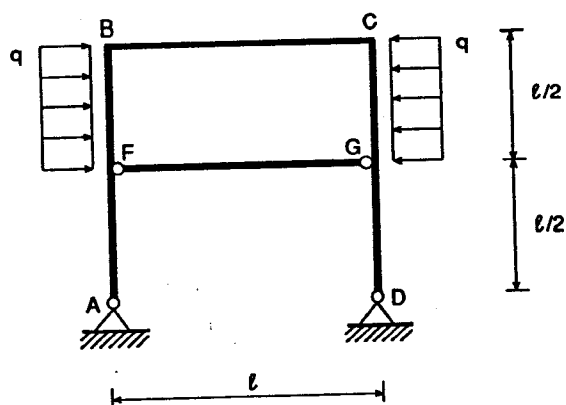
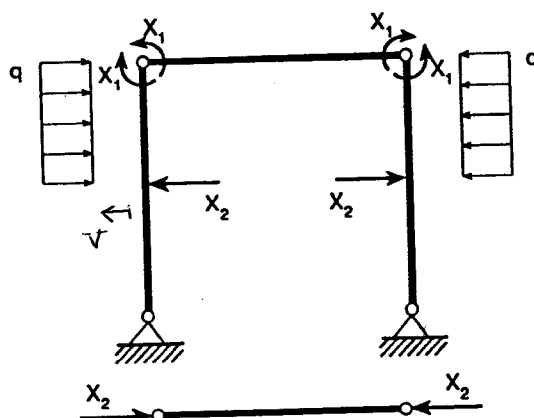
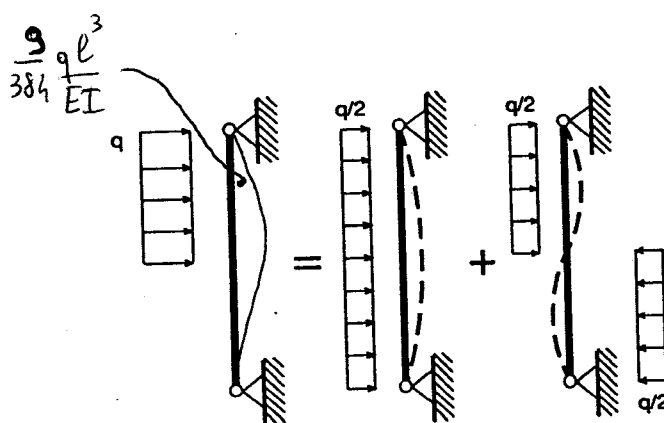




(a)



(b)



(c)

Figura 15.9

EQ. DI CONGRUENZA

$$\begin{cases} \int q_{ec} = q_{ba} \\ V_F = 0 \end{cases}$$

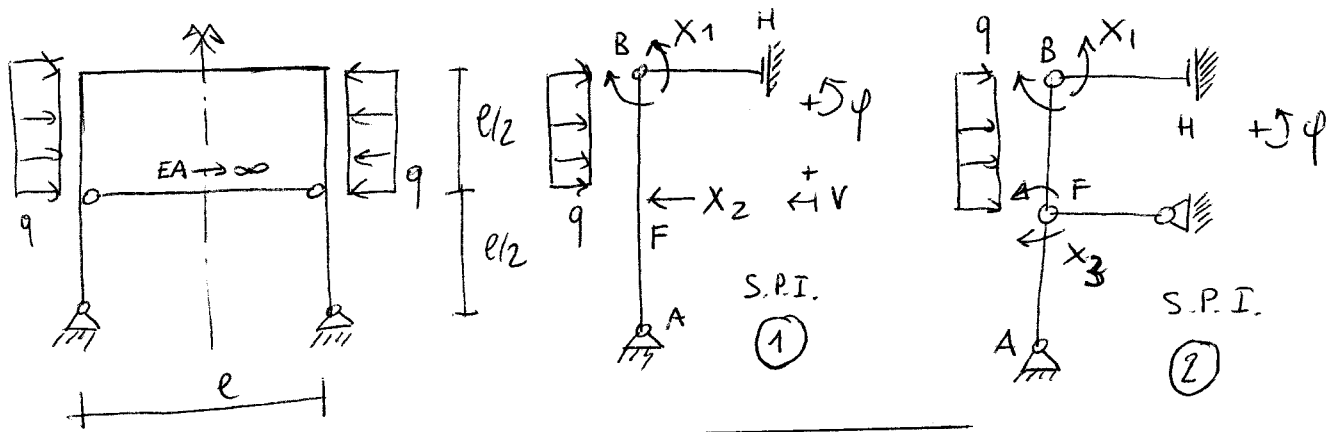
$$\frac{X_1 l}{3EI} + \frac{X_1 l}{6EI} = -\frac{X_1 l}{3EI} - \frac{X_2 l^2}{16EI} + \frac{9}{384} \frac{q l^3}{EI}$$

$$\frac{X_1 l^2}{16EI} + \frac{X_2 l^3}{48EI} - \frac{5}{384} \frac{q l^4}{2EI} = 0$$

$$X_1 = \frac{3}{496} q l^2$$

$$X_2 = \frac{73}{248} q l$$

ESERCIZIO FIG. 15.9 (CARPINTERI 2)

