

# Eco-Doppler

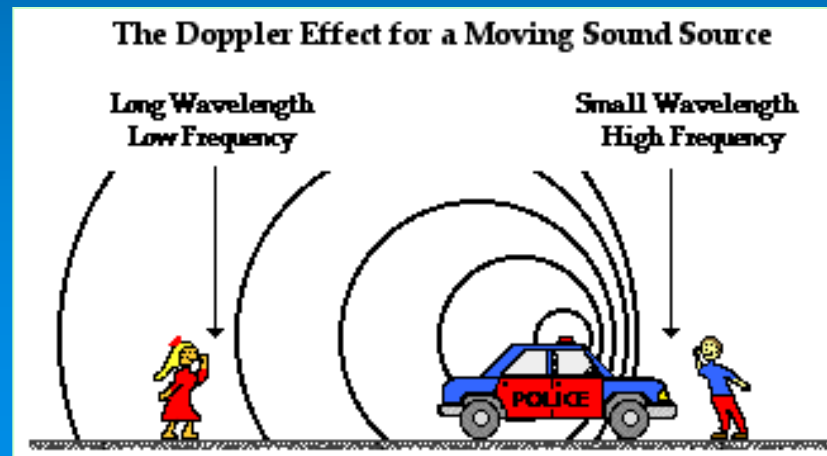
✓ Ultrasound (US) is a relatively inexpensive, portable, safe, and real-time modality, all of which make it one of the most widely used imaging modalities in medicine

✓ In addition, the Doppler effect is used to make quantitative measurements of absolute blood velocity and to map blood flow over a large field of view (FOV) in a semiquantitative manner

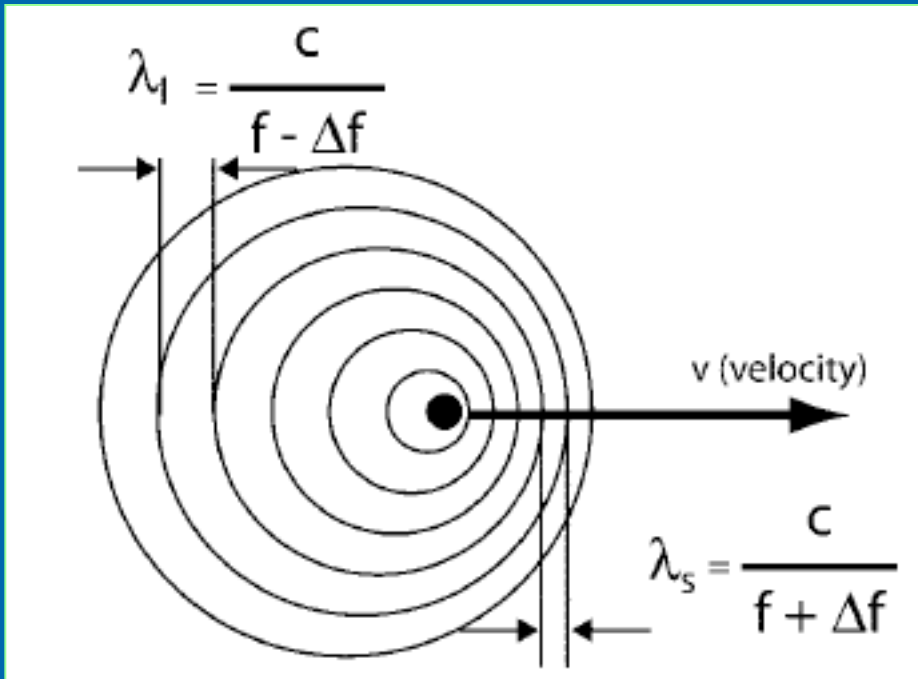
*N.J. Hangiandreou RadioGraphics 2003; 23:1019–1033*

# Doppler effect

- The Doppler effect produced with US to determine whether flow is present
  - It has been used in medicine for ~ 50 years
- The underlying physics of the Doppler effect is simple
- Instrumentation and how the information is applied for diagnosis can be complex
  - involves a number of assumptions



# Doppler effect



$$\lambda_1 = \frac{c + v}{f} = \frac{c}{f - \Delta f}$$
$$\lambda_s = \frac{c - v}{f} = \frac{c}{f + \Delta f}$$

These equations apply to the specific condition that the object is traveling either directly toward or directly away from the observer

$c$  = speed of sound propagation

$v$  = velocity of the moving object

$f$  = frequency of the sound

$\lambda_1 \lambda_s$  wavelengths lengthened or shortened

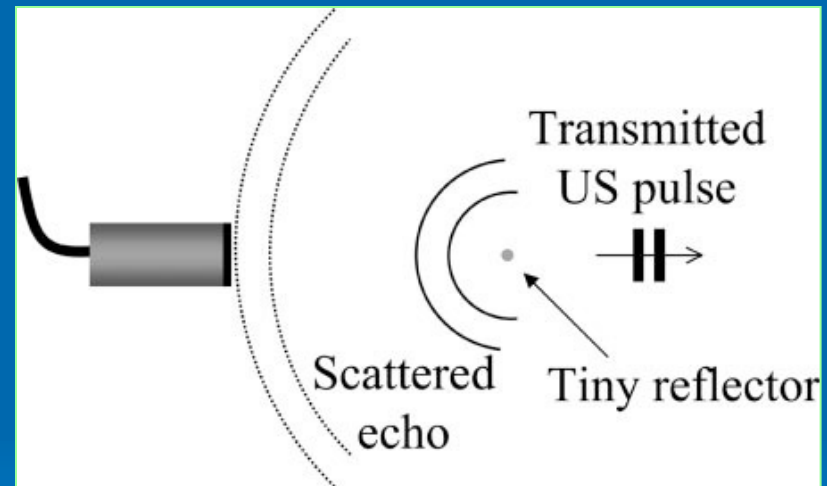
$\Delta f$  = Doppler effect– induced frequency shift

# Doppler effect blood flow

## US scattering back from moving objects

- Eg: red blood cells

- I. Doppler effect with the sound arriving at the moving scattering object
- II. Doppler effect as the sound is reflected from that object back toward the US transducer

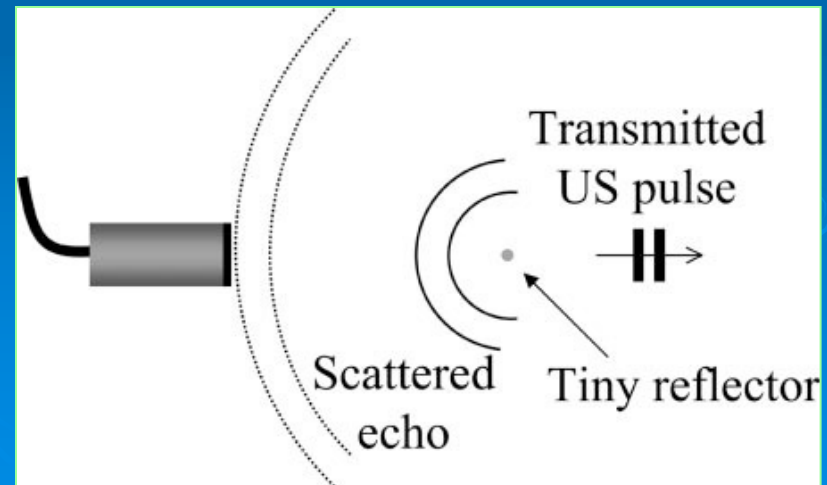


# Doppler effect blood flow

- US scattering back from red blood cells
  - $c = 1540$  m/s
  - $f_0$  frequency of sound produced in a transducer,
    - propagating toward a red blood cell
  - $v_{RBC}$  velocity of the red blood cell
  - $f_{RBC}$  frequency of the sound as it is perceived by the red blood cell

$$f_0 = \frac{c}{\lambda_0} \rightarrow \lambda_0 = \frac{c}{f_0}$$

$$f_{RBC} = \frac{c + v_{RBC}}{\lambda_0} = f_0 + \frac{v_{RBC}}{\lambda_0}$$

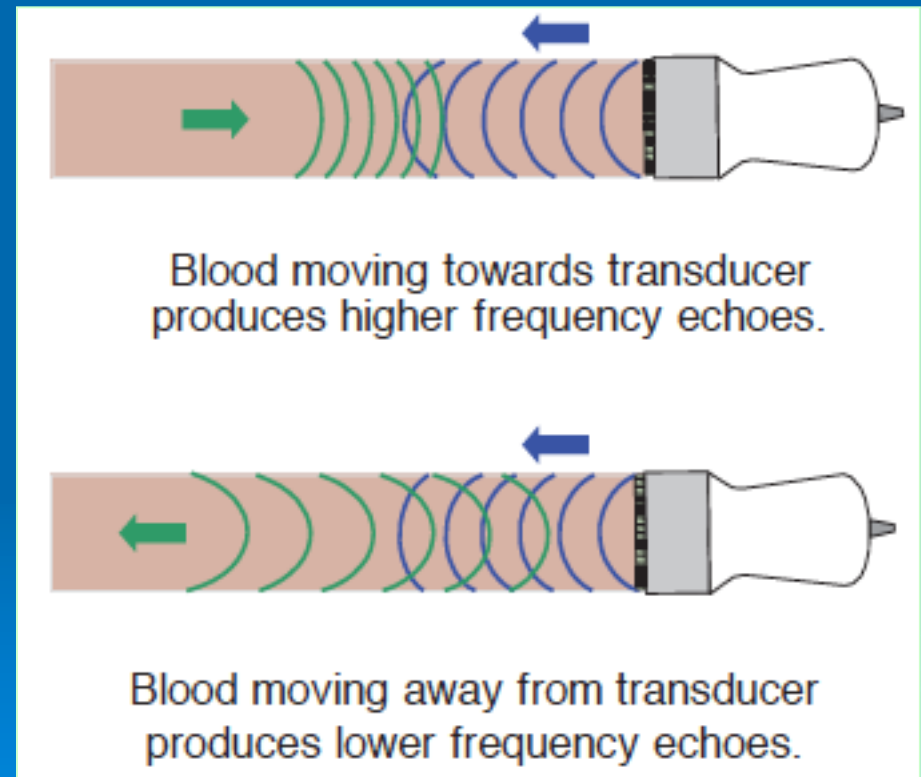


# Frequency returning back I

$$f' = f_{\text{RBC}} + \frac{v_{\text{RBC}}}{\lambda_{\text{RBC}}}$$
$$= f_0 + \frac{v_{\text{RBC}}}{\lambda_0} + \frac{v_{\text{RBC}}}{\lambda_{\text{RBC}}}$$

- The frequency of sound arriving back at the transducer ( $f'$ ) is shifted again in proportion to the  $v_{\text{RBC}}$

- $\lambda_{\text{RBC}} = c / f_{\text{RBC}}$





# Frequency returning back II

**f'** in terms of

- $v_{\text{RBC}}$
- $f_0$  the original frequency
- $c$  the speed of sound

$$\begin{aligned} f' &= f_0 + \frac{v_{\text{RBC}}}{\lambda_0} + \frac{v_{\text{RBC}}}{\lambda_{\text{RBC}}} \\ &= f_0 + \frac{v_{\text{RBC}} f_0}{c} + \frac{v_{\text{RBC}} f_{\text{RBC}}}{c} \\ &= f_0 + \left( \frac{v_{\text{RBC}}}{c} \right) (f_0 + f_{\text{RBC}}) \\ &= f_0 + \left( \frac{v_{\text{RBC}}}{c} \right) \left( f_0 + f_0 + \frac{v_{\text{RBC}}}{\lambda_0} \right) \\ &= f_0 + \left( \frac{v_{\text{RBC}}}{c} \right) \left( 2 \cdot f_0 + \frac{v_{\text{RBC}} f_0}{c} \right) \\ &= f_0 + 2f_0 \left( \frac{v_{\text{RBC}}}{c} \right) + f_0 \left( \frac{v_{\text{RBC}}}{c} \right)^2. \end{aligned}$$

# Doppler shift frequency

$$\begin{aligned}f_D &= f' - f_0 \\&= f_0 + 2f_0\left(\frac{v_{\text{RBC}}}{c}\right) + f_0\left(\frac{v_{\text{RBC}}}{c}\right)^2 - f_0 \\&= \frac{2f_0 v_{\text{RBC}}}{c} + f_0\left(\frac{v_{\text{RBC}}}{c}\right)^2.\end{aligned}$$

