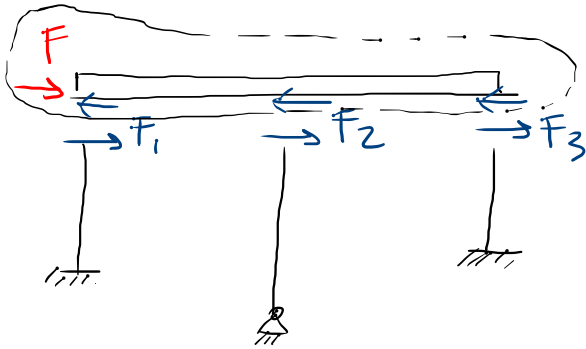
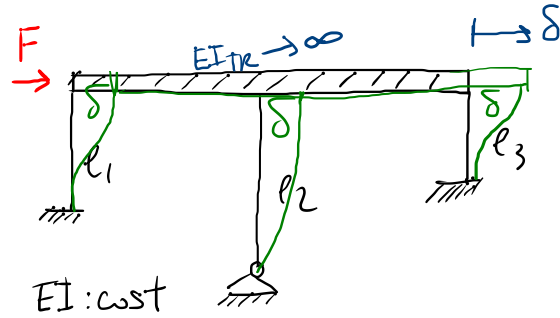


2° ESEMPIO: RIPARTIZ. DI UNA FORZA ORIZZ. APPLICATA AD UNA TRAVE RIGIDA (SHEAR-TYPE)

28/3/23



EQUIL. TRASL. ORIZZ DELLA TRAVE

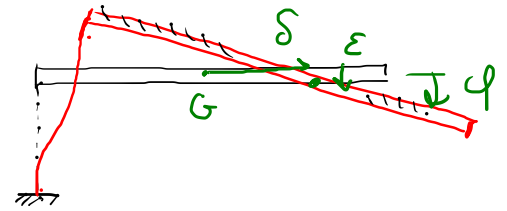
$$F - F_1 - F_2 - F_3 = 0$$

RIDIGEREA ALLA TRASL.:

$$F = \left[\frac{12EI}{l_1^3} + \frac{3EI}{l_2^3} + \frac{12EI}{l_3^3} \right] \delta$$

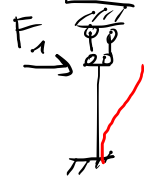
$$F = K_T \delta \Rightarrow \delta = \frac{F}{K_T}$$

IN GENERALE QUESTO SIST. HA 3 GDL, δ, ϵ, ϕ .



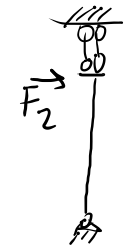
PERO' PER CALCOLE LA DISTRIBUZ. DI F NEI 3 PILASTRI E' SUFFICIENTE, TENUO CONTO CHE

I PILASTRI SONO QUASI INESTENSIBILI, CONSID. SOLO LA TRASL. δ .



$$\delta = \frac{F_1 l_1^3}{12EI}$$

$$F_1 = \frac{12EI}{l_1^3} \delta$$



$$F_2 = \frac{3EI}{l_2^3} \delta$$

QUANDO VALGONO F_1, F_2, \dots ?

$$p_1 + p_2 + p_3 = 1$$

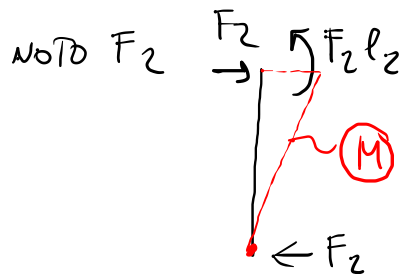
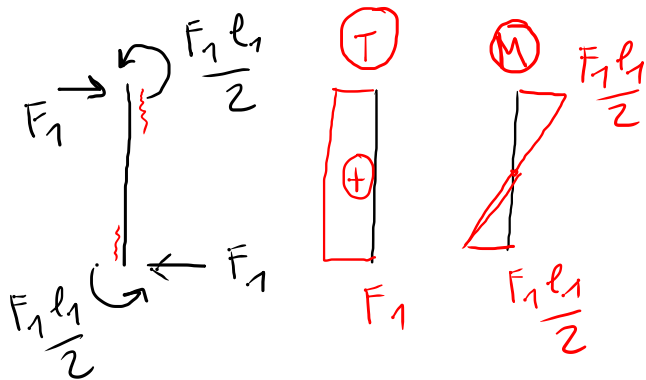
p_1
COEFF DI
F RIPARTIZIONE

$$F_1 = \frac{12 EI}{l_1^3} \frac{F}{K_T} = \frac{12 EI}{l_1^3} \frac{1}{K_T} F$$

