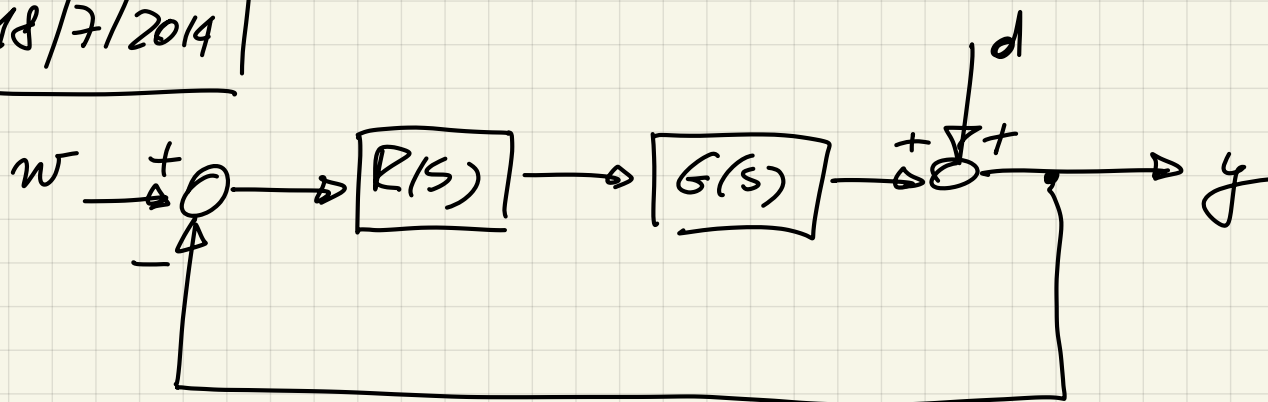



18/7/2014



$$G(s) = \frac{10}{1+10s} \cdot e^{-2s}$$

specifiche di progetto:

