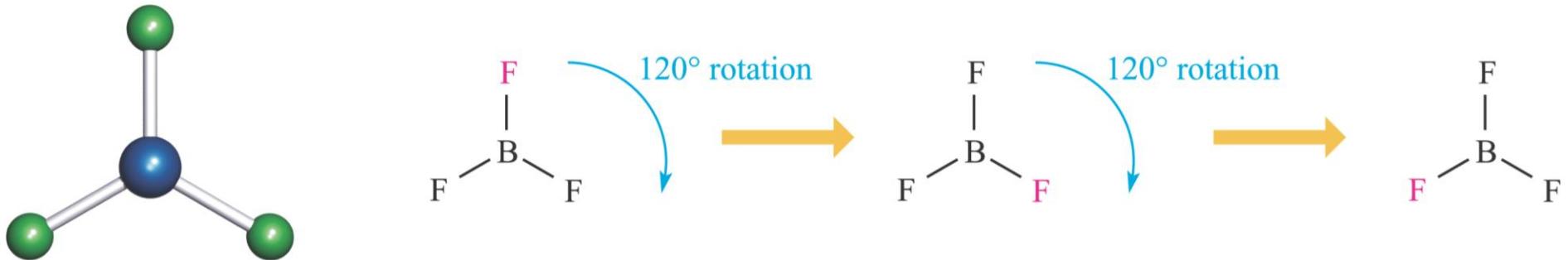


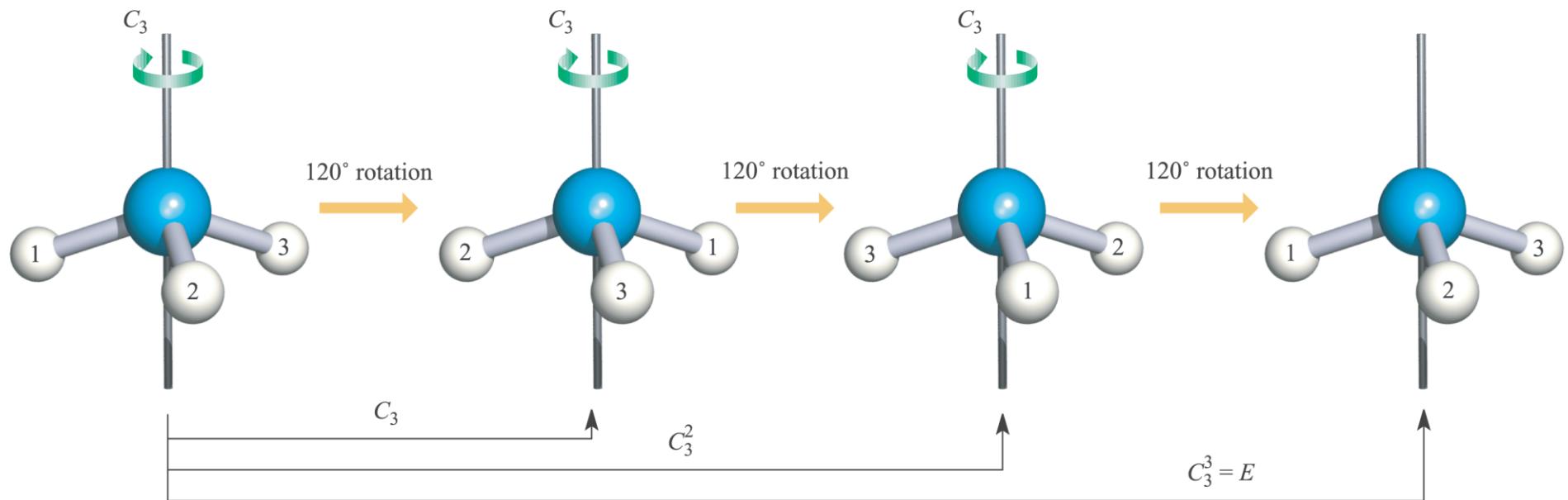
*Una molecola ha una **simmetria** se possiede due o più orientazioni nello spazio (o configurazioni) che sono indistinguibili*

*Una **operazione di simmetria** muove una molecola (o, in generale, un oggetto) intorno a un elemento di simmetria fino a una configurazione indistinguibile da quella originale*

