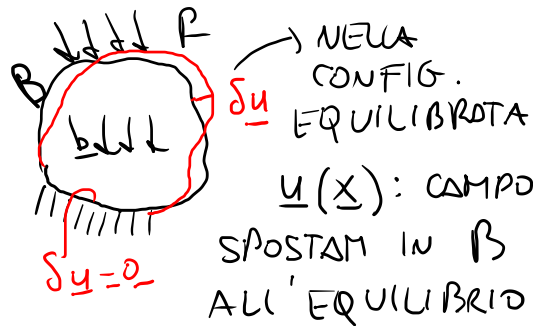


PRINCIPIO DI STAZIONARIETÀ DELL'EN. POT. TOTALE

MADS, 6/10/23

NELLA MECCANICA DEI SIST. DISCRETI QUESTO PRINCIPIO PERMETTE DI STUDIARE LE CONFIGURAZIONI DI EQUILIBRIO.



$$\Gamma(\underline{u}) = \underbrace{\frac{1}{2} \int_B \underline{\sigma} \cdot \underline{\varepsilon} dV}_{\text{E.P.T. EN. ELASTICA}} - \underbrace{\left\{ \int_B \underline{b} \cdot \underline{u} dV + \int_{\partial B} \underline{p} \cdot \underline{u} dS \right\}}_{\text{POTENZIALE DEI CARICHI}}$$

$$\underline{u} \rightsquigarrow \underline{\varepsilon} = \frac{1}{2} (\nabla \underline{u} + \nabla \underline{u}^T)$$

$$\underline{\sigma} = \mathbb{C} \underline{\varepsilon}$$

APPLICHO UNA 'VARIAZIONE' DELLO SPOST. $\delta \underline{u}$
 ($\delta \underline{u}$: ANALOGO ALLO SPOSTAM. VIRTUALE)

$$\Pi(\underline{u} + \delta \underline{u}) = \frac{1}{2} \int_B \underbrace{\underline{C}(\underline{\xi} + \delta \underline{\xi})}_{\underline{\sigma}} \cdot (\underline{\xi} + \delta \underline{\xi}) dV - \int_B \underline{b} \cdot (\underline{u} + \delta \underline{u}) dV - \int_{\partial B} \underline{p} \cdot (\underline{u} + \delta \underline{u}) dS$$

$\forall \delta \underline{u}$

$$\underbrace{\Pi(\underline{u})}_{\substack{\text{EPT} \\ \text{PG PREC}}} + \underbrace{\delta \Pi}_{\substack{\text{VARIAZ} \\ \Pi = \Pi(\delta \underline{u})}} = \frac{1}{2} \int_B \underline{C} \underline{\xi} \cdot \underline{\xi} + 2 \underline{C} \underline{\xi} \cdot \delta \underline{\xi} + \underline{C} \delta \underline{\xi} \cdot \delta \underline{\xi} dV - \int_B \underline{b} \cdot \underline{u} - \int_B \underline{b} \cdot \delta \underline{u} - \int_{\partial B} \underline{p} \cdot \underline{u} - \int_{\partial B} \underline{p} \cdot \delta \underline{u}$$

$$\delta \Pi = \underbrace{\int_B \underline{C} \underline{\xi} \cdot \delta \underline{\xi} - \int_B \underline{b} \cdot \delta \underline{u} - \int_{\partial B} \underline{p} \cdot \delta \underline{u}}_{\delta \Pi^{(1)} \text{ (lineare in } \delta \underline{u})}} + \underbrace{\frac{1}{2} \int_B \underline{C} \delta \underline{\xi} \cdot \delta \underline{\xi}}_{\substack{\text{VARIAZ. SECONDA} \\ \delta \Pi^{(2)} \text{ (quadratica in } \delta \underline{u})}}$$

ALL' EQUILIBRIO $\delta \Pi^{(1)}$ (VARIAZ. PRIMA) $\bar{e} = 0$

Per il T.L.V. $\delta \Pi^{(1)} = 0 \quad (\forall \delta \underline{u})$

STAZIONARIETA' DELL' ENERGIA
ALL' EQUILIBRIO

SYSTEMA A \rightleftharpoons SYSTEMA B

$\text{div } \underline{\sigma}^A + \underline{b}^A = 0$

$\underline{\sigma}_{M}^A = \underline{p}$

$\underline{\sigma}^B = \frac{1}{2} (\underline{\Pi} \delta \underline{u}^B + \delta \underline{u}^{BT})$

$\int \underline{\sigma}^A \cdot \delta \underline{\xi}^B = \int \underline{b}^A \cdot \delta \underline{u}^B + \int \underline{p}^A \cdot \delta \underline{u}^B$

