



Graphs

Chapter 22 of Cormen's book

Giulia Bernardini

giulia.bernardini@units.it

Algorithmic Design and Algorithms for Scientific

Computing

a.y. 2023/2024

BFS: Pseudocode



BFS(G, s) - G is represented by the adjacency lists $Adj[\cdot]$ of its vertices

for each $u \in V \setminus \{s\}$

$u.color \leftarrow \text{white};$

$u.distance \leftarrow \infty;$

$s.color \leftarrow \text{gray};$

$s.distance \leftarrow 0;$

$Q \leftarrow \emptyset;$

enqueue(Q, s);

while $Q \neq \emptyset$

$u \leftarrow \text{dequeue}(Q);$

for each $v \in Adj[u]$

if $v.color = \text{white}$

$v.color \leftarrow \text{gray};$

$v.distance \leftarrow u.distance + 1;$

enqueue(Q, v);

$u.color \leftarrow \text{black};$

Initialisation

Visit of the source

Visit of the other vertices

BFS: Complexity



BFS(G, s) - G is represented by the adjacency lists $Adj[\cdot]$ of its vertices

for each $u \in V \setminus \{s\}$

$u.color \leftarrow \text{white};$

$u.distance \leftarrow \infty;$

$s.color \leftarrow \text{gray};$

$s.distance \leftarrow 0;$

$Q \leftarrow \emptyset;$

enqueue(Q, s);

while $Q \neq \emptyset$

$u \leftarrow \text{dequeue}(Q);$

for each $v \in Adj[u]$

$O(1)$ **if** $v.color = \text{white}$

$v.color \leftarrow \text{gray};$

$v.distance \leftarrow u.distance + 1;$

enqueue(Q, v);

$u.color \leftarrow \text{black};$

Initialisation: $O(|V|)$

Visit of the source: $O(1)$

Visit of the other vertices:
each iteration of the **for** loop
enqueues $v \in Adj[u]$ only if
it is white, and it
immediately turns its color
to gray \implies each vertex is
inserted in Q at most once.

Cost of the **while** loop:

$$O\left(\sum_{u \in V} |Adj[u]| \right) = O(|E|)$$

$O(|Adj[u]|)$

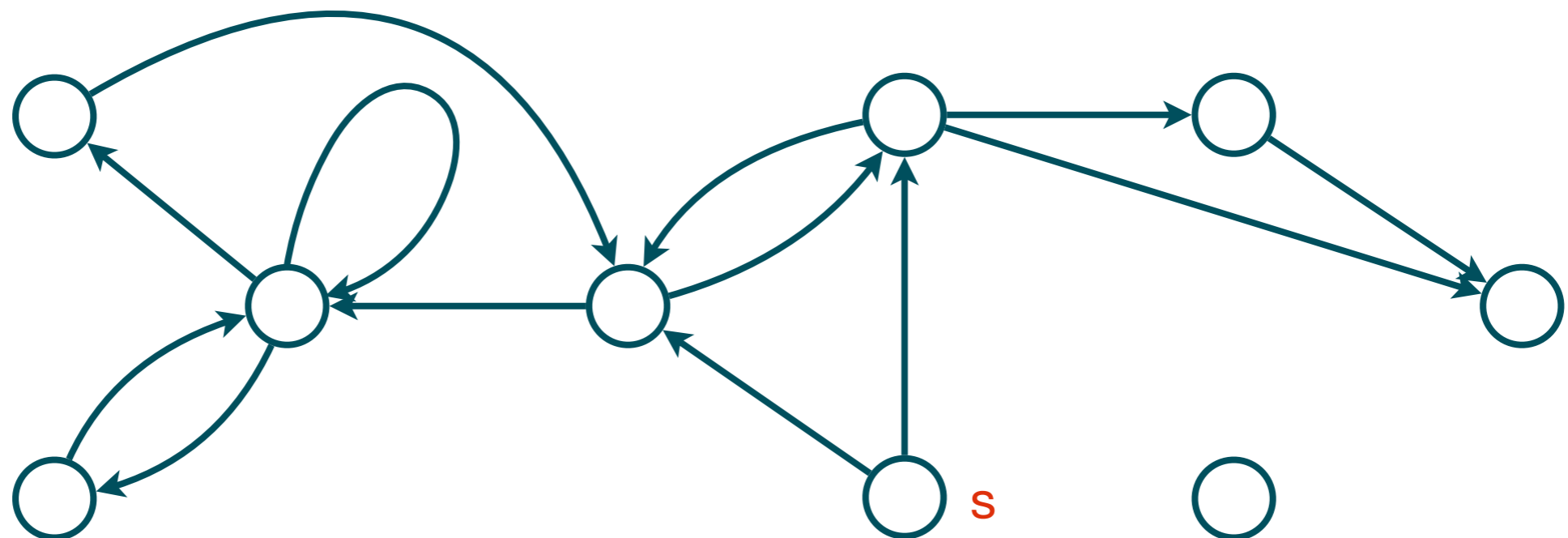
Breadth-First Search



The visiting order is related to the **distance from a source node**: the closer a node to the source, the sooner it will be visited

BFS produces a breadth-first tree: the tree consisting of the shortest paths from the source to any reachable node

White nodes have not been discovered yet;



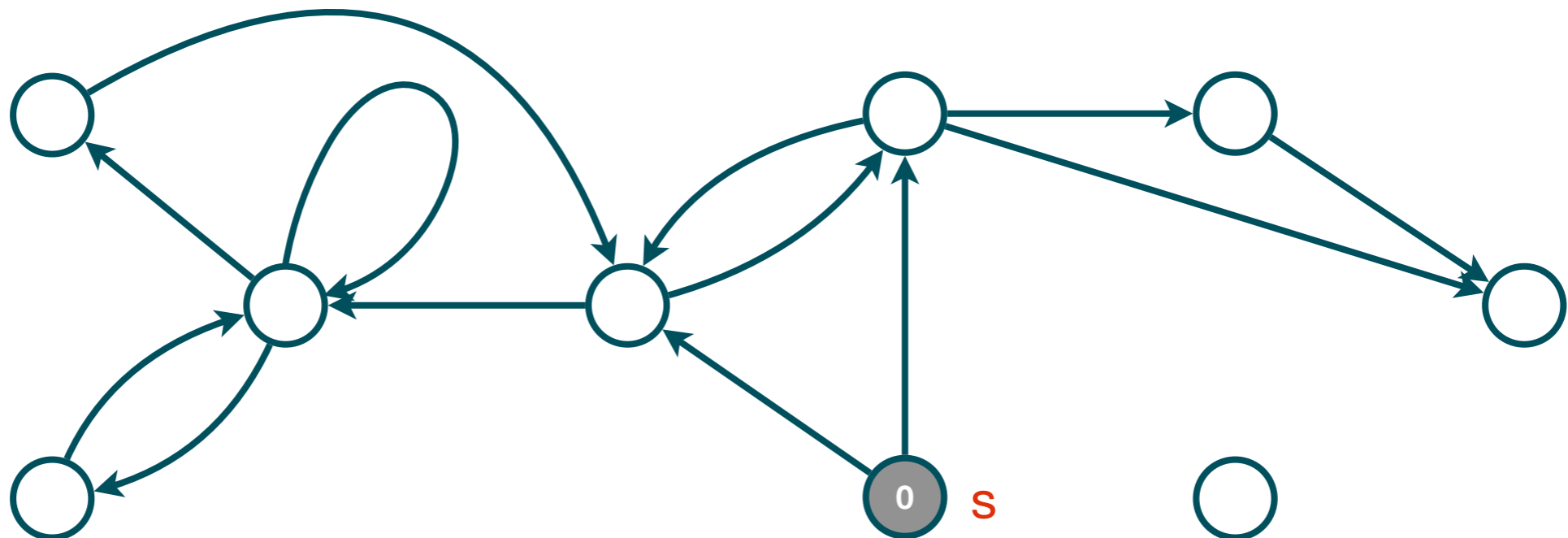
Breadth-First Search



The visiting order is related to the **distance from a source node**: the closer a node to the source, the sooner it will be visited

BFS produces a breadth-first tree: the tree consisting of the shortest paths from the source to any reachable node

White nodes have not been discovered yet; gray nodes have been discovered but have undiscovered neighbours;



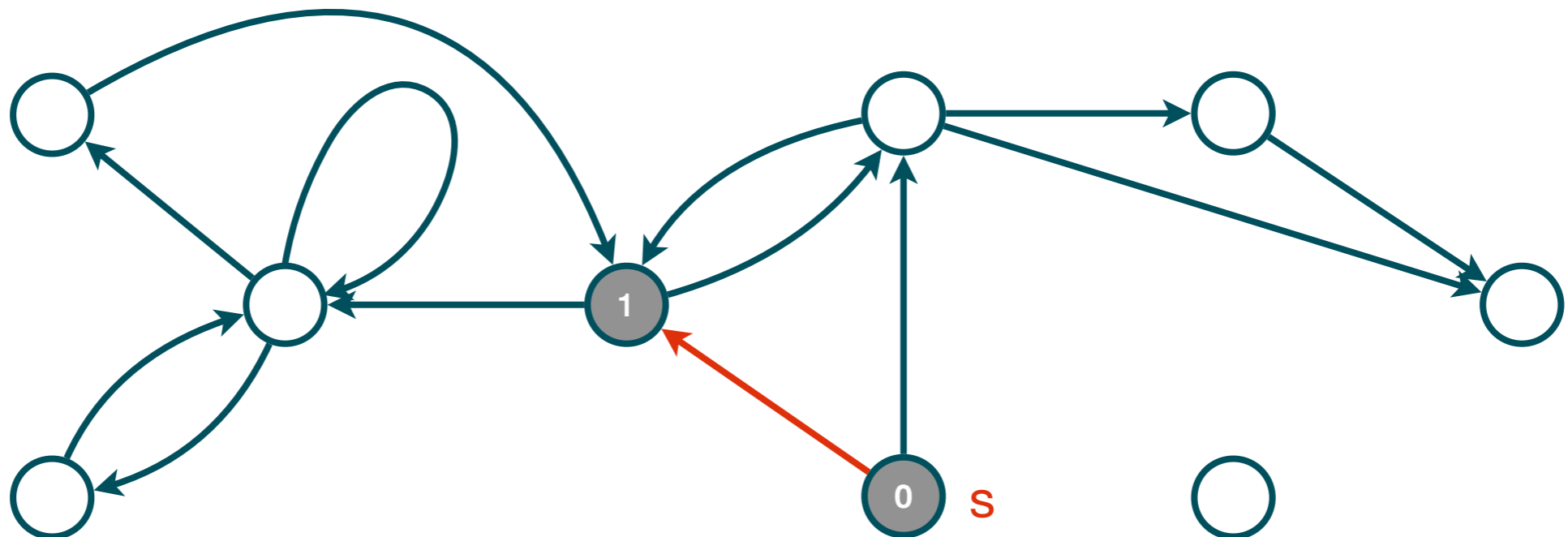
Breadth-First Search



The visiting order is related to the **distance from a source node**: the closer a node to the source, the sooner it will be visited

BFS produces a breadth-first tree: the tree consisting of the shortest paths from the source to any reachable node

White nodes have not been discovered yet; gray nodes have been discovered but have undiscovered neighbours;



