Basic IIR Digital Filter Structures

- The causal IIR digital filters we are concerned with in this course are characterized by a real rational transfer function of z^{-1} or, equivalently by a constant coefficient difference equation
- From the difference equation representation, it can be seen that the realization of the causal IIR digital filters requires some form of feedback

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Basic IIR Digital Filter Structures

- An *N*-th order IIR digital transfer function is characterized by 2*N*+1 unique coefficients, and in general, requires 2*N*+1 multipliers and 2*N* two-input adders for implementation
- **Direct form IIR filters** : Filter structures in which the multiplier coefficients are precisely the coefficients of the transfer function

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Direct Form IIR Digital Filter Structures Various other noncanonic direct form structures can be derived by simple block diagram manipulations as shown below Copyright © 2001, S. K. Mitra



Direct Form IIR Digital Filter Structures

- Likewise, the signal variables at nodes(2) and (2) are the same, permitting the sharing of the middle two delays
- Following the same argument, the bottom two delays can be shared
- Sharing of all delays reduces the total number of delays to 3 resulting in a canonic realization shown on the next slide along with its transpose structure

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Realization of Allpass Filters

- An *M*-th order real-coefficient allpass transfer function $A_M(z)$ is characterized by *M* unique coefficients as here the numerator is the mirror-image polynomial of the denominator
- A direct form realization of $A_M(z)$ requires 2M multipliers
- Objective Develop realizations of $A_M(z)$ requiring only *M* multipliers

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- The stability test algorithm described earlier in the course also leads to an elegant realization of an *M*th-order allpass transfer function
- The algorithm is based on the development of a series of (m-1)th-order allpass transfer functions $A_{m-1}(z)$ from an *m*th-order allpass transfer function $A_m(z)$ for m = M, M - 1, ..., 1

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 $\begin{array}{l} \textbf{Realization Using Two-Pair}_{\text{Extraction Approach}} \\ \textbf{Substitution Approach} \\ \textbf{Substitution Approach} \\ \textbf{Substitution Approach}_{\text{A}_{m}(z)} = \frac{d_{m} + d_{m-1}z^{-1} + d_{m-2}z^{-2} + \dots + d_{1}z^{-(m-1)} + z^{-m}}{1 + d_{1}z^{-1} + d_{2}z^{-2} + \dots + d_{m-1}z^{-(m-1)} + d_{m}z^{-m}} \\ \textbf{Substitution Approximate recursion} \\ \textbf{A}_{m-1}(z) = z[\frac{A_{m}(z) - k_{m}}{1 - k_{m}A_{m}(z)}], \quad m = M, M - 1, \dots, 1 \\ \text{where } k_{m} = A_{m}(\infty) = d_{m} \\ \textbf{Substitution Approximate results} \\ \textbf{Substitution Approximate results} \\ \textbf{A}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \text{for } m = M, M - 1, \dots, 1 \\ \textbf{B}_{m}^{2} < 1 \quad \textbf{B}_{m}^{2} < 1 \\ \textbf{B}_{m}^{2} < 1 \quad \textbf{B}_{m}^{2} < 1 \\ \textbf{B}_{m}^{2} < 1 \quad \textbf{B}_{m}^{2} < 1 \\ \textbf{B}_{m}^{2} < 1 \\$

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Realization Using Two-Pair Extraction Approach It follows from our earlier discussion that

- It follows from our earlier discussion that $A_M(z)$ is stable if the magnitudes of all multiplier coefficients in the realization are less than 1, i.e., $|k_m| < 1$ for m = M, M 1, ..., l
- The cascaded lattice allpass filter structure requires 2*M* multipliers
- A realization with *M* multipliers is obtained if instead the single multiplier two -pair is used

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