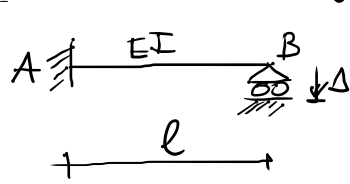
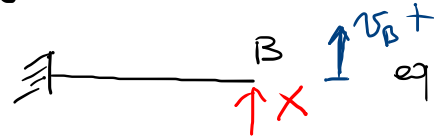


IPERST. CON CEDIM. ANELASTICO

SDC 1371W, 20/12/23



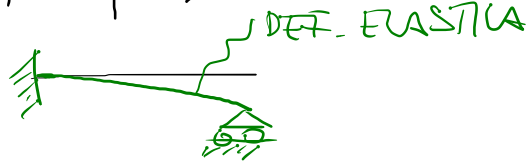
⇒ S.P. 1



eq di congruenza

$$v_B = -\Delta$$

$$M, T = f(\Delta)$$

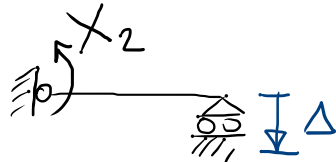


$$\frac{X l^3}{3EI} = -\Delta \Rightarrow X = -\frac{3EI}{l^3} \Delta$$

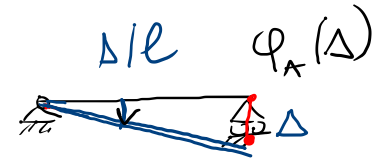
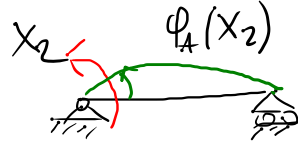


T COSTANTE

⇒ S.P. 2



$$\phi_A = 0$$

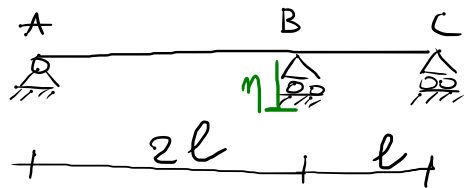


CATENA CINEMATICA

$$\phi_A(x_2) + \phi_A(\Delta) = 0 ; \frac{x_2 l}{3EI} - \frac{\Delta}{l} = 0 ; x_2 = +\frac{EI}{l^2} 3 \Delta$$

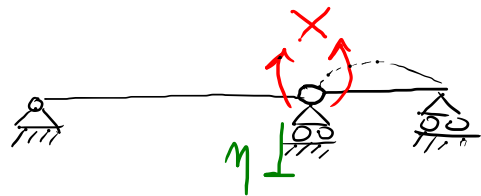


ES



1 V IPERST. $\Rightarrow$ STATO COAZIONE $f(\eta)$

S.p.

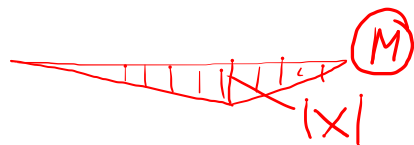
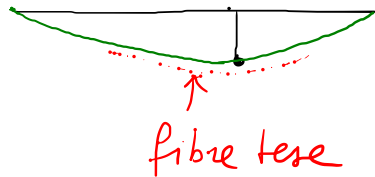
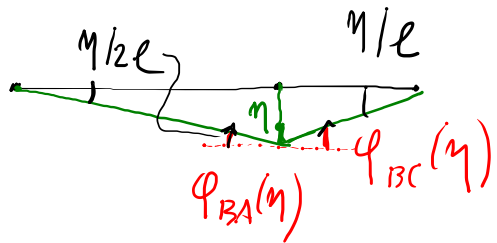


$$+ \varphi_{BA} = \varphi_{BC}$$

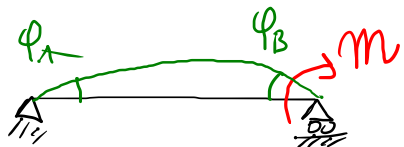
$$\left[-\frac{X \cdot 2l}{3EI} - \frac{\eta}{2l} = \frac{X \cdot l}{3EI} + \frac{\eta}{l} \right]$$