② $|e_p| \rightarrow 0$

for $w(t) = A \cdot 1(t)$

$d(t) = B \cdot 1(t)$

$A, B \in \mathbb{R}$

① $d=0$ $\omega_c \geq 0,5 \text{ rad/s}$

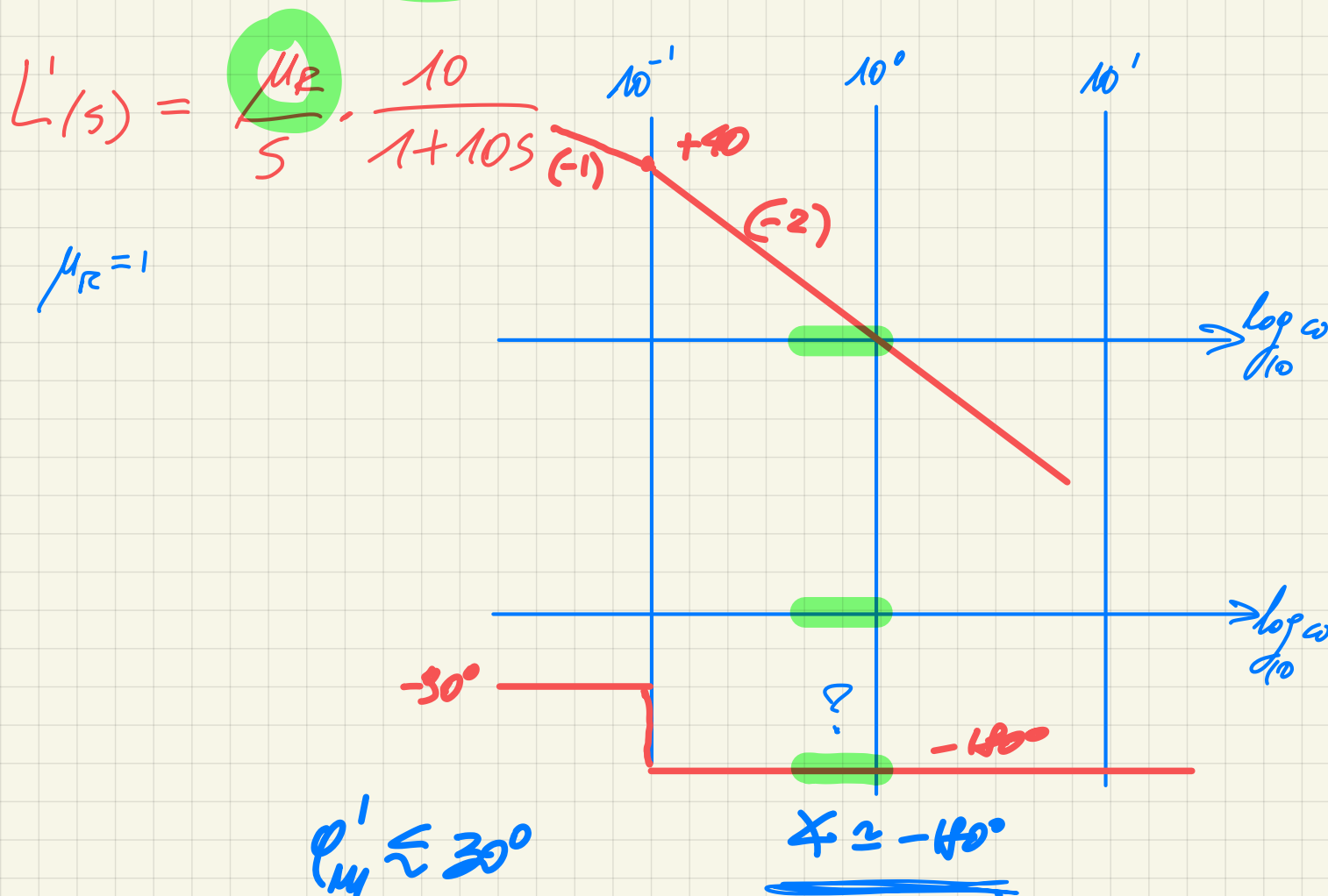
③ $d=0$ $\varphi_m \geq 30^\circ$

$$\begin{aligned} \angle G(j\omega) &= \arg(10) - \arg(1+j10\omega) \\ &\quad + \arg(e^{-2j\omega}) \\ &= 0^\circ - \arctan(10\omega) - 2\omega \end{aligned}$$

$\varphi_m \geq 30^\circ$

$$G(s) = G'(s) e^{-2s}$$

$$\frac{10}{1+10s}$$



$$\varphi_M = \varphi'_M - 2\omega_c < 30^\circ!!$$

$$G(s) = \frac{10}{1+10s} e^{-2s} \quad R_1(s) = \frac{\mu_R}{s}$$

$$L(s) = \frac{10\mu_R}{s(1+10s)} e^{-2s}$$

$$\nexists L(j\omega) \geq -150^\circ$$

$$\arg(10\mu_R) - 90^\circ - \arg(10\omega) - 2\omega \geq -150^\circ$$

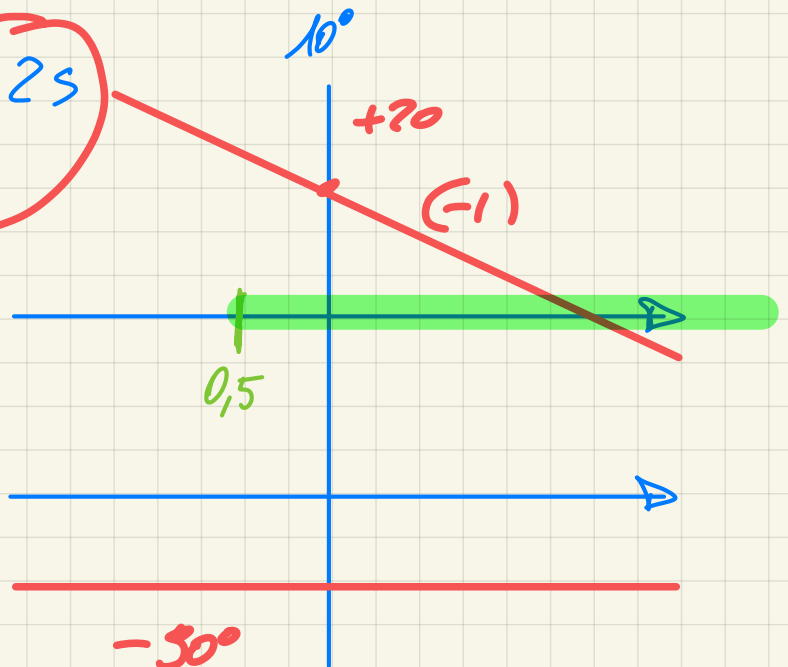
$$\arg(10\omega) \leq 60^\circ - 2\omega$$