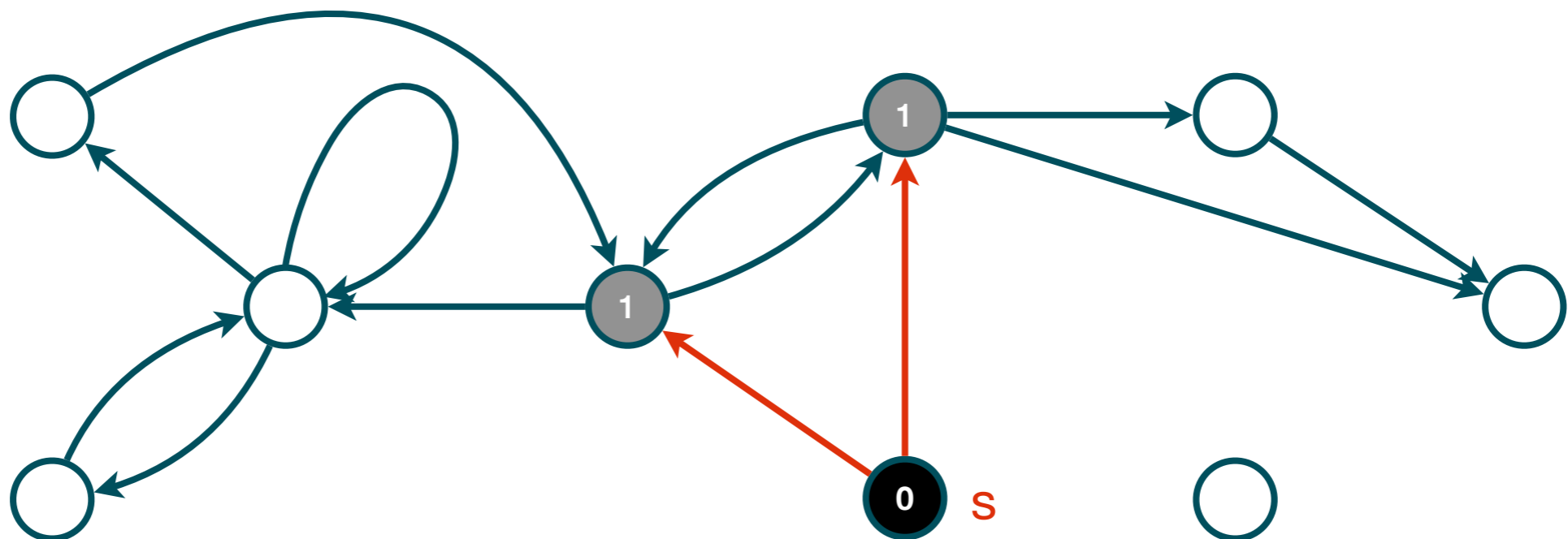
Breadth-First Search



The visiting order is related to the **distance from a source node**: the closer a node to the source, the sooner it will be visited

BFS produces a breadth-first tree: the tree consisting of the shortest paths from the source to any reachable node

White nodes have not been discovered yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.



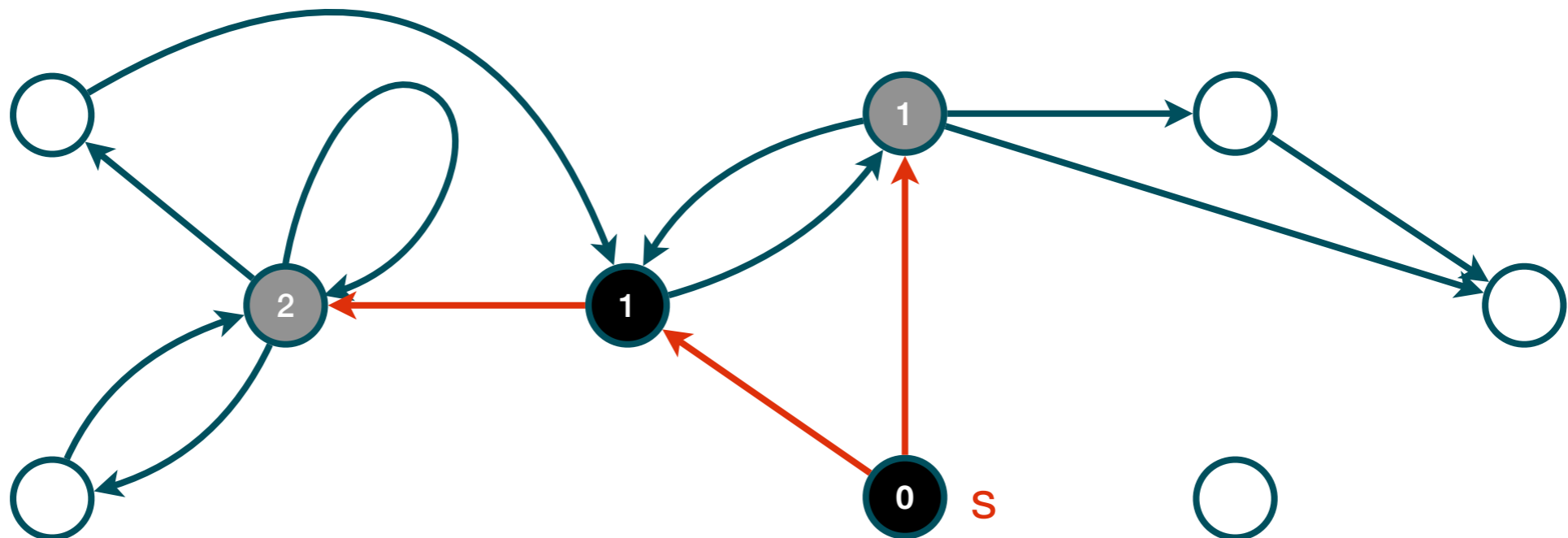
Breadth-First Search



The visiting order is related to the **distance from a source node**: the closer a node to the source, the sooner it will be visited

BFS produces a breadth-first tree: the tree consisting of the shortest paths from the source to any reachable node

White nodes have not been discovered yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.



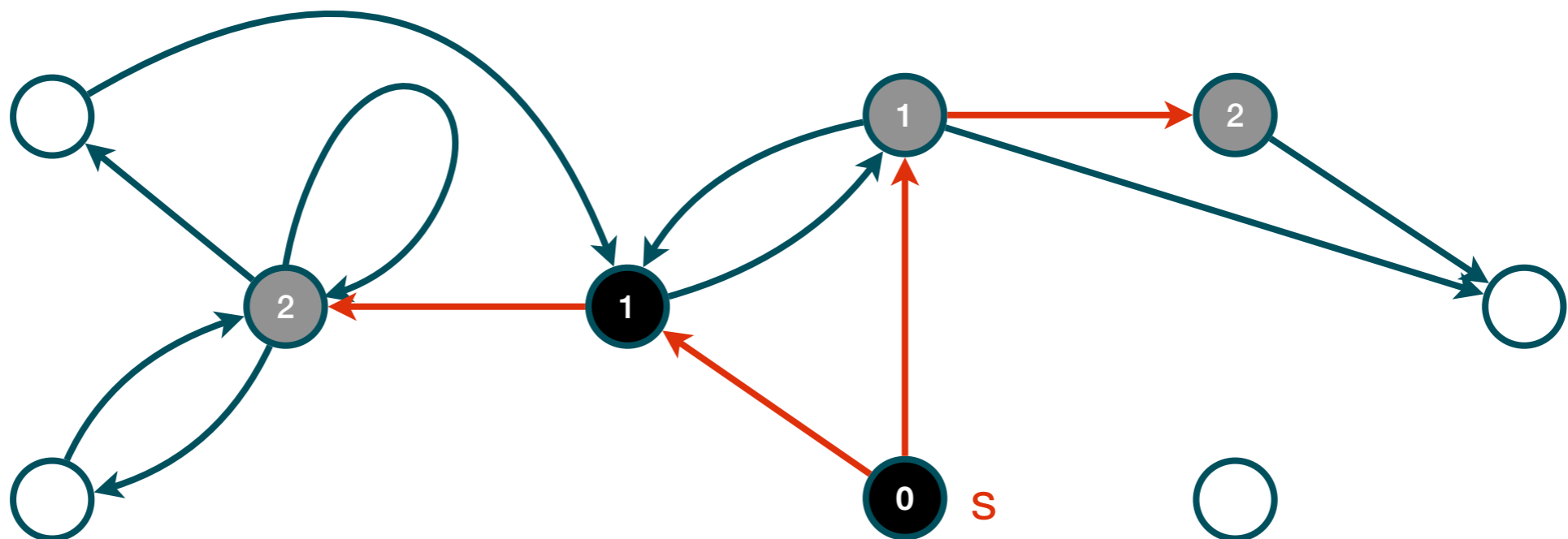
Breadth-First Search



The visiting order is related to the **distance from a source node**: the closer a node to the source, the sooner it will be visited

BFS produces a breadth-first tree: the tree consisting of the shortest paths from the source to any reachable node

White nodes have not been discovered yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.



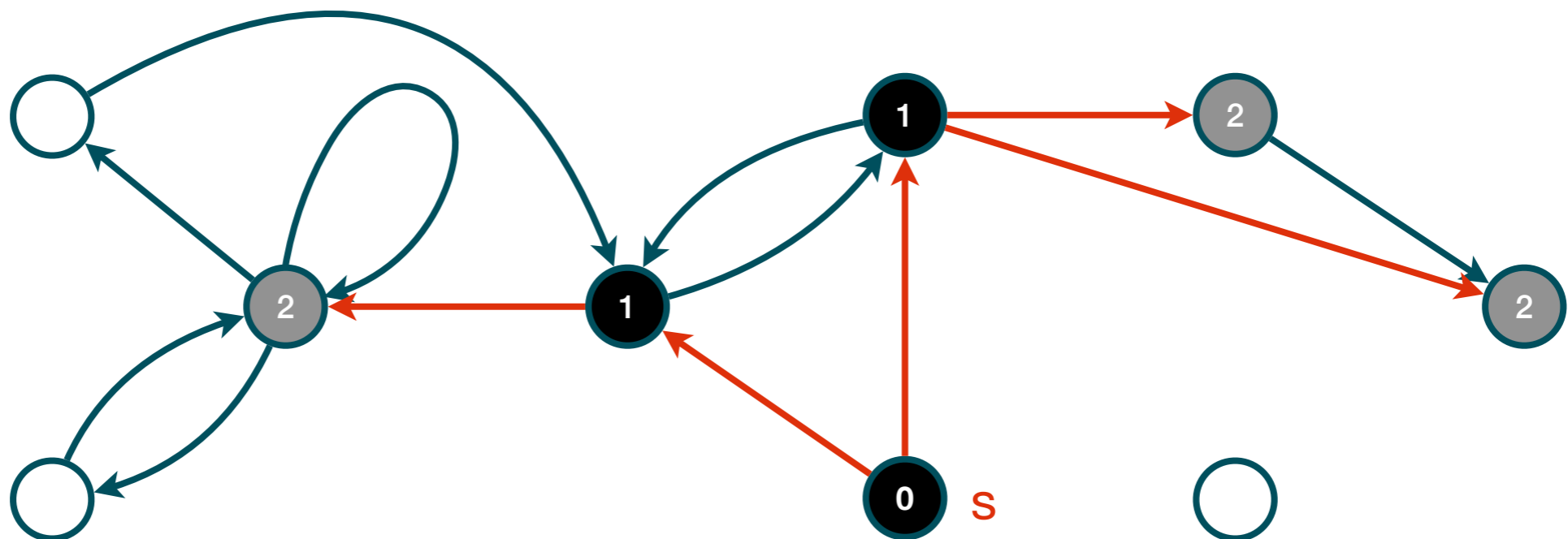
Breadth-First Search



The visiting order is related to the **distance from a source node**: the closer a node to the source, the sooner it will be visited

BFS produces a breadth-first tree: the tree consisting of the shortest paths from the source to any reachable node

White nodes have not been discovered yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.