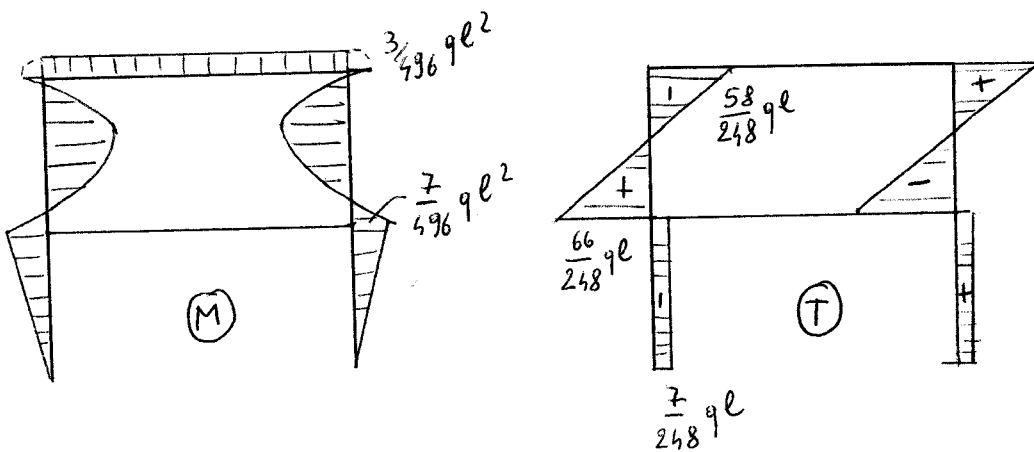


EQ. DI CONGRUENZA SPI ①

$$\left\{ \begin{array}{l} \varphi_{BA} = \varphi_{BH} \\ v_F = 0 \end{array} \right. \quad \left\{ \begin{array}{l} -\frac{x_1 l}{3EI} + \frac{9}{384} \frac{q l^3}{EI} - \frac{x_2 l^2}{16EI} = + \frac{x_1 l/2}{EI} \\ \frac{x_1 l^2}{16EI} + \frac{x_2 l^3}{48EI} - \frac{5}{384} \frac{q l^4}{2EI} = 0 \end{array} \right. \quad \left\{ \begin{array}{l} x_1 = \frac{3}{496} q l^2 \\ x_2 = \frac{73}{248} q l \end{array} \right.$$

EQ. DI CONGRUENZA SPI (2)

$$\begin{cases} \varphi_{BA} = \varphi_{BF} \\ \varphi_{FB} = \varphi_{FA} \end{cases} \quad \begin{cases} -\frac{x_1 l/2}{3EI} - \frac{x_3 l/2}{6EI} + \frac{q(l/2)^3}{24EI} = \frac{x_1 l/2}{EI} \\ \frac{x_3 l/2}{3EI} + \frac{x_1 l/2}{6EI} - \frac{q(l/2)^3}{24EI} = -\frac{x_3 l/2}{3EI} \end{cases} \quad \begin{cases} x_1 = \frac{3}{496} q l^2 \\ x_3 = \frac{7}{496} q l^2 \end{cases}$$



