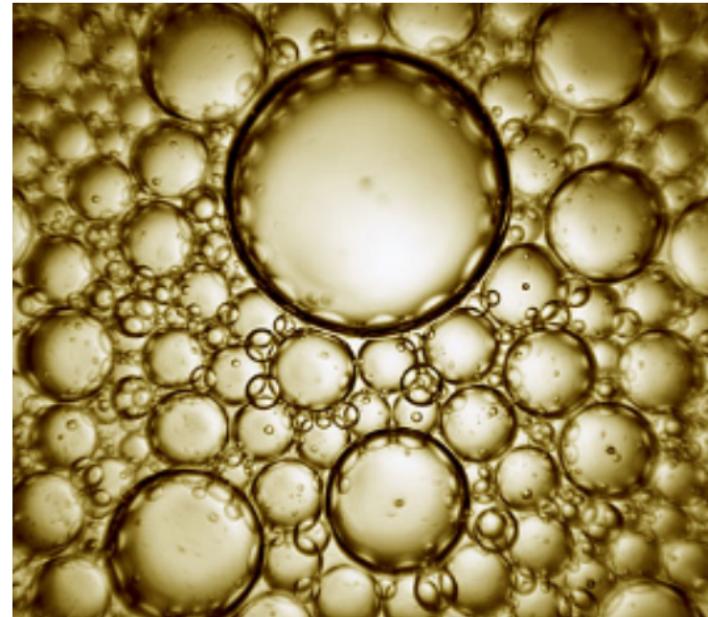
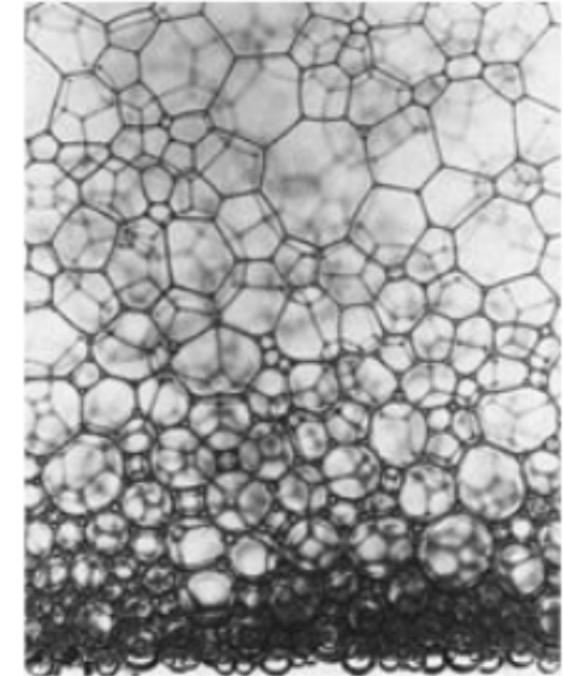


SOSPENSIONE
COLLOIDALE



EMULSIONE



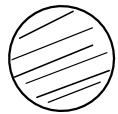
SCHUMA

COLLOIDI

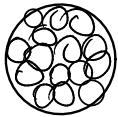
Def: miscela fortemente asimmetrica composta da particelle solide di taglia mesoscopica sospese in un solvente liquido (micro)

micro: $10^{-10} - 10^{-9}$ m

meso: $10^{-9} - 10^{-5}$ m $\sim 10^{-6}$ μ m



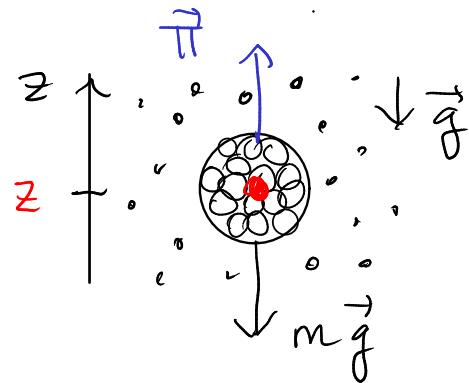
$$N \sim N_A \sim 10^{23}$$



$$N \sim \left(\frac{L}{a}\right)^3 \sim \left(\frac{10^{-6}}{10^{-10}}\right)^3 \sim 10^{12} \Rightarrow \text{agitazione termica}$$

Stabilità \rightarrow sedimentazione

Criterio di stabilità



σ : dim. lineari

ρ_c : densità colloide

ρ_s : densità solvente ($\rho_s \ll \rho_c$)

T : temperatura, equilibrio

$$H = H_0 + U(z)$$

\uparrow

particella
colloidale

$$K_0 + U_0$$

\uparrow

campo
esterno

Prob. di trovare la particella ad altezza z

$$\text{Tr} [] = \text{Tr}_z [\text{Tr}_0 [\dots]]$$

$$U = \int_c \sigma^3 g z \rightarrow \Delta g \sigma^3 g z$$

$$p(z) \sim e^{-\beta U(z)}$$

$$p(z) = \frac{\text{Tr}_0 [e^{-\beta H}]}{\text{Tr} [e^{-\beta H}]} = \frac{\text{Tr}_0 [e^{-\beta H_0} e^{-\beta U(z)}]}{\text{Tr}_z [\text{Tr}_0 [e^{-\beta H_0} e^{-\beta U(z)}]]} = \frac{\cancel{\text{Tr}_0 [e^{-\beta H_0}]} e^{-\beta U(z)}}{\cancel{\text{Tr}_0 [e^{-\beta H_0}]} \text{Tr}_z [e^{-\beta U(z)}]}$$

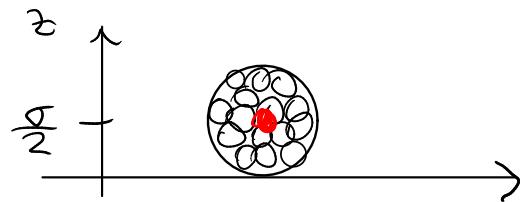
$$= \frac{e^{-\beta U(z)}}{\int_0^\infty dz e^{-\beta U(z)}} = \frac{e^{-\beta g_c \sigma^3 z}}{\int_0^\infty dz e^{-\beta g_c \sigma^3 z}} = \frac{e^{-kz}}{\int_0^\infty dz e^{-kz}}$$

$$k = \beta g_c \sigma^3 g$$

$$\langle z \rangle = \frac{\int_0^\infty dz z e^{-kz}}{\int_0^\infty dz e^{-kz}} = \frac{1}{\frac{1}{k}} \left\{ \underbrace{\left[-\frac{1}{k} e^{-kz} \cdot z \right]_0^\infty}_{=0} + \frac{1}{k} \int_0^\infty dz e^{-kz} \right\} = \frac{1}{k}$$

$$\langle z \rangle = \frac{k_B T}{g g_c \sigma^3}$$

$$\frac{k_B T}{g g_c \sigma^3} \gtrsim \sigma$$



Stabilità

$$\frac{k_B T}{g g_c \sigma^4} \gtrsim 1$$

Es: grafite in H_2O @ T_a

$$g_c \approx 10^3 \frac{kg}{m^3}$$

$$k_B T_a \approx 10^{-23} \frac{J}{K} \cdot 300K = 4 \times 10^{-21} J$$

$$\sigma = \left(\frac{4 \times 10^{-21}}{10 \times 10^3} m^4 \right)^{1/4} \sim 10^{-6} m$$