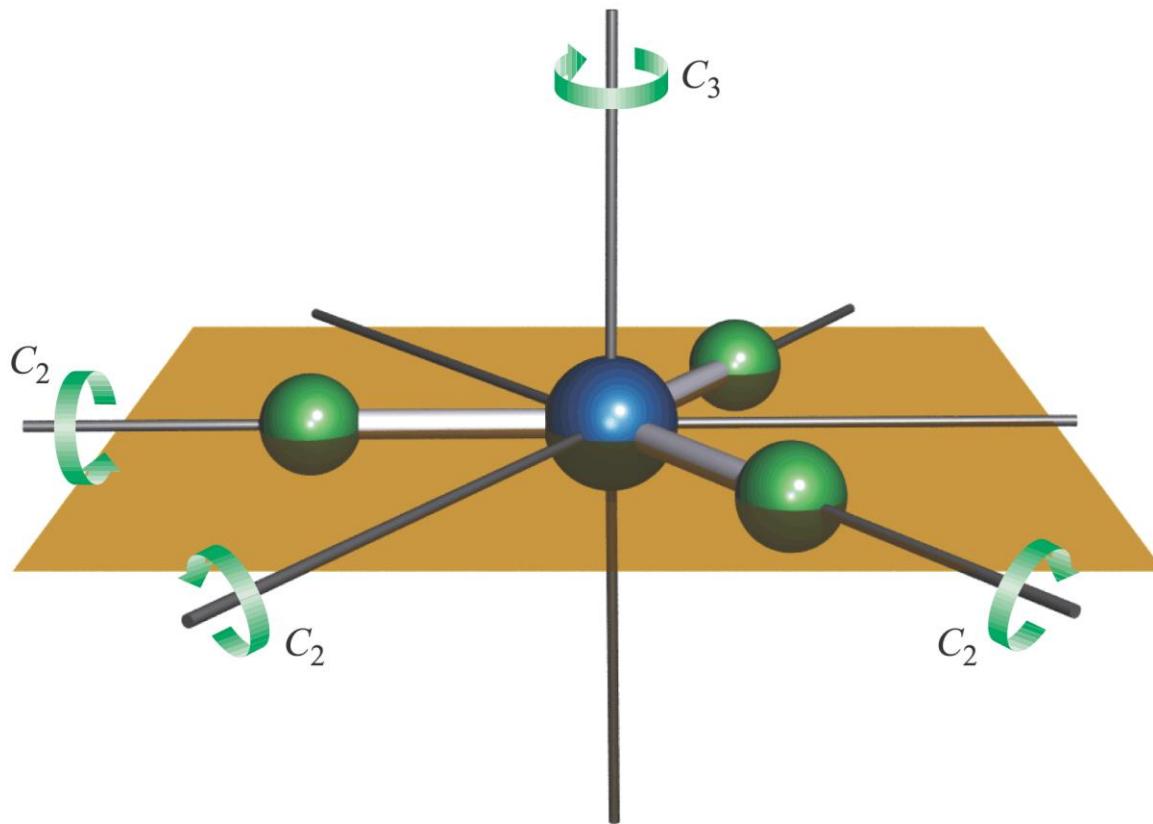
Asse C_n = rotazione di $360^\circ/n$



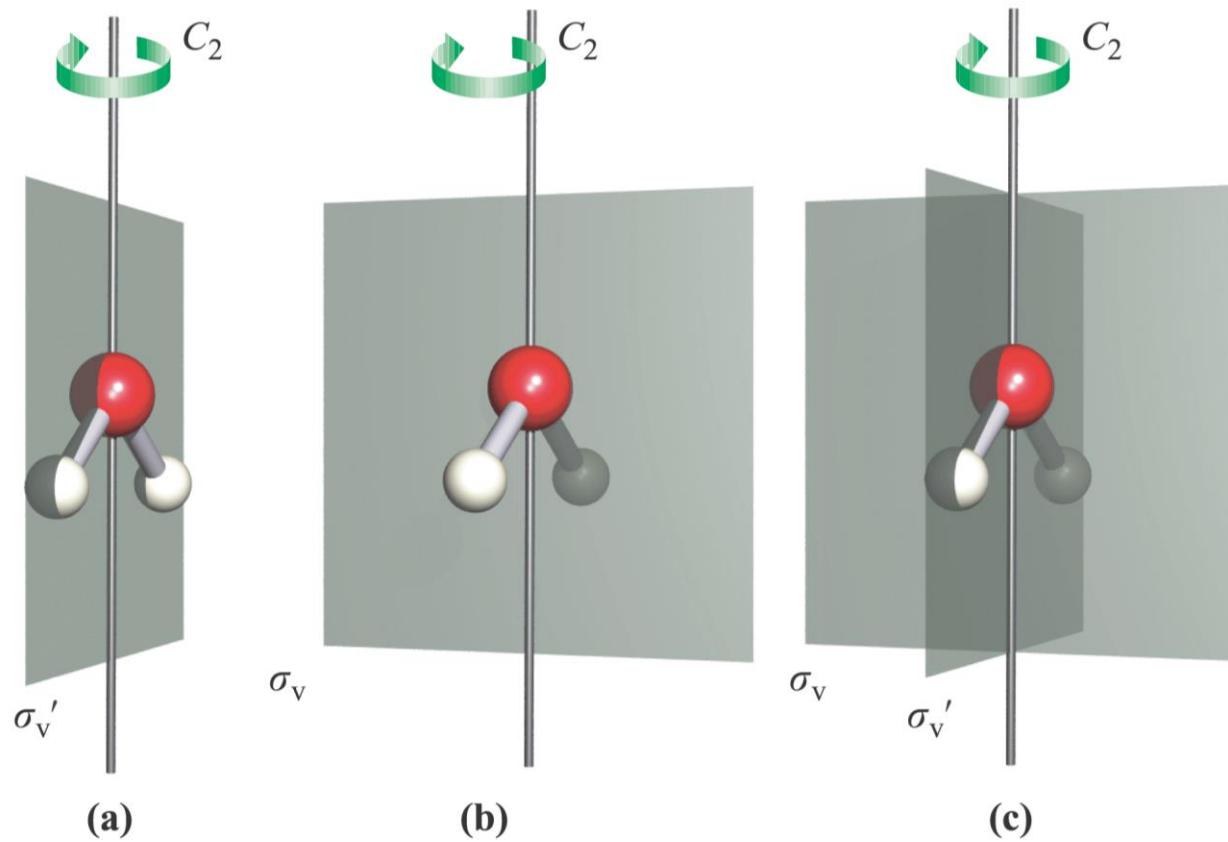
$$C_n^n = E$$

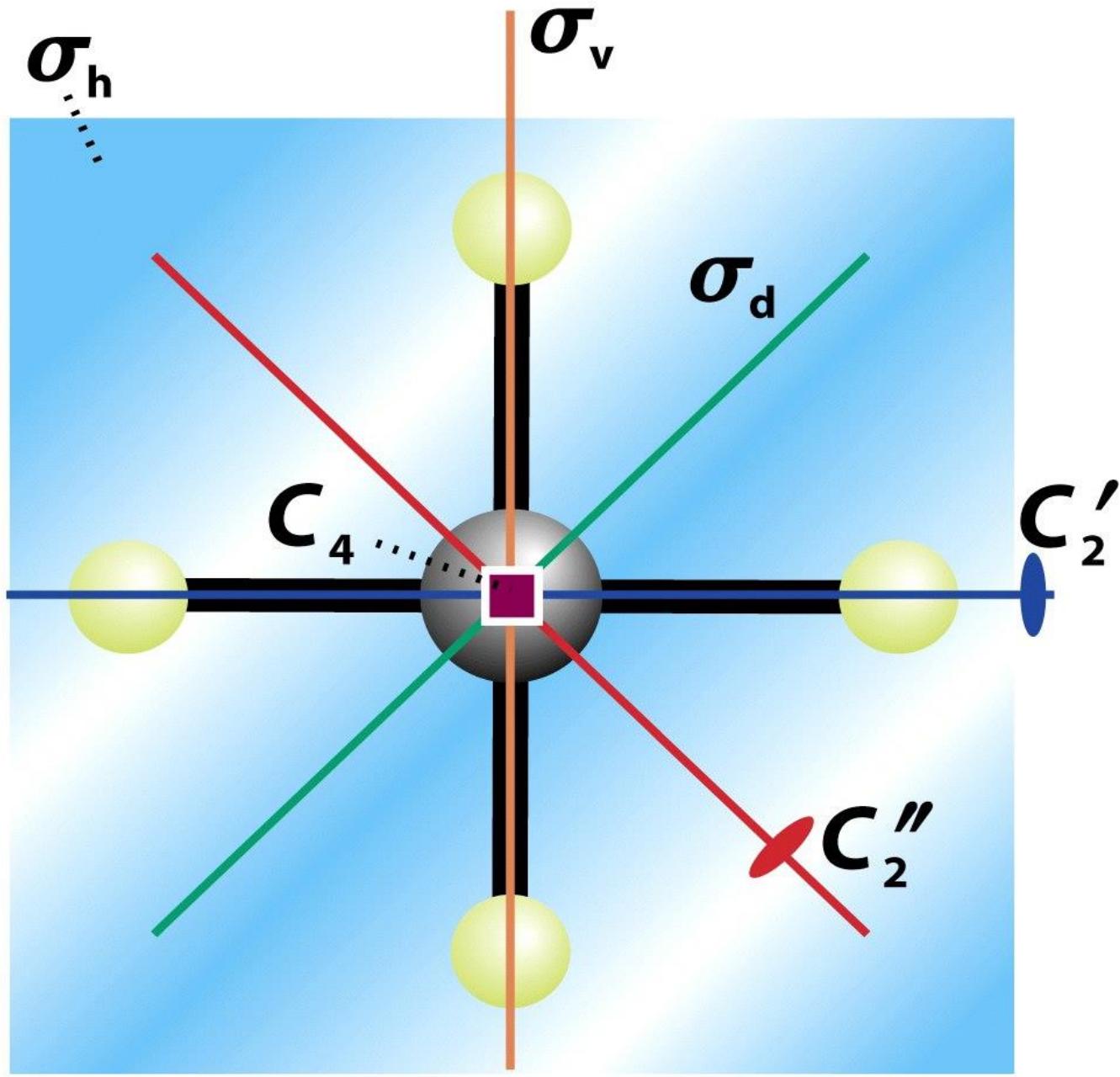


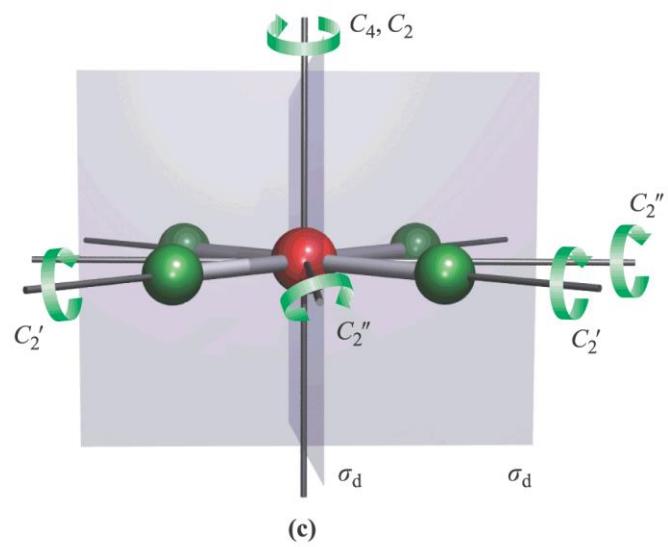
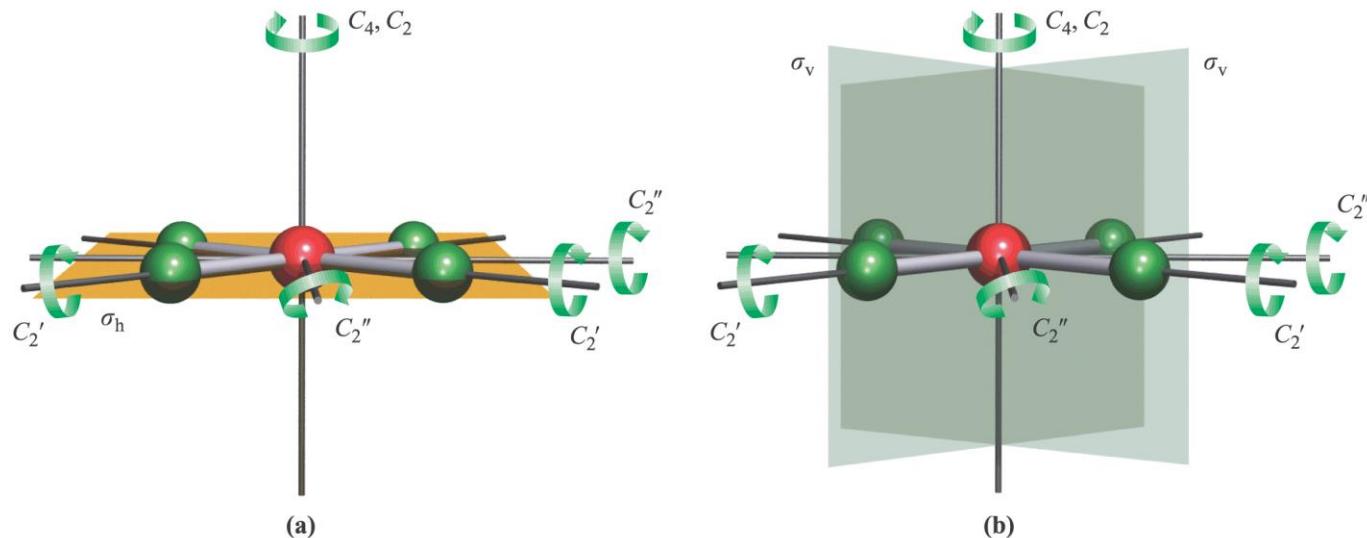
Asse principale



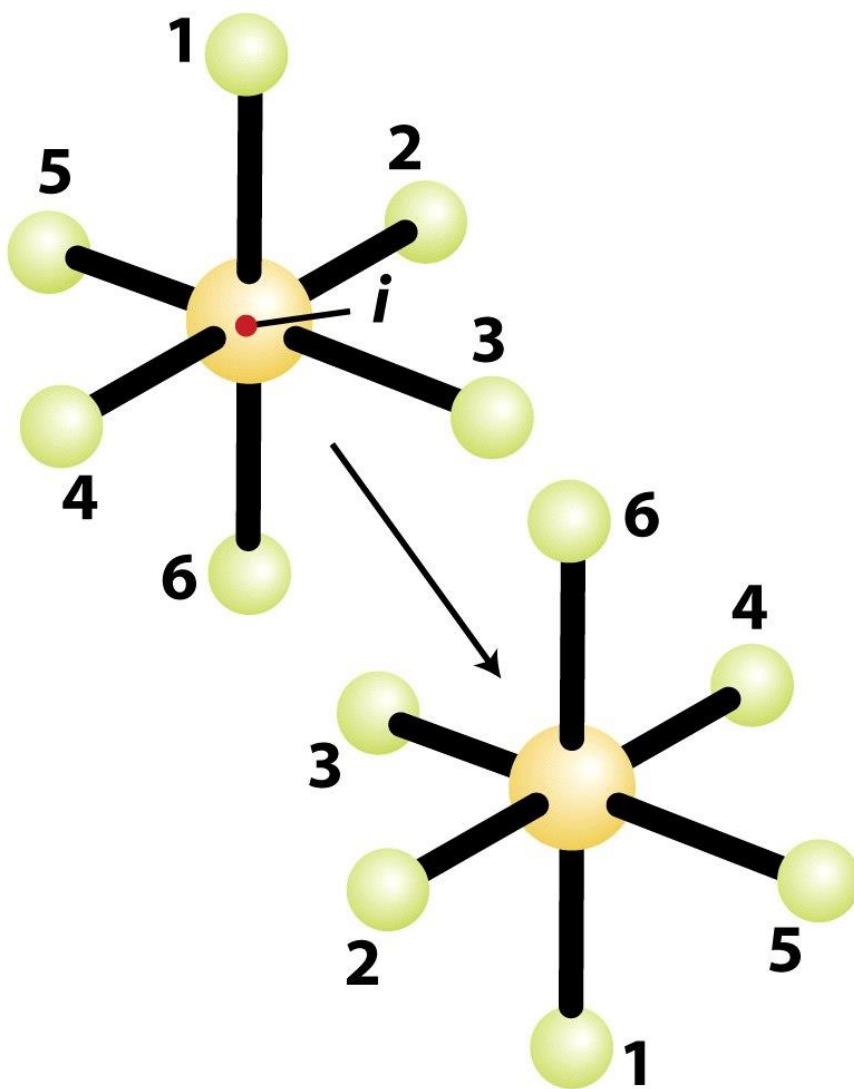
Piani di simmetria: σ_v , σ_h , σ_d





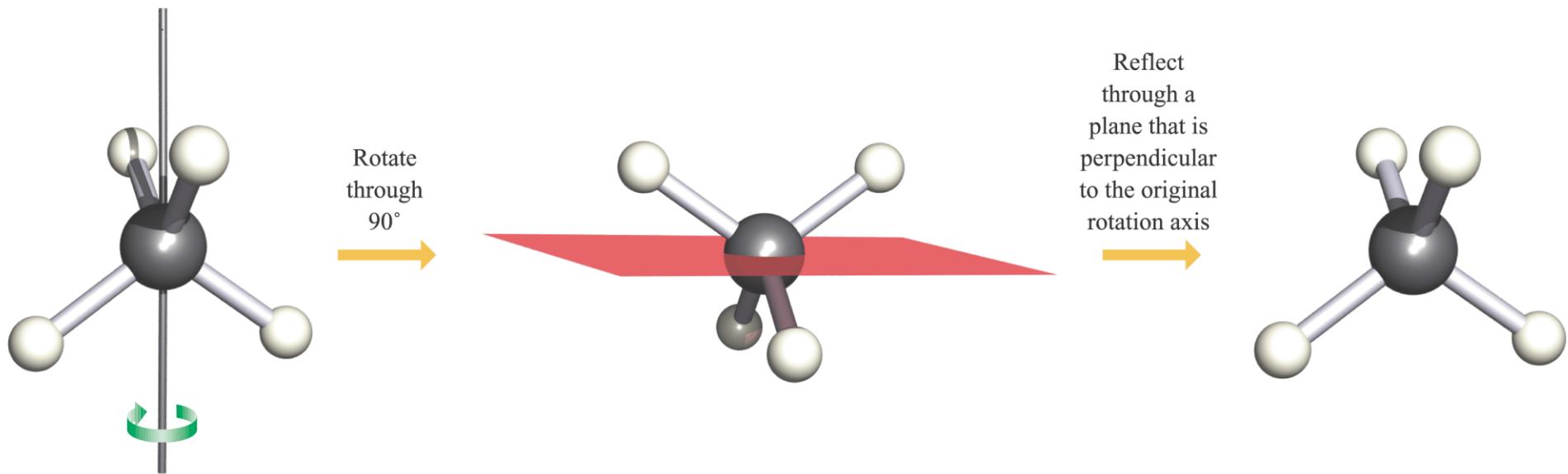


Centro di simmetria (centro di inversione), i



Rotazione impropria o roto-riflessione Assi S_n

Axis bisects the
H-C-H bond
angle



$$S_1 = \sigma \text{ e } S_2 = i$$

Esempi

cis-CH₂Cl₂ (σ_v , C₂)

trans-CH₂Cl₂ (σ_h , C₂)

Etano:

conformazione eclissata (C₃, 3C₂, σ_h , 3 σ_v , S₃)

conformazione sfalsata (C₃, 3C₂, 3 σ_d , i, S₆)

BCl₃ vs PCl₃ (C₃ + 3C₂ + 3 σ_v + σ_h vs C₃ + 3 σ_v)

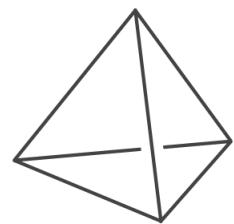
Gruppi puntuali

L'insieme degli elementi di simmetria di una molecola forma un gruppo di simmetria o **gruppo puntuale**. Ogni gruppo puntuale è identificato con un simbolo, detto **Simbolo di Schoenflies**.

