s = \frac{F_1}{F_2}$$

- Definire e usare base \vec{e}_x, \vec{e}_y per esprimere i vettori



- Ipotesi \Rightarrow conclusioni



delle x e delle y \rightarrow da che cosa?

Nota che $\vec{n} = mg \cos \theta$; $\vec{f}_s = mg \sin \theta$

forza normale \otimes forza di attrito statico

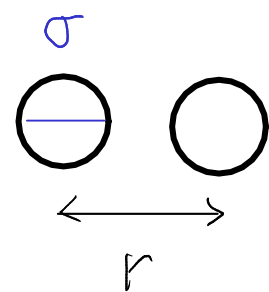
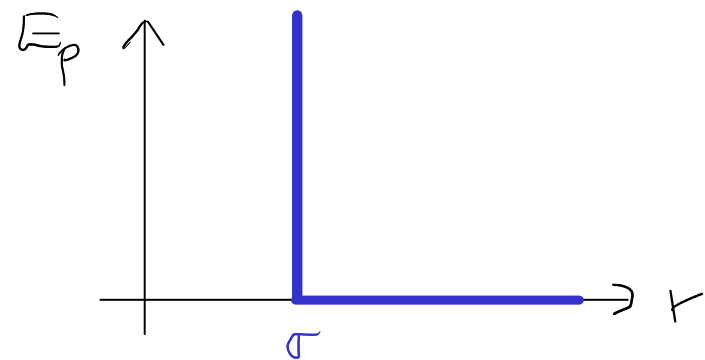
Devi partire da $\Sigma \vec{F} = m \vec{a} = \vec{0}$

So che affinché il blocco sia "fermo"

