

19 maggio

$$f \in C^1(A, \mathbb{R})$$

$$A \subseteq \mathbb{R}^d$$

allora $Df \in C^0(A, \underbrace{\mathcal{L}(\mathbb{R}^d, \mathbb{R})}_{\mathbb{R}^d})$

e tale che $D^2f(x_0)$ entrerà in $x_0 \in A$

$$D^2f(x_0) = \left(\partial_i \partial_j f(x_0) \right)_{i,j=1}^d$$

matrice Hessian

$$\exists A \in SO(\mathbb{R}^d) \quad d \times d \quad t \leq$$

$$A^{-1} D^2f(x_0) A = {}^t A D^2f(x_0) A \\ = \text{diag}(\lambda_1, \dots, \lambda_d)$$

$$x = Ay + x_0$$

$$g(y) := f(Ay + x_0) \quad , \quad v \in \mathbb{R}^d$$

$$Dg(0)v = \frac{d}{dt} g(tv) \Big|_{t=0}$$

$$= \frac{d}{dt} f(Atv + x_0) \Big|_{t=0}$$

$$= Df(x_0) Av$$

$$\frac{d}{dt} Dg(\gamma + tv) \Big|_{t=0} = Dg(\gamma) v$$

$$= \frac{d}{dt} f(A\gamma + Atv + x_0) \Big|_{t=0}$$

$$= Df(A\gamma + x_0) Av$$

$$Dg(\gamma) v = Df(A\gamma + x_0) Av$$

$$D^2g(0)(v, v) = D^2g(0) v^2$$

$$= \frac{d}{dt} Dg(tv) v \Big|_{t=0} = {}^t v D^2g(0) v$$

$$= \frac{d}{dt} Df(Atv + x_0) Av \Big|_{t=0} =$$

$$= {}^t(Av) D^2f(x_0) Av$$

$$= {}^t v \left({}^t A D^2f(x_0) A \right) v$$

$$= {}^t v \left(\text{diag}(\lambda_1, \dots, \lambda_d) \right) v \quad D^2g(0)$$

$$= \sum_{j=1}^d \lambda_j v_j^2$$

Notare che ~~da~~ se x_0 è un punto
critico di f $Df(x_0) = 0$

$$\Leftrightarrow Dg(0) = Df(x_0) A$$

$$\Leftrightarrow Dg(0) = 0.$$

Ovviamente x_0 è un punto max/min
locale per f

$\Leftrightarrow 0$ è un punto max/min
locale per g

$$g(y) = f(Ay + x_0)$$

Consideriamo l'espressione di Taylor

$$g(y) = \sum_{|\alpha| \leq 2} \frac{1}{\alpha!} \partial^\alpha g(0) y^\alpha + o(|y|^2)$$

$$\left\{ \begin{array}{l} \alpha = (\alpha_1, \dots, \alpha_d) \\ \partial^\alpha = \partial_1^{\alpha_1} \dots \partial_d^{\alpha_d} \\ y^\alpha = y_1^{\alpha_1} \dots y_d^{\alpha_d} \\ \approx g(y) = g(0) + \sum_{j=1}^d \frac{1}{2} \partial_j^2 g(0) y^j + o(|y|^2) \end{array} \right.$$

$$\begin{array}{c} \partial_1^2 \\ \alpha = (2, 0, \dots, 0) \\ \alpha! = 2! \underbrace{0! \dots 0!}_{d-1} \end{array}$$

$$g(y) = g(0) + \sum_{j=1}^d \frac{1}{2} \lambda_j y^j + o(|y|^2)$$

Def $D^2 f(x^0)$ e' strett (positive) nonitro κ
 $\lambda_j > 0 \quad \forall j = 1, \dots, d$
 $(\lambda_j \geq 0)$

Def Diciamo che un punto critico

x_0 di f è non degenera e
 $D^2 f(x_0)$ è isomorfo $\mathbb{R}^d \ni$.

$$\overset{\uparrow}{L^2(\mathbb{R}^d, \mathbb{R})} \sim L(\mathbb{R}^d, \mathbb{R}^d)$$