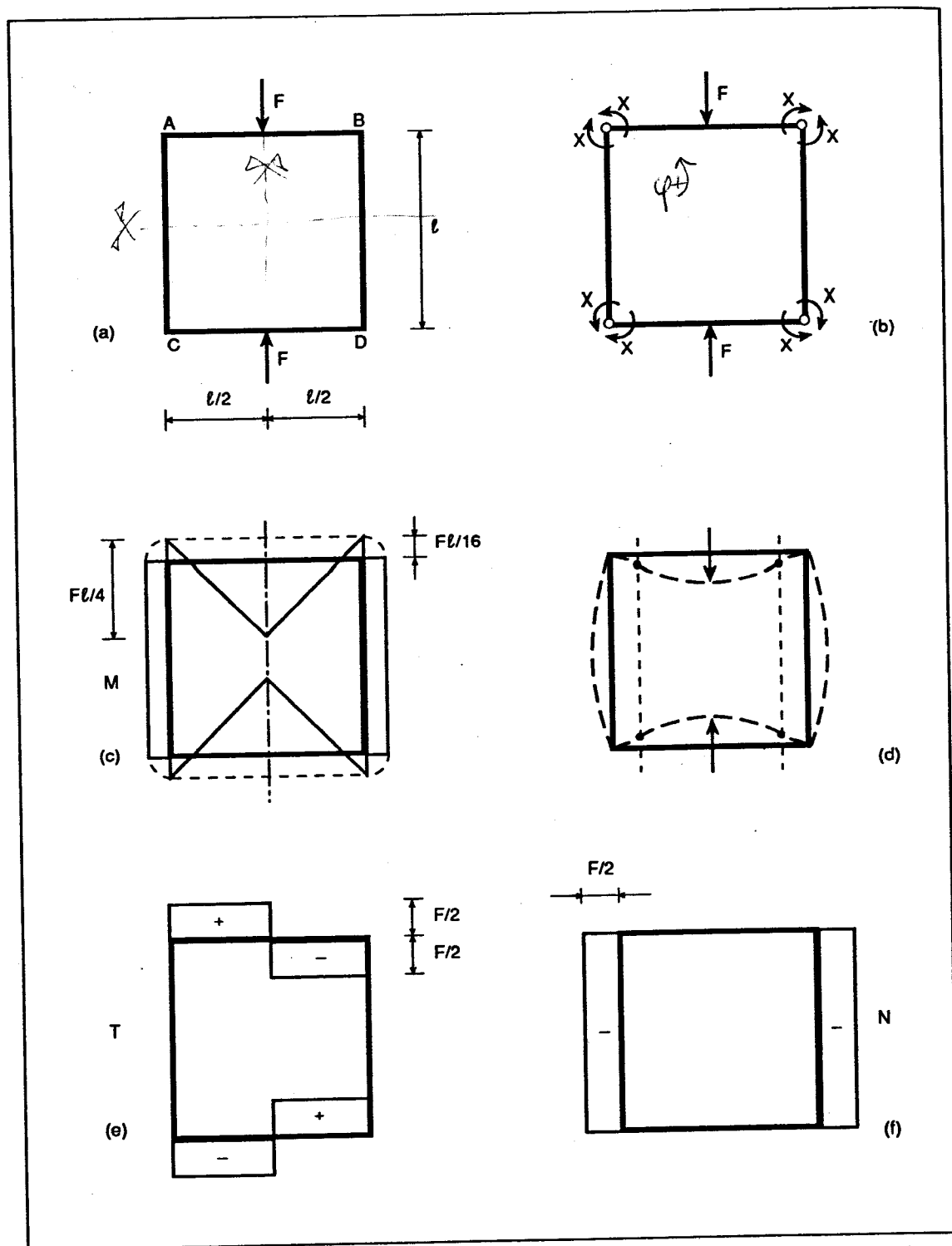
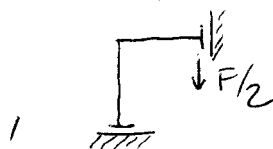


Figura 15.8 EQ. DI CONGRUENZA MODO A (SERVE UNA SOLA EQUAZIONE IN UNA INCOGNITA)

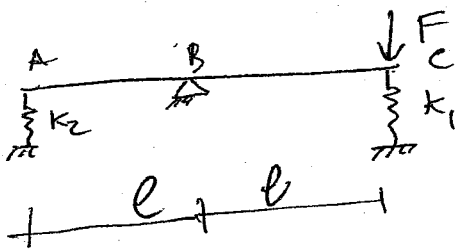
$$\frac{Xl}{3EI} + \frac{Xl}{6EI} - \frac{Fl^2}{16EI} = -\frac{Xl}{3EI} - \frac{Xl}{6EI} \rightarrow X = \frac{Fl}{16}$$

SCHEMI ALTERNATIVI
BASATI SULLA SIMMETRIA

CARRELLI CHE
BLOCCA IL MOVIMENTO
RIGIDO VERTECALE



ESERCIZIO

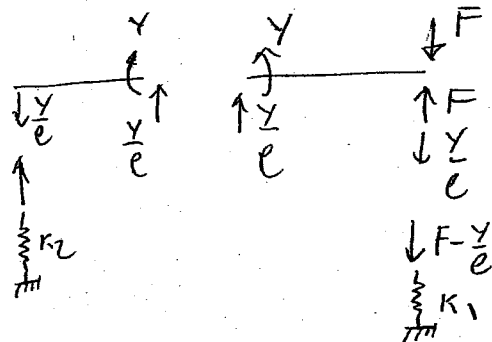
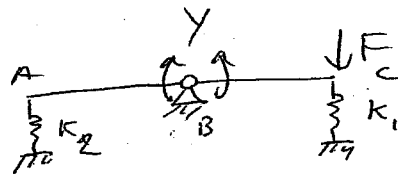


