



Università di Trieste
Corso di Laurea Magistrale in Esplorazione Geologica

Anno accademico 2021 - 2022

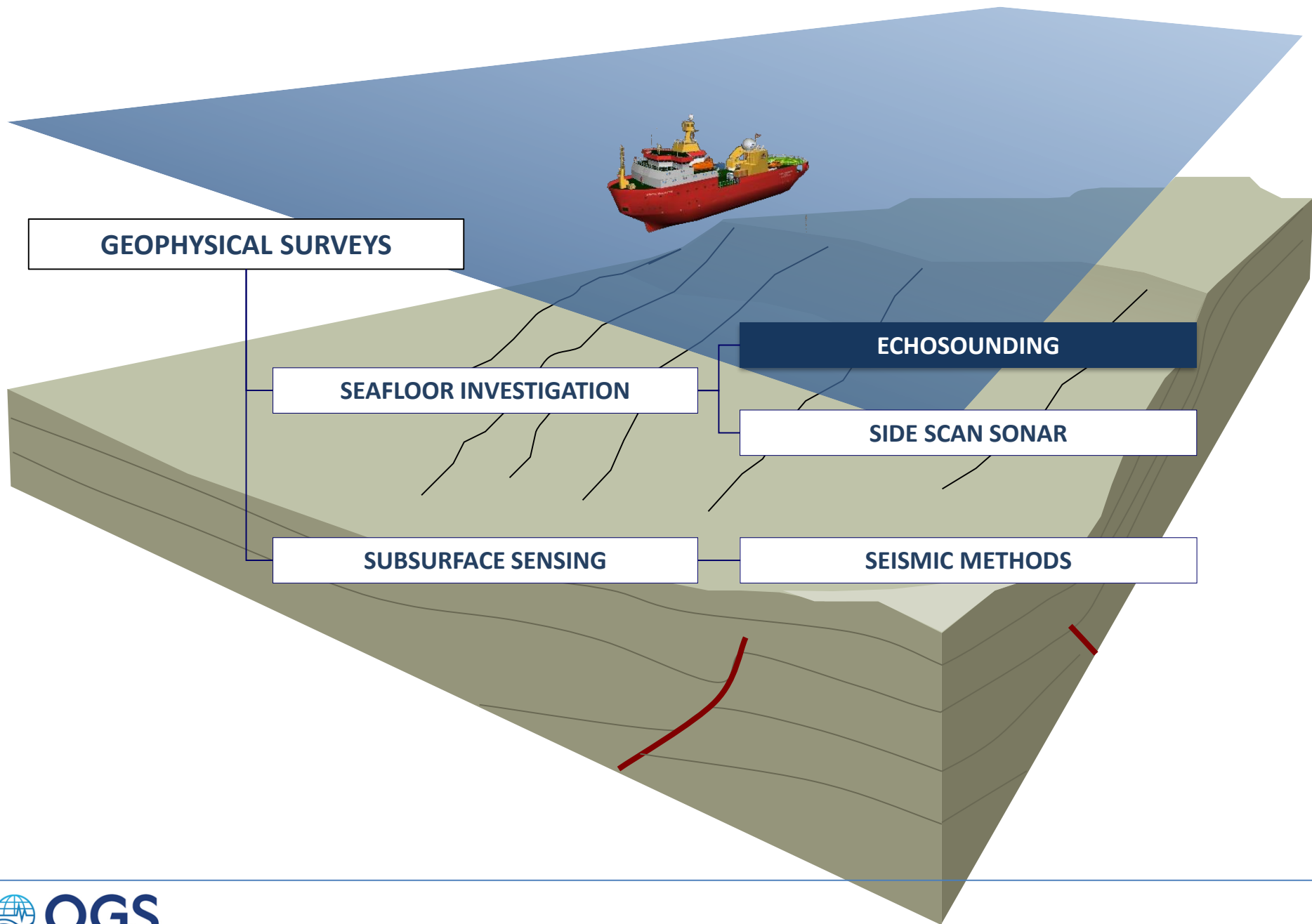
Geologia Marina

Parte II

Modulo titolo: Metodi acustici

Docente

Fabrizio Zgur



IT IS USED FOR

Morphobatymetry surveys aim at mapping the seafloor with large areal coverage. The result is a 3D **D**igital **T**errain **M**odel (**DTM**) mad up of a grid of cells whose size depends on the resolution.

HOW IT WORKS

Multibeam echosounders use transducers that produce a fan of pre-formed beams. The fan can vary from 45° to up to 150° depending on the unit. The returns from these beams can be processed with GPS position information and ship motion compensation to give bathymetry as well as the backscatter information that is obtained by conventional sidescans. A single ship's track can map a swath between 2 and 7.4 times water depth, depending on the system. Beam widths fore and aft vary between 1.5° and 4.5° depending on the system.

ENVIRONMENT AND SOCIETY

Navigation charts

- Bathymetric surveys
- Pre / Post dredge surveys
- Breakwaters, piers, bridges
- Harbor and rivers surveys
- Flood damage assessment
- Underwater inspections

RESEARCH

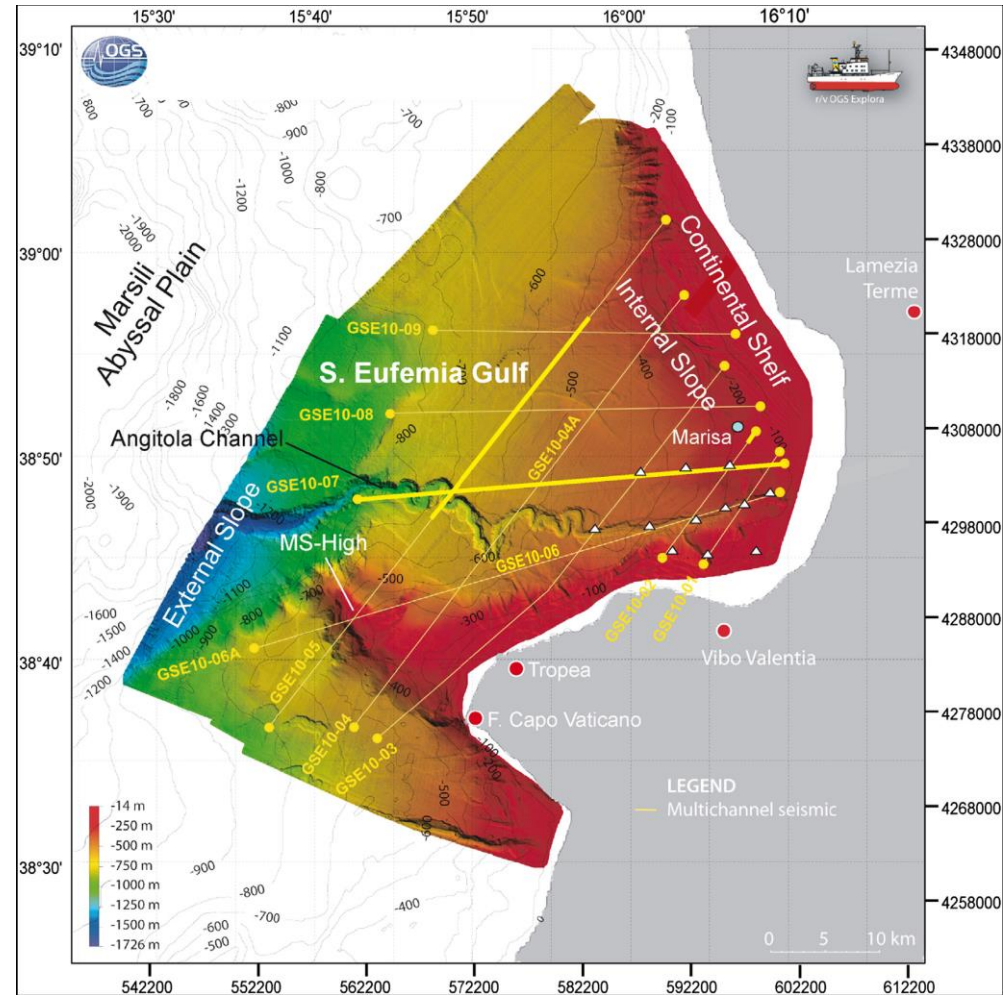
Marine Geology and Biology

- Geomorphology
- Geo hazard (slope stability)
- Fluid escapes (water column)
- Neotectonic related surface expressions
- Study of benthic habitats

INDUSTRY

Foundation studies for offshore infrastructures

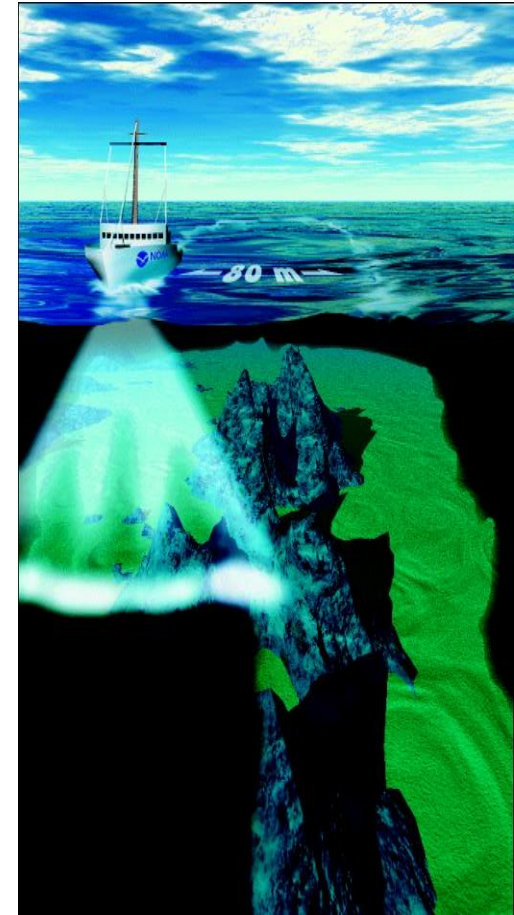
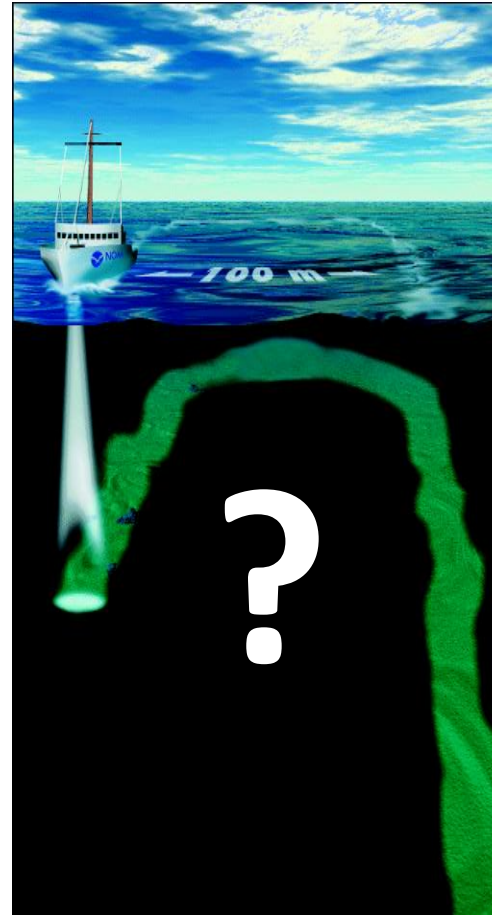
- Cable surveys
- Well site surveys