Lemma $f \in C^1(A, \mathbb{R})$ $A \subseteq \mathbb{R}^d, x_0 \in A$

$D^2 f(x_0)$ esiste, $Df(x_0) = 0, x_0$

pt critico non degenera. Allora

- 1) $\lambda_j \neq 0 \quad \forall j = 1, \dots, d$
- 2) Se $D^2 f(x_0)$ è strett. positivo
 allora x_0 è un punto di min locale
- 3) Se $D^2 f(x_0)$ strett. neg. ...
 ... x_0 ... max locale
- 4) Se $\exists i \text{ e } j$ con $\lambda_i < 0 < \lambda_j$
 allora x_0 non è né un min
 né un max locale.

Dim 1) $\underbrace{\det D^2 f(x_0)}_{\neq 0} = \lambda_1 \dots \lambda_d$

$$\Leftrightarrow \lambda_j \neq 0 \quad \forall j$$

2) $D^2 f(x_0) \succ 0 \Rightarrow \lambda_j > 0 \quad \forall j$

$$0 < c_0 = \min \{ \lambda_1, \dots, \lambda_d \}$$

verifichiamo che 0 è un punto di
min locale per $g(y)$

$$g(y) = g(0) + \sum_{j=1}^d \frac{1}{2} \lambda_j y_j^2 + o(|y|^2)$$

$o(|y|^2)$ significa che $\forall$

$$\forall \varepsilon > 0 \quad \exists \delta_\varepsilon > 0 \quad \text{t.c.} \quad 0 < |y| < \delta_\varepsilon$$

$$\Rightarrow |o(|y|^2)| < \varepsilon |y|^2$$

$$\varepsilon = \frac{c_0}{4}$$

$$0 < |y| < \delta_\varepsilon$$

$$g(y) = g(0) + \sum_{j=1}^d \frac{1}{2} \lambda_j y_j^2 + o(|y|^2)$$

$$\geq f(0) + \frac{c_0}{2} |y|^2 - |o(|y|^2)|$$

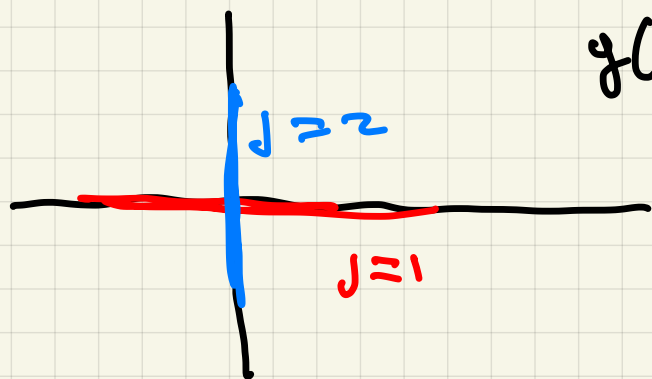
$$> f(0) + \frac{c_0}{2} |y|^2 - \frac{c_0}{4} |y|^2$$