$$\Rightarrow X = X(\eta) \rightarrow M(\eta), T(\eta)$$

$$X < 0$$



PREPARAZIONE AL METODO DEGLI SPOSTAMENTI: SCHEMI ELEMENTARI



$$\varphi_A = \frac{m l}{6EI}; \quad \varphi_B = \frac{m l}{3EI}$$

$$m = \left(\frac{3EI}{l} \right) \varphi_B$$

$$m = \left(\frac{EI}{l} \right) \varphi_B$$

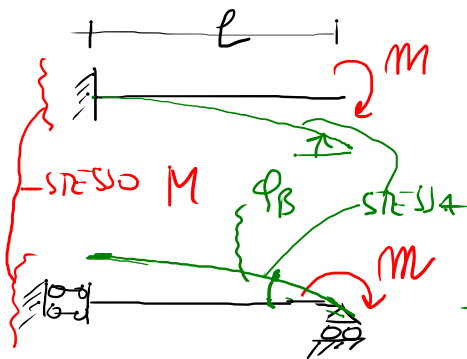


RIGIDEZZA ROTAZIONALE

$$m = K_\varphi \varphi$$

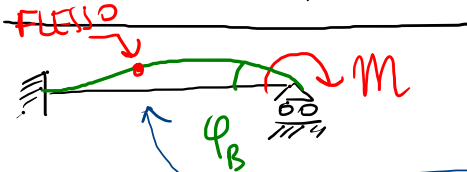
$$[FL] = [FL][\quad]$$

|
Nm



$$\varphi_B = \frac{m l}{EI}$$

DEFORMATA



$$m = K_\varphi \varphi_B$$



$$\varphi_A = 0$$

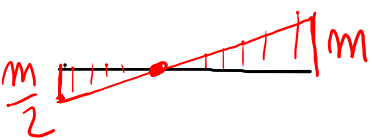


$$+\frac{Xl}{3EI} + \frac{ml}{6EI} = 0$$

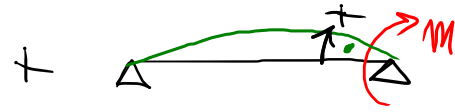
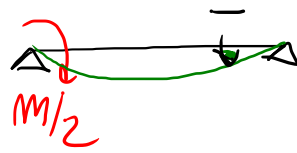
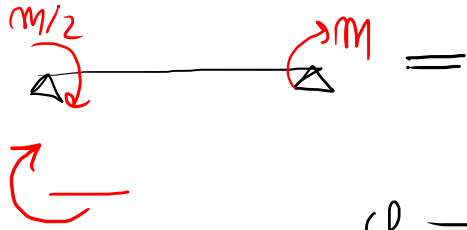
$$X = -\frac{m}{2}$$



SCL EQUILIBRO e CONGRUENZE



$\varphi_B?$



$\varphi_B =$

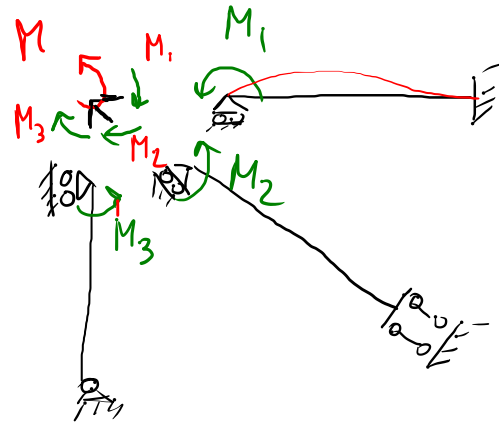
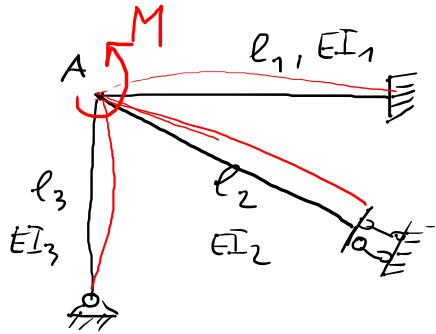
$$-\frac{m}{2} \frac{l}{6EI}$$

$$+\frac{ml}{3EI} = \frac{-1+4}{12} = +\frac{ml}{4EI}$$

$$m = \frac{4EI}{l} \varphi_B$$

METODO DEGLI SPOSTAMENTI (DELL'EQUILIBRIO) FORZE (DELLA CONGRUENZA)