Since  $v_{\text{RBC}} \ll c$

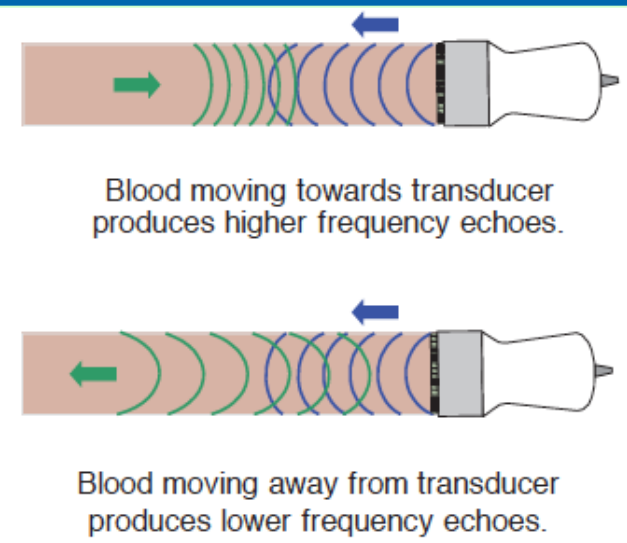
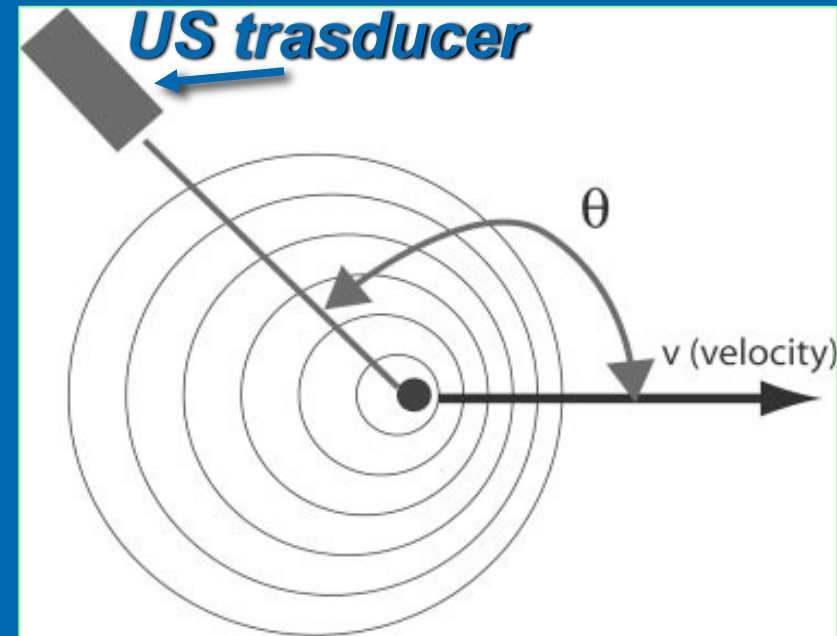
$$f_D \cong \frac{2f_0 v_{\text{RBC}}}{c}$$

$v_{\text{RBC}} \sim 0.1\% c$



# General geometry

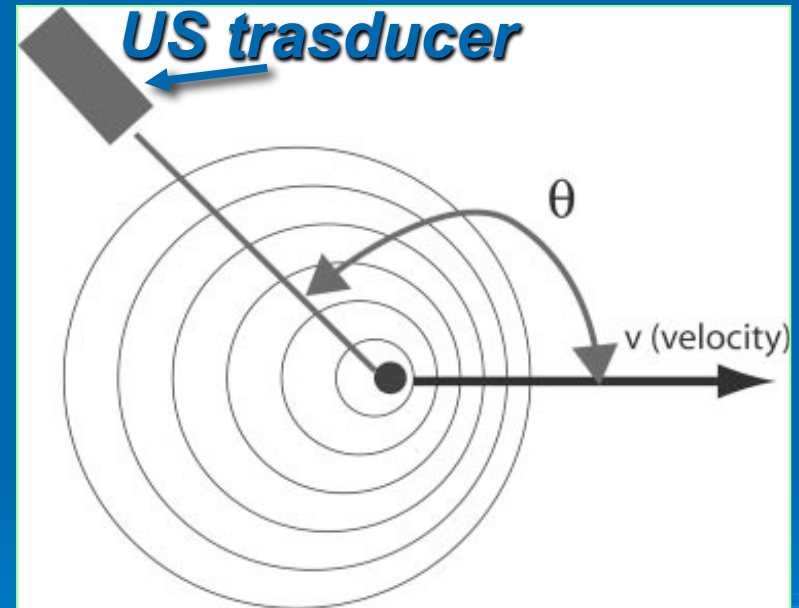
- The relative velocity between the RBC and the transducer is dependent on the angle of the line down which the US is traveling and the direction of the RBC motion
  - If the RBC were traveling directly toward the transducer the relative velocity would be at a maximum
    - or the negative maximum



# General geometry

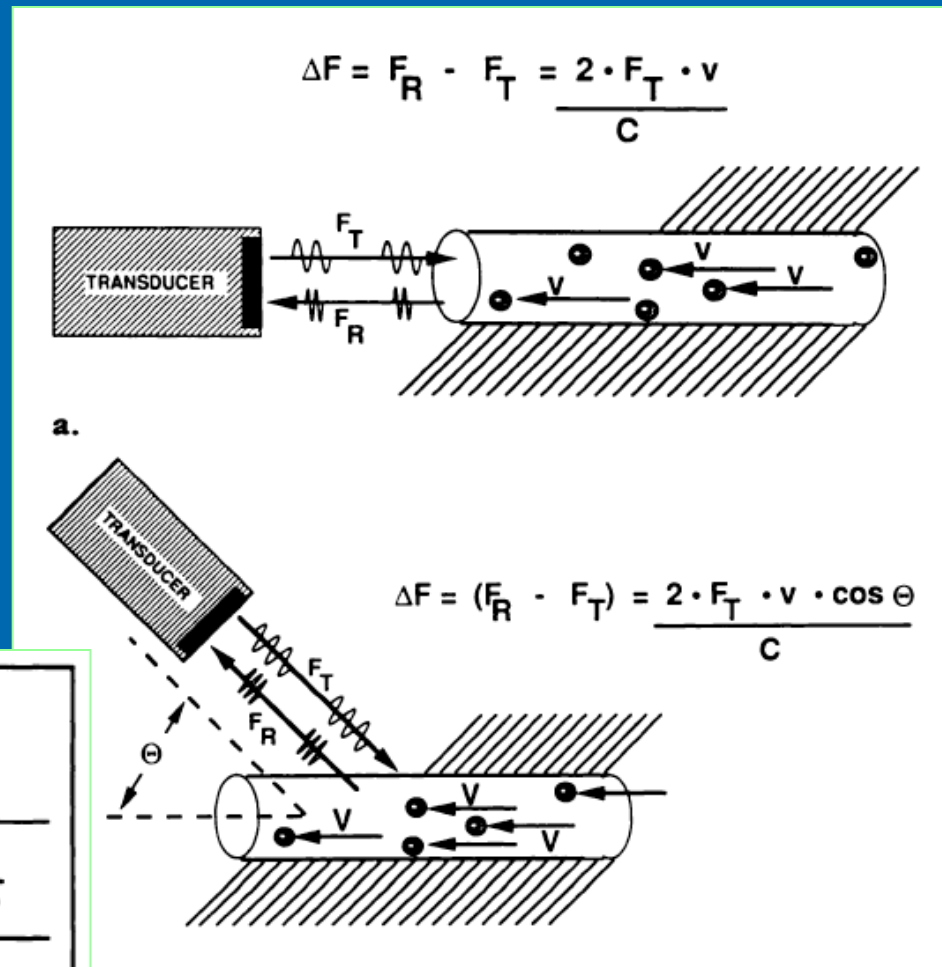
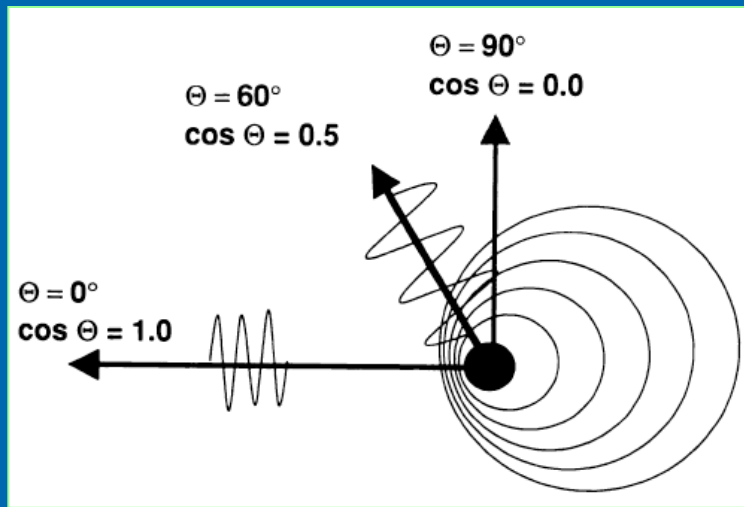
$$f_D = \Delta f = \frac{2 \cdot f_0 \cdot v_r}{c}$$
$$= \frac{2 \cdot f_0 \cdot v_{RBC} \cdot \cos \theta}{c}$$

$$v_{RBC} = \frac{f_D}{f_0} \cdot \frac{c}{2 \cdot \cos \theta}$$
$$= \left( \frac{f' - f_0}{f_0} \right) \cdot \frac{c}{2 \cdot \cos \theta}$$



- $v_{RBC}$  is estimated by  $\Delta f$ ,  $f_0$  and  $\cos \theta$
- $v_r$  relative velocity between the RBC and the transducer

# General geometry



The frequency shift is in the audible range: 15 Hz to 20 kHz

**Table 1**  
**Doppler Frequency Shifts (kHz) for a Target**  
**Moving 1.00 m/sec**

| $F_T$ (kHz) | Scanning Angles |            |            |            |
|-------------|-----------------|------------|------------|------------|
|             | $0^\circ$       | $45^\circ$ | $60^\circ$ | $80^\circ$ |
| 2.0         | 2.6             | 1.8        | 1.3        | 0.5        |
| 2.5         | 3.2             | 2.3        | 1.6        | 0.6        |
| 3.0         | 3.9             | 2.8        | 1.9        | 0.7        |
| 5.0         | 6.5             | 4.6        | 3.2        | 1.1        |
| 7.5         | 9.7             | 6.8        | 4.9        | 1.6        |

*C.R.B. Merritt*

*RadioGraphics 1991; 11:109-119*

# Doppler US

## Limitations in clinical practice:

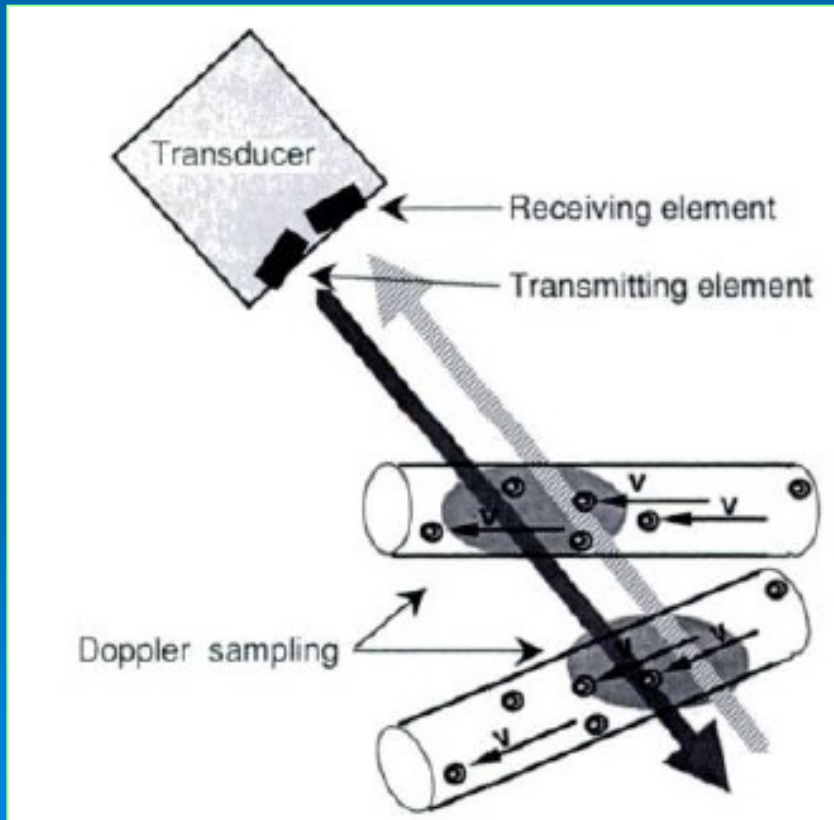
- the geometry of the blood vessel and the ultrasound beam
- varying blood flow velocities across the vessel lumen
- the variation of blood flow velocity with the cardiac cycle

Compromises are used to achieve an efficient measurement of blood velocity that can be resolved in both time and space

<https://www.youtube.com/watch?v=9nzkF0hmy04>

# Basic Doppler US Technology

## Continuous-wave Doppler US



**Continuous wave:**

- sound is emitted from a transmitting transducer 100% of the time
- echoes back must be detected by a second receiving transducer

