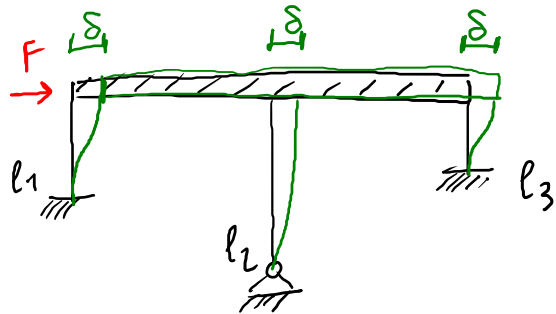


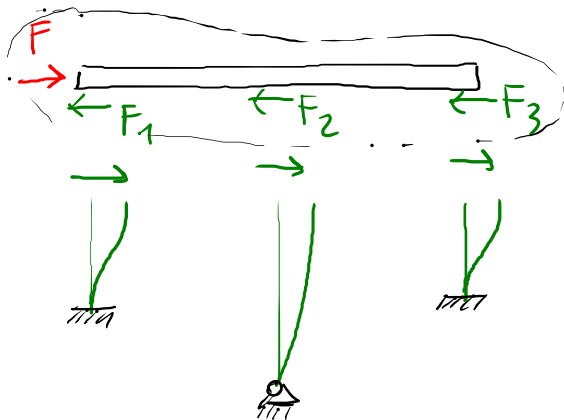
(PROSEGUIAMO CON IL METODO SPOST...)

23/4/24

RIPARTIZIONE AZIONI TRAVI CON TRAVE SHEAR-TYPE
(S: UNICO GDL DEL PROBL.)



EI : cost



EQUIL. ORIZZ:

$$F - F_1 - F_2 - F_3 = 0 \Rightarrow \delta(F)$$

$$F - \frac{12EI}{l_1^3} \delta - \frac{3EI}{l_2^3} \delta - \frac{12EI}{l_3^3} \delta = 0$$

$$F = \left(\frac{12EI}{l_1^3} + \frac{3EI}{l_2^3} + \frac{12EI}{l_3^3} \right) \delta \Rightarrow \delta = \frac{F}{K_T}$$

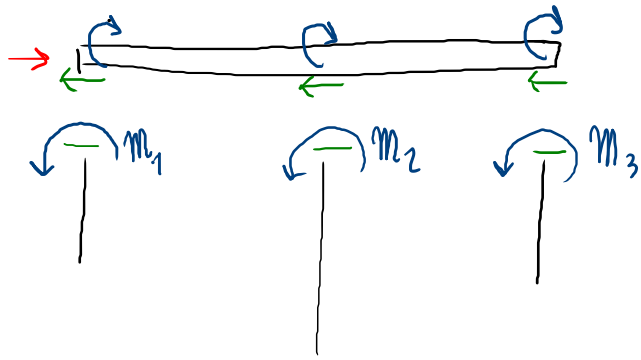
K_T : RIGIDEZZA

$$F_1 = \frac{12EI}{l_1^3} \frac{F}{K_T} = p_1 F$$

COEFF DI RIP.

$$F_2 = \frac{3EI}{l_2^3} \frac{F}{K_T} = p_2 F$$

$$F_3 = p_3 F, \quad p_3 = \frac{12EI}{l_3^3} \frac{1}{K_T}$$

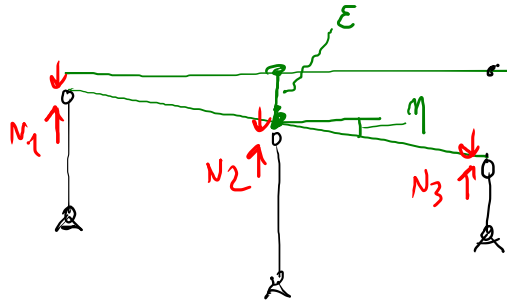
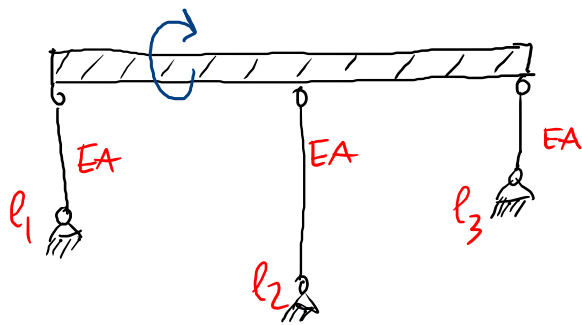


