

Predator-Prey Models

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Dynamical Systems vs. Computation

- Dynamics:
 - Focus on how things *change*.
 - Describe systems undergoing continual temporal change.
 - View change geometrically: Trajectories, attractors, bifurcations.
 - Stability of patterns of change as a function of system parameters.
 - Scaling limitation: Quantitative analysis only feasible for low-dimensional systems.
- Computation:
 - Focus on *internal structure*.
 - Equivalence classes.
 - Marr's *representation and algorithm* level of description.

Styles of Modeling I (review)

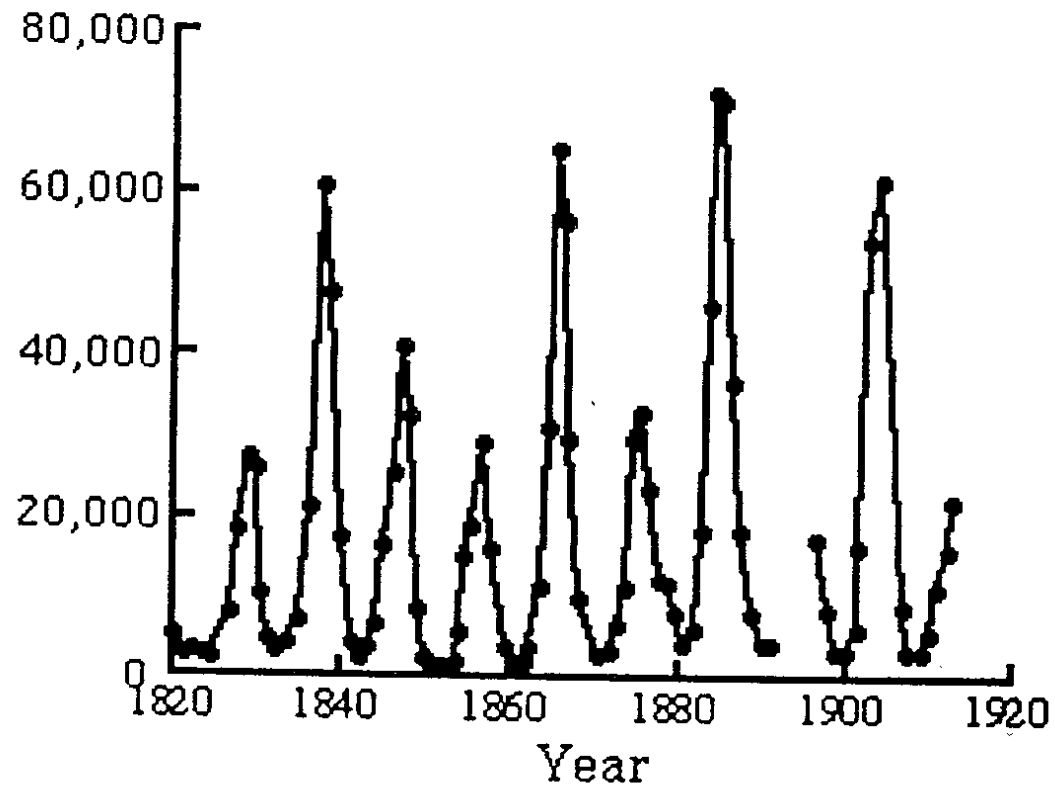
Aggregate / Differential Equations

- Describe the global behavior of a system
- Average out individual differences
- Assume infinite-sized populations
- Assume all possible genotypes always present in population.
- Easier to do theory and make quantitative predictions.
- Examples:
 - Fractals
 - Mackey-Glass systems
 - Lotka-Volterra systems

Styles of CAS Modeling II (review) ***Computational / Individual-based / Agent-based***

