

$$S_n(\omega) = W_n(\omega) \frac{u(z1, \omega)}{u(z2, \omega)}$$

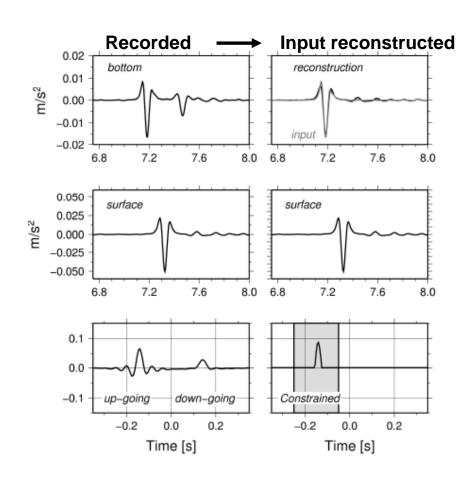
where

$$W_n(\omega) = 1 - (1 - \tau |u(z2, \omega)|^2)^n$$

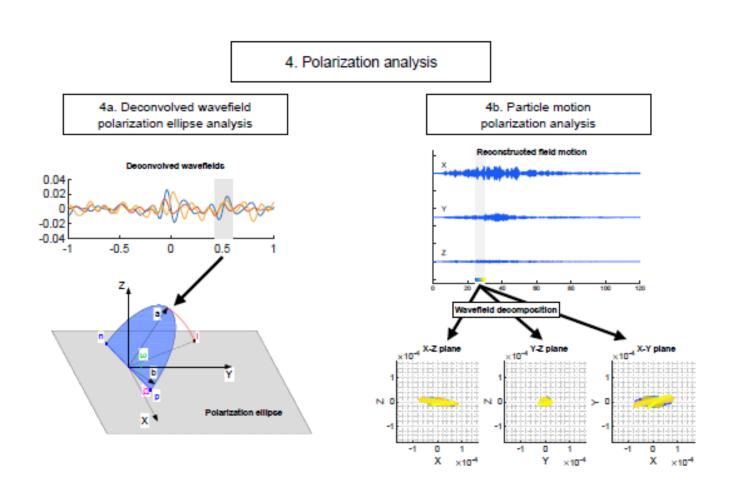
is the Landweber filter

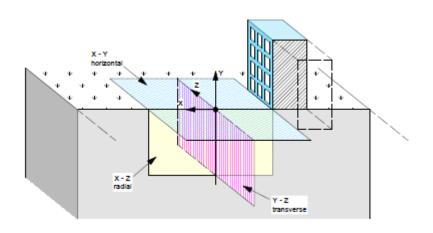
Bindi et al., 2010

The input ground motion at depth is reconstructed from that at the surface without requiring the knowledge of the borehole velocity structure