Come risolvere?
per via grafica?
no vale la pena?

$$R_2(s) = \frac{\mu_R(1+10s)}{s}$$

$$L_2(s) = 10 \frac{\mu_R}{s} e^{-2s}$$

$$\mu_R = 1$$



$$\omega_c \geq 0,5$$

$$\varphi_m \geq 30^\circ$$

$$\nexists L_2(j\omega) \geq -150^\circ \iff \varphi_m \geq 30^\circ$$

$$-\frac{\pi}{2} - 2\omega \geq -\frac{5}{6}\pi$$

$$-2\omega \geq -\frac{\pi}{3}$$

$$0,5 \leq \omega$$

$$\omega \leq \frac{\pi}{6} \approx 0,52 \text{ rad/s}$$

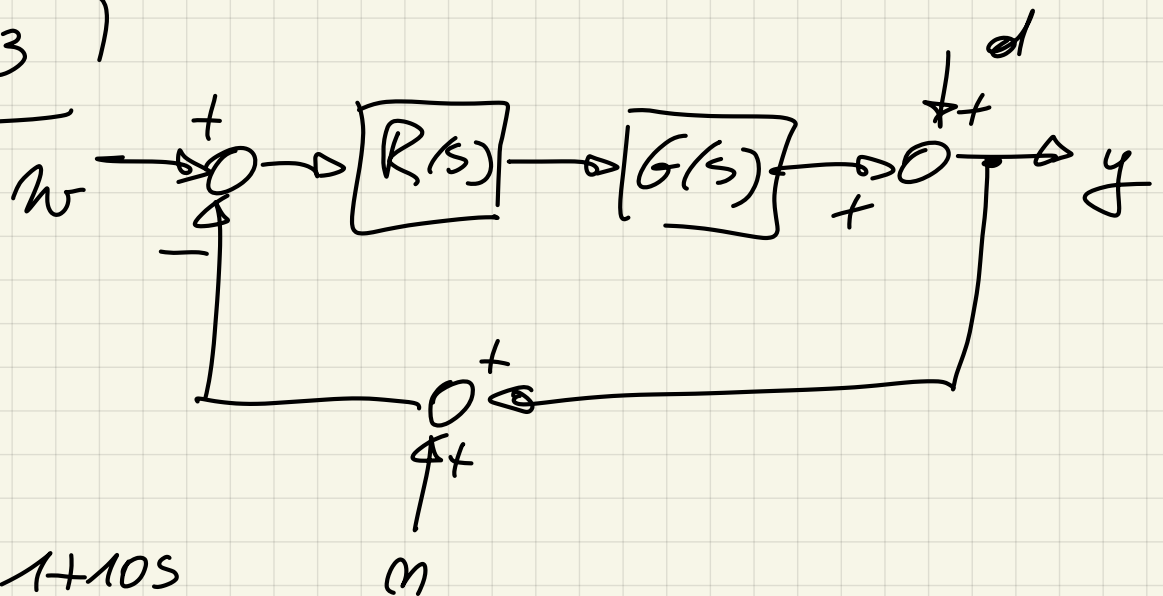
$$0,5 \leq \bar{\omega}_c < 0,52$$

$$-0,25$$

e

$$|L_2(j\bar{\omega}_c)| = 1$$

14/01/2013



$$G(s) = 2 \frac{1+10s}{(1+s)^2}$$

$R(s)$ finit, realizzabile tale che:

