

# Image Processing for Physicists

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Linear image systems



# Overview

- Definition of resolution
- Imaging systems:
  - Linear transfer model
  - Noise

# Resolution

“the smallest detail that can be distinguished”

- No unique definition
  - Numerical aperture
  - Pixel size
  - Other criteria (PSF, MTF)
- What is “detail”?
- What is “distinguish”?

# Resolution

1280 x 1280



640 x 640

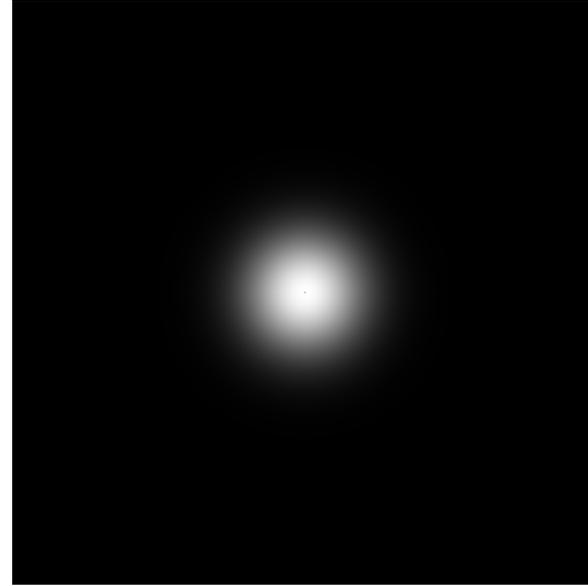
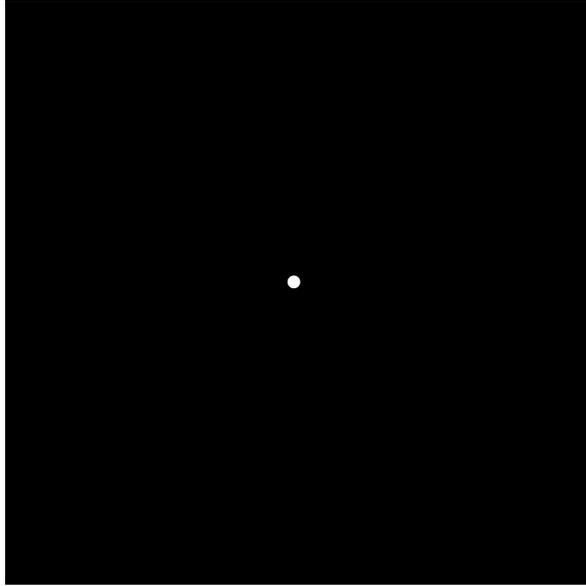


- **not** simply given by pixel size (i.e. sampling rate)
- light quality, optics quality, detector quality, algorithm quality, noise, ...

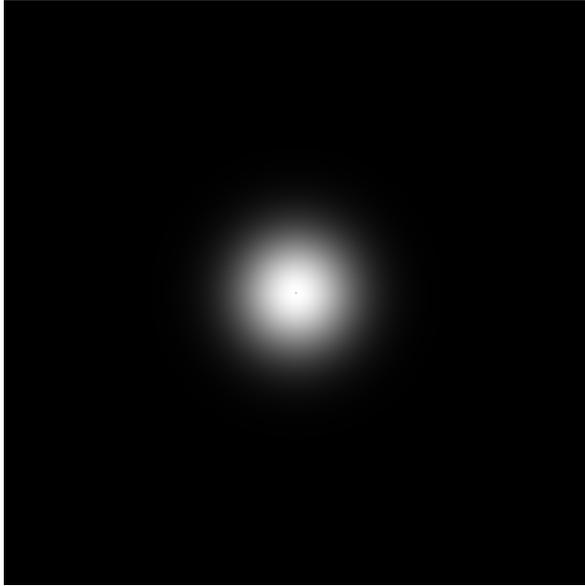
# Linear translation-invariant systems

- Point spread function (“impulse response”)
- LTI system: convolution with PSF

# Point spread function



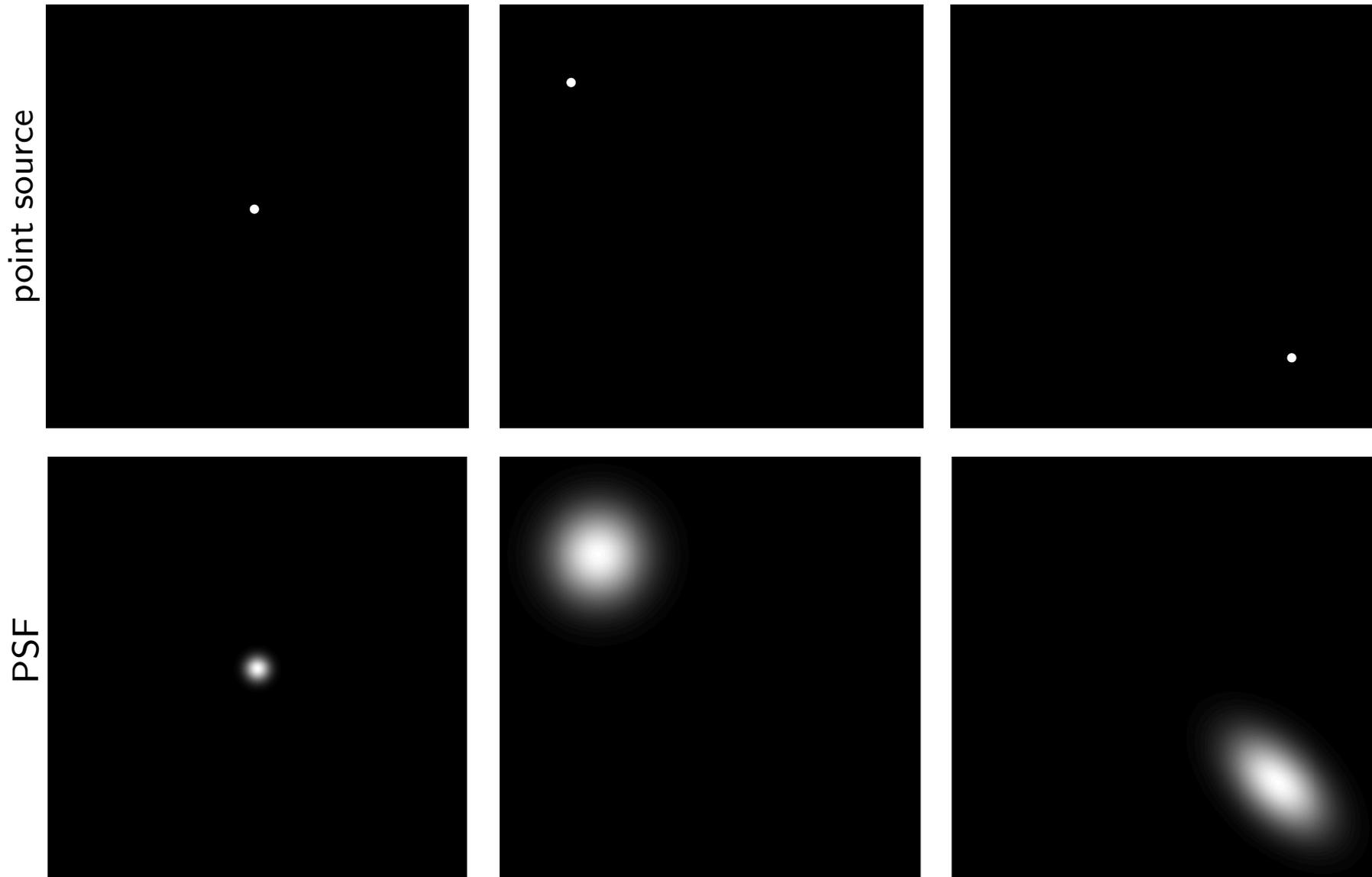
# PSF and resolution



# Measurement of the PSF

- Direct measurement from impulse
- Line-spread function

# PSF and translation invariance



- Not translation invariant  $\rightarrow$  PSF depends on position  $\rightarrow$  not a convolution
- Useful to model system imperfections, lens aberrations, ...