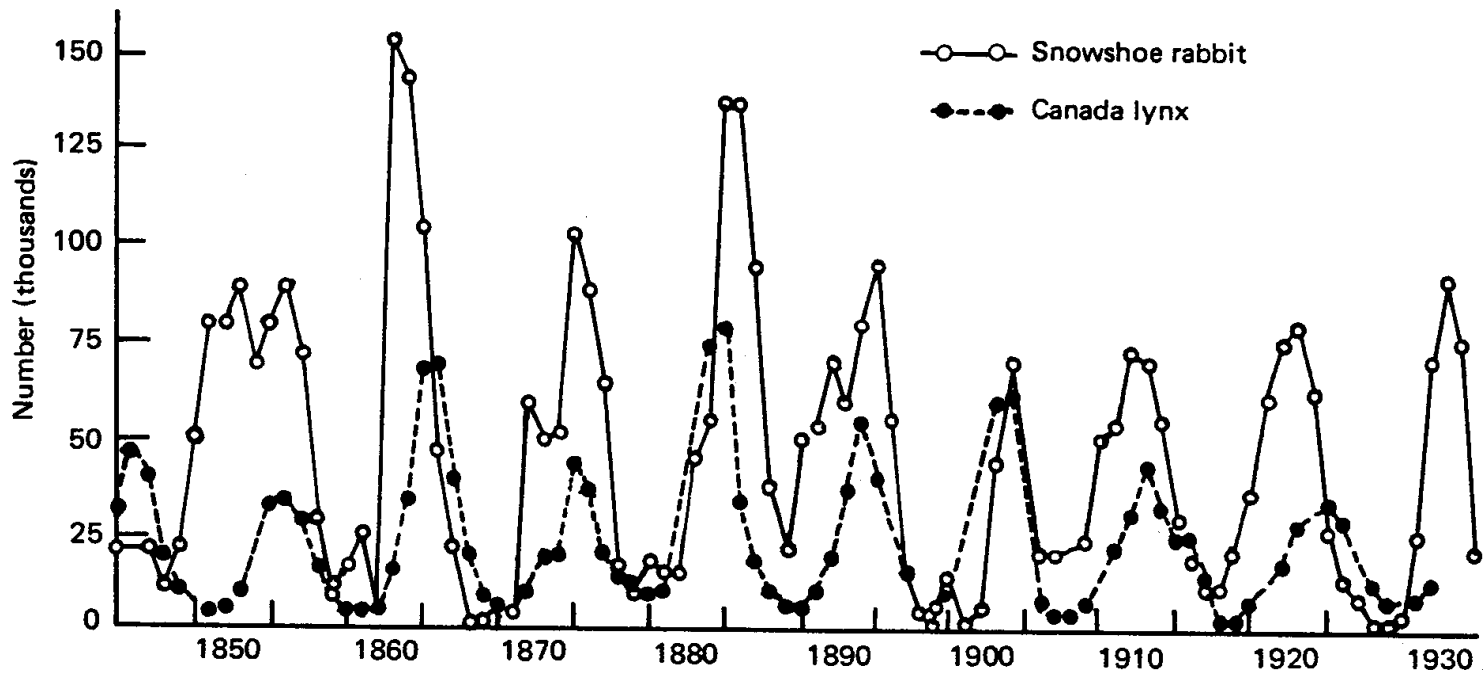
- A computational artifact that captures essential components and interactions (I.e. a computer program).
- Encodes a theory about relevant *mechanisms*:
 - Want relevant behavior to arise spontaneously as a consequence of the mechanisms. The mechanisms give rise to macro-properties without being built in from the beginning.
 - This is a very different kind of explanation than simply predicting what will happen next.
 - Example: Cooperation emerges from Iterated Prisoner's Dilemma model.
 - Simulation as a basic tool. Observe distribution of outcomes.
- Study the behavior of the artifact, using theory and simulation:
 - To understand its intrinsic properties, and wrt modeled system.

Lynx Historical Data (Predators)