TELAIO AD UN NODO FISSO



φ_A : ROTAZIONE DEL NODO φ_A INCOGNITA

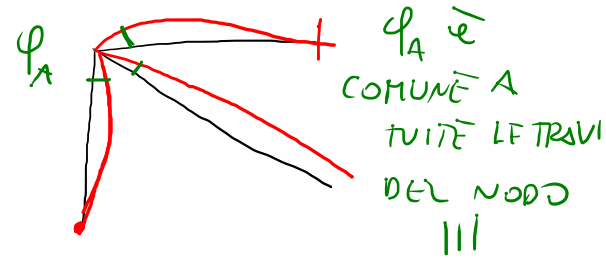
EQ. EQUILIBRIO DEL NODO A: $\curvearrowright^+$

$$M_1 + M_2 + M_3 - M = 0$$

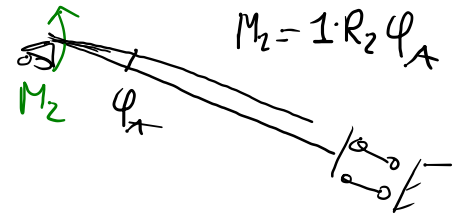
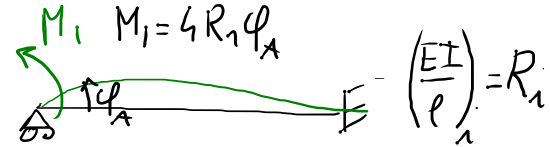
$$4R_1\varphi_A + R_2\varphi_A + 3R_3\varphi_A = M$$

φ_A : INCOGNITA

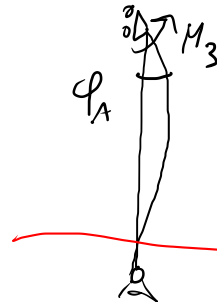
$$\varphi_A (4R_1 + R_2 + 3R_3) = M$$



CONGRUENZA



$$M_2 = 1 \cdot R_2 \varphi_A$$



$$M_3 = 3 \cdot R_3 \varphi_A$$

$$\varphi_A = \varphi_A(M)$$

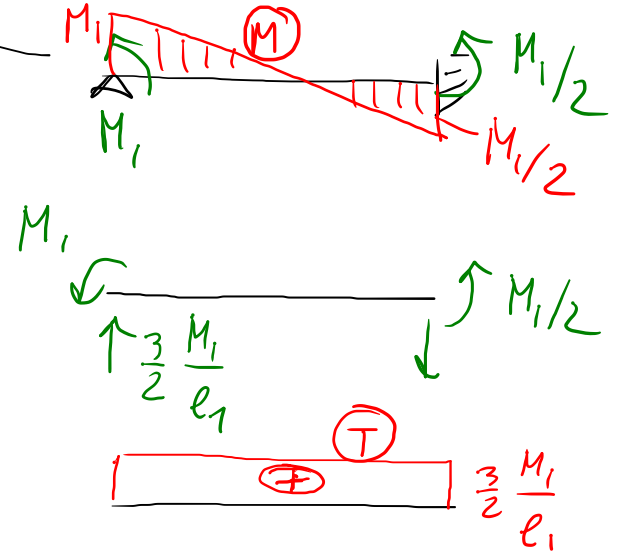
NOTO φ_A

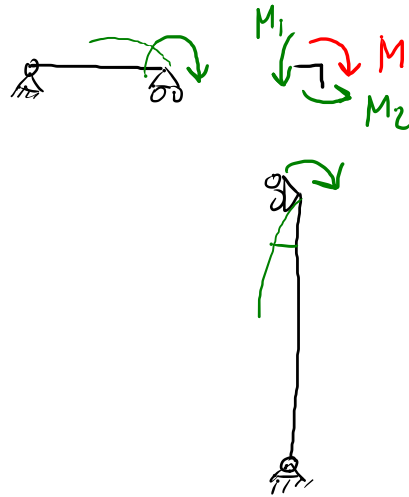
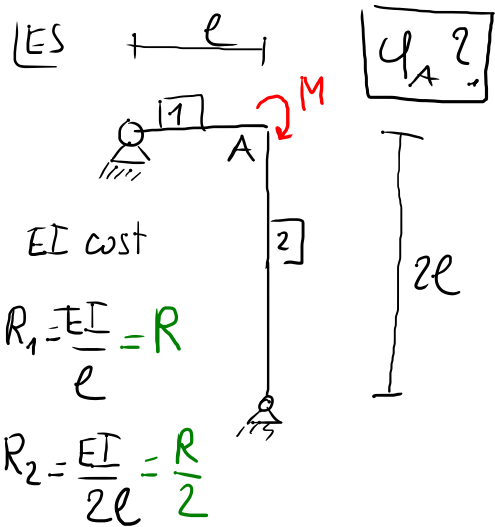
$$M_1 = 4R_1 \frac{M}{\sum_{i=1}^3 c_i R_i} \varphi_A$$