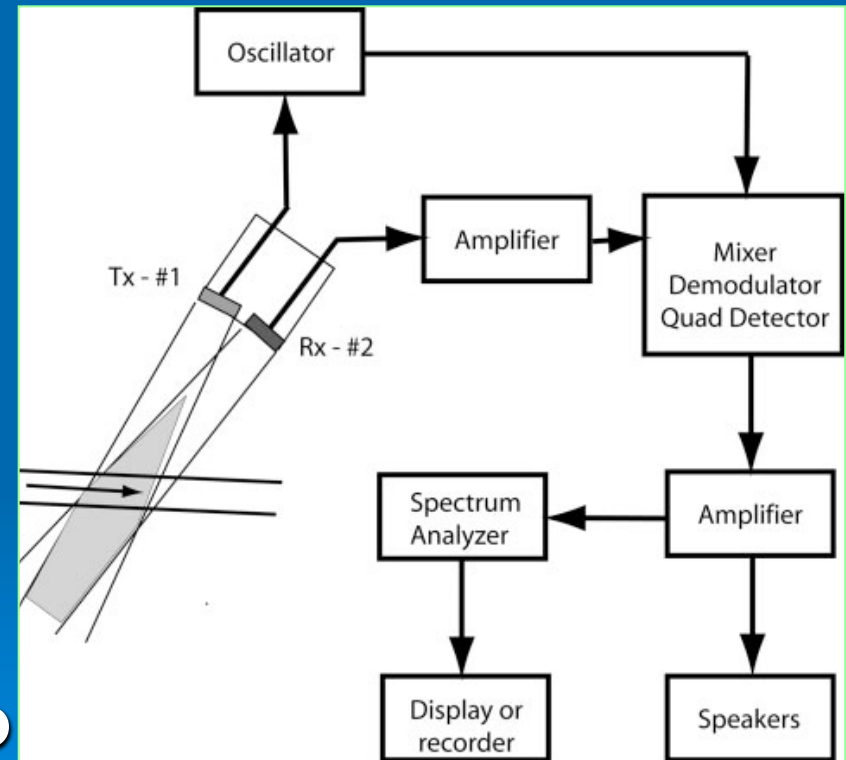
*The continuous wave Doppler system is the simplest and least expensive device for measuring blood velocity*



# Basic Doppler US Technology

## Continuous-wave Doppler US

- **Transducer #1:**  
continuous sound source
- **Transducer #2:**  
backscattered sound detector
- **Analysis circuit:**  
the outgoing signal frequency is compared with the returning signal to determine the shift in frequency



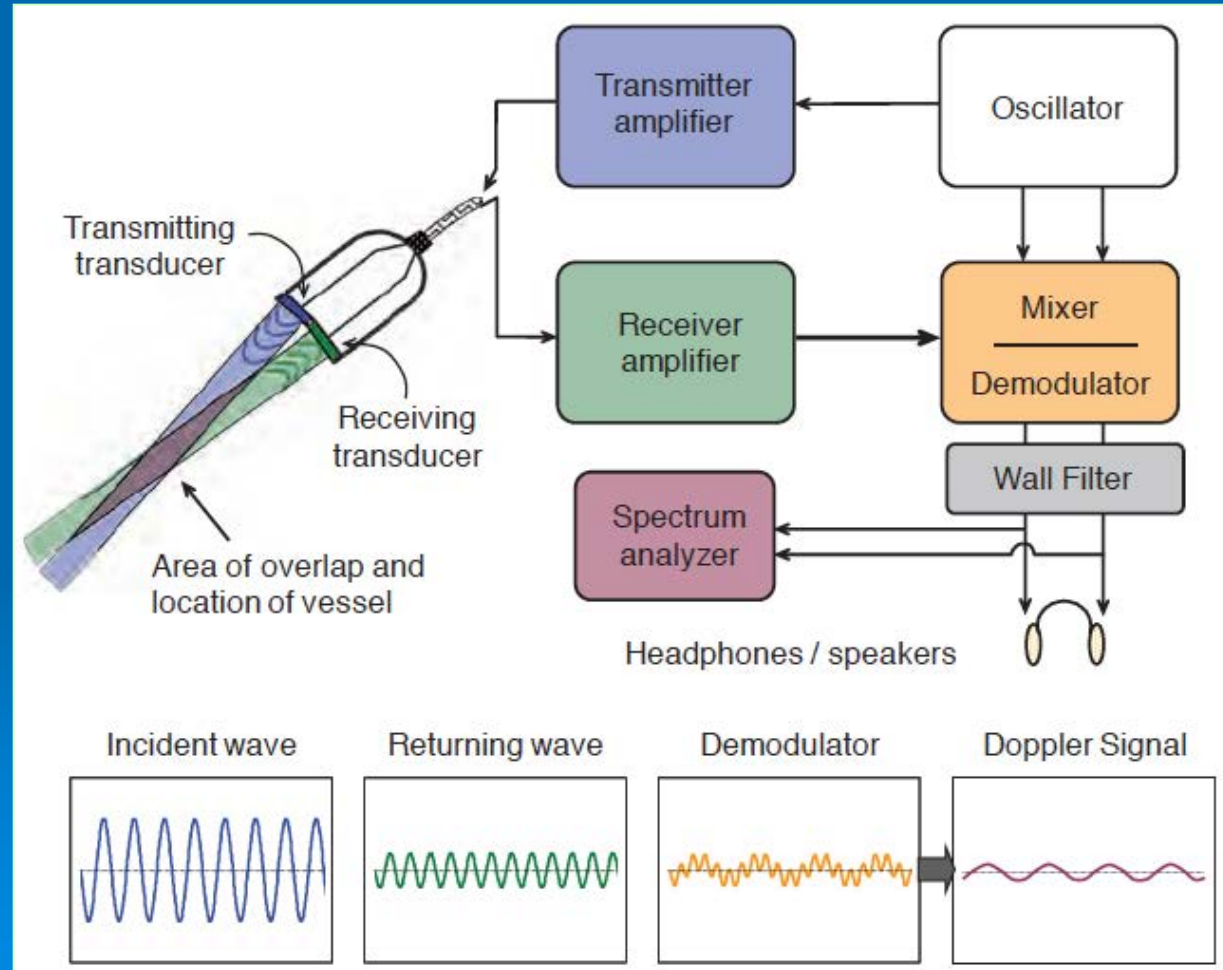


# Basic Doppler US Technology

## Continuous-wave Doppler US

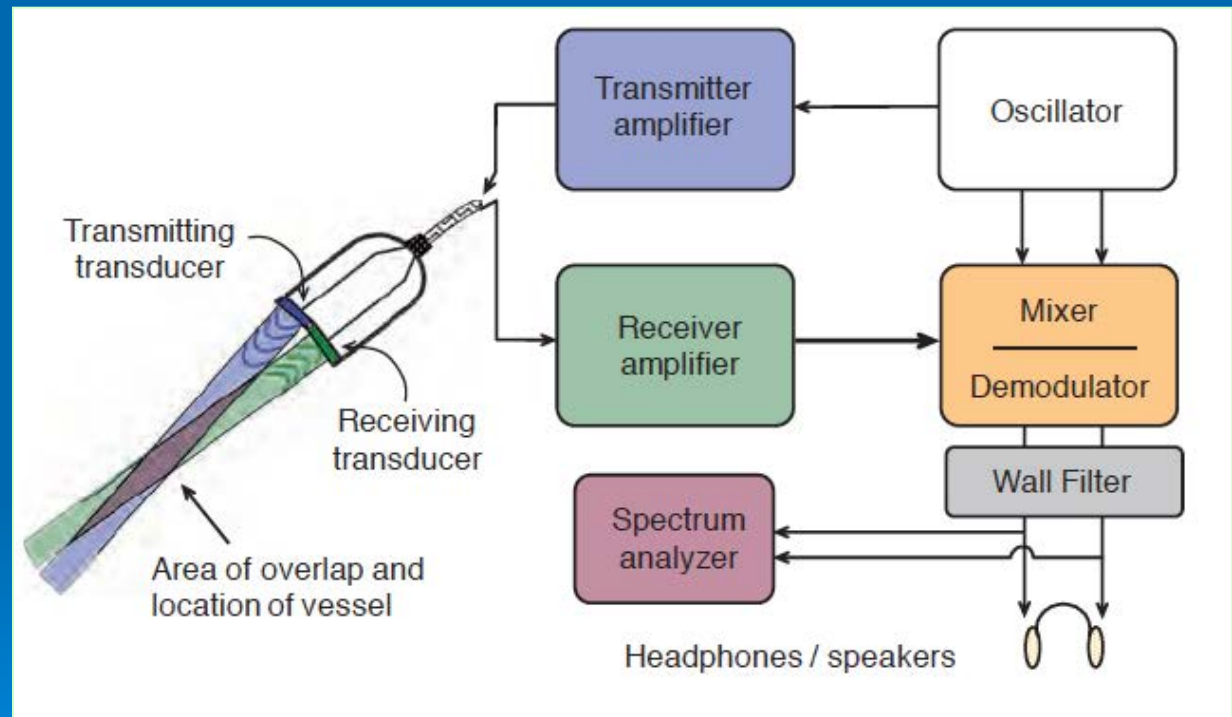
Signals comparison by mixing the transmitted with the incoming signal then filtering out the high-frequency result

- mixing-demodulation



# Continuous-wave Doppler US

- Continuous wave Doppler suffers from depth selectivity
- Overlying vessels will result in superimposition

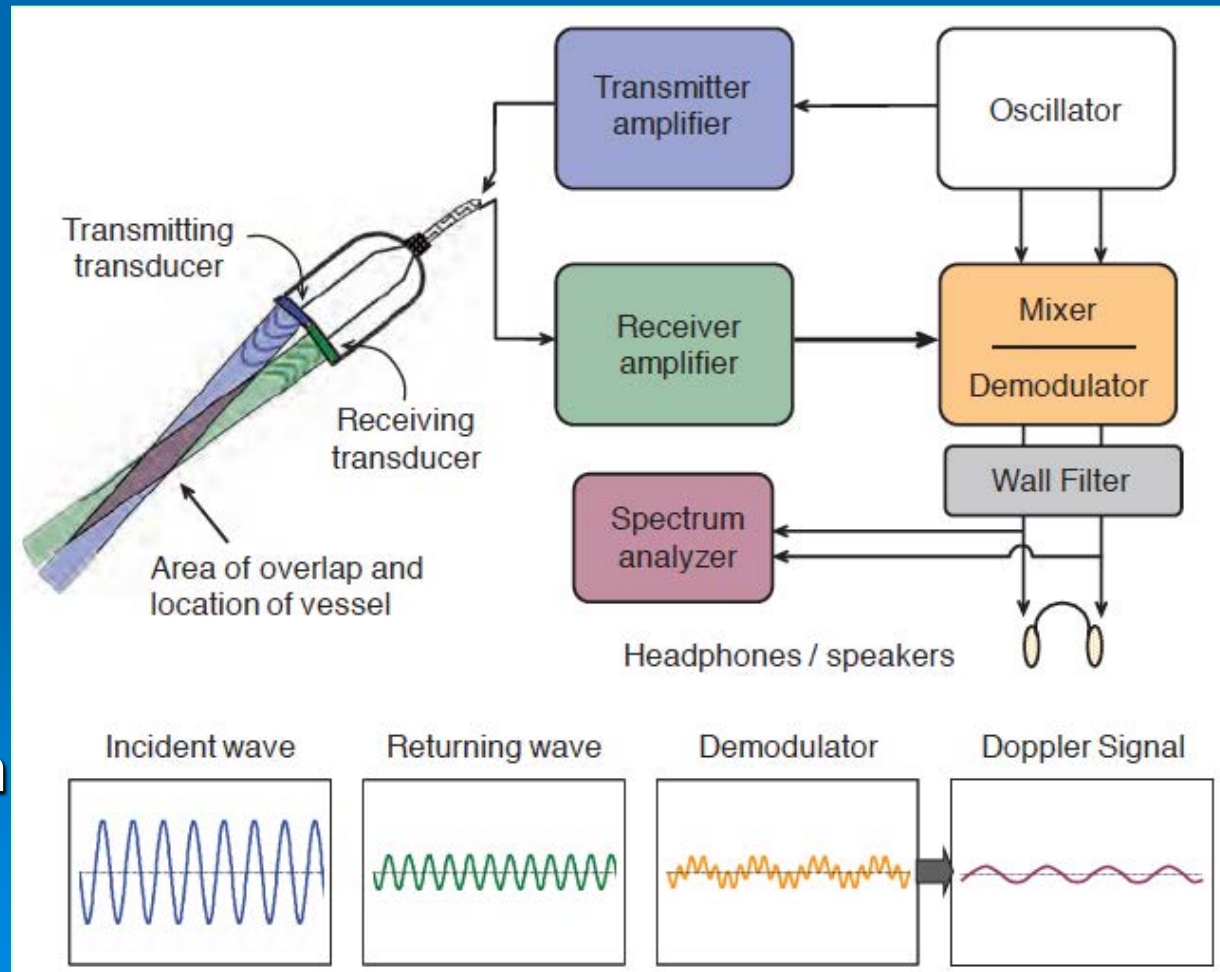


# Continuous-wave Doppler US

## Advantages:

➤ high accuracy of the Doppler shift measurement because a narrow frequency bandwidth is used