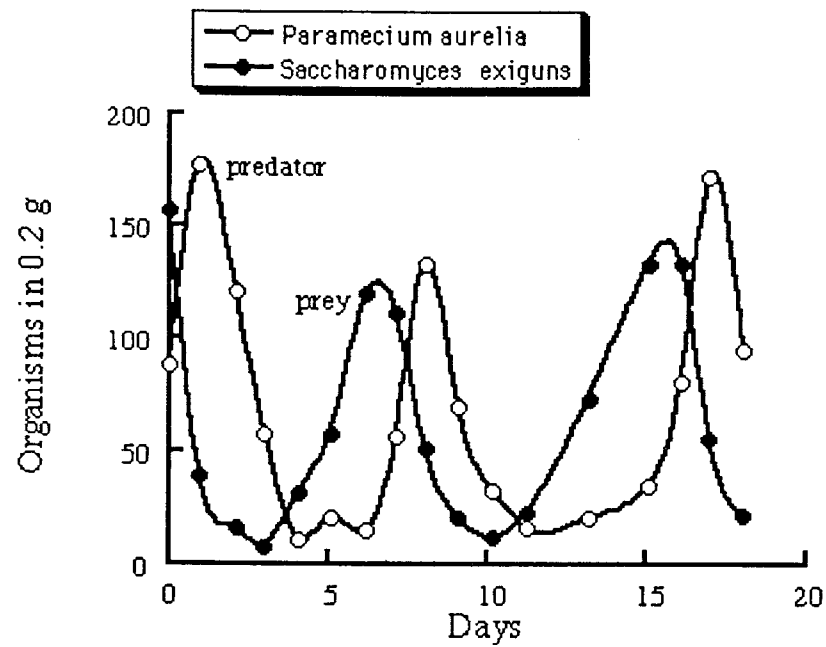


[D'Ancona, 1954]

Lynx/Rabbit Historical Data (Predators)



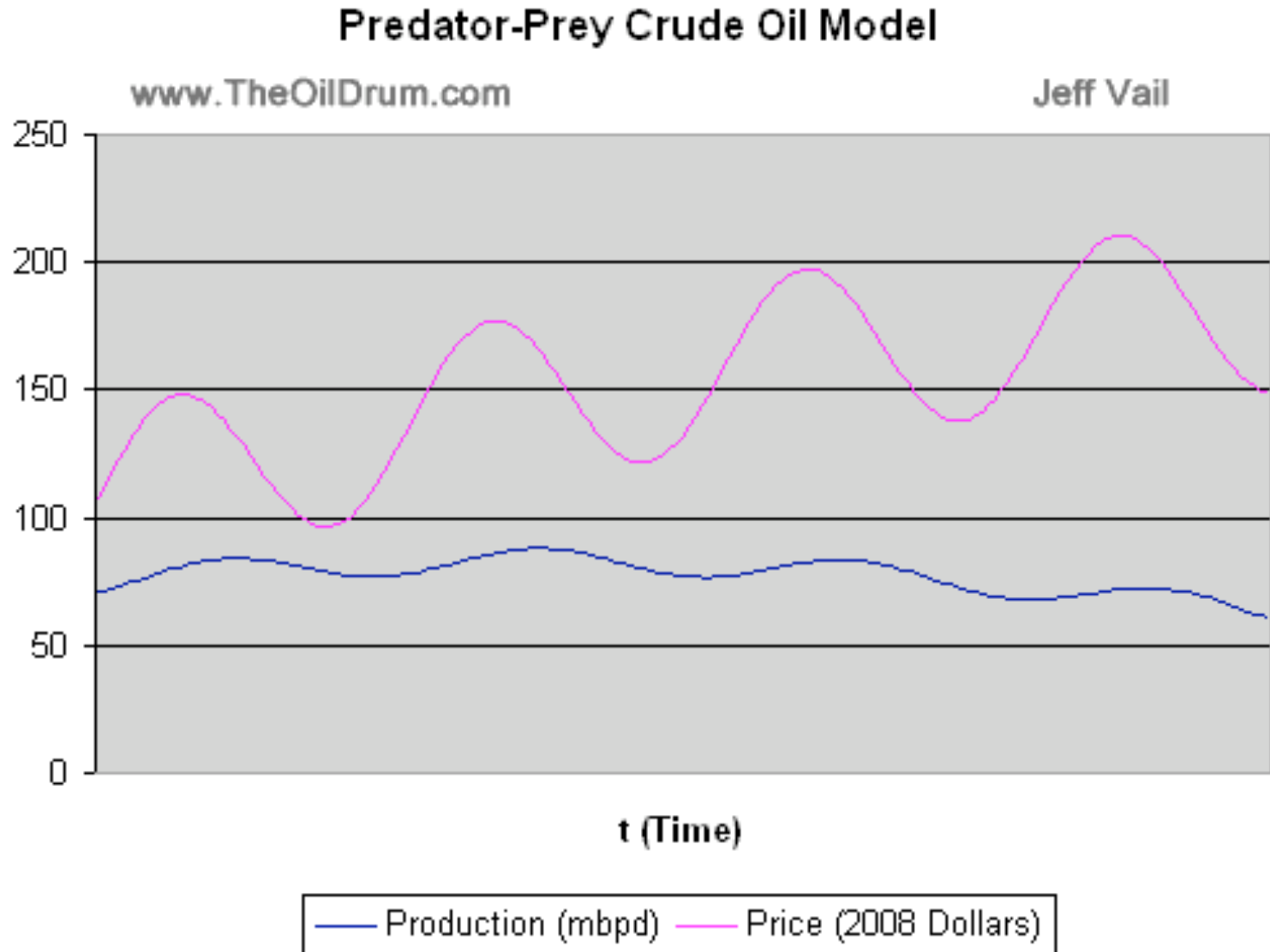
Paramecium Data



Oscillations in the populations of paramecia and yeast, from D'Ancona, 1954

Predator-Prey Dynamics in Demand Destruction and Oil Prices

The predator-prey oscillations of price increases and demand destruction/production increases superimposed on top of a geological depletion scenario--note how the volatility for the predator-prey dynamic works to conceal the underlying geological and geopolitical trends.