Particella libera : $\vec{F}_{est} = \vec{0}$

$$\frac{d\vec{v}}{dt} = -\frac{\xi}{m} \vec{v} + \frac{1}{m} \vec{\theta}(t) \quad \rightarrow \text{Ito, Stratonovich}$$

$$\frac{dx}{dt} = ax(t) + b(t)$$

$$x(t) = e^{at} y(t)$$

$$\cancel{ae^{at} y(t)} + e^{at} \frac{dy}{dt} = \cancel{ae^{at} y(t)} + b(t)$$

$$\frac{dy}{dt} = e^{-at} b(t) \quad \rightarrow \quad y(t) = \underbrace{y(0)}_{x(0)} + \int_0^t ds e^{-as} b(s)$$

$$x(t) = x(0) e^{at} + \int_0^t ds e^{-a(s-t)} b(s) \quad a = -\frac{\xi}{m}$$

Soluzione "formale":

$$\vec{v}(t) = \vec{v}(0) e^{-\xi/m t} + \frac{1}{m} \int_0^t ds e^{-\xi/m (t-s)} \vec{\theta}(s)$$

Relazione fluttuazione-dissipazione

$\vec{\Theta} \leftrightarrow \xi$ stato di equilibrio

$$\langle \vec{v}(t) \cdot \vec{v}(t) \rangle = \langle |\vec{v}(t)|^2 \rangle \quad \begin{matrix} = \vec{0} \\ \langle \vec{\Theta}(s) \rangle \cdot \langle \vec{v}(0) \rangle \end{matrix}$$

$$\langle |\vec{v}(t)|^2 \rangle = \langle |\vec{v}(0)|^2 \rangle e^{-2\xi/m t} + \frac{2}{m} \int_0^t ds e^{-\xi/m(2t-s)} \langle \vec{\Theta}(s) \cdot \vec{v}(0) \rangle$$
$$+ \frac{1}{m^2} \int_0^t ds \int_0^t ds' e^{-\xi/m(2t-s-s')} \langle \vec{\Theta}(s) \cdot \vec{\Theta}(s') \rangle$$

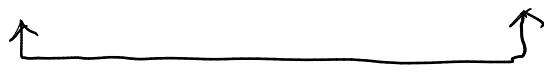
$$\frac{6\theta_0}{m^2} \int_0^t ds \int_0^t ds' e^{-\xi/m(2t-s-s')} \delta(s-s') = \frac{6\theta_0}{m^2} \int_0^t ds e^{-2\xi/m(t-s)}$$
$$= \frac{6\theta_0}{m^2} \frac{m}{2\xi} \left[e^{2\xi/m(s-t)} \right]_0^t \quad 1-0$$

$$\lim_{t \rightarrow \infty} \langle |\vec{v}(t)|^2 \rangle = \lim_{t \rightarrow \infty} \langle |\vec{v}|^2 \rangle e^{-2\xi/m t} + \lim_{t \rightarrow \infty} \frac{3\theta_0}{m\xi} \left[e^{\frac{2\xi}{m}(s-t)} \right]_0^t = \frac{3\theta_0}{m\xi}$$

= 0

Solvente = bagno termico in eq. a temp. T : teor. equipartizione energia

$$\frac{1}{2} m \langle |\vec{v}|^2 \rangle = \frac{3}{2} k_B T \quad \langle |\vec{v}|^2 \rangle = \frac{3 k_B T}{m}$$

$$\frac{\cancel{3} \theta_0}{m \cancel{3}} = \frac{\cancel{3} k_B T}{\cancel{3}} \Rightarrow \theta_0 = k_B T \cdot \xi$$


relazione fluttuazione - dissipazione

Funzione di autocorrelazione della velocità

$$\vec{v}(t) = \vec{v}(0) e^{-\frac{\gamma}{m}t} + \frac{1}{m} \int_0^t ds e^{-\frac{\gamma}{m}(t-s)} \vec{\theta}(s)$$

1d:

$$C_v(t', t'') = \langle (v(t') - \langle v \rangle) (v(t'') - \langle v \rangle) \rangle$$

$$C_v(t', t'') = \langle v(t') v(t'') \rangle$$

3d:

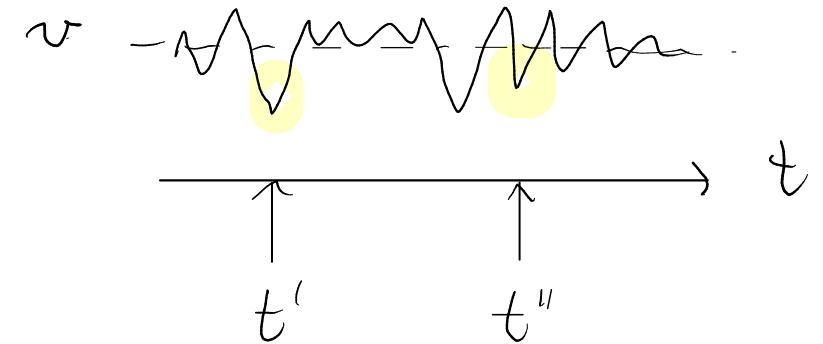
$$C_v(t', t'') = \frac{1}{3} \langle \vec{v}(t') \cdot \vec{v}(t'') \rangle$$

$$\langle \vec{v}(t) \rangle = \langle \vec{v}(0) \rangle e^{-\frac{\gamma}{m}t} + \frac{1}{m} \int_0^t ds e^{-\frac{\gamma}{m}(t-s)} \langle \vec{\theta}(s) \rangle = \vec{v}(0) e^{-\frac{\gamma}{m}t}$$

$\langle \vec{\theta}(s) \rangle = 0$

Equilibrio: $\langle u \rangle = \langle u \rangle_{eq}$

$$C_v(t) = \frac{1}{3} \langle \vec{v}(t) \cdot \vec{v}(0) \rangle_{eq} \quad t > 0 \quad (t'' > t')$$



