

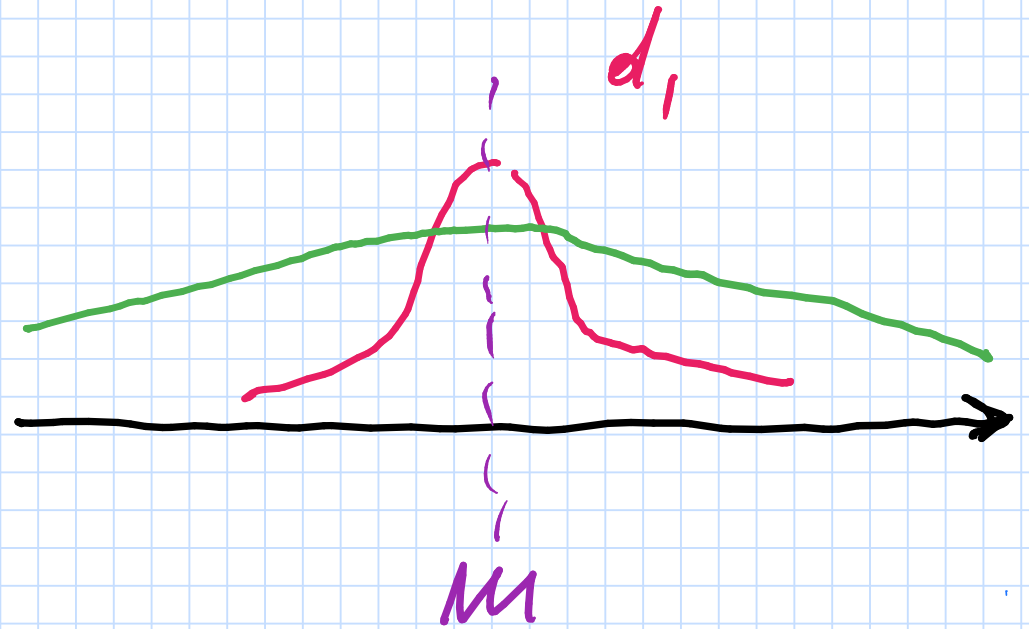
Eserciti su stima di Bayes

Sistemi Dinamici 2e. 2021/23

Es] 2 v. a. indipendenti, gaussiane d_1, d_2

$$d_1 \sim \mathcal{G}(m, 2)$$

$$d_2 \sim \mathcal{G}(m, 4)$$



Stimare m con una osservazione di d_1 ed d_2

$$\hat{m} = \alpha d_1 + \beta d_2$$

① NO BIAS

$$E(\hat{\mu}) = \mu$$

$$E[\hat{\mu}] = \alpha E[d_1] + \beta E[d_2]$$

$$= (\alpha + \beta) \mu$$

$$\text{NO BIAS} \iff \alpha + \beta = 1$$

② Varianza minima

$$\text{var } \hat{\mu} = E \left[(\hat{\mu} - \mu)^2 \right]$$

$$\begin{aligned} \hat{\mu} &= \alpha d_1 + \beta d_2 \\ \alpha + \beta &= 1 \end{aligned}$$

$$= E \left[(\alpha d_1 + \beta d_2 - \underbrace{1}_{\alpha + \beta} \cdot \mu)^2 \right]$$

$\alpha + \beta$

$$= E \left[(\alpha(d_1 - \mu) + \beta(d_2 - \mu))^2 \right] \rightarrow$$

$$\rightarrow \alpha^2 E[(d_1 - \mu)^2] + \beta^2 E[(d_2 - \mu)^2]$$

→ tutti gli altri termini valgono 0

$$= \alpha^2 \cdot 2 + \beta^2 \cdot 4 = 2\alpha^2 + 4\beta^2$$

$$\alpha + \beta = 1 \rightarrow \beta = 1 - \alpha$$

$$\text{var } \hat{\mu} = 6\alpha^2 - 8\alpha + 4$$

$$\text{var } \hat{u} = 6\alpha^2 - 8\alpha + 4$$

$$\frac{d}{d\alpha} (\text{var } \hat{u}) = 0 \rightarrow 12\alpha - 8 = 0$$

$$\left\{ \begin{array}{l} \alpha = \frac{2}{3} \\ \beta = \frac{1}{3} \end{array} \right.$$

$$\hat{u} = \frac{2}{3}d_1 + \frac{1}{3}d_2 \quad \text{var } \hat{u} = \frac{4}{3}$$

[45] (2) consideriamo 2 v. r. x, w

$$E(x) = 0$$

$$E(w) = 0$$

scorrelate

$$\sigma_x^2 = 1$$

$$\sigma_w^2 = 1$$

$$E(xw) = 0$$

Vouci conoscere il valore attuale di x all'istante t (faccio un esperimento) $\rightarrow x$ non osservabile. Posso osservare un'altra v. r.

