

PROVA SCRITTA DI SISTEMI DINAMICI
A.A. 2020/2021

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Nome e Cognome:

gruppo: Gruppo A

esercizio: Esercizio 1

Note: Scrivere le risposte su un singolo foglio bianco usando penna nera. Non scrivere con inchiostro blu o a matita. Non consegnare fogli aggiuntivi. La chiarezza e precisione nelle risposte sarà oggetto di valutazione.

Dichiaro che le risposte a questo esercizio sono frutto del mio e solo del mio lavoro e che non mi sono consultato con altri.

Soluzione

esercizio 2

Domanda 2

Siano $x(\cdot)$ e $z(\cdot)$ due **processi stazionari di rumore bianco gaussiano, indipendenti tra loro**, con

$$E[x(t)] = 5.0, \sigma_x^2 = 0.4 \quad E[z(t)] = 0.0, \sigma_z^2 = 6.25 \quad \forall t$$

Si supponga di poter osservare la variabile

$$y(t) = 2.3x(t) + 4.2z(t)$$

e di aver osservato i valori seguenti:

$$y(1) = 4.815 \quad y(2) = 1.623$$

1. Facendo uso della **formula di Bayes**, determinare lo **stimatore ottimo** di $x(1)$ in base alla sola osservazione $y(1)$.

Quanto vale la varianza della stima?

2. Sempre facendo uso della **formula di Bayes**, determinare lo **stimatore ottimo** di $x(2)$ in base ad entrambe le osservazioni $y(1), y(2)$.

Quanto vale la varianza della stima stavolta? E quanto vale l'innovazione di $y(2)$ rispetto all'osservazione $y(1)$?

punto 1: stima e predice dalla 1^a osservazione

della Teoria

Bayes Estimation: Generalisations

- If $E(d) = d_m$, $E(\vartheta) = \vartheta_m$, then:

$$\begin{cases} \hat{\vartheta} = \vartheta_m + \frac{\lambda_{\vartheta d}}{\lambda_{dd}} (d - d_m) \\ \text{var}(\vartheta - \hat{\vartheta}) = \lambda_{\vartheta\vartheta} - \frac{\lambda_{\vartheta d}^2}{\lambda_{dd}} \end{cases}$$

- If d and ϑ are vectors with $E(d) = d_m$, $E(\vartheta) = \vartheta_m$ and

$$\text{var} \left(\begin{bmatrix} d \\ \vartheta \end{bmatrix} \right) = \begin{bmatrix} \Lambda_{dd} & \Lambda_{d\vartheta} \\ \Lambda_{\vartheta d} & \Lambda_{\vartheta\vartheta} \end{bmatrix} \quad \Lambda_{d\vartheta} = \Lambda_{\vartheta d}^\top$$

Then:

$$\begin{cases} \hat{\vartheta} = \vartheta_m + \Lambda_{\vartheta d} \Lambda_{dd}^{-1} (d - d_m) \\ \text{var}(\vartheta - \hat{\vartheta}) = \Lambda_{\vartheta\vartheta} - \Lambda_{\vartheta d} \Lambda_{dd}^{-1} \Lambda_{d\vartheta} \end{cases}$$

Bisogna notare le varianze e covarianze presenti nelle formule:

$$\Lambda_{\vartheta\vartheta} = \text{var}(x) = 0,9$$

$$\Lambda_{\vartheta\vartheta} = \text{var}(y) \leftarrow \text{da calcolare}$$

$$\Lambda_{\vartheta d} = \text{cov}(x, y) \leftarrow \text{da calcolare}$$

$$\text{var}(y) = (2.3)^2 \text{var}(x) + (4.2)^2 \text{var}(z) = 112,3660$$

$$d_{\mu} = E[y] = 2.3 E[x] + 4.2 E[z]$$

$$= 11,500$$

$$\Lambda_{\delta\delta} = \text{cov}(x, y) = E[(x - \bar{x})(y - \bar{y})] =$$

$$\bar{x} = E(x)$$

$$\bar{y} = E(y)$$

$$= E\left\{ (x - \bar{x}) \left[2.3(x - \bar{x}) + 4.2(z - \bar{z}) \right] \right\}$$

$$= 2.3 E[(x - \bar{x})^2] + 4.2 E[(x - \bar{x})(z - \bar{z})]$$

$$\text{var}(x)$$

$$\text{cov}(x, z) = 0$$

Sono indipendenti

$$= 2.3 \text{var}(x)$$

$$= 0,9200$$

A questo punto

$$\hat{x} = \bar{x} + \Lambda_{\delta\delta}^{-1} \cdot \Lambda_{\delta d}^{-1} \cdot [y(1) - \bar{y}]$$