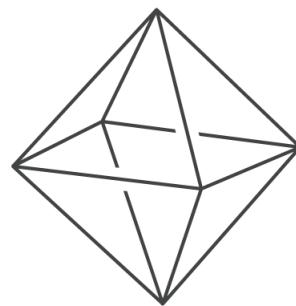
Gruppi puntuali

Simboli di Schoenflies

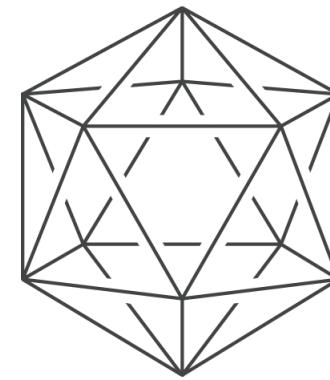
Point group	Characteristic symmetry elements	Comments
C_s	E , one σ plane	
C_i	E , inversion centre	
C_n	E , one (principal) n -fold axis	
C_{nv}	E , one (principal) n -fold axis, $n \sigma_v$ planes	
C_{nh}	E , one (principal) n -fold axis, one σ_h plane, one S_n -fold axis which is coincident with the C_n axis	The S_n axis necessarily follows from the C_n axis and σ_h plane For $n = 2, 4$ or 6 , there is also an inversion centre
D_{nh}	E , one (principal) n -fold axis, $n C_2$ axes, one σ_h plane, $n \sigma_v$ planes, one S_n -fold axis	The S_n axis necessarily follows from the C_n axis and σ_h plane For $n = 2, 4$ or 6 , there is also an inversion centre
D_{nd}	E , one (principal) n -fold axis, $n C_2$ axes, $n \sigma_v$ planes, one S_{2n} -fold axis	For $n = 3$ or 5 , there is also an inversion centre
T_d		Tetrahedral
O_h		Octahedral
I_h		Icosahedral



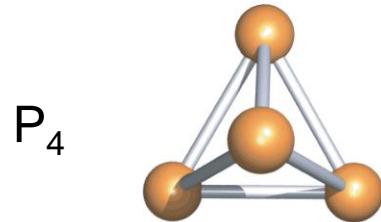
Tetrahedron



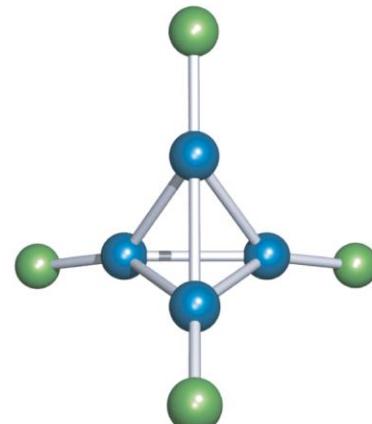
Octahedron



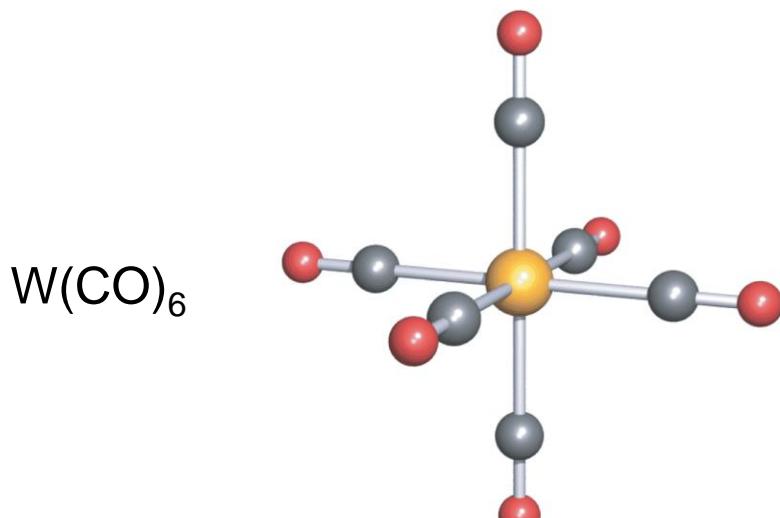
Icosahedron



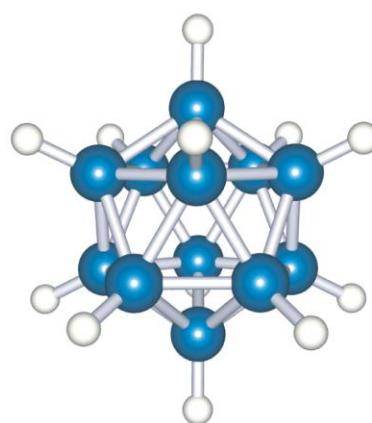
(a)



(b)



(c)

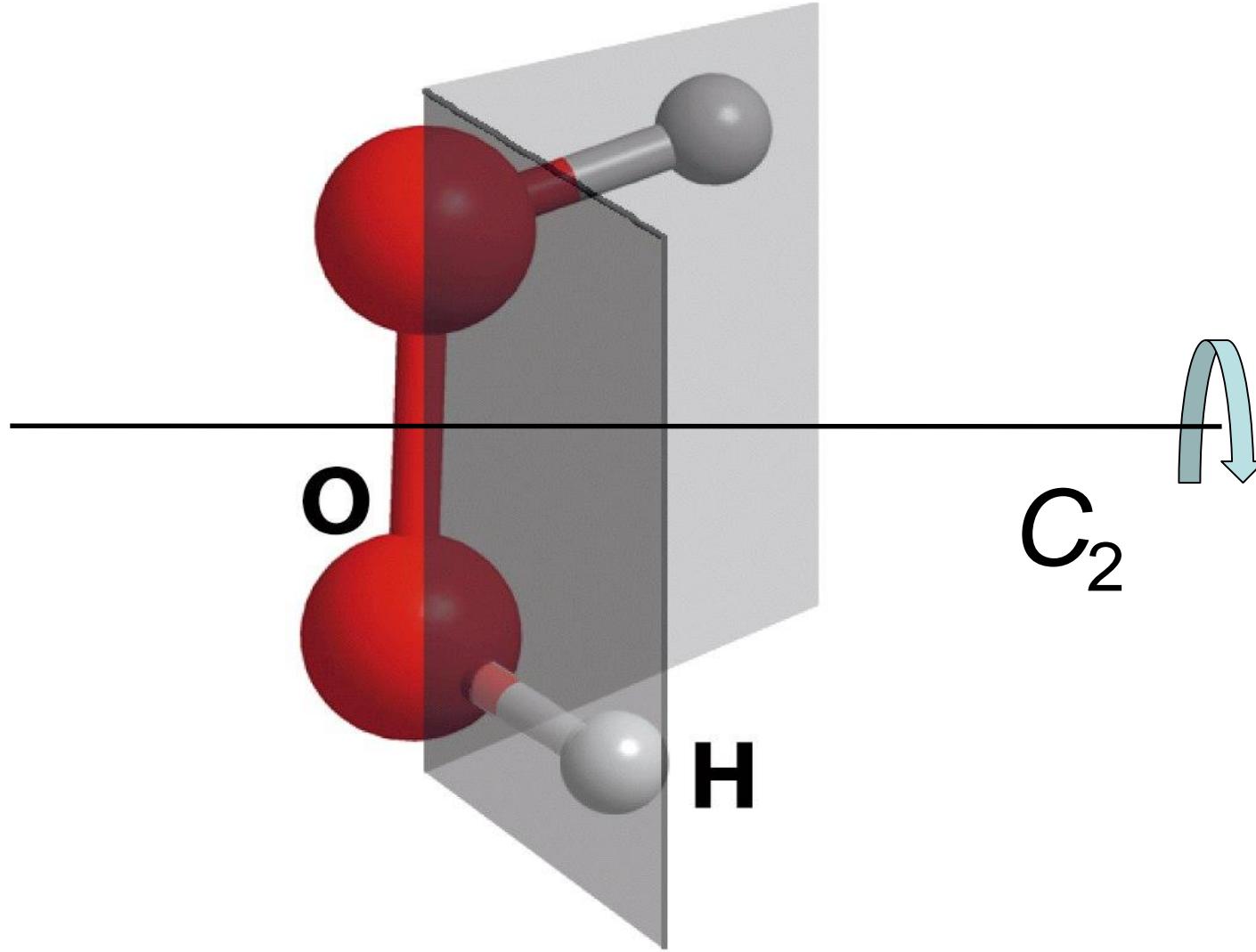


(d)