DOPO AVER RIPARTITO LA F CONOSCO:

- M, T di tutti i pilastri
- N nelle trave

SONO ANCORA INCOGNITI GLI SFORZI N dei pilastri
(E QUINDI T DELLA TRAVE).

$$m = \sum_i m_i$$



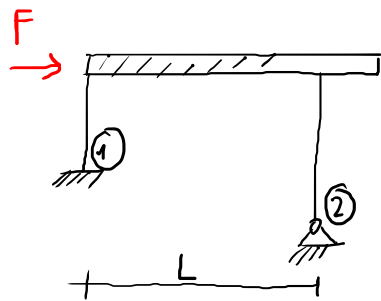
IMPOSTO UN PROBL. AGLI
SPOST. DOVE CONSIDERO
2 GDL (ϵ, η) DELLA
TRAVE (ESCLUSO TRASLAZ.
ORIZZONTALE)

$$N_1 = N_1(\epsilon, \eta) ; N_2 = N_2(\epsilon, \eta) ; N_3 = N_3(\epsilon, \eta)$$

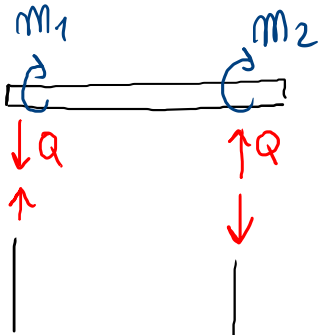
LE 2 EQUAZ. PER DETERMINARE ϵ, η SONO:

- EQUIL. TRASL. VERTIC.
- EQUIL. ROTAZ.

CASO PARTICOLARE (PROBL. STATIC. DETERMINATO PER GLI



N_i)



$$N_1 = +Q$$

$$N_2 = -Q$$

$$Q = \frac{m_1 + m_2}{L}$$

PROBL. AGLI SPOST.

" " "

OSSERVAZIONE

FORZA-MOMENTO
APPL.

CON 1 GDL: $F = K \delta$

RIGIDEZZA

GDL

SPOST-ROTAZ

CON $N > 1$ GDL: $\underline{K} \underline{q} = \underline{F}$

↑

MAT. RIGIDEZZA

↑ VETTORE

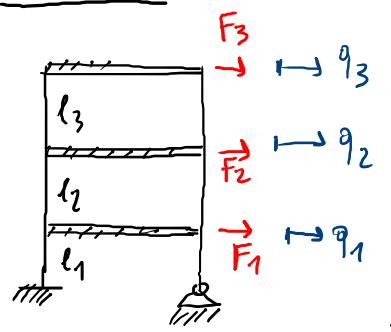
↑ FORZE

↑ APPLIC.

CONSTR. DELLA \tilde{K} : DAL PUNTO DI VISTA OPERATIVO LA COMPONENTE K_{ij}

CORRISPONDE ALLA FORZA CORRELATA ALLO SPOSTAMENTO i -ESIMO QUANDO IL GDL j -ESIMO VALE 1 E TUTTI I RESTANTI GDL SONO NULLI.

ESEMPIO



EI cost

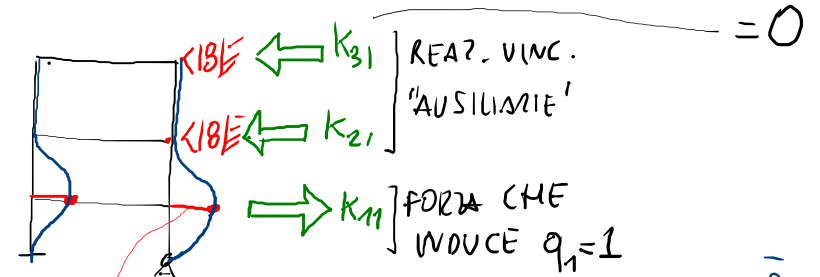
$$\tilde{K} \underline{q} = \underline{F}$$

$$\tilde{K} = [3 \times 3] ; \underline{F} = \begin{bmatrix} F_1 \\ F_2 \\ F_3 \end{bmatrix}$$

$$\underline{q} = \begin{bmatrix} q_1 \\ q_2 \\ q_3 \end{bmatrix}$$

$$\underline{q} = \tilde{K}^{-1} \underline{F}$$

$q_1=1, q_2=q_3=0 \Rightarrow K_{11}, K_{21}, K_{31}$



$K_{21} = -2 \cdot \frac{12EI}{l_2^3} 1$ \bar{e} DISCORDE RISPETTO A q_2

$\frac{12EI}{l_1^3} 1 + 3 \frac{EI}{l_1^3} 1 + 2 \left(\frac{12EI}{l_2^3} \right) 1 = K_{11}$