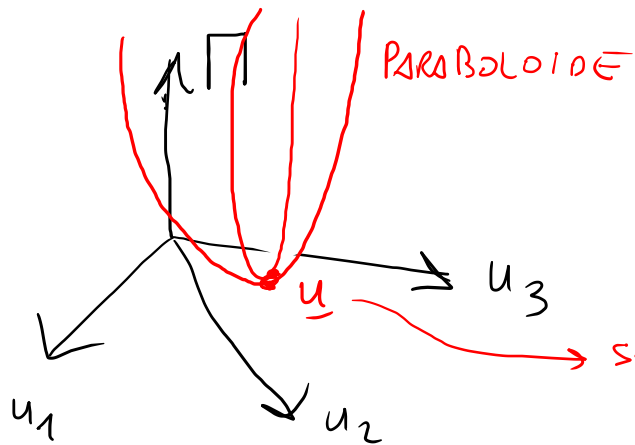
ALL' EQUIL.

All'equil. $\delta \Pi^{(1)} = 0$; $\delta \Pi = \delta \Pi^{(2)}$

$$\delta \Pi^{(2)} > 0$$

$$\left(\int_B \bar{C} \delta \underline{\xi} \cdot \delta \underline{\xi} dV > 0 \right) \quad (\forall \delta \underline{u})$$

perché \bar{C} è un tensore
definito positivo.



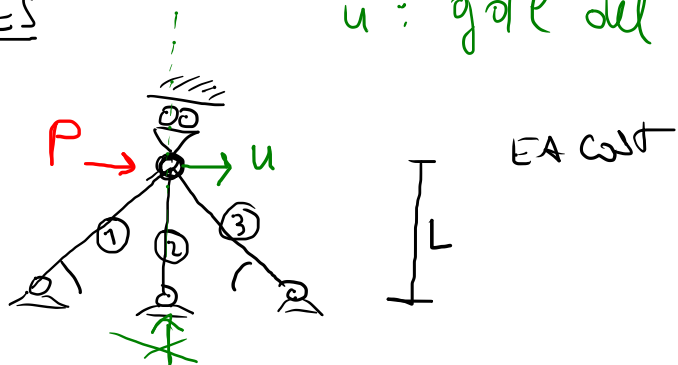
u è un minimo dell'energia

SOLUZ. EQUILIBRIO (STAZIONARIETA' ENERGIA)

PRINCIPIO DI STAZ. DELL'E.P.T: TRA TUTTE LE CONFIG. CONGRUENTI, LA
SOLUZ. EQUILIBRATA RENDE STAZIONARIA L'E.P.T.

ES

u : spost. del sist.; DETERMINO MEDIANTE STAT. E.P.T. LA SOLUZ. u^*



$N \leftarrow \text{---} \text{---} \text{---} \rightarrow N$
 $\rightarrow \Delta x$

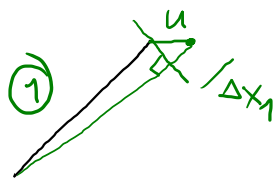
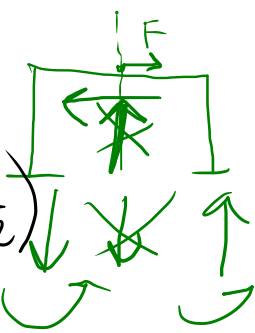
$$N = \frac{EA}{l} \Delta x$$

$$E_{el}(\text{biella}) = \frac{1}{2} K \Delta x^2 = \frac{1}{2} \frac{EA}{l} \Delta x^2$$

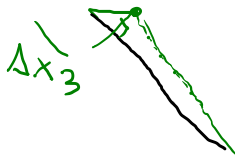
$$\Pi(u) = EN. ELASTICA - P u$$

$$= \frac{1}{2} \sum_{i=1}^3 \left(\frac{EA}{l} \Delta x_i^2 \right), \text{ con } \Delta x_i = f(u)$$

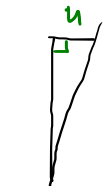
$$\Pi(u) = \frac{1}{2} EA \left(\frac{u^2}{2} \frac{1}{L\sqrt{2}} + 0 + \left(\frac{-u}{\sqrt{2}} \right)^2 \frac{1}{L\sqrt{2}} \right) - P u$$