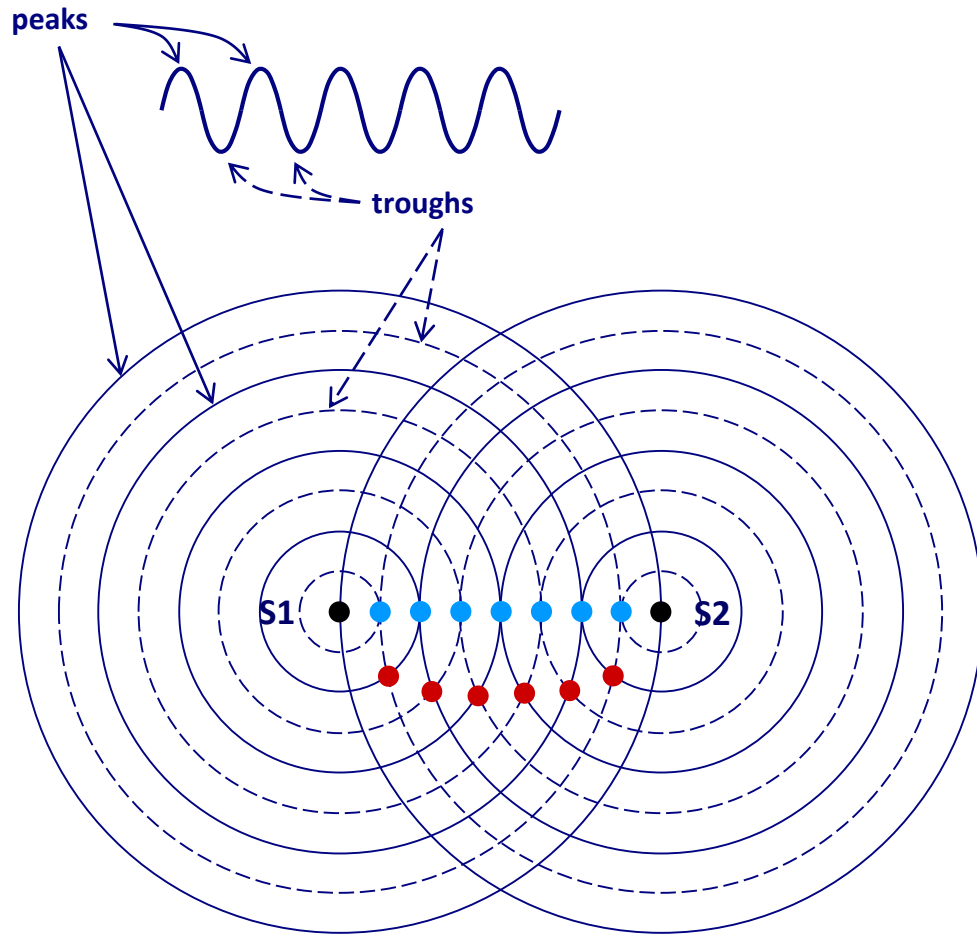


Loreto et al., 2013. Approaching the seismogenic source of the Calabria 8 September 1905 earthquake: New geophysical, geological and biochemical data from the S. Eufemia Gulf (S Italy). *Marine Geology* 343 (2013) 62–75.

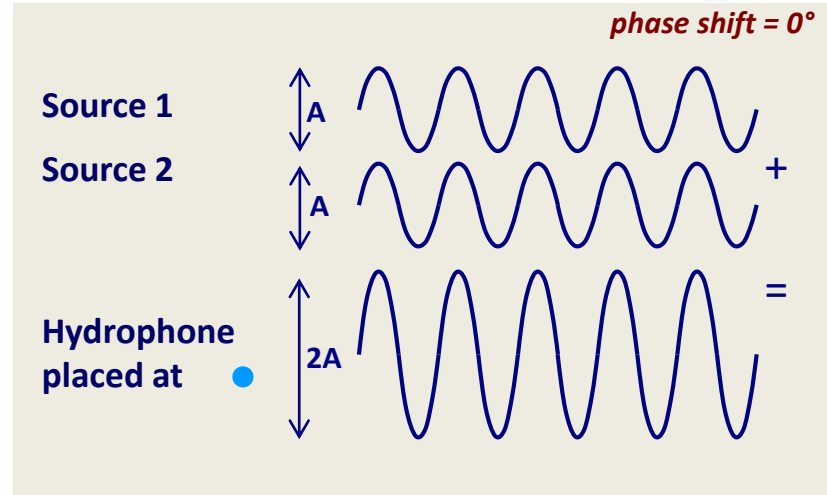
ADVANTAGES OF MBES COMPARED TO SBES

- ➔ Wide profile of depths in a line perpendicular to the ship's direction of travel.
- ➔ Total ensonification of the bottom possible
- ➔ Wider coverage in deeper water
- ➔ Backscatter imagery for bottom analyses
- ➔ Water column recorded

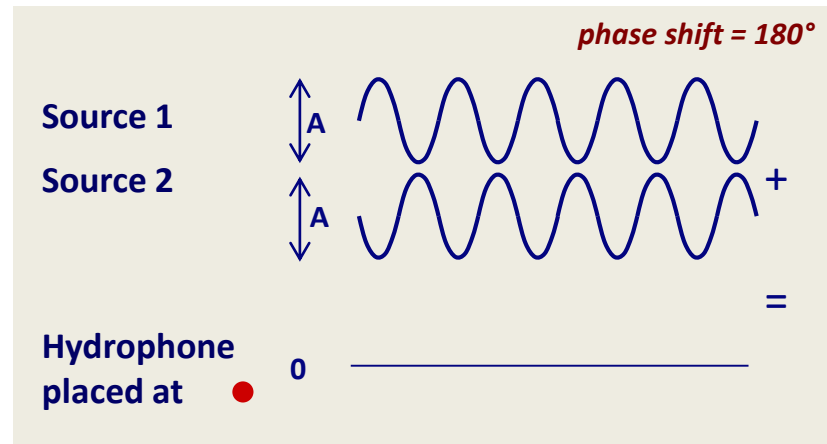




● CONSTRUCTIVE INTERFERENCE



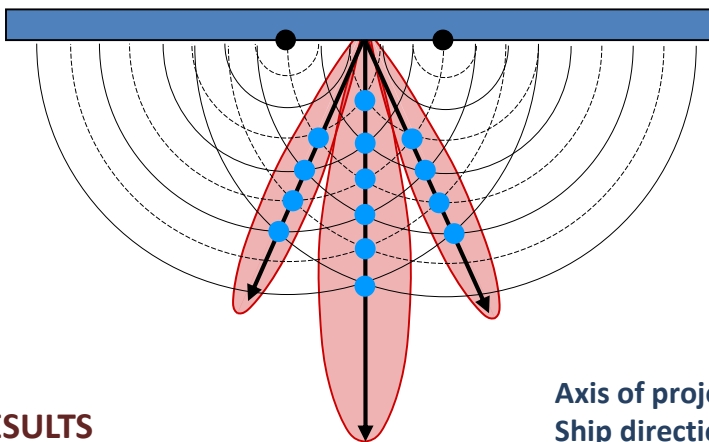
● DESTRUCTIVE INTERFERENCE



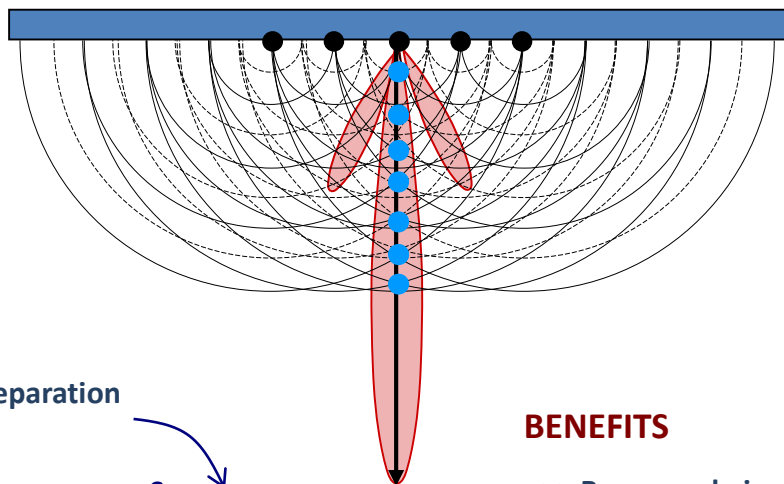
PROJECTORS AND RECEIVERS ARRAYS

FLAT ARRAYS

Two sources activated simultaneously



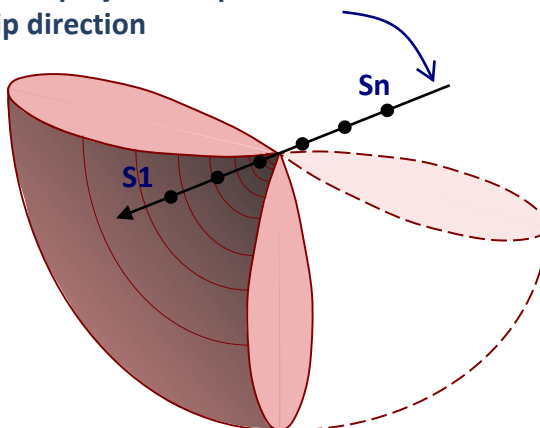
Adding more staves



RESULTS

- >> Directivity (90°)
- >> Sidelobes (undesirable side effect)

Axis of projector separation
Ship direction



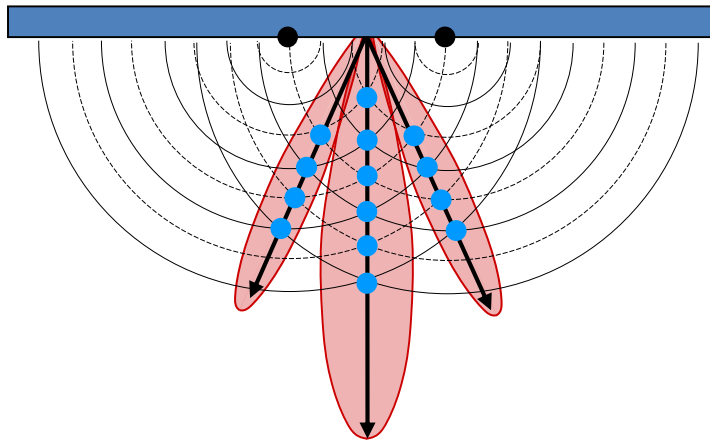
BENEFITS

- >> Beam angle improvement
- >> Reduced sidelobes
- >> Improved directivity
- >> Narrower beams > HR

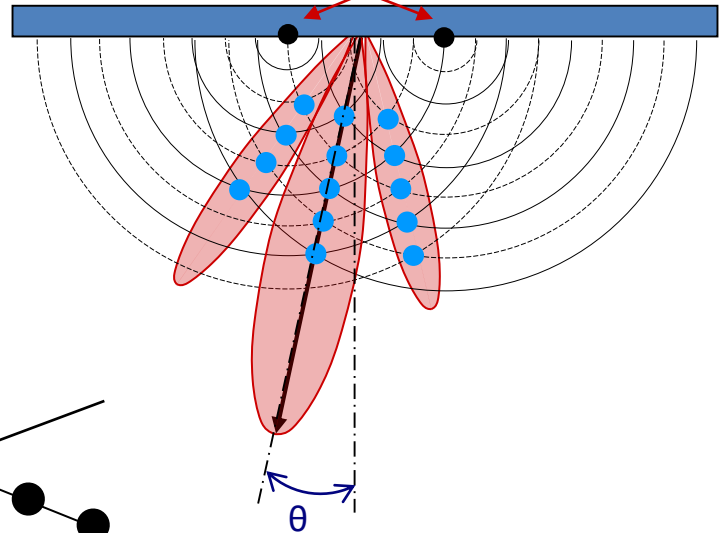
BEAMFORMING APPLIES TO BOTH PROJECTOR AND RECEIVERS ARRAYS

FLAT ARRAYS

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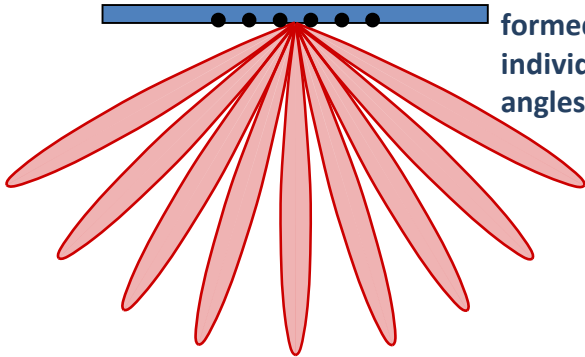