$$= 9,8953$$

$$\text{var}(x - \hat{x}) = \Lambda_{\delta\delta} - \Lambda_{\delta d}^2 \cdot \Lambda_{\delta d}^{-1} = 0,3925$$

giunto 2: stima usando Zonnestromi

dalle teorie

Recursive form of Bayes estimation

- For now, denote by ϑ the unknown to be estimated and by d the observed data.
- Suppose (just for simplicity and without loss of generality) that
 - ϑ scalar
 - $d(1), d(2)$ two scalar data
 - $E(\vartheta) = 0, E[d(1)] = 0, E[d(2)] = 0$
- Then

$$\begin{bmatrix} \vartheta \\ d(1) \\ d(2) \end{bmatrix} \sim G \left(\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} \lambda_{\vartheta\vartheta} & \lambda_{\vartheta 1} & \lambda_{\vartheta 2} \\ \lambda_{1\vartheta} & \lambda_{11} & \lambda_{12} \\ \lambda_{2\vartheta} & \lambda_{21} & \lambda_{22} \end{bmatrix} \right)$$

where $\lambda_{\vartheta\vartheta} = E(\vartheta^2), \lambda_{\vartheta 1} = E[\vartheta d(1)], \dots$

Recursive form of Bayes estimation (cont.)

- The estimate of ϑ based on the **single data point** $d(1)$ is given by

$$E[\vartheta | d(1)] = \frac{\lambda_{\vartheta 1}}{\lambda_{11}} d(1)$$

- Instead, the estimate of ϑ based on **two data points** $d(1), d(2)$ is

$$E[\vartheta | d(1), d(2)] = [\lambda_{\vartheta 1} \quad \lambda_{\vartheta 2}] \begin{bmatrix} \lambda_{11} & \lambda_{12} \\ \lambda_{21} & \lambda_{22} \end{bmatrix}^{-1} \begin{bmatrix} d(1) \\ d(2) \end{bmatrix}$$

where $\lambda_{12} = \lambda_{21}$ But

$$\begin{bmatrix} \lambda_{11} & \lambda_{12} \\ \lambda_{21} & \lambda_{22} \end{bmatrix}^{-1} = \frac{1}{\lambda_{11}\lambda_{22} - \lambda_{12}^2} \begin{bmatrix} \lambda_{22} & -\lambda_{12} \\ -\lambda_{12} & \lambda_{11} \end{bmatrix}$$

and hence

$$E[\vartheta | d(1), d(2)] = \frac{1}{\lambda_{11}\lambda_{22} - \lambda_{12}^2} [(\lambda_{\vartheta 1}\lambda_{22} - \lambda_{\vartheta 2}\lambda_{12}) d(1) + (-\lambda_{\vartheta 1}\lambda_{12} + \lambda_{\vartheta 2}\lambda_{11}) d(2)]$$

Recursive form of Bayes estimation (cont.)

recursion

$$E[\vartheta | d(1), d(2)] = \frac{1}{\lambda^2} \left(\lambda_{\vartheta 2} - \lambda_{\vartheta 1} \frac{\lambda_{12}}{\lambda_{11}} \right) d(2) + \frac{1}{\lambda^2} \left(\lambda_{\vartheta 1} \frac{\lambda_{22}}{\lambda_{11}} - \lambda_{\vartheta 2} \frac{\lambda_{12}}{\lambda_{11}} - \lambda_{\vartheta 1} \frac{\lambda^2}{\lambda_{11}} \right) d(1) + \frac{\lambda_{\vartheta 1}}{\lambda_{11}} d(1)$$

- substituting $\lambda^2 = \lambda_{22} - \frac{\lambda_{12}^2}{\lambda_{11}}$ we have

$$E[\vartheta | d(1), d(2)] = \frac{\lambda_{\vartheta 1}}{\lambda_{11}} d(1) + \frac{1}{\lambda^2} \left(\lambda_{\vartheta 2} - \lambda_{\vartheta 1} \frac{\lambda_{12}}{\lambda_{11}} \right) \left[d(2) - \frac{\lambda_{12}}{\lambda_{11}} d(1) \right]$$

- **Definition.** Given two random variables $d(1)$ and $d(2)$ we call **innovation** of $d(2)$ with respect to $d(1)$ the quantity:

$$e = d(2) - E[d(2) | d(1)] = d(2) - \frac{\lambda_{12}}{\lambda_{11}} d(1)$$

Generalization to the vector case

- Now, if $\vartheta, d(1), d(2)$ are **zero-mean vectors** we have:

$$\begin{bmatrix} \vartheta \\ d(1) \\ d(2) \end{bmatrix} \sim G \left(\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} \Lambda_{\vartheta\vartheta} & \Lambda_{\vartheta 1} & \Lambda_{\vartheta 2} \\ \Lambda_{1\vartheta} & \Lambda_{11} & \Lambda_{12} \\ \Lambda_{2\vartheta} & \Lambda_{21} & \Lambda_{22} \end{bmatrix} \right)$$

where $\Lambda_{\vartheta 1} = \Lambda_{1\vartheta}^\top$, $\Lambda_{\vartheta 2} = \Lambda_{2\vartheta}^\top$, $\Lambda_{21} = \Lambda_{12}^\top$