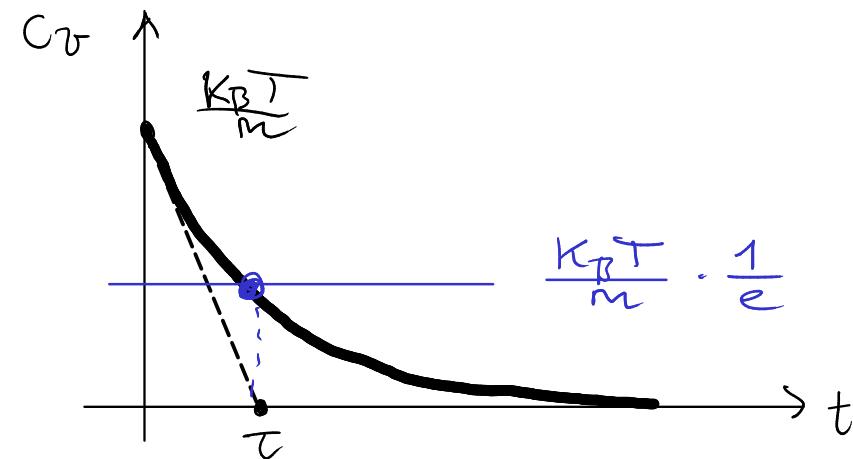
$$\begin{aligned}
C_v(t) &= \frac{1}{3} \langle \vec{v}(t) \cdot \vec{v}(0) \rangle_{eq} \\
&= \frac{1}{3} \langle |\vec{v}(0)|^2 \rangle_{eq} e^{-\xi/m t} + \frac{1}{m} \int_0^t ds e^{-\xi/m(t-s)} \langle \vec{v}(0) \cdot \vec{\Theta}(s) \rangle_{eq} \\
&= \frac{k_B T}{m} e^{-\xi/m t}
\end{aligned}$$

Tempo di correlazione: $\tau = \frac{m}{\xi}$

$m \uparrow \tau \uparrow$
 $\xi \uparrow \tau \downarrow$

$$\langle \vec{v}(t) \rangle = \vec{v}(0) e^{-\xi/m t}$$

↑
tempo di rilassamento



(es.) Mostra che

$$\langle \vec{v}(t') \cdot \vec{v}(t'') \rangle = \left[|\vec{v}(0)|^2 - \frac{3\theta_0}{m\xi} \right] e^{-\xi/m(t'+t'')} + \frac{3\theta_0}{m\xi} e^{-\xi/m|t''-t'|} \leftarrow \triangle!$$

$$\langle |\vec{v}(0)|^2 \rangle_v = \frac{3\theta_0}{m\xi}$$

Spostamento quadratico medio

$$\langle |\Delta \vec{F}(t)|^2 \rangle_{eq} = \langle |\vec{F}(t) - \vec{F}(0)|^2 \rangle_{eq} \quad \text{equilibrio} \quad \langle \dots \rangle = \langle \dots \rangle_{eq}$$

Relazione generale tra $\langle |\Delta \vec{F}|^2 \rangle$ e $C_v(t)$

$$\Delta \vec{F} = \int_0^t \vec{v}(s) ds$$

$$\langle |\Delta \vec{F}(t)|^2 \rangle = \int_0^t ds \int_0^t ds' \langle \vec{v}(s) \cdot \vec{v}(s') \rangle$$

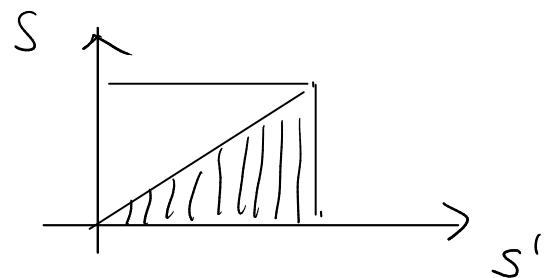
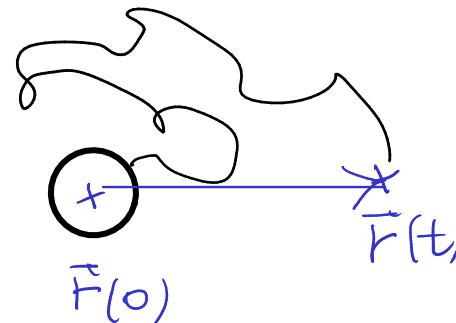
$$= 2 \int_0^t ds \int_0^s ds' \langle \vec{v}(s) \cdot \vec{v}(s') \rangle$$

$$= 6 \int_0^t ds \int_0^s ds' C_v(s' - s) = 6 \int_0^t ds \int_0^s dt' C_v(t')$$

$$= 6 \left\{ \left[s \int_0^s dt' C_v(t') \right]_0^t - \int_0^t ds s C_v(s) \right\}$$

$$= 6 \left\{ t \int_0^t dt' C_v(t') - \int_0^t ds s C_v(s) \right\}$$

$$= 6 t \left\{ \int_0^t ds \left(1 - \frac{s}{t} \right) C_v(s) \right\} \quad \square$$



Cambio variabile: $t' = s' - s$

(es.) Mostra che:

$$\langle |\Delta \vec{r}|^2 \rangle = 6 \frac{k_B T}{\zeta} \left[t + \frac{m}{\zeta} (e^{-\zeta/m t} - 1) \right]$$

Tempi corti: $t \ll \frac{m}{\zeta}$ Taylor II ordine

$$\langle |\Delta \vec{r}|^2 \rangle \approx 6 \frac{k_B T}{\zeta} \left[t + \frac{m}{\zeta} \left(1 - \frac{\zeta}{m} t + \frac{1}{2} \frac{\zeta^2}{m^2} t^2 - 1 \right) \right]$$

$$= 6 \frac{k_B T}{\zeta} \left[t - t + \frac{1}{2} \frac{\zeta}{m} t^2 \right]$$

$$= \frac{3 k_B T}{m} t^2 = \langle |\vec{v}|^2 \rangle t^2 \quad \text{balistico}$$

Tempi lunghi: $t \gg \frac{m}{\zeta}$

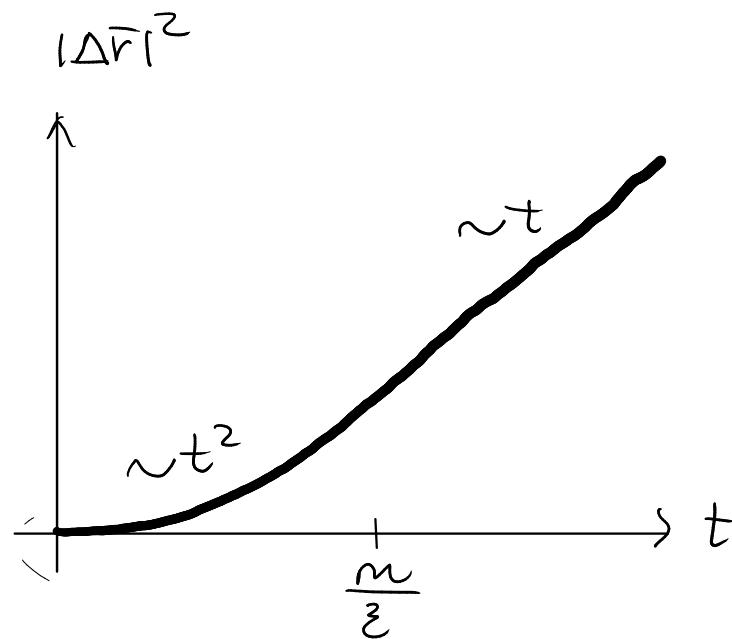
$$\langle |\Delta \vec{r}|^2 \rangle \approx 6 \frac{k_B T}{\zeta} t \quad \text{diffusivo}$$

$$= 2 \cdot d \cdot D \cdot t$$

\downarrow
=3

coeff. di diffusione: $D = \frac{k_B T}{\zeta}$

$\rightarrow \zeta \searrow D$
 $\nearrow T \nearrow D$



EQUAZIONE DI LANGEVIN SOVRA-AMORTITA

Sovra-amortito: effetti inerziali trascurabili

$$m \frac{d\vec{v}}{dt} = -\zeta \vec{v} + \vec{\Theta}(t) \quad \Theta_0 \sim \zeta \quad \zeta \rightarrow \infty$$

$$\approx 0$$

$$\zeta \frac{d\vec{r}}{dt} = \vec{\Theta}(t) \quad \text{particella libera, sovra-amortito}$$