① $|e_{\infty}| \rightarrow 0$ per $w(t) = 1(t)$
 $d(t) \equiv 0$

② $d(t) \neq 0$ $d(t) = D \sin(\omega t)$

$\omega \in \left[\frac{1}{10}, \frac{1}{2} \right] \text{ rad/s}$

$D > 0$

$|y_{reg}^d| \leq D/5$

$$c) \quad m(t) = N \sin(\omega t)$$

$$\omega \in [20, 200] \text{ rad/s}$$

$$N > 0$$

il rumore α rimane in uscita ~~non~~ attenuato
 almeno di un fattore 10 $\rightarrow$

$$|y_{reg}^m| \leq \frac{N}{10}$$

Esercizio 5

Si faccia riferimento allo schema a blocchi seguente

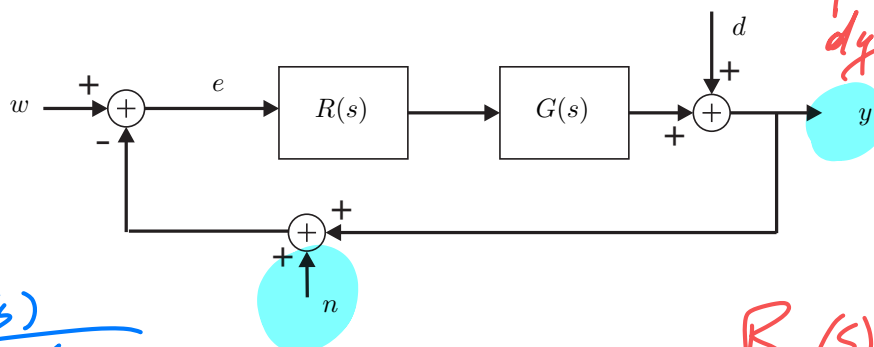


Figura 2: Progetto di un regolatore.

$$T_{ny} = -F(s) = -\frac{L(s)}{1+L(s)}$$

dove $G(s) = 2 \cdot \frac{(1+10s)}{(1+s)^2}$

$$T_{dy}(s) = \frac{1}{1+L(s)} = S(s)$$

$$R_1(s) = \frac{K_R}{s}$$

Domanda 5.1. Utilizzando i diagrammi asintotici di Bode (si usi la carta logaritmica alla pagina seguente), si progettino un regolatore $R(s)$ **fisicamente realizzabile** tale da soddisfare le seguenti specifiche:

- errore a regime nullo nella risposta (a ciclo chiuso) allo scalino unitario $w(t) = 1(t)$
- supponendo che il disturbo $d(t)$ sia descrivibile come

$$d(t) = D \sin(\omega t) \quad \omega \in \left[\frac{1}{10}, \frac{1}{2} \right] \text{ rad/s} \quad D > 0$$

l'uscita a regime a ciclo chiuso a fronte del solo disturbo $d(t)$ (con tutti gli altri ingressi posti a zero) possieda ampiezza non superiore a $\frac{D}{5}$.

- supponendo che il rumore $n(t)$ sia descrivibile come

$$n(t) = N \sin(\omega t) \quad \omega \in [20, 200] \text{ rad/s} \quad N > 0$$

il rumore a regime in uscita a ciclo chiuso sia attenuato almeno di un fattore 10, cioè l'ampiezza dell'uscita a regime a ciclo chiuso quando sia applicato il solo rumore $n(t)$ (con tutti gli altri ingressi posti a zero) sia inferiore a $\frac{N}{10}$.

$$T_{ny} = -\frac{L(s)}{1+L(s)}$$

$$d(t) = D \sin(\bar{\omega} t) \quad \bar{\omega} \in \left[\frac{1}{10} ; \frac{1}{2} \right]$$

$$y_d^\infty(t) = |S(j\bar{\omega})| \cdot D \sin(\bar{\omega} t + \angle S(j\bar{\omega}))$$

$$D/5 \quad \searrow$$

$$\forall \bar{\omega} \in \left[\frac{1}{10} ; \frac{1}{2} \right] |S(j\bar{\omega})| \leq \frac{1}{5}$$

$$\frac{1}{|L(j\omega)|} \ll 1$$

$$|S(j\omega)| = \frac{1}{|1 + L(j\omega)|}$$

$$|L(j\omega)| \gg 1$$

$$|L(j\omega)| \ll 1$$

$$\frac{1}{|L(j\omega)|} \leq \frac{1}{5} \quad \forall \omega \in \left[\frac{1}{10} ; \frac{1}{2} \right]$$