- Archimede

INTERPRETAZIONE MICROSCOPICA DELL' ENTROPIA

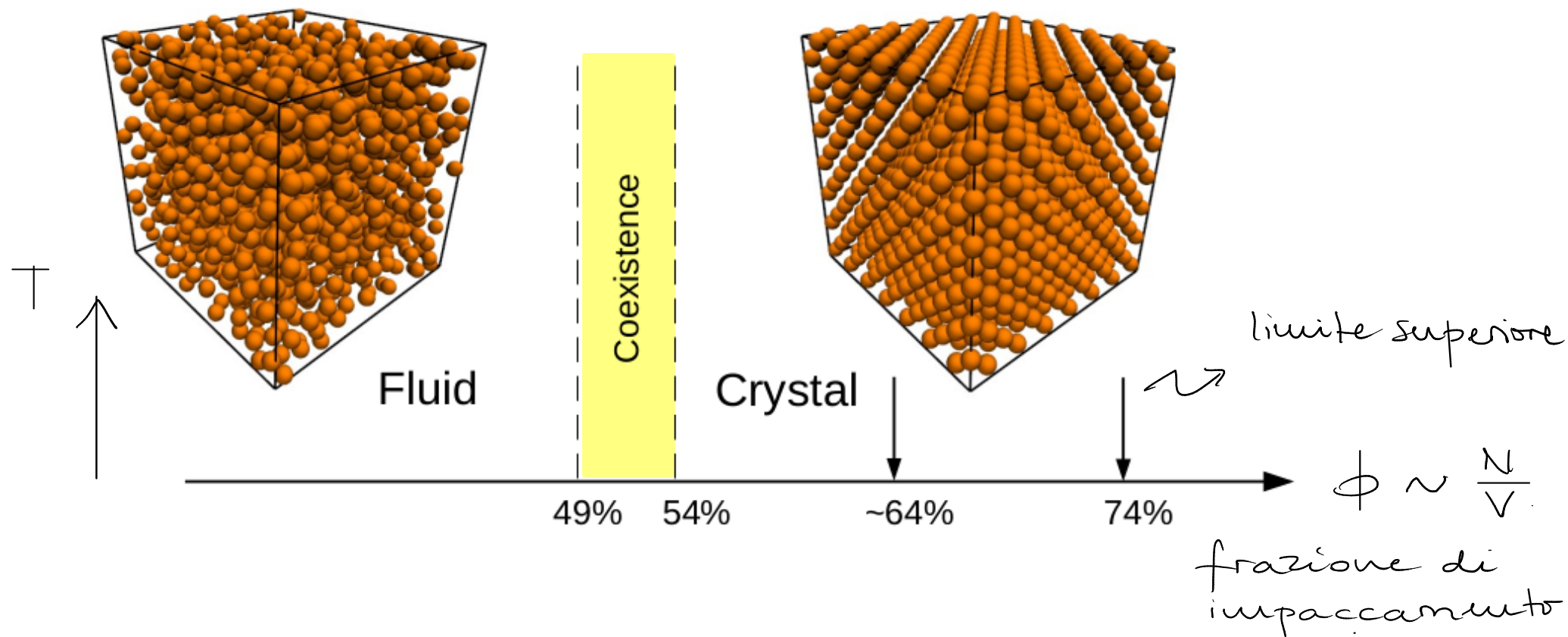
Modello di sfere dure



$$E_p = \begin{cases} 0 & r > \sigma \\ \infty & r \leq \sigma \end{cases}$$

Sospensioni colloidali

Diagramma di fase



Dinamica molecolare: integrazione numerica delle equazioni del moto

Phase Transition for a Hard Sphere System

B. J. ALDER AND T. E. WAINWRIGHT

University of California Radiation Laboratory, Livermore, California

(Received August 12, 1957)

A CALCULATION of molecular dynamic motion has been designed principally to study the relaxations accompanying various nonequilibrium phenomena. The method consists of solving exactly (to the number of significant figures carried) the simultaneous classical equations of motion of several hundred particles by means of fast electronic computers. Some of the

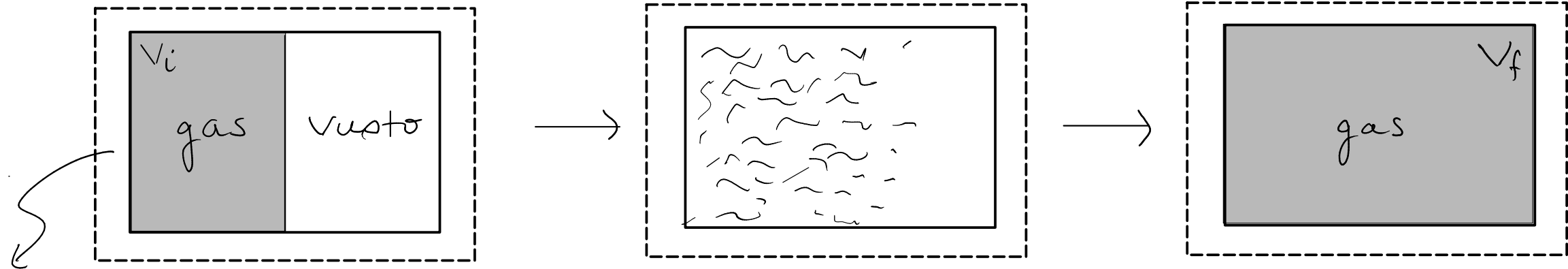


Benji Alder '57

Se $\phi > 54\%$, Scristallo $>$ fluido

entropia \Rightarrow disordine

Espansione libera di un gas perfetto



adiabatiche
rigide

Iniziale

espansione libera

Finale

Trasf. adiabatica è reversibile?

$$dS = \frac{\delta Q}{T} \quad QS$$

Variazione di S tra i e f

$$\Delta S = \int_i^f dS = \int_i^f \frac{\delta Q}{T} = \int_i^f \frac{dT}{T} + \int_i^f \frac{P}{T} dV = C_v \int_{U_i}^{U_f} \frac{dU}{U} + nR \int_{V_i}^{V_f} \frac{dV}{V}$$

trasm. immaginaria
QS tra i e f

$$\delta Q = dU - \delta W = dU + PdV$$

$$= G_V \ln \frac{U_f}{U_i} + nR \ln \frac{V_f}{V_i} = nR \ln \frac{V_f}{V_i} = Nk_B \ln \frac{V_f}{V_i}$$

$$\text{I pr: } \Delta U = U_f - U_i = W + Q = 0 \Rightarrow U_f = U_i$$

$= 0 \quad = 0$

rigide
+ espansione nel vuoto

$$\text{Es: } V_f = 2V_i \Rightarrow \Delta S = Nk_B \ln 2 > 0 \quad \text{OK per il II pr.}$$

Macro

Termodinamica

$$\{P, T, V, N, U, S\}$$

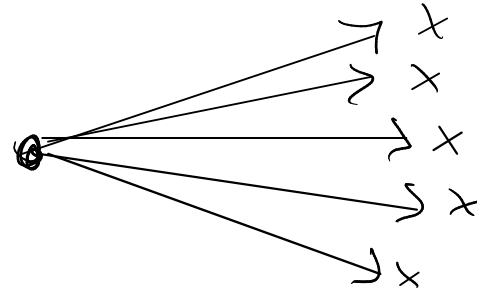
macro - stato

Micro

Dinamica Newtoniana

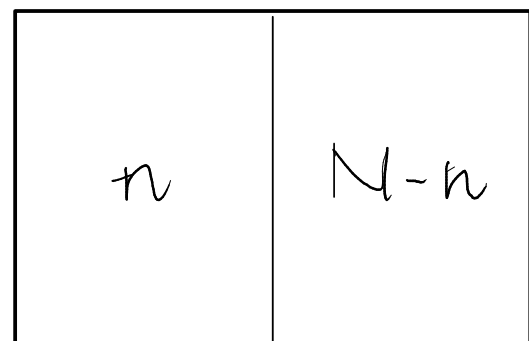
$$\{\vec{F}_1, \dots, \vec{F}_N, \vec{v}_1, \dots, \vec{v}_N\}$$