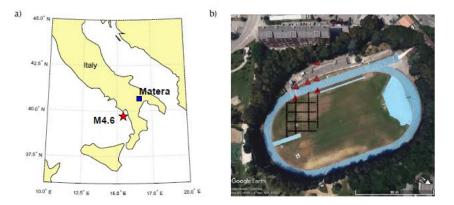
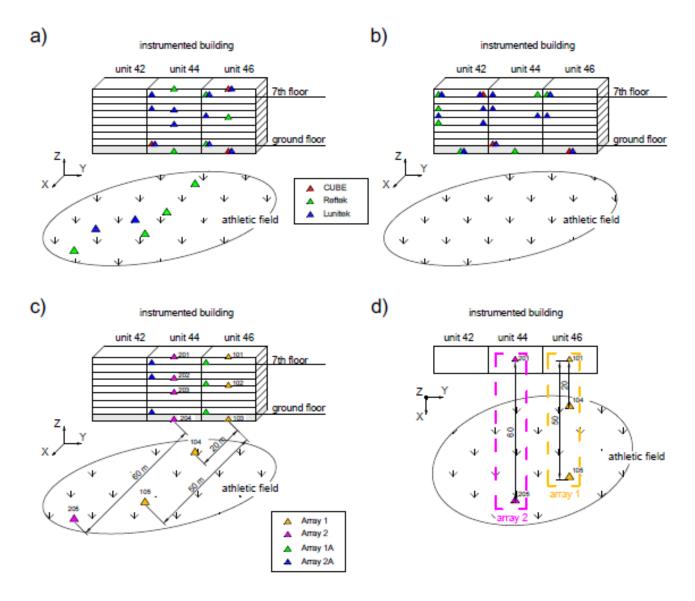
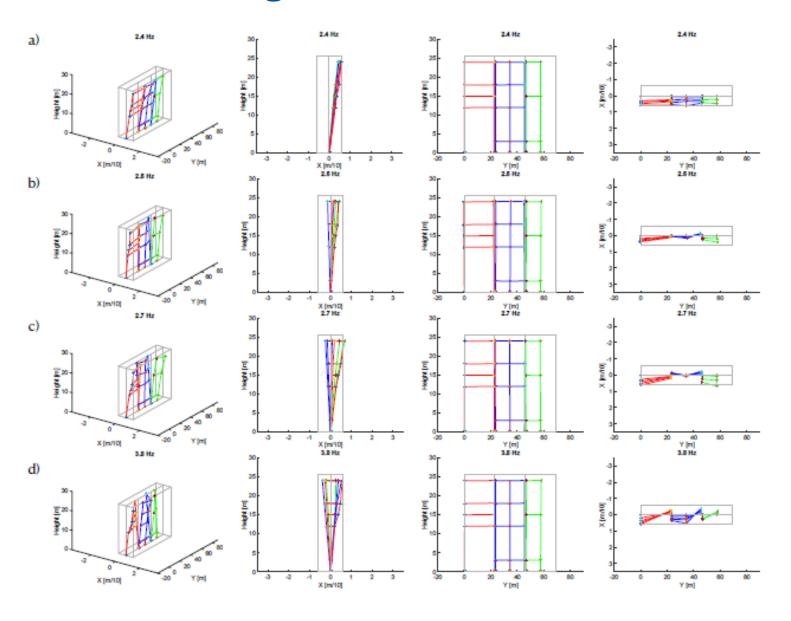


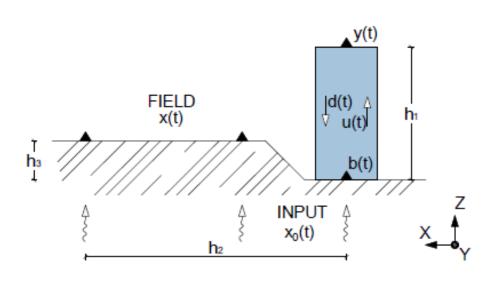
Figure 4.1: (a) Location of Matera test site (blue square) and the epicenter of the M4.6 Catanzaro earthquake on 25.10.2019 (red star). (b) Satellite view of Matera test site. Athletic field instrumentation deployment is indicated with red triangles (three-component sensors) and black dots (vertical geophones).



Figure 4.2: a) The building instrumented during the Matera experiment. b) Reftek digitizer connected to LE-3Dlite 1 s sensor. c) CUBE digitizer connected to LE-3Dlite 1 s sensor. d) Lunitek Sentinel Geo. Photographs author: Bojana Petrovic.