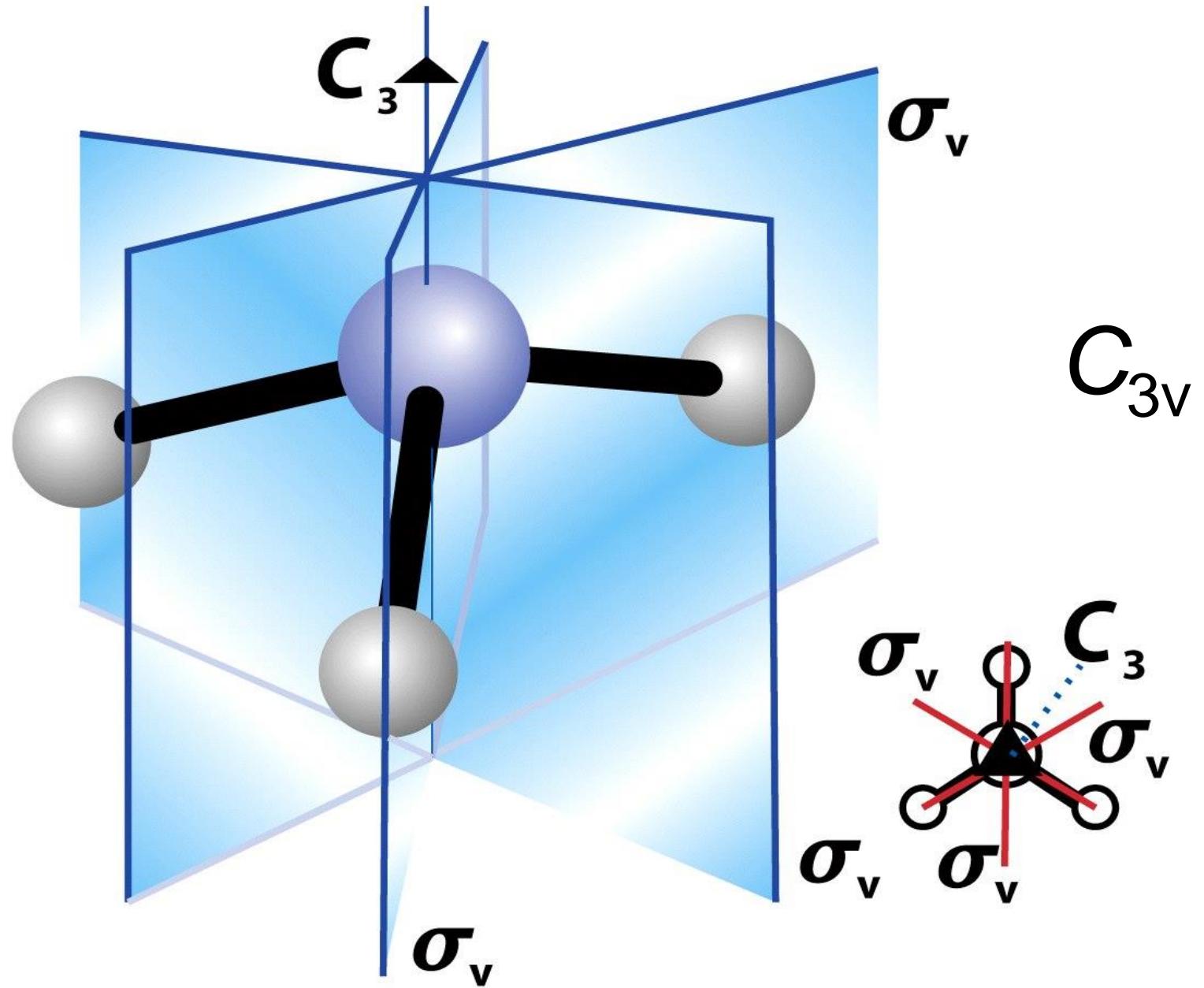


Point group	Characteristic symmetry elements	Comments
C_s	E , one σ plane	
C_i	E , inversion centre	
C_n	E , one (principal) n -fold axis	
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T_d		Tetrahedral
O_h		Octahedral
I_h		Icosahedral