Modeling Predator-Prey Interactions

- The Lotka-Volterra model is the simplest model of predator-prey interactions. It was developed independently by:
 - Alfred Lotka, an American biophysicist (1925), and
 - Vito Volterra, an Italian mathematician (1926).
- Basic idea: Population change of one species depends on:
 - Its current population.
 - Its reproduction rate.
 - Its interactions with other species (predation or prey).
- Model expressed as coupled differential equations:

$$\frac{dx}{dt} = Ax - Bxy$$

$$\frac{dy}{dt} = -Cy + Dxy$$

The Lotka-Volterra Model cont.

- Example: Rabbits and Lynxes (bobcats):
 - Rabbits reproduce at a rate proportional to their population. Let x denote the number (density) of rabbits.
 - Lynxes eat rabbits, and die at a constant rate. Let y denote the density of lynxes.
 - See population plots from real experiments (previous slides).
- The model:
 - Population x (the rabbits) increases at rate $dx = Axdt$.
 - Population x (the rabbits) decreases at rate $dx = -Bxydt$.
 - Population y (the lynxes) increases at rate $dy = Dxydt$.
 - Population y (the lynxes) decreases at rate $dy = -Cydt$.
- The parameters:
 - A = natural reproduction rate of rabbits in the absence of predation.
 - B = death rate per encounter of rabbits due to predation.
 - C = natural death rate of lynxes in the absence of food (rabbits).
 - D = the efficiency of turning predated rabbits into new lynxes.

Lotka-Volterra Model

Rabbit and Lynx Population

- The change in the rabbit population is equal to how many rabbits are born minus the number eaten by lynxes:

$$\frac{dx}{dt} = Ax - Bxy$$

- The change in lynx population is equal to how fast they reproduce (depends on how many rabbits are available to eat) minus their death rate:

$$\frac{dy}{dt} = -Cy + Dxy$$

- Note: In some versions $B=D$.

Can we predict how the model will behave?

- Are the populations ever stable?
- That is,

$$\frac{dx}{dt} = \frac{dy}{dt} = 0$$

$$\begin{aligned} A - By &= 0 & y &= \frac{A}{B} \\ -C + Dx &= 0 & x &= \frac{C}{D} \end{aligned}$$

- Stationary point at $(x,y) = (C/D, A/B)$.
 - Fig. 12.1 fixed point (F,S): (1.167,0.74)
- Typical behavior is one of oscillating populations.