# The Fourier picture

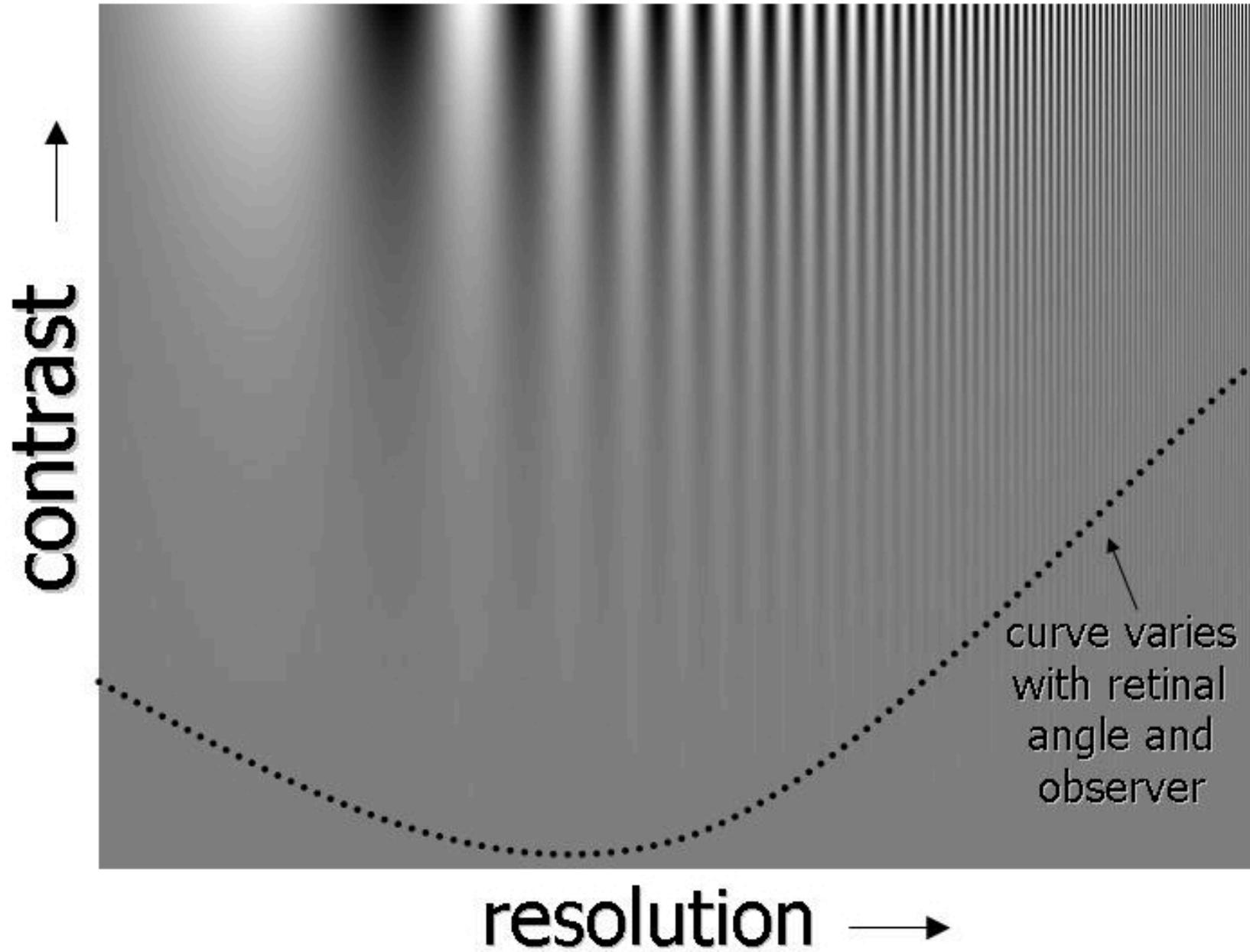
# Optical transfer function

Response of a system to an oscillating signal with well-defined frequency

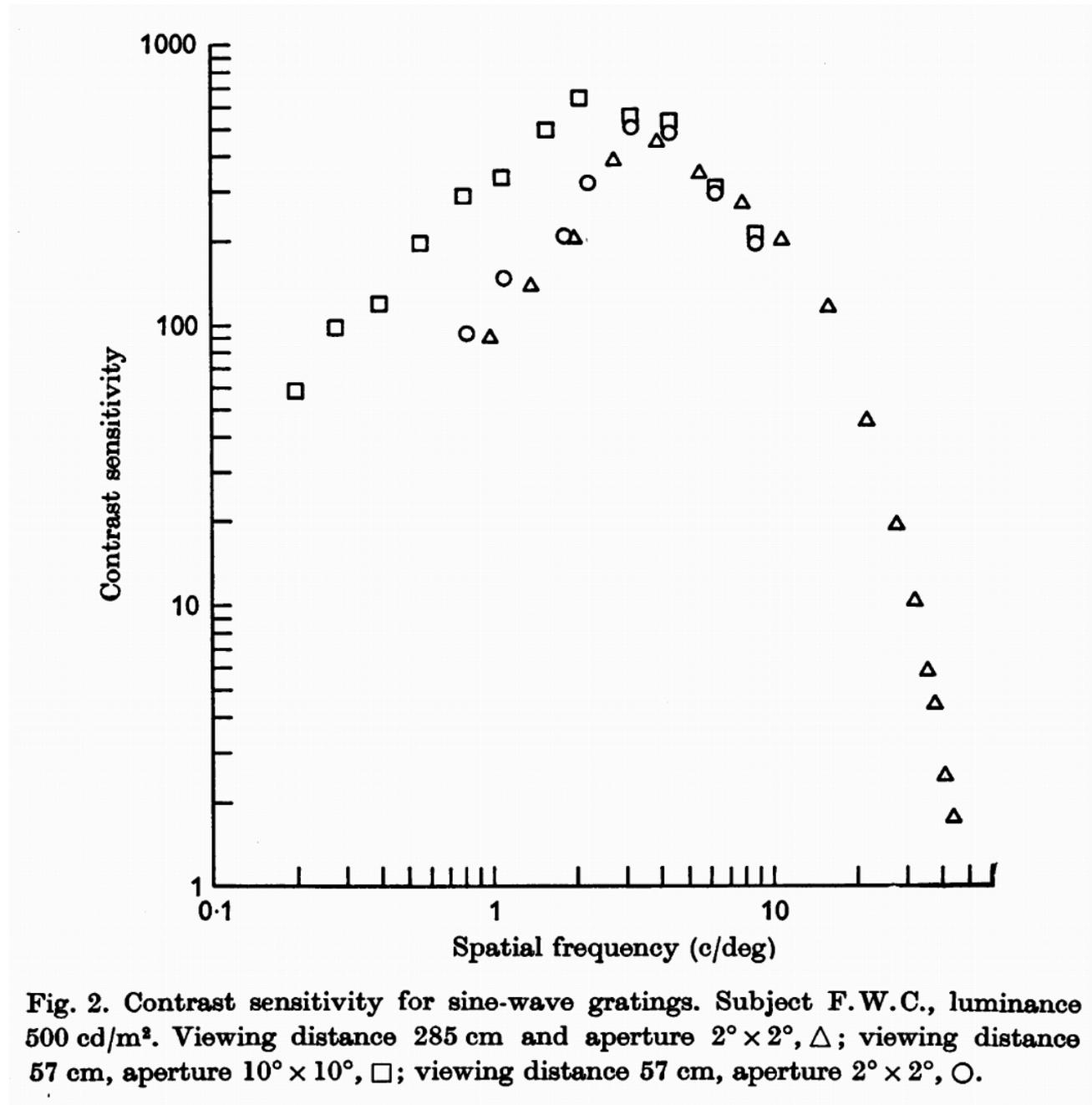
# Modulation transfer function

Amplitude change of an oscillating signal for a given frequency

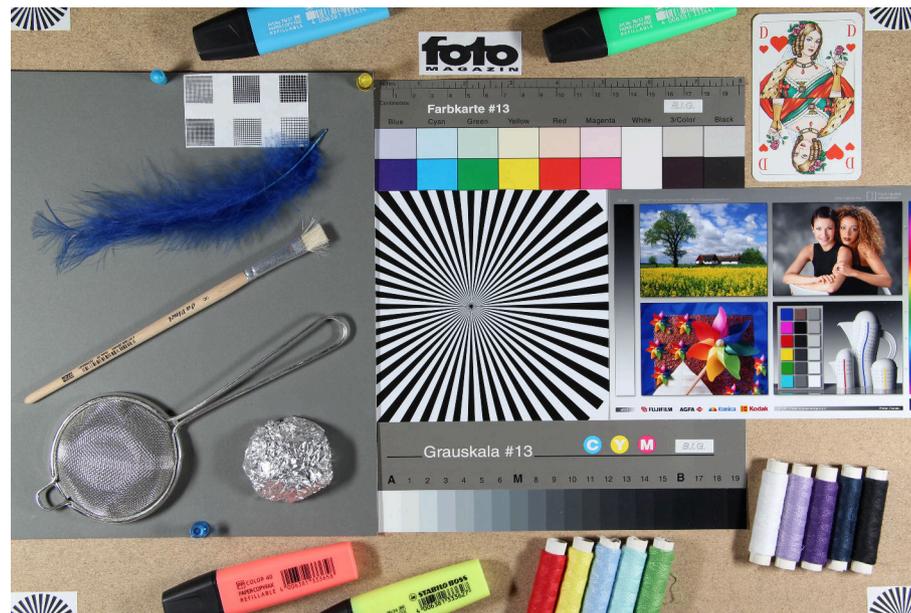
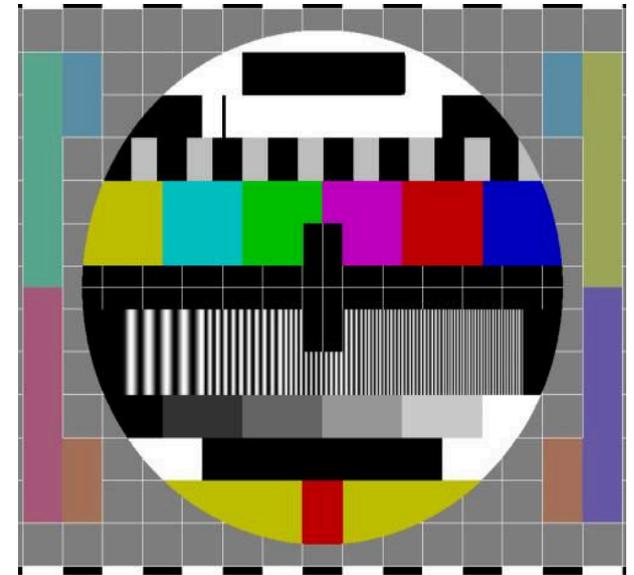
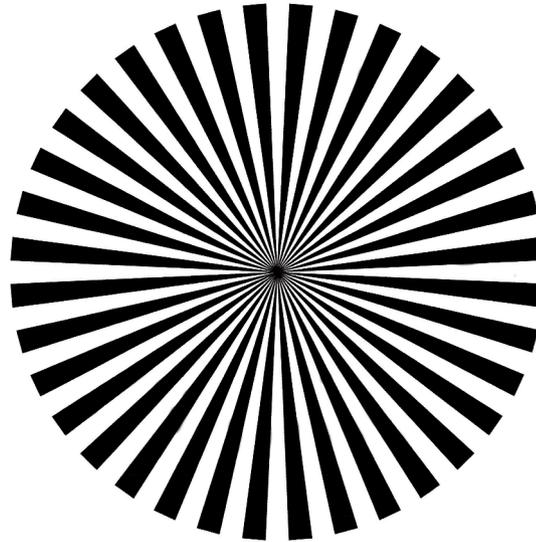
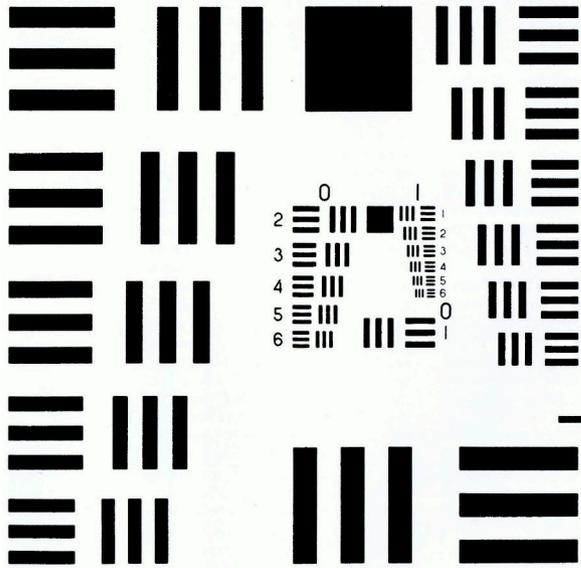
# Eye MTF



# Campbell-Robson curve



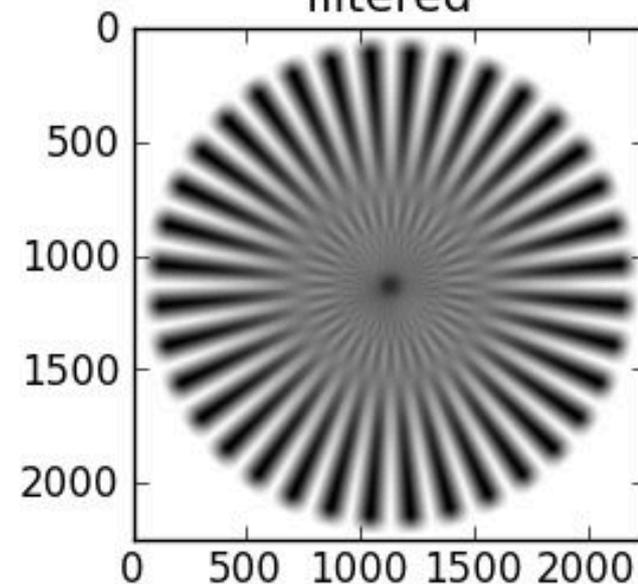
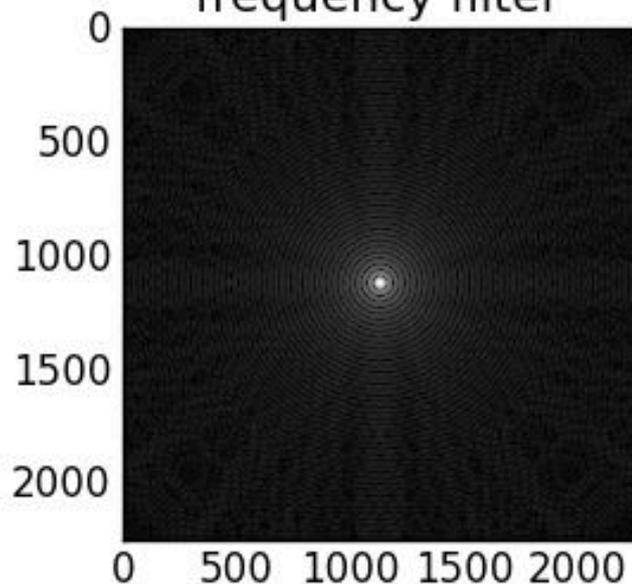
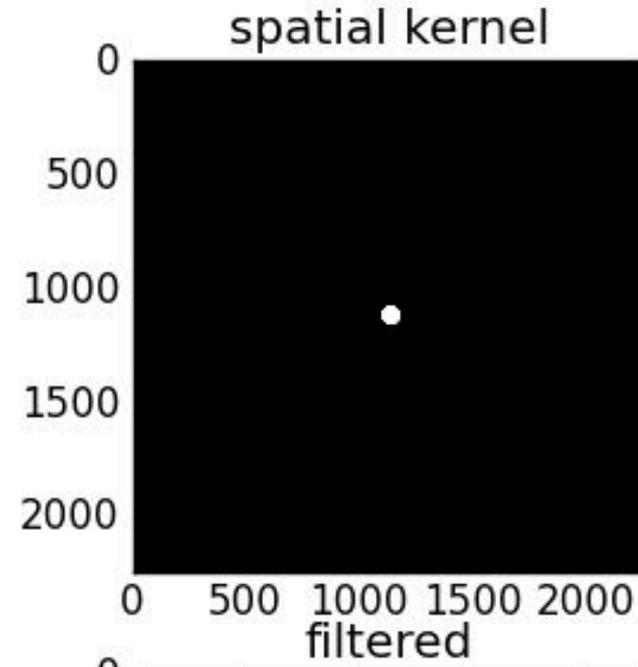
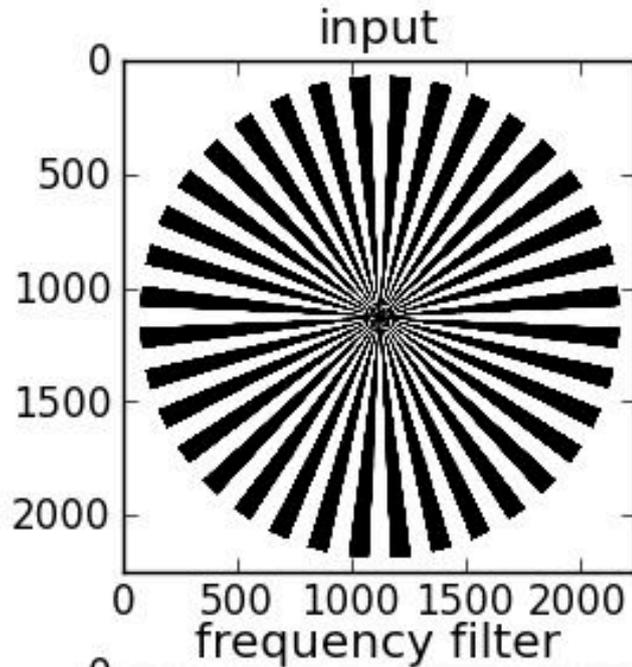
# Measurement of MTF



source: <http://fotomagazin.de>

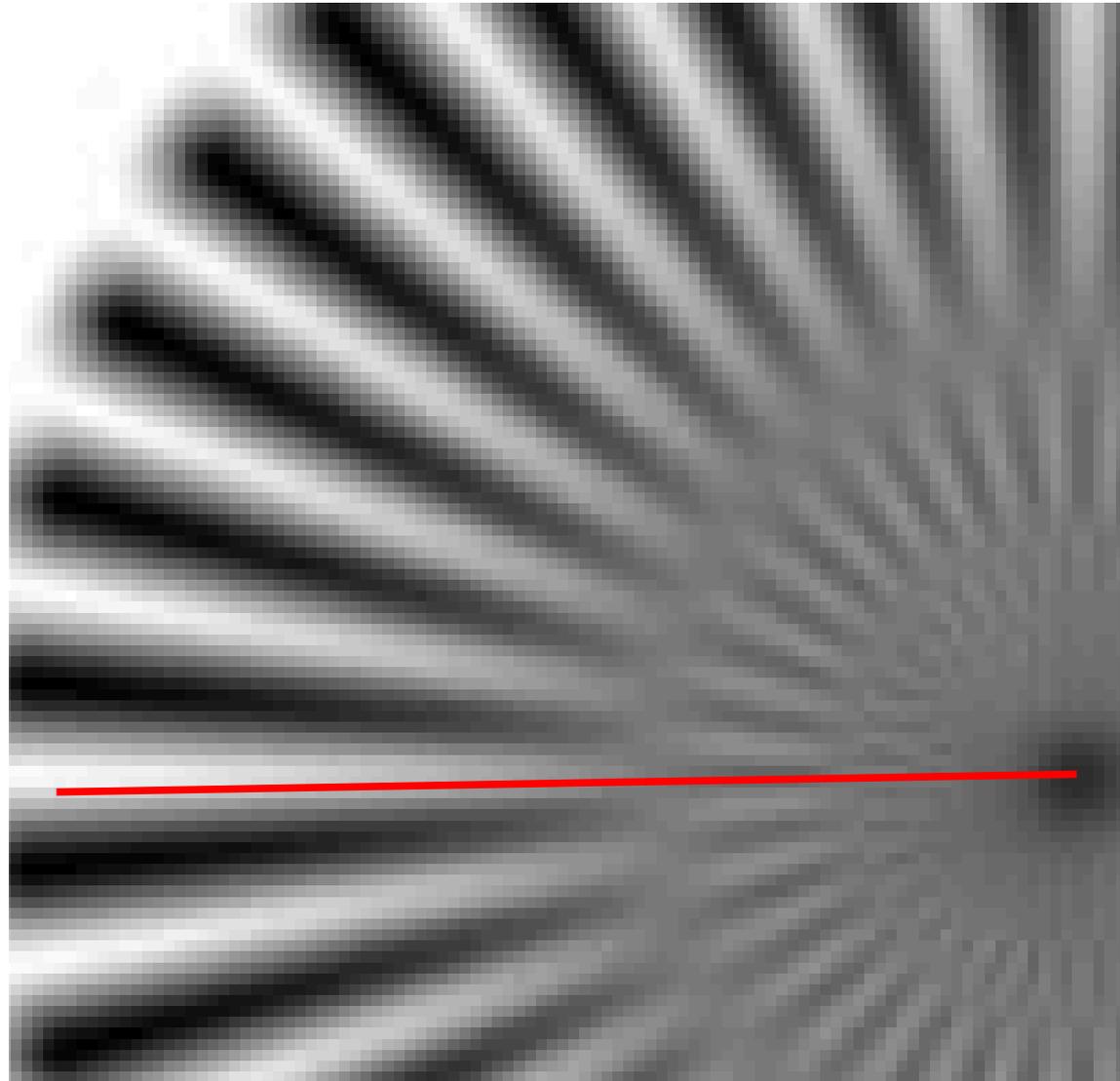
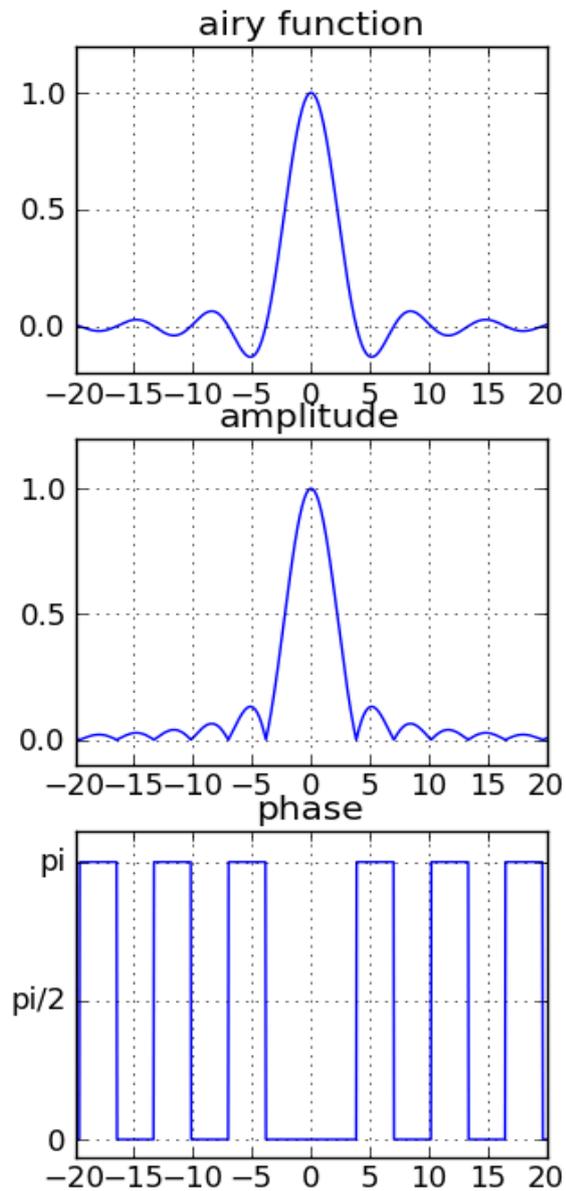
# Phase transfer function

describes how an oscillating signal changes in phase due to system



# Phase transfer function

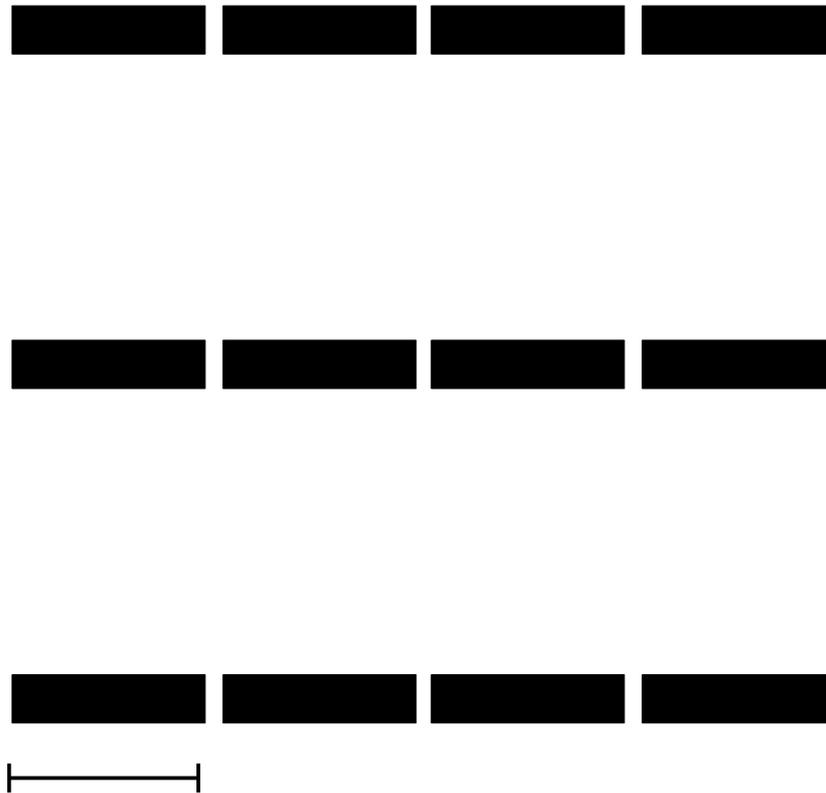
describes how an oscillating signal changes in phase due to system