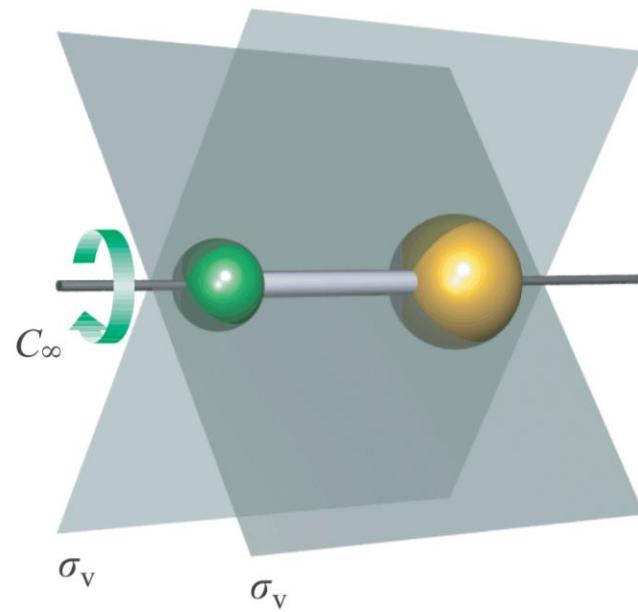
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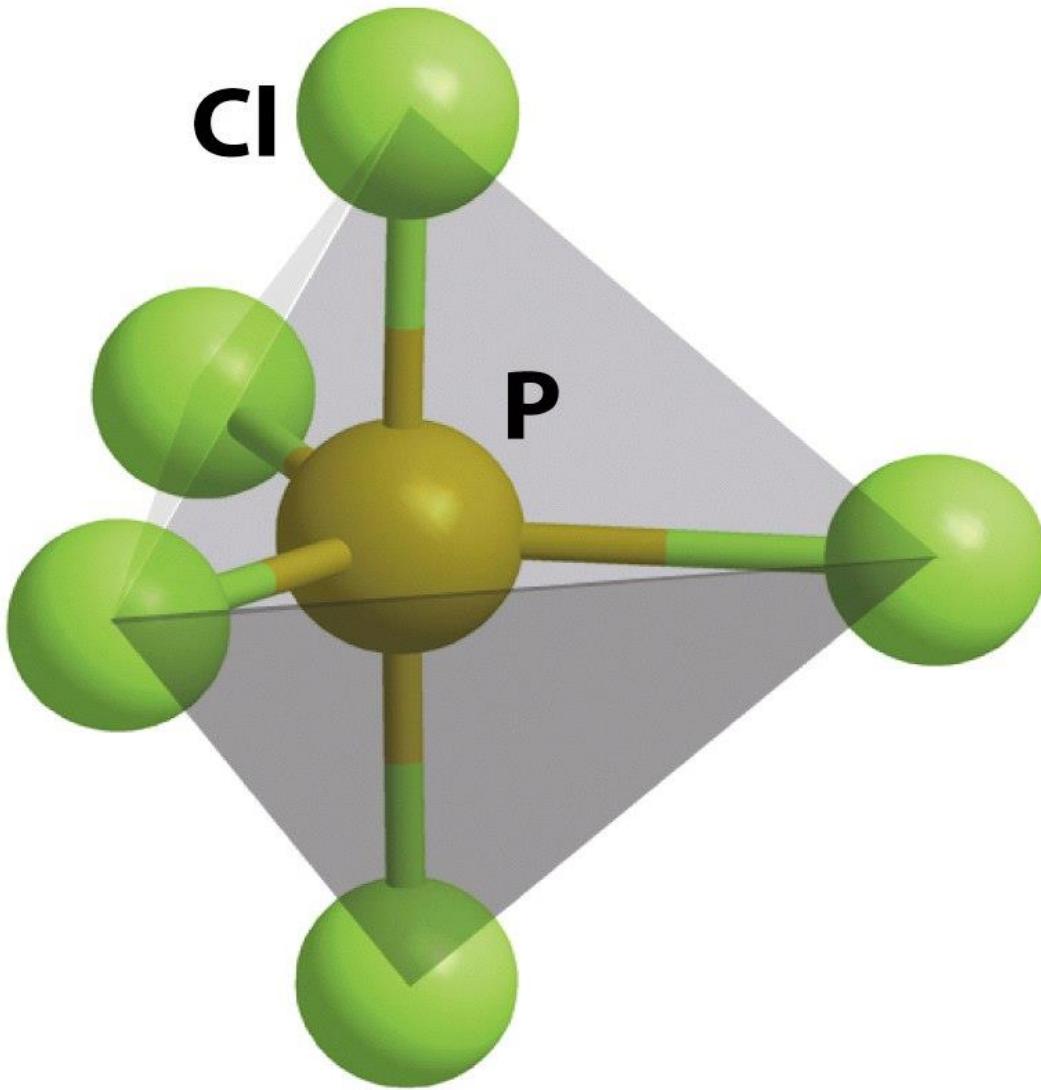
Point group	Characteristic symmetry elements	Comments
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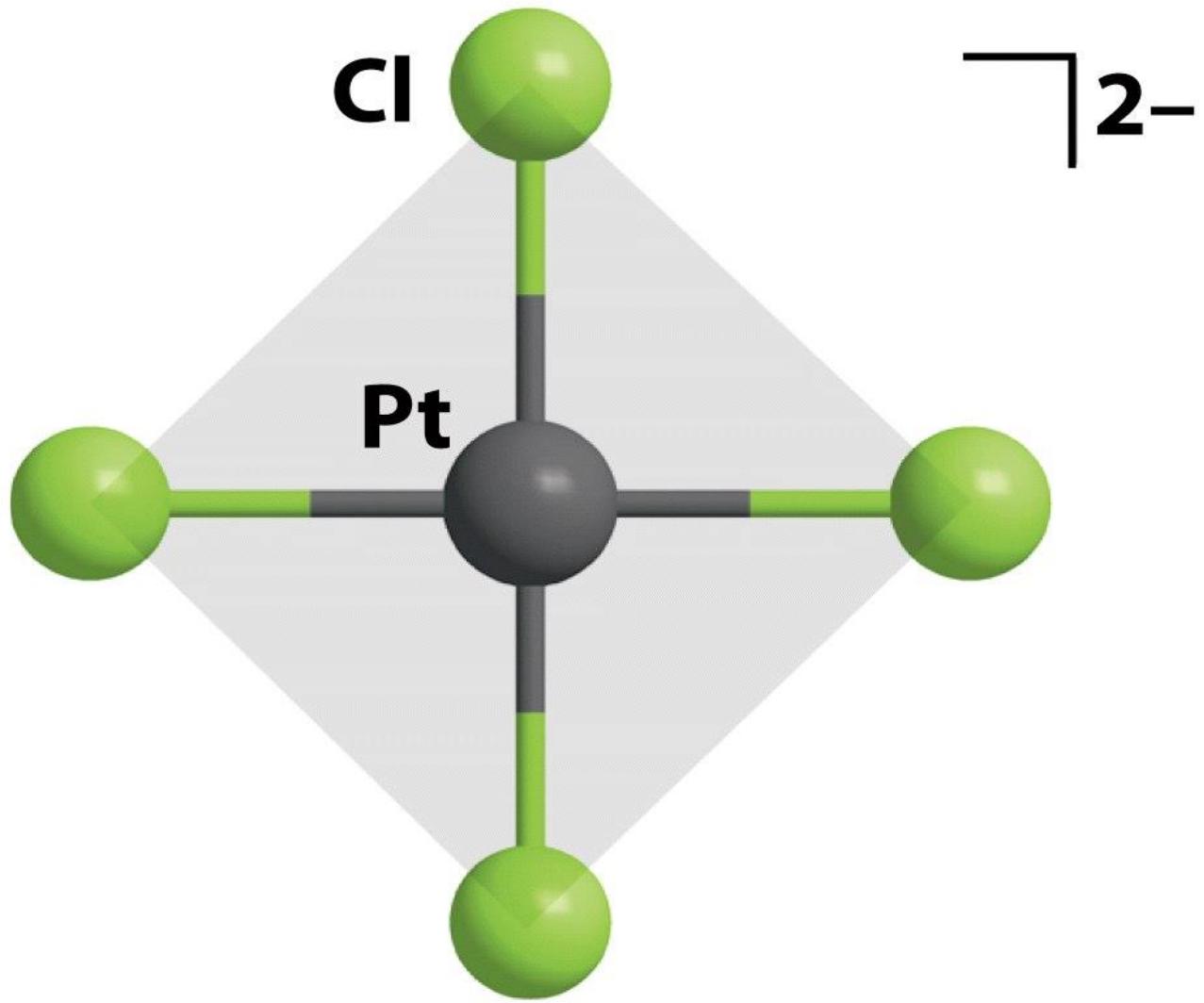
$C_{\infty V}$



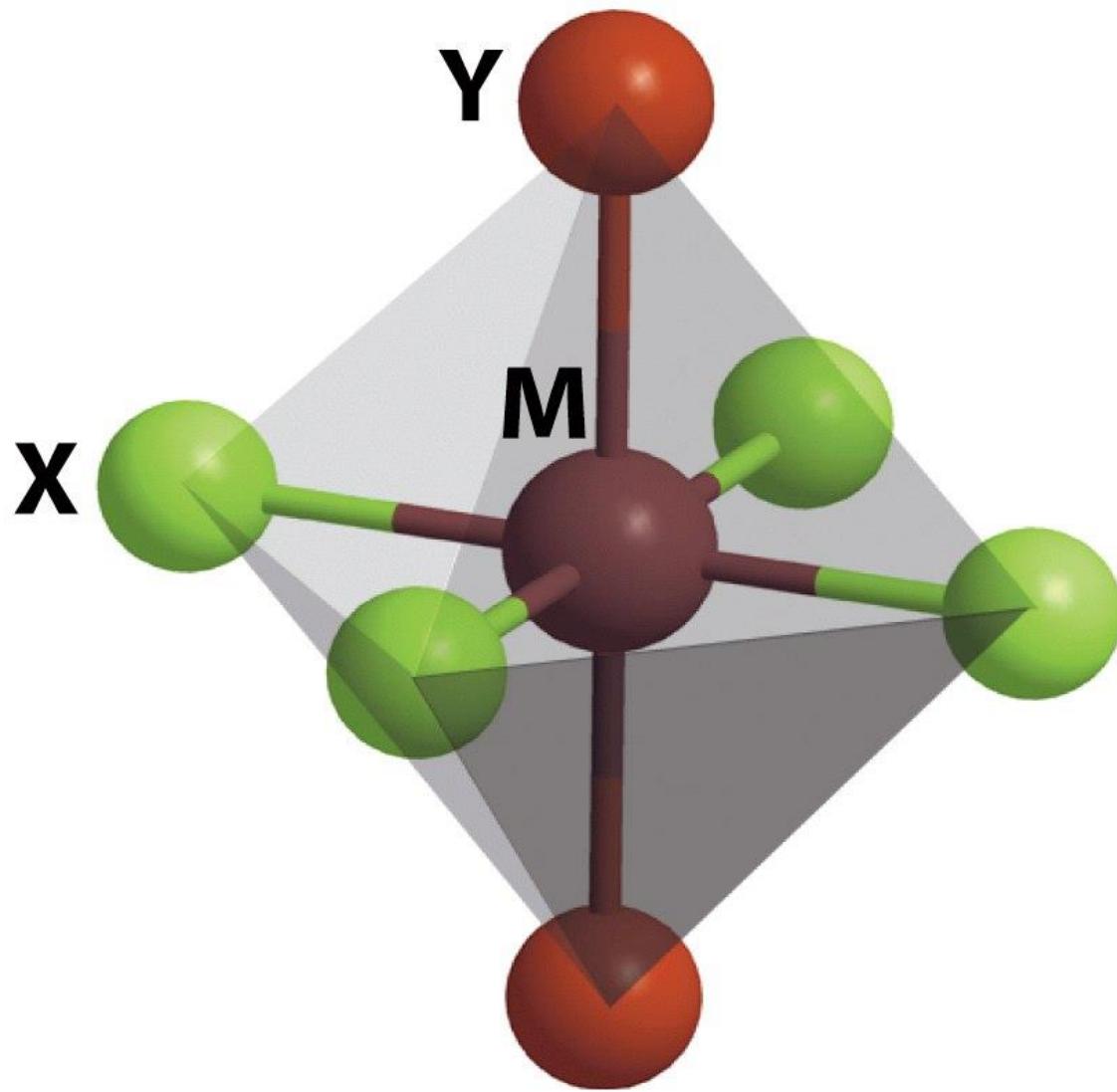
Point group	Characteristic symmetry elements	Comments
C_s	E , one σ plane	
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O_h		Octahedral
I_h		Icosahedral