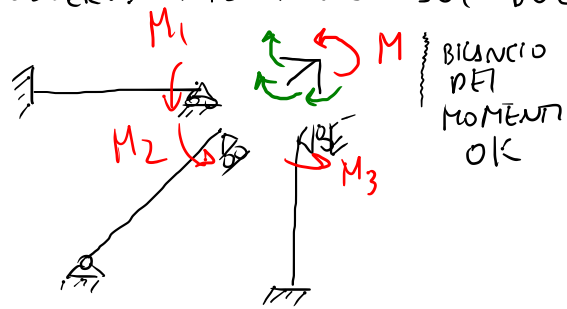
$$F_2 = \frac{3 EI}{l_2^3} \frac{F}{K_T} = \frac{3 EI}{l_2^3} \frac{1}{K_T} F$$

$$F_3 = \frac{12 EI}{l_3^3} \frac{F}{K_T}$$

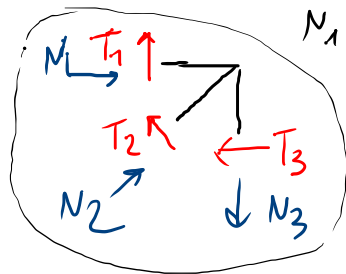
NOTO F_1 ...



OSSERV. IMPORTANTI SUI DUE ESEMPI INTRODOTTI



BILANCIO
DEI
MOMENTI
OK



N_1, N_2, N_3

SONO TALI
DA BILANCIARE
LE FORZE
NEL NODO.

NOTI I MOMENTI M_i È SEMPLICE
CALCOLARE ANCHE I TAGLI T_i

(HO PERO' A
DISPOSIZ. SOLO

COSA POSSIAMO DIRE PER QUANTO
RIGUARDA LE FORZE NORMALI N_i ?

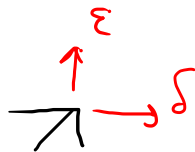
2 EQ. DI BILANCIO;

CON IL METODO INTRODOTTO NON POSSIAMO
DIRE NULLA

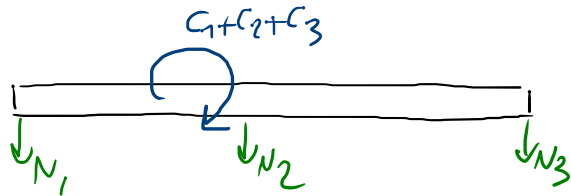
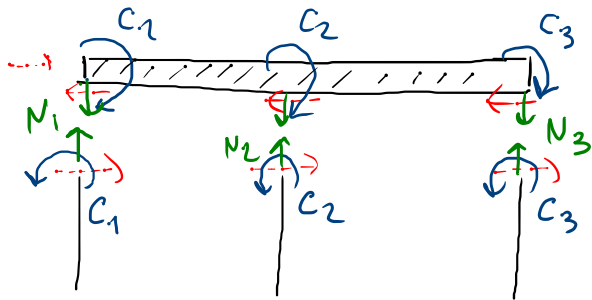
QUINDI HO UN NUOVO
PROBLEMA IPERSTATICO

- 2 EQ IN 3 INCOGNITE.

INTRODUCO GLI SPOST.
 δ_i DEL NODO -)



PER LA TRAVE RIGIDA (TIPO SHEAR-TYPE)

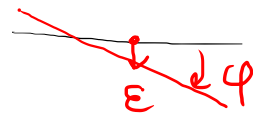


N_1, N_2, N_3 : SONO 3

INCIGNITE DEL

"NUOVO" PROBLEMA:

1 G.D.L. COINVOLTI SONO



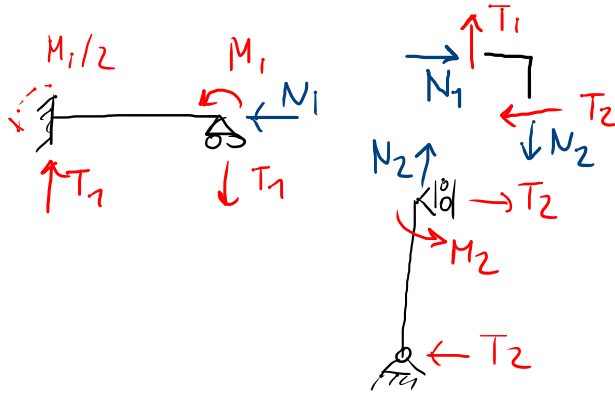
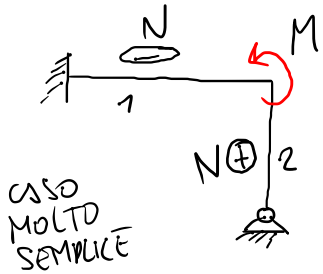
IMPONGO IL BILANCIO
DELLE FORZE VERTICALI E
DEI MOMENTI;