$$= f(0) + \frac{c_0}{4} |y|^2 > f(0)$$

$\Rightarrow$ e' un punto di minimo

4) Possiamo supporre $\lambda_1 > 0$ e $\lambda_2 < 0$

$$h_j(t) = f(te_j) \quad j=1, 2$$



$$f(y) = f(0) + \sum \frac{1}{2} \lambda_j y_j^2 + o(|y|^2)$$

$$h_1(t) = f(te_1) =$$

$$= f(0) + \frac{\lambda_1}{2} t^2 + o(t^2)$$

$$h_2(t) = f(te_2) = f(0) + \frac{\lambda_2}{2} t^2 + o(t^2)$$

$$c_0 = \min \{ \lambda_1, -\lambda_2 \}$$

$$h_1(t) \geq f(0) + \frac{c_0}{2} t^2 - |o(t^2)|$$

$$h_2(t) \leq f(0) - \frac{c_0}{2} t^2 + |o(t^2)|$$

$$\varepsilon = \frac{c_0}{4} \quad 0 < |t| < \delta_\varepsilon$$

$$|o(t^2)| < \frac{c_0}{4} t^2$$

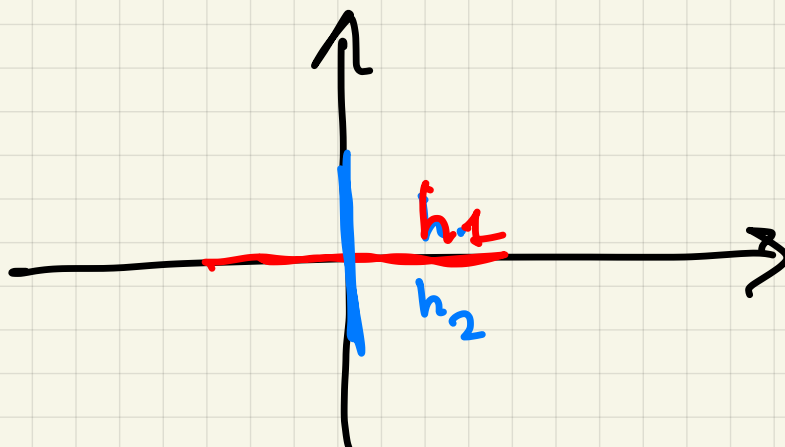
$$0 < |t| < \delta_\varepsilon$$

$$h_1(t) \geq f(0) + \frac{c_0}{2} t^2 - \frac{c_0}{4} t^2 =$$

$$= f(0) + \frac{c_0}{4} t^2 \Rightarrow t=0 \text{ è punto di } \text{min}$$

$$h_2(t) < f(0) - \frac{c_0}{2} t^2 + \frac{c_0}{4} t^2 = f(0) - \frac{c_0}{4} t^2$$

$$\Rightarrow t=0 \text{ è punto di } \text{max}$$



$$f(x, y) = \frac{x^4}{4} - \frac{x^3}{3} - x^2 + y^4 + y^2$$

$$\lim_{(x, y) \rightarrow \infty} f(x, y) = \lim_{(x, y) \rightarrow \infty} \left(\frac{x^4}{4} + y^4 \right) = +\infty$$

$$\begin{cases} \partial_x f = x^3 - x^2 - 2x = x(x^2 - x - 2) = 0 \\ \partial_y f = 4y^3 + 2y = 2(2y^2 + 1)y = 0 \end{cases}$$

$$x = 0 \quad x_{\pm} = \frac{1}{2} \pm \frac{\sqrt{9}}{2} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

$$y = 0$$

$$(0, 0), \quad (2, 0) \quad (-1, 0)$$

$$\begin{aligned} H_f(x, y) &= \begin{pmatrix} \partial_x^2 f & 0 \\ 0 & \partial_y^2 f \end{pmatrix} = \\ &= \begin{pmatrix} 3x^2 - 2x - 2 & 0 \\ 0 & 12y^2 + 2 \end{pmatrix} \end{aligned}$$

$$H_f(0, 0) = \begin{pmatrix} -2 & 0 \\ 0 & 2 \end{pmatrix} \quad \text{selb}$$

$$H_f(-1, 0) = \begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix} \text{ not min loc}$$