$\vec{C} + \boxed{\varphi_{BA} = \varphi_{BC}}$ congruente

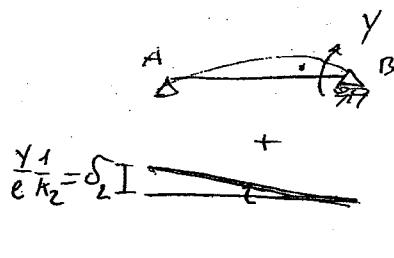
$\varphi_{BA}(Y, \text{moto rigido molle})$

$\varphi_{BC}(Y, F, \text{moto rigido molle})$

S.P.

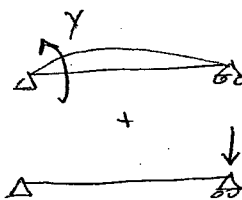


$\varphi_{BA} = \frac{Yl}{3EI} + \underbrace{\frac{Y}{l} \frac{1}{K_2} \frac{1}{l}}_{\delta_2}$



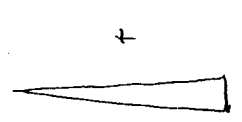
allungamento delle molle 2

$\varphi_{BC} = -\frac{Yl}{3EI} + \underbrace{\left(F - \frac{Y}{l}\right) \frac{1}{K_1} \frac{1}{l}}_{\delta_1}$



$\varphi_{BC}(Y)$

$\varphi_{BC}(F) = 0$



$\delta_1 = \left(F - \frac{Y}{l}\right) \frac{1}{K_1}$

$\varphi_{BC}(\text{moto rigido molle 1})$

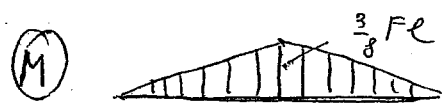
$\frac{Yl}{3EI} + \frac{Y}{l^2 K_2} = -\frac{Yl}{3EI} - \frac{Y}{l^2 K_1} + \frac{F}{K_1 l}$

RIVOLUZIONE ($K_1 = K_2$)

