

ES 1)

5)

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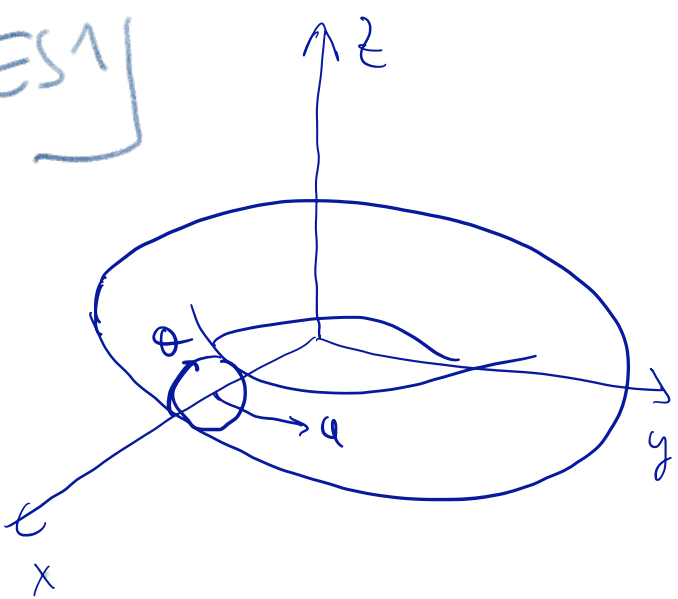
$$S = \int_{t_1}^{t_2} \left(\frac{m}{2} \dot{x}^2 + \frac{m\omega^2}{2} x^2 \right) dt$$

$$\delta S = \int_{t_1}^{t_2} (m \dot{x} \delta \dot{x} + m\omega^2 x \delta x) dt =$$

$$= \int_{t_1}^{t_2} (-m \ddot{x} + m\omega^2 x) \delta x dt \quad \leftarrow \overset{\delta x}{=} 0$$

se $x(t) = e^{i\omega t}$

ES 1



$$x = (R + r \cos \theta) \cos \varphi$$

$$y = (R + r \cos \theta) \sin \varphi$$

$$z = r \sin \theta$$

$$x^2 + y^2 = (R + r \cos \theta)^2$$

$$R > r$$

$$\dot{x} = -r \sin \theta \cos \varphi \dot{\theta} - (R + r \cos \theta) \sin \varphi \dot{\varphi}$$

$$\dot{y} = -r \sin \theta \sin \varphi \dot{\theta} + (R + r \cos \theta) \cos \varphi \dot{\varphi}$$

$$\dot{z} = r \cos \theta \dot{\theta}$$

$$T = \frac{m}{2} (\dot{x}^2 + \dot{y}^2 + \dot{z}^2) = \frac{m}{2} (r^2 \dot{\theta}^2 + (R + r \cos \theta)^2 \dot{\varphi}^2)$$

$$V = \frac{k}{2} (R + r \cos \theta)^2$$

$$Q = \begin{pmatrix} m r^2 & 0 \\ 0 & m (R + r \cos \theta)^2 \end{pmatrix}$$

1) $L = T - V \leftarrow$ Non dipende da φ .

$$2) \frac{d}{dt} \frac{\partial L}{\partial \dot{\varphi}} = \frac{d}{dt} (m (R + r \cos \theta)^2 \dot{\varphi}) = -2m (R + r \cos \theta) r \sin \theta \dot{\theta} \dot{\varphi} + m (R + r \cos \theta)^2 \ddot{\varphi}$$

eq. Lap: $\ddot{\varphi} = \frac{2r \sin \theta}{R + r \cos \theta} \dot{\theta} \dot{\varphi}$

3) φ ciclico

$$p_{\varphi} = \frac{\partial L}{\partial \dot{\varphi}} = m (R + r \cos \theta)^2 \dot{\varphi} = l \rightarrow \varphi = \frac{l}{m (R + r \cos \theta)^2}$$