2 EQ. IN 3 INCIGNITE

FORMULO UN NUOVO
PROBLEMA NEGLI

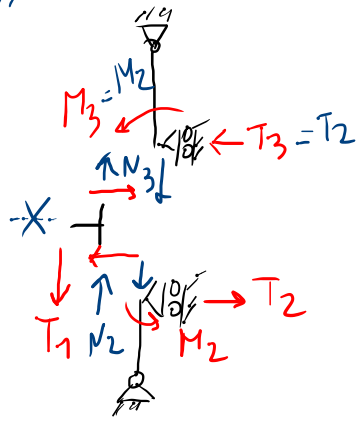
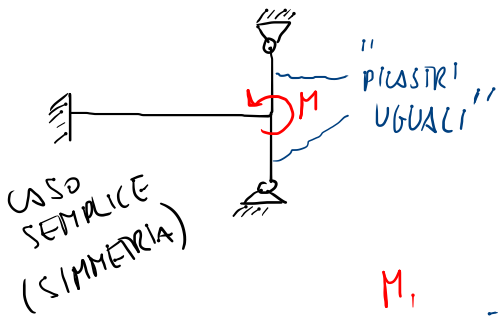
SPOST. E, φ .

ALCUNI CASI SEMPLICI DI DETERMINAZIONE DI FORZE NORMALI NELLE ASTE



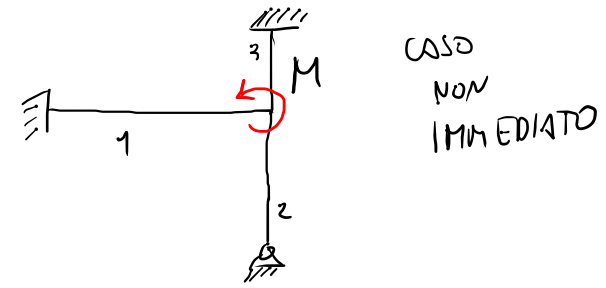
$$N_1 = T_2$$

$$N_2 = T_1$$

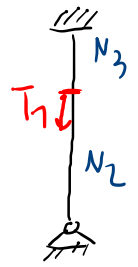


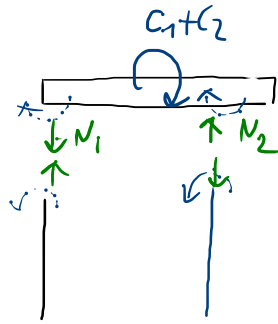
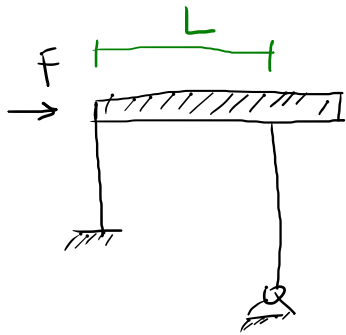
$$N_2 = N_3 = \frac{T_1}{2}$$

$$N_1 = 0$$



Per calcolare N_2 ed N_3 devo ripartire T_1 con uno scheme iperstatico:

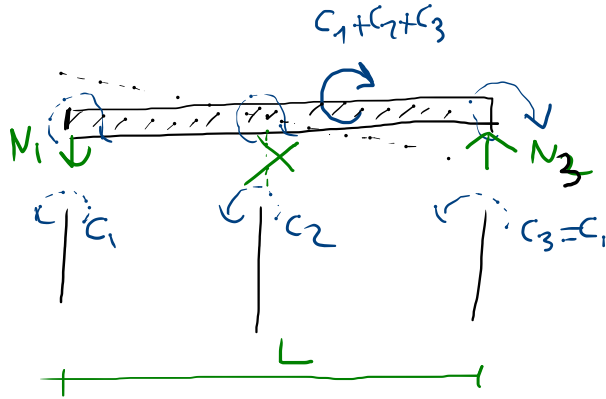
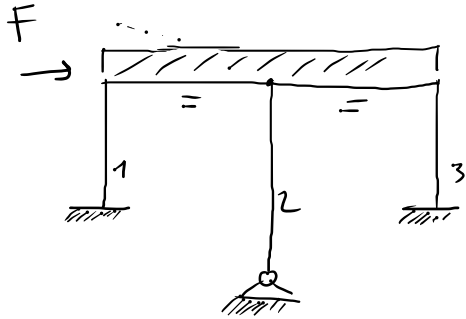