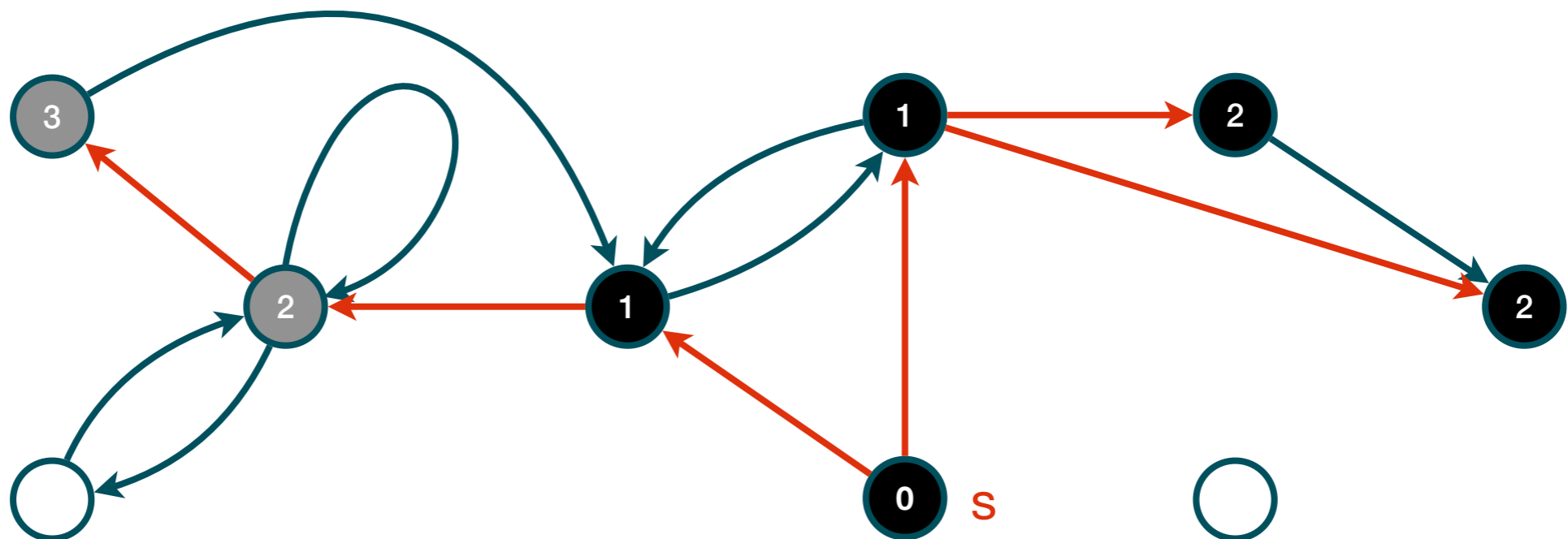
Breadth-First Search



The visiting order is related to the **distance from a source node**: the closer a node to the source, the sooner it will be visited

BFS produces a breadth-first tree: the tree consisting of the shortest paths from the source to any reachable node

White nodes have not been discovered yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.



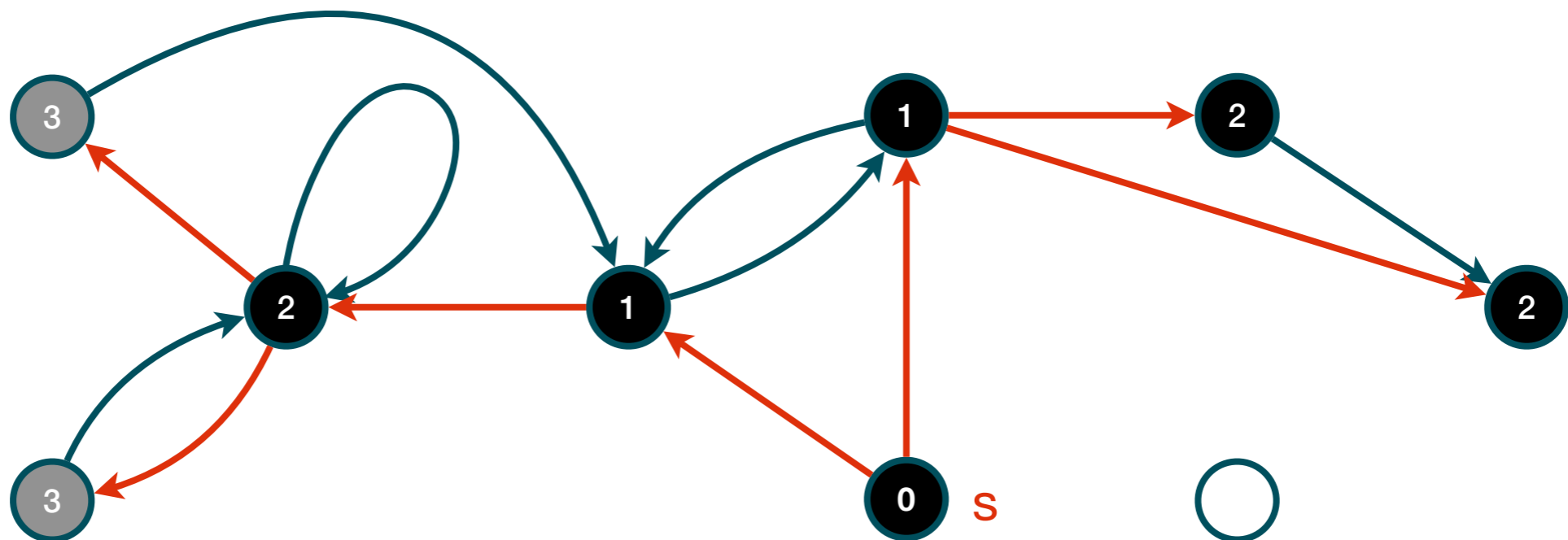
Breadth-First Search



The visiting order is related to the **distance from a source node**: the closer a node to the source, the sooner it will be visited

BFS produces a breadth-first tree: the tree consisting of the shortest paths from the source to any reachable node

White nodes have not been discovered yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.



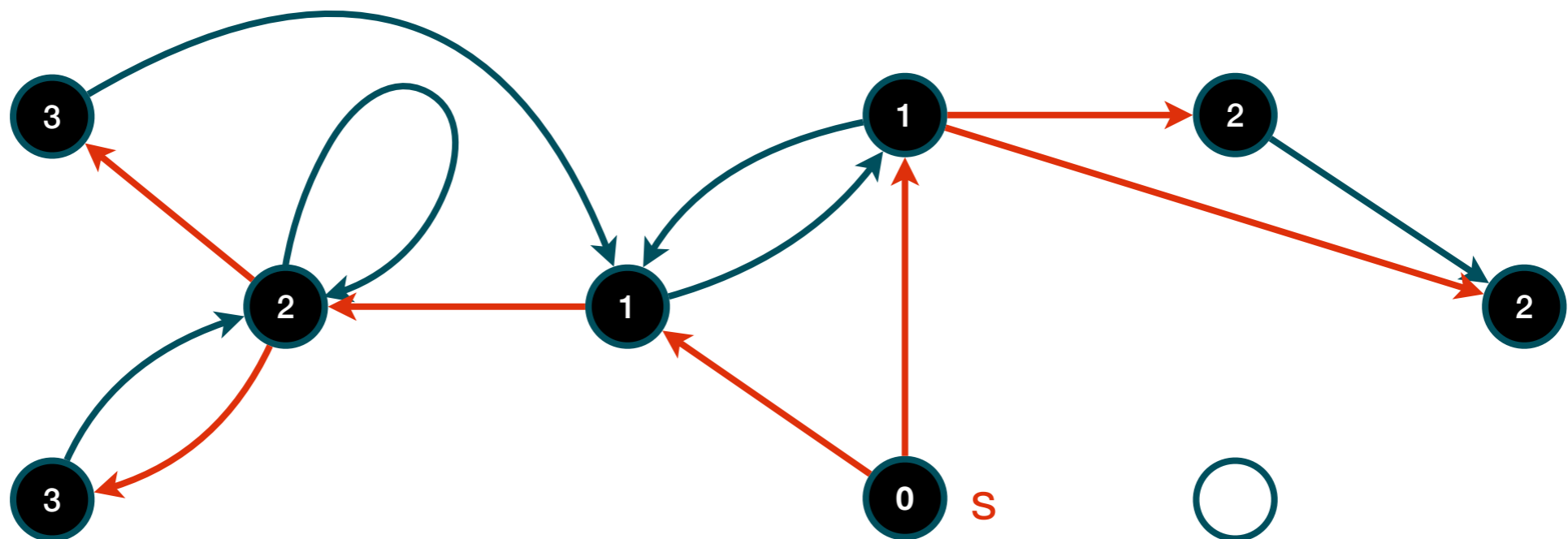
Breadth-First Search



The visiting order is related to the **distance from a source node**: the closer a node to the source, the sooner it will be visited

BFS produces a breadth-first tree: the tree consisting of the shortest paths from the source to any reachable node

White nodes have not been discovered yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.



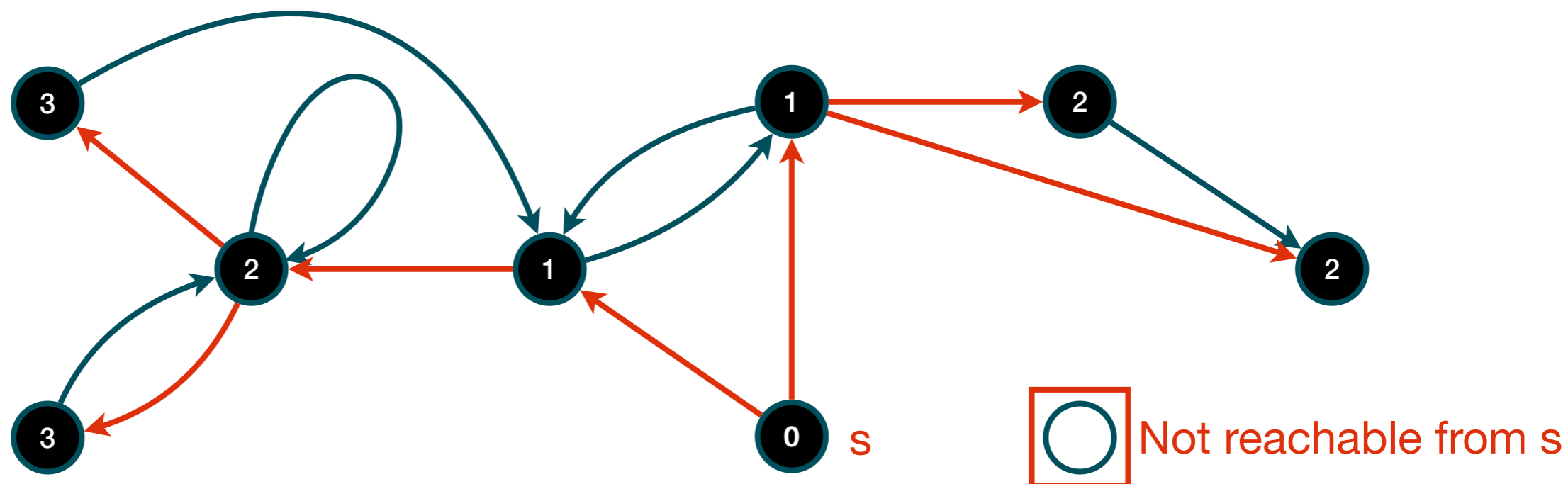
Breadth-First Search



The visiting order is related to the **distance from a source node**: the closer a node to the source, the sooner it will be visited

BFS produces a breadth-first tree: the tree consisting of the shortest paths from the source to any reachable node

White nodes have not been discovered yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.



BFS: Properties



Lemma 1. The time complexity of BFS is $O(|V|+|E|)$ (linear in the size of the adjacency-list representation of G)

Lemma 2. Let $Q=[v_1, \dots, v_n]$ be the queue at any iteration of BFS. Then $v_i.distance \leq v_{i+1}.distance$ and $v_n.distance \leq v_1.distance + 1$, for all $i=1, \dots, n-1$

Lemma 2 tells us that, at any iteration, if the head node of Q is at distance d from s , Q only contains nodes at distance d or $d+1$ from s ; possible nodes at distance $d+2$ will be only enqueued after all nodes at distance d have been dequeued.