$$|L(j\omega)| \geq 5 \quad \forall \omega \in \left[\frac{1}{10} ; \frac{1}{2} \right]$$

$$|L(j\omega)|_{dB} \geq 14 \text{ dB} \quad \forall \omega \in \left[\frac{1}{10} ; \frac{1}{2} \right]$$

$$T_{ny}(s) = -F(s) = - \frac{L(s)}{1 + L(s)}$$

$$m(t) = N \sin(\tilde{\omega} t) \quad \tilde{\omega} \in [20; 200]$$

$$g_m^\infty(t) = \underbrace{N |-F(j\tilde{\omega})|}_{\text{highlighted}} \cdot \sin(\tilde{\omega} t + \angle[-F(j\tilde{\omega})])$$

$$\leq \frac{N}{10} \Rightarrow |-F(j\tilde{\omega})| \leq \frac{1}{10}$$

$$|F(j\omega)| \leq \frac{1}{10} \quad \omega \in [20; 200]$$

$$|F(j\omega)| = \frac{|L(j\omega)|}{|1 + L(j\omega)|}$$

$|L| \ll 1 \Rightarrow |L(j\omega)|$
 $|L| \gg 1 \Rightarrow \approx 1$



$$|L(j\omega)| \leq \frac{1}{10} \quad \forall \omega \in [20; 200]$$

$$|L(j\omega)|_{dB} \leq -20 \text{ dB} \quad \forall \omega \in [20; 200]$$

②

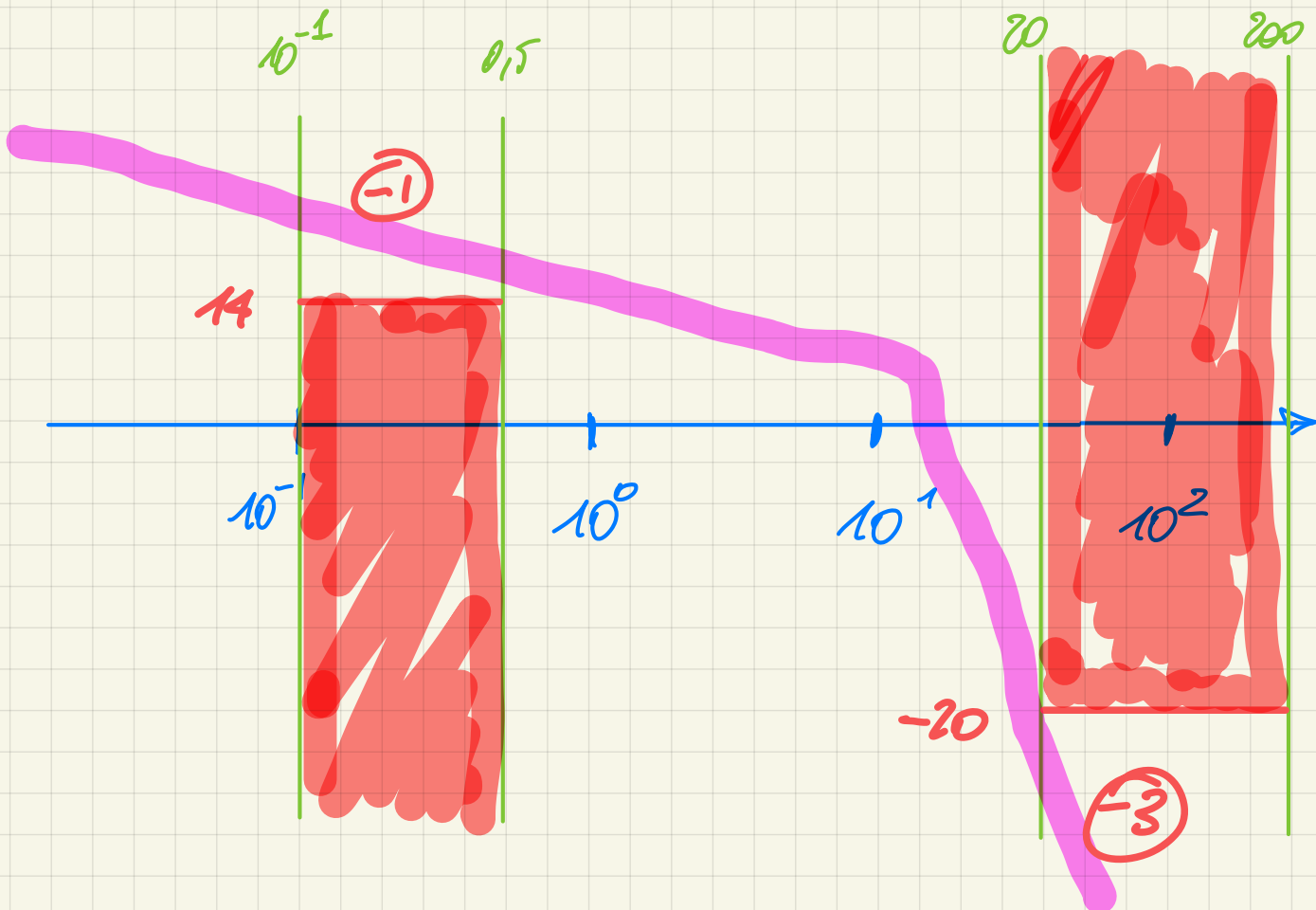
$$G(s) = \frac{2(1+10s)}{(1+s)^2}$$

$$R_1(s) = \frac{\mu_R}{s}$$

$$|L(j\omega)|_{dB} \geq 14dB \quad \omega \in \left[\frac{1}{10}; \frac{1}{2}\right]$$