Phase shift (time delay) between staves

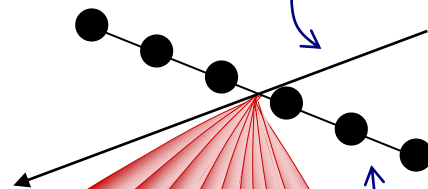


R1 Rn

Multiple simultaneously formed beams at individual steering angles

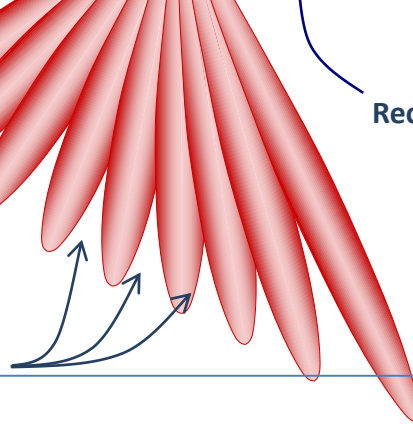


Ship direction



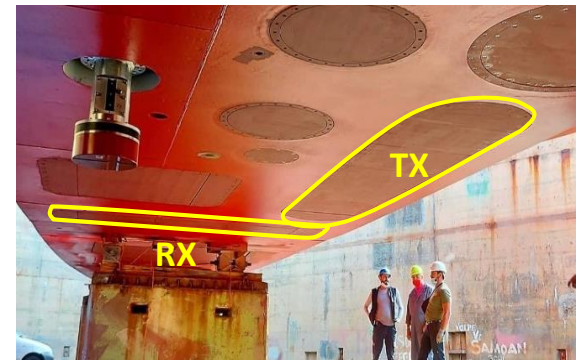
Receiver array Axis

Receive beams

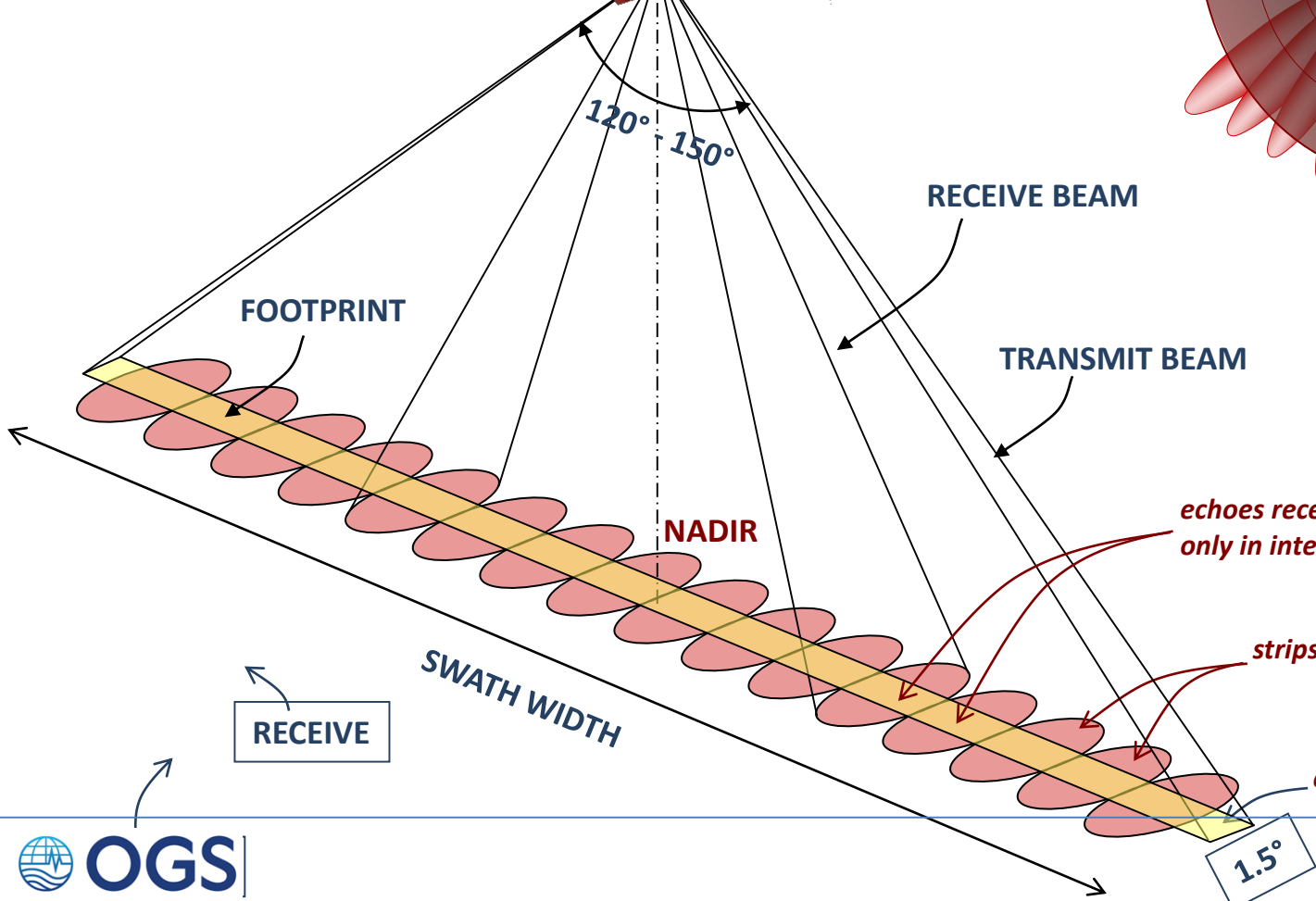
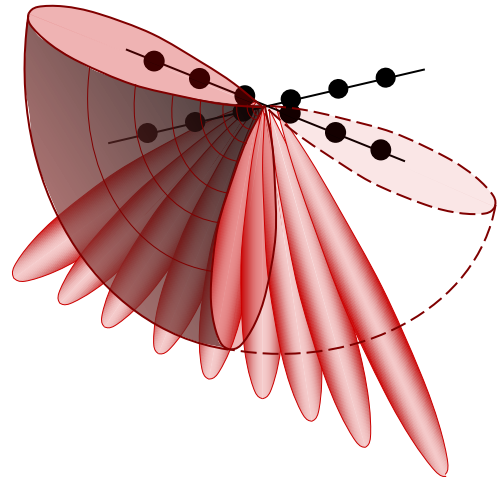


MULTIBEAM ECHOSOUNDER

THE T CONFIGURATION



detection



echoes received by each beam only in intersecting areas

strips observed by each beam

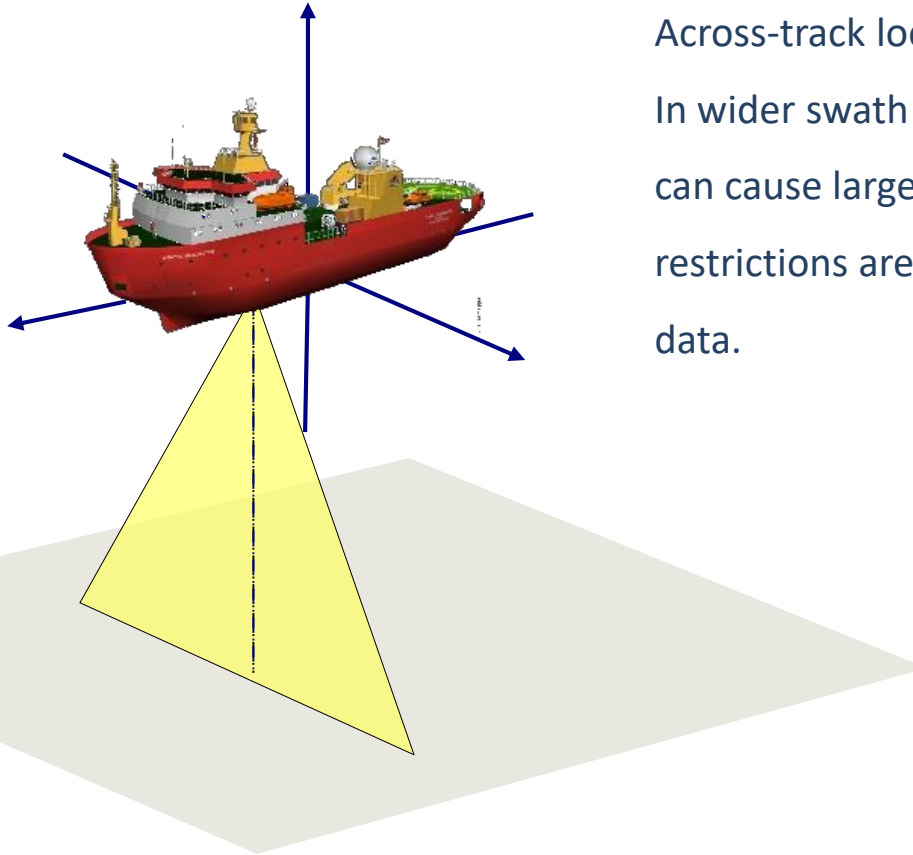
ensonified strip

Beam size = Resolution

DYNAMIC CORRECTIONS

Horizontal positioning accuracy is dependent upon the ability of the system to compensate for pointing errors caused by vessel roll, pitch, and yaw.

Across-track location of each bottom point is critical. In wider swath systems, even a small degree of roll can cause large errors in the outer beams; thus restrictions are typically placed on use of outer beam data.