$$N_1 = N_2$$

$$N_1 L = C_1 + C_2 \Rightarrow N_1 = \frac{C_1 + C_2}{L}$$

CASO MOLTO
SEMPLICE

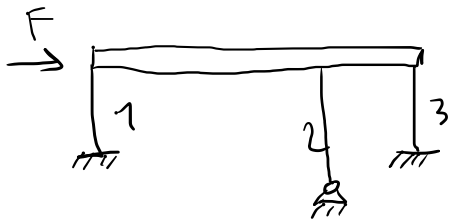


$$N_1 = N_3$$

$$N_1 L = C_1 + C_2 + C_3 \Rightarrow N_1$$

$$N_2 = 0$$

CASO SEMPLICE
(SIMMETRIA)

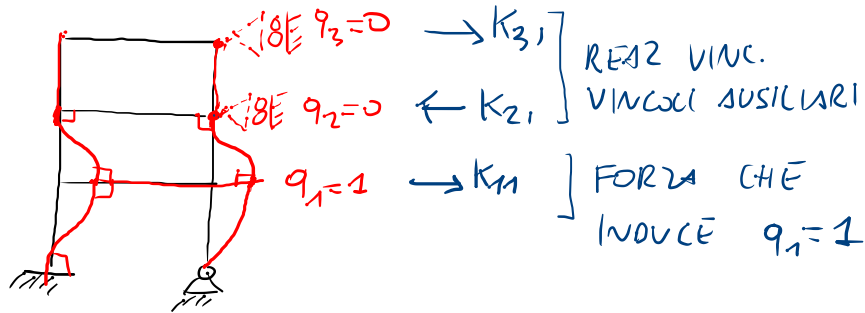
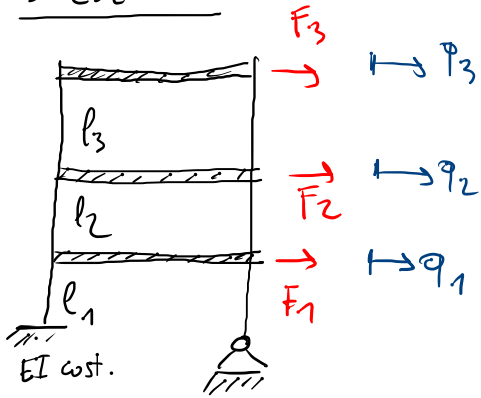


Per calcolare N_1, N_2, N_3 devo impostare un problema generale esprimendo $N_1(\xi, \varphi)$
 $N_2(\xi, \varphi), N_3(\xi, \varphi)$

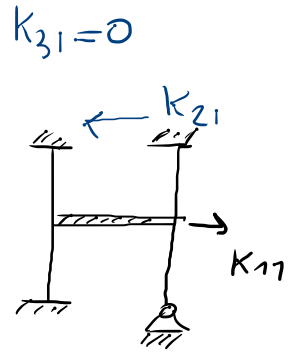
DAL PUNTO DI VISTA OPERATIVO LA COMPONENTE K_{ij} DELLA MATRICE DI RIGIDEZZA CORRISPONDE ALLA FORZA CORRETTA ALLO SPOST. i -SIMO QUANDO IL GDL j -SIMO VALE 1 E TUTTI I RESTANTI GDL SONO NULLI.

3° ESEMPIO

$$\boxed{q_1 = 1; q_2 = q_3 = 0} \Rightarrow K_{11}, K_{21}, K_{31} \text{ I COLONNA DI } K_{ij}$$



REAZ. VINC.
VINCOLI AUSILIARI
FORZA CHE INDUCE $q_1 = 1$



TEORIO SHEAR-TYPE

$$\underset{\text{STATICO}}{\sim} \underline{q} = \underline{F} ; \underset{\sim}{K} = \begin{bmatrix} 3 \times 3 \end{bmatrix} ; \underline{F} = \begin{bmatrix} F_1 \\ F_2 \\ F_3 \end{bmatrix} \Rightarrow \underline{q} = \underset{\sim}{K}^{-1} \underline{F}$$