Lemma 3. Let $d(v,s)$ be the distance between v and s , for any $v \in V$. Then:

(i) $v.distance \neq \infty \iff v$ is reachable from s

(ii) if $v.distance \neq \infty \implies v.distance = d(v,s)$

DFS: Pseudocode



DFS(G) - G is represented by the adjacency lists $Adj[\cdot]$ of its vertices

for each $u \in V$

$u.color \leftarrow \text{white};$

$t \leftarrow 0;$

for each $u \in V$

if $u.color = \text{white}$

DFS_visit(G, u)

DFS_visit(G, u)

$t \leftarrow t+1;$

$u.d \leftarrow t;$

$u.color \leftarrow \text{gray};$

for each $v \in Adj[u]$

if $v.color = \text{white}$

DFS_visit(G, v);

$u.color \leftarrow \text{black};$

$t \leftarrow t+1;$

$u.f \leftarrow t;$

Initialisation

Start the search from
a new source

Visit the graph recursively

DFS: Complexity



DFS(G) - G is represented by the adjacency lists $Adj[\cdot]$ of its vertices

```
for each  $u \in V$ 
     $u.color \leftarrow white$ ;
 $t \leftarrow 0$ ;
for each  $u \in V$ 
    if  $u.color = white$ 
        DFS_visit( $G, u$ )
```

Initialisation: $O(|V|)$

Start the search from a new source: this only happens when a vertex is white $\implies O(|V|)$ calls

```
DFS_visit( $G, u$ )
     $t \leftarrow t+1$ ;
     $u.d \leftarrow t$ ;
     $u.color \leftarrow gray$ ;
    for each  $v \in Adj[u]$ 
        if  $v.color = white$ 
            DFS_visit( $G, v$ );
     $u.color \leftarrow black$ ;
     $t \leftarrow t+1$ ;
     $u.f \leftarrow t$ ;
```

Visit the graph recursively: this procedure is only called on white vertices, which are immediately painted gray

$$\implies O\left(\sum_{u \in V} |Adj[u]| \right) = O(|E|)$$

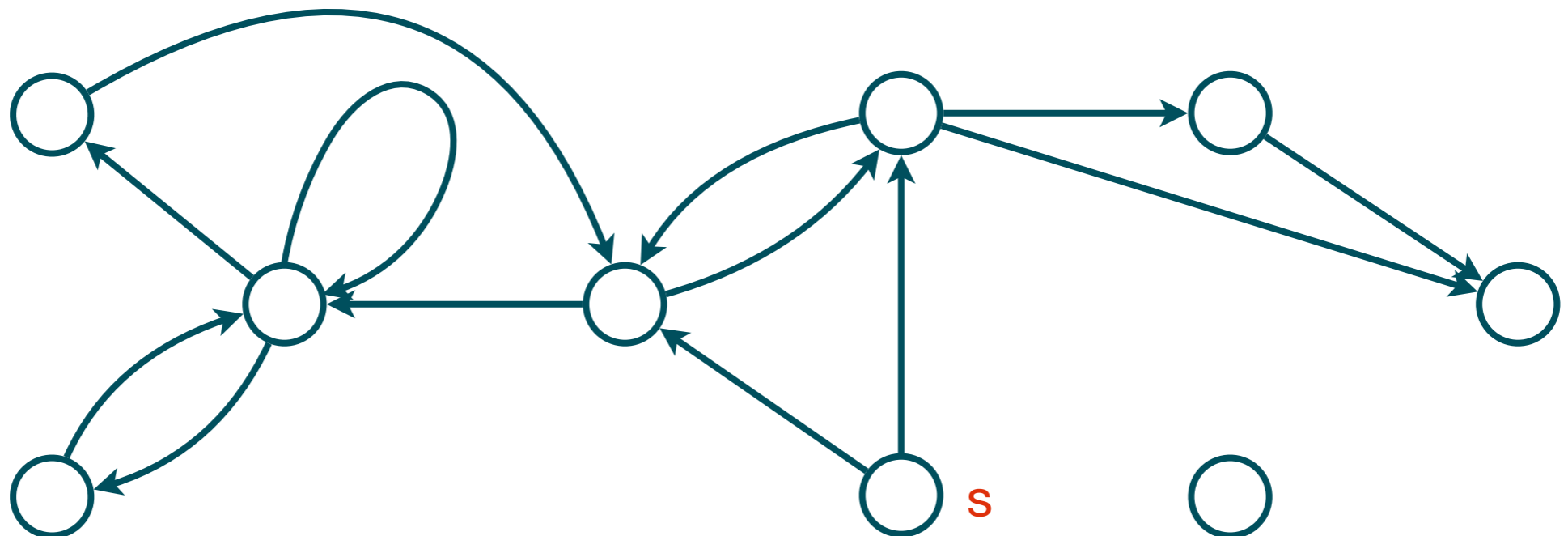
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



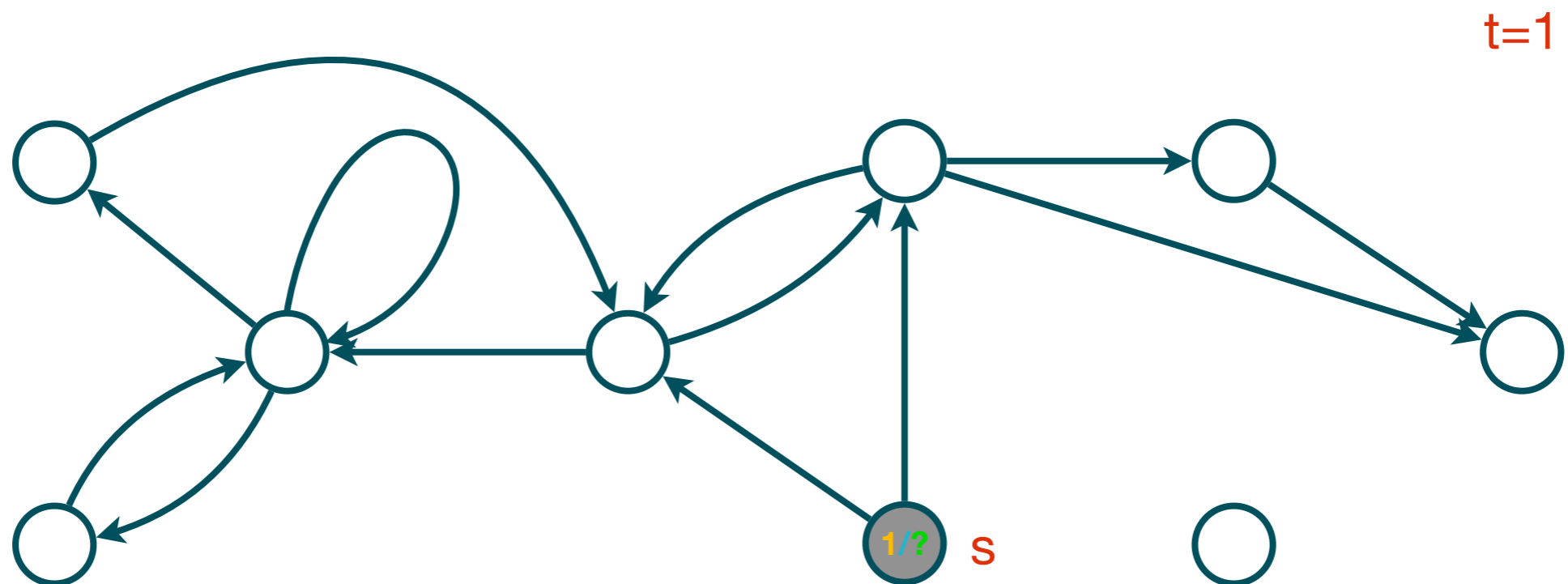
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



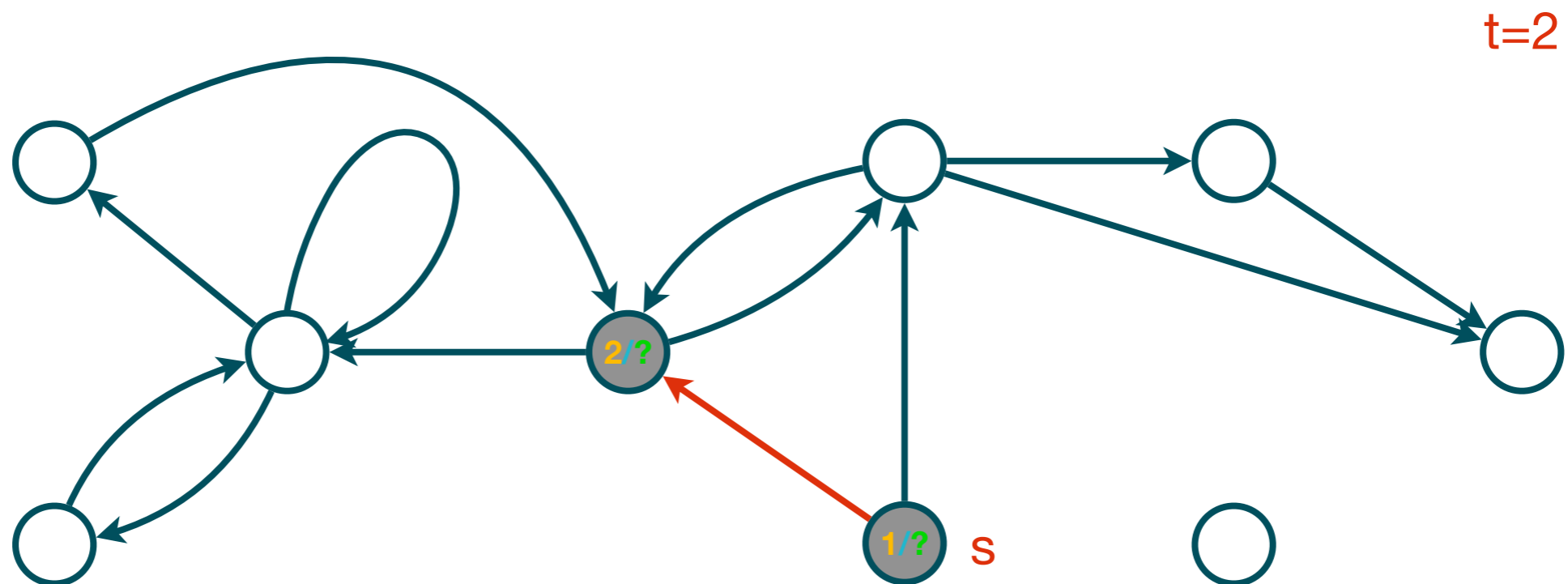
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



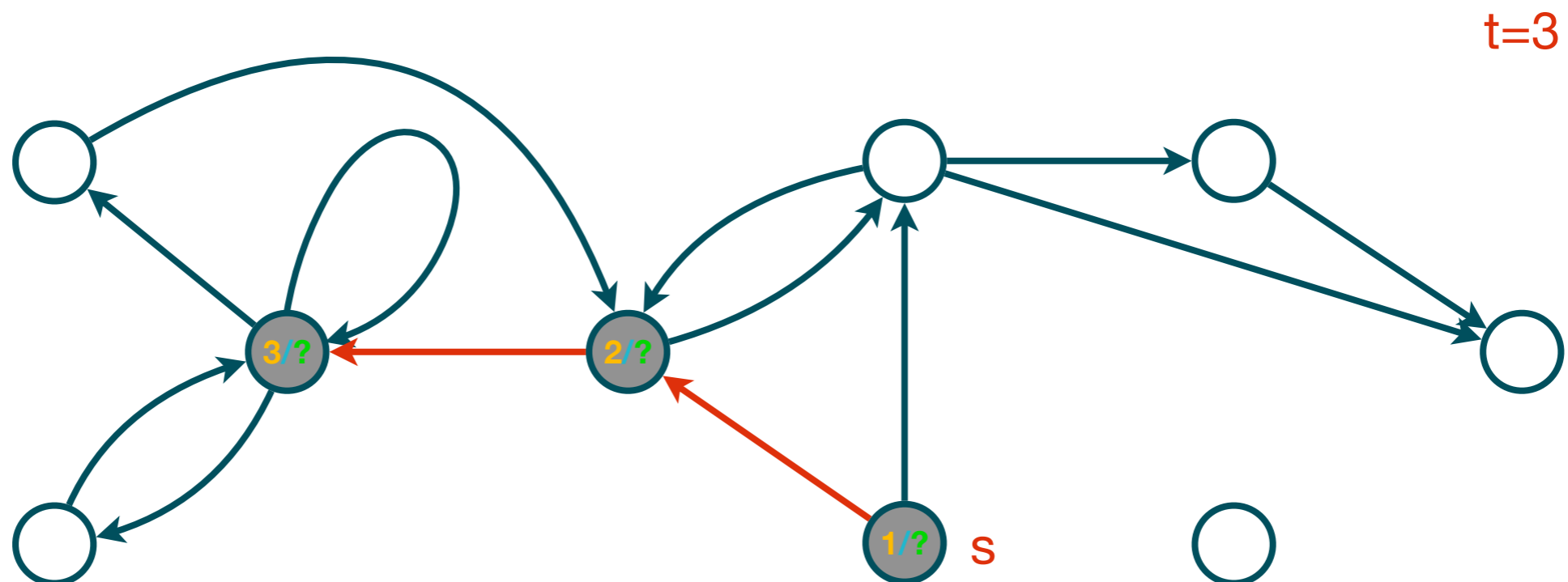
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