- no aliasing when high velocities are measured



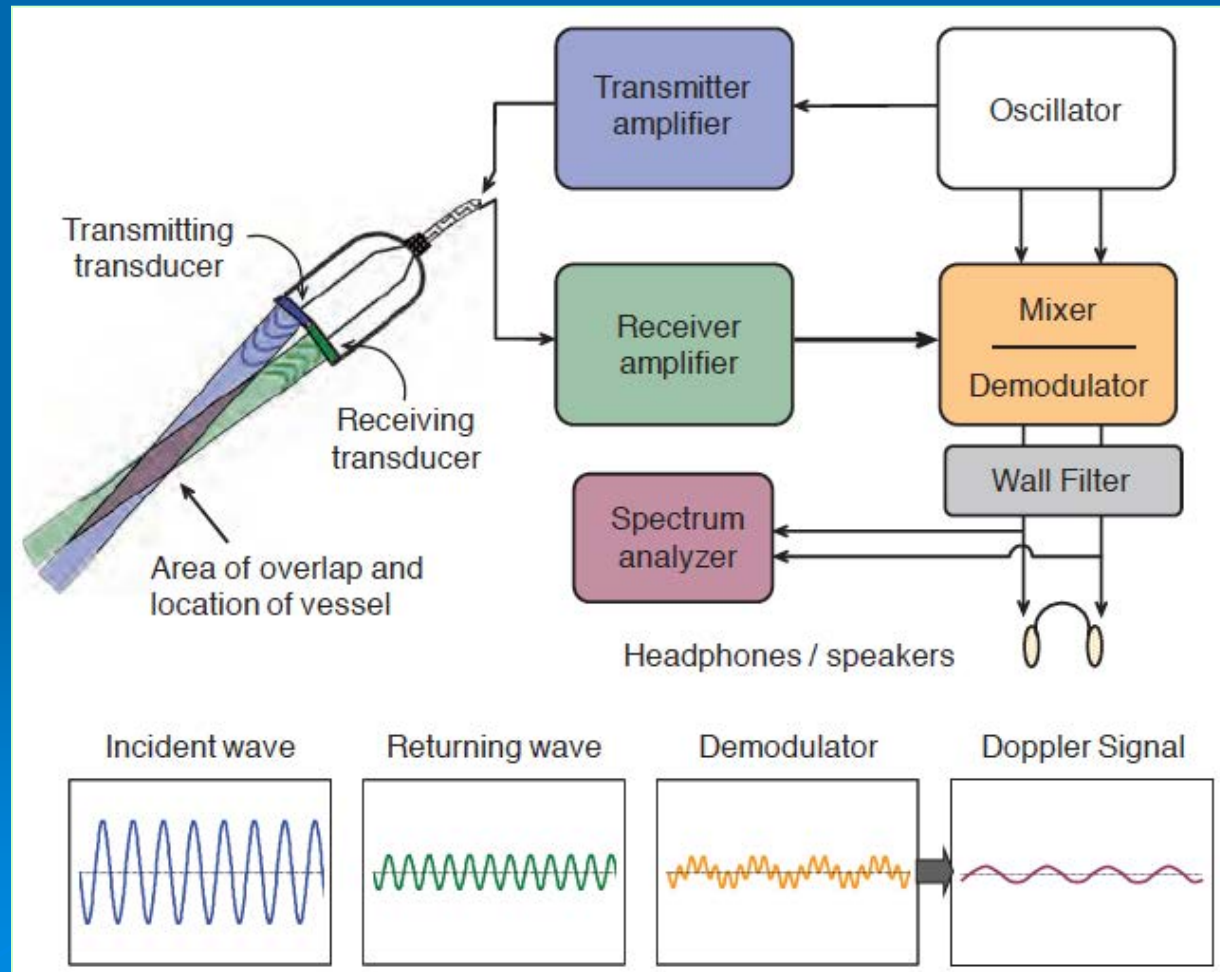
# Continuous-wave Doppler US

## Quadrature detection

➤ The demodulation technique measures the magnitude but does not reveal the direction of the Doppler shift

➤ flow toward or away from the transducers

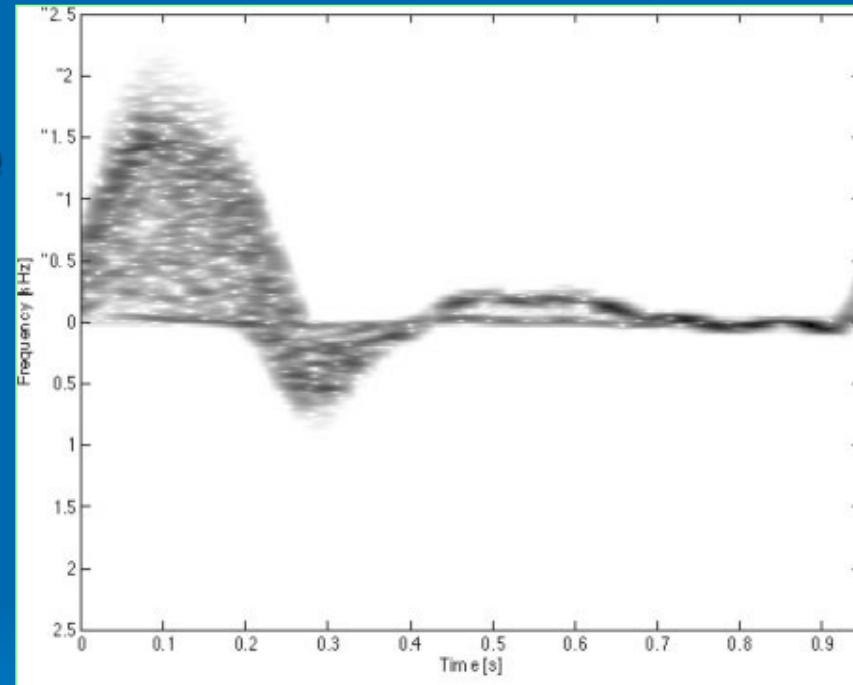
➤ Quadrature detection technique is phase sensitive and indicates the direction of flow





# Frequency Content

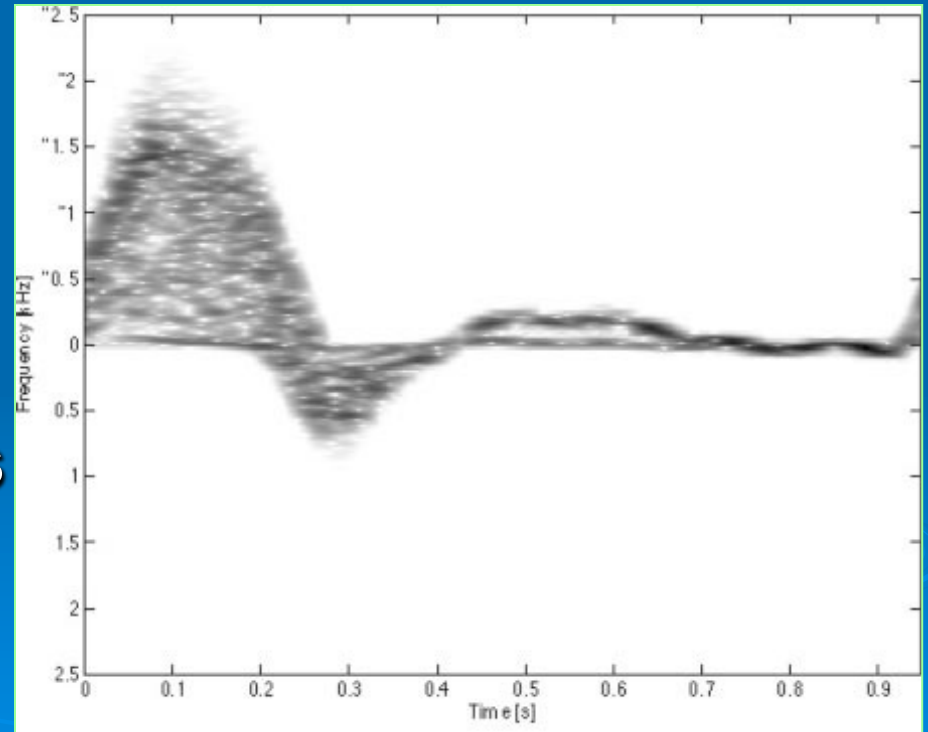
- The Doppler shifted frequencies returned from a vessel are not of a single frequency
- A range of frequencies corresponding to a range of blood flow velocities is present in the backscattered signal
  - spectral broadening
  - frequencies range vary over time and the duration of the cardiac cycle



# Frequency Content

## Doppler frequency spectrum

- Time along the x axis and Doppler shift frequencies along the y axis
  - expressed in units of velocity
- The relative intensities of Doppler shift frequencies are depicted by using varying gray scales

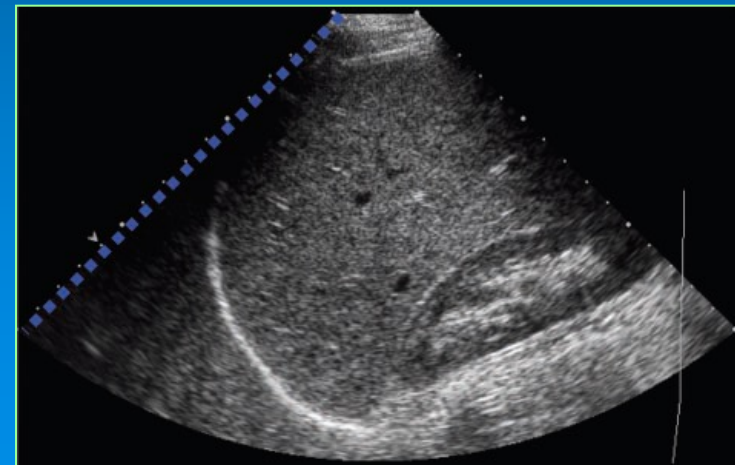




# Pulsed wave Doppler US

- In continuous-wave Doppler US no image formation
- Pulsed Doppler US combines the velocity determination of continuous wave Doppler systems and the range discrimination of pulse-echo imaging
  - Bright mode

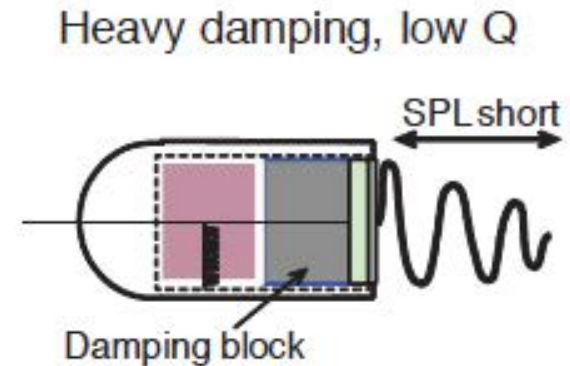
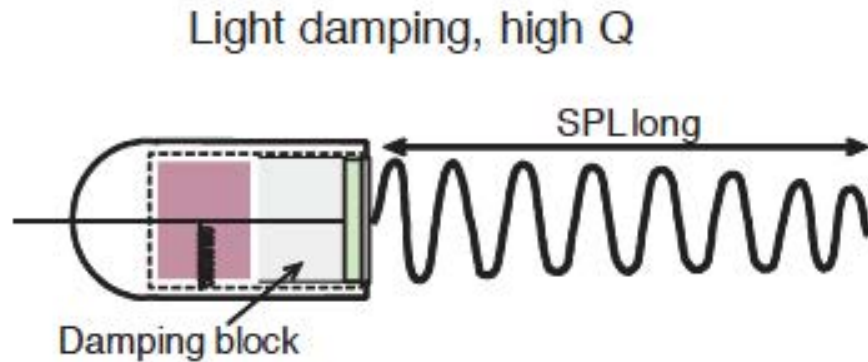
$$t_{\text{echo}} = \frac{2 \cdot d_{\text{object}}}{c} \Rightarrow d_{\text{object}} = \frac{t_{\text{echo}} \cdot c}{2}$$



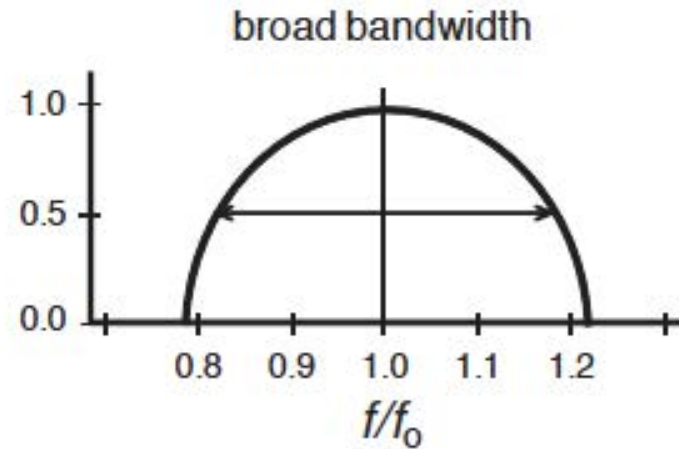
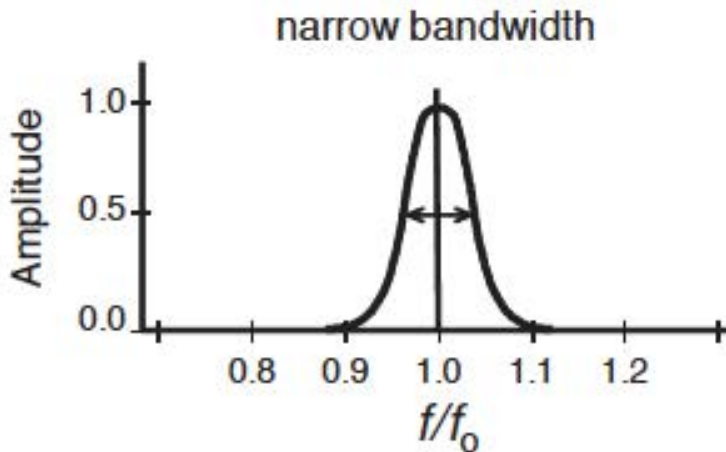
# Pulsed wave Doppler US

- A transducer tuned for pulsed Doppler operation is used in a pulse-echo format
  - similar to imaging
- The SPL is longer to provide a higher Q factor and improve the measurement accuracy of the frequency shift
  - SPL spatial pulse length
  - a minimum of 5 cycles per pulse up to 25 cycles per pulse
    - at the expense of axial resolution