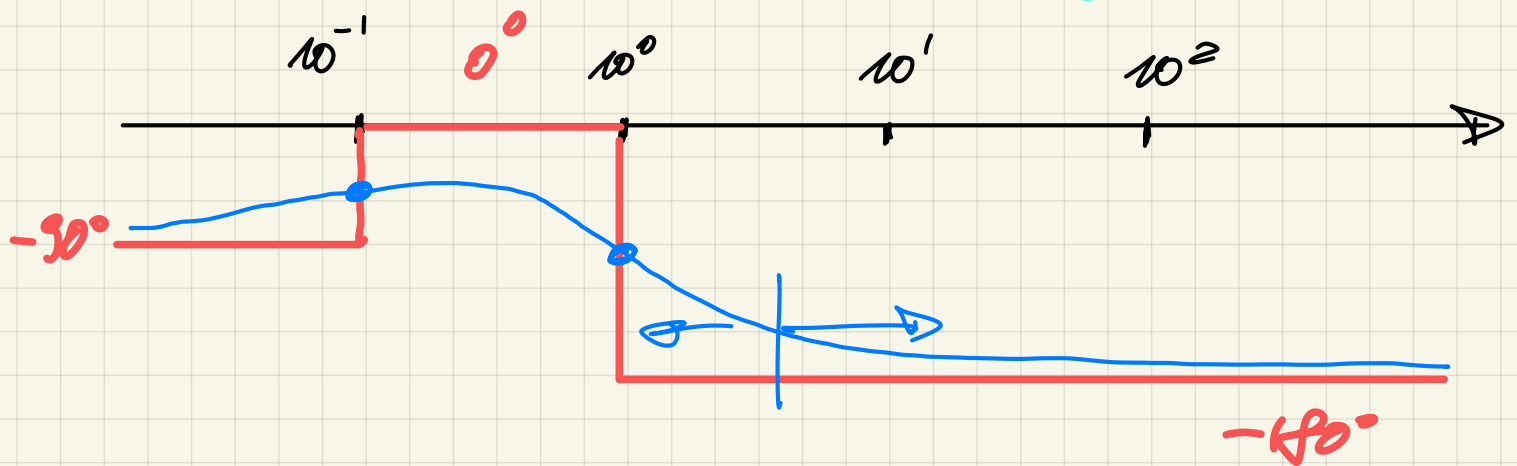
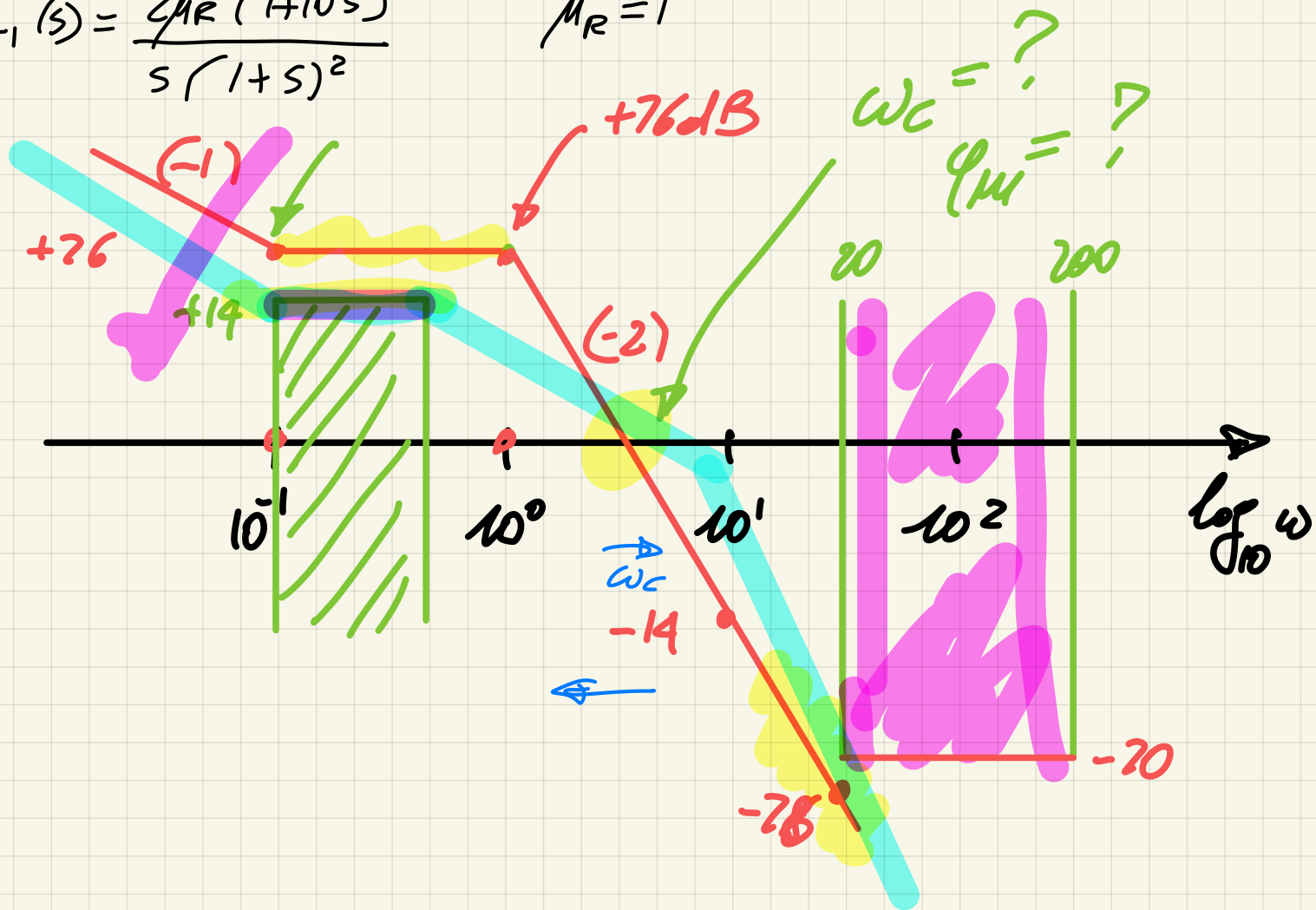
$$|L(j\omega)|_{dB} \leq -20dB \quad \omega \in [20; 200]$$

$$L_1(s) = \frac{2\mu_R(1+10s)}{s(1+s)^2}$$



$$L_1(s) = \frac{2\mu_R (1+10s)}{s(1+s)^2}$$

$$\mu_R = 1$$



$$\mu_R = 1 \quad |L(j\omega_c)| = 1$$

$$\frac{2 |1 + 10j\omega_c|}{\omega_c |1 + j\omega_c|^2} = 1$$

$$\omega_c \left[|1 + j\omega_c|^2 \right] |1 + j\omega_c| \cdot |1 + j\omega_c|$$