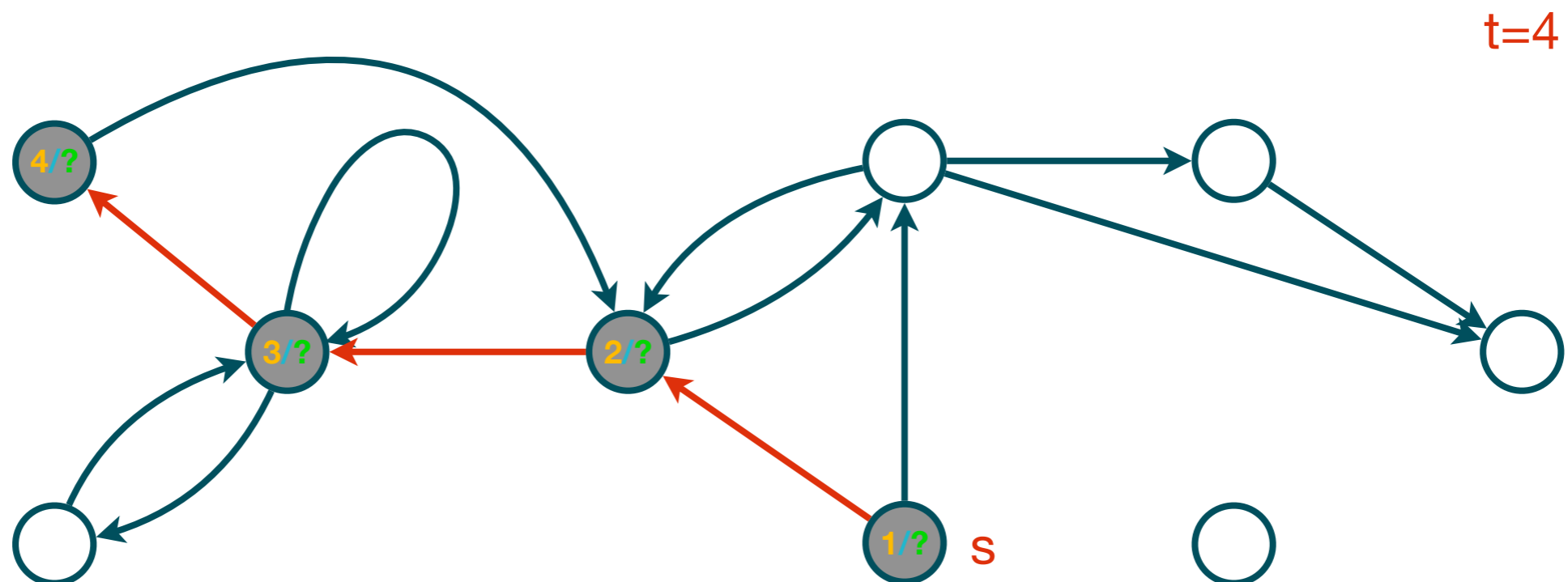
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



Depth-First Search



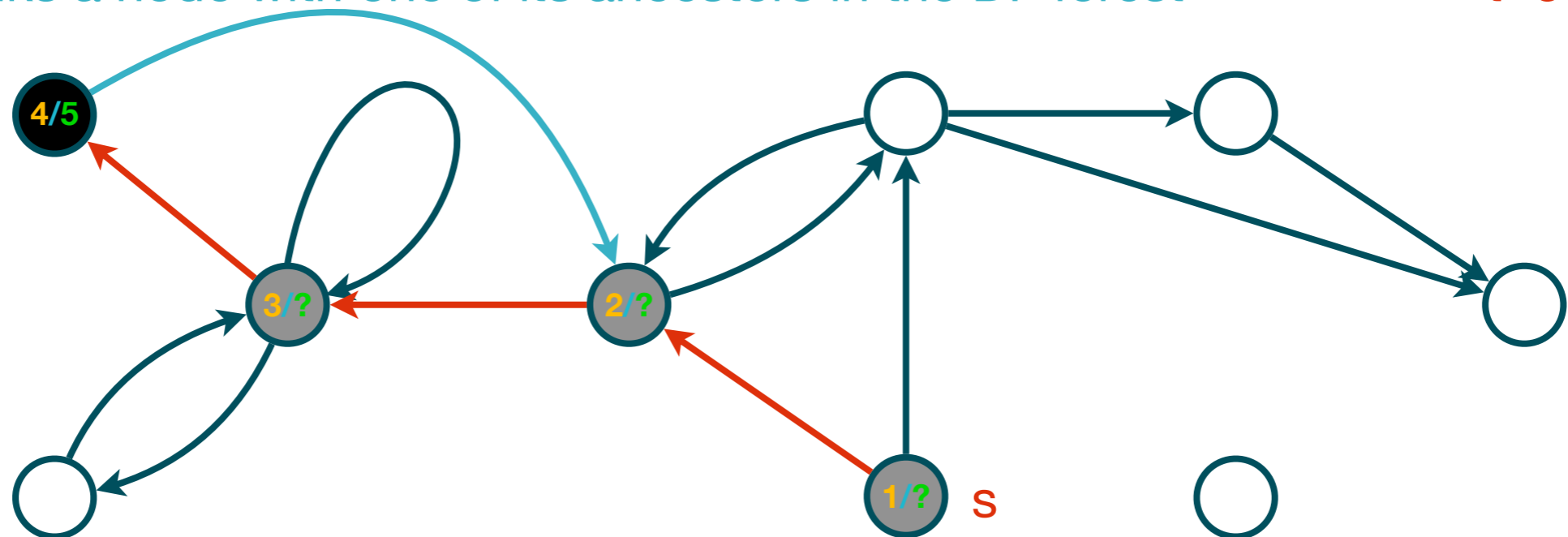
Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.

Back edge: links a node with one of its ancestors in the DF forest

$t=5$



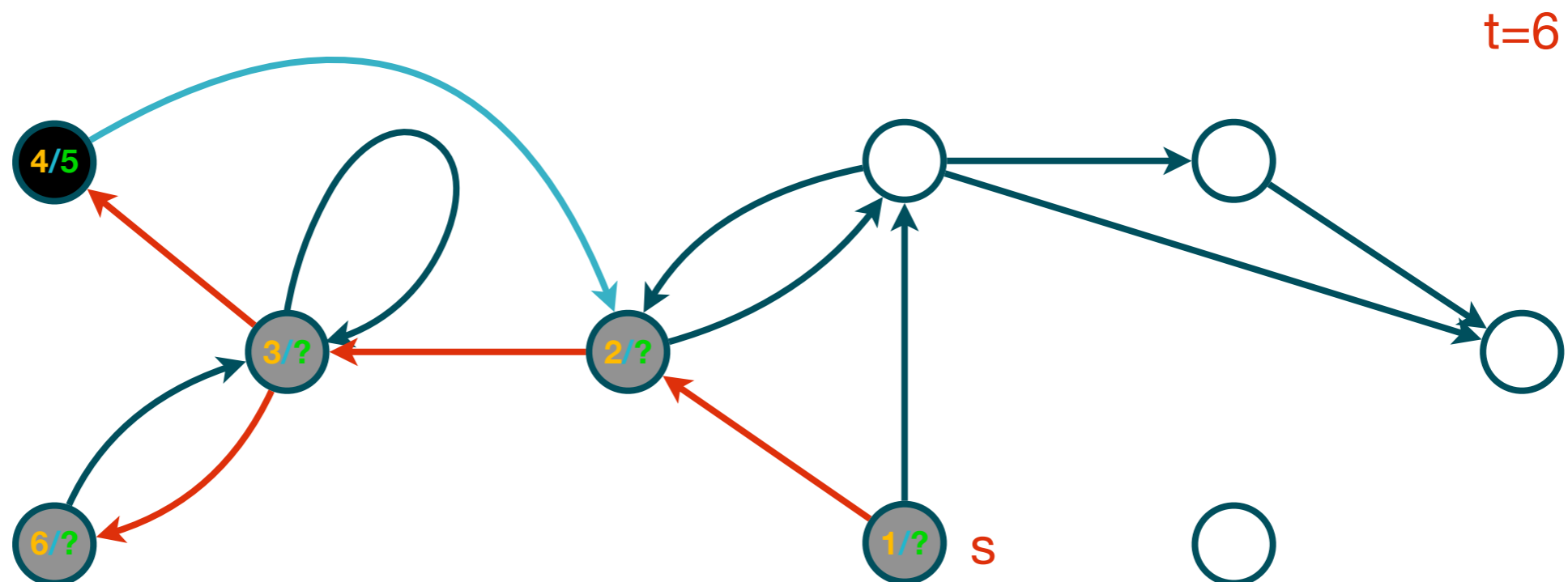
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



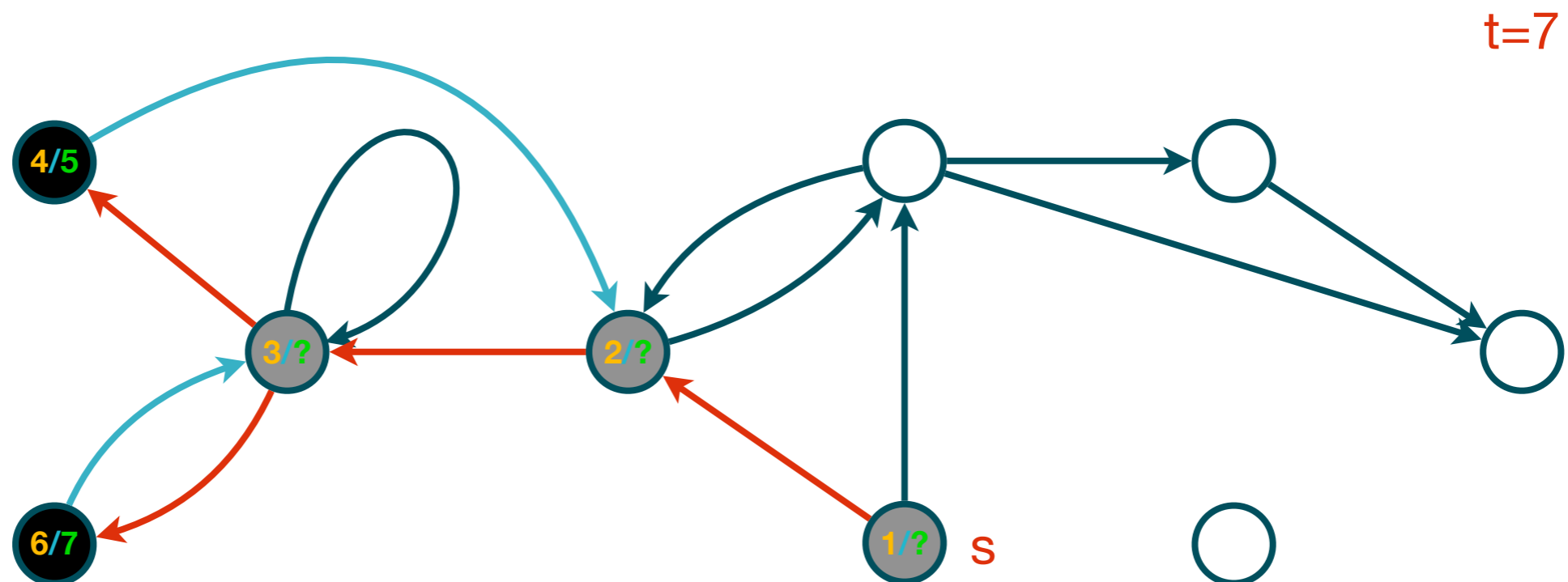
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