PCl_5, D_{3h}

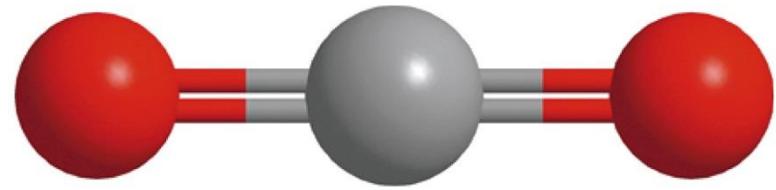


$[\text{PtCl}_4]^{2-}, D_{4h}$

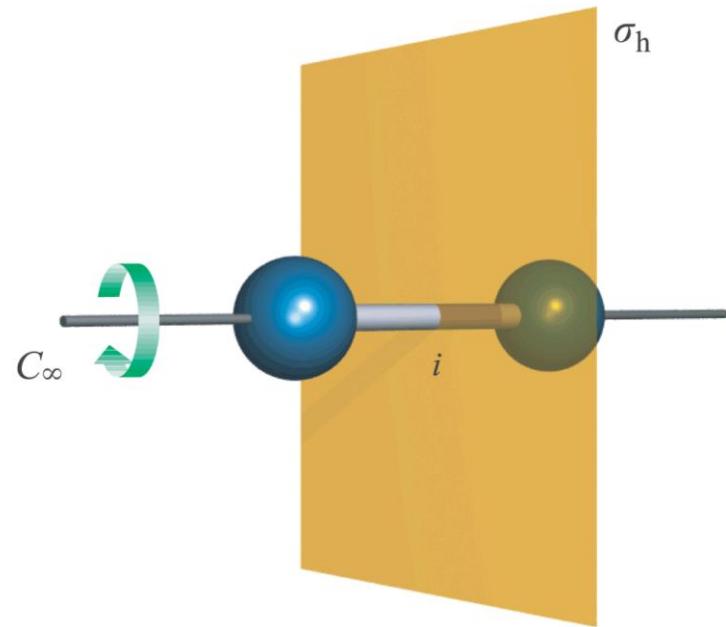


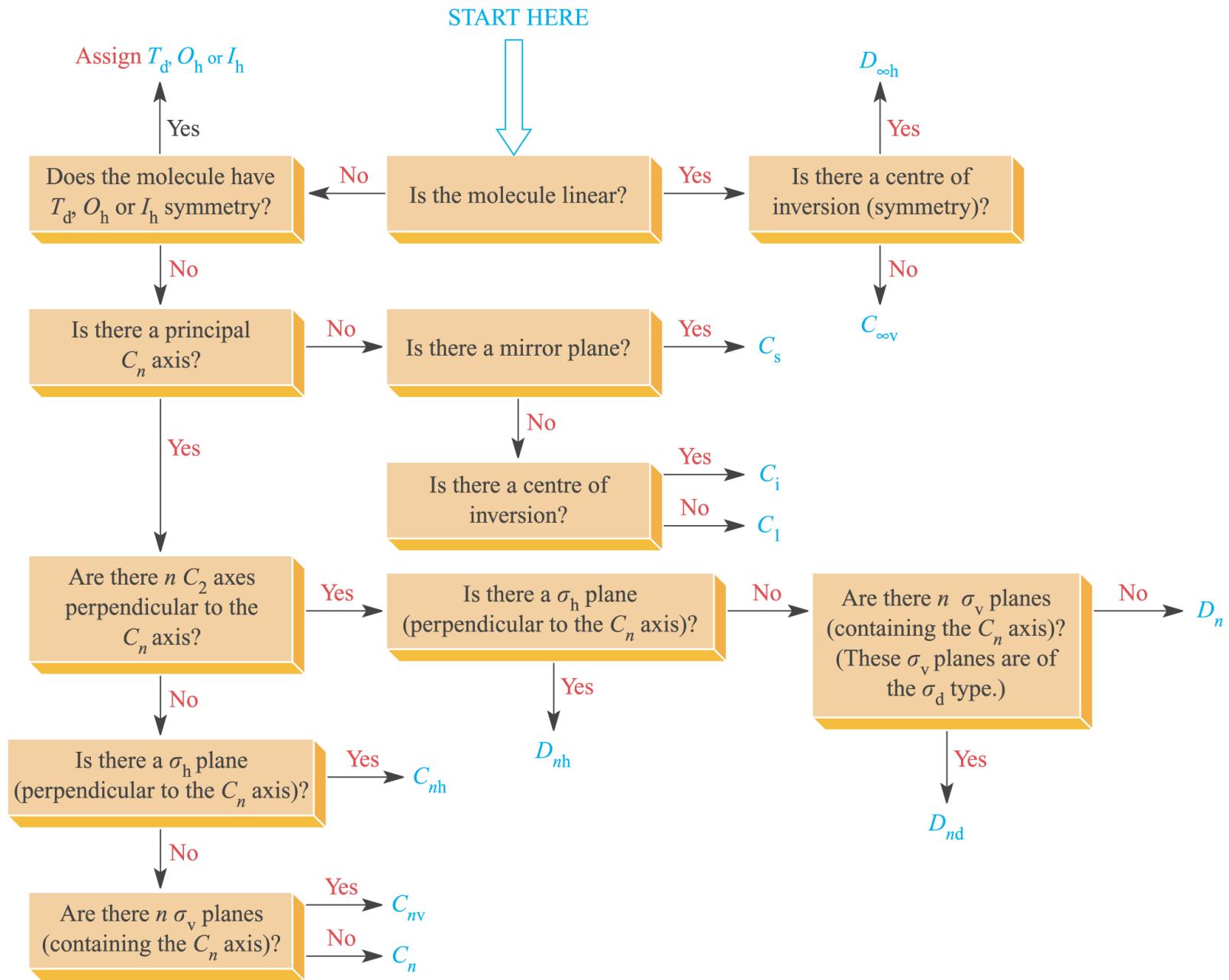
Geometria ottaedrica, simmetria inferiore