# Damping and Q factor



## Frequency Spectrum

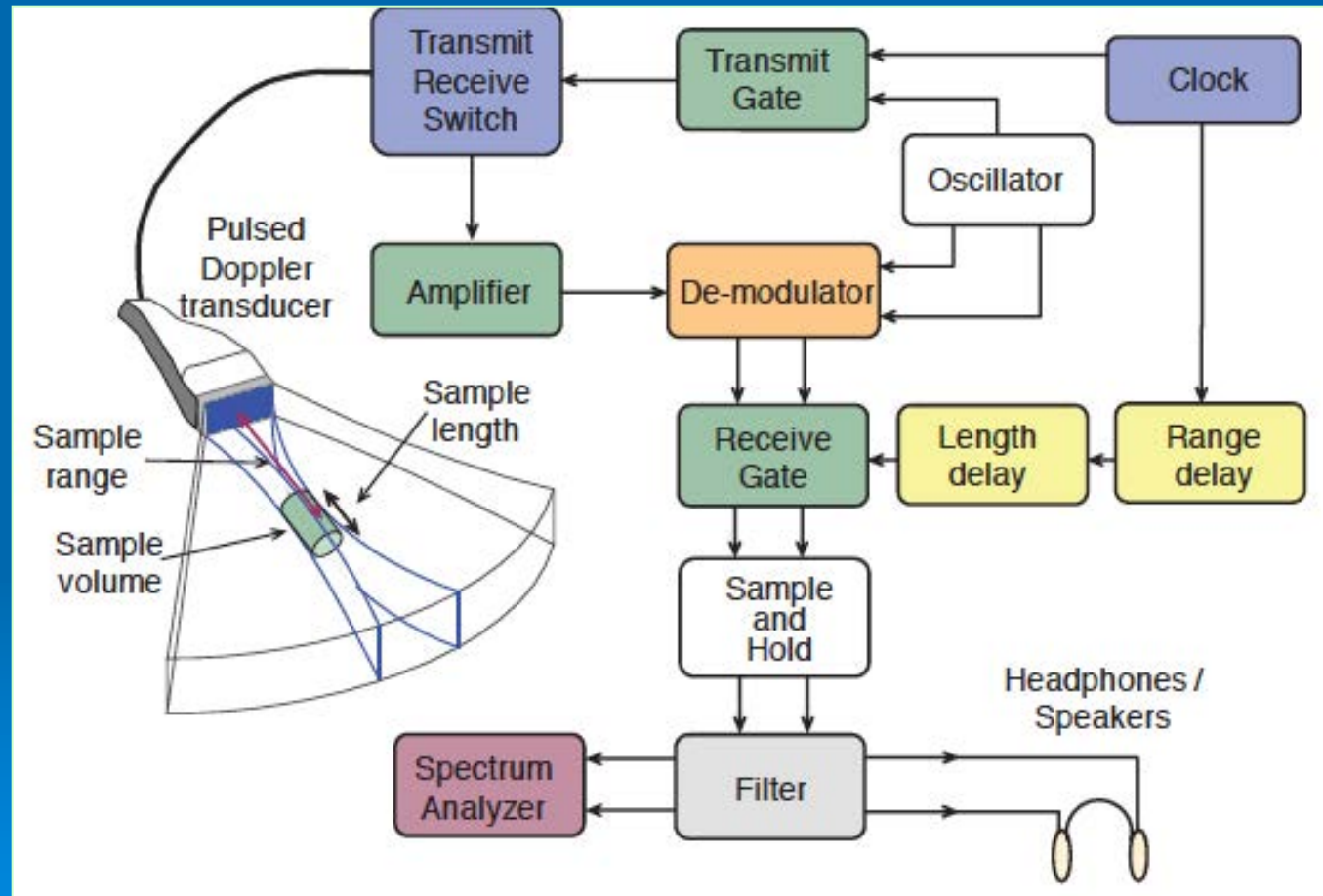


low Q does not imply poor quality in the signal

# Pulsed wave Doppler US

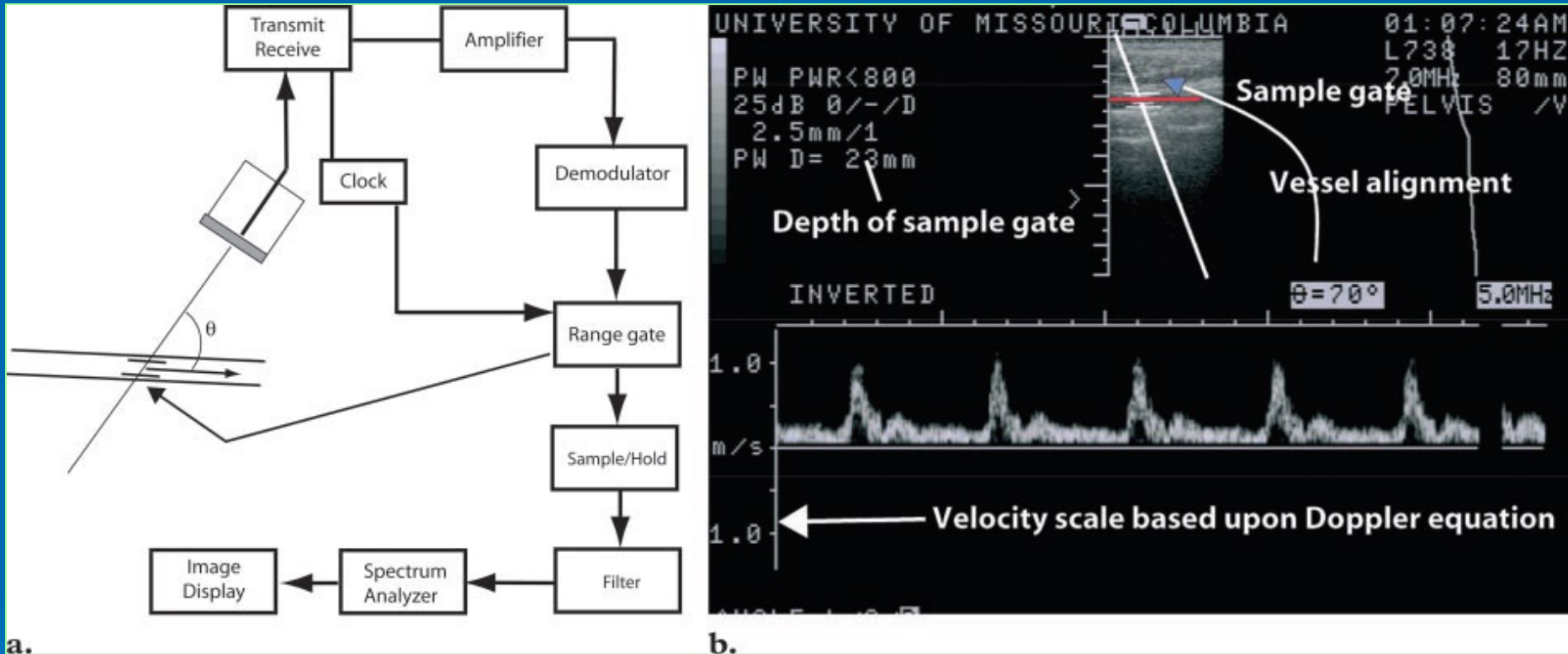
Depth selection is achieved with a time gate to reject all echo signals except those falling within the gate window

- Determined by the operator



<https://www.youtube.com/watch?v=tQn8jKtwk6o>

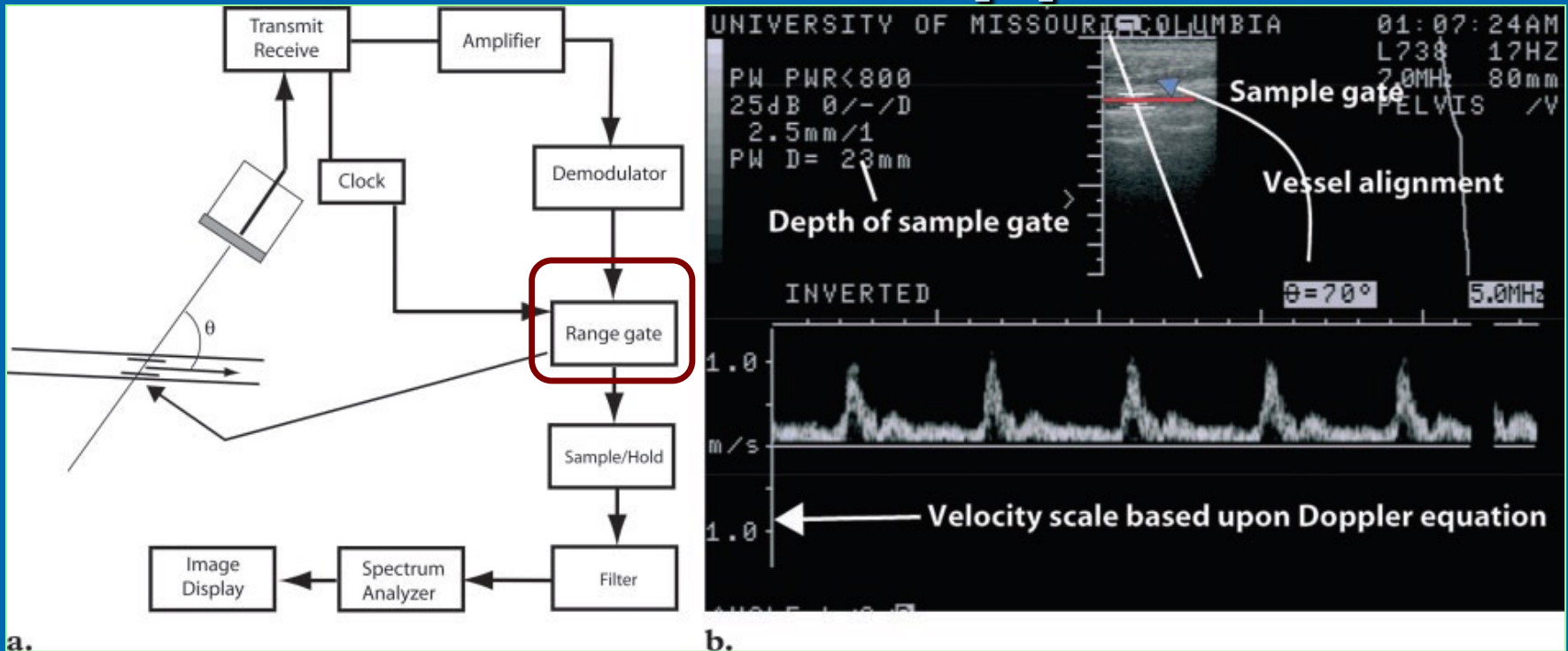
# Pulsed wave Doppler US



- a.** A single transducer is used in pulse-echo mode
- b.** Image display from pulsed-wave Doppler US
  - Red line indicates the axial line used to interrogate a volume contained within the range gate
  - The angle correction is also indicated



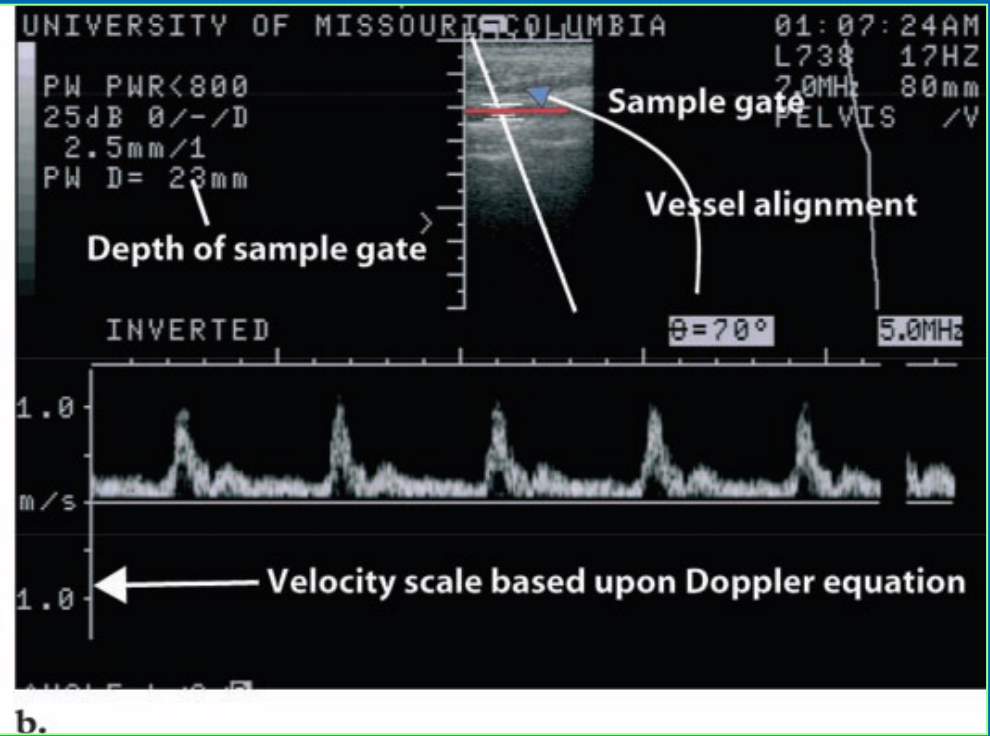
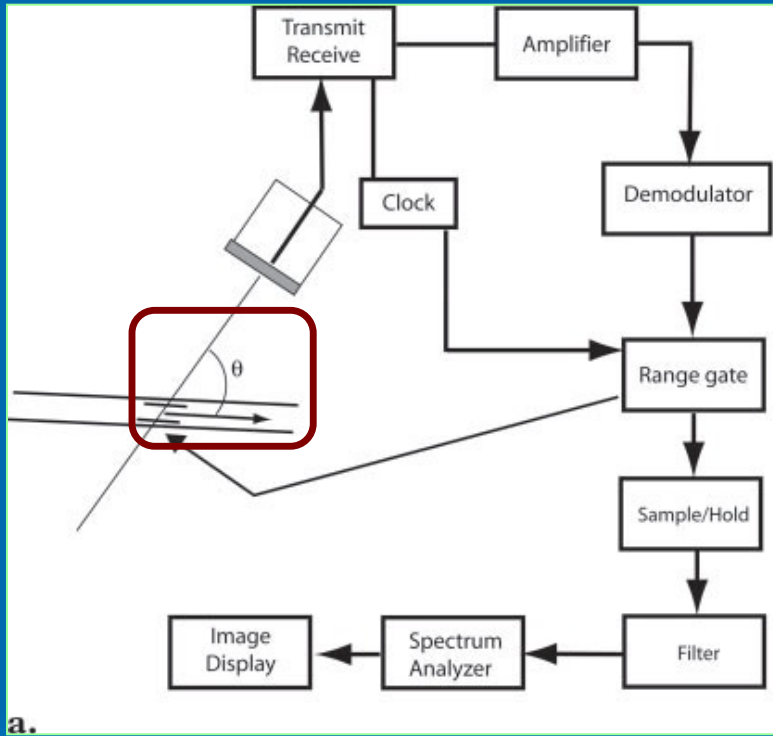
# Pulsed wave Doppler US