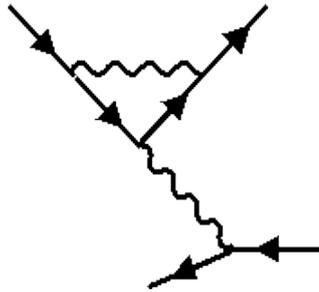
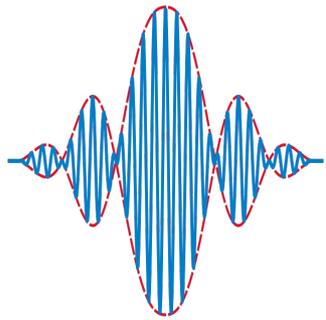
# MTF of an ideal pixel

# Pixel MTF

Modulation transfer function of a single detector pixel

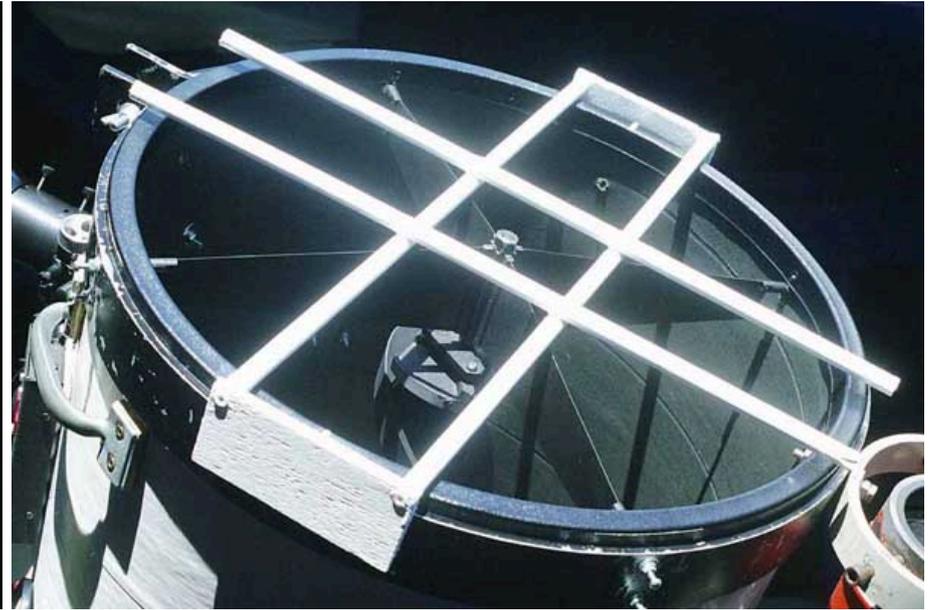


# Imaging as a linear filter



# PSF examples

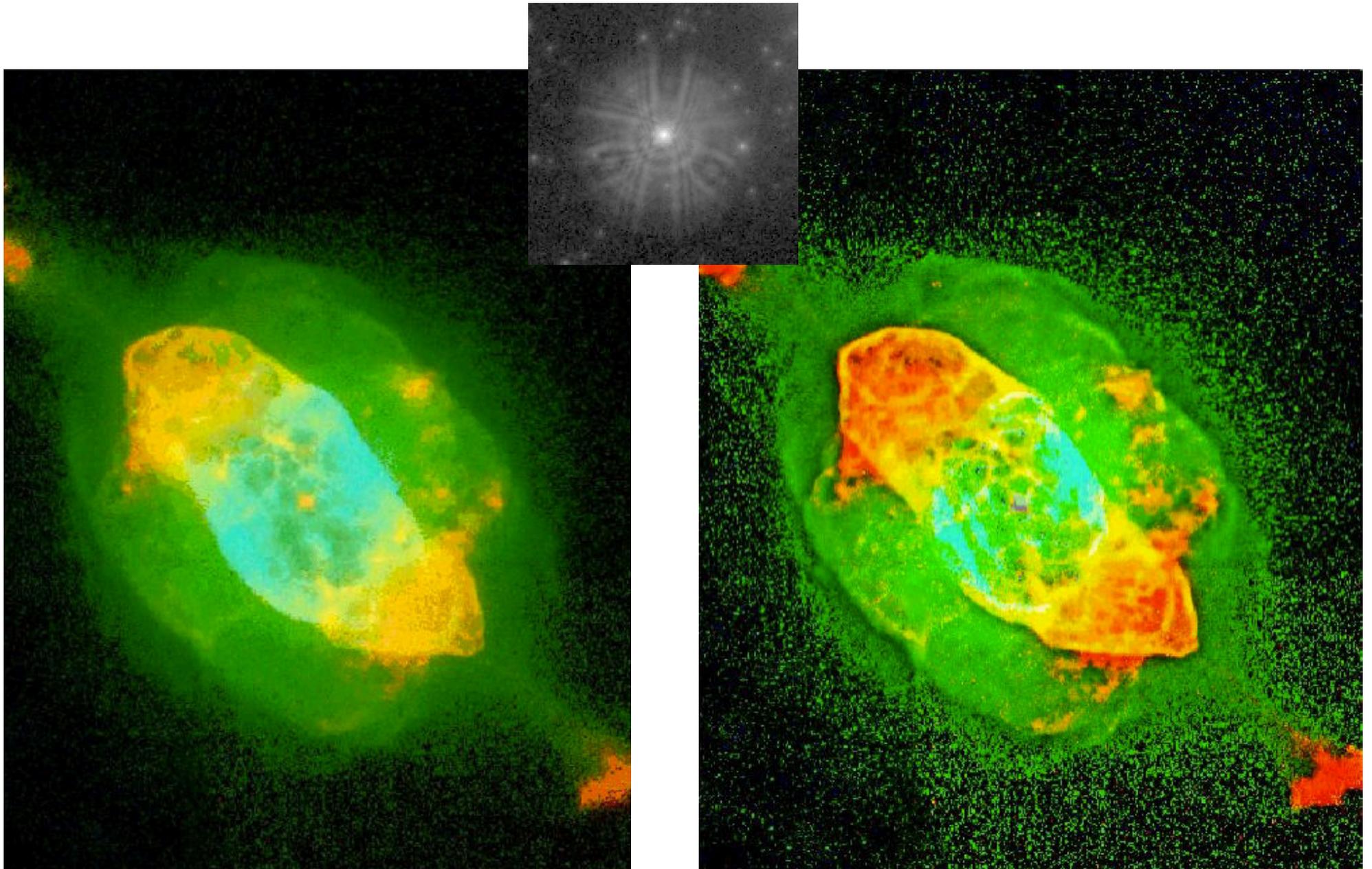
- isolated stars are essentially PSFs



source: [www.apod.nasa.gov](http://www.apod.nasa.gov)

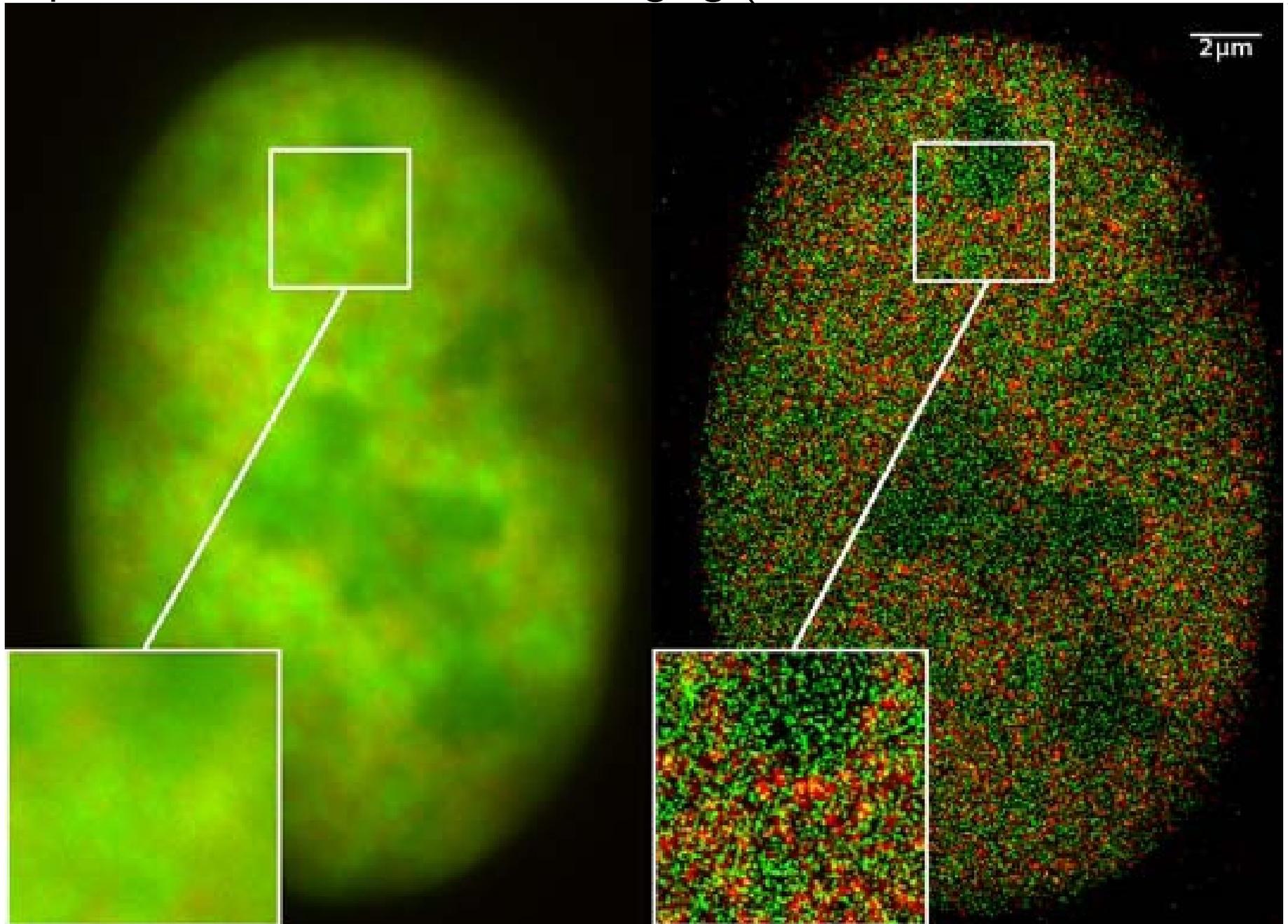
# PSF examples

Hubble flawed mirror deconvolution (correction for spherical aberration)



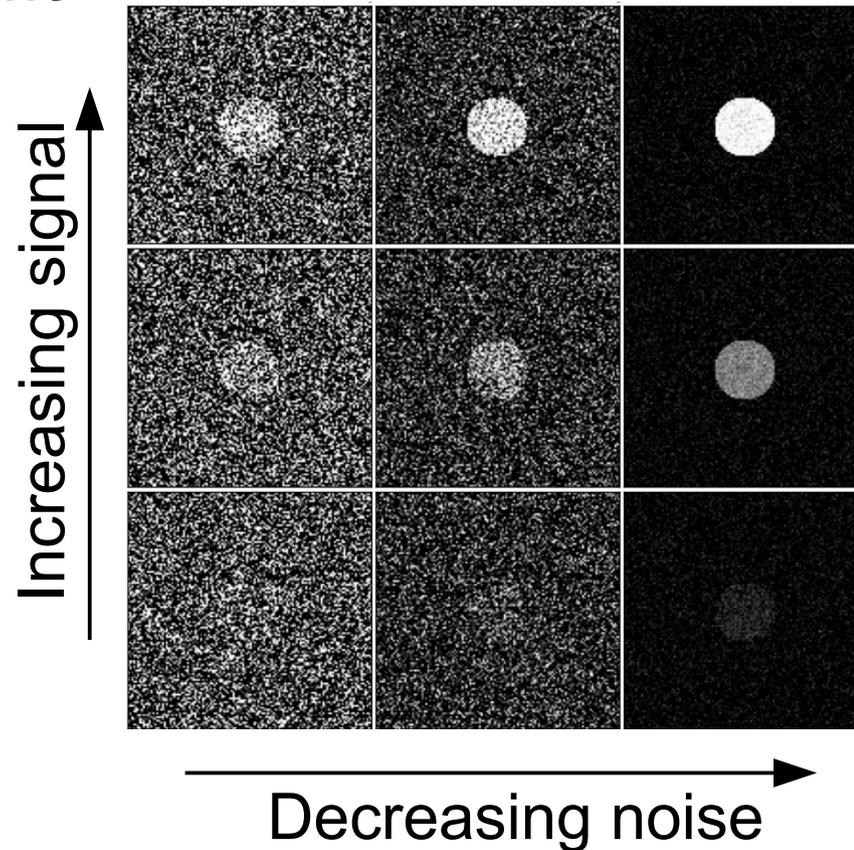
# PSF examples

Super-resolution fluorescence imaging (STORM, STED, PALM, ...)