\uparrow cost. del moto

$$4) L^* = \frac{m}{2} r^2 \dot{\theta}^2 - \frac{l^2}{2m (R + r \cos \theta)^2} - \frac{k}{2} (R + r \cos \theta)^2$$

$$V_{eff} = \frac{l^2}{2m (R + r \cos \theta)^2} + \frac{k}{2} (R + r \cos \theta)^2$$

5)

$$V'_{eff} = + \frac{l^2 r \sin \theta}{m (R+r \cos \theta)^3} - k(R+r \cos \theta) \sin \theta = 0$$

$$\frac{l^2 r \sin \theta}{m (R+r \cos \theta)^3} \left[1 - \frac{km}{rl^2} (R+r \cos \theta)^4 \right]$$

$$\theta = 0, \pi$$

$$e \quad R+r \cos \theta = \left(\frac{rl^2}{km} \right)^{1/4}$$

$$\rightarrow \cos \theta^* = \left(\frac{l^2}{kmr^3} \right)^{1/4} - \frac{R}{r}$$

$$\exists \text{ se } \uparrow \quad (R-r)^4 < \frac{rl^2}{km} < (R+r)^4$$

$$V''_{eff} = + \frac{3l^2 r^2 \sin^2 \theta}{m (R+r \cos \theta)^4} + \frac{l^2 r \cos \theta}{m (R+r \cos \theta)^3} - k(R+r \cos \theta) \cos \theta + kr \sin^2 \theta$$

$$V''_{eff}(0) = \frac{l^2}{m} \frac{r}{(R+r)^3} - k(R+r) \rightarrow \text{stab. e } \frac{rl^2}{km} > (R+r)^4$$

$$V''_{eff}(\pi) = - \frac{l^2}{m} \frac{r}{(R-r)^3} + k(R-r) \rightarrow \text{stab. e } \frac{rl^2}{km} < (R-r)^4$$

$$V''_{eff}(\theta^*) = \frac{3l^2}{m} r^2 (1 - \cos^2 \theta^*) \cdot \frac{km}{rl^2} + \frac{rl^2}{m} \frac{\cos \theta^*}{\left(\frac{km}{rl^2} \right)^{3/4}} = \dots$$

θ^* è STABILE purché V_{eff} è continua e $\theta = 0, \pi$ sono INSTAB. quindi $\pm \theta^*$ esistono

6) $k=0 \rightarrow \theta^*$ non esiste come solut. e $\theta=0$ e' STAB.