- The range gate is a means by which the returning echoes from a particular range in time are separated out for analysis by the Doppler instrumentation
  - adjusted by the operator



# Pulsed wave Doppler US

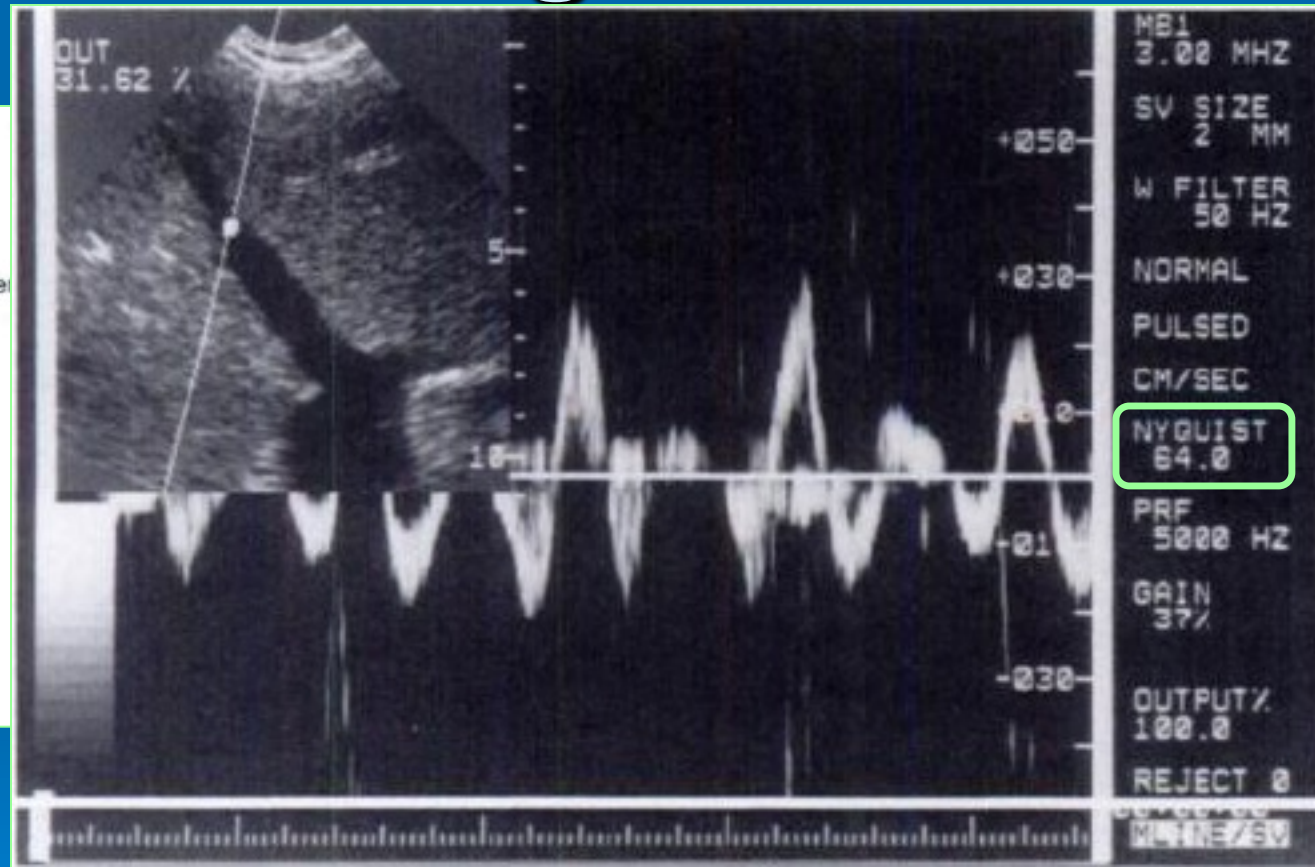
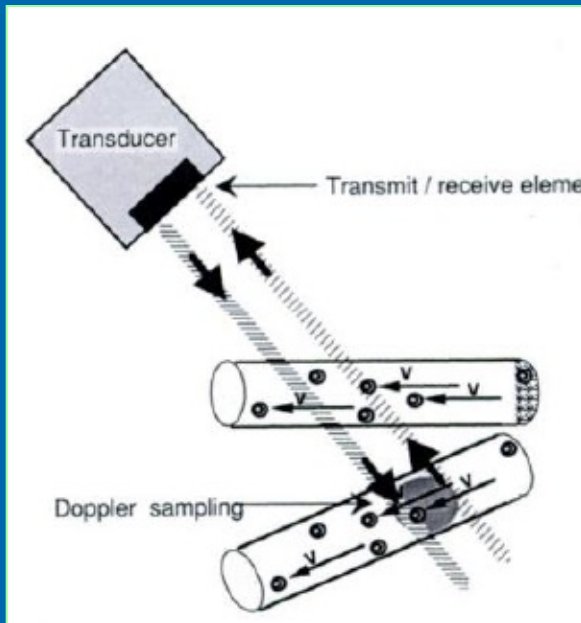


Doppler angles between  $30^\circ$  and  $60^\circ$  are easiest to image while providing the minimal error in velocity estimation

**Table 1**  
Doppler Frequency Shifts (kHz) for a Target Moving 1.00 m/sec

| $F_T$ (kHz) | Scanning Angles |            |            |            |
|-------------|-----------------|------------|------------|------------|
|             | $0^\circ$       | $45^\circ$ | $60^\circ$ | $80^\circ$ |
| 2.0         | 2.6             | 1.8        | 1.3        | 0.5        |
| 2.5         | 3.2             | 2.3        | 1.6        | 0.6        |
| 3.0         | 3.9             | 2.8        | 1.9        | 0.7        |
| 5.0         | 6.5             | 4.6        | 3.2        | 1.1        |
| 7.5         | 9.7             | 6.8        | 4.9        | 1.6        |

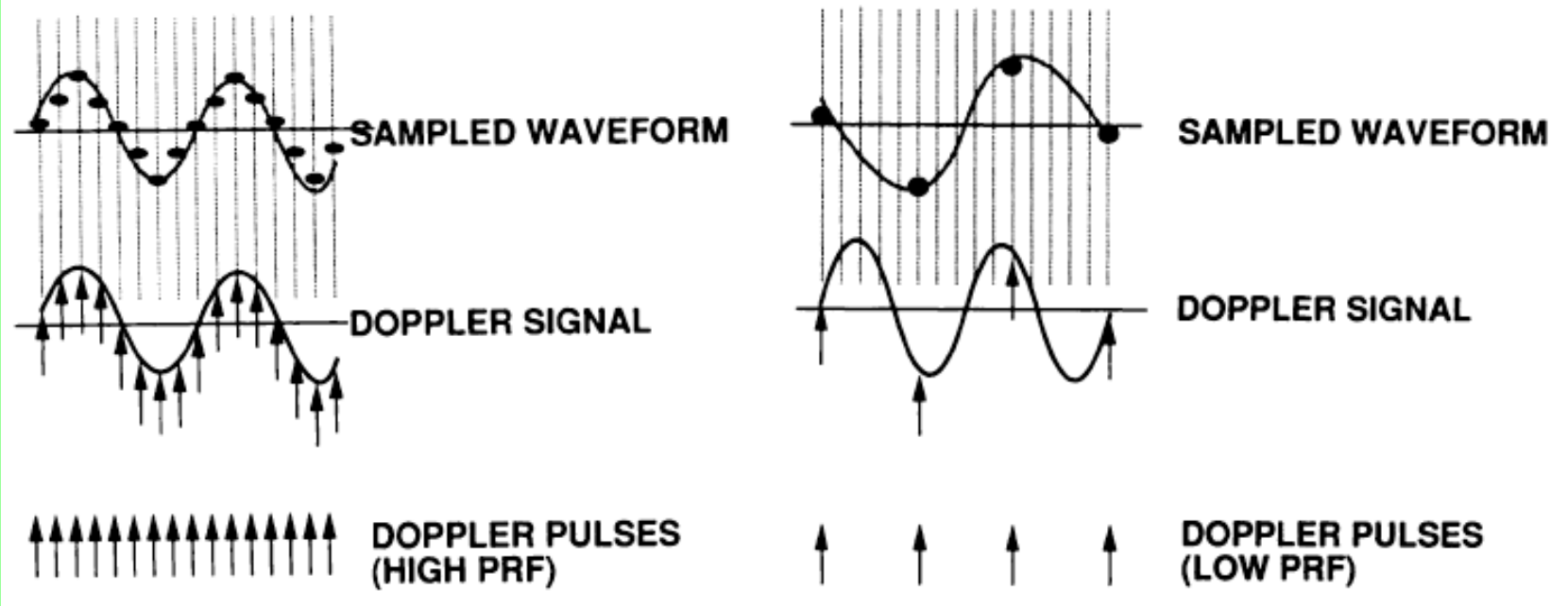
# Aliasing



Aliasing occurs in pulsed-wave Doppler US when the rate at which interrogating pulses are sent to obtain the phase shift information is less than two times Doppler shifted frequencies

- Nyquist criteria

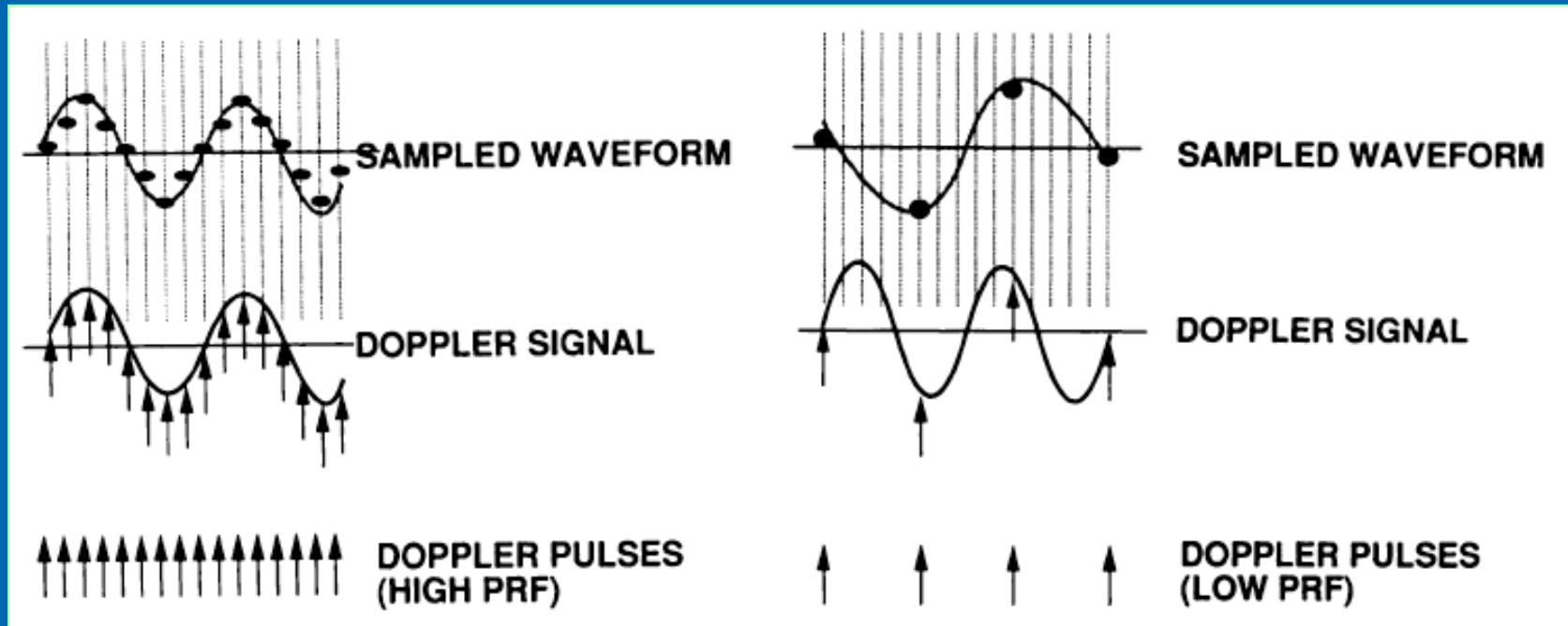
# Aliasing



- Nyquist criteria dictate that there must be at least 2 samples per period of the maximum frequency
- Anything less will result in an artifactually lower frequency being reconstructed
- The sampling rate is dictated by the depth of the range gate in the body !