- We obtain:

$$e = d(2) - E[d(2) | d(1)] = d(2) - \Lambda_{21} \Lambda_{11}^{-1} d(1)$$

and hence:

$$\begin{aligned} E[\vartheta | d(1), d(2)] &= E[\vartheta | d(1)] + E[\vartheta | e] \\ &= \Lambda_{\vartheta 1} \Lambda_{11}^{-1} d(1) + \Lambda_{\vartheta e} \Lambda_{ee}^{-1} e \end{aligned}$$

Generalization to the non-zero mean case

- Now, if ϑ , $d(1)$, $d(2)$ are **non-zero mean vectors** we have:

$$\begin{bmatrix} \vartheta \\ d(1) \\ d(2) \end{bmatrix} \sim G \left(\begin{bmatrix} \vartheta_m \\ d(1)_m \\ d(2)_m \end{bmatrix}, \begin{bmatrix} \Lambda_{\vartheta\vartheta} & \Lambda_{\vartheta 1} & \Lambda_{\vartheta 2} \\ \Lambda_{1\vartheta} & \Lambda_{11} & \Lambda_{12} \\ \Lambda_{2\vartheta} & \Lambda_{21} & \Lambda_{22} \end{bmatrix} \right)$$

- We obtain:

$$\begin{aligned} E[\vartheta | d(1), d(2)] &= E[\vartheta | d(1)] + E[\vartheta | e] - \vartheta_m \\ &= \vartheta_m + \Lambda_{\vartheta 1} \Lambda_{11}^{-1} [d(1) - d(1)_m] + \Lambda_{\vartheta e} \Lambda e e^{-1} e \end{aligned}$$

where, in analogy with the zero-mean scalar case we have:

- $E(e) = 0$
- $\Lambda_{1e} = E \{ [d(1) - d(1)_m]^T e \} = 0$
- $\Lambda_{\vartheta e} = \Lambda_{\vartheta 2} - \Lambda_{\vartheta 1} \Lambda_{11}^{-1} \Lambda_{12}$

Per determinare le misure di coerenza delle osservazioni:

$$\begin{bmatrix} d_{11} & d_{12} \\ d_{21} & d_{22} \end{bmatrix} = \begin{bmatrix} \text{var}[y(1)] & \text{cov}[y(1), y(2)] \\ \text{cov}[y(2), y(1)] & \text{var}[y(2)] \end{bmatrix}$$

$$\text{var}[y(1)] = \text{var}[y]$$

$$\text{var}[y(2)] = \text{var}[y]$$

il processo di $y(\cdot)$ è
 stazionario!

$$E \left\{ \left[y^{(1)} - \underbrace{E(y^{(1)})}_{\bar{y}} \right] \left[y^{(2)} - \underbrace{E(y^{(2)})}_{\bar{y}} \right] \right\} = \text{cov}[y^{(1)}, y^{(2)}]$$

$$E \left\{ \left[y^{(1)} - \bar{y} \right] \cdot \left[y^{(2)} - \bar{y} \right] \right\} \quad y = 2.3x + 9.2z$$

$$= E \left\{ y^{(1)} y^{(2)} - \bar{y} [y^{(1)} + y^{(2)}] + \bar{y}^2 \right\} =$$

$$\hookrightarrow E \left\{ \left[2.3x^{(1)} + 9.2z^{(1)} \right] \left[2.3x^{(2)} + 9.2z^{(2)} \right] \right\} +$$

$$- \bar{y} \left[\underbrace{E(y^{(1)})}_{\bar{y}} + \underbrace{E(y^{(2)})}_{\bar{y}} \right] + \bar{y}^2$$

-2\bar{y}^2 -\bar{y}^2

$$= (2.3)^2 E \{ x^{(1)} \cdot x^{(2)} \} + (9.2)^2 E \{ z^{(1)} \cdot z^{(2)} \} +$$

$$+ (2.3 \cdot 9.2) E [x^{(1)} \cdot z^{(2)}] +$$

$$+ (2.3 \cdot 9.2) E [x^{(2)} \cdot z^{(1)}] - \bar{y}^2$$

*x^{(1)} e z^{(1)}
sono indipendenti*

$$\bar{y}^2 = (2.3\bar{x} + 9.2\bar{z})^2$$

$\bar{z} = 0$
 $= (2.3)^2 (\bar{x})^2$

$$\text{cov}[y(1), y(2)] =$$

$$= (2,3)^2 E\{x(1) \cdot x(2)\} + (9,2)^2 E\{z(1) \cdot z(2)\} + \text{cov}[z(1), z(2)]$$