Roll

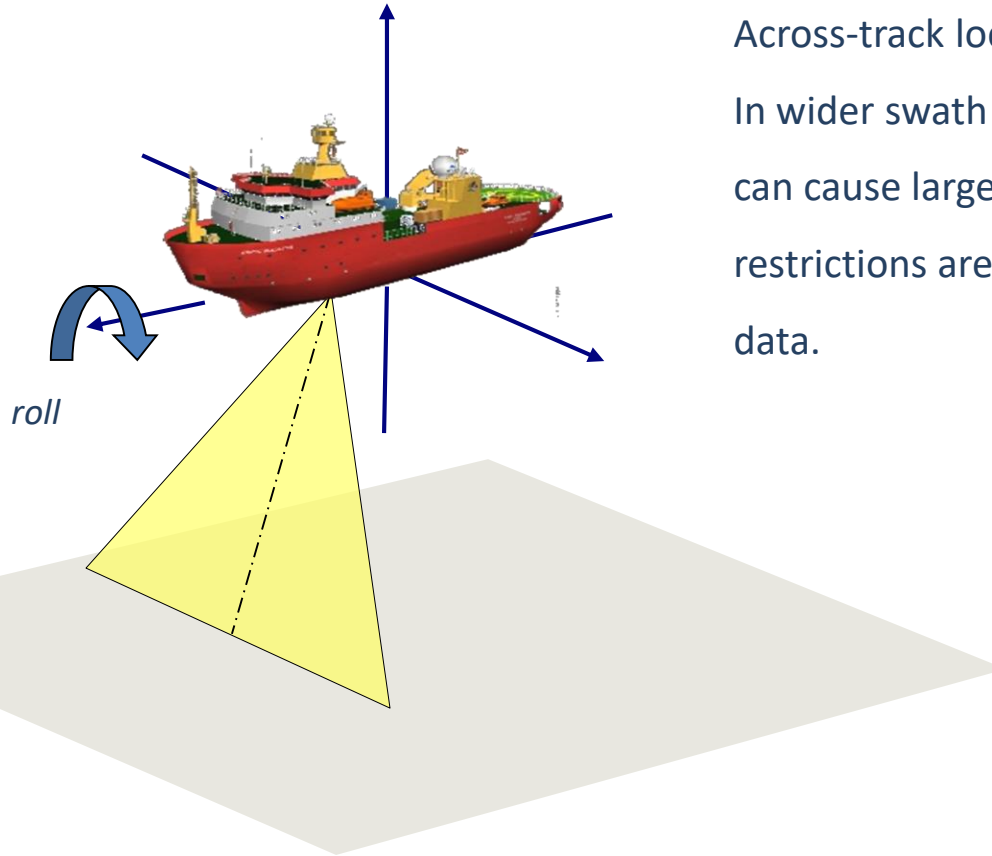
Pitch

Yaw

Heave

Positioning

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Roll

Pitch

Yaw

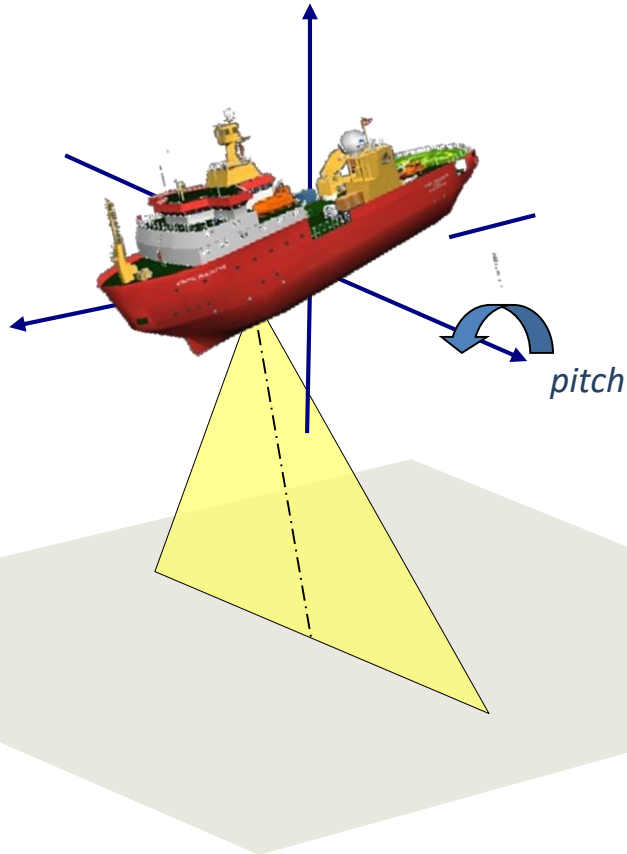
Heave

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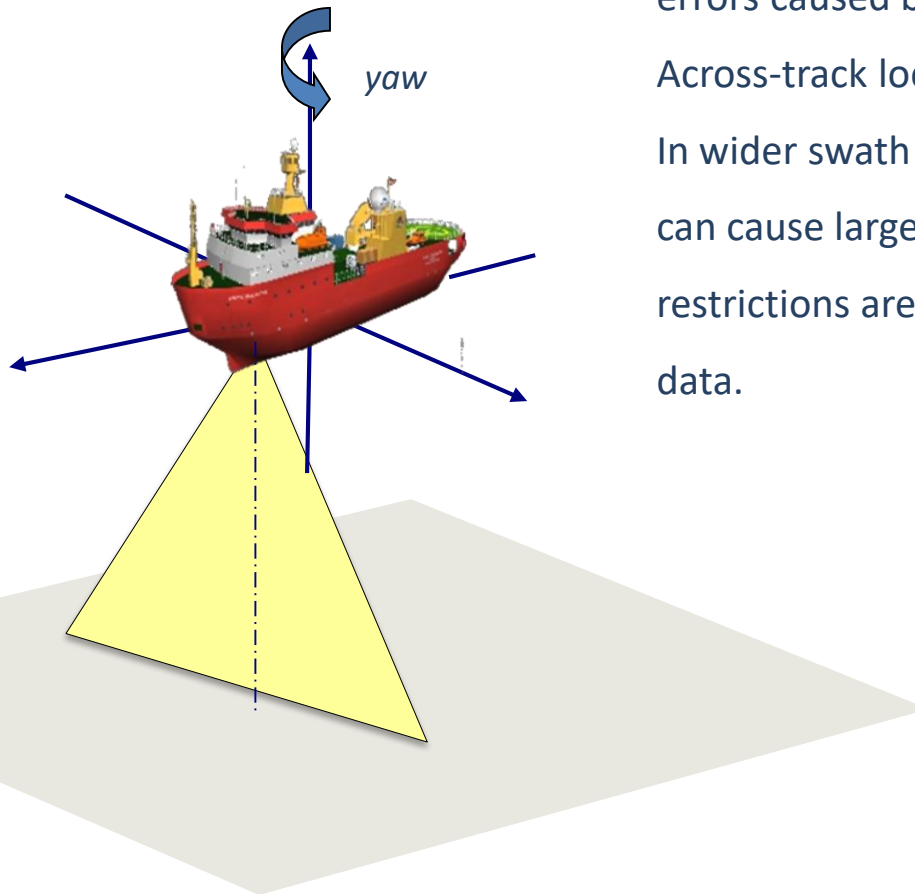
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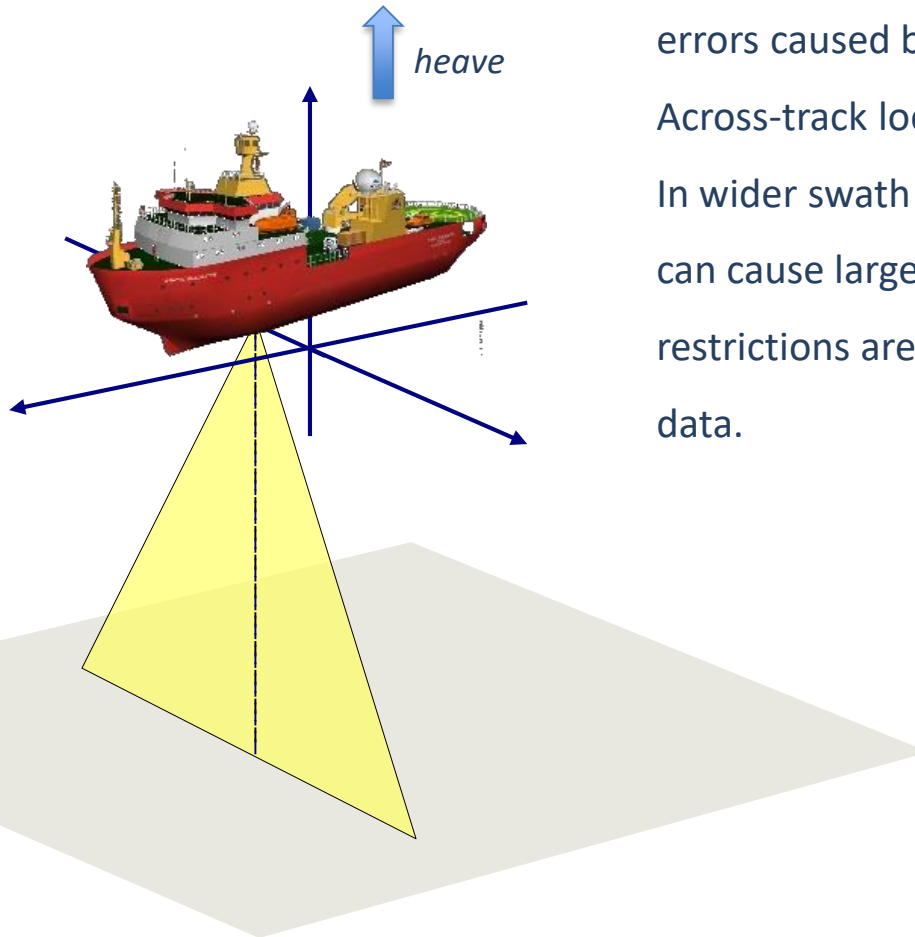
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Roll

Pitch

Yaw

Heave

Positioning

Sound velocity can vary considerably from point to point in the ocean

Vs is dependent on three main factors:

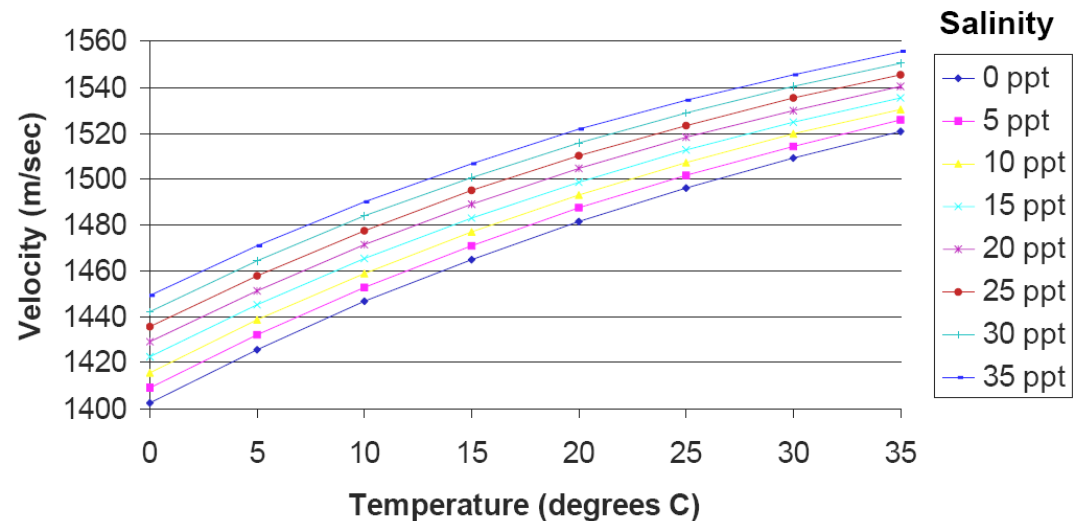
SALINITY

- Ranges from 32 - 38ppt (parts per thousand)
- A change in salinity causes a density variation which changes the sound propagation velocity
- Varies geographically (Baltic 7ppt, Dead Sea 300 ppt)
- Change of 1ppt = approx 1.3m/s velocity change

TEMPERATURE

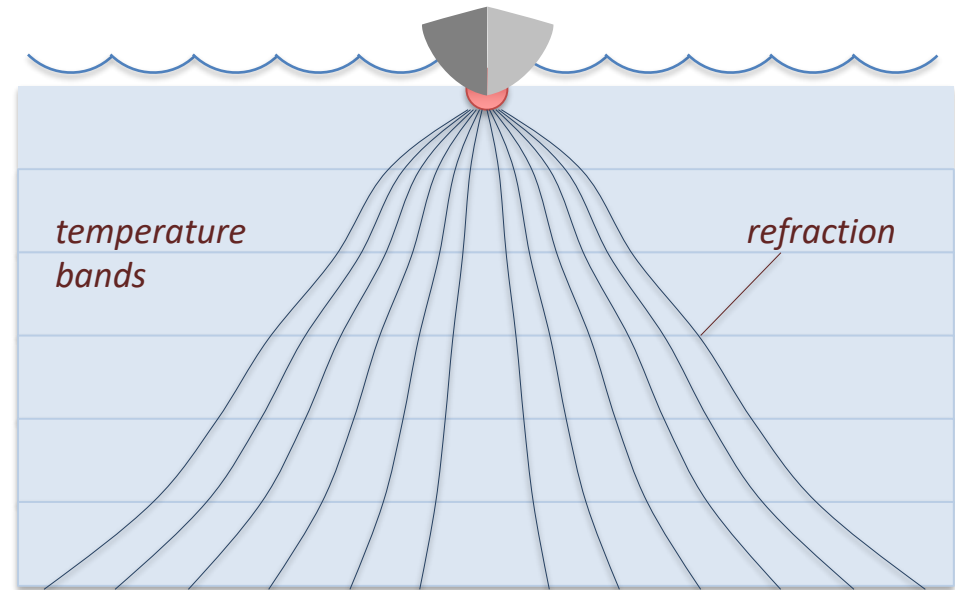
- Temperature usually decreases with depth
- A change of 1°C will change Vs by 3m/s
- Above 1000m water depth, temperature is the predominant influence on underwater sound velocity