# Contrast and noise

- Intensity operation:  
higher contrast,  
higher noise
- Contrast-to-noise  
remains constant



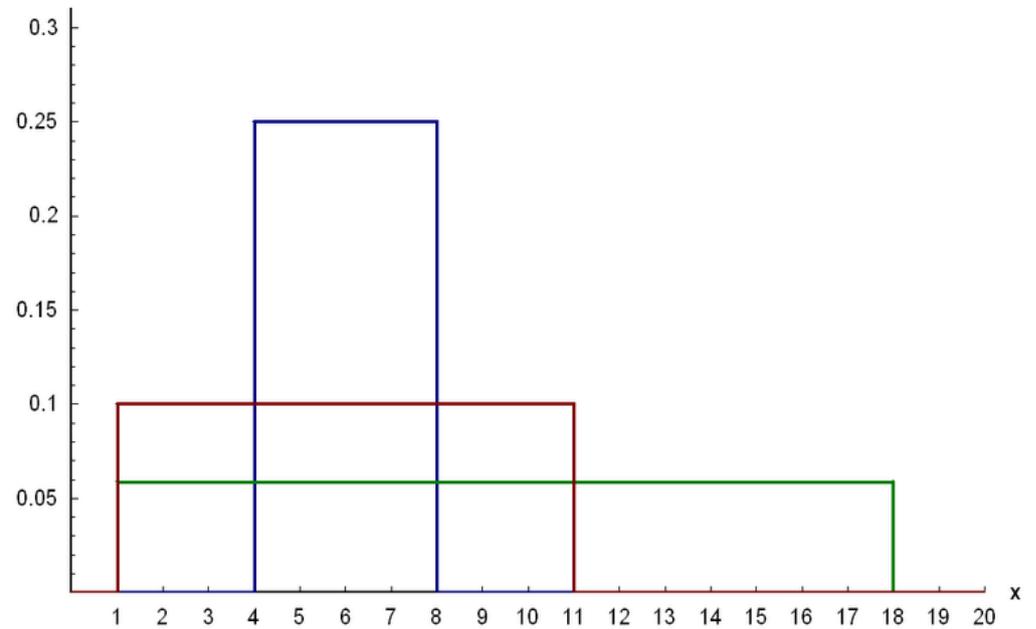
# Random variables

- random variable, sample space
- probability density function
- expectation value
- variance

# Uniform distribution

- probability density function

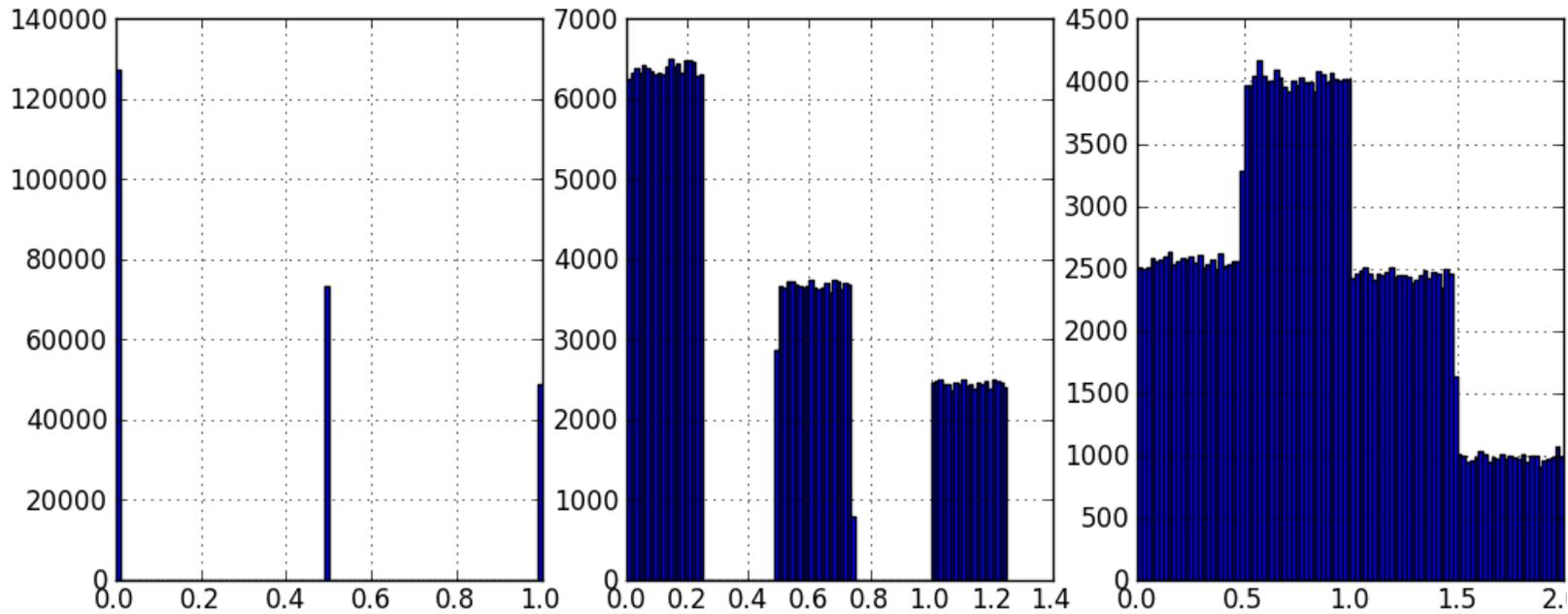
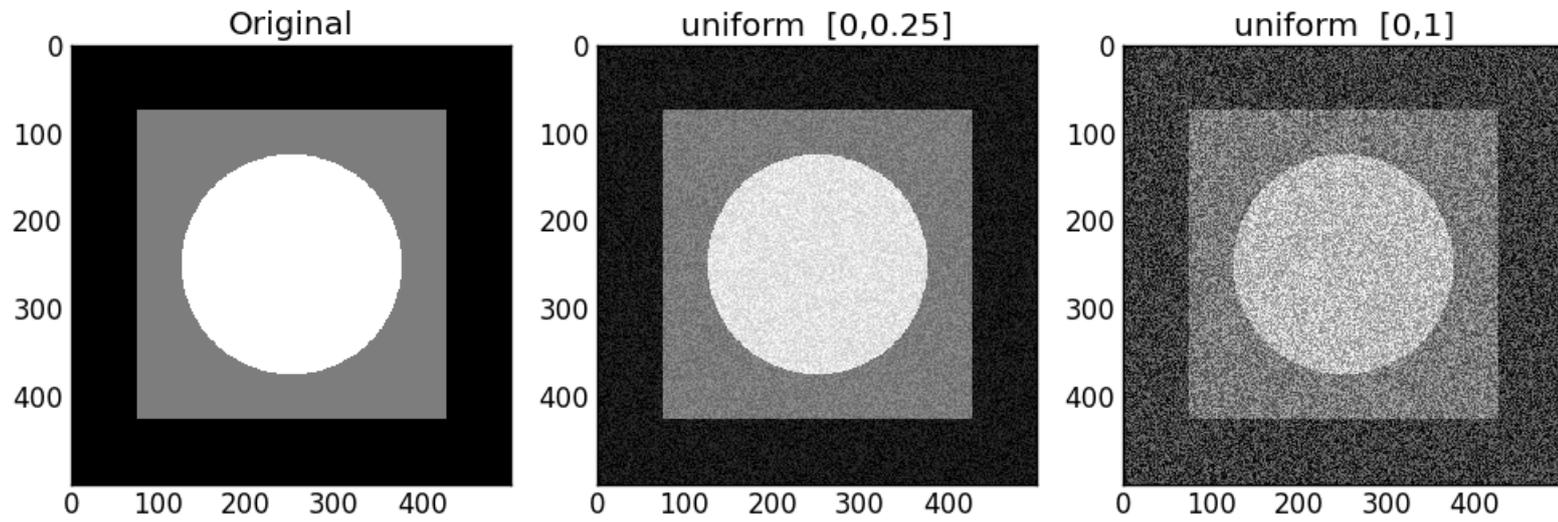
- expectation value



- variance

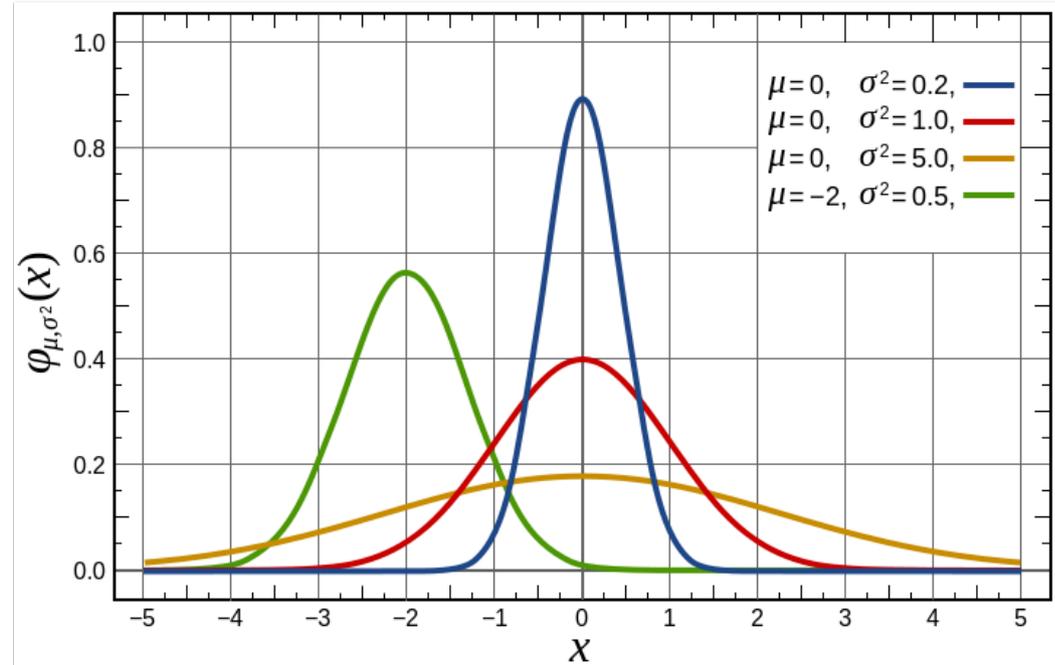
- occurrence

# Uniform distribution



# Gaussian distribution

- probability density function

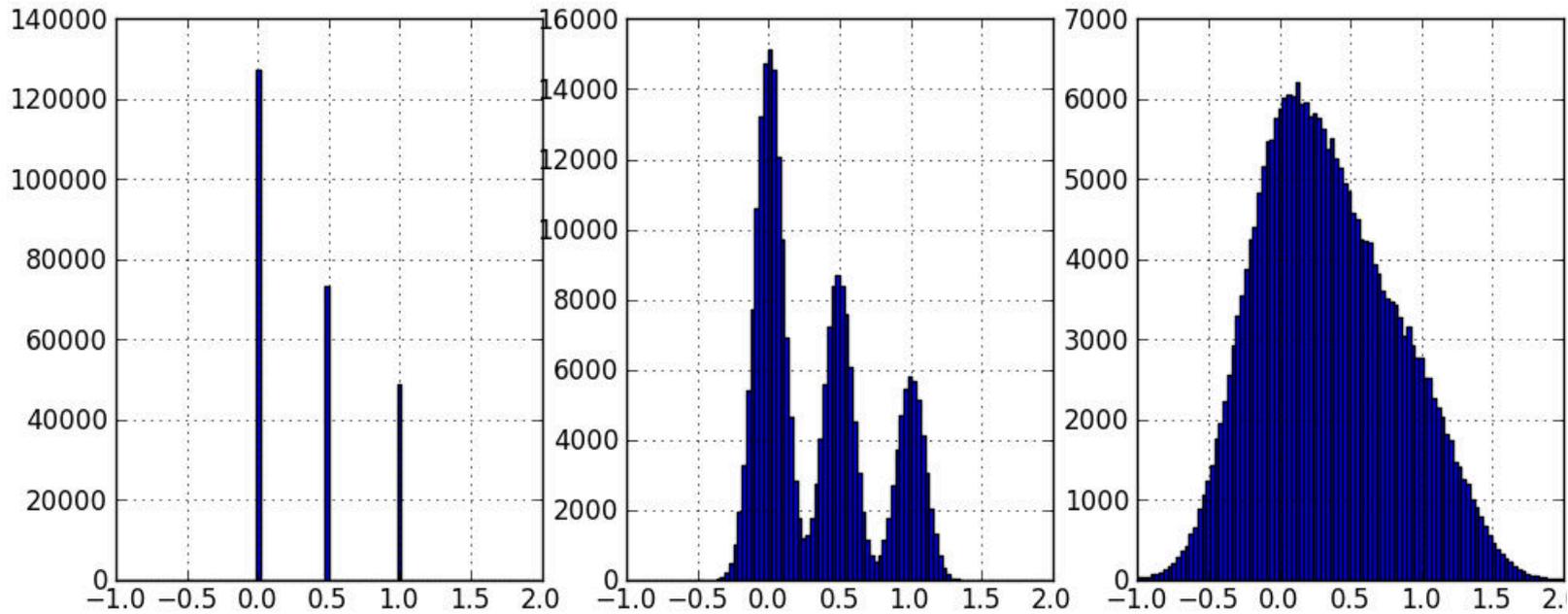
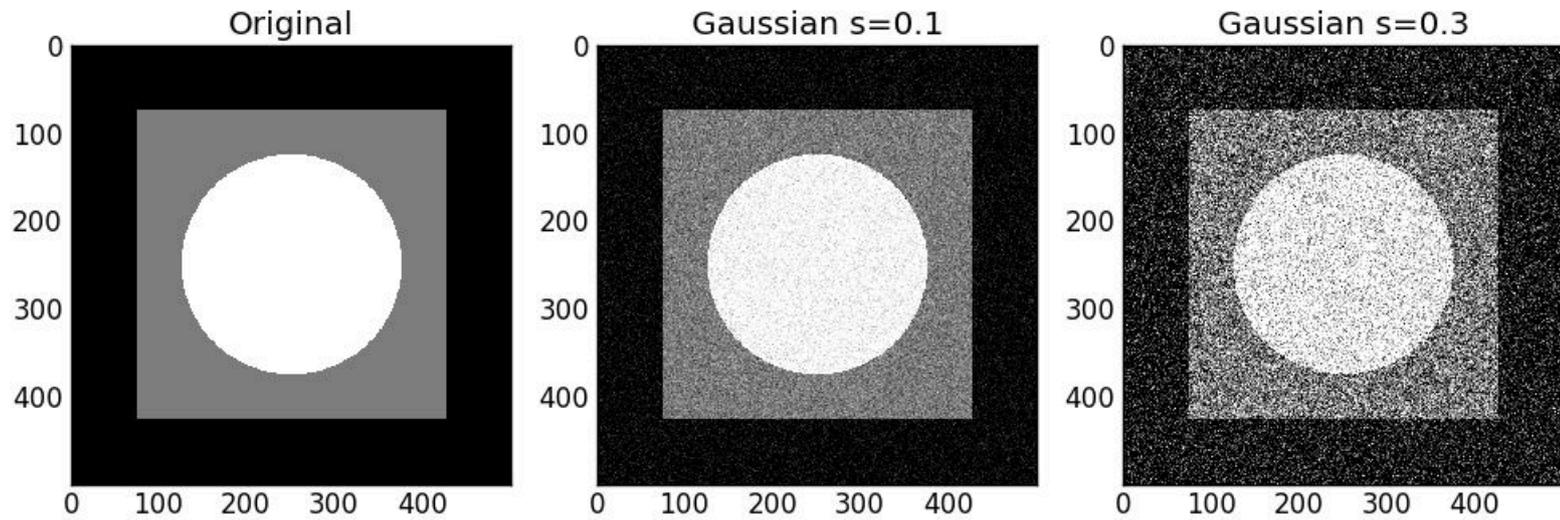