Soluzione formale:

$$\vec{r}(t) = \vec{r}(0) + \frac{1}{\zeta} \int_0^t ds \vec{\Theta}(s)$$

$$\langle |\Delta \vec{r}|^2 \rangle = \langle |\vec{r}(t) - \vec{r}(0)|^2 \rangle = \frac{1}{\zeta^2} \int_0^t ds \int_0^t ds' \langle \vec{\Theta}(s) \cdot \vec{\Theta}(s') \rangle \sim \delta(s-s') \rightarrow \mathcal{D}$$

$$= \frac{6\Theta_0}{\zeta^2} \int_0^t ds = 6 \frac{\Theta_0}{\zeta^2} t$$

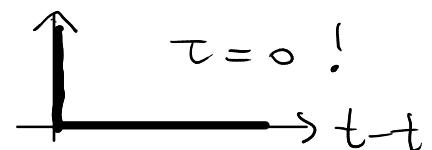
$$\zeta \frac{d\vec{r}}{dt} = \vec{F}_{est} + \vec{\Theta}(t) \quad \Theta_0 = k_B T \cdot \zeta \Rightarrow \langle |\Delta \vec{r}|^2 \rangle_{eq} = 6 \frac{k_B T}{\zeta} t$$

↳ Langevin

$$1d: \langle \theta(t) \theta(t') \rangle = 2\theta_0 \delta(t-t')$$

$$\langle \theta \rangle = 0$$

$$C_\theta(t-t') = 2\theta_0 \delta(t-t')$$



Esempi (Notebooks)

- forza costante ↙
- potenziale armonico ↘

- forza sinusoidale ↙
- particella attiva ↙

Algoritmo di Ermak: potenziale generico

Dinamica browniana:

$$3d: \quad \Sigma \frac{d\vec{r}}{dt} = \vec{F}_{est} + \vec{\Theta}(t)$$

$$1d: \quad \Sigma \frac{dx}{dt} = F_{est}(x) + \Theta(t) \quad \langle \Theta(t) \rangle = 0 \quad \langle \Theta(t) \Theta(t') \rangle = 2\theta_0 \delta(t-t')$$

Eulero: passo temporale Δt

$$x(t+\Delta t) = x(t) + \frac{1}{\Sigma} \int_t^{t+\Delta t} ds F_{est} + \frac{1}{\Sigma} \int_t^{t+\Delta t} ds \Theta(s)$$
$$\approx x(t) + \frac{1}{\Sigma} F_{est} \Delta t + \tilde{\Theta}(t; \Delta t)$$

$\tilde{\Theta}$ sia distribuita secondo gaussiana

$$\langle \tilde{\Theta}(t; \Delta t) \rangle = 0$$

$$\langle \tilde{\Theta}(t; \Delta t) \tilde{\Theta}(t'; \Delta t) \rangle = \frac{1}{\Sigma^2} \int_t^{t+\Delta t} ds \int_t^{t+\Delta t} ds' \langle \Theta(s) \Theta(s') \rangle \sim \delta(s-s')$$

$$= \frac{2\theta_0}{z^2} \int_t^{t+\Delta t} ds = \frac{2\theta_0}{z^2} \Delta t \stackrel{\text{eq.}}{=} 2 \frac{k_B T}{z} \Delta t$$

Distribuzione di $\tilde{\theta}$

$$p(\tilde{\theta}) = \frac{1}{\sqrt{4\pi D \Delta t}} \exp\left(-\frac{\tilde{\theta}^2}{4D \Delta t}\right)$$

3d:

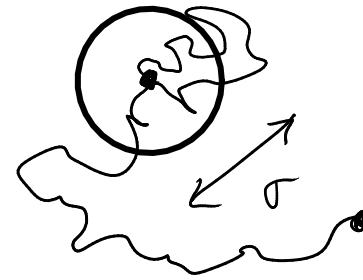
$$p(\vec{\tilde{\theta}}) = \frac{1}{(4\pi D \Delta t)^{3/2}} \exp\left(-\frac{|\vec{\tilde{\theta}}|^2}{4D \Delta t}\right)$$

Condizione di validità dell'eq. Langevin sovra-amortita

$\tau = \frac{m}{\xi}$ tempo di correlazione

$$D \sigma^2 = \frac{\xi \sigma^2}{k_B T} \gg \frac{m}{\xi} \Rightarrow \xi \gg \sqrt{\frac{m \cdot k_B T}{\sigma^2}}$$

es.: $\sqrt{\langle |\vec{v}|^2 \rangle} \tau \approx \sigma$



$$\langle |\Delta \vec{r}(t)|^2 \rangle \approx Dt \approx \sigma^2$$

$$D = \frac{k_B T}{\xi}$$

Langevin



$p(\vec{v})$

$p(\vec{r}, \vec{v})$

Fokker-Planck

Kramers

$$\vec{F}_{est} = \vec{0}$$

Sovra-amortita



$p(\vec{r})$

Smoluchowski

$$\vec{F}_{est} \neq \vec{0}$$

Eq. diff. ordinarie
STOCASTICHE

Eq. derivate parziali
DETERMINISTICHE

EQUAZIONE DI SMOLUCHOWSKI.

$$\zeta \frac{dx}{dt} = F(x) + \theta(t) \quad \langle \theta(t) \rangle = 0 \quad \langle \theta(t') \theta(t'') \rangle = 2\theta_0 \delta(t-t') \quad \theta_0 = k_B T \cdot \zeta$$

Spostamento h durante Δt

$$h = \frac{1}{\zeta} F(x) \Delta t + \frac{1}{\zeta} \int_t^{t+\Delta t} ds \langle \theta(s) \rangle = \frac{1}{\zeta} F(x) \Delta t$$

$$D = \frac{k_B T}{\zeta}$$

Densità di prob. di h

$$\Pi(h, x) = \frac{1}{\sqrt{4\pi D \Delta t}} \exp \left[-\frac{(h - \frac{F}{\zeta} \Delta t)^2}{4 D \Delta t} \right]$$

$$\left\{ \begin{array}{l} \langle h \rangle = \frac{F}{\zeta} \Delta t \end{array} \right.$$