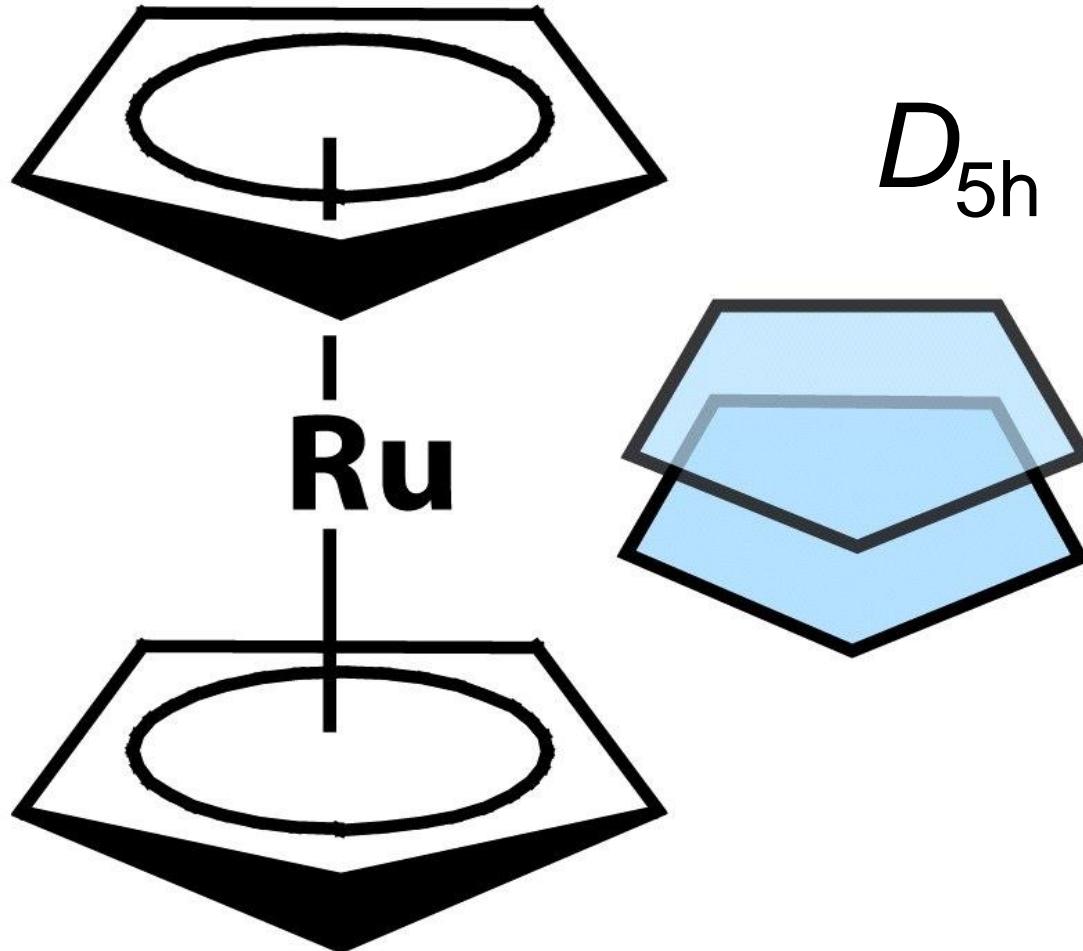
$$D_{\infty h}$$



CO₂







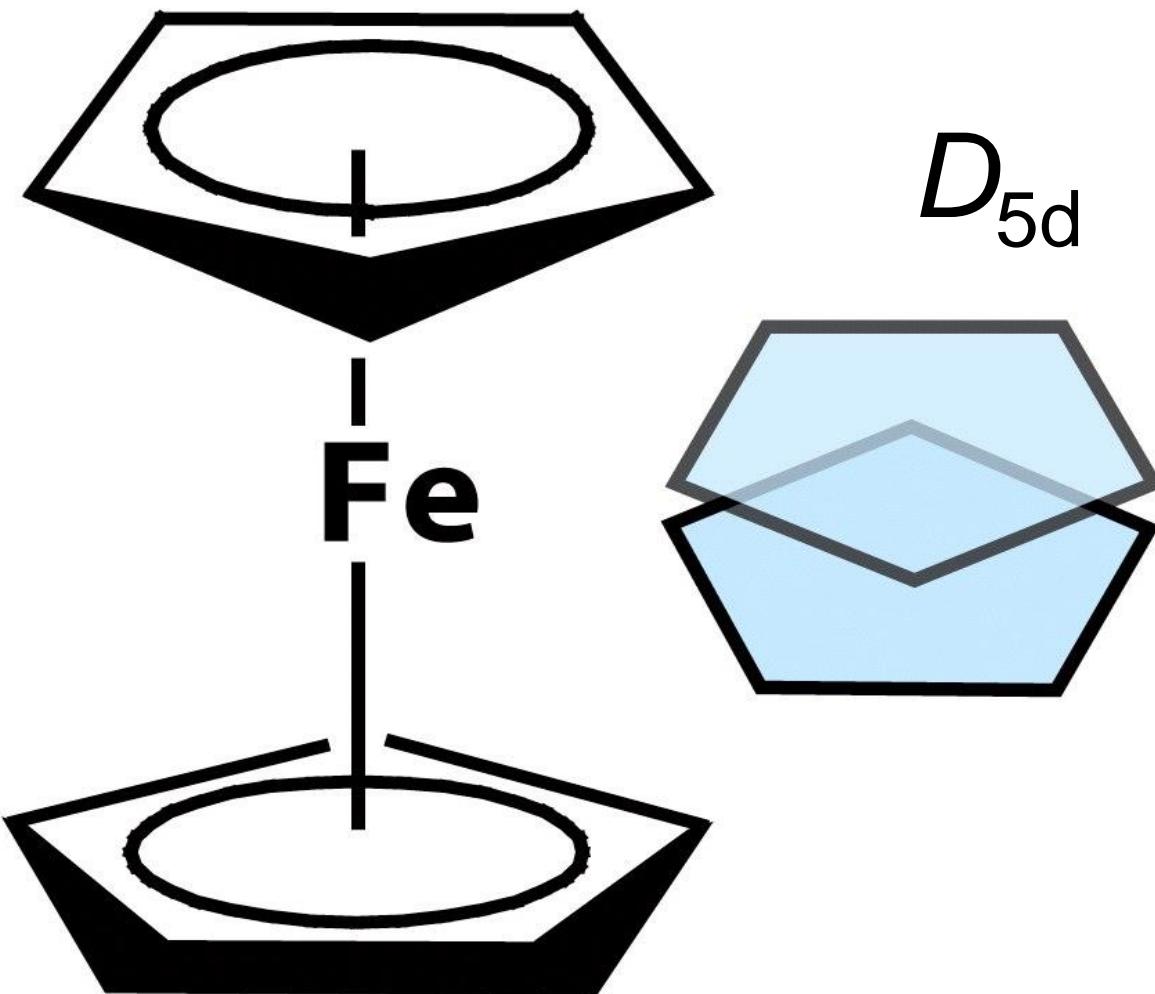


Tabella dei caratteri per il gruppo puntuale C_{2v}

SIMBOLO DI SCHOENFLIES

OPERAZIONI DI SIMMETRIA

C_{2v}	E	C_2	$\sigma_v(xz)$	$\sigma_v'(yz)$		
A_1	1	1	1	1	z	x^2, y^2, z^2
A_2	1	1	-1	-1	R_z	xy
B_1	1	-1	1	-1	x, R_y	xz
B_2	1	-1	-1	1	y, R_x	yz

SIMBOLI DI MULLIKEN
(Dimensione)

FUNZIONI DI BASE

PRODOTTI BINARI DI
FUNZIONI

RAPPRESENTAZIONI IRRIDUCIBILI

Tabella dei caratteri per il gruppo puntuale C_{3v}

Gruppi puntuali che possiedono assi di rotazione di ordine 3 o superiore possono avere rappresentazioni irriducibili di dimensione 2 (indicata con E) o 3 (T)

C_{3v}	E	$2C_3$	$3\sigma_v$	
A_1	1	1	1	z
A_2	1	1	-1	R_z
E	2	-1	0	$(x, y) (R_x, R_y)$

DIMENSIONE 2

COPPIE DI FUNZIONI DI BASE

Tabella dei caratteri per il gruppo puntuale D_{4h}

	E	$2C_4(z)$	C_2	$2C'_2$	$2C''_2$	i	$2S_4$	σ_h	$2\sigma_v$	$2\sigma_d$	linears, rotations	quadratic
A_{1g}	1	1	1	1	1	1	1	1	1	1		x^2+y^2, z^2
A_{2g}	1	1	1	-1	-1	1	1	1	-1	-1	R_z	
B_{1g}	1	-1	1	1	-1	1	-1	1	1	-1		x^2-y^2
B_{2g}	1	-1	1	-1	1	1	-1	1	-1	1		xy
E_g	2	0	-2	0	0	2	0	-2	0	0	(R_x, R_y)	(xz, yz)
A_{1u}	1	1	1	1	1	-1	-1	-1	-1	-1		
A_{2u}	1	1	1	-1	-1	-1	-1	-1	1	1	z	
B_{1u}	1	-1	1	1	-1	-1	1	-1	-1	1		
B_{2u}	1	-1	1	-1	1	-1	1	-1	1	-1		
E_u	2	0	-2	0	0	-2	0	2	0	0	(x, y)	