PRF: pulse repetition frequency

# Aliasing



$$\Delta f_{\max} = \frac{\text{PRF}}{2} = \frac{2 f_0 V_{\max} \cos(\theta)}{c}$$

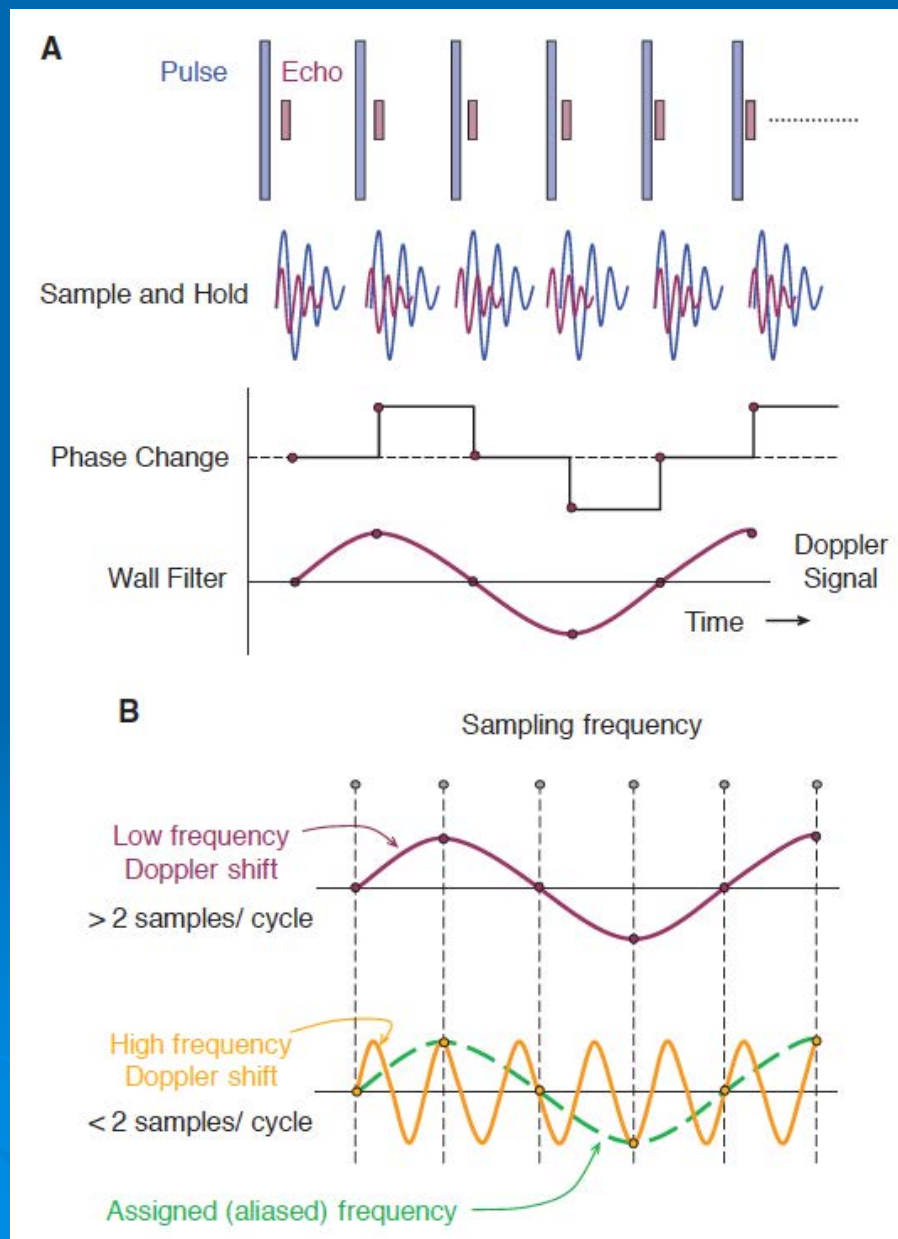
$$V_{\max} = \frac{c \times \text{PRF}}{4 \times f_0 \times \cos(\theta)}$$

**PRF: pulse repetition frequency**



# Aliasing

- PRF can reach only a maximum that is allowed by the round trip time between the transducer and the range gate depth
  - identical to the pulse-echo range equation



# Aliasing

Any one of the following changes will allow  $v_{\max}$  to increase:

- Reducing the depth of the range gate will allow an increase in the PRF
- Reducing the frequency of the transmitted pulse,  $f_0$ , will reduce the Doppler shift frequency
- Increasing the angle between the beam axis and the vessel axis will reduce the Doppler shift frequency

**Table 2**  
**Doppler Frequency Shifts (kHz) for Targets of Differing Velocities\***

| $F_T$ (kHz) | Velocity (m/sec) |      |      |       |
|-------------|------------------|------|------|-------|
|             | 0.01             | 0.10 | 1.00 | 5.00  |
| 2.0         | 0.018            | 0.18 | 1.8  | 9.18  |
| 3.0         | 0.028            | 0.28 | 2.8  | 13.78 |
| 5.0         | 0.046            | 0.46 | 4.6  | 22.96 |
| 7.5         | 0.069            | 0.69 | 6.9  | 34.50 |

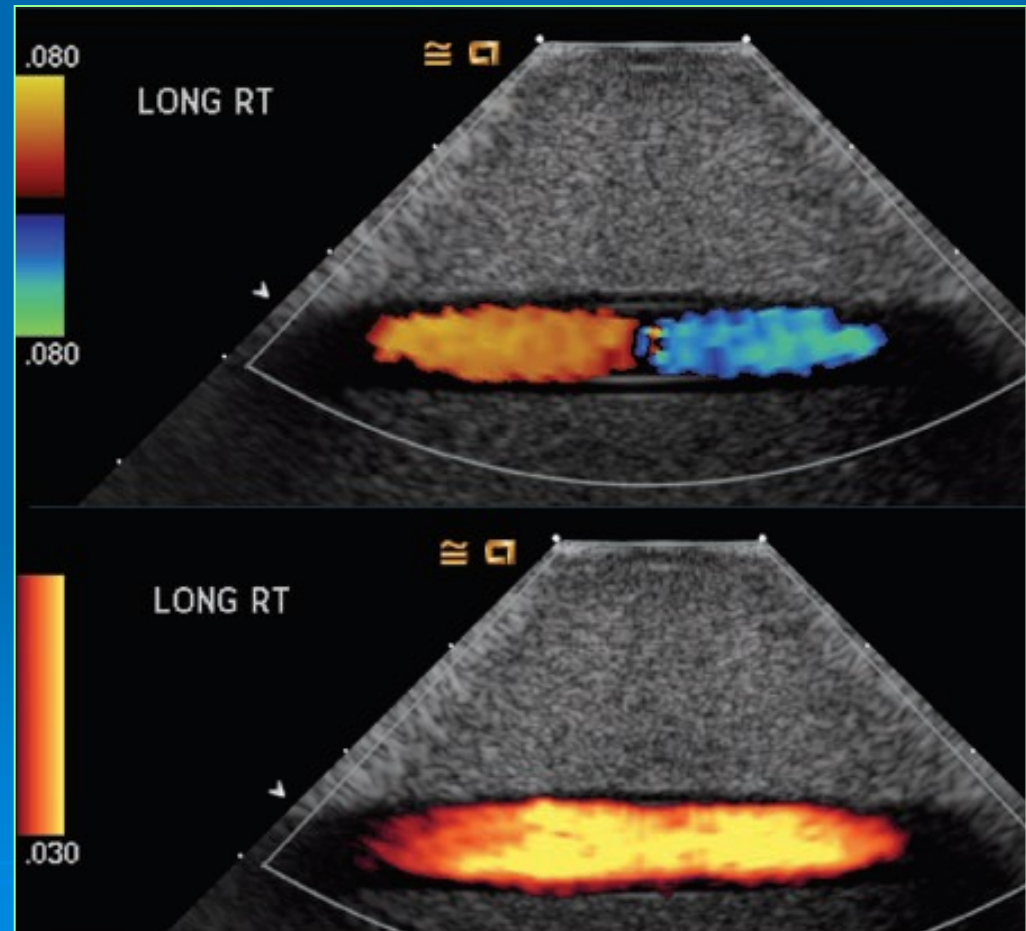
\* Calculated for a 45° scanning angle.



# Color Doppler & Power Doppler

Color flow (top) and power Doppler (bottom) images of the same phantom under the same conditions

- The directions of flow toward and away from the transducer are seen in the color flow image
- The power Doppler image displays only the intensity of the Doppler shift



# Power Doppler

## A comparison of color Doppler and power Doppler

Enhanced sensitivity of the power Doppler acquisition

- particularly in areas perpendicular to the beam direction
  - where the signal is lost in the color Doppler image



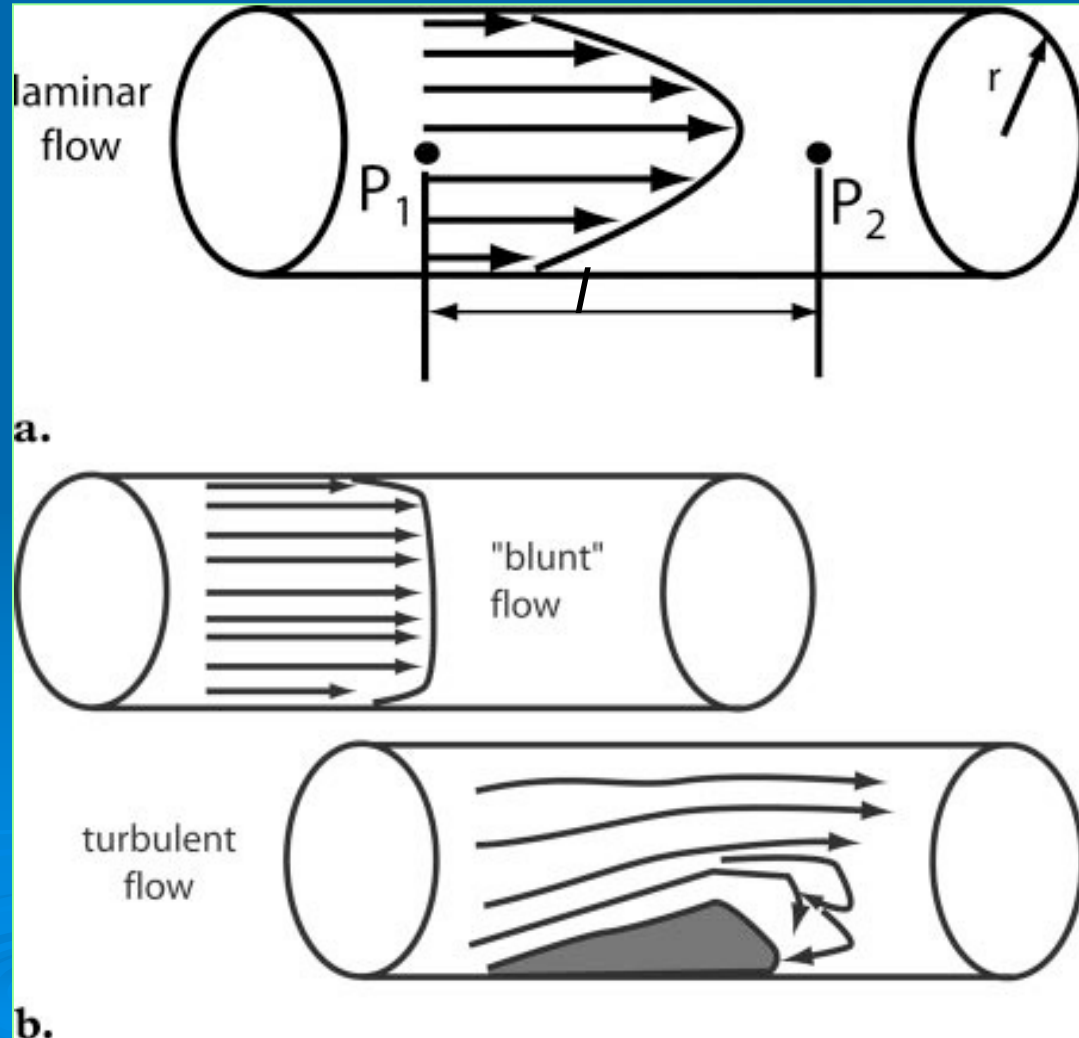
# Types of Blood Flow and Physics of Flow Resistance