Sound velocity (at surface)



RAY BENDING

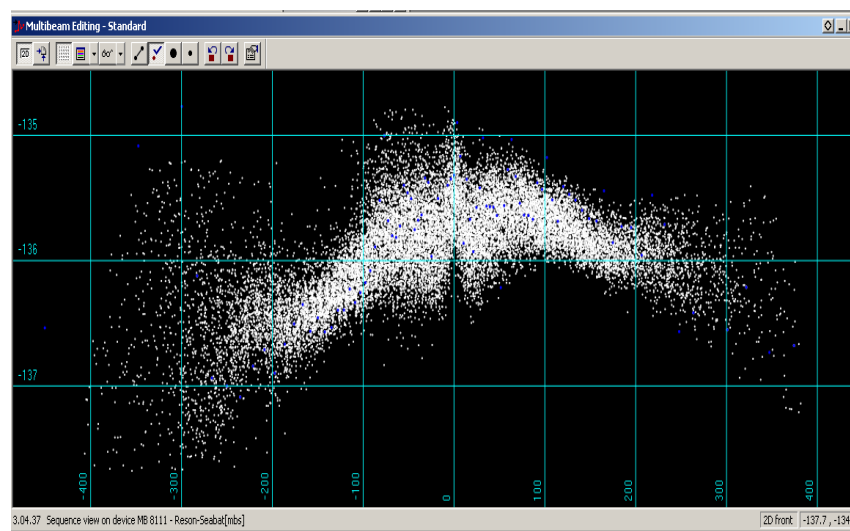
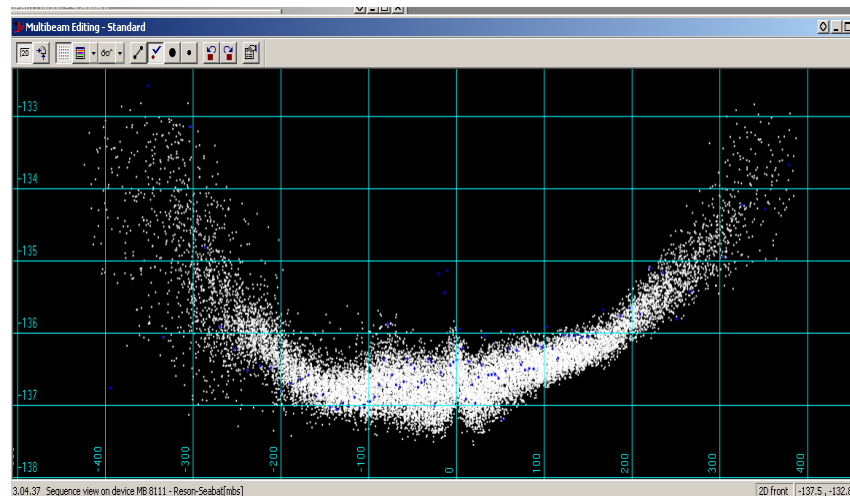
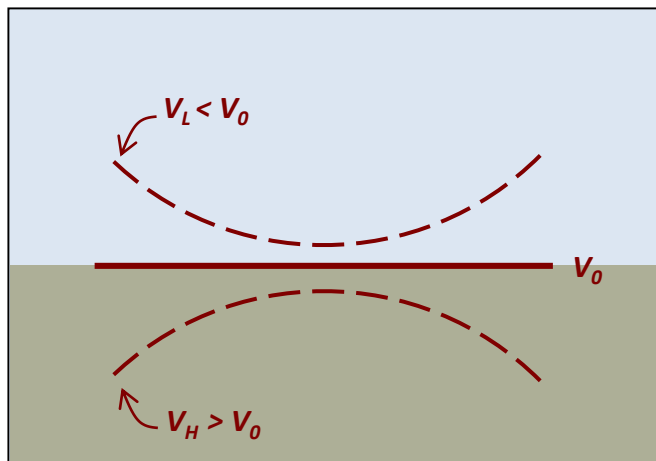
- MBES are dependent upon the two-way travel time of sound (i.e. sound velocity) in water
- The value for sound velocity in oceanic water is subject to changes associated with differences in density (primarily a function of temperature)
- Depending on the angle of beam travel, bending (refraction) can cause deviations in the travel path as a result of changes in density
- Generally, the greater the beam direction angle, the more likely the chances are for refraction



SMILES & FROWNS

Indicates errors in the sound velocity setting

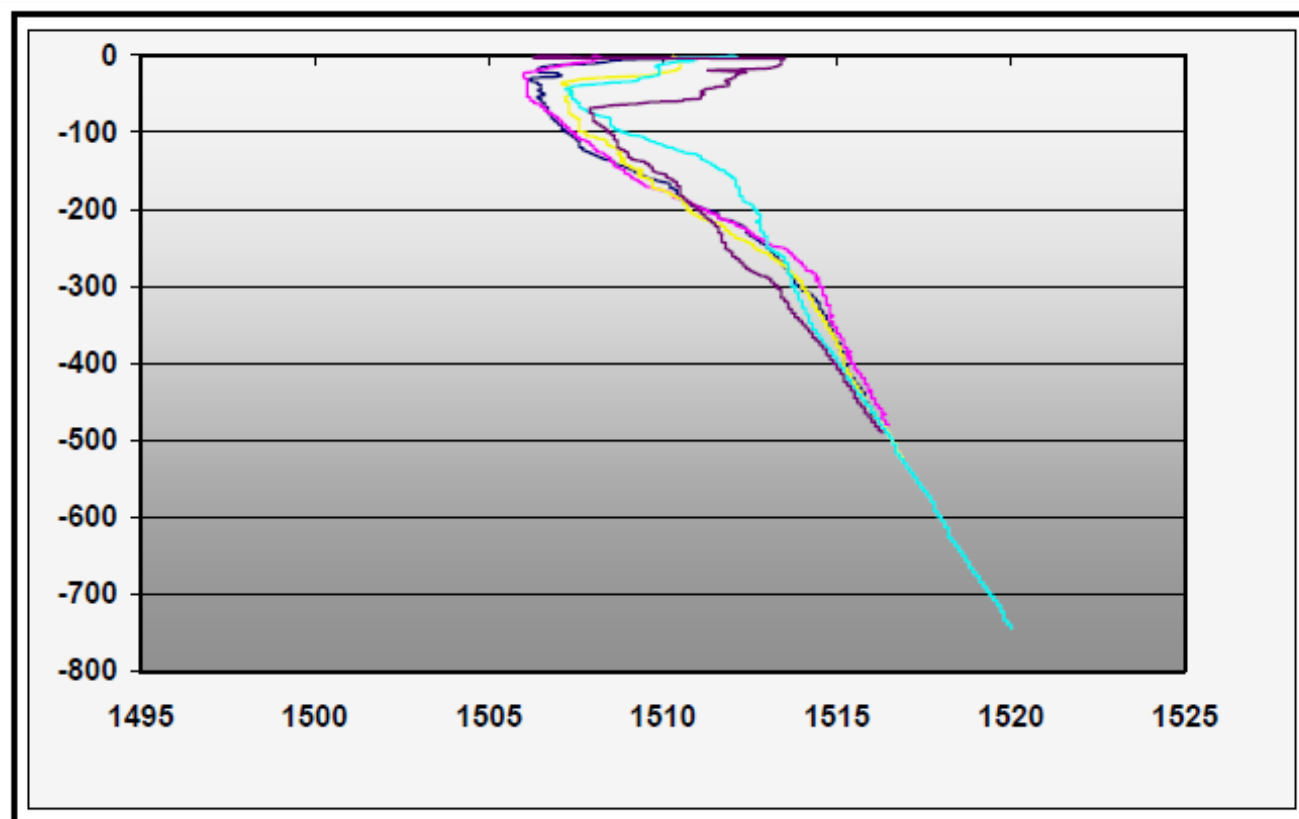
$$\text{Range} = \frac{1}{2} * V * \Delta t$$





SOUND VELOCITY PROBE

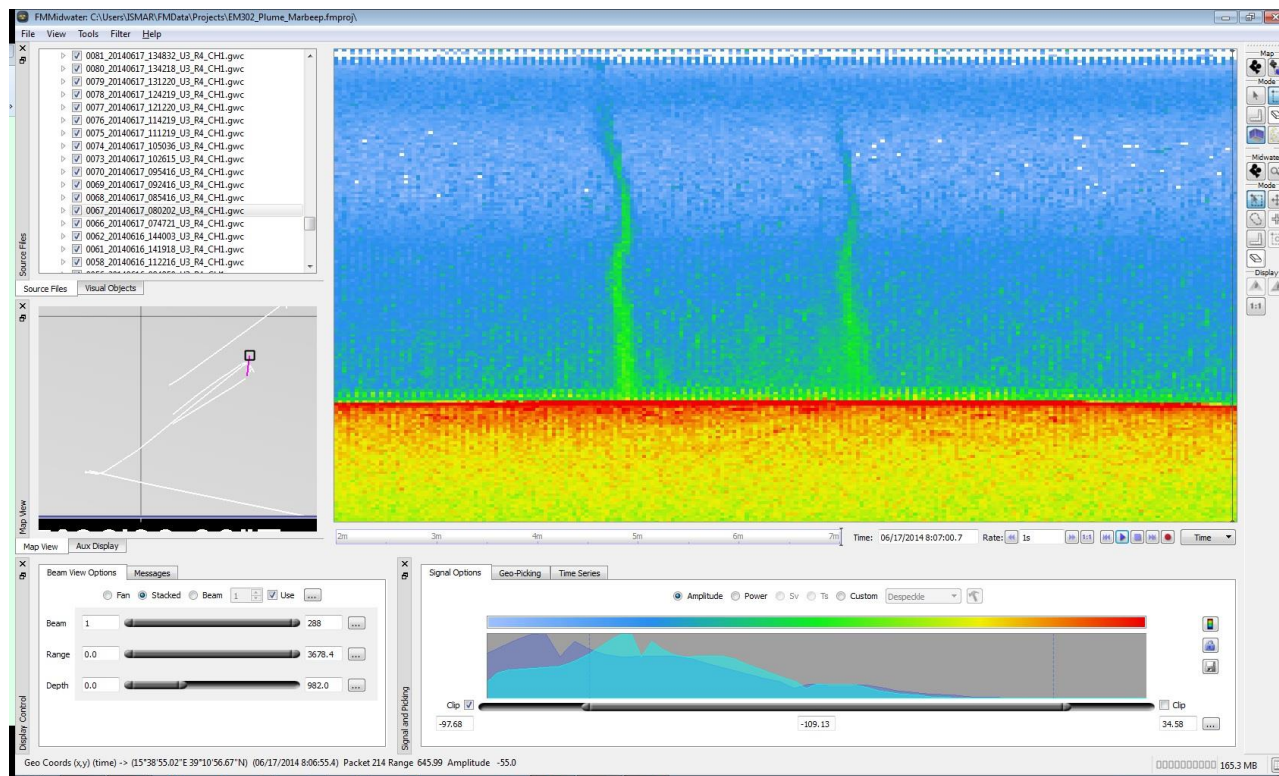
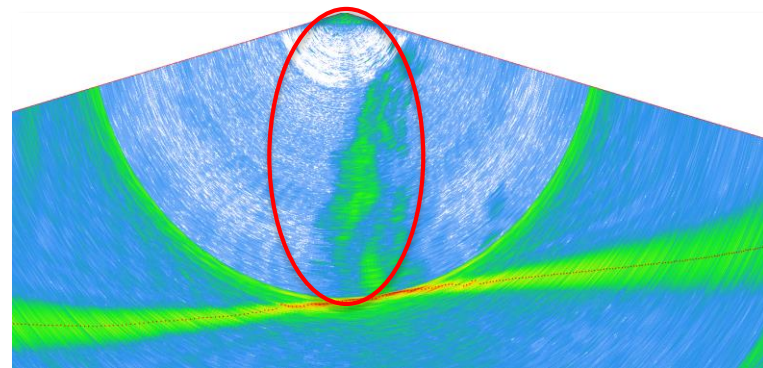
- Collects a profile of sound velocities at predetermined depth intervals
- Operates autonomously (no electrical cable)
- Data downloaded into computer and uploaded in the acquisition software