$$y = x + w$$

$\hat{x} = ?$

stimatore lineare ottimo

$$\hat{\beta} = \frac{D'Y}{D'D}$$

$D'Y$ (circled in red)

$D'D$ (circled in red)

D (circled in red)

osservazione

D' (circled in red)

$D \rightarrow Y$
 $D \rightarrow X$

$D'D \leftrightarrow \Sigma_Y$

$D'Y \leftrightarrow \Sigma_{XY}$

$$E(xy) = E[x(x+w)] = \underbrace{E(x^2)}_{\sigma_x^2} + \underbrace{E(xw)}_0$$

$$= \sigma_{xy}$$

$$\hat{x} = \frac{\sigma_{xy}}{\sigma_y^2} \cdot y = \frac{1}{2} y$$

$$\text{var}(\theta - \hat{\theta}) = \sigma_\theta^2 - \frac{\sigma_{\theta y}^2}{\sigma_y^2}$$

Supponiamo che le v.v. siano x, w, z IND.
e di poter fare 2 osservazioni differenti

$$x \rightarrow E(x) = 0 \\ \text{Var}_x = 1$$

$$w \rightarrow E(w) = 0 \\ \text{Var}_w = 1$$

$$z \rightarrow E(z) = 0 \\ \text{Var}_z = 2^2$$

$$\begin{cases} y_1 = x + w \\ y_2 = x + z \end{cases}$$

$$\vec{g} = \underbrace{\Lambda}_{g_d} \cdot \underbrace{\Lambda^{-1}}_{d_d} \cdot d$$

$$\vec{x} = \underbrace{\Lambda}_{x_d} \cdot \underbrace{\Lambda^{-1}}_{d_d} \begin{bmatrix} f_1 \\ f_2 \end{bmatrix}$$

$$\underbrace{\Lambda}_{d_d} = \begin{bmatrix} \underbrace{d_{f_1}^2} \\ \underbrace{d_{f_1 f_2}} \\ \underbrace{d_{f_2}^2} \end{bmatrix}$$

$$d_{f_1}^2 = 2$$

$$d_{f_2}^2 = 1 + d^2$$

$$\mathbf{\Sigma}_{y_1 y_2} = E \begin{bmatrix} y_1 & y_2 \end{bmatrix} = E \begin{bmatrix} (x+w) & (x+z) \end{bmatrix}$$

$$= E(x^2) + \cancel{E(xw)} + \cancel{E(xz)} + \cancel{E(wz)}$$

0 0 0

$$= \mathbf{I}$$

$$\mathbf{\Lambda}_{\text{old}} = \begin{bmatrix} 2 & & & \\ & 1 & & \\ & & & \\ 1 & & & 1+d^2 \end{bmatrix}$$

$$\Lambda_{dd}^{-1} = \begin{bmatrix} \frac{d^2+1}{2d^2+1} & -\frac{1}{2d^2+1} \\ -\frac{1}{2d^2+1} & \frac{2}{2d^2+1} \end{bmatrix}$$

$$\Lambda_{d\sigma} = \begin{bmatrix} F(y_1, x) \\ F(y_2, x) \end{bmatrix} \quad \Lambda_{\sigma d} = \Lambda_{d\sigma}^T$$

$$E(\delta_1 x) = E[(x+w)x] = 1$$

$$E(\delta_2 x) = E[(x+z)x] = 1$$

$$\Lambda_{d0} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Lambda_{d1} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\hat{x} = \sqrt{\frac{1}{2d}} \cdot \sqrt{\frac{1}{d}} \cdot d = \sqrt{\frac{1}{2}} \sqrt{\frac{1}{d}} \sqrt{d} \begin{bmatrix} g_1 \\ g_2 \end{bmatrix}$$

$$= \frac{1}{\sqrt{2d+1}} (g_2 + \sqrt{2} g_1)$$

$$\begin{array}{l} \text{se } \sqrt{2} \gg 1 \quad \Rightarrow \quad \hat{x} \rightarrow \frac{1}{\sqrt{2}} g_1 \\ \text{se } \sqrt{2} \ll 1 \quad \Rightarrow \quad \hat{x} \rightarrow g_2 \end{array}$$

$$\begin{cases} x \\ y_2 = z \end{cases} ?$$

$$\begin{cases} y_1 = x + w \\ y_2 = z \end{cases}$$

$$E(z) = 0$$

$$V_z^2 = 1$$

$$E(x+w) = 0$$

$$E(x+z) = 0$$

$$E(wz) = 0$$

$$\Lambda_{dd} = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\Lambda_{dy} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\hat{x} = \Lambda^{-1} \Lambda^{-1} \cdot d$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1/2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$= \begin{bmatrix} 1/2 & y_1 \\ 0 & y_2 \end{bmatrix}$$

$$\text{var}(x - \hat{x}) = \sigma_x^2 - \sqrt{\sigma_d} \sqrt{\sigma_d}^{-1} \sqrt{\sigma_d}$$

$$= I - \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 1/2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= 1/2$$