$$\Delta x_1 = + \frac{u}{\sqrt{2}}$$



$$\Delta x_3 = - \frac{u}{\sqrt{2}}$$



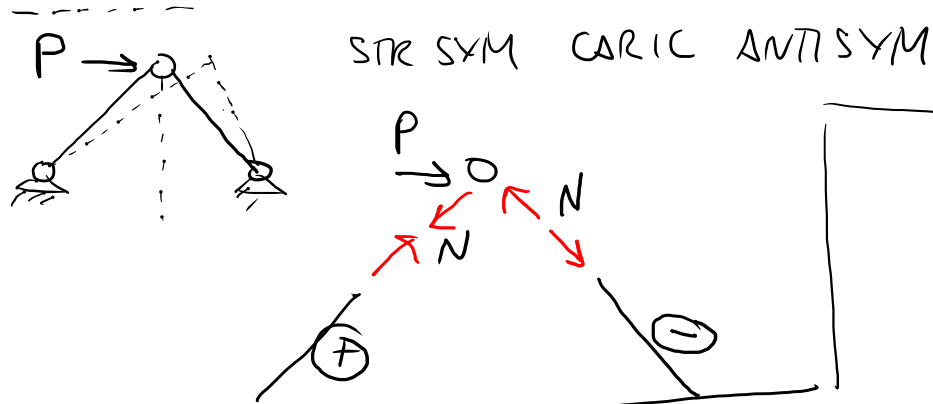
$$\Delta x_2 = 0$$

$$\Pi(u) = \frac{1}{2} EA \frac{u^2}{L\sqrt{2}} - P u$$

$$\delta \Pi^{(1)}(u) = \frac{\partial \Pi}{\partial u} \delta u, \delta \Pi = 0; \frac{\partial \Pi}{\partial u} = 0$$

$$\frac{d\Pi}{du} = 0 : EA \frac{u^*}{L\sqrt{2}} - P = 0 \quad ; \quad \boxed{u^* = \frac{P L \sqrt{2}}{EA}}$$

($u \Rightarrow u^*$)



LA STR. DELL' EPT ($\delta \Pi^H(u) = 0$) CONDUCE ALLA FORMULA DEL METODO DEGLI SPOSTAMENTI.

RICORDIAMOCI CHE ESISTE L'EN. ELASTICA COMPLEMENTARE... $\bar{\Phi}^c = \frac{1}{2} \int \underline{\sigma} \cdot \bar{\mathbb{C}}^{-1} \underline{\sigma} \, dV$

$$\Pi^c(\underline{\sigma}) = \frac{1}{2} \int_B \underline{\sigma} \cdot \bar{\mathbb{C}}^{-1} \underline{\sigma} \, dV - \int_B \underline{p} \cdot \underline{u} - \int_{\partial B} \underline{p} \cdot \underline{u}$$

$\bar{\Phi}^c(\underline{\sigma})$

↳ EPT

COMPLEMENT.

DA VINCI

EPT PER STRUTTURE INFLESSE (EULERO-BERNOULLI)

$\underbrace{\downarrow v(s)} \rightarrow \Phi(\kappa)$: EN. ELASTICA DI UNA TRAVE INFLESSA IN FUNZ. DELLA CURVATURA κ .

$$\bar{\Phi} = \frac{1}{2} \int \underline{\sigma} \cdot \underline{\varepsilon}$$

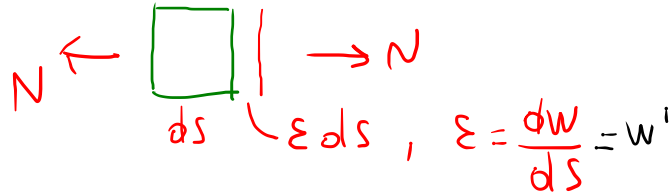
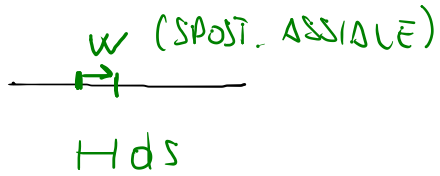


$$\kappa = \frac{M}{EI} \quad ; \quad \kappa = -v''(s)$$

$$\Phi(\kappa) = \frac{1}{2} \int_s M \underbrace{\kappa}_{d\varphi} ds = \frac{1}{2} \int_B EI \kappa^2 ds = \frac{1}{2} \int_s EI (v'')^2 ds \Rightarrow$$

$$\Phi(v) = \frac{1}{2} \int_s EI v''^2$$

IL CONTRIBUTO $\delta \Phi$ della FORZA NORMALE è il seguente



$$\delta \Phi(w) = \frac{1}{2} N \varepsilon ds$$

$$= \frac{1}{2} N w' ds$$

$$\Phi(w) = \int_s \frac{1}{2} N w' ds$$

$$\varepsilon = \frac{N}{EA} = w' \quad N = EA w'$$

$$\Phi(w) = \frac{1}{2} \int_s EA (w')^2 ds$$

EN ENERCA CORRISPONDE AD EFFETTI DI FORZA NORMALE.

IN CONCLUSIONE NELLE TRAVI SNELLE

$$\Phi(w, v) = \frac{1}{2} \int_s EA w'^2 + EI v''^2 ds$$

E.P.T. per una trave snella:

$$\Pi(w, v) = \frac{1}{2} \int_s EA w'^2 + EI v''^2 ds$$

$$- \int_s qv + pw ds$$

← POTENZ. - CARICHI
ESTERNI