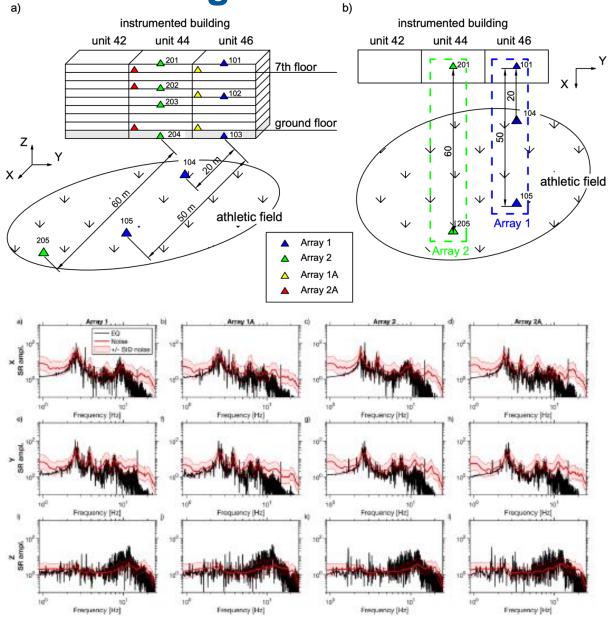
$$\frac{X(f)}{Y(f)} = P_1 + P_2 + P_3$$

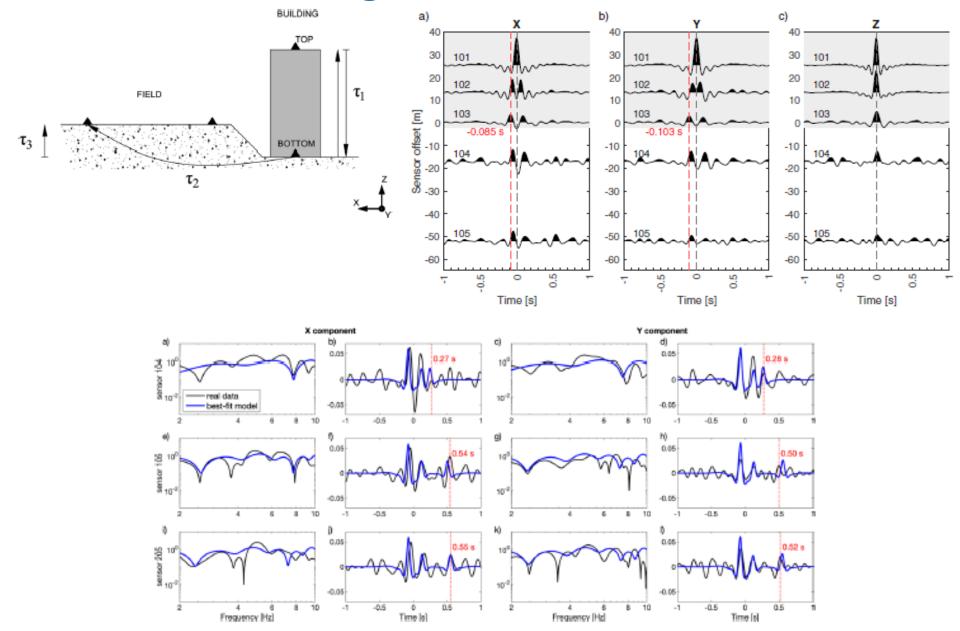
$$P_1 = \frac{1}{1+r} e^{-i2\pi f(-\tau_1 + \tau_3)},$$

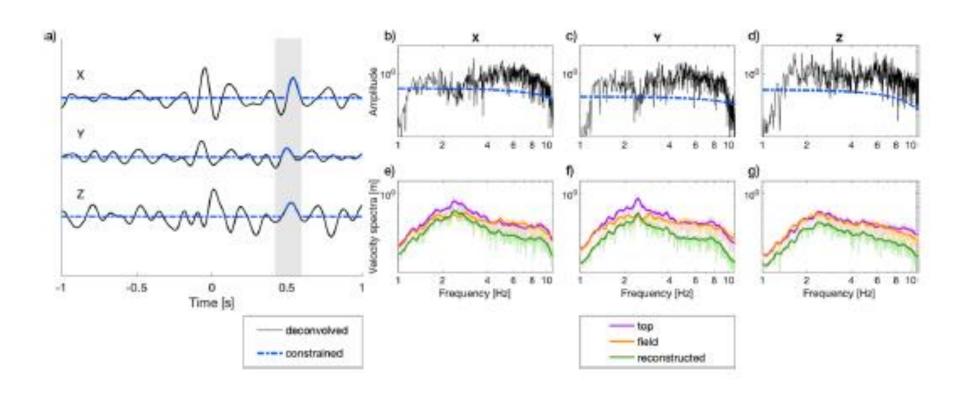
$$P_2 = \frac{r}{1+r}e^{-i2\pi f(\tau_1+\tau_3)},$$

