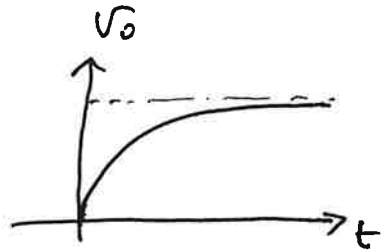
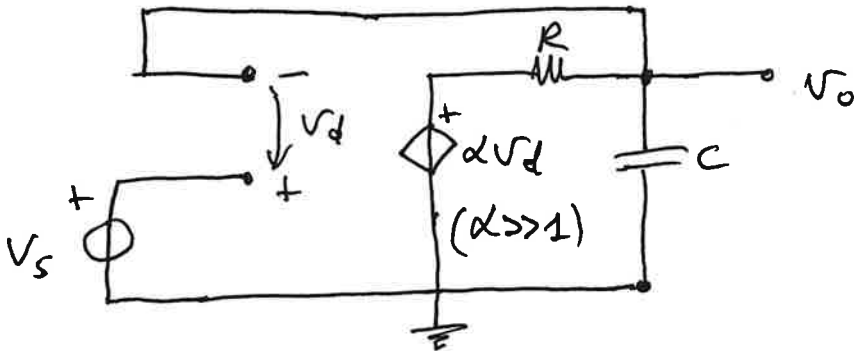
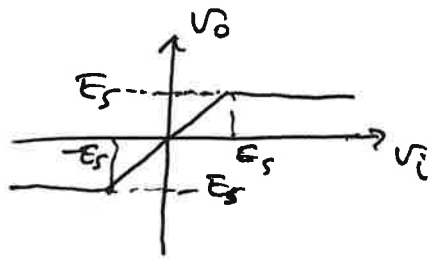
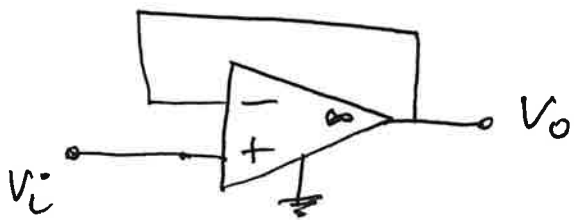
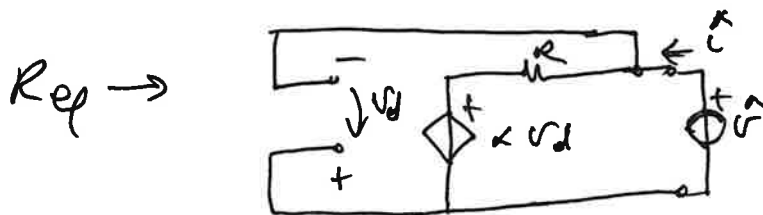


# INSEGUITORE DI TENSIONE



EQUIVALENTE DI THEVENIN AI MORSETTI DI C :



$$V_d = 0 - \hat{V} = -\hat{V}$$

$$\hat{V} = \alpha V_d + R \hat{I} = -\alpha \hat{V} + R \hat{I}$$

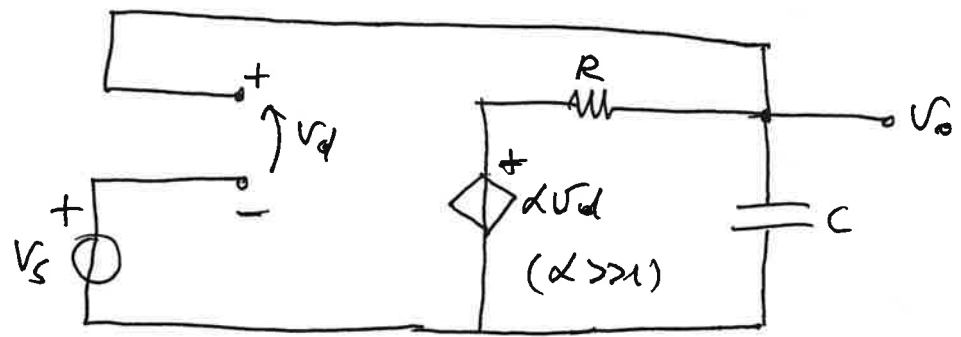
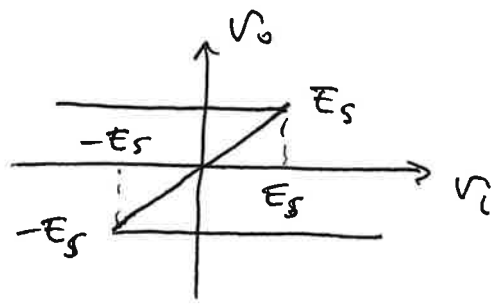
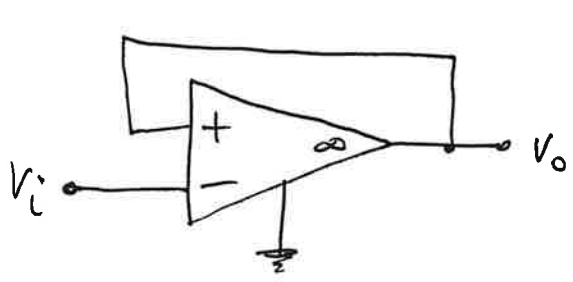
$$R_{eq} = \frac{\hat{V}}{\hat{I}} = \frac{R}{\alpha + 1} \approx \frac{R}{\alpha}$$

$$V_{eq} \rightarrow \begin{aligned} V_{eq} &= \alpha V_d \\ V_d &= V_s - \alpha V_d \end{aligned} \Rightarrow V_d(\alpha + 1) = V_s$$

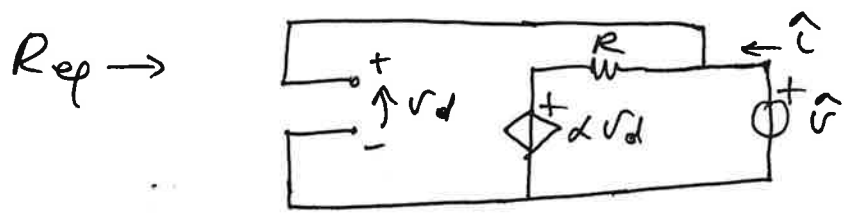
$$V_{eq} = \alpha V_d = \frac{\alpha}{\alpha + 1} V_s \approx V_s$$

CIRCUITO STABILE

# INSEGUITORE DI TENSIONE SBALZIATO



EQUIVALENTE DI THEVENIN AL MORSETTI DI C :



$$V_d = \hat{V}$$

$$\hat{V} = \alpha V_d + R \hat{i} = \alpha \hat{V} + R \hat{i}$$

$$R_{eq} = \frac{\hat{V}}{\hat{i}} = \frac{R}{1-\alpha} \approx -\frac{R}{\alpha} < 0$$

$$V_{eq} \rightarrow V_{eq} = \alpha V_d$$

$$V_d = \alpha V_d - V_s$$

$$\Rightarrow V_d (\alpha - 1) = V_s$$

$$V_{eq} = \alpha V_d = \frac{\alpha}{\alpha - 1} V_s$$

$$\approx V_s$$

CIRCUITO INSTABILE