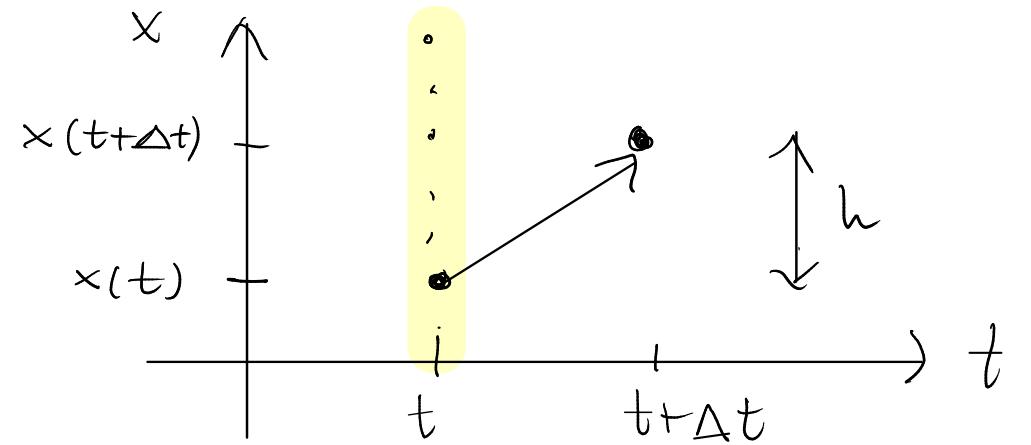
$$\left\{ \begin{array}{l} \underbrace{\langle (h - \langle h \rangle)^2 \rangle}_{\langle \delta h^2 \rangle} = \frac{1}{\zeta^2} \int_t^{t+\Delta t} ds \int_t^{t+\Delta t} ds' \langle \theta(s) \theta(s') \rangle = 2 \frac{\theta_0}{\zeta^2} \Delta t = 2 D \Delta t \end{array} \right.$$

Master equation per $p(x,t)$

$$p(x, t+\Delta t) = \int_{-\infty}^{\infty} dh \underbrace{p(x-h, t) \Pi(h, x-h)}_{\varphi(x-h) = \varphi(y)}$$

$$\varphi(x-h) = \varphi(y)$$

$$y = x-h$$



Taylor II ordine: $y_0 = x$ $\Delta y = -h$ $\frac{d\varphi}{dy} = \frac{d\varphi}{dx}$

$$\int_{-\infty}^{\infty} dh \left[\varphi(x) + \frac{d\varphi}{dy} \Delta y + \frac{1}{2} \frac{d^2\varphi}{dy^2} \Delta y^2 \right] = \int_{-\infty}^{\infty} dh \left[\varphi(x) - \frac{d\varphi}{dx} h + \frac{1}{2} \frac{d^2\varphi}{dx^2} h^2 \right]$$

$$= \int_{-\infty}^{\infty} dh \left\{ p(x,t) \Pi(h,x) - \frac{\partial}{\partial x} [p(x,t) \Pi(h,x)] h + \frac{1}{2} \frac{\partial^2}{\partial x^2} [p(x,t) \Pi(h,x)] h^2 \right\}$$

$$= p(x,t) - \frac{\partial}{\partial x} \left[p(x,t) \underbrace{\int_{-\infty}^{\infty} dh \Pi(h,x) h}_{\frac{1}{2} F(x) \Delta t} \right] + \frac{1}{2} \frac{\partial^2}{\partial x^2} \left[p(x,t) \underbrace{\int_{-\infty}^{\infty} dh \Pi(h,x) h^2}_{\langle \delta h^2 \rangle - \langle h \rangle^2} \right]$$

$2D\Delta t$ $O(\Delta t^2)$

Taylor I ordine in Δt

$$p(x, t) + \frac{\partial p}{\partial t} \Delta t + o(\Delta t^2) = p(x, t) - \frac{\partial}{\partial x} \left[\frac{1}{\Sigma} F(x) p(x, t) \right] \Delta t + \frac{\partial^2}{\partial x^2} \left[D p(x, t) \right] \Delta t + o(\Delta t^2)$$

$$\frac{\partial p}{\partial t} = - \frac{\partial}{\partial x} \left[\frac{1}{\Sigma} F(x) p(x, t) \right] + \frac{\partial^2}{\partial x^2} \left[D p(x, t) \right] \quad \underline{\text{Eq. Smoluchowski}}$$

$$\frac{\partial p}{\partial t} = - \vec{\nabla} \cdot \left[\frac{1}{\Sigma} \vec{F}(\vec{r}) p(\vec{r}, t) \right] + \nabla^2 \left[D p(\vec{r}, t) \right] \quad \text{in 3d}$$

$$\frac{\partial p}{\partial t} + \vec{\nabla} \cdot \left[\frac{1}{\Sigma} \vec{F}(\vec{r}) p(\vec{r}, t) \right] - \vec{\nabla} \cdot \vec{\nabla} \left[D p(\vec{r}, t) \right] = 0 \quad D = \text{cost}$$

$$\frac{\partial p}{\partial t} + \vec{\nabla} \cdot \left[\frac{1}{\Sigma} \vec{F}(\vec{r}) p(\vec{r}, t) - \vec{\nabla} (D p(\vec{r}, t)) \right] = 0 \quad \rightarrow \text{eq. continuit\`a}$$

$$\frac{\partial p}{\partial t} = - \vec{\nabla} \cdot \left[\frac{1}{\Sigma} \vec{F} p \right] + D \nabla^2 p \quad \frac{\partial p}{\partial t} = D \frac{\partial^2 p}{\partial x^2} \quad \text{Eq. deriva-diffusione}$$

deriva diffusione

$$\text{Fokker-Planck: } \frac{\partial p}{\partial t} = \frac{\partial}{\partial v} \left(\frac{\Sigma}{m} v(t) p(v, t) + \frac{\Sigma^2}{m^2} D \frac{\partial p}{\partial v} \right) \rightarrow p(v, t)$$

Casi particolari:

1) Equilibrio

$$p(x,t) \sim \exp\left(-\frac{U(x)}{k_B T}\right)$$

$$F(x) = -\frac{dU}{dx}$$

$$\frac{\partial p}{\partial t} = -\frac{\partial}{\partial x} \left(\frac{1}{\xi} F(x) p(x,t) \right) + D \frac{\partial^2 p}{\partial x^2} = \frac{\partial}{\partial x} \left(-\frac{1}{\xi} F(x) p(x,t) + D \frac{\partial p}{\partial x} \right)$$

$$-\frac{1}{\xi} F(x) \exp\left(-\frac{U(x)}{k_B T}\right) + \frac{k_B T}{\xi} \left(-\frac{1}{k_B T} \frac{dU}{dx} \right) \exp\left(-\frac{U(x)}{k_B T}\right) = 0 \Rightarrow J=0$$

$$\Rightarrow \frac{\partial p}{\partial t} = 0 \rightarrow \text{stazionario}$$

2) Particella libera

$$\vec{F} = \vec{0} \quad 3d : \quad \frac{\partial p}{\partial t} = D \nabla^2 p$$

$$p = p(\vec{r}, t) \rightarrow \text{eq. di diffusione}$$

Trasf. Fourier:

$$p_{\vec{K}}(t) = \int d\vec{r} e^{-i\vec{k} \cdot \vec{r}} p(\vec{r}, t)$$

Anti-trasf. Fourier:

$$p(\vec{r}, t) = \frac{1}{(2\pi)^3} \int d\vec{k} e^{i\vec{k} \cdot \vec{r}} p_{\vec{K}}(t)$$

$$\frac{\partial \bar{p}_k}{\partial t} = -k^2 D \bar{p}_k \quad \frac{\partial}{\partial x} \rightarrow ik$$

$$\bar{p}_k(t) = \bar{p}_k(0) \exp(-k^2 D t)$$

Condizioni iniziali: $p(\bar{r}) = \delta(\bar{0})$
 $\rightarrow \bar{p}_k(0) = 1$