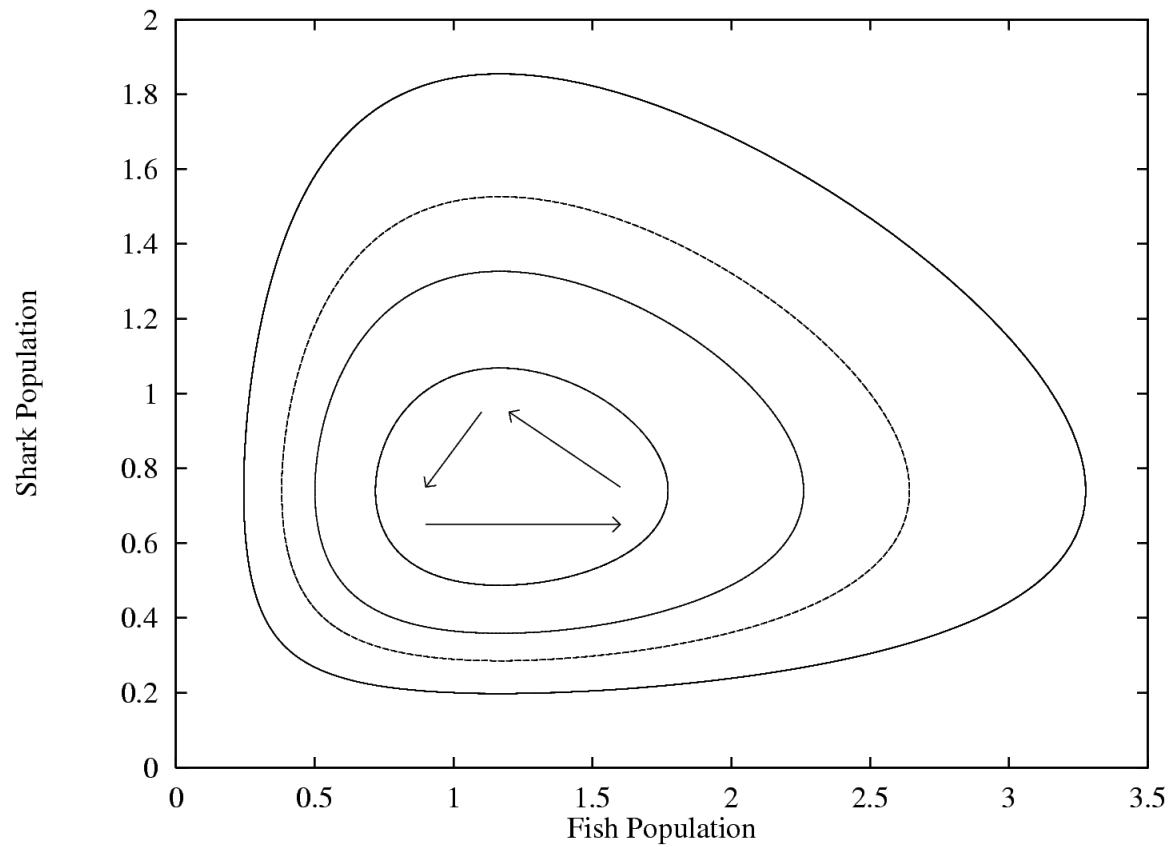


Figure 12.1 A simple Lotka-Volterra attractor which shows four (out of an infinite number of possible) limit cycles. The value of the four parameters are equal to 3.029850, 4.094132, 1.967217, and 2.295942, which yields a fixed point at 1.1671, 0.740047.

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Stability of Fixed Point

- What happens if we perturb the system?
 - Perturb initial conditions
 - Perturb system coefficients
 - Stability of system
 - Can analyze mathematically (compute the Jacobian and study eigenvalues)
- Experiment with small perturbations
 - What happens if you increase A slightly (rabbit reproduction rate)?
 - What happens if you increase C slightly (lynx death rate)?

Comments on the Lotka-Volterra Model

- Doesn't consider competition among prey or predators:
 - Prey population may grow infinitely without any resource limits (the rabbits never run out of food).
 - Carrying capacity
 - Predators have no saturation: Their consumption rate is unlimited (the lynxes never get full).
 - Only considers two interacting species.
- Nanofoxes?
- Many extensions and refinements exist, including models of three interacting species model. The 3-species model can have chaotic dynamics.
- Extending Lotka-Volterra to 3 species:

$$\frac{dx_i}{dt} = x_i \sum_{j=1}^n A_{ij} (1 - x_j)$$

- X_j represents the i -th species.
- A_{ij} represents the effect that species j has on species i .
 - Represent A as a matrix.