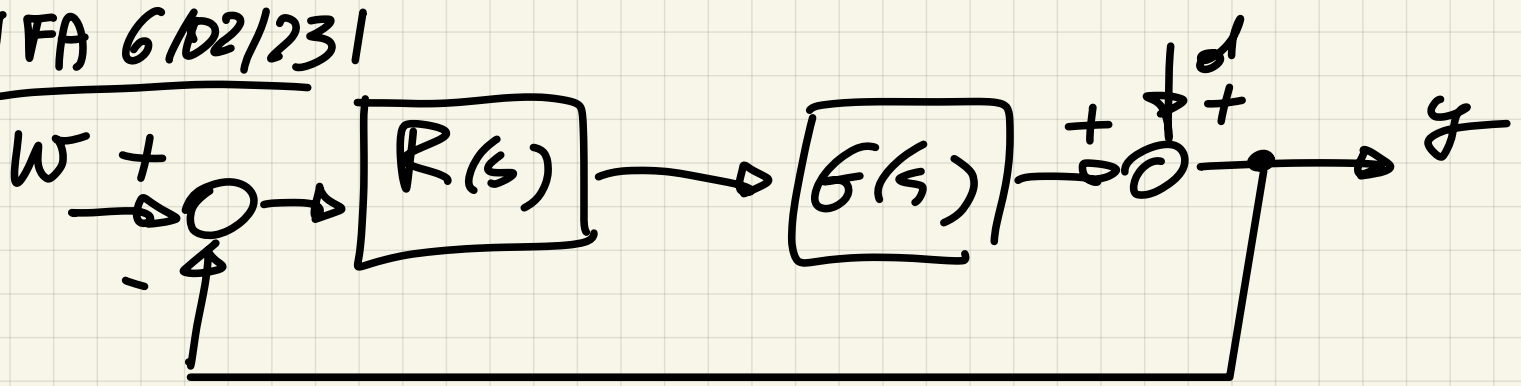
$$4(1 + 100\omega_c^2) = \omega_c^2(1 + \omega_c^2)^2$$

$$\omega_c \approx 4,36 \text{ rad/s}$$

$$\varphi_c \approx -155^\circ (= \angle L(j\omega_c))$$

$$\varphi_{\text{III}} \approx 75^\circ //$$

FA 6/02/23



$$G(s) = s \frac{1 + \frac{1}{10}s}{1 + Ts}$$

$$T \in \left[\frac{1}{2}; 10 \right]$$

incertezza
intervallo

$$① t_e \leq 10 \text{ s}$$

$$② |e_\infty| = 0 \text{ per } w(t) = 1(t)$$

$$③ \varphi_M \geq 40^\circ$$

$$R_1(s) = \frac{\mu_R}{s}$$

$$L(s) = \frac{\mu_R (1 + \frac{1}{10}s)}{s(1 + Ts)}$$

$$\mu_R > 0$$

$$① |e_\infty| = 0 \rightarrow R_1(s) = \frac{\mu_R}{s} \quad \#$$

$$② t_e \leq 10$$

$$\varphi_M > 75^\circ$$

$$(\varphi_M > 40^\circ)$$

$$t_e \approx \frac{5}{\omega_c} \leq 10$$

$$\omega_c \geq 0,5 \text{ rad/s}$$

$$\varphi_M = 40^\circ$$

$$t_a \geq \frac{5}{\frac{\varphi_M}{100} \cdot \omega_c} \leq 10$$

$$\frac{5}{0,4 \cdot \omega_c} \leq 10$$

$$\omega_c \geq \frac{5}{4}$$

$$\omega_c \geq 1,25 \text{ rad/s}$$

$$L_1(s) = g_{MR} \frac{1 + s/10}{s(1 + Ts)}$$

$$\frac{1}{T} \in \left[\frac{1}{10}; 2 \right]$$