In spazio reale:

$$p(\bar{r}, t) = \frac{1}{(4\pi D t)^{3/2}} \exp\left(-\frac{|\bar{r}|^2}{4 D t}\right)$$

3) Forza costante

$$F = \text{cost} \quad \frac{\partial p}{\partial t} = -\frac{F}{\Sigma} \frac{\partial p}{\partial x} + D \frac{\partial^2 p}{\partial x^2}$$

$$y = x - \frac{F}{\Sigma} t$$

$$p(x, t) \rightarrow q(y, t)$$

$$p(x, t) dx dt = q(y, t) dy dt$$

$$p(x, t) = q(y, t)$$

Condizioni contorno:

- $p=0$: assorbenti

- $J=0$: riflettenti

Condizioni iniziali: $p(\bar{r}, t=0)$

$$p(\bar{r}, 0) = \delta(\bar{r}=0)$$

$$\frac{\partial q}{\partial t} + \frac{\partial q}{\partial y} \frac{\partial y}{\partial t} = - \frac{F}{\xi} \frac{\partial q}{\partial y} + D \frac{\partial^2 q}{\partial y^2}$$

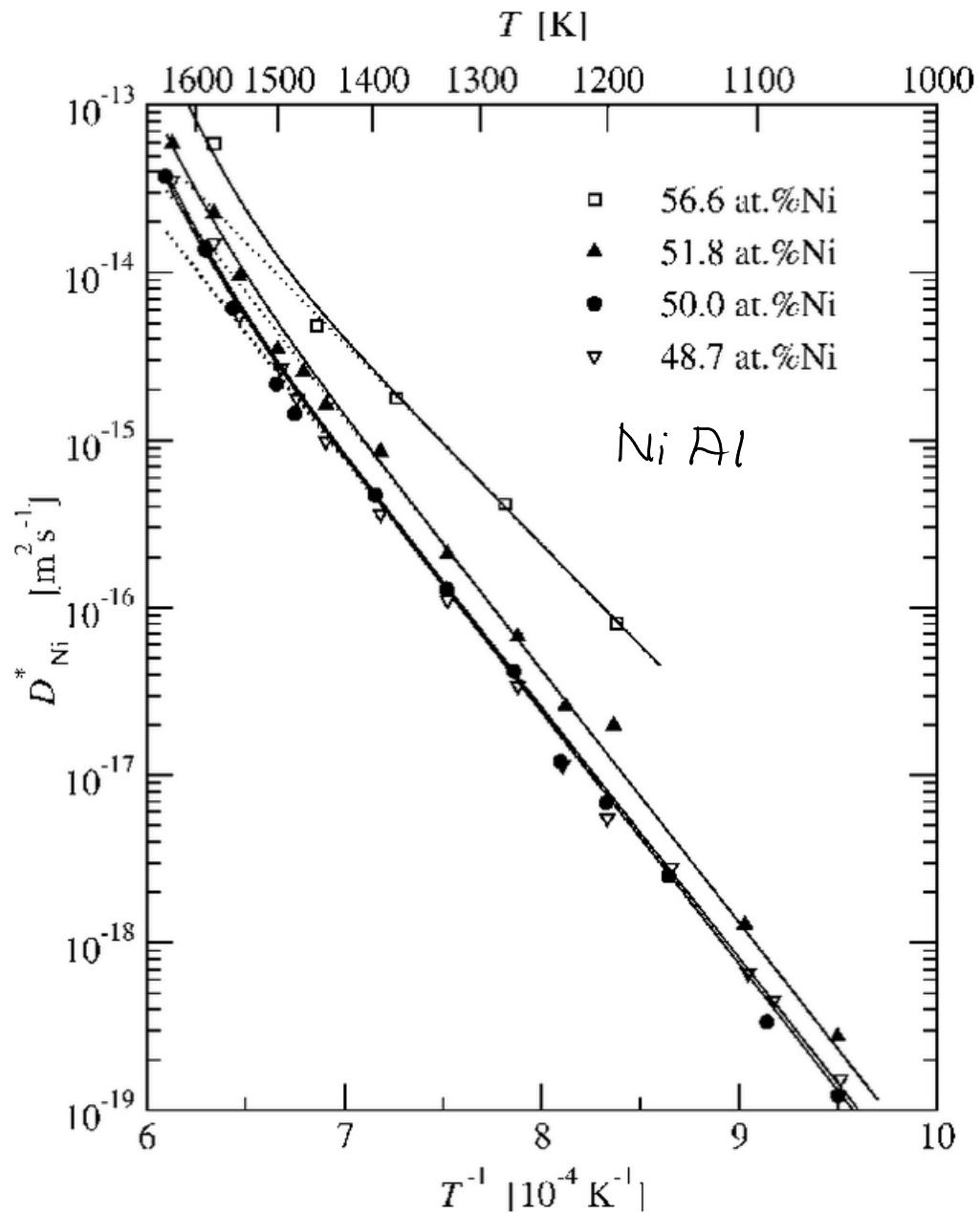
$$\frac{\partial q}{\partial t} - \cancel{\frac{F}{\xi} \frac{\partial q}{\partial y}} = - \cancel{\frac{F}{\xi} \frac{\partial q}{\partial t}} + D \frac{\partial^2 q}{\partial y^2} \Rightarrow \frac{\partial q}{\partial t} = D \frac{\partial^2 q}{\partial y^2}$$

Solution:

$$q(y, t) = \frac{1}{\sqrt{4\pi Dt}} \exp\left(-\frac{y^2}{4Dt}\right)$$

$$p(x, t) = \frac{1}{\sqrt{4\pi Dt}} \exp\left(-\frac{(x - \frac{F}{\xi}t)^2}{4Dt}\right)$$

$$\left\{ \begin{array}{l} \langle x(t) \rangle = \frac{F}{\xi} t \quad \rightarrow \text{drift} \\ \langle (x(t) - \langle x(t) \rangle)^2 \rangle = 2Dt \quad \rightarrow \text{diffusion} \end{array} \right. \quad \langle |x(t) - x(0)|^2 \rangle$$



The Arrhenius diagram of Ni diffusion in different NiAl alloys (the composition is indicated in at.%Ni). The dotted lines present the extrapolation of the Arrhenius fits obtained in the low-temperature interval, $T < 1500$ K, of the experiments.