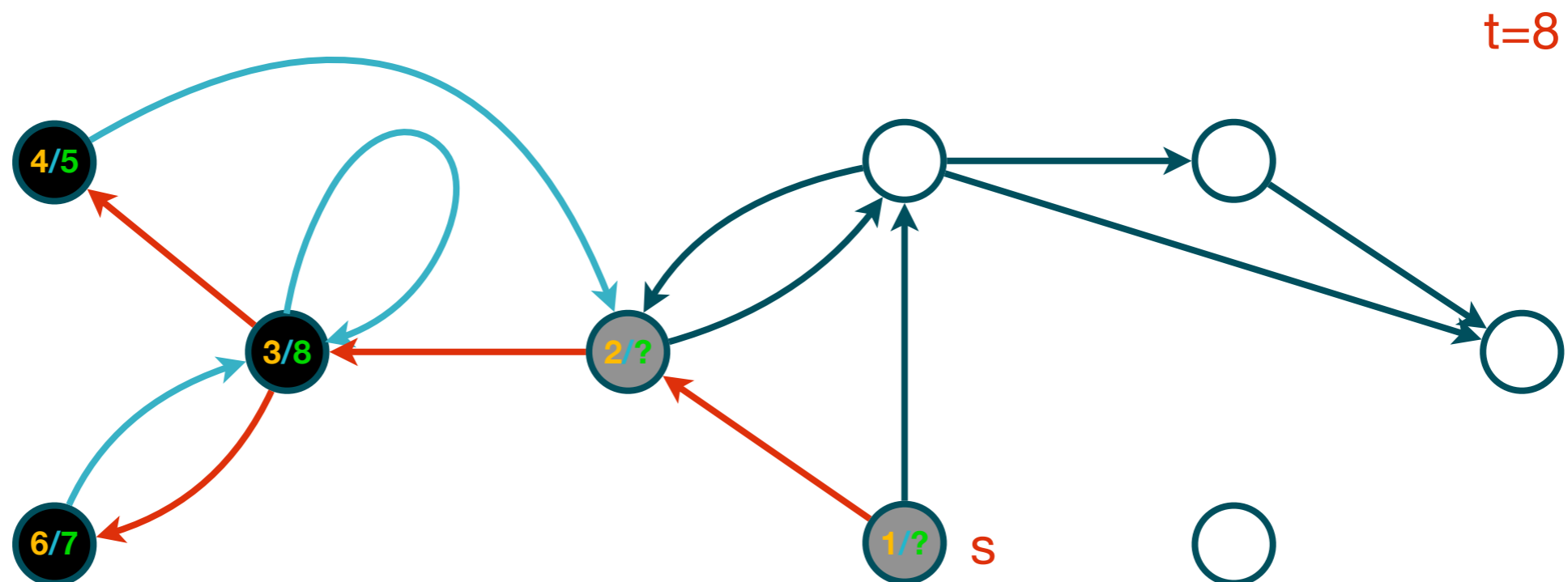
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



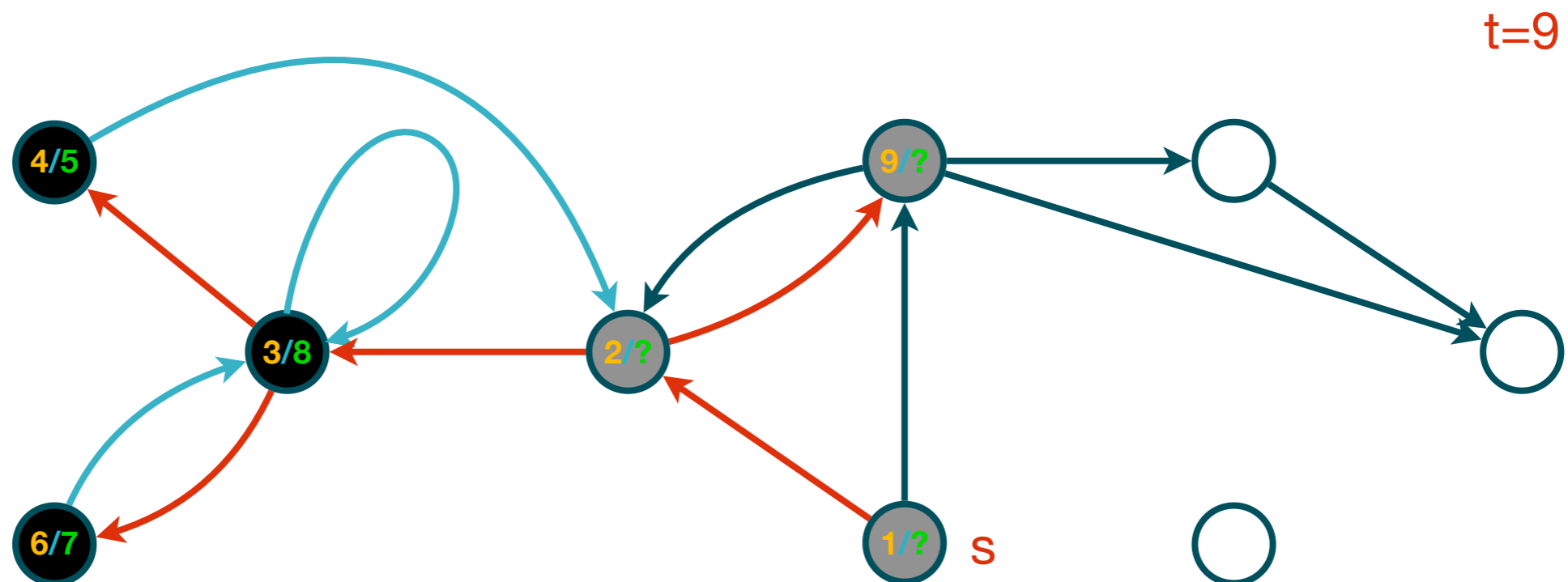
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



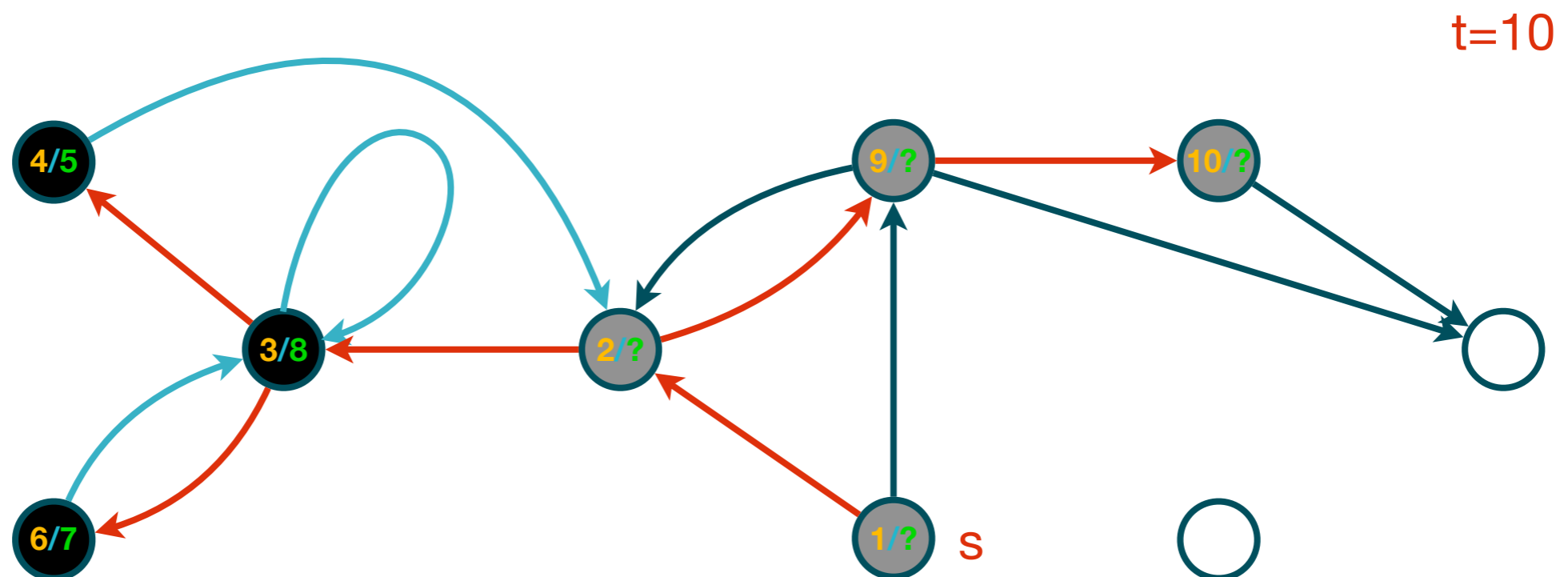
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



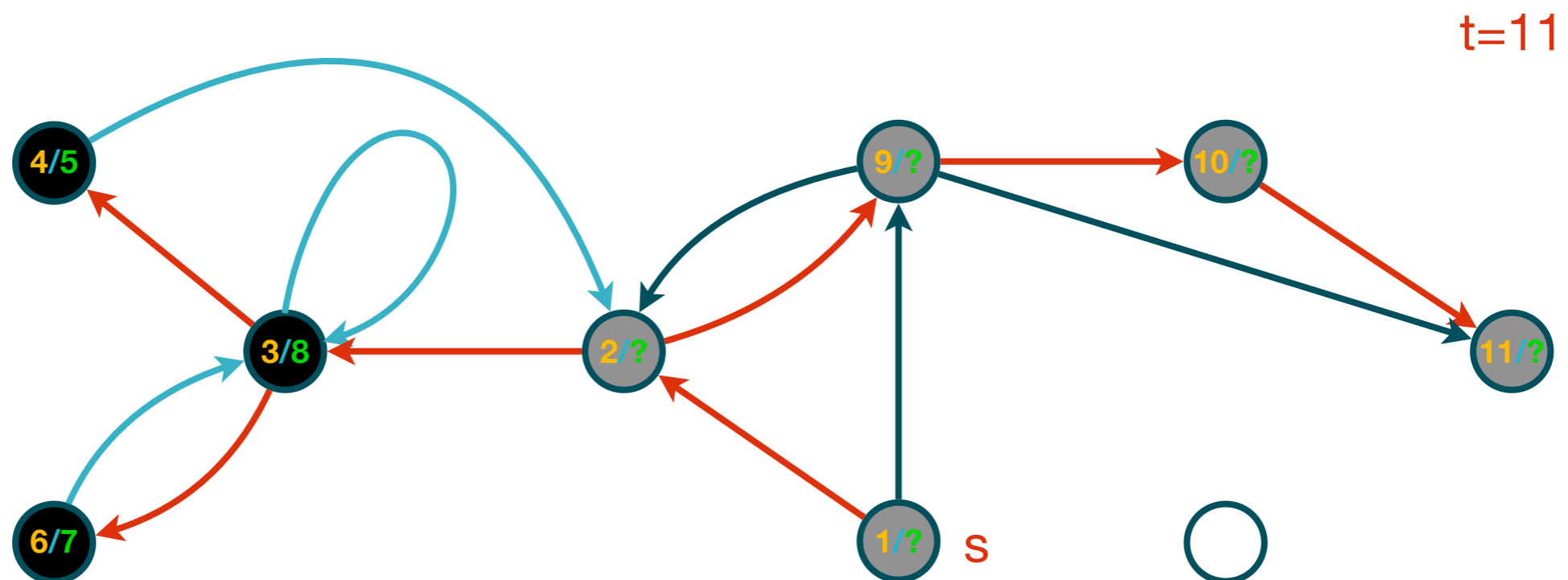
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