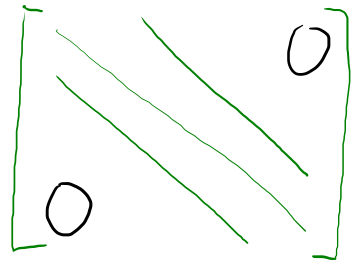
SPOST. $q_1=1$

$$K_{\sim} = \begin{bmatrix} \frac{15EI}{l_1^3} + \frac{24EI}{l_2^3} & & & \\ -\frac{24EI}{l_2^3} & & & \\ & & & \\ 0 & & & \end{bmatrix}$$

$$\begin{bmatrix} -24 \frac{EI}{l_2^3} & & & \\ 24 EI \left(\frac{1}{l_2^3} + \frac{1}{l_3^3} \right) & & & \\ & & & \\ -24 \frac{EI}{l_3^3} & & & \end{bmatrix}$$

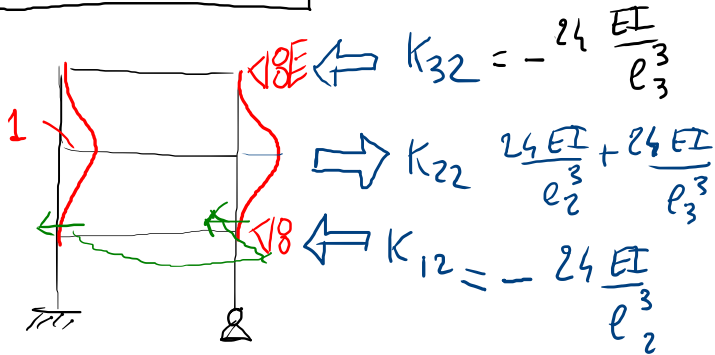
$$\begin{bmatrix} 0 & & & \\ -24 \frac{EI}{l_3^3} & & & \\ 24 \frac{EI}{l_3^3} & & & \\ & & & \end{bmatrix}$$

\bar{e} SIMMETRICA!!

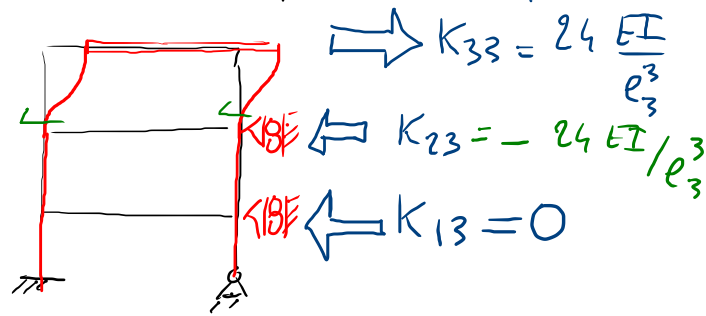


TEMA STIERS-TYPE:
MATRICE TRIDIAGONALE

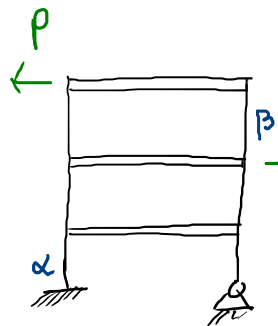
$$q_2 = 1, q_1 = q_3 = 0$$



$$q_1 = q_2 = 0, q_3 = 1$$



ESEMPIO DI UTILIZZO DELLA \tilde{K} OTTENUTA:



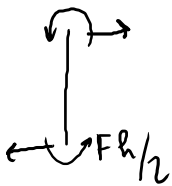
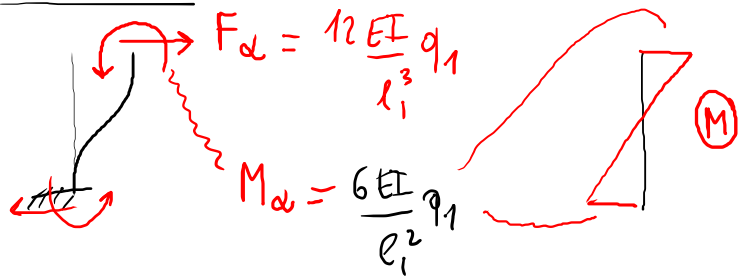
$\rightarrow q_3$
 $\rightarrow q_2$
 $\rightarrow q_1$