## Poiseuille's law

$$P_2 - P_1 = \frac{8l\eta Q}{\pi r^4}$$

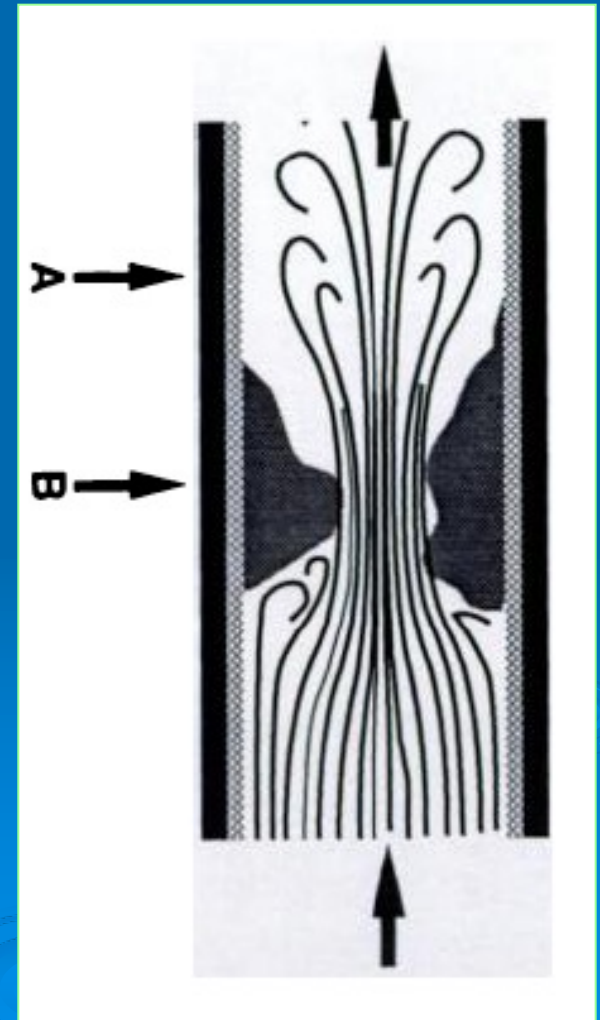
- $P_2 - P_1$  pressure difference
- $l$  length
- $r$  radius
- $\eta$  viscosity
- $Q$  flow rate

**General model: the flow rate through a cylindrical vessel is determined by pressure difference**



# Types of Blood Flow and Physics of Flow Resistance

- Blood is a complex fluid, exhibiting properties that are referred to as non-Newtonian
- The viscosity of blood increases as the flow rate slows down
- The vessel structure itself is very complex
- Blood vessels are curved, can branch and change diameter, and are viscoelastic
  - (eg, behave like plastics)





# Flow Parameters: Derivations and Meaning

- Doppler US demonstrates changes in flow
- US-based quantitative values provide diagnostic thresholds for disease conditions
- Absolute quantification of the flow velocity is difficult because of the angle dependence of the Doppler equation
  - In some cases, it is problematic to make an adequate estimate of the Doppler angle



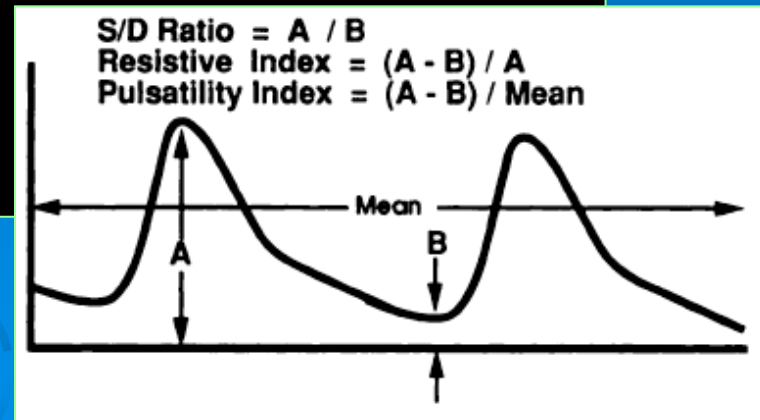
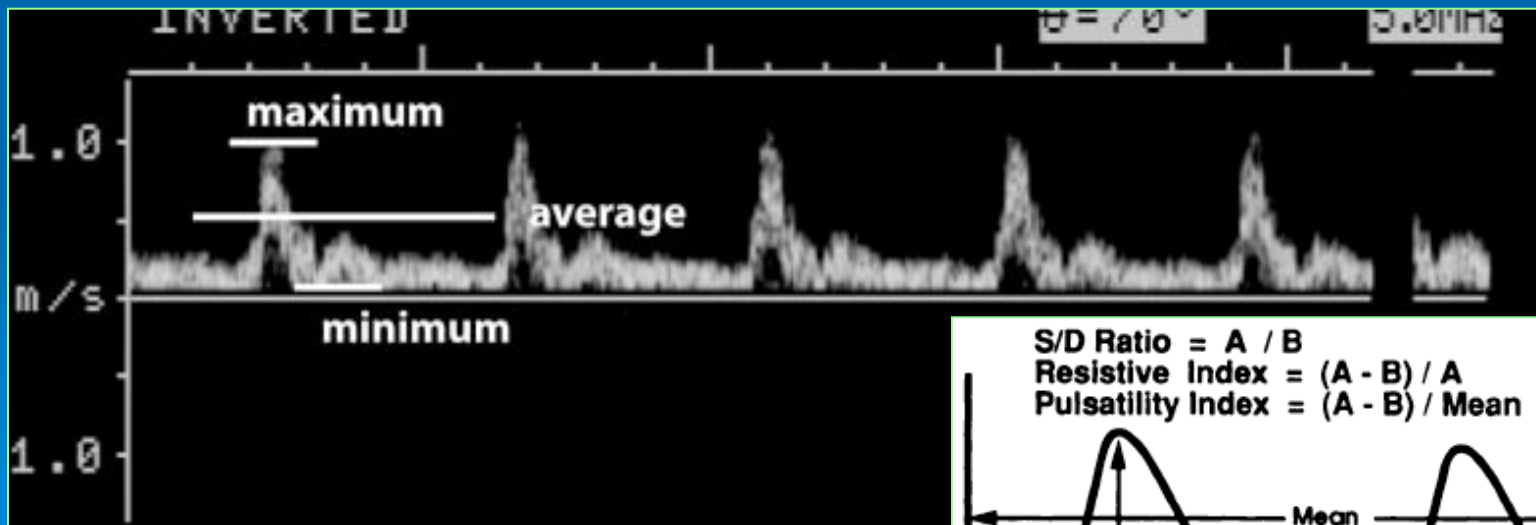
# Flow parameters

- PI pulsatility index
- RI resistivity index

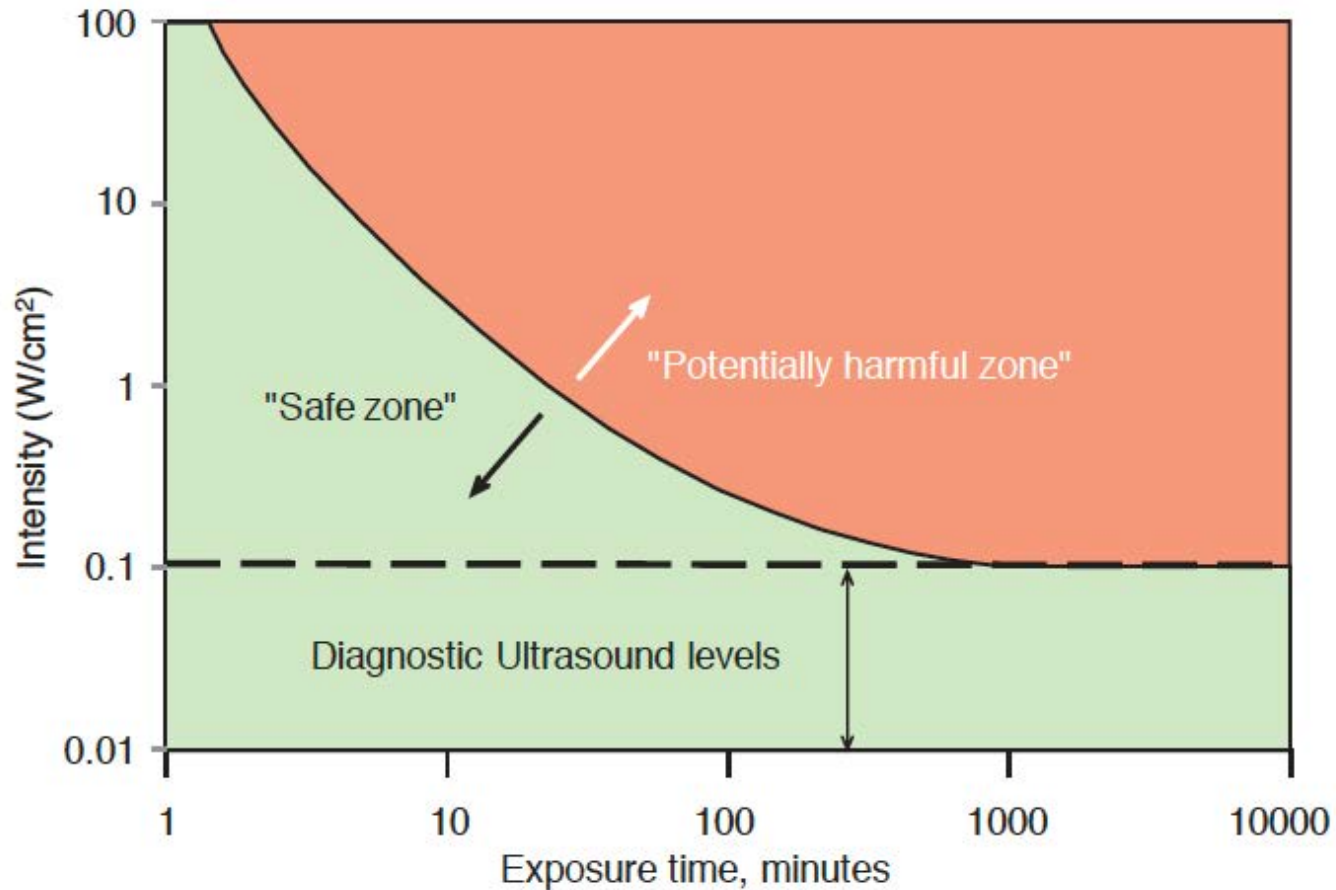
$$v_{\text{RBC}} = \frac{f_D}{f_0} \cdot \frac{c}{2 \cdot \cos \theta}$$

$$\text{PI} = \frac{v_{\text{max}} - v_{\text{min}}}{v_{\text{mean}}} = \frac{S - D}{\text{mean}}$$

$$\text{RI} = \frac{v_{\text{max}} - v_{\text{min}}}{v_{\text{max}}} = \frac{S - D}{S}$$



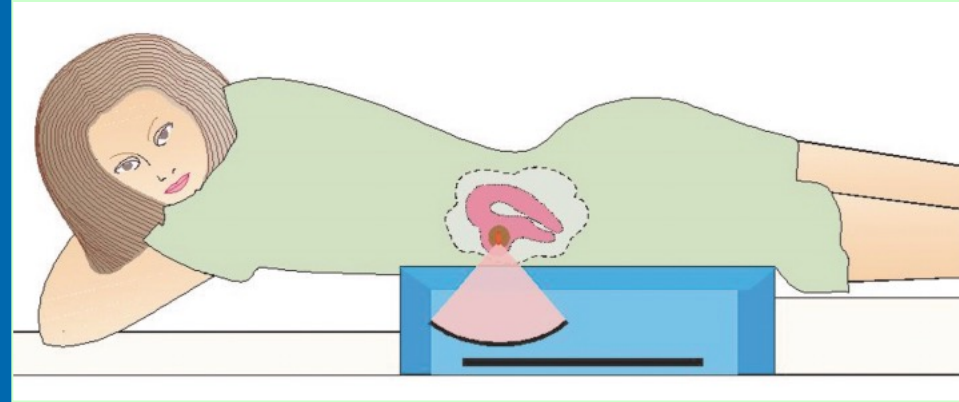
# US potential bioeffects



# High Intensity Focused Ultrasound (HIFU) Therapy

The ability to focus and accurately target a lesion with HIFU allows precise ablation of lesions of any shape without damage to surrounding structures

- by using real-time US or magnetic resonance imaging guidance



- Schematic representation of patient lying focused ultrasound system ready to be placed into MRI unit.
- Ultrasound transducer found in sealed water bath within MR table

*J. Hindley et al  
MRI Guidance of Focused Ultrasound  
Therapy of Uterine Fibroids  
AJR 2004;183:1713–1719*

# References

## US

### ➤ Doppler US: The Basics

- CRB Merritt, RadioGraphics 1991; 11:109-119

### ➤ Fundamental Physics of Ultrasound and Its Propagation in Tissue

- Marvin C. Ziskin, RadioGraphics 1993; 13:705-709

### ➤ B-mode US: Basic Concepts and New Technology

- N.J. Hangiandreou, RadioGraphics 2003; 23:1019–1033

### ➤ Doppler US Techniques: Concepts of Blood Flow Detection and Flow Dynamics

- Evan J. Boote, RadioGraphics 2003; 23:1315–1327