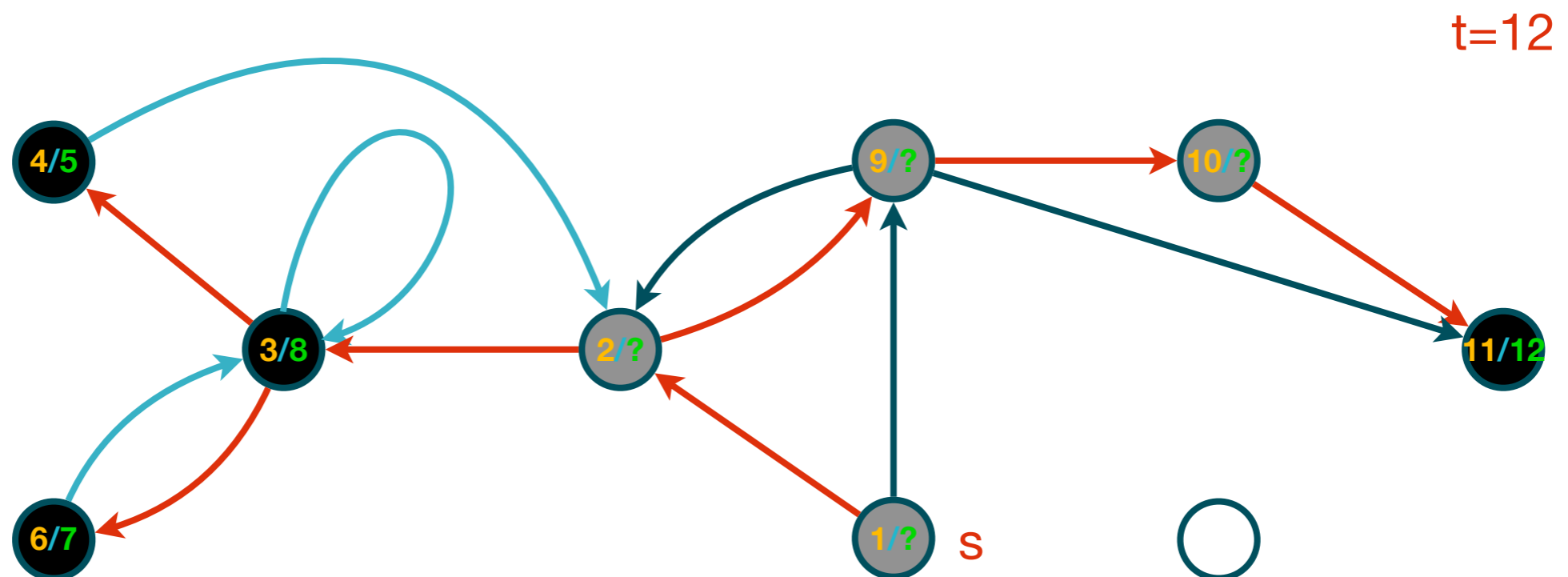
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



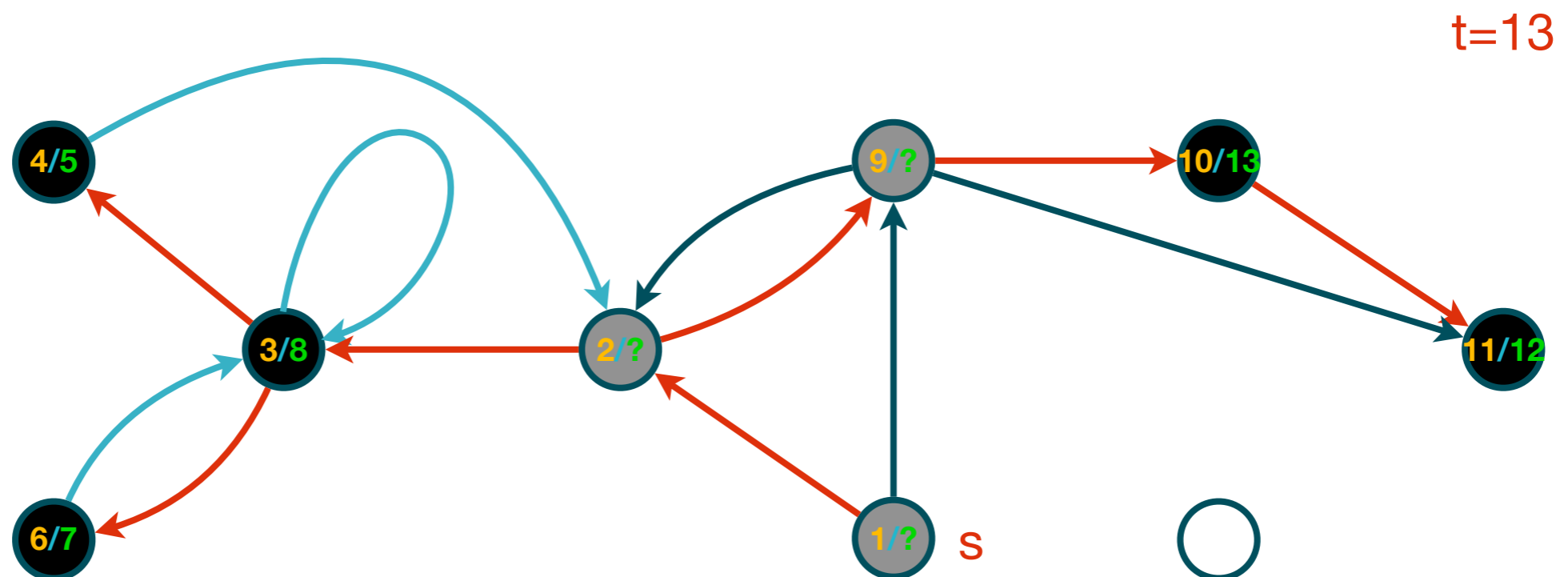
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



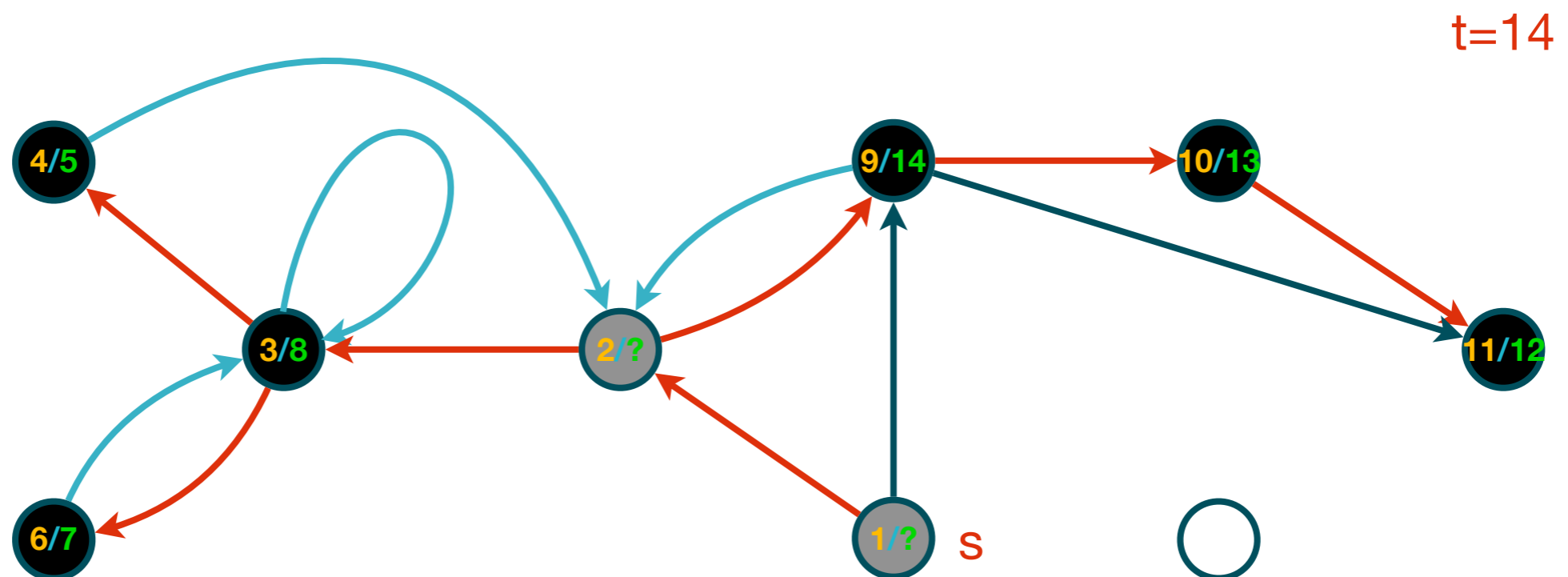
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



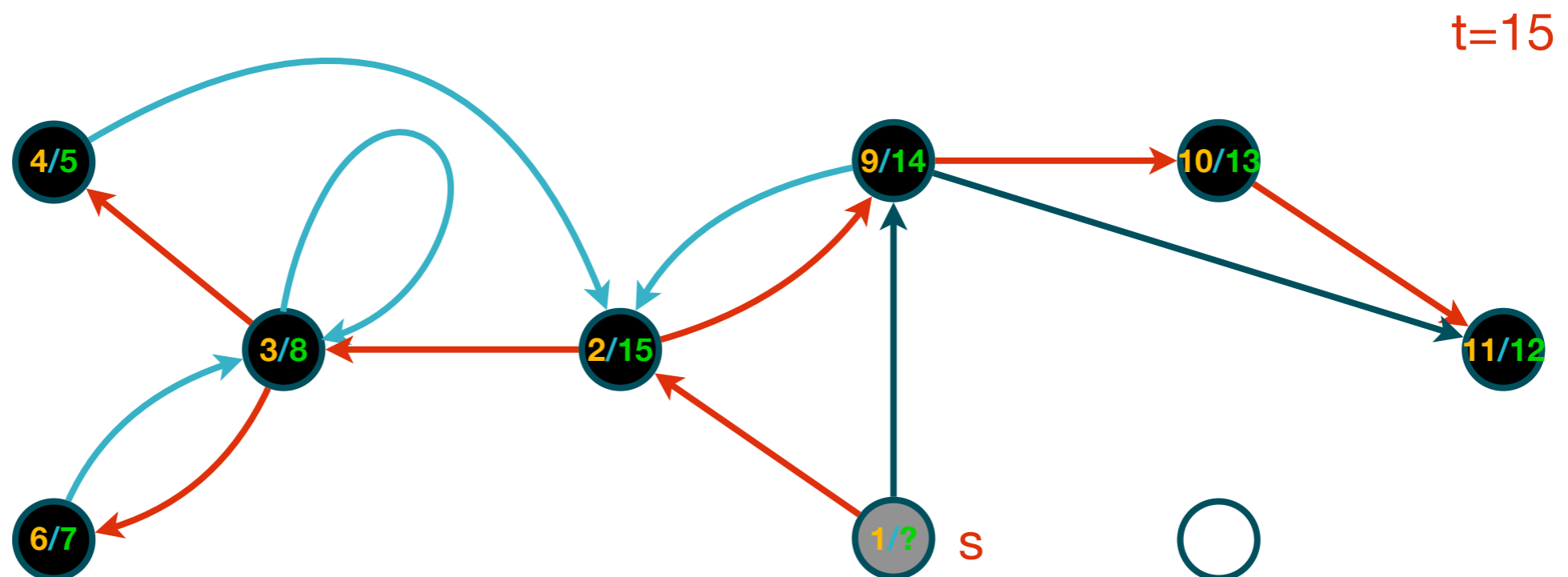
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