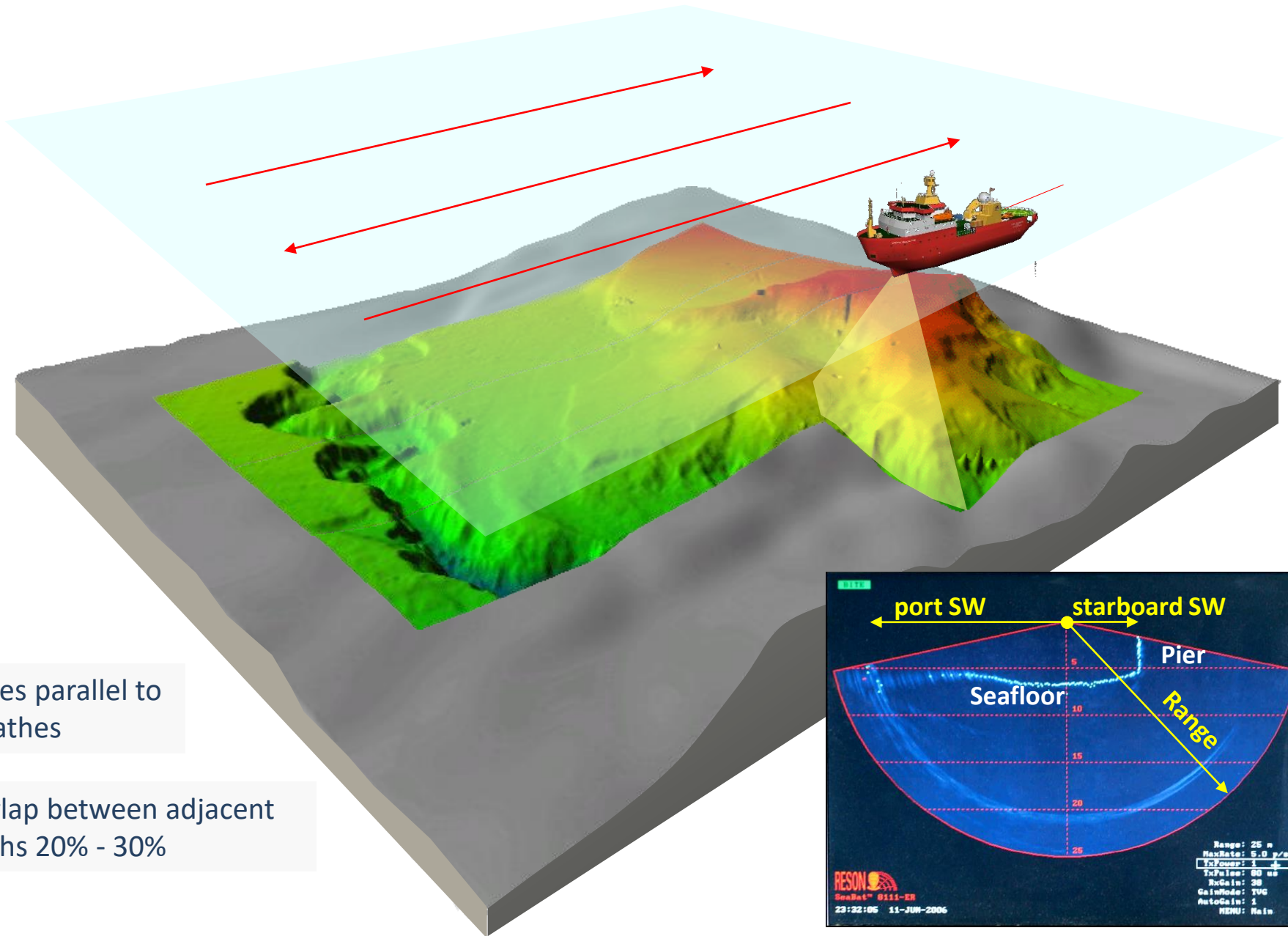


GAS PLUMES DETECTION

Stacked gas plumes detected in the water column by the EM302 multibeam system along a transect over a mud volcano. Rovere et al., 2014. Normal faults control fluid flow structures at the rear of the Calabrian Arc (Paola Ridge, southeastern Tyrrhenian Sea). GNGTS 2014.