- expectation value

- variance

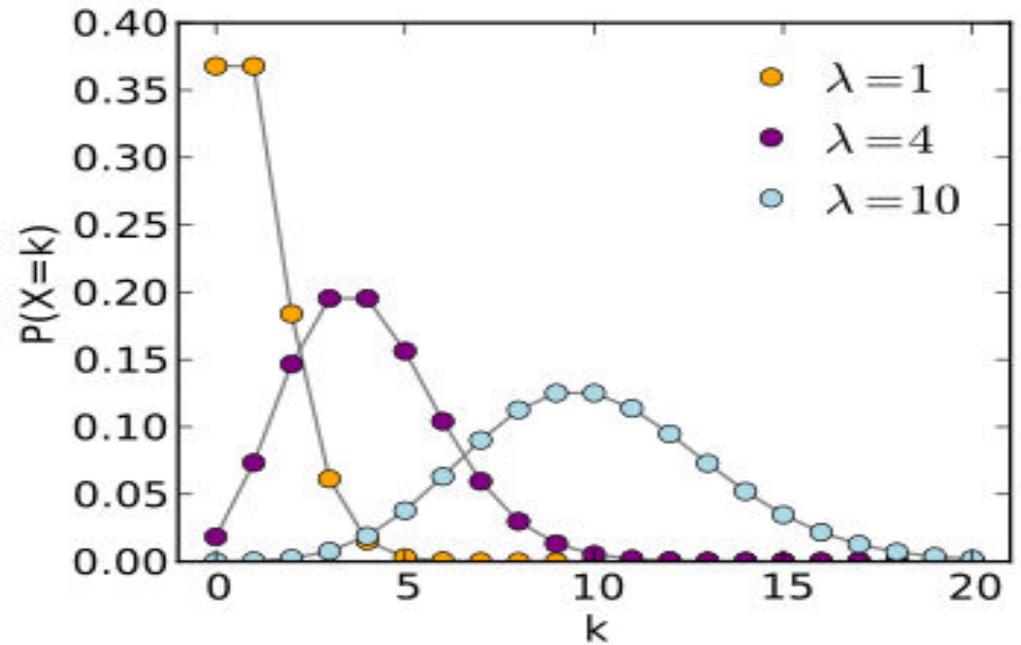
- occurrence

# Gaussian distribution



# Poisson distribution

- probability mass function

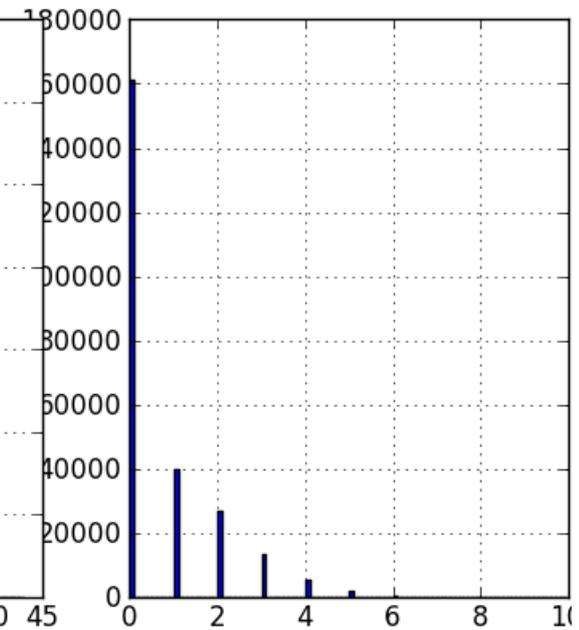
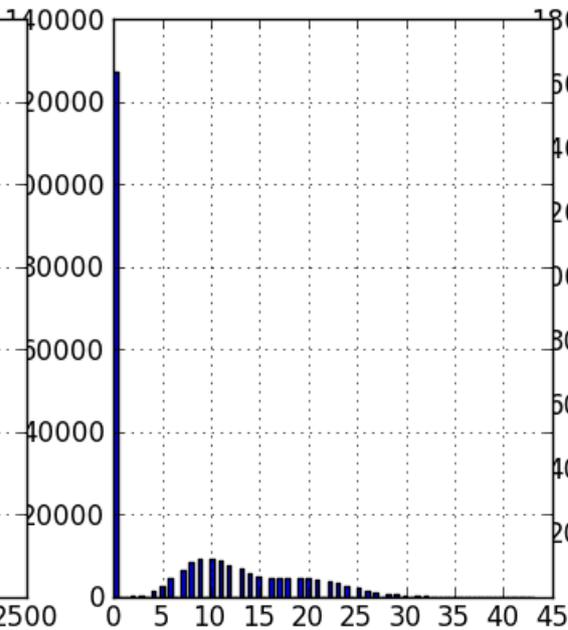
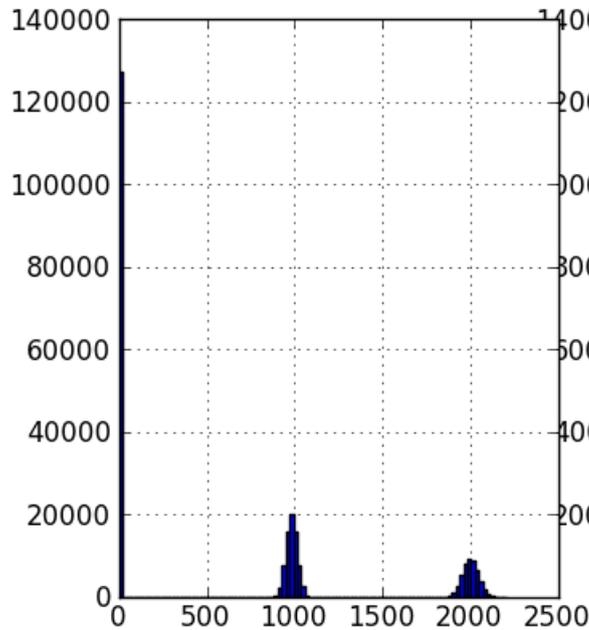
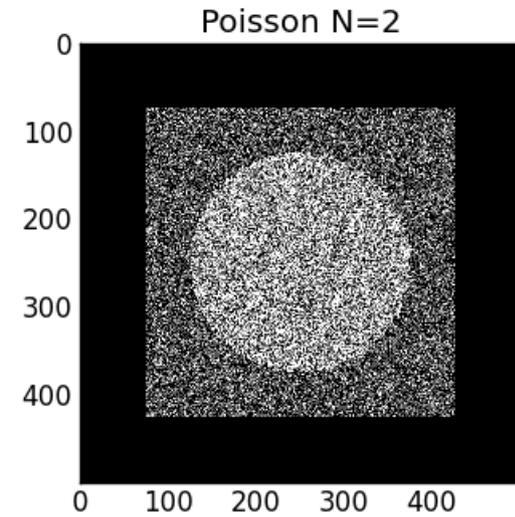
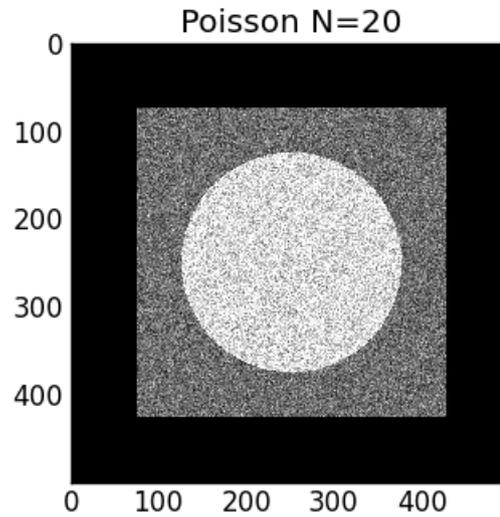
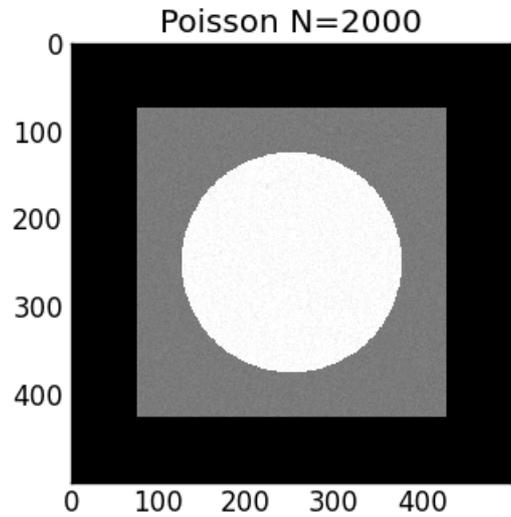


- expectation value

- variance

- occurrence

# Poisson distribution

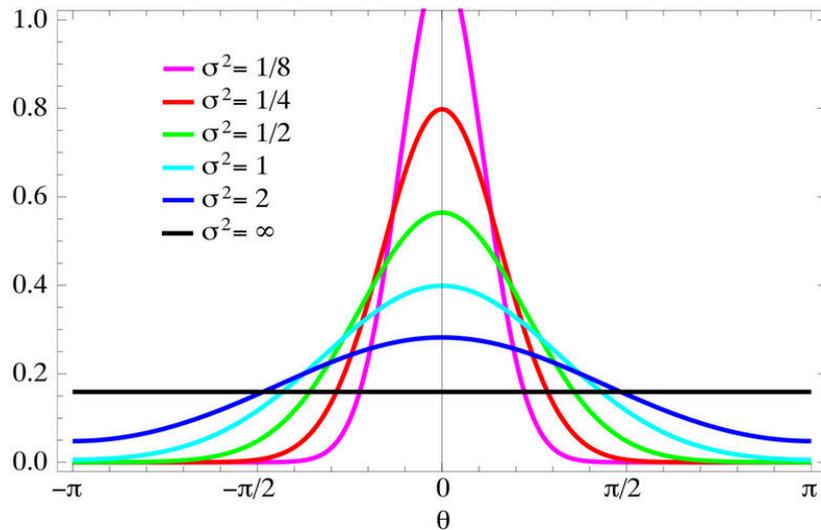


# Poisson distribution

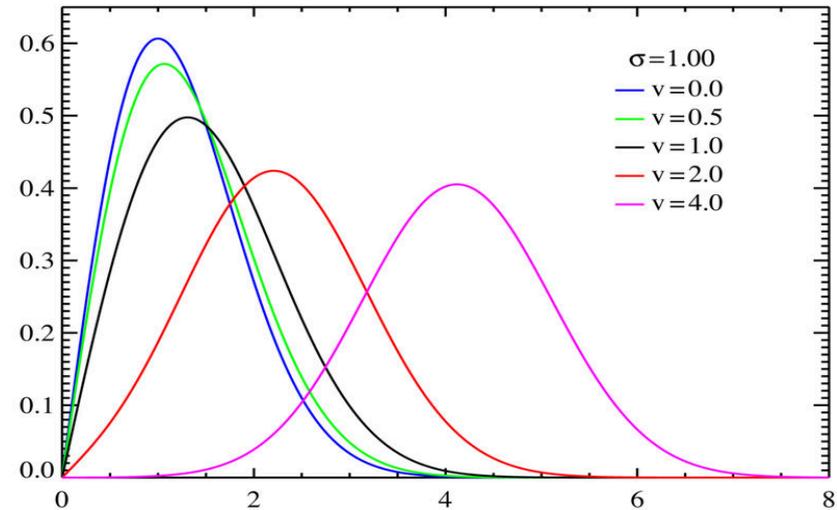


# Many other distributions

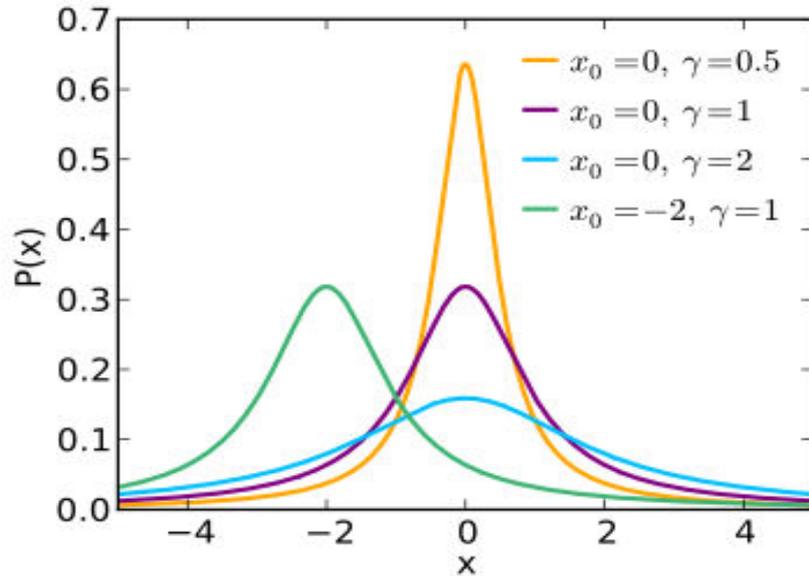
## Wrapped normal distribution



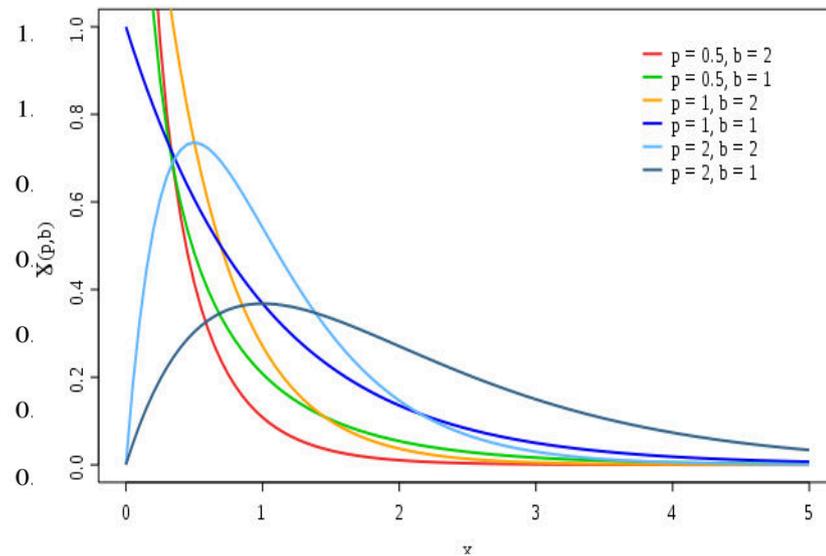
## Rice distribution



## Lorentz distribution



## Gamma distribution



# Detector noise (CCD)

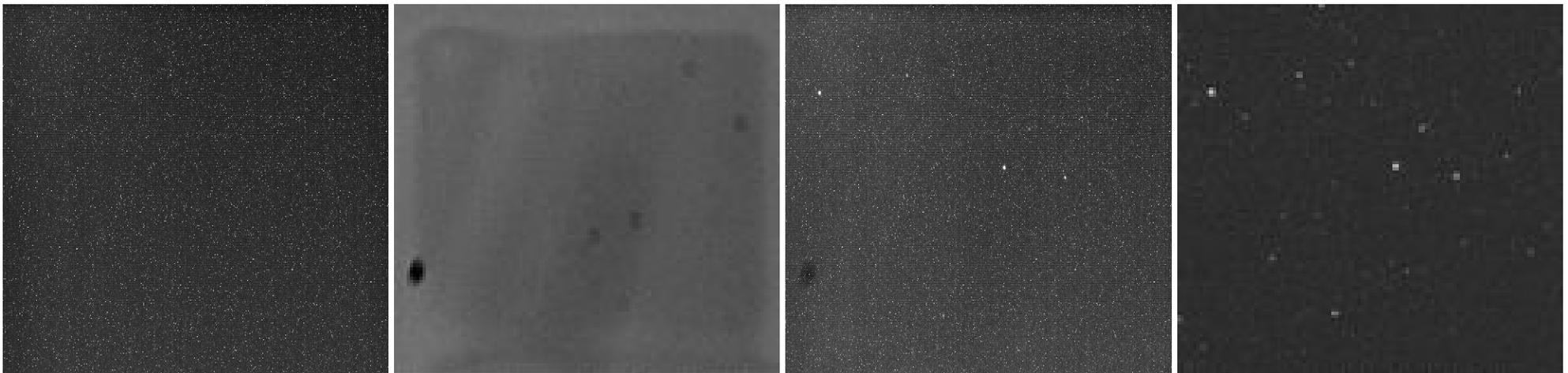
- Various sources:
  - shot noise (photon statistics, Poisson)
  - dark current (thermal electronic fluctuations in semiconductor, Poisson)
  - readout noise (fluctuations during amplification and digitization, Gauss)
  - many other imperfections ...
- dark frame measures detector noise, hot pixels, dead pixels
- bright frame measures gain differences and imperfections (dust, etc)

