

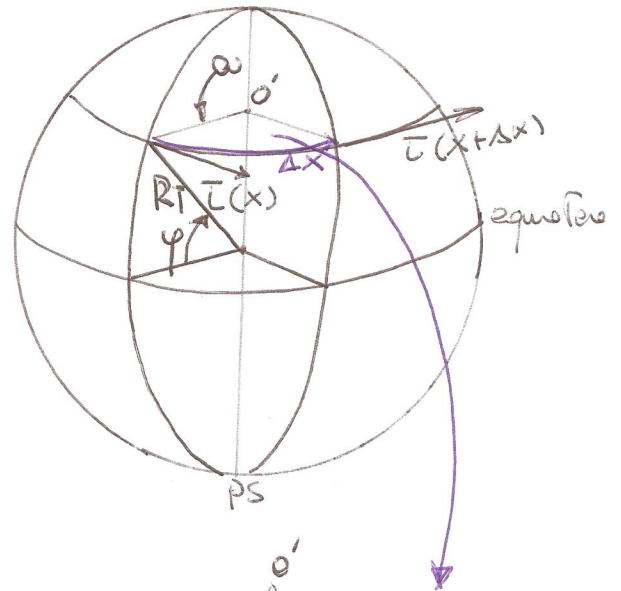
Analisi della variazione del versore \vec{L}

$$\frac{d\vec{L}}{dt} = \frac{\partial \vec{L}}{\partial t} + u \frac{\partial \vec{L}}{\partial x} + v \frac{\partial \vec{L}}{\partial y} + w \frac{\partial \vec{L}}{\partial z}$$

↑
nulla in quanto $\vec{L}(x, y, t)$ ma non dipende da t

(rispettivamente)

$$\frac{\partial \vec{L}}{\partial x} = \lim_{\Delta x \rightarrow 0} \frac{\vec{L}(x+\Delta x) - \vec{L}(x)}{\Delta x}$$



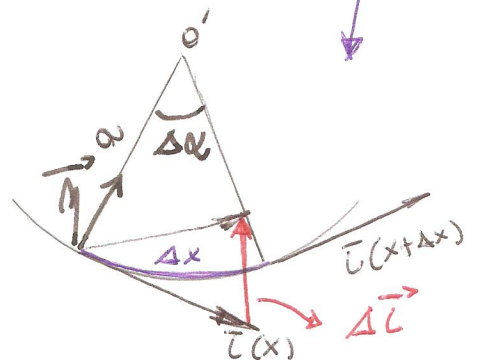
Ricordando che $|\vec{L}| = 1$ (versore)

$$|\Delta \vec{L}| = |\vec{L}(x+\Delta x) - \vec{L}(x)| = 1 \cdot \Delta \alpha$$

$$\Delta \alpha = \frac{\Delta x}{a}$$

$$\cos \alpha = (R_T + z) \cos \varphi \approx R_T \cos \varphi$$

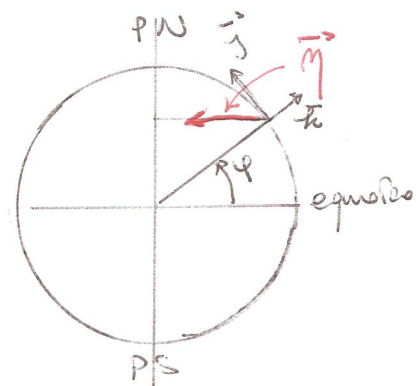
$$\text{Da cui } |\Delta \vec{L}| = \frac{\Delta x}{R_T \cos \varphi}$$



Quindi:

$$\begin{aligned} \frac{\partial \vec{L}}{\partial x} &= \lim_{\Delta x \rightarrow 0} \frac{\Delta x}{R_T \cos \varphi} \frac{1}{\Delta x} \vec{\eta} \\ &= \frac{1}{R_T \cos \varphi} (-\cos \varphi \vec{k} + \sin \varphi \vec{j}) \\ &= \frac{1}{R_T} \tan \varphi \vec{j} - \frac{1}{R_T} \vec{k} \end{aligned}$$

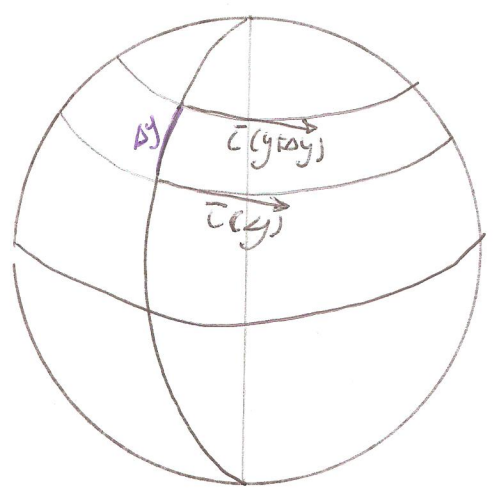
con $\vec{\eta}$ versore



Osservando che $\vec{\eta} = 0 \vec{i} + \sin \varphi \vec{j} - \cos \varphi \vec{k}$

$$\frac{\partial \vec{u}}{\partial y} = \lim_{\Delta y \rightarrow 0} \frac{\vec{u}(y+\Delta y) - \vec{u}(y)}{\Delta y}$$

Osservando che $\vec{u}(y+\Delta y)$ e $\vec{u}(y)$ sono vettori paralleli (identici)

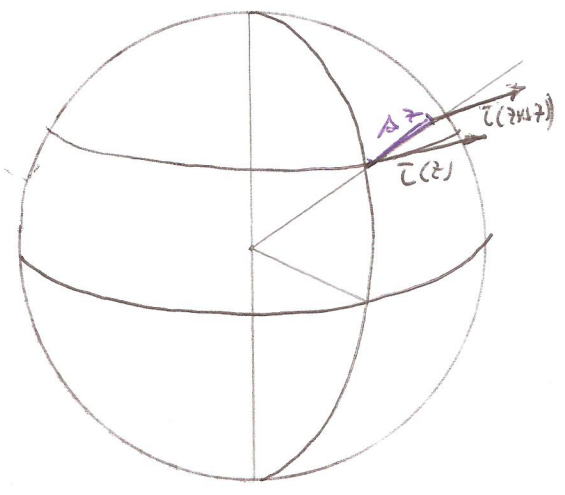


da cui $\Delta \vec{u} = \vec{u}(y+\Delta y) - \vec{u}(y) = 0$

Quindi: $\frac{\partial \vec{u}}{\partial y} = 0$

$$\frac{\partial \vec{u}}{\partial z} = \lim_{\Delta z \rightarrow 0} \frac{\vec{u}(z+\Delta z) - \vec{u}(z)}{\Delta z}$$

Osservando che: $\vec{u}(z+\Delta z)$ e $\vec{u}(z)$ sono due vettori paralleli (identici)



da cui $\Delta \vec{u} = \vec{u}(z+\Delta z) - \vec{u}(z) = 0$

Quindi: $\frac{\partial \vec{u}}{\partial z} = 0$

Sommando tutti gli addendi dello $\frac{d\vec{u}}{dt}$ si ottiene

$$\frac{d\vec{u}}{dt} = 0 + \mu \frac{1}{R_T} \tan \varphi \vec{j} - \mu \frac{1}{R_T} \vec{k} + 0 + 0$$

Quindi: $\frac{d\vec{u}}{dt} = \frac{\mu}{R_T} \tan \varphi \vec{j} - \frac{\mu}{R_T} \vec{k}$

Osservando che la variazione di \vec{u} da due contributi su assi diversi da \vec{u}