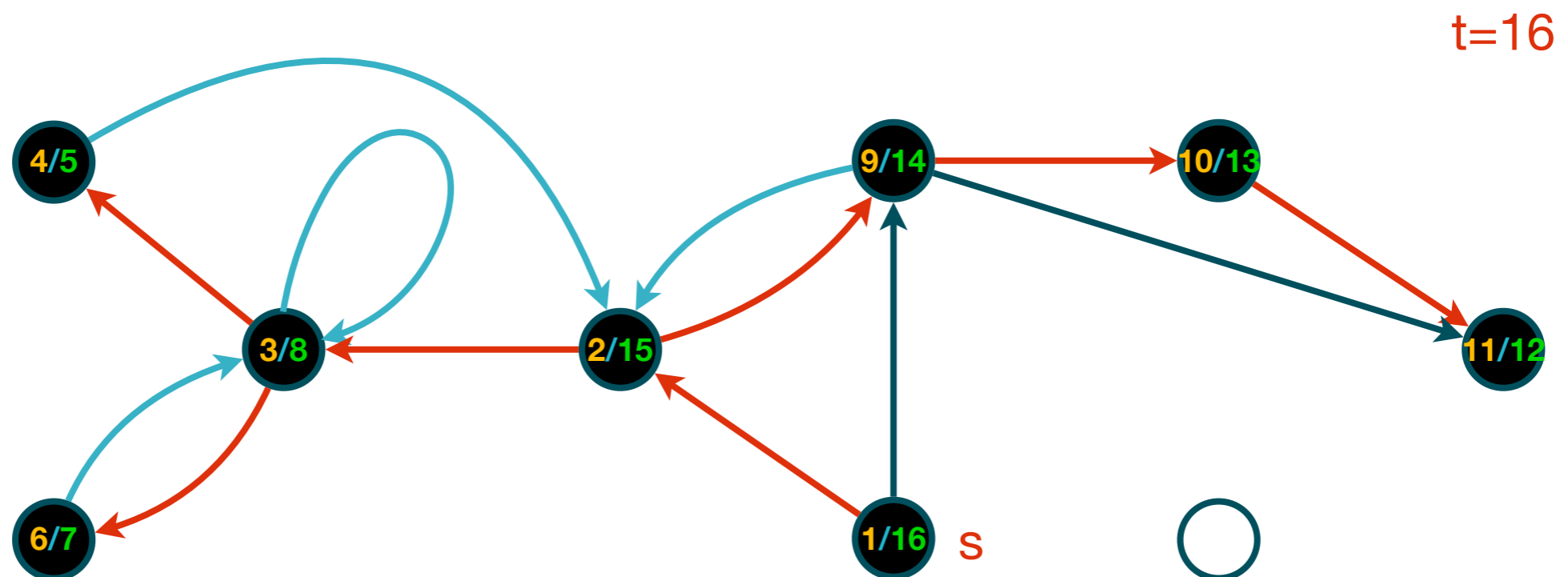
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



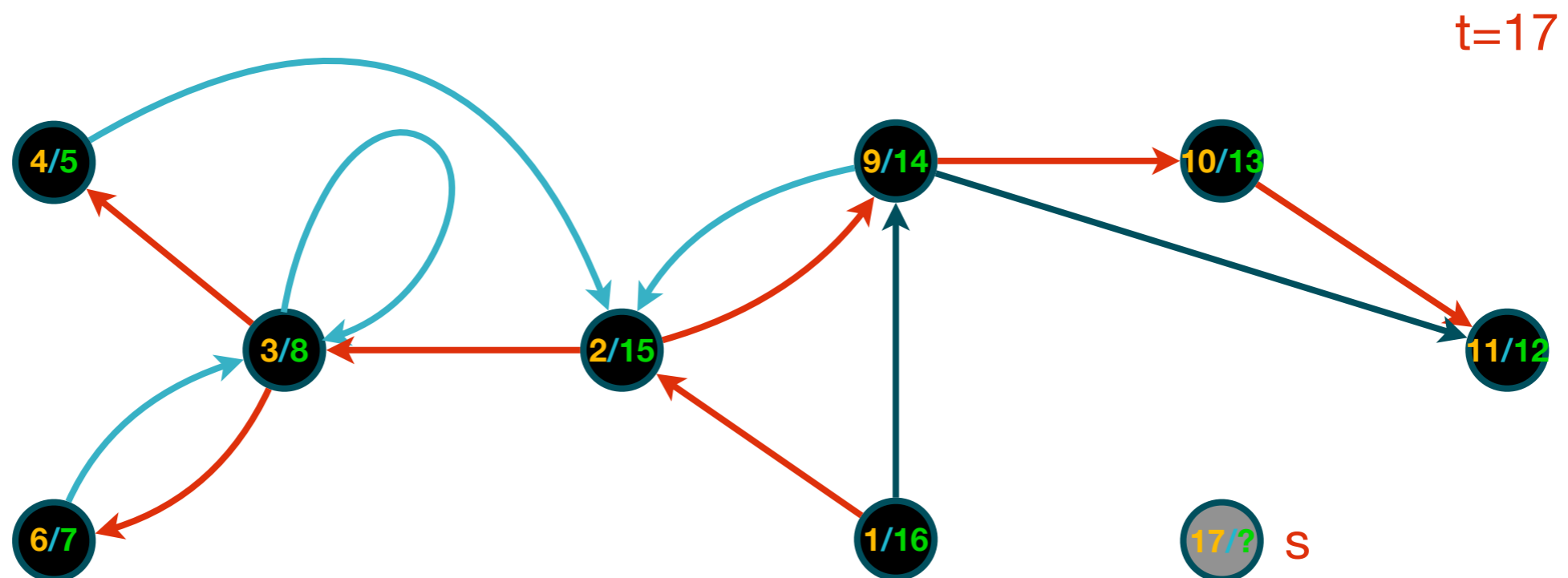
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



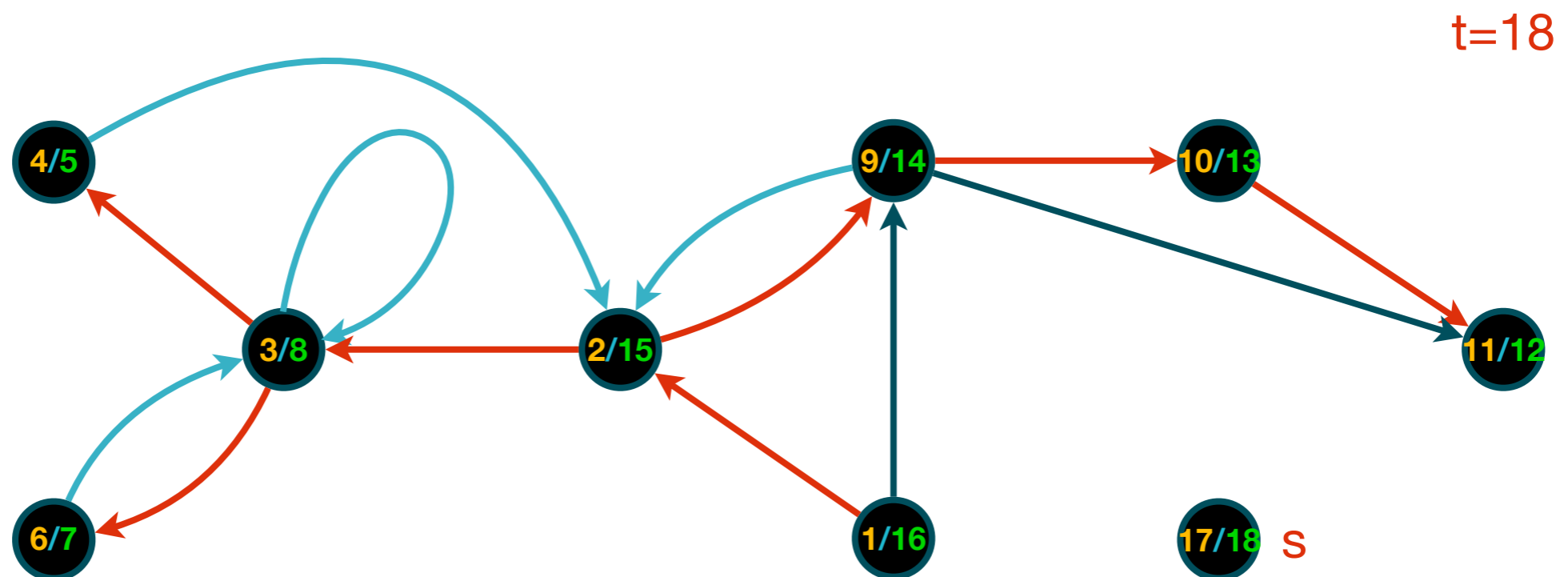
Depth-First Search



Much like BFS, DFS colors the nodes of G during the visit.

Again, white nodes have not been visited yet; gray nodes have been discovered but have undiscovered neighbours; black nodes have been discovered and their neighbours too.

DFS assigns two **timestamps** to each node v : $v.d$ records when v becomes gray, $v.f$ records when it becomes black.



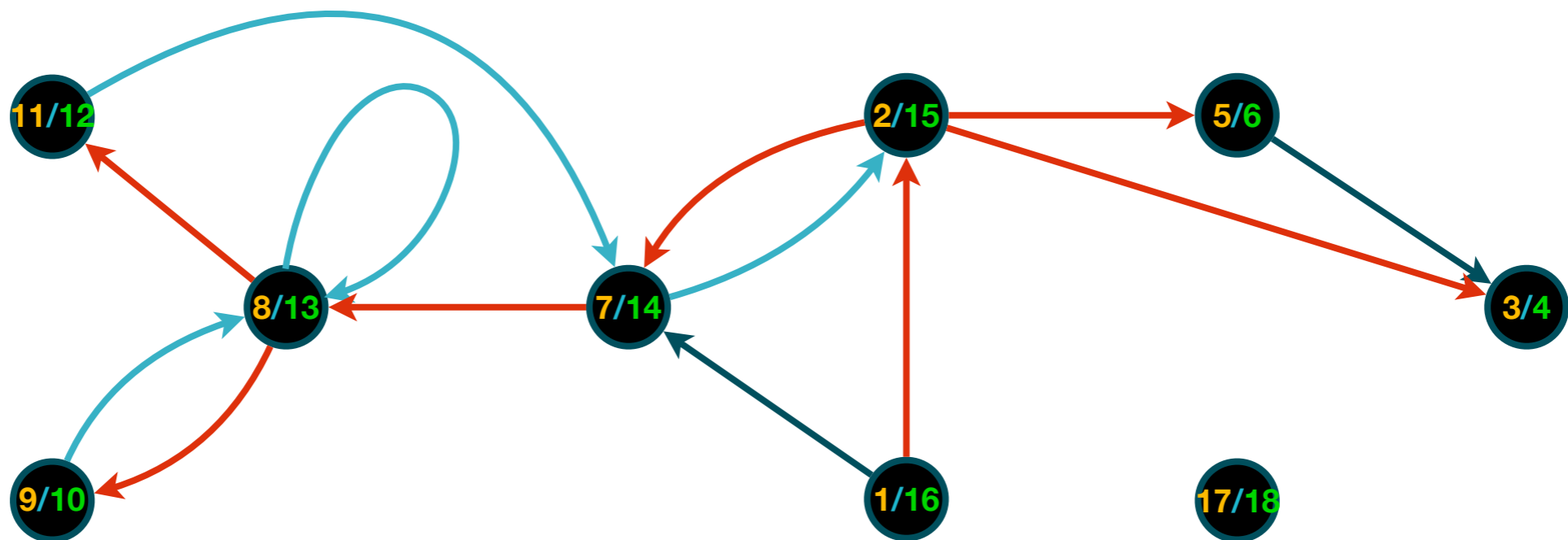
Depth-First Search