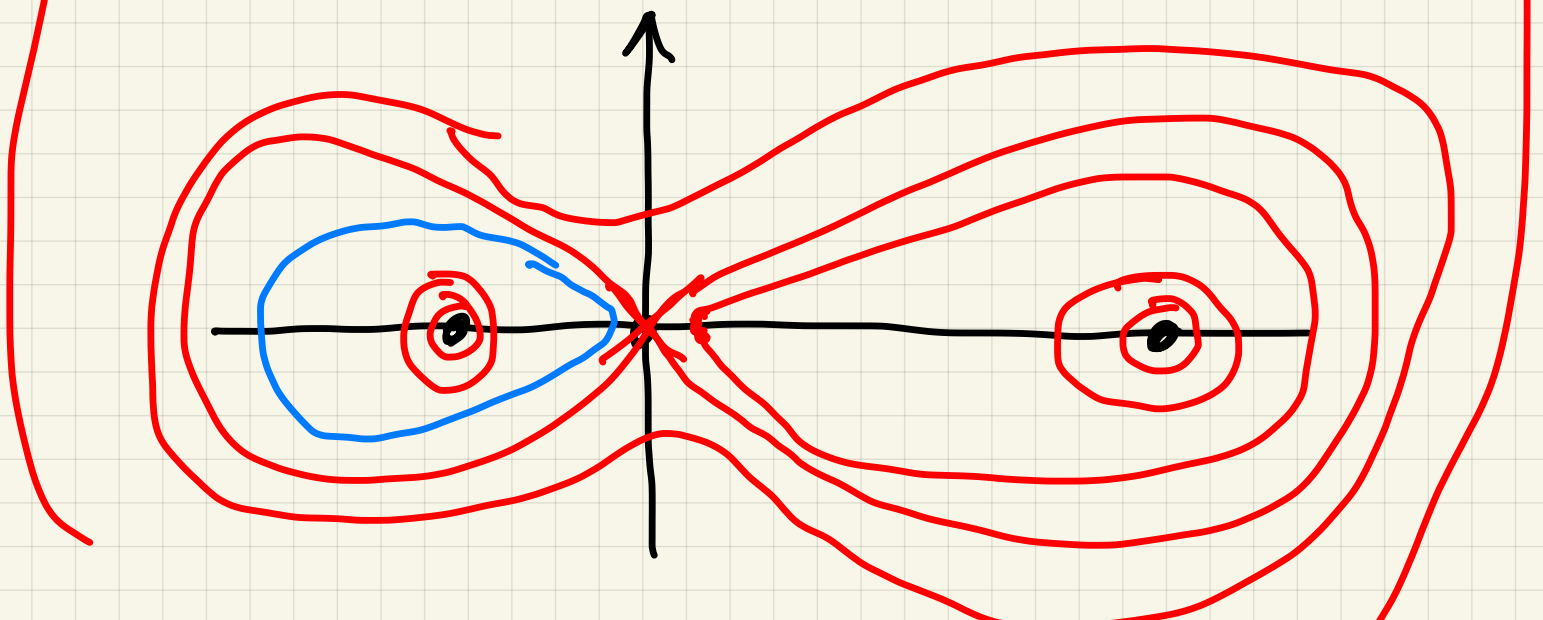
$$H_f(2, 0) = \begin{pmatrix} 6 & 0 \\ 0 & 2 \end{pmatrix} \text{ not min loc}$$

$$f(x, y) = \frac{x^4}{4} - \frac{x^3}{3} - x^2 + y^4 + y^2$$

$$f(-1, 0) = \frac{1}{4} + \frac{1}{3} - 1 = \frac{3+4}{12} - 1 = -\frac{5}{12}$$

$$f(2, 0) = -\frac{8}{3}$$

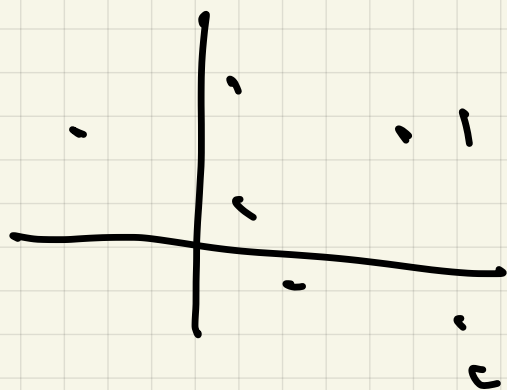
$(2, 0)$ not min absolute



Beispiel

$(x_1, y_1), \dots, (x_n, y_n)$

non aligned



$$\left| \frac{ax_j - y_j + b}{\sqrt{a^2 + 1}} \right|$$

$$y = ax + b$$

$$ax - y + b = 0$$

$$f(a, b) = \sum_{j=1}^n (ax_j + b - y_j)^2$$

$$\begin{aligned} &= a^2 \underbrace{\sum_{j=1}^n x_j^2}_P + nb^2 + \underbrace{\sum_{j=1}^n y_j^2}_Q \\ &\quad + 2ab \underbrace{\sum_{j=1}^n x_j}_X - 2a \underbrace{\sum_{j=1}^n x_j y_j}_S - 2b \underbrace{\sum_{j=1}^n y_j}_Y \end{aligned}$$