$\left[\begin{array}{c} 3 \times 3 \\ \tilde{K} \end{array} \right]$

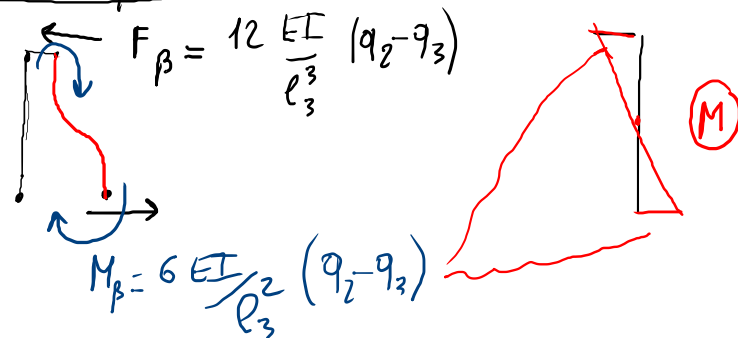
$$\begin{bmatrix} q_1 \\ q_2 \\ q_3 \end{bmatrix} = \begin{bmatrix} 0 \\ Q \\ -P \end{bmatrix}$$

$$\underline{q} = \tilde{K}^{-1} \begin{bmatrix} 0 \\ Q \\ -P \end{bmatrix} \rightarrow \begin{array}{l} q_1 > 0 \\ q_2 > 0 \\ q_3 > 0 \end{array}$$

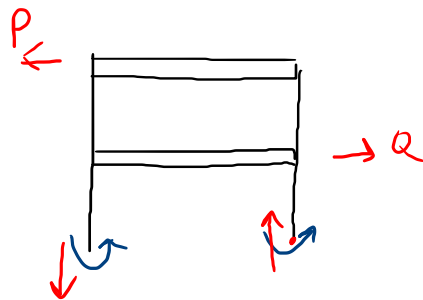
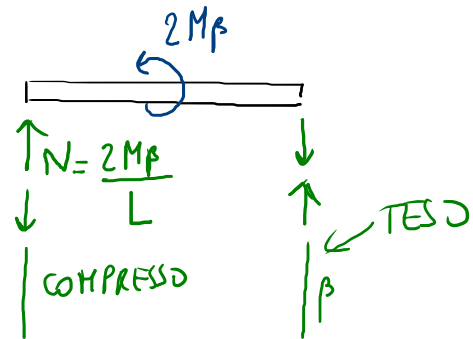
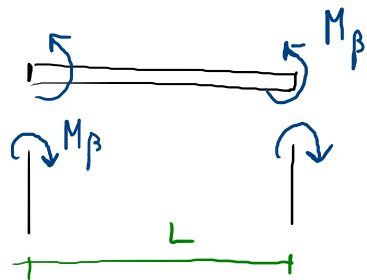
PILASTRO α



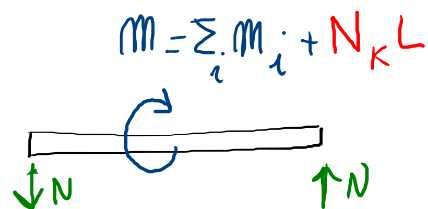
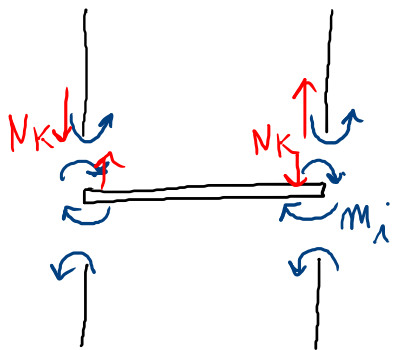
PILASTRO β



N del pilastro β



N del pilastro α



OCCORRE TENERE
 CONTO DEI MOMENTI
 AI PIEDI DEI PILASTRI
 SUPERIORI E DEI N_k
 DEI PILASTRI CHE
 ARRIVANO DA SOPRA