micro - stato



$S \rightarrow$ numero di micro - stati compatibili
con un macro - stato

Modellizzazione Schematica



Numero di realizzazioni totali

$$\Omega = 2^N$$

macro - stato : n

micro - stato : combinazione di n tra N

Combinazioni compatibili con macro - stato n

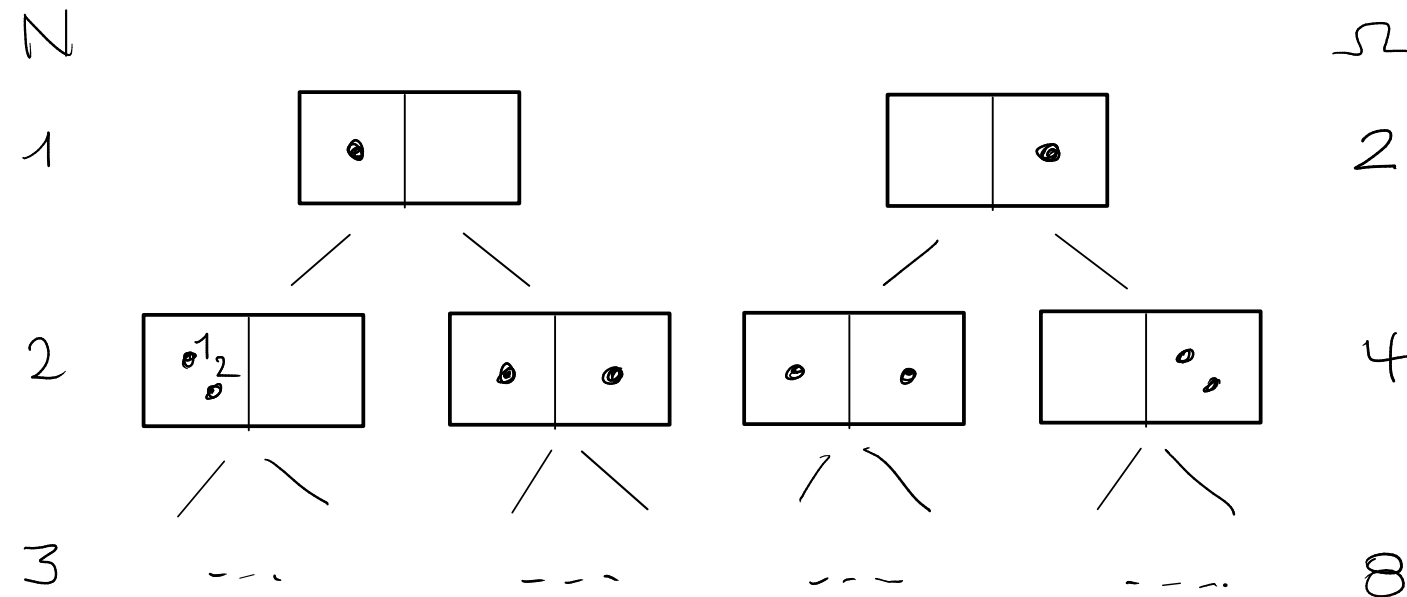
$$W_n = C_n^N = \binom{N}{n} = \frac{N!}{n!(N-n)!}$$