$$D \sim \exp\left(-\frac{A}{T}\right)$$

$$\eta \sim \exp\left(\frac{A}{T}\right)$$

$$\langle |\Delta F|^2 \rangle \sim Dt$$

$$\sigma^2 = D\tau_D$$

$$\tau_D \sim \frac{1}{D}$$

$$\tau_D \sim \exp\left(\frac{A}{T}\right)$$

$$\eta = G_0 \tau$$

$$\tau \sim \exp\left(\frac{A}{T}\right)$$

legge di

ARRHENIUS

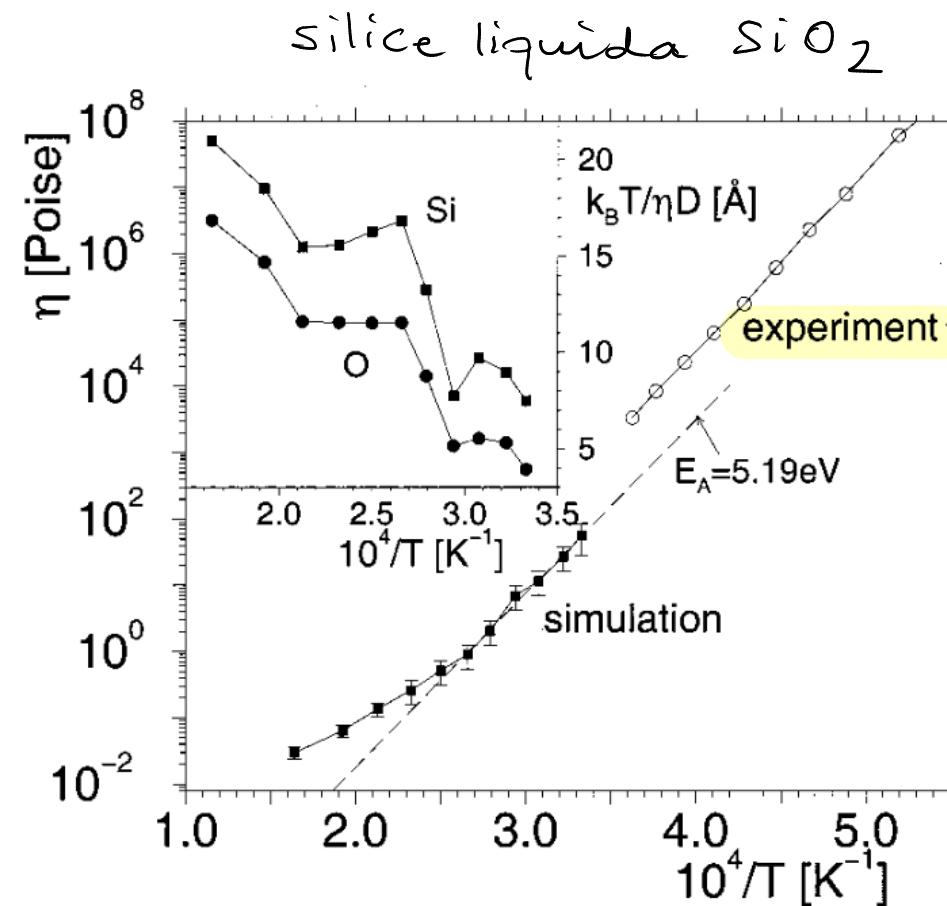
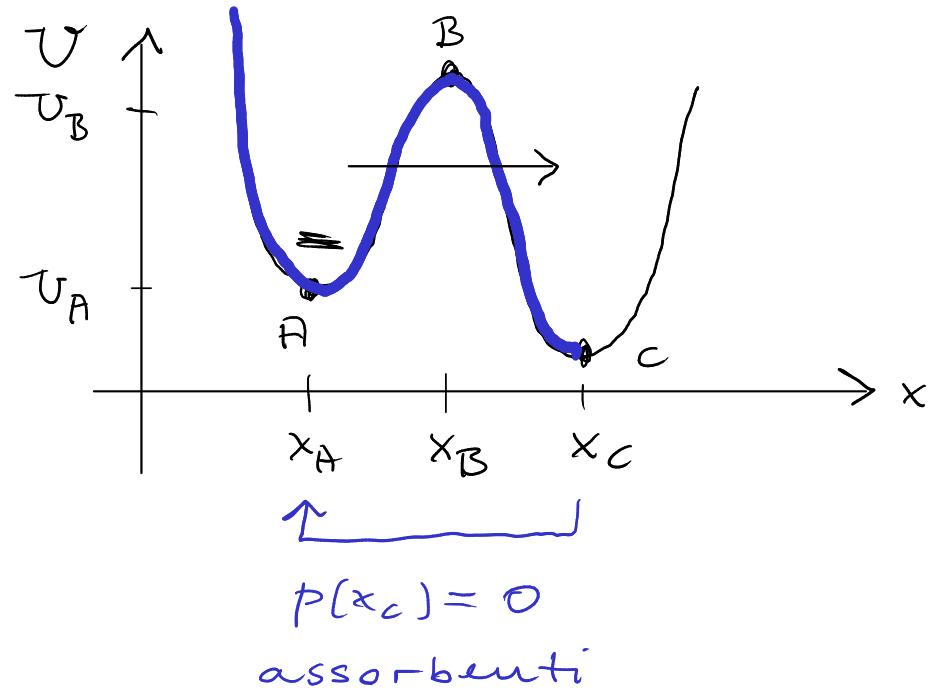


FIG. 10. Main figure: Arrhenius plot of the shear viscosity from the simulation (solid squares). The dashed line is a fit with an Arrhenius law to our low-temperature data. The open circles are experimental data from Urbain *et al.* (Ref. 35). Inset: temperature dependence of the left hand side of Eq. (12) to check the validity of the Stokes-Einstein relation.

4) Attivazione termica: problema di Kramers (1940)



Modello: particella browniana in una doppia buca di potenziale

$$\Delta U = U_B - U_A \gg k_B T$$

Goal: tempo di uscita medio

$$\frac{\partial p}{\partial t} = \frac{\partial}{\partial x} \left[-\frac{F}{\zeta} p + D \frac{\partial p}{\partial x} \right] \quad D = \frac{k_B T}{\zeta}$$

$$= \frac{\partial}{\partial x} \left[\underbrace{\frac{1}{\zeta} \frac{dU}{dx} p + \frac{k_B T}{\zeta} \frac{\partial p}{\partial x}}_{-J} \right]$$