$$M_2 = R_2 \frac{M}{\sum_{i=1}^3 c_i R_i}$$

$$M_3 = 3R_3 \frac{M}{\sum_{i=1}^3 c_i R_i}$$

$$c_1 = 4, c_2 = 1, c_3 = 3$$





$$M_1 = 3R\varphi_A = 3R \frac{2}{3} \frac{M}{R} = \frac{6}{3} M$$

$$M_2 = 3 \frac{R}{2} \varphi_A = \frac{3}{2} R \frac{2}{3} \frac{M}{R} = \frac{3}{3} M$$

M



EQUILIBRIO ($\downarrow +$): $M - M_1 - M_2 = 0$

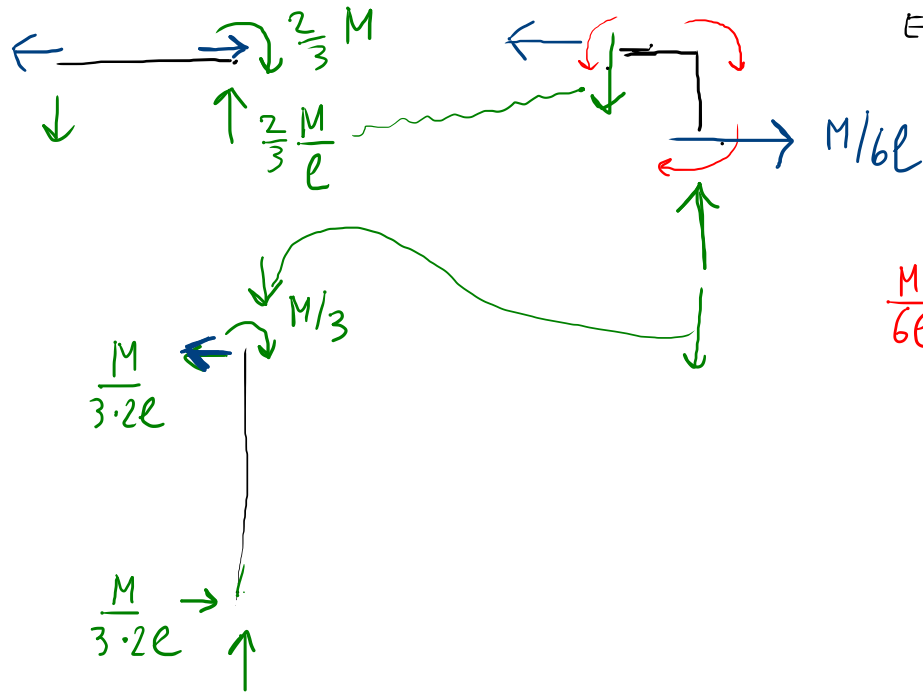
$$M = M_1 + M_2 = 3R_1\varphi_A + 3R_2\varphi_A$$

$$\varphi_A = \frac{M}{3R_1 + 3R_2} = \frac{M}{3R + \frac{3}{2}R} = \frac{M}{R} \frac{1}{\frac{6+3}{2}} = \frac{M}{R} \frac{2}{9}$$

VISTO CHE $R_2 = \frac{R_1}{2}$ e $c_1 = c_2 = 3 \Rightarrow$

$$\Rightarrow M_2 = \frac{M_1}{2}$$

LE TRAVI PIÙ "RIGIDE" NEL NODO
ASSORBONO UN'ALiquOTA MAGGIORE
DI MOMENTO



EQUIL. COMPLETO NEL NODO
 ANCHE CON TAGLI E FORZE NORMALI
 DELLE TRAVI CORRISPONDENTI