$$f(a,b) = a^2 P + b^2 m + Q + 2Xab - 2Sa - 2by$$

$$f_a = 2(aP + bX - S) = 0$$

$$f_b = 2(aX + mb - y) = 0$$

$$\begin{cases} aP + bX = S \\ aX + mb = y \end{cases}$$

$$\begin{pmatrix} P & X \\ X & m \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} S \\ y \end{pmatrix}$$

$$\begin{pmatrix} a \\ b \end{pmatrix} = \frac{1}{Pm - X^2} \begin{pmatrix} m & -X \\ -X & P \end{pmatrix} \begin{pmatrix} S \\ y \end{pmatrix}$$

$$mP - X^2 > 0$$

$$\boxed{mP - X^2} = m \sum_{j=1}^n x_j^2 - \left(\sum_{j=1}^n x_j \right)^2 =$$

$$= m \sum_{j=1}^n x_j^2 - \sum_{j,k=1}^n x_j x_k$$

$$> m \sum_{j=1}^n x_j^2 - \sum_{j,k=1}^n \frac{x_j^2 + x_k^2}{2}$$

$$\begin{aligned}
 & x_j, x_k \leq \frac{x_j^2 + x_k^2}{2} \Leftrightarrow (x_j - x_k)^2 \geq 0 \\
 & \left| \begin{aligned} &= nP - \frac{1}{2} \sum_{k=1}^n \underbrace{\sum_{j=1}^n x_j^2}_P - \frac{1}{2} \sum_{j=1}^n \underbrace{\sum_{k=1}^n x_k^2}_P \\ &= nP - \frac{1}{2} nP - \frac{1}{2} nP = 0 \end{aligned} \right.
 \end{aligned}$$

$$nP - X^2 > 0$$

$$f(a,b) = a^2 P + b^2 n + Q + 2Xab \Rightarrow 2Sa - 2bY$$

$$H_f(a,b) = 2 \begin{pmatrix} P & X \\ X & n \end{pmatrix}$$

$$\begin{pmatrix} P-\lambda & X \\ X & n-\lambda \end{pmatrix} = 0$$

$$= (P-\lambda)(n-\lambda) - X^2 =$$

$$= \lambda^2 - (P+n)\lambda + Pn - X^2 = 0$$

$$\lambda_{\pm} = \frac{P+m}{2} \pm \frac{\sqrt{(P+m)^2 - 4Pm + 4X^2}}{2}$$

$$X^2 < Pm$$

$$f(1,4) = 8$$

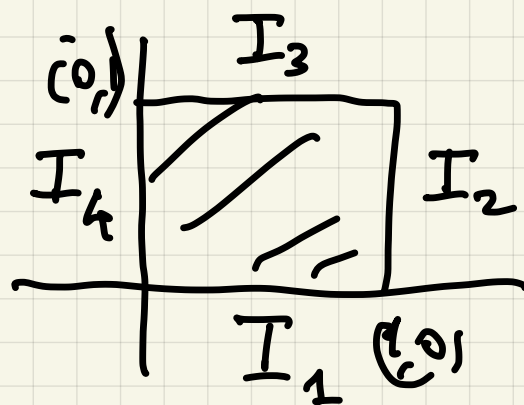
Domini con bordo

$$f(0,0) = 2$$

$$f(1,0) = -1$$

$$f(x,y) = x^2 + y^2 + 8y - 4x + 2 \quad f(0,1) = 11$$

$$Q = [0,1] \times [0,1]$$



Q^o

$$f_x = 2x - 4 = 2(x - 2) = 0$$

$$(2, -4)$$

$$f_y = 2y + 8 = 2(y + 4) = 0$$

$$I_1 \quad f(x,0) = x^2 - 4x + 2$$

$$f_x(x,0) = 2(x - 2) < 0$$

$$I_2 \quad f_y(1,y) = 2y + 8 > 0$$

		min	max
		I_1	$(0,0)$
		I_2	$(1,1)$
		I_3	$(0,1)$
I_3	$f_x(x,1) = 2(x-2) < 0$	I_4	$(0,1)$
I_4	$f_y(0,y) = 2y+8 > 0$		