Three-Species Lotka-Volterra

Example of Chaotic Behavior

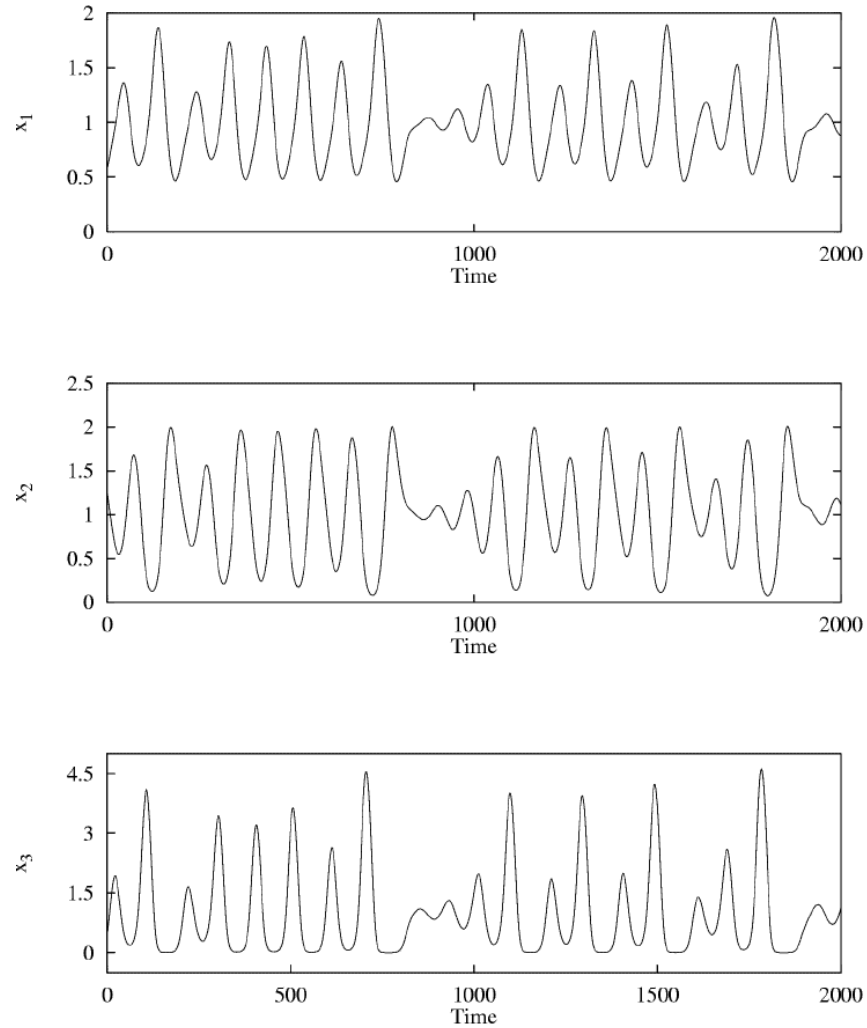


Figure 12.3 Population levels for the three-species Lotka-Volterra system

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The Interaction Terms

- A_{ij} represents the effect that species j has on species i :

$$A = \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{bmatrix} = \begin{bmatrix} 0.5 & 0.5 & 0.1 \\ -0.5 & -0.1 & 0.1 \\ \alpha & 0.1 & 0.1 \end{bmatrix}$$

- This choice of A was discovered to have chaotic dynamics:
 - Tune α to see full range of dynamical behaviors.
 - See Figure 12.4.

Three-Species Lotka-Volterra cont.