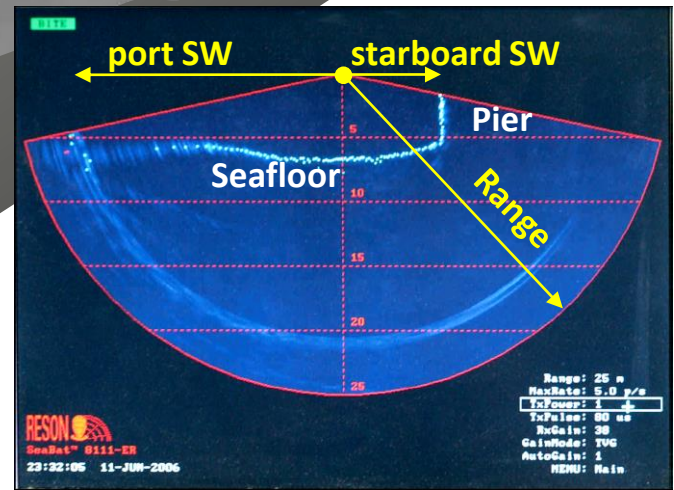
Raw sonar data

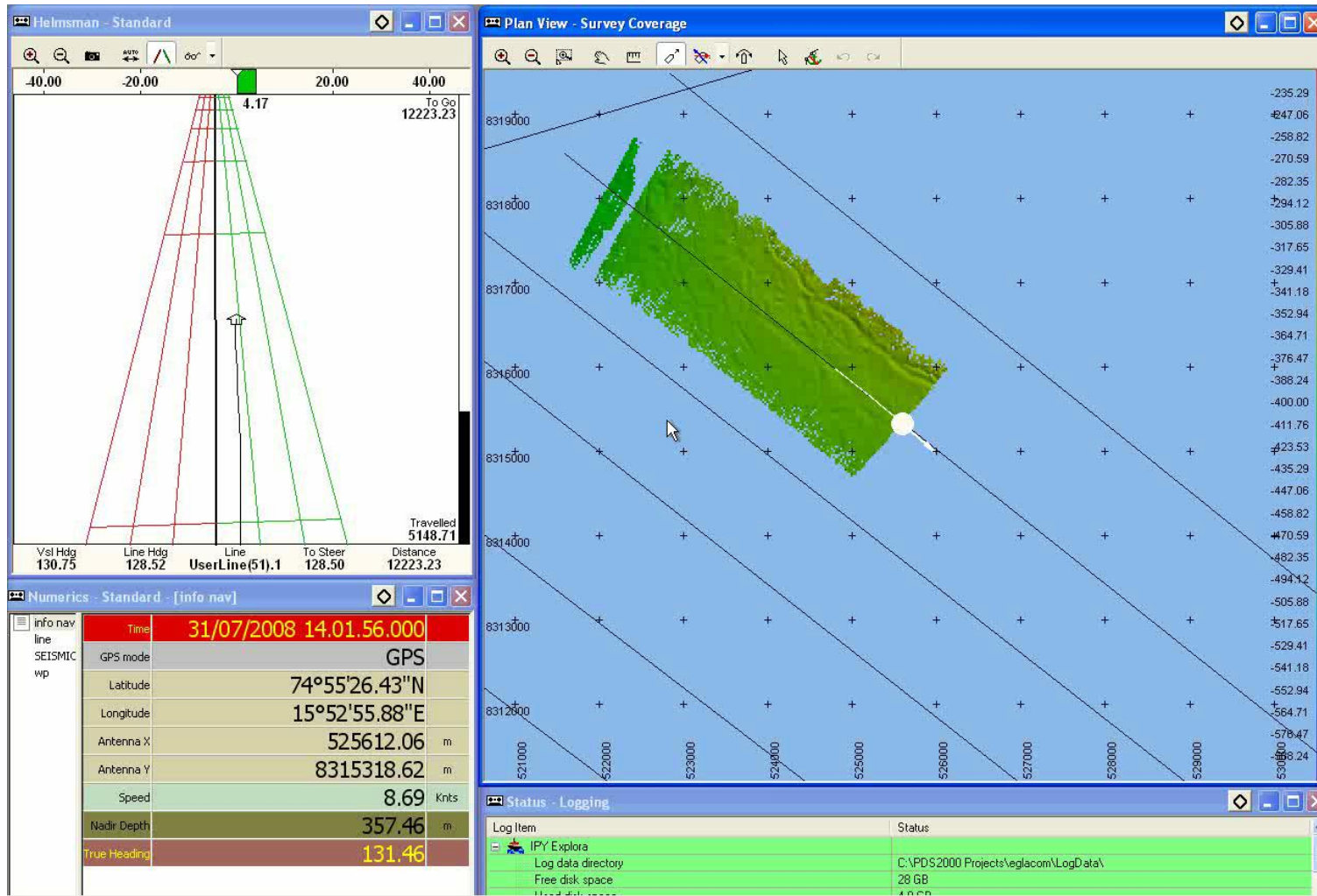


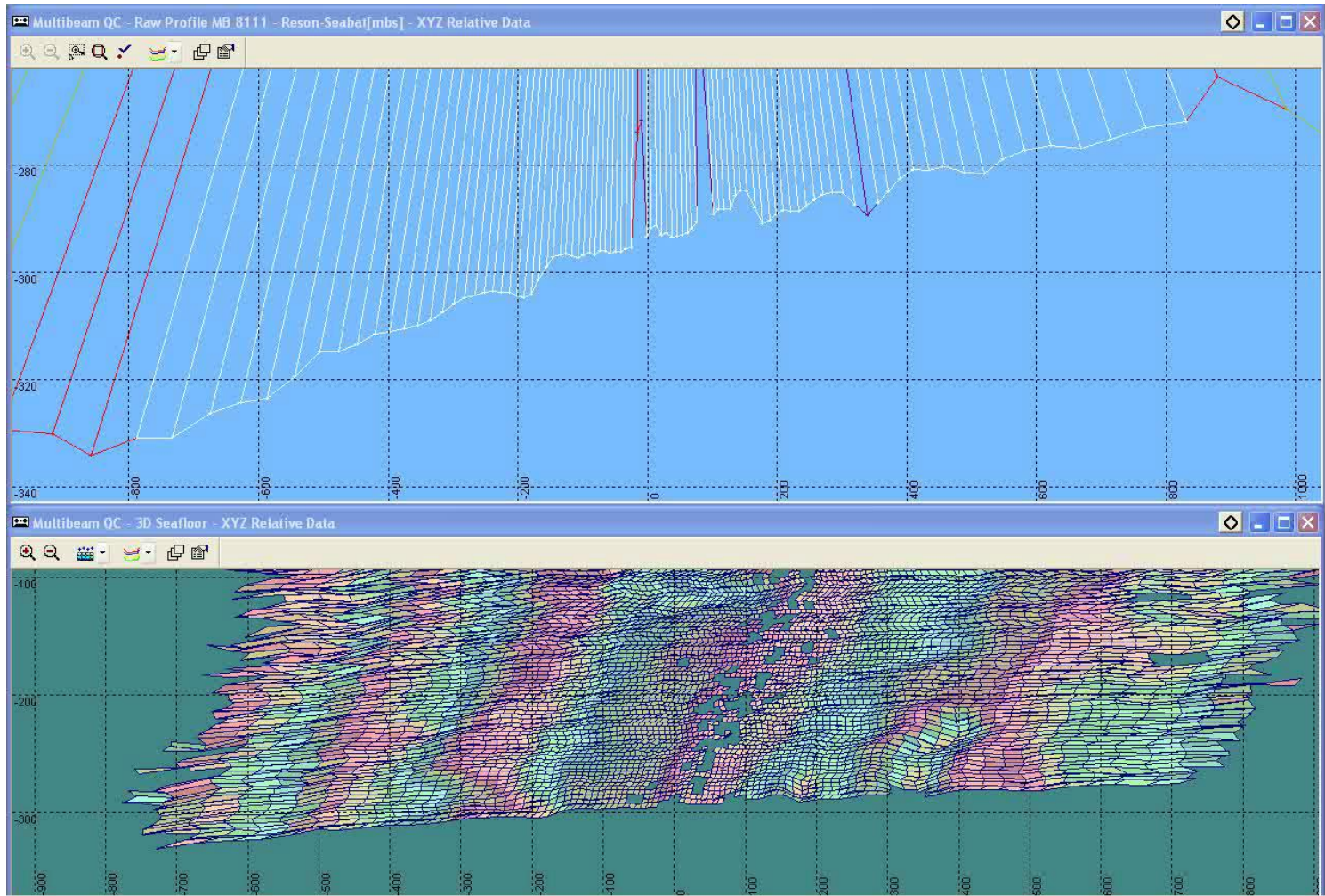


Routes parallel to isobathes

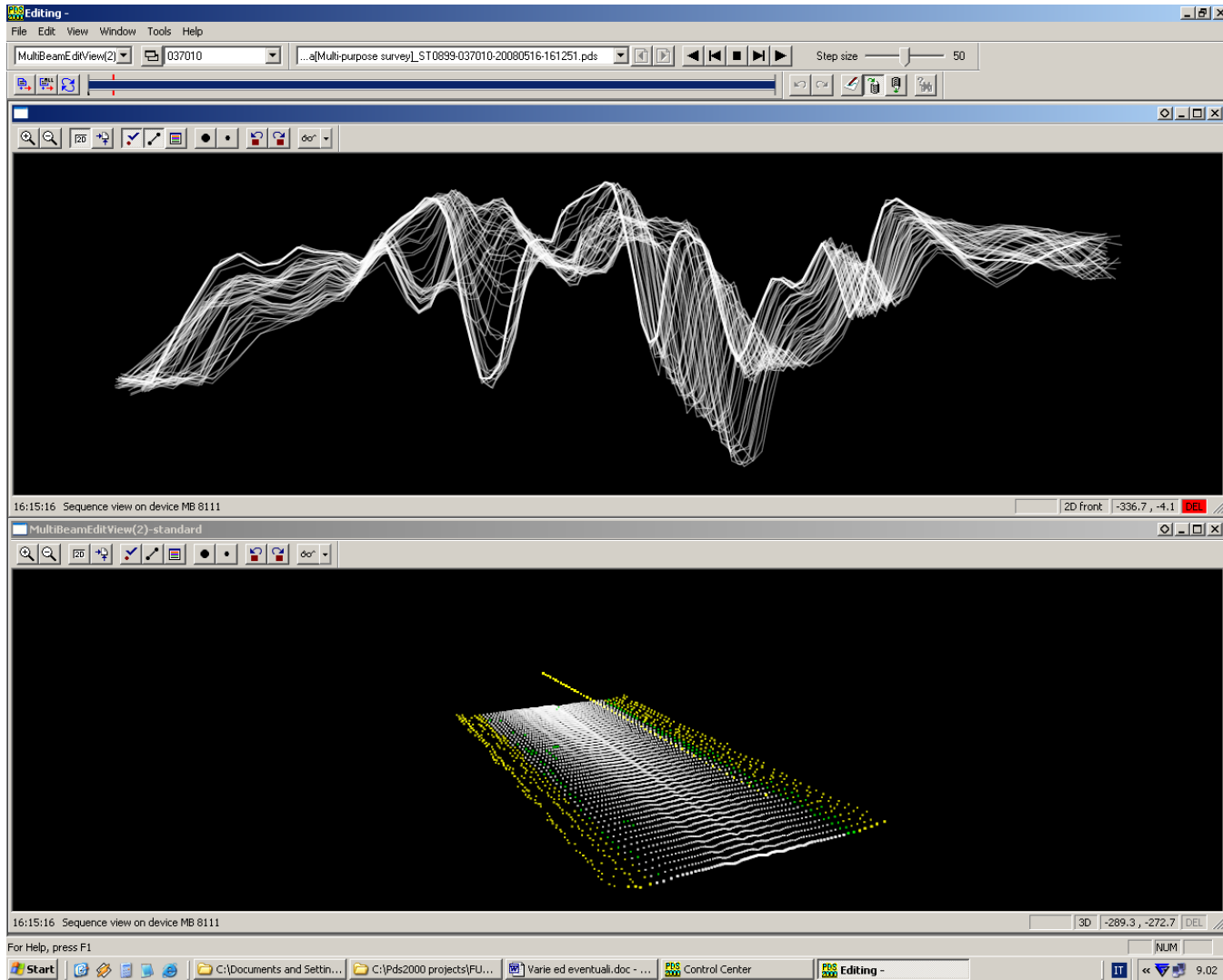
Overlap between adjacent swaths 20% - 30%



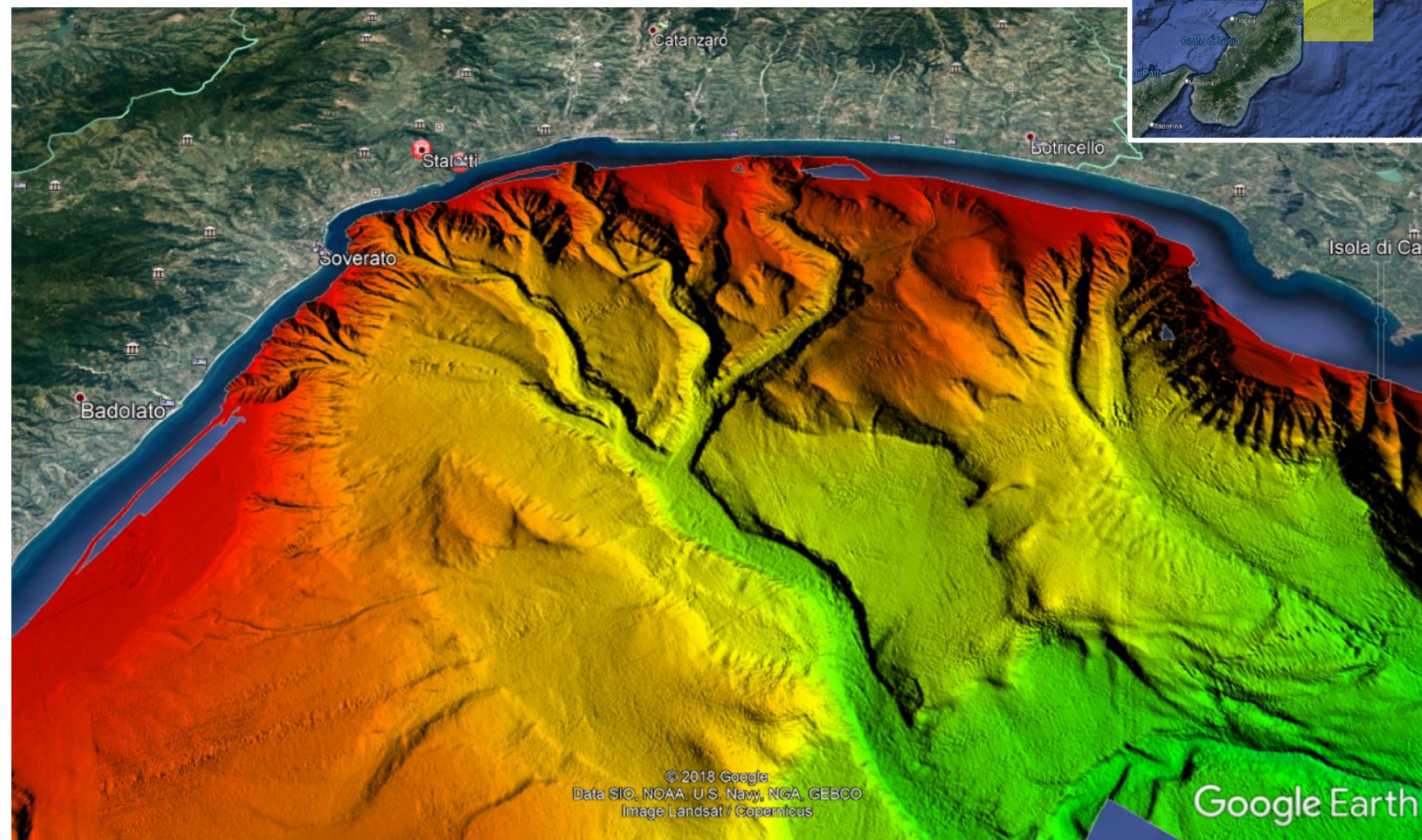
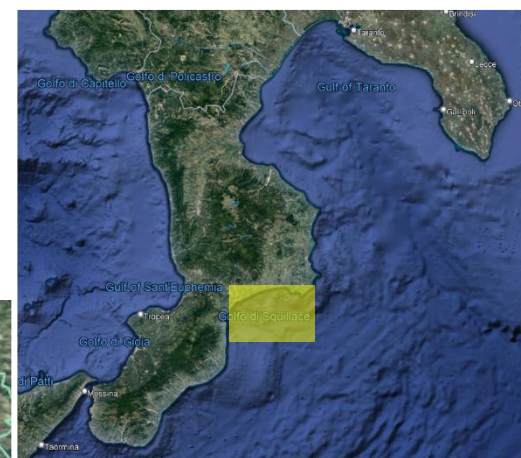