$(0,1)$ max absolute

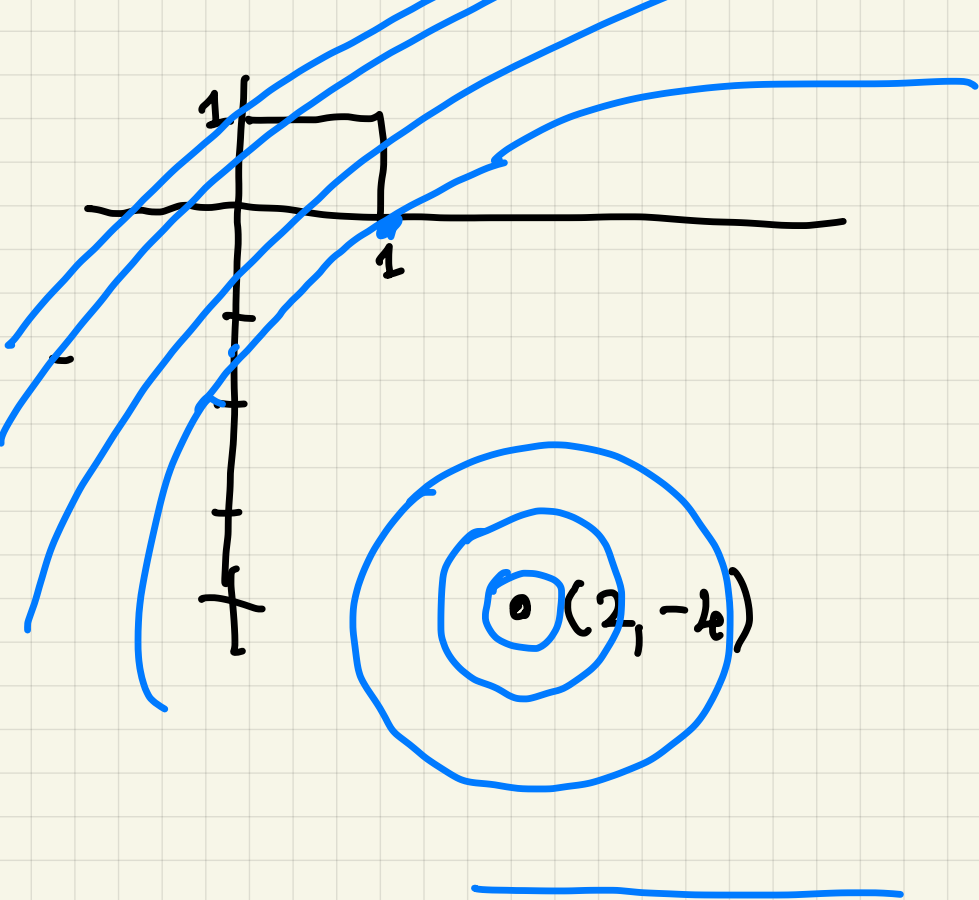
$(1,0)$ min absolute

$f(x,y)$

$$f(x,y) = x^2 + y^2 + 8y - 4x + 2 =$$

$$= x^2 - 4x + y^2 + 8y + 2 =$$

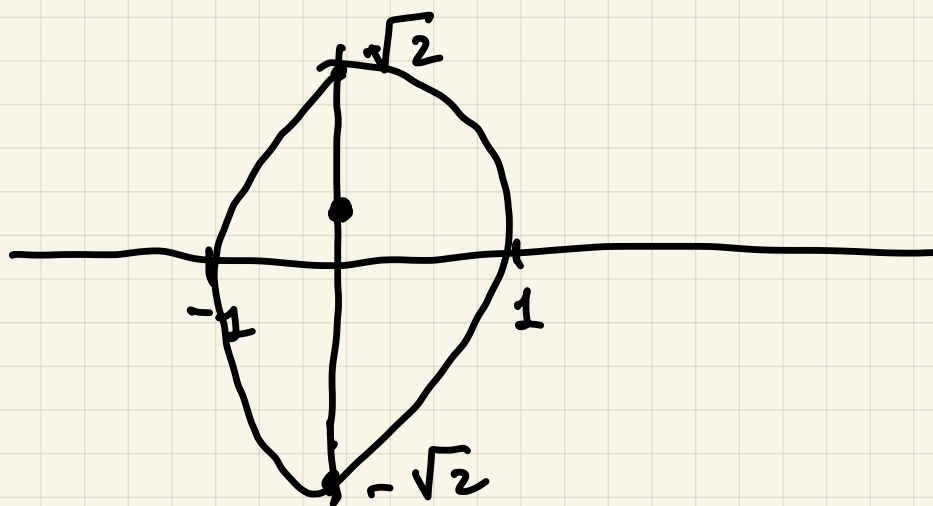
$$= (x-2)^2 + (y+4)^2 - 4 - 16 + 2 = \underline{\underline{C}}$$



$$f(x, y) = x^2 - y^2 + y$$

$$x^2 + \frac{y^2}{2} \leq 1$$

Ω



$$f_x = 2x = 0$$

$$x = 0$$

$$(0, \frac{1}{2})$$

$$f_y = -2y + 1 = 0$$

$$y = \frac{1}{2}$$

$$f_{xx} = 2$$

$$f_{yy} = -2$$

$$H_f(x, y) = \begin{pmatrix} 2 & 0 \\ 0 & -2 \end{pmatrix}$$

$$f \rightarrow x^2 - y^2 + \frac{1}{2}y$$

$$x^2 + \frac{y}{2} = 1$$

$$\begin{cases} x = \cos \vartheta \\ y = \sqrt{2} \sin \vartheta \end{cases}$$

$$f(\cos \vartheta, \sqrt{2} \sin \vartheta) =$$

$$h(\vartheta) = \cos^2 \vartheta - 2 \sin^2 \vartheta + \sqrt{2} \sin \vartheta =$$