*dark frame*

*bright frame*

*raw image*

*calibrated image*

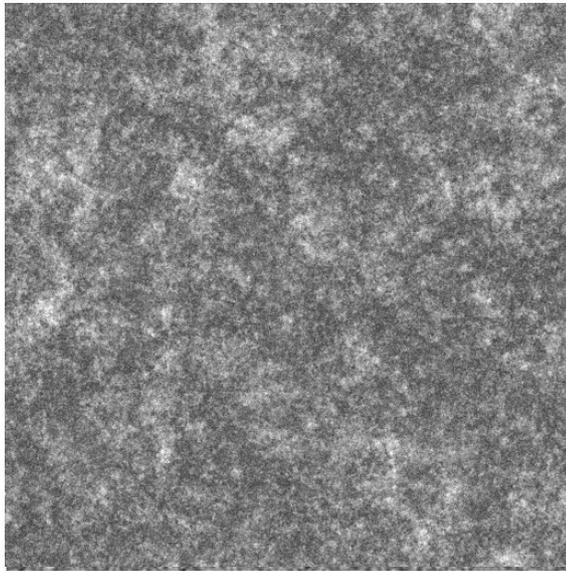


# Correlation & Convolution

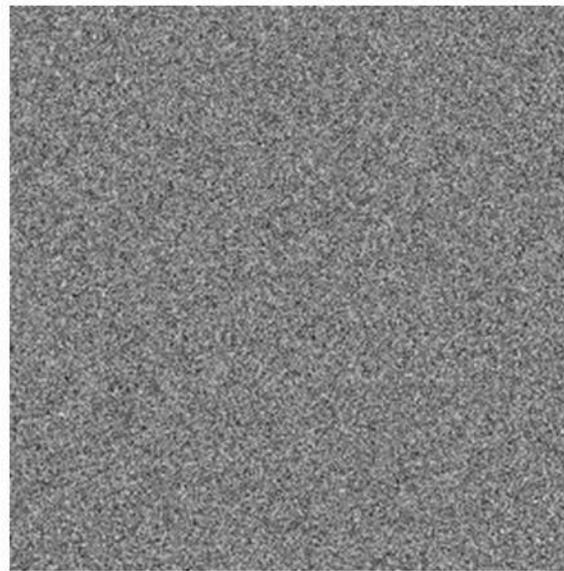


# Noise power spectrum

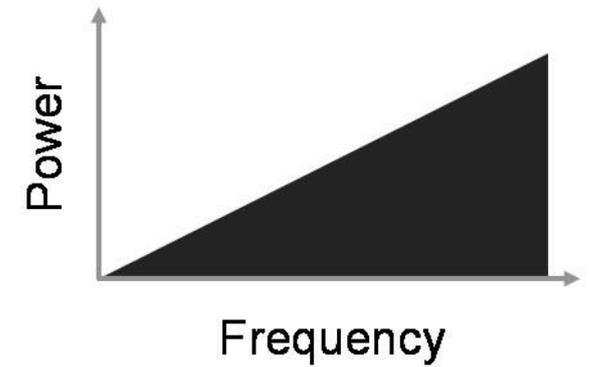
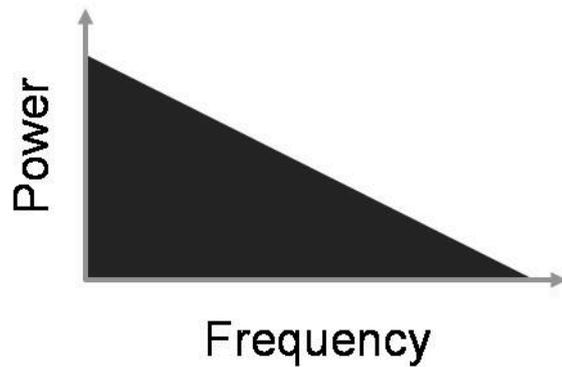
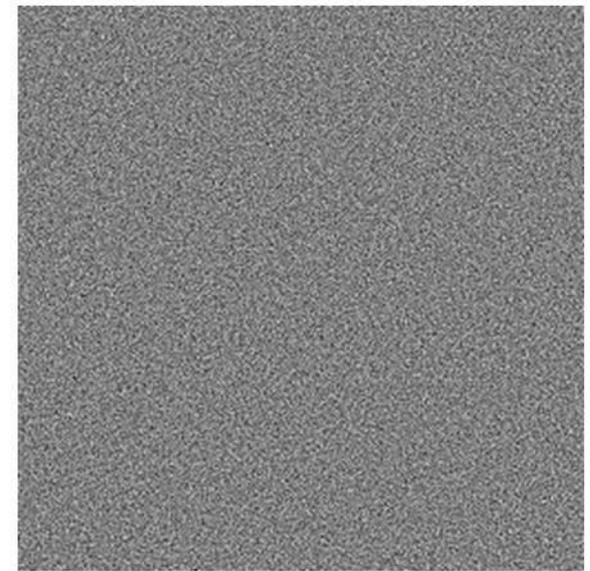
Red noise



White noise

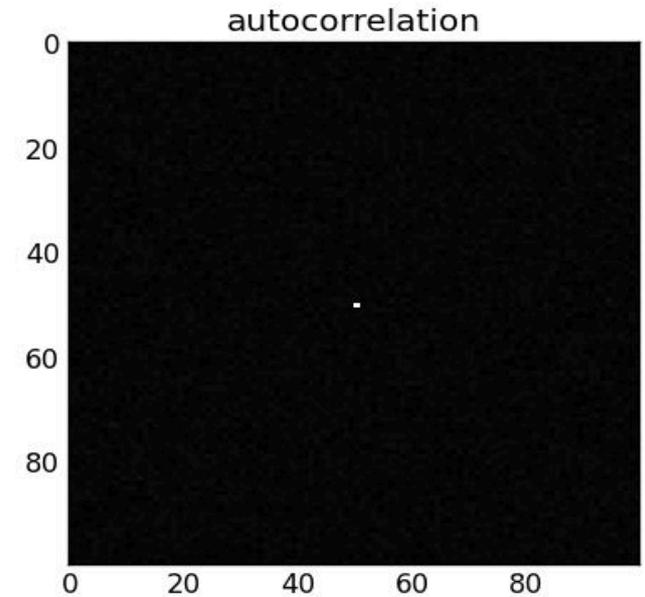
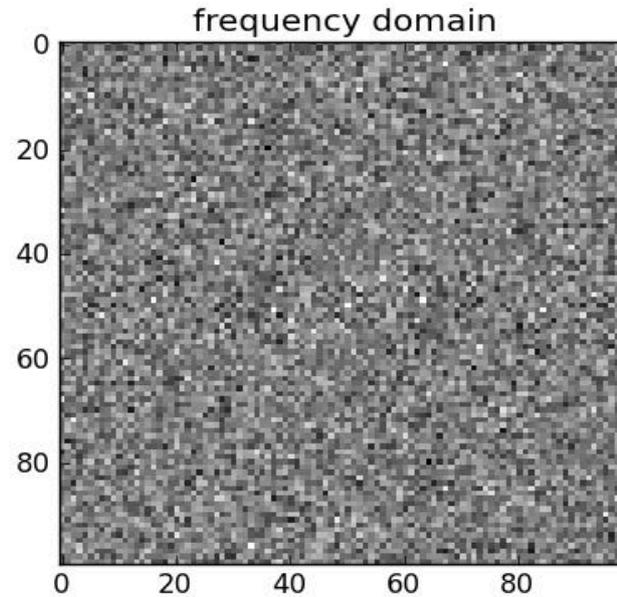
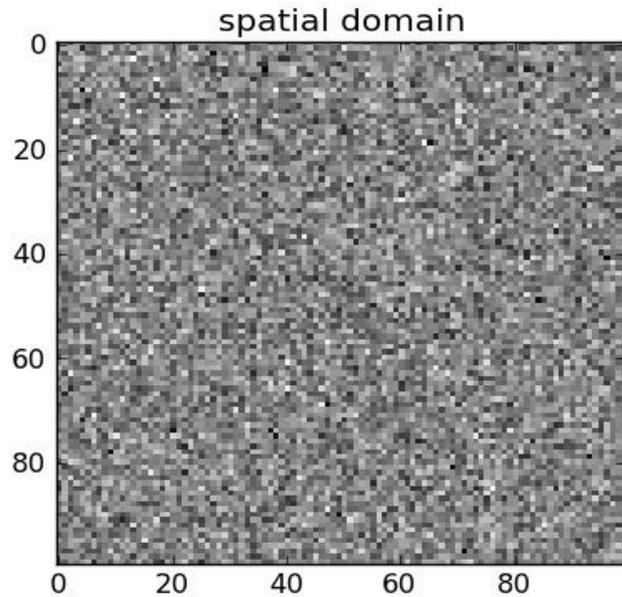


Blue noise



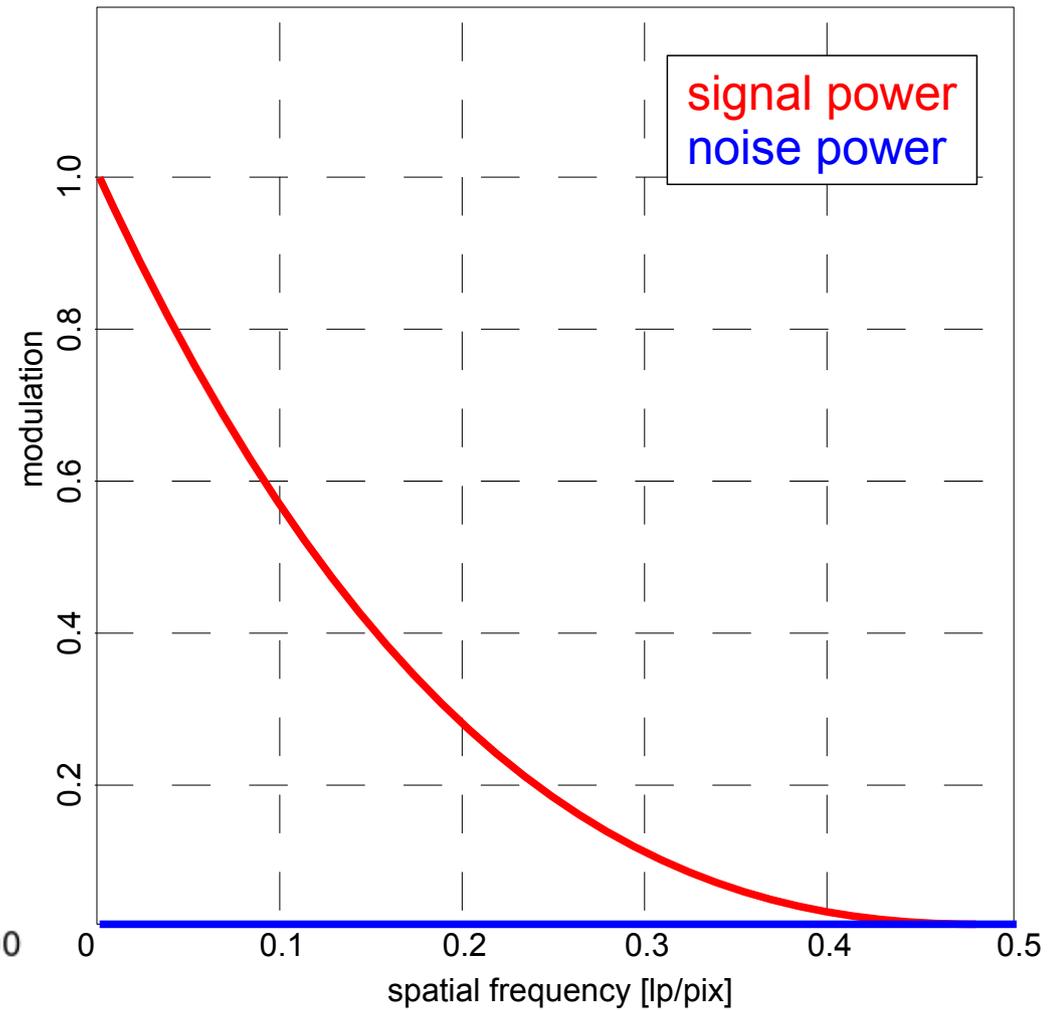
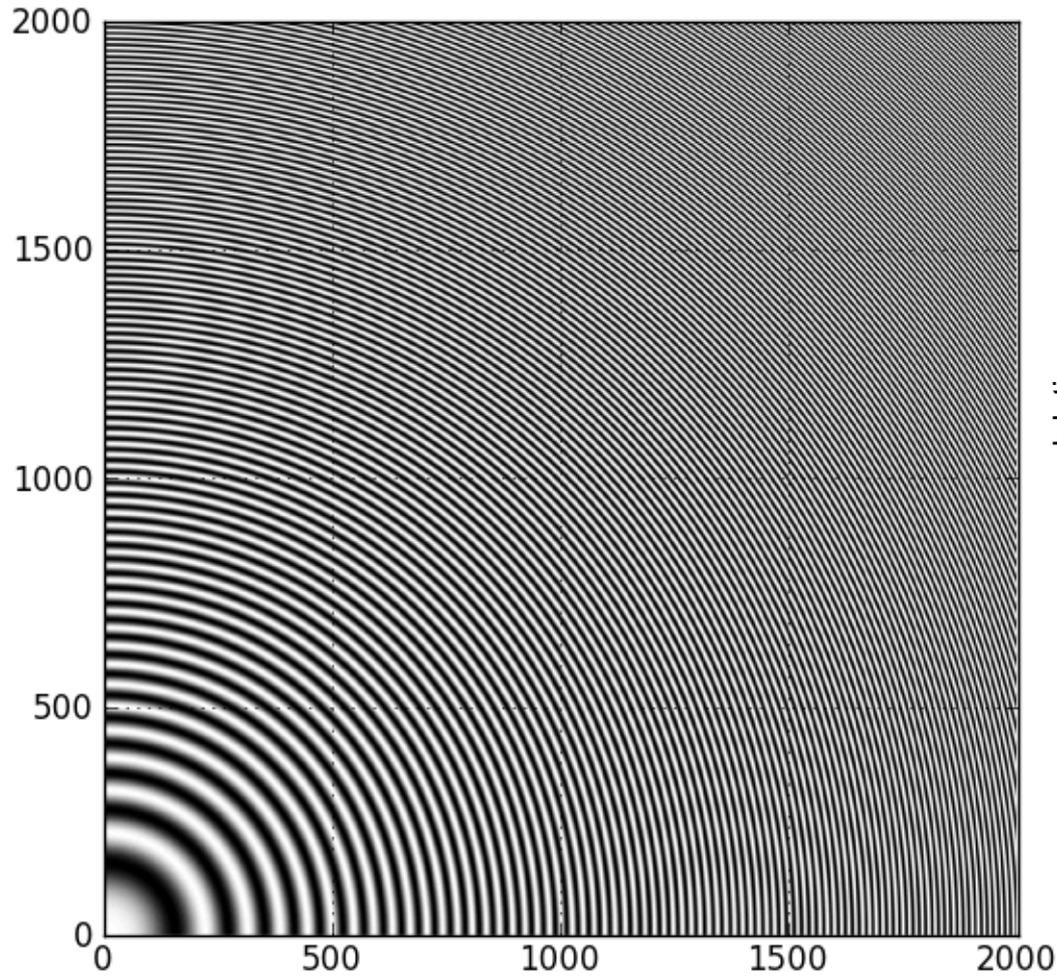
source: [http://scien.stanford.edu/pages/labsite/2008/psych221/projects/08/AdamWang/project\\_report.htm](http://scien.stanford.edu/pages/labsite/2008/psych221/projects/08/AdamWang/project_report.htm)