$\rightarrow \frac{2}{3} \frac{Yl}{EI} + \frac{2Y}{l^2 K_1} = \frac{F}{K_1 l}$

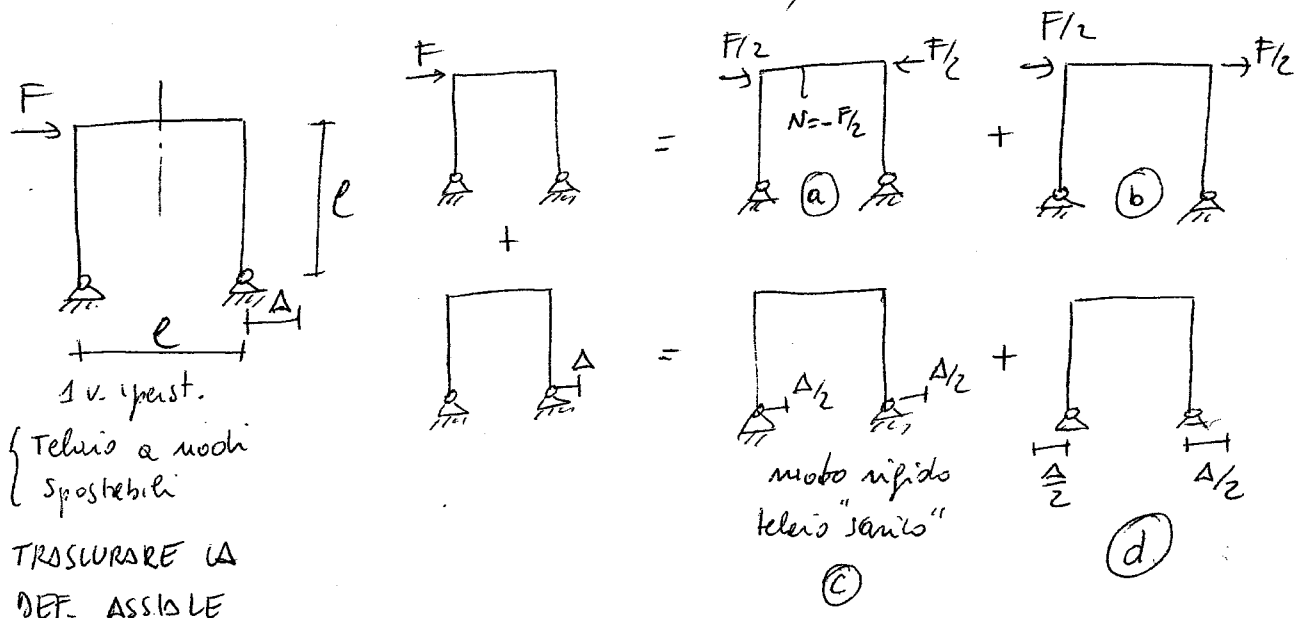
ASSUMO $K_1 = \frac{EI}{l^3}$

$\rightarrow \frac{2}{3} Y + 2Y = Fl \rightarrow \frac{8}{3} Y = Fl, Y = \frac{3}{8} Fl$

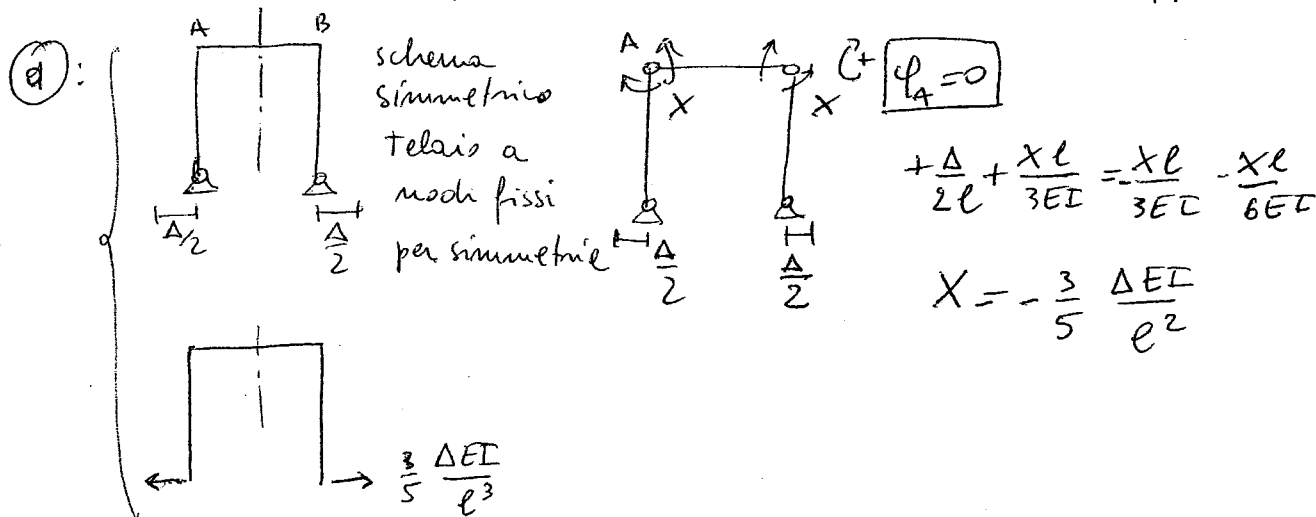
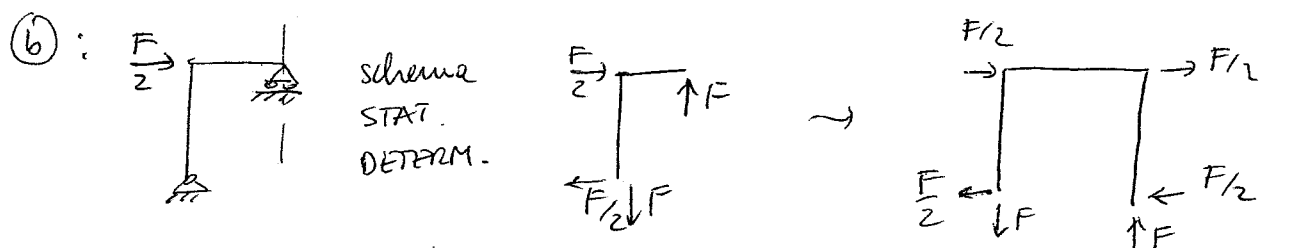


DEFORMATA : δ_1, δ_2 spost. molle.

ESERCIZIO (TELAIO A NODI SPOSTABILI)



Occorre risolvere (b) e (d):



Reatt. esterne compressive