$$= 1 - 3 \sin^2 \vartheta + \sqrt{2} \sin \vartheta$$

$$h'(\vartheta) = (-6 \sin \vartheta + \sqrt{2}) \cos \vartheta = 0$$

$$\cos \vartheta = 0$$

$$\vartheta = \frac{\pi}{2}, \frac{3}{2}\pi$$

$$\sin \vartheta = \frac{\sqrt{2}}{6}$$

$$\vartheta = \frac{\pi}{2}$$

$$(0, \sqrt{2})$$

$$\vartheta = \frac{3}{2}\pi$$

$$(0, -\sqrt{2})$$

$$\text{or } \sin \vartheta = \frac{\sqrt{2}}{6}$$

$$y = \sqrt{2} \quad \sin \vartheta = \frac{\sqrt{2}}{6} = \frac{2}{6} = \frac{1}{3}$$

$$x = \pm \sqrt{\frac{17}{18}}$$

$$x^2 = 1 - \frac{y^2}{2} = 1 - \frac{1}{18} = \frac{17}{18}$$

$$f(x, y) = x^2 - y^2 + y$$

$$f(0, \sqrt{2}) = -2 + \sqrt{2} < 0$$

$$f(0, -\sqrt{2}) = -2 - \sqrt{2} < 0 \quad \text{not min. on.}$$

$$f\left(\pm\sqrt{\frac{17}{18}}, \frac{1}{3}\right) = \frac{17}{18} - \frac{1}{9} + \frac{1}{3}$$

↗ punkt max oder min

$$z = f(x, y)$$