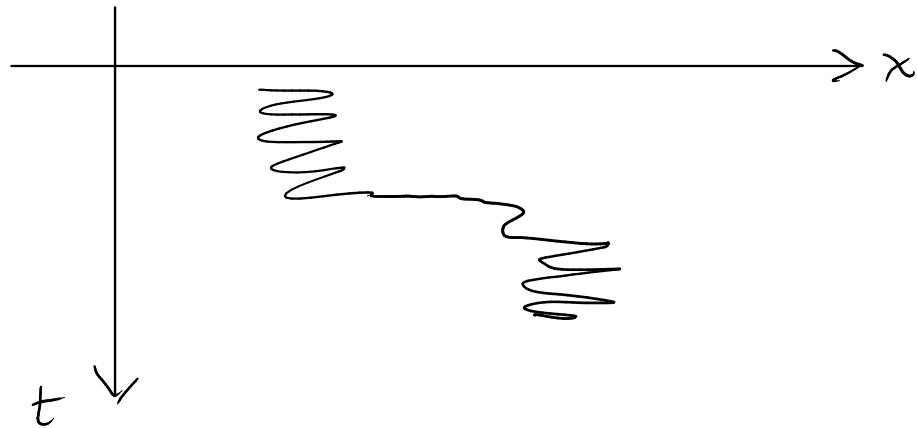
Regime stazionario: $\frac{\partial p}{\partial t} = 0 \Rightarrow J = \text{cost}$

$$\frac{1}{\zeta} \frac{dU}{dx} p + \frac{k_B T}{\zeta} \frac{dp}{dx} = -J$$

$$p(x) = \psi(x) \exp\left(-\frac{U(x)}{k_B T}\right)$$



H. Kramers
1894 - 1952

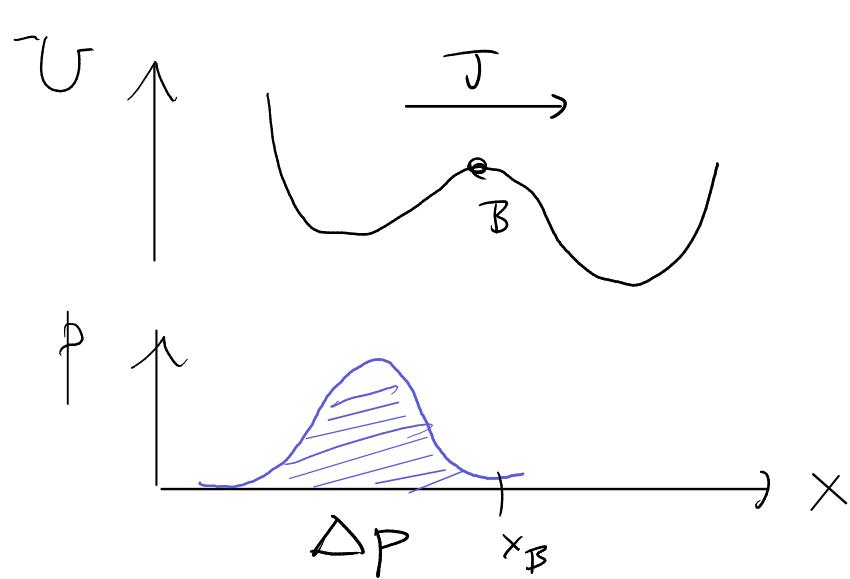


$$\frac{1}{\xi} \frac{dU}{dx} \psi(x) \exp\left(-\frac{U}{k_B T}\right) + \frac{k_B T}{\xi} \frac{d\psi}{dx} \exp\left(-\frac{U}{k_B T}\right) + \frac{k_B T}{\xi} \psi(x) \left(-\frac{dU}{dx}\right) \frac{1}{k_B T} \exp\left(-\frac{U}{k_B T}\right) = -J$$

$$\frac{d\psi}{dx} = -\frac{J \xi}{k_B T} \exp\left(\frac{U}{k_B T}\right) \quad \text{conditione al contorno: } p(x_c) = 0 \Rightarrow \psi(x_c) = 0$$

$$\psi(x) = \frac{J \xi}{k_B T} \int_x^{x_c} dx' \exp\left(\frac{U(x')}{k_B T}\right) \rightarrow p(x) = \frac{J \xi}{k_B T} \exp\left(-\frac{U(x)}{k_B T}\right) \int_x^{x_c} dx' \exp\left(\frac{U(x')}{k_B T}\right)$$

Tempo di uscita medio: τ



$$J = \frac{\Delta n}{\tau} \Rightarrow \tau J = \int_{-\infty}^{x_B} dx p(x) = \Delta p$$

$$\tau J = \frac{J \xi}{k_B T} \int_{-\infty}^{x_B} dx'' \exp\left(-\frac{U(x'')}{k_B T}\right) \int_{x''}^{x_c} dx' \exp\left(\frac{U(x')}{k_B T}\right)$$

$$\tau = \frac{\xi}{k_B T} \int_{-\infty}^{x_B} dx'' \exp\left(-\frac{U(x'')}{k_B T}\right) \underbrace{\int_{x''}^{x_c} dx' \exp\left(\frac{U(x')}{k_B T}\right)}_{\approx \text{cost per } x'' \approx x_A} \quad (*)$$

$\approx \text{cost per } x'' \approx x_A$

Taylor per $x' \approx x_B$: $U(x') \approx U_B - \frac{1}{2} m \omega_B^2 (x - x_B)^2$

$$\textcircled{1} \exp\left(\frac{U_B}{k_B T}\right) \int_{x''}^{x_C} dx' \exp\left[-\frac{1}{2} \frac{m \omega_B^2}{k_B T} (x - x_B)^2\right]$$

$$\approx \exp\left(\frac{U_B}{k_B T}\right) \int_{-\infty}^{\infty} dx' \exp\left[-\frac{1}{2} \frac{m \omega_B^2}{k_B T} (x - x_B)^2\right] = \exp\left(\frac{U_B}{k_B T}\right) \sqrt{\frac{2\pi k_B T}{m \omega_B^2}}$$

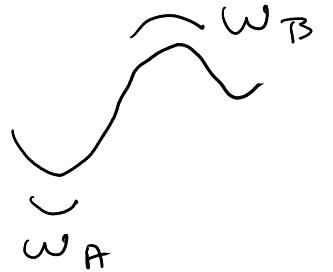
$$\tau = \frac{Z}{k_B T} \sqrt{\frac{2\pi k_B T}{m \omega_B^2}} \exp\left(\frac{U_B}{k_B T}\right) \int_{-\infty}^{x_B} dx'' \exp\left(-\frac{U(x'')}{k_B T}\right)$$

Taylor per $x'' \approx x_A$: $U(x'') \approx U_A + \frac{1}{2} m \omega_A^2 (x - x_A)^2$

$$\tau = \frac{Z}{k_B T} \sqrt{\frac{2\pi k_B T}{m \omega_B^2}} \exp\left(\frac{U_B}{k_B T}\right) \exp\left(-\frac{U_A}{k_B T}\right) \int_{-\infty}^{\infty} dx'' \exp\left[-\frac{1}{2} \frac{m \omega_A^2}{k_B T} (x - x_A)^2\right]$$

$$= \frac{Z}{k_B T} \sqrt{\frac{2\pi k_B T}{m \omega_B^2}} \sqrt{\frac{2\pi k_B T}{m \omega_A^2}} \exp\left(\frac{\Delta U}{k_B T}\right)$$

$$\tau = \frac{2\pi \Sigma}{m \omega_A \omega_B} \exp\left(\frac{\Delta U}{k_B T}\right)$$



$\omega_A \uparrow \omega_B \uparrow \Rightarrow \tau \downarrow$
 $\Sigma \uparrow \Rightarrow \tau \uparrow$

↑
fattore di Arrhenius