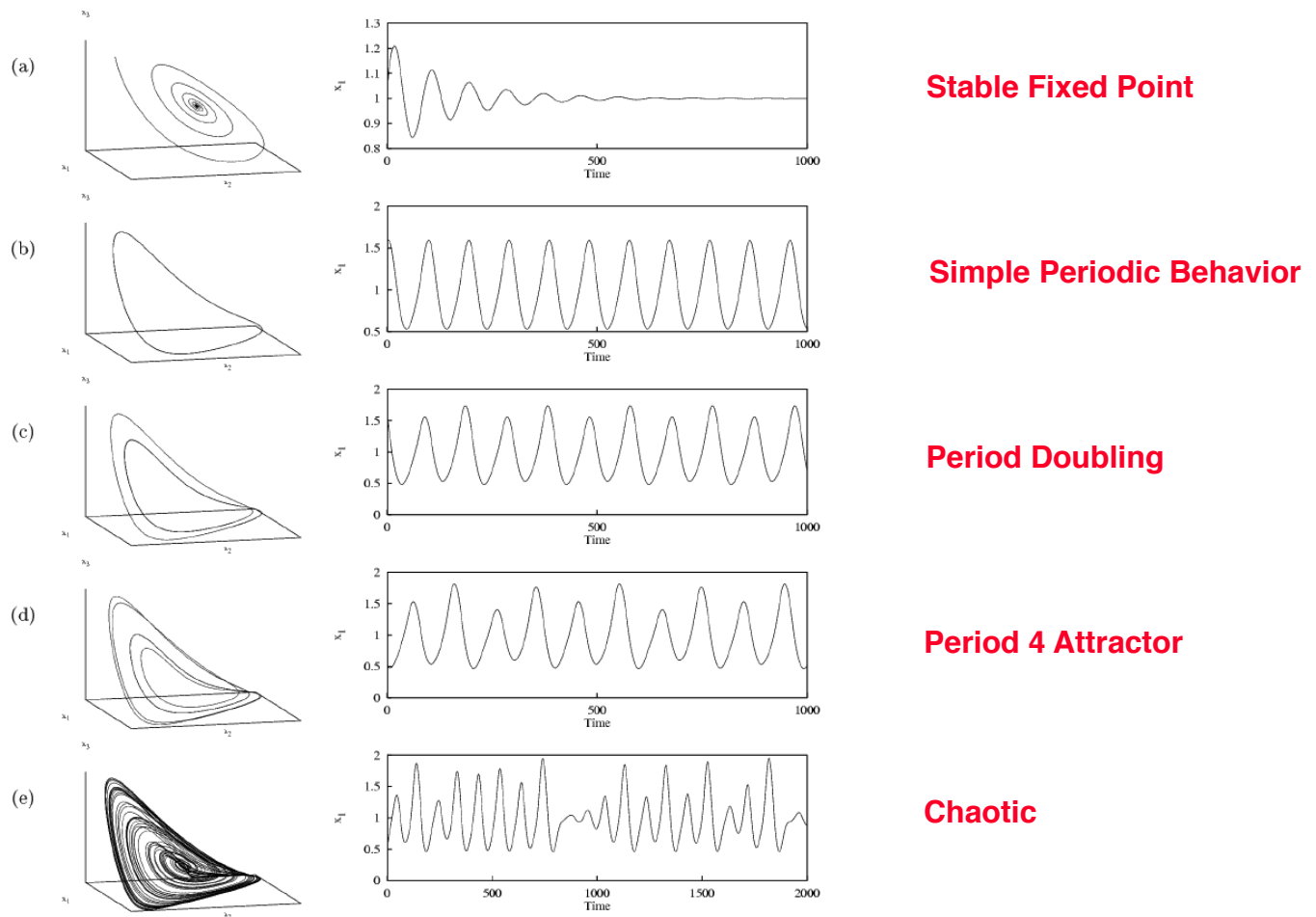


Figure 12.4 Period doublings in a three-species Lotka-Volterra system: phase space is on the left and x_1 is plotted on the right. (a) spiral fixed point, (b) simple periodic orbit, (c) period-2 orbit, (d) period-4 orbit, (e) chaos

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An Alternative Approach (Agent-based modeling)

- Taken from *The Computational Beauty of Nature*.
- Represent each individual in the population explicitly.
 - Rules for encounters between individuals.
- Write down interaction rules between individuals.
- Represent physical space explicitly:
 - 2-d grid.
 - Each grid site is either empty or contains a single individual.
- Three types of individuals:
 - Plants.
 - Herbivores (rabbits).
 - Carnivores (lynxes).

Individual-based Models

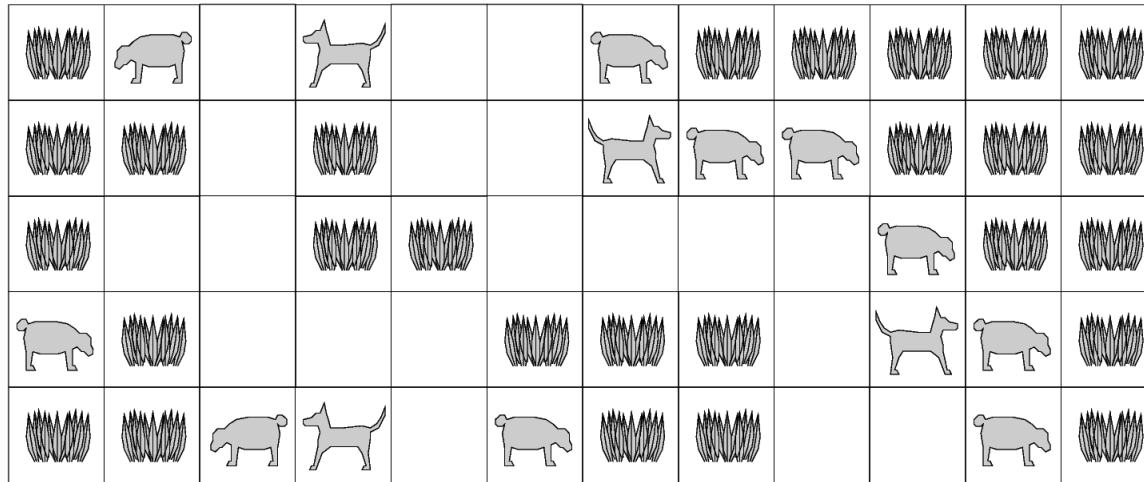


Figure 12.5 An individual-based three-species ecosystem

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Agent Rules

- Plants can:
 - Spread into contiguous empty space.
 - Be eaten by herbivores.
- Herbivores can:
 - Die (by starving to death or being eaten by carnivores).
 - Move into contiguous locations.
 - Eat plants.
 - Have babies (if they have stored enough energy).
- Carnivores can:
 - Die (by starving to death).
 - Move to a contiguous location.
 - Eat herbivores.
 - Have babies (if they have stored enough energy).