\swarrow *random process*
 \emptyset

$$= (2,3)^2 \left\{ E[x(1) \cdot x(2)] - (\bar{x})^2 \right\} = \emptyset$$

$$\text{cov}[x(1), x(2)] = \emptyset$$

random process

In definition

$$\Delta_{\text{dd}} = \begin{bmatrix} \text{var}(y(1)) & \text{cov}[y(1), y(2)] \\ \text{cov}[y(2), y(1)] & \text{var}[y(2)] \end{bmatrix}$$

$$= \begin{bmatrix} \text{var } y & \emptyset \\ \emptyset & \text{var } y \end{bmatrix}$$

Quindi

$$\begin{bmatrix} d_{11} & d_{12} \\ d_{21} & d_{22} \end{bmatrix} = \begin{bmatrix} \text{var } y & 0 \\ 0 & \text{var } y \end{bmatrix}$$

Il momento da calcolare d_{01} e d_{02}

$$d_{01} = \text{cov}[x, y^{(1)}] =$$

$$= E[(x - \bar{x})(y^{(1)} - \bar{y})] = 2.3 \text{ var } x$$

$$d_{02} = \text{cov}[x, y^{(2)}] =$$

$$= E[(x - \bar{x})(y^{(2)} - \bar{y})] = 2.3 \text{ var } x$$

perché iici
2 fogli ripetuto

A questo sto: $e = [d(z) - d(z)_m] - \frac{d_{12}}{d_{11}} [d(1) - d(1)_m]$

ma $d_{12} = 0$

$$e \triangleq y(z) - \bar{y}$$

$y(\cdot)$ è combinazione
di variabili
indip. ! S' N/A !

$$\sigma_{01} = \text{cov}[x, g(\cdot)] = E[(x^{(i)} - \bar{x})(g^{(i)} - \bar{y})]$$

B quando osservo $y^{(i)}$, la v.a. x assume
nel $x^{(i)}$

$$= E[x^{(i)} g^{(i)} - x^{(i)} \bar{y} - \bar{x} g^{(i)} + \bar{x} \bar{y}] =$$

$$= E[x^{(i)} g^{(i)}] - \bar{y} E[x^{(i)}] - \bar{x} E[g^{(i)}] + \bar{x} \bar{y} =$$

$$= E[x^{(i)} \cdot g^{(i)}] - \bar{x} \bar{y} - \bar{x} \bar{y} + \bar{x} \bar{y}$$

$$= E[x^{(i)} \cdot (2.3 x^{(i)} + 4.2 z^{(i)})] - \bar{x} \bar{y} =$$

$$= 2.3 E[x^{(i)} \cdot x^{(i)}] + 4.2 E[x^{(i)} z^{(i)}] - \bar{x} \bar{y} =$$

$$= 2.3 E[(x^{(i)})^2] - 2.3 \bar{x}^2$$

$$\bar{y} = 2.3 \bar{x} + 4.2 \bar{z} = 2.3 \bar{x}$$

indipendenti

\emptyset

$$\sigma_1 = 2.3 \left\{ E[(x^{(1)})^2] - [E[x^{(1)}]]^2 \right\}$$

$$E(x^2) - [E(x)]^2 = \text{var } x$$

$$= 2.3 \text{ var } (x) //$$

Analoghi passaggi su σ_2

Per questo riguarda la stima

$$E[x | y(1), y(2)] = E(x) + \frac{d_{01}}{d_{11}} [y(1) - \bar{y}] + \frac{d_{02}}{d_{22}} e$$

$$e = y(2) - \bar{y}$$

$$d_{0e} = d_{02} - d_{01} \frac{d_{12}}{d_{11}} = d_{02}$$

$$d_{ee} = d_{22} - \frac{d_{12}^2}{d_{11}} = d_{22}$$

In definitiva:

$$\hat{x}(2) = 5,0 + \frac{0,92}{112,3660} \cdot (-6,6850) +$$

$$+ \frac{0,92}{112,3660} \cdot (-9,8770) \approx 4,8649$$

$$\text{var}[x(z) - \hat{x}(z)] = \text{var} x +$$

$$- [d_{01} \ d_{02}] \begin{bmatrix} d_{11} & d_{12} \\ d_{12} & d_{22} \end{bmatrix}^{-1} \begin{bmatrix} d_{01} \\ d_{02} \end{bmatrix} =$$

$$= 0,3899$$

$$B \quad \text{var}[x(1) - \hat{x}(1)] > \text{var}[x(2) - \hat{x}(2)]$$