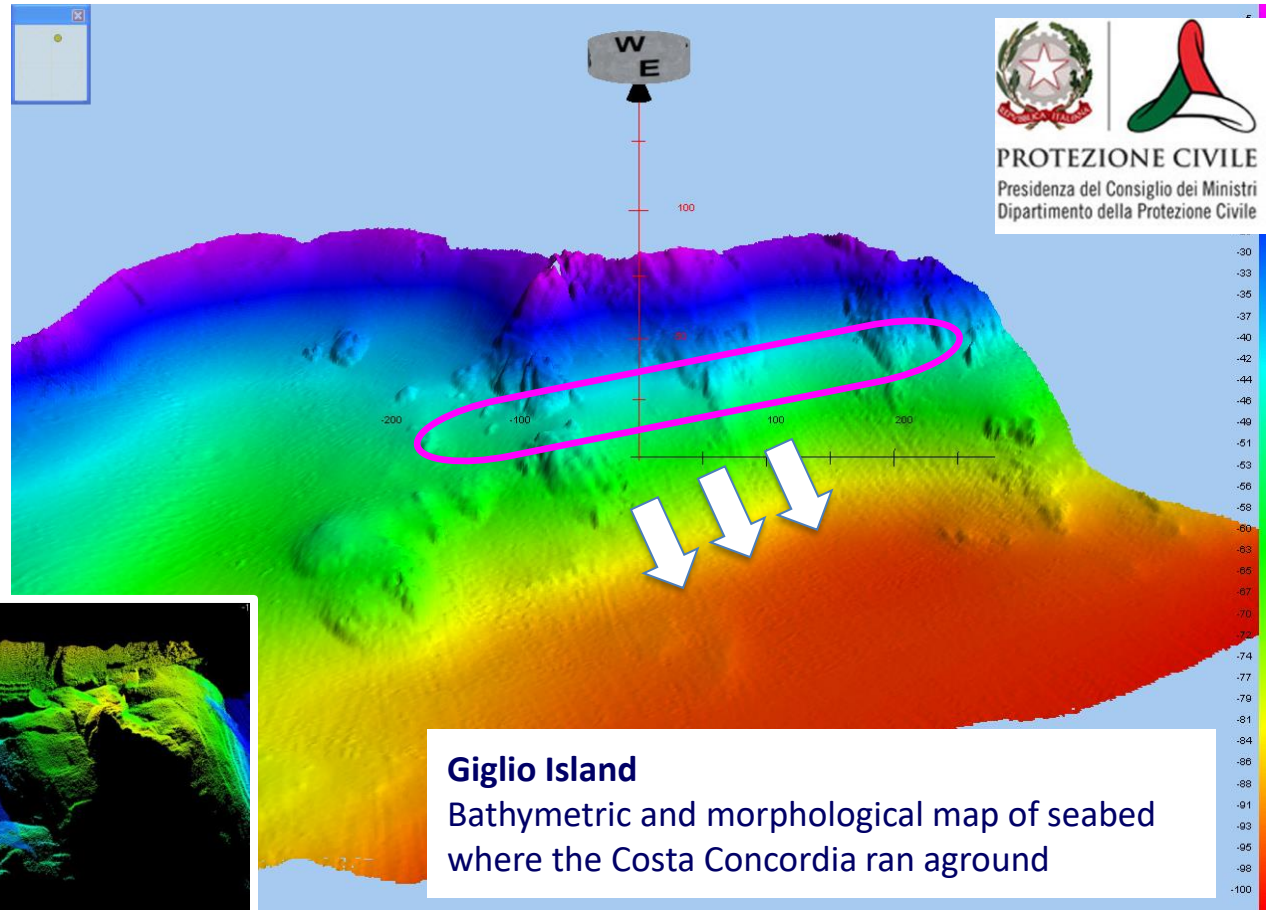
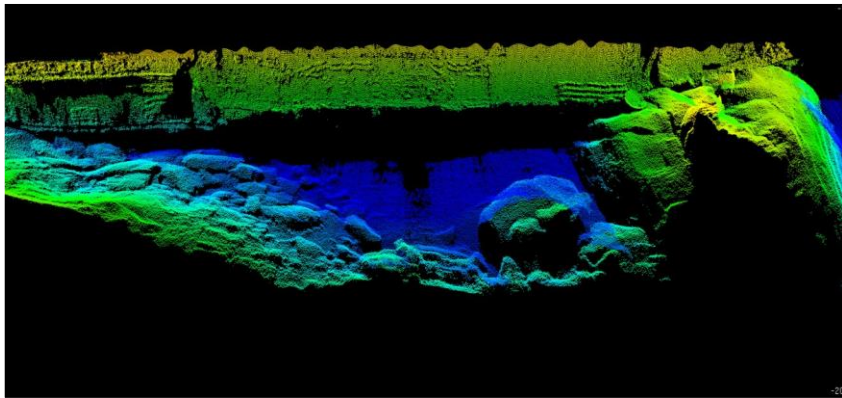
SWATH EDITING



GEO HAZARD: SUBMARINE CANYONS AS A THREAT TO COASTAL INFRASTRUCTURES



CIVIL PROTECTION: SLOPE STABILITY



Giglio Island

Bathymetric and morphological map of seabed where the Costa Concordia ran aground

Courtesy of D. Cotterle, E. Gordini, and M. Deponete, OGS, 2012

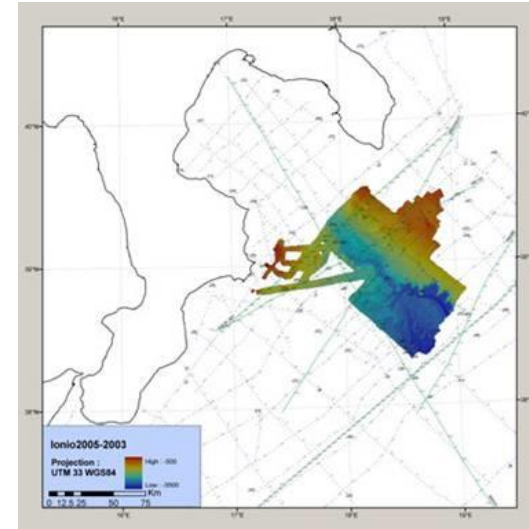
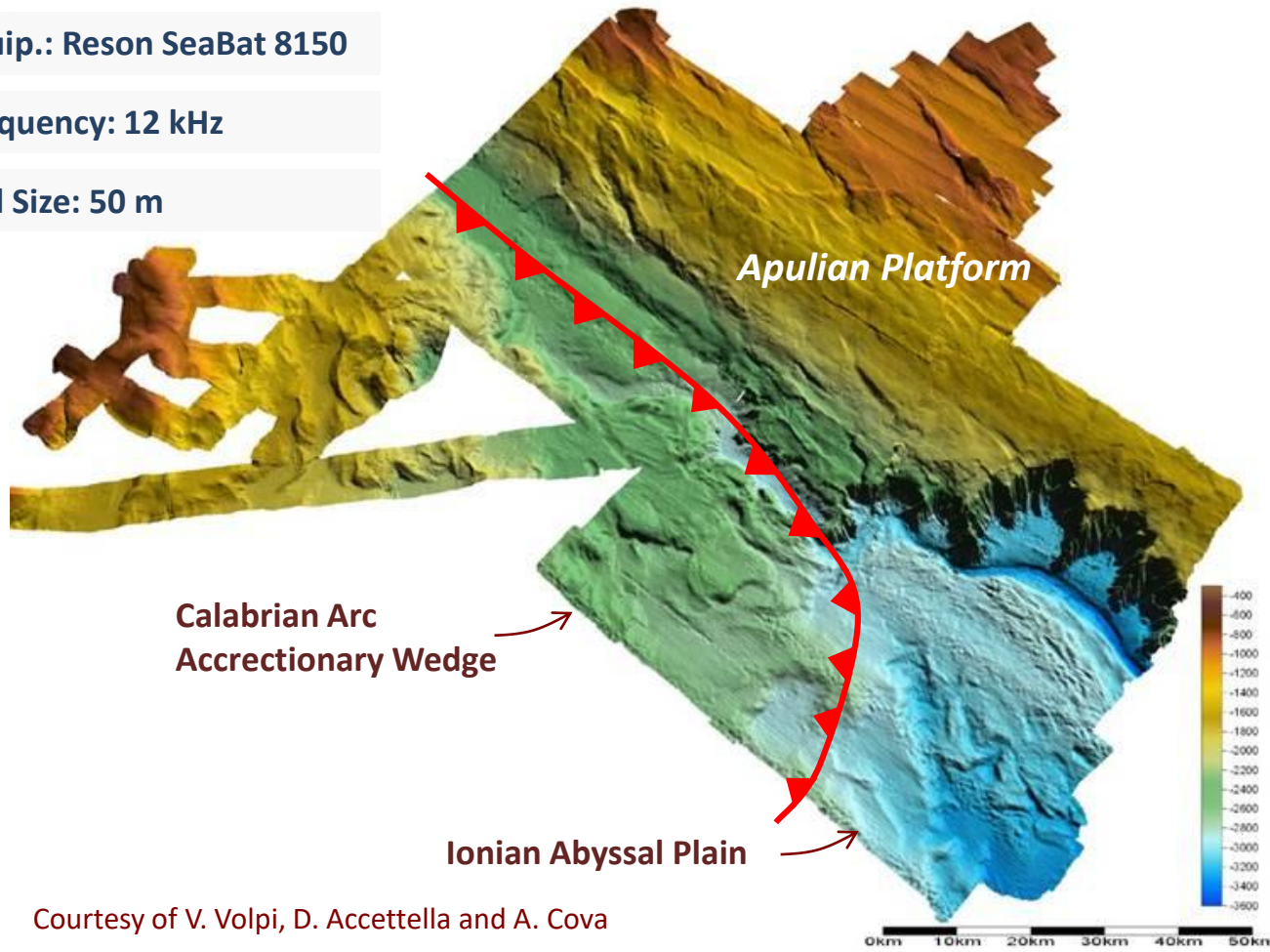
RESEARCH: GEODINAMIC STUDIES

M/V OGS Explora, 2003

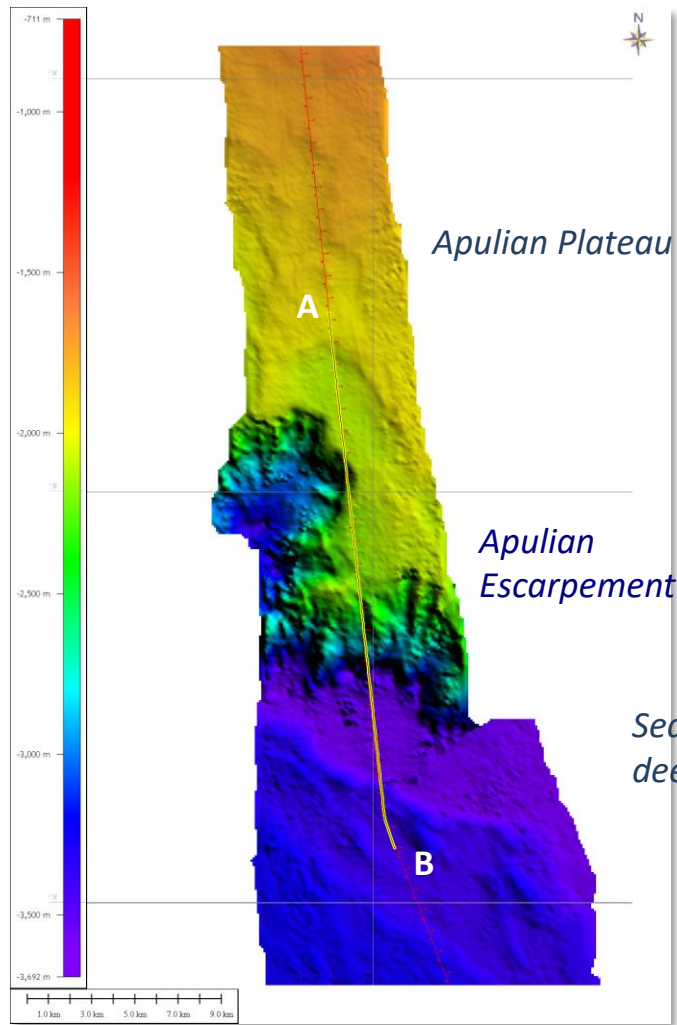
Equip.: Reson SeaBat 8150

Frequency: 12 kHz

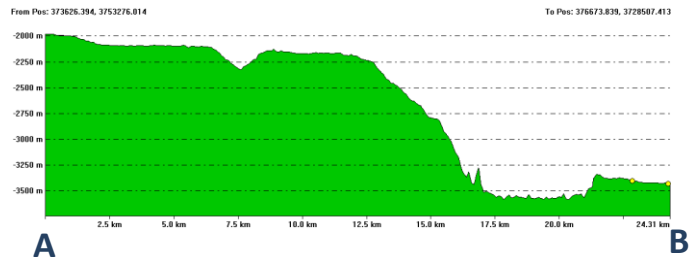
Cell Size: 50 m



Courtesy of V. Volpi, D. Accettella and A. Cova



Bathymetric profile



Avg. gradient = 25°
Max gradient >40°