# White noise

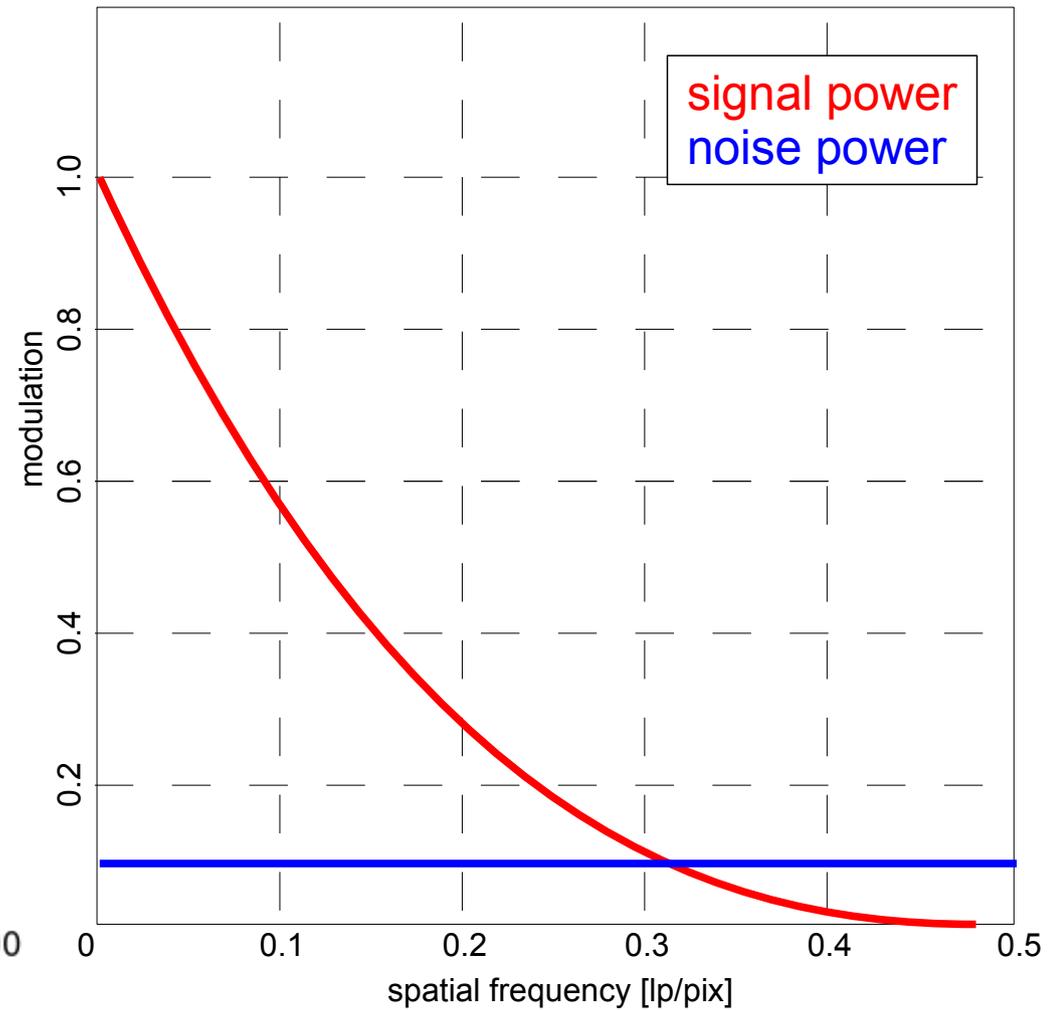
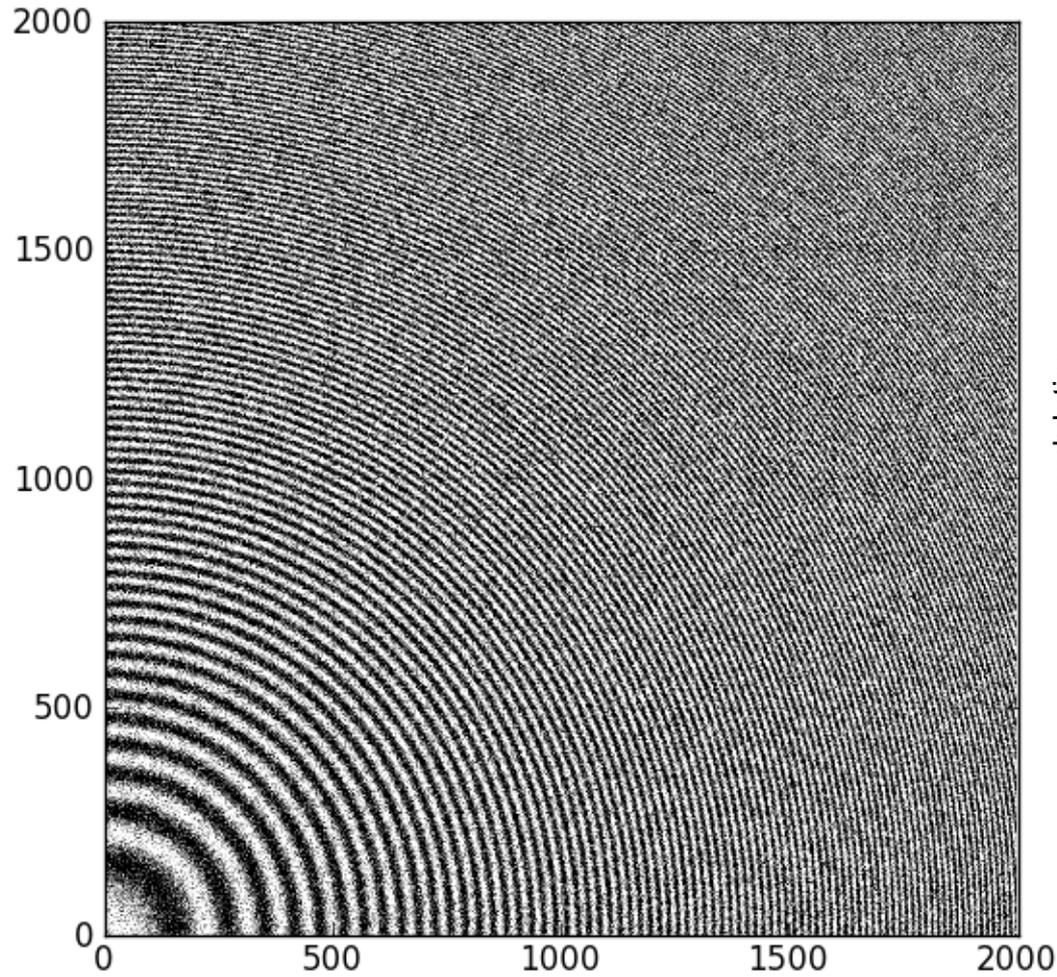


- white noise in spatial domain equals white noise in frequency domain
- white noise is perfectly uncorrelated
- all other types of noise are correlated to some degree
- white noise is an idealization

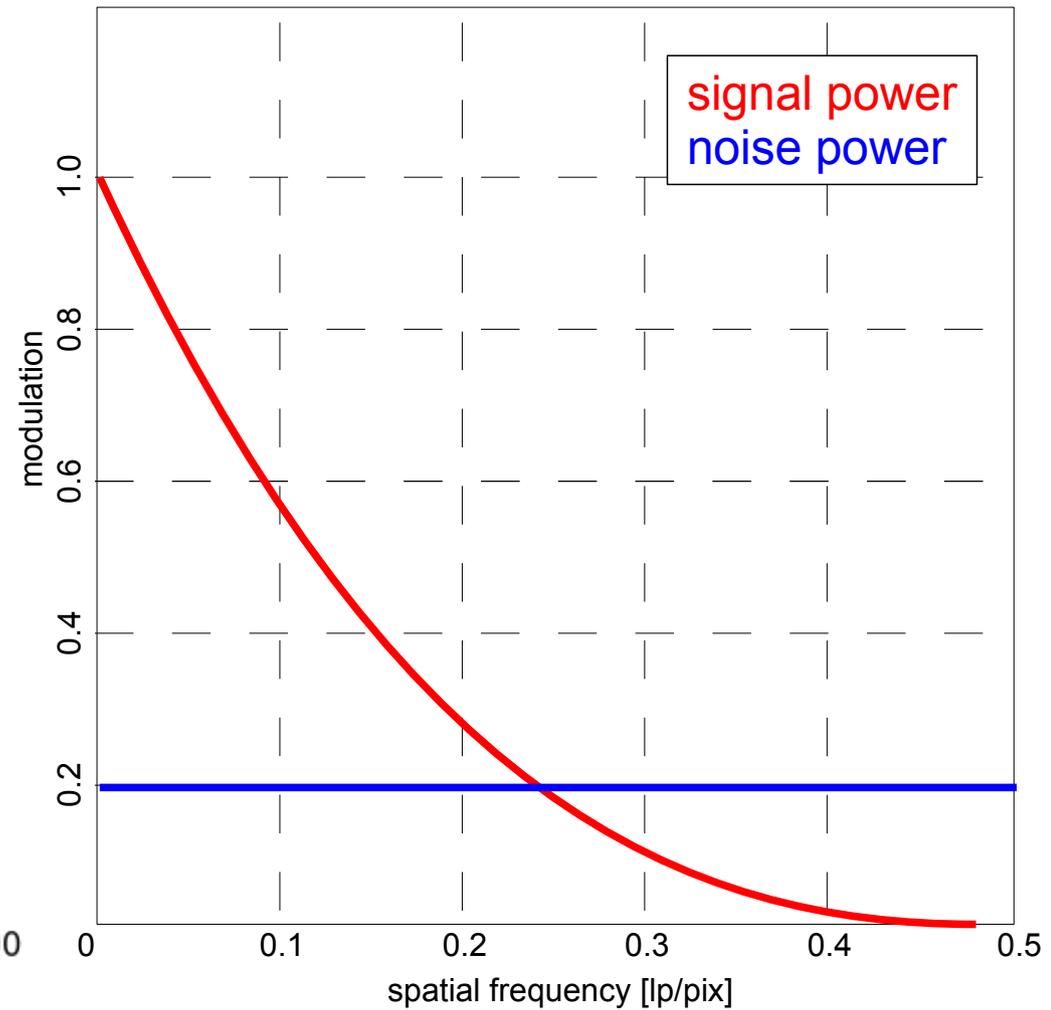
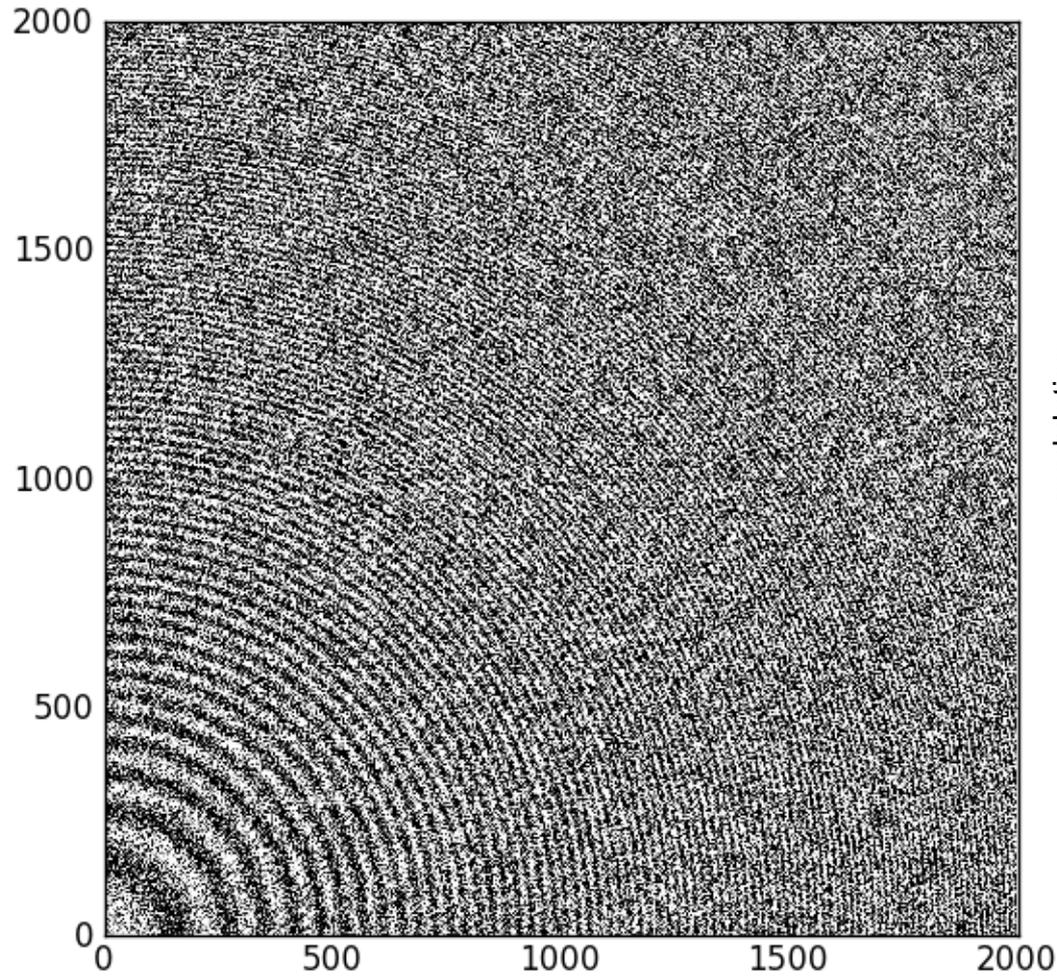
# Signal power vs. noise power