Population Dynamics (Time Series) in an Individual-based Model

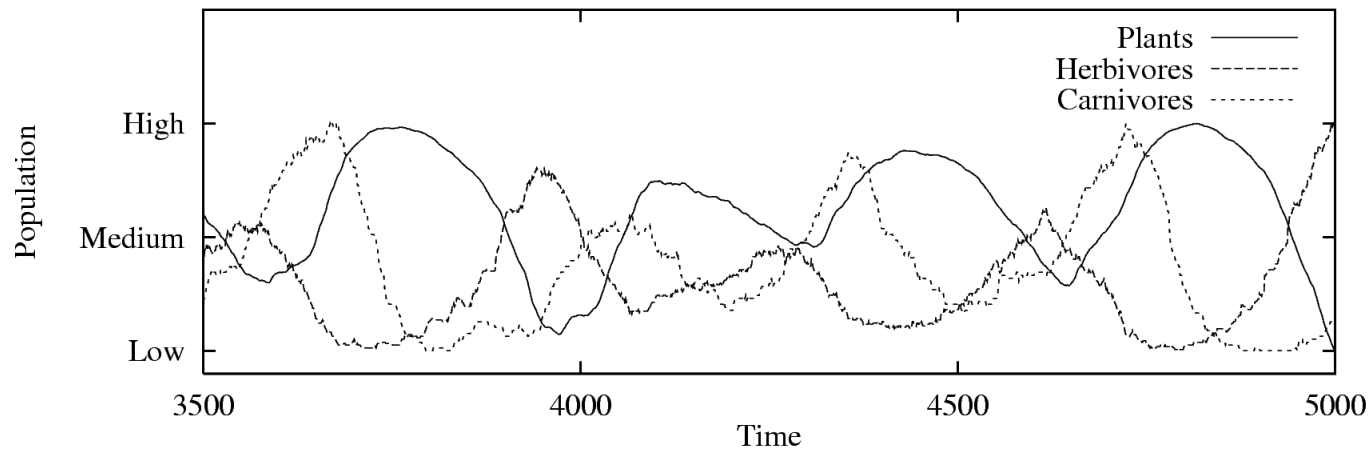


Figure 12.7 Population levels for all creatures, normalized for comparison

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Comparison with Lotka-Volterra Model

- How is this model different from Lotka-Volterra?
- How is this model the same as Lotka-Volterra?
- Do we expect fixed points?

Comparison with Lotka-Volterra Model

- How is this model different from Lotka-Volterra?
 - Potential for non-uniform mixing (because space is represented explicitly)
 - Non-deterministic movement into adjacent spaces.
 - Discrete time.
 - Discrete population values.
 - Discrete threshold for reproduction.
- How is this model the same as Lotka-Volterra?
 - Similar interaction rules.
 - Similar dynamics.
- Do we expect fixed points?

How Should We Study/Analyze the Behavior of this Agent-based Model?

- Look at one run carefully?
- Look at many runs and “note” the analogy to Lotka-Volterra models?
- Look at many runs and compute statistics?
- Look at very large runs?
- Can we make the analogy more precise?
 - Suppose we ignore space and simply record the relative population values for the entire grid, over time.
 - What is the state space?
 - Record how population changes at each point in state space.
 - Compare with phase portrait for Lotka-Volterra.

Conclusions

- Species eye view of the world vs. individual eye:
 - Lotka-Volterra ignores variations among individuals.
 - Lotka-Volterra assumes infinite-size populations and perfect mixing.
- The agent-based alternative is not exactly a cellular automaton.
- These models form the basis of many more complicated models.
- Examples:
 - Echo (Holland, 1994)
 - One type of agent. Agents can: mate, fight, trade.
 - Agent rules and preferences can evolve over time.
 - Maley's models of Barrett's Esophagus, CancerSim.
 - Disease modeling