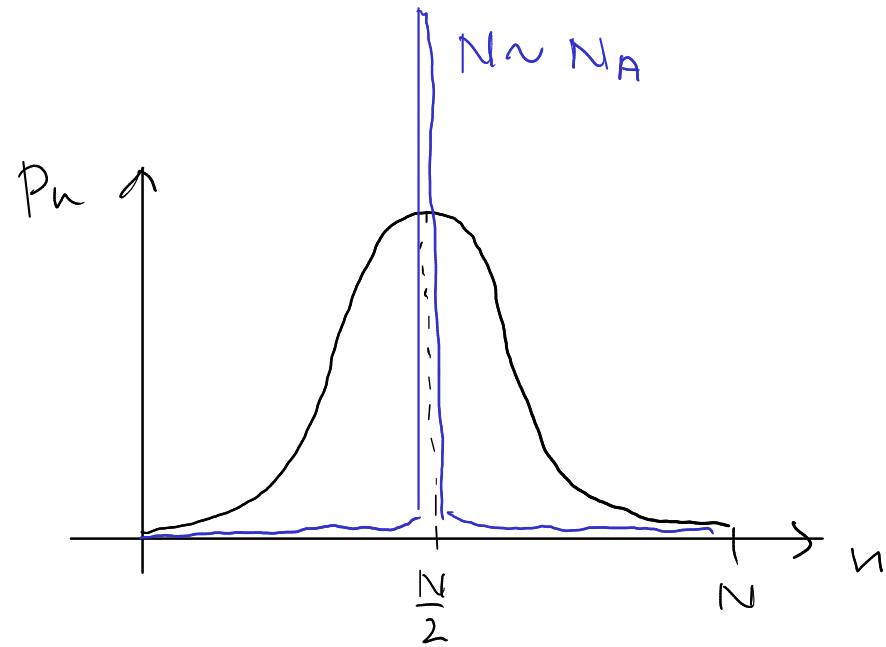
coefficiente binomiale

$$\left[\sum_{n=0}^N C_n^N = 2^N \right]$$

Probabilità del macro n stato

$$P_n = \frac{C_n^N}{\sum_{n=0}^N C_n^N} = \frac{W_n}{2^N}$$





$$N = N_A$$

Iniziale : $n = N$

Finale : $n = \frac{N}{2}$

$$P_N = \frac{1}{2^{10^{23}}} = 2^{-10^{23}} \approx 10^{-10^{22}}$$

Entropia di Boltzmann → sistema isolato

Microstati hanno tutti uguale probabilità

$$S \sim \log w$$

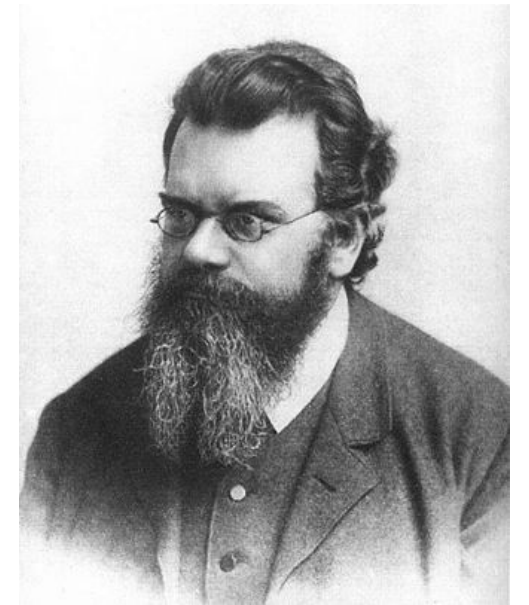
↑
numero di micro-stati
compatibili con il
macro-stato

→

$$S \equiv k_B \log w$$

↑
costante di Boltzmann

Nota: $\log \equiv \ln$
in base e



Ludwig Boltzmann
1844 - 1906

S è additiva

$$\boxed{1} \quad \boxed{2}$$

$S_1 \quad S_2$

$$S_{\{1,2\}} = S_1 + S_2$$

$$w_1 \cdot w_2 = w$$

$$\log(w_1 w_2) = \log w_1 + \log w_2$$

Equilibrio → stato più probabile (n. massimo di realizzazioni micro)

S: misura della nostra ignoranza / incertezza riguardo allo stato microscopico del sistema

Es. espansione libera

$$S_n = k_B \ln \omega_n$$

$$\Delta S = S_{\frac{N}{2}} - S_N = k_B \ln \left[\frac{N!}{\left(\frac{N}{2}\right)! \left(\frac{N}{2}\right)!} \right] - k_B \ln \left[\frac{\cancel{N!}}{\cancel{N!} \cdot 1} \right]$$

$\underbrace{\hspace{10em}}_{=0}$

$$= k_B \ln(N!) - 2k_B \ln \left[\left(\frac{N}{2}\right)! \right] = k_B \ln(N!) - 2k_B \ln \left[\left(\frac{N}{2}\right)! \right]$$

$$\approx k_B N \ln N - k_B N - \cancel{2} \frac{N}{\cancel{2}} k_B \ln \left(\frac{N}{2}\right) + \cancel{2} k_B \frac{N}{\cancel{2}}$$

$$= k_B N \cancel{\ln N} - k_B N \cancel{\ln N} + N k_B \ln 2$$

$$= k_B N \ln 2 \quad \square$$

Approssimazione di Stirling, $N \gg 1$

$$\ln(N!) \approx N \ln N - N$$