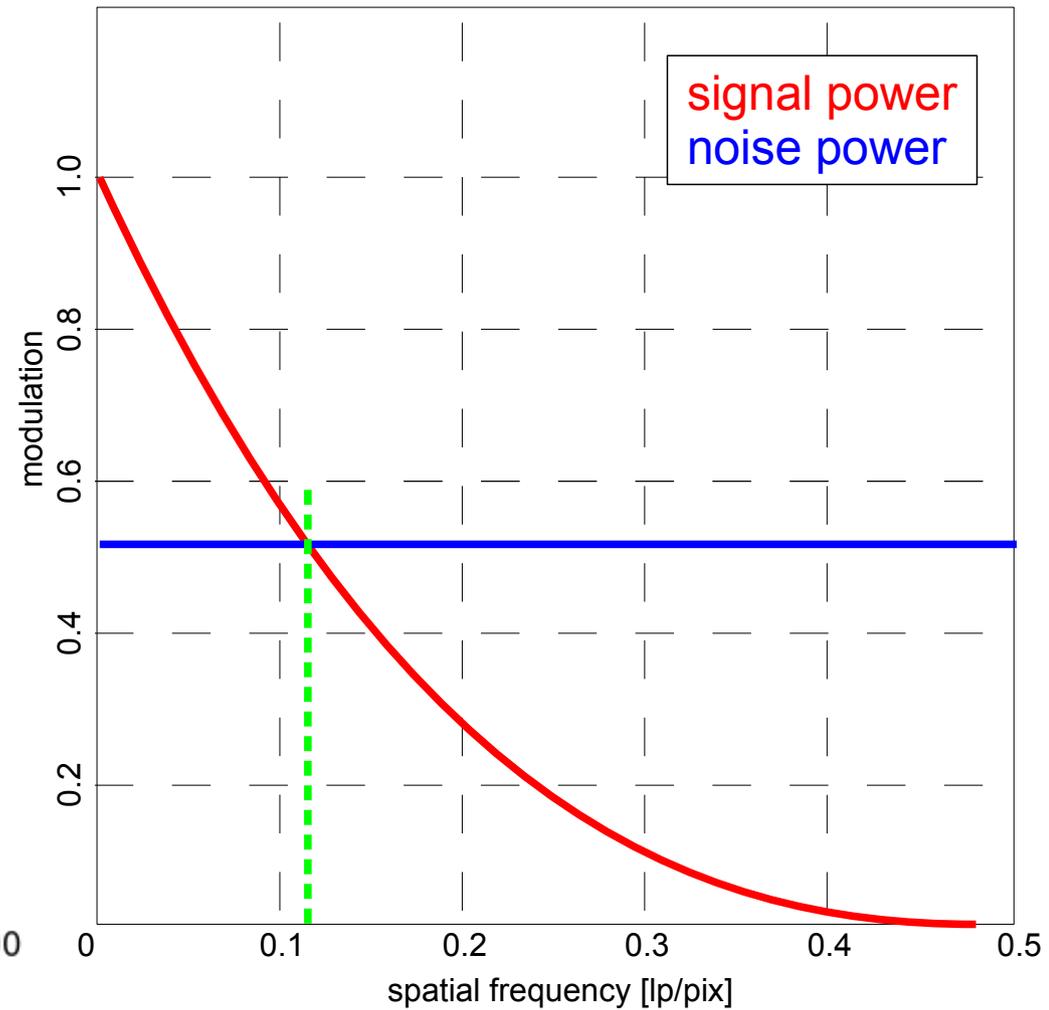
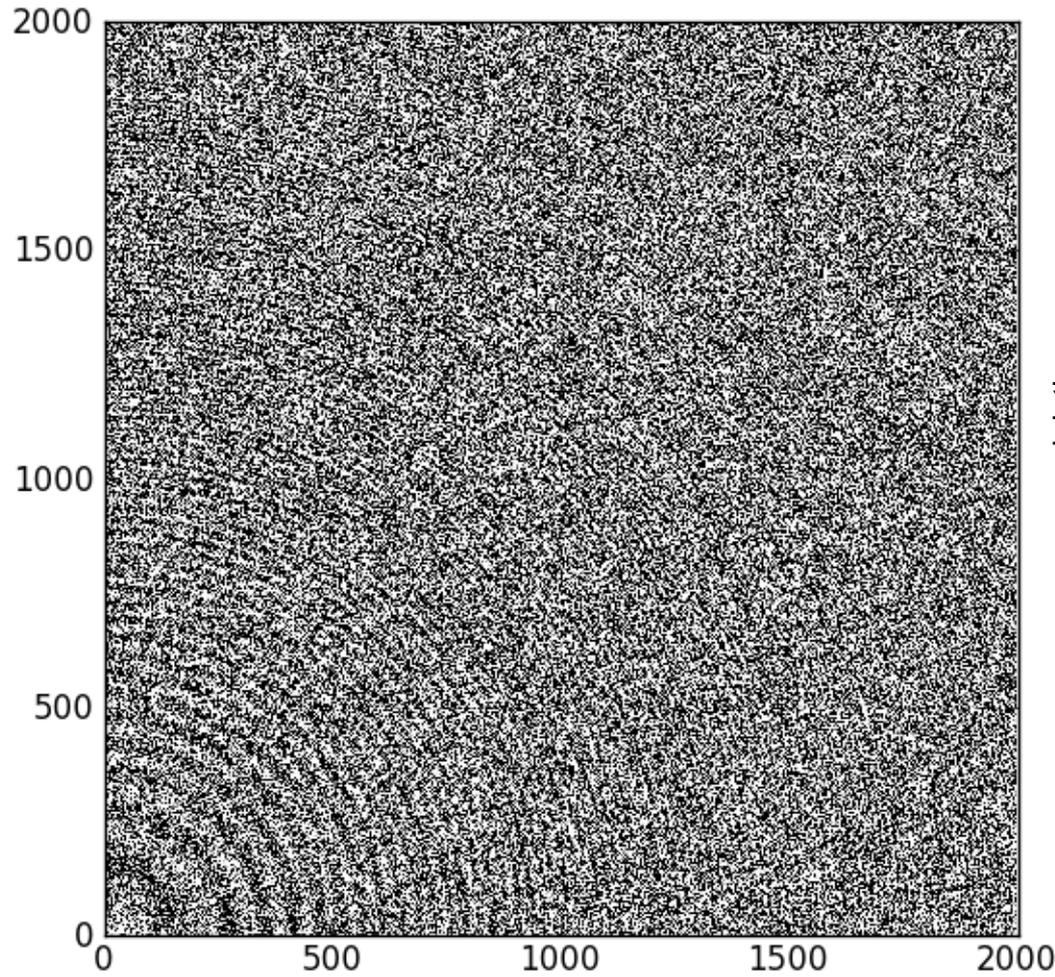
# Signal power vs. noise power



# Signal power vs. noise power

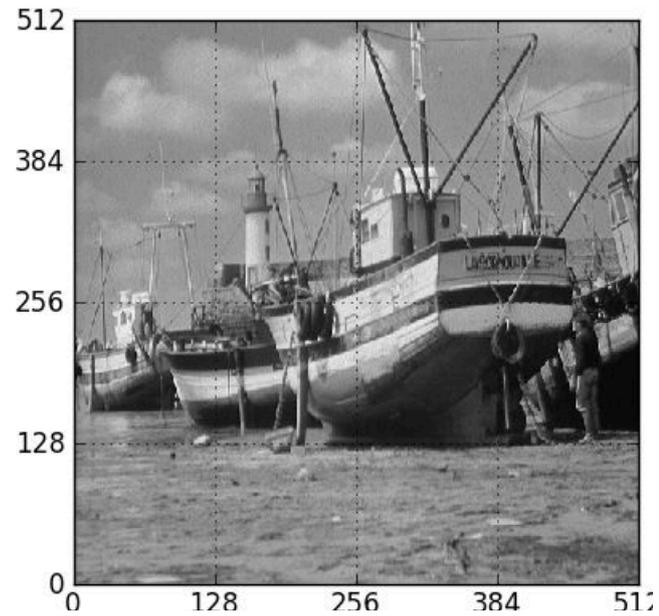
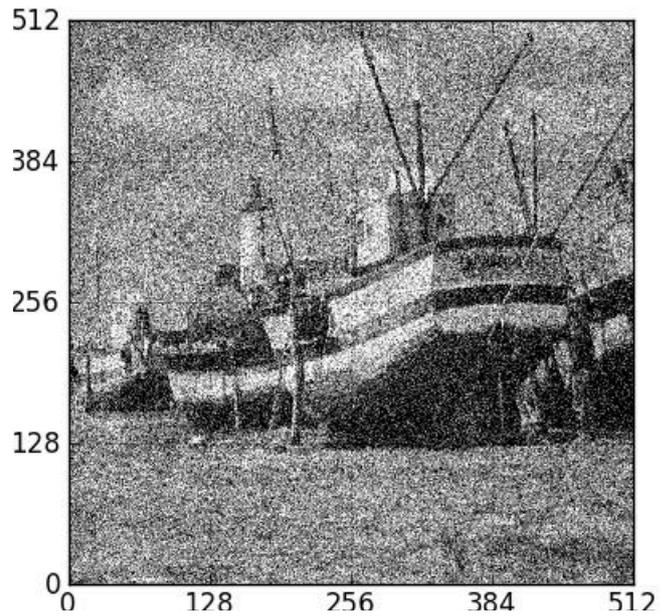
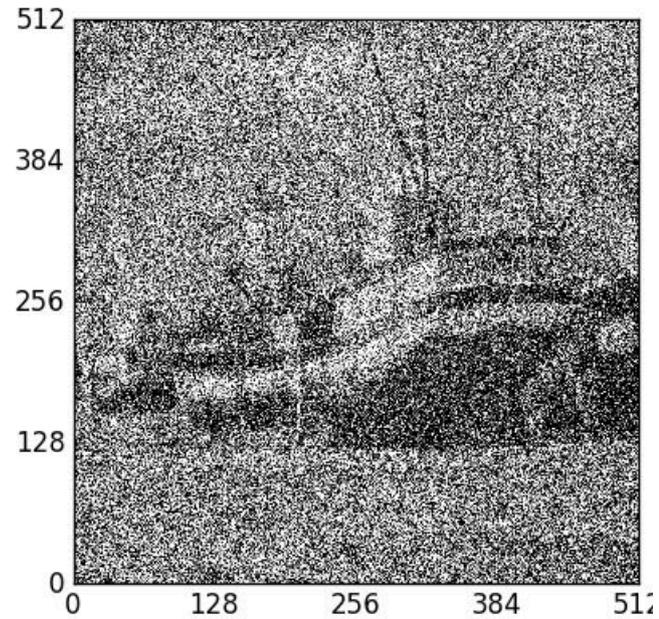
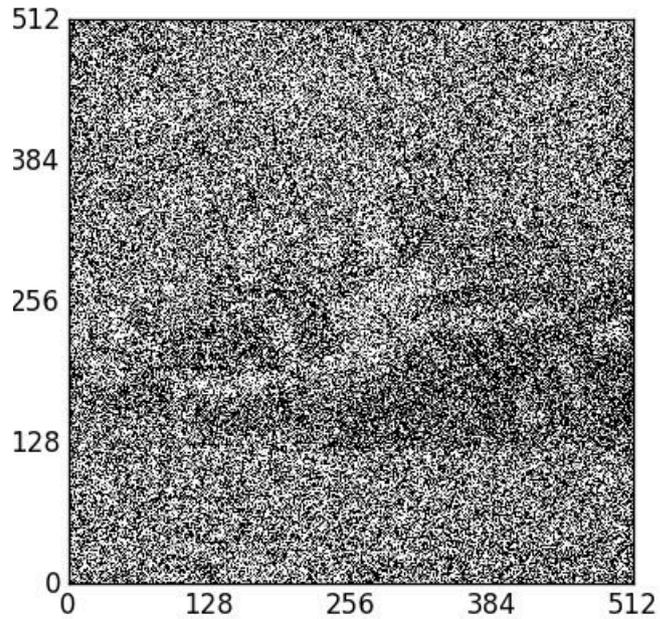


# Signal power vs. noise power



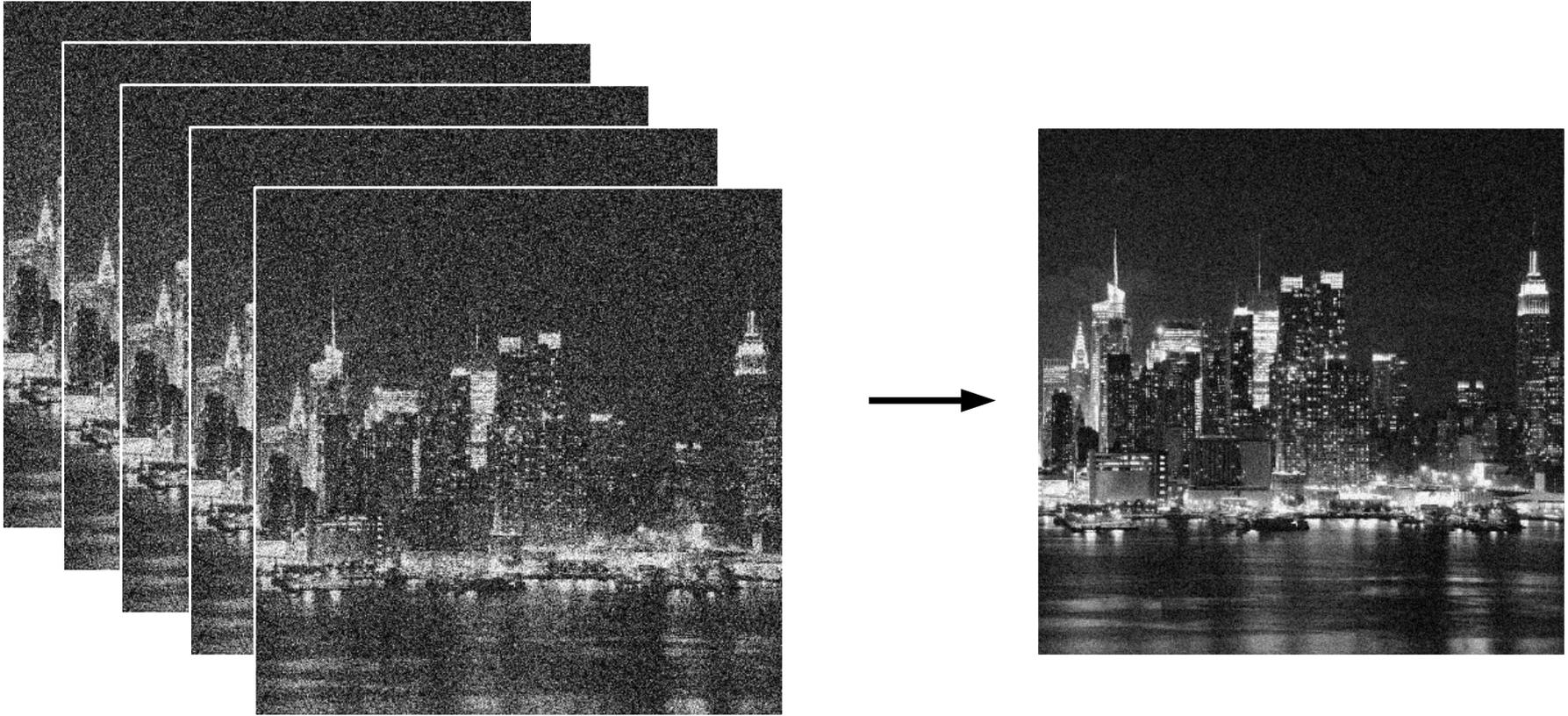
- Noise power exceeds signal power for high frequencies
- Small scale image details are lost in noise first

# Signal power vs. noise power



# Noise reduction by averaging

- Average multiple images



- requirement: additive noise, zero mean

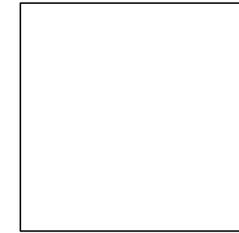
# Denoising by linear filtering

- use spatial convolution or frequency filtering to reduce noise
- noise reduction possible, but at cost of sharpness
- trade-off between noise reduction and resolution
- need fancier methods

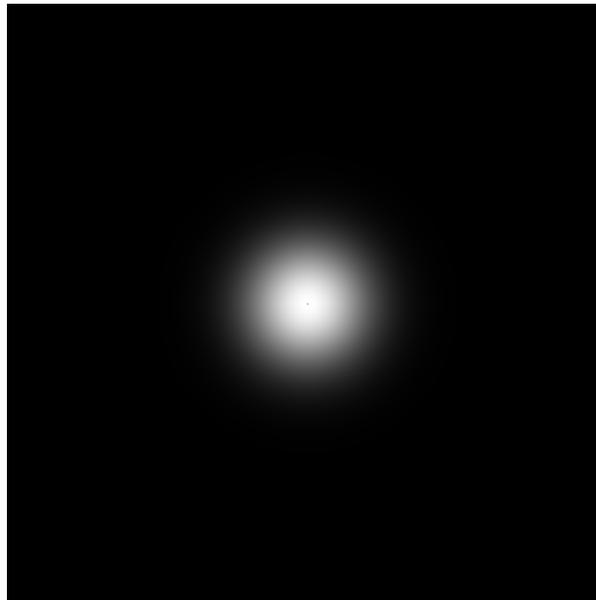
original



convolution kernel



frequency filter



Resulting image



# Median filtering

- Use median as estimator for fat tail distributions
- less sensitive to outliers in pixel ensemble, better edge preservation

Salt and pepper noise



Gauss sigma=1 pixel



Median 1 pixel



# Median filtering

1x Gauss



2x Gauss



5x Gauss



1x Median



2x Median



5x Median



# Common abbreviations

Abbreviation	Name	Definition
IRF	Impulse response function	Linear operator map of delta function
PSF	Point spread function	Image of point object (optical IRF)
OTF	Optical transfer function	Fourier transform of PSF
PTF	Phase transfer function	Phase part of OTF
MTF	Modulation transfer function	Amplitude of OTF
CTF	Contrast transfer function	MTF for non-sinusoidal objects
PDF	Probability density function	Probability distribution for a given random variable
SPS	Signal power spectrum	Amplitude squared of signal F.T.
NPS	Noise power spectrum	Amplitude squared of noise F.T.
SNR	Signal to noise ratio	Mean signal / mean noise
CNR	Contrast to noise ratio	Mean contrast / mean noise