$$\omega^2 = \frac{V_{eff}''(0)}{mr^2} = \frac{l^2}{m^2 r^2} \frac{r}{(r+R)^3}$$

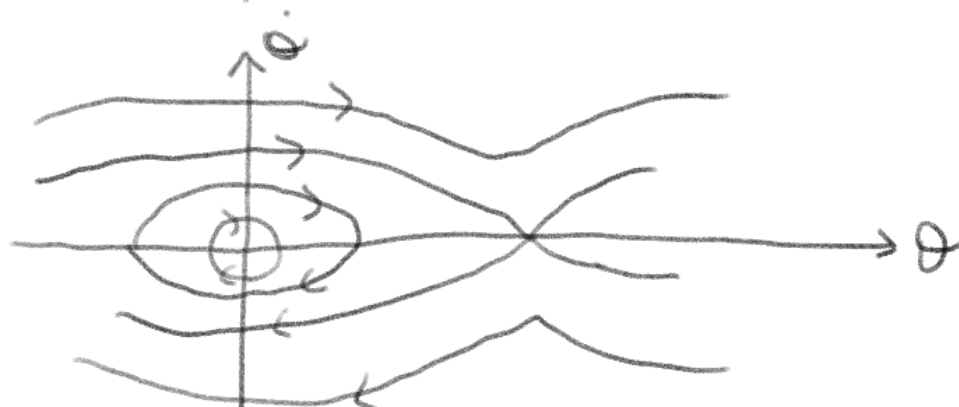
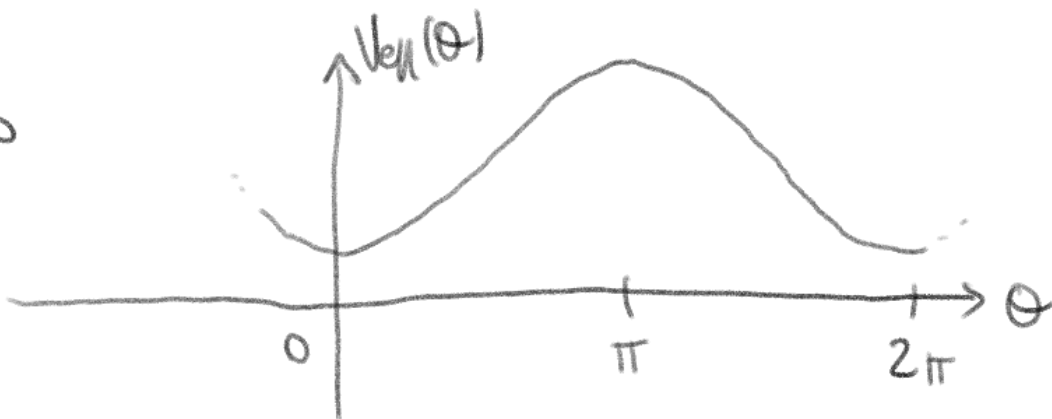
$$L^* = \frac{1}{2} m r^2 \dot{\theta}^2 - \frac{l^2}{2m(R+r \cos \theta)^2} \quad \theta = 0 + \delta \theta$$

$$\approx \frac{1}{2} m r^2 \delta \dot{\theta}^2 - \frac{l^2}{2m(R+r)^2 \left(1 - \frac{r \delta \theta^2}{2(R+r)}\right)^2}$$

$$\approx \frac{1}{2} m r^2 \delta \dot{\theta}^2 - \frac{l^2}{2m(R+r)^2} \left(1 + \frac{r \delta \theta^2}{R+r}\right)$$

$$= \frac{1}{2} m r^2 \delta \dot{\theta}^2 - \frac{1}{2} m r^2 \omega^2 \delta \theta^2$$

7) $k=0$



ES. 3 $\varphi_0(q) = a_0 e^{-q^2/2}$

$$A \varphi_0 = \frac{a_0}{\sqrt{2}} \left(q + \frac{d}{dq} \right) e^{-q^2/2} = \frac{a_0}{\sqrt{2}} (q - q) e^{-q^2/2} = 0$$

$$A^+ A \varphi(q) = \frac{1}{2} \left(q - \frac{d}{dq} \right) \left(q + \frac{d}{dq} \right) \varphi(q) =$$

$$= \frac{1}{2} \left(q - \frac{d}{dq} \right) (q\varphi + \varphi') =$$

$$= \frac{1}{2} (q^2\varphi + \cancel{q\varphi'} - \cancel{q\varphi'} - \varphi - \varphi'') =$$

$$= \frac{1}{2} (-\varphi'' + q^2\varphi) - \frac{\varphi}{2} = \frac{1}{\hbar\omega} \hat{H} - \frac{1}{2} \mathbb{1}$$

$$H\varphi = -\frac{\hbar^2}{2m} \varphi'' + \frac{1}{2} m\omega^2 x^2 \varphi = -\frac{\hbar^2}{2m} \frac{m\omega}{\hbar} \varphi'' + \frac{1}{2} m\omega^2 \frac{\hbar}{m\omega} q^2 \varphi =$$

$$= \hbar\omega \left(-\frac{\varphi''}{2} + q^2\varphi \right)$$

$$\Rightarrow A^+ A \psi_1 = \left(\frac{1}{\hbar\omega} \hat{H} - \frac{1}{2} \mathbb{1} \right) \psi_1 = \left(\frac{1}{\hbar\omega} \hbar\omega \left(1 + \frac{1}{2} \right) - \frac{1}{2} \right) \psi_1 = \psi_1$$