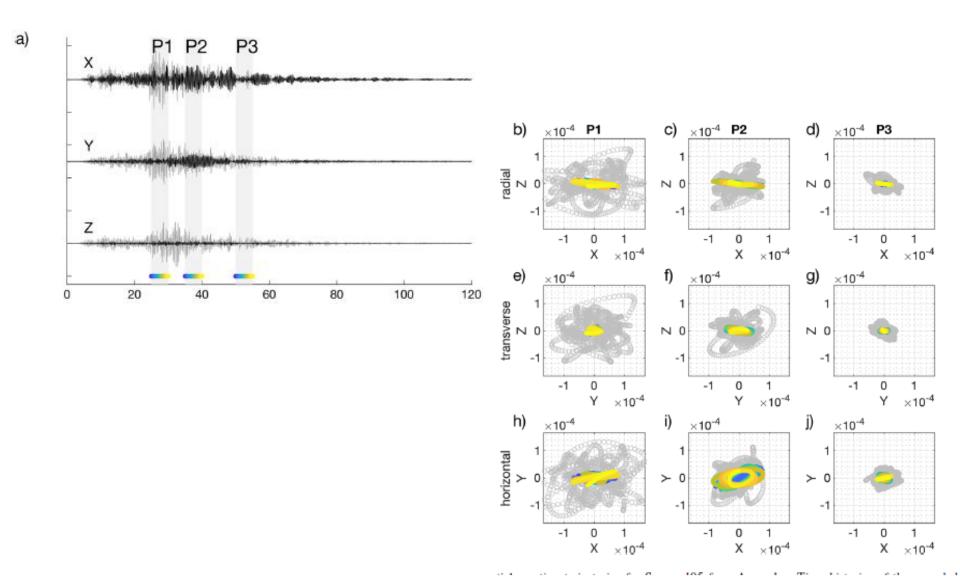
$$P_3 = \frac{(1-r)}{2} e^{-i2\pi f(\tau_1 + \tau_2 + \tau_3)}.$$

$$X(f) = Y(f)\frac{1}{1+r}\left[e^{-i2\pi f(-\tau_1)} + re^{-i2\pi f\tau_1}\right] + (1-r)Y(f)e^{-i2\pi f(\tau_1+\tau_2+\tau_3)}$$

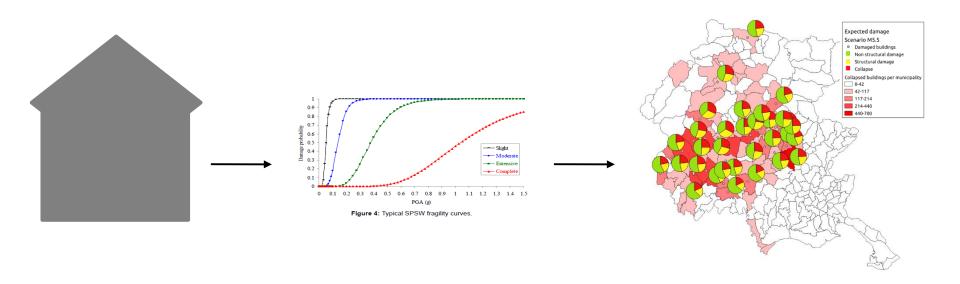








Damage assessment

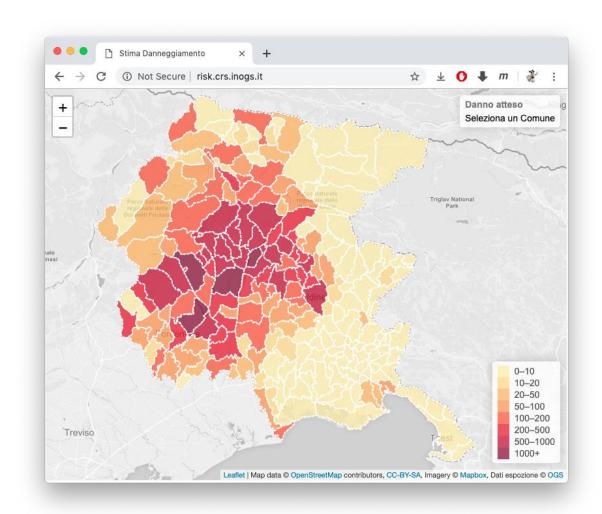


Building typologies (taxonomy to grasp specific characteristics)

Fragility curves for different damage states. Curves based on building characteristics

Number of buildings with complete, extensive, moderate and slight damage

Damage maps



Damage calculation performed by Openquake, based on Shakemaps produced at CRS.

Features:

- Multiple layers (ground motion, intensity, damage, casualties, population..)
- Different scales and granularity (municipality, census units)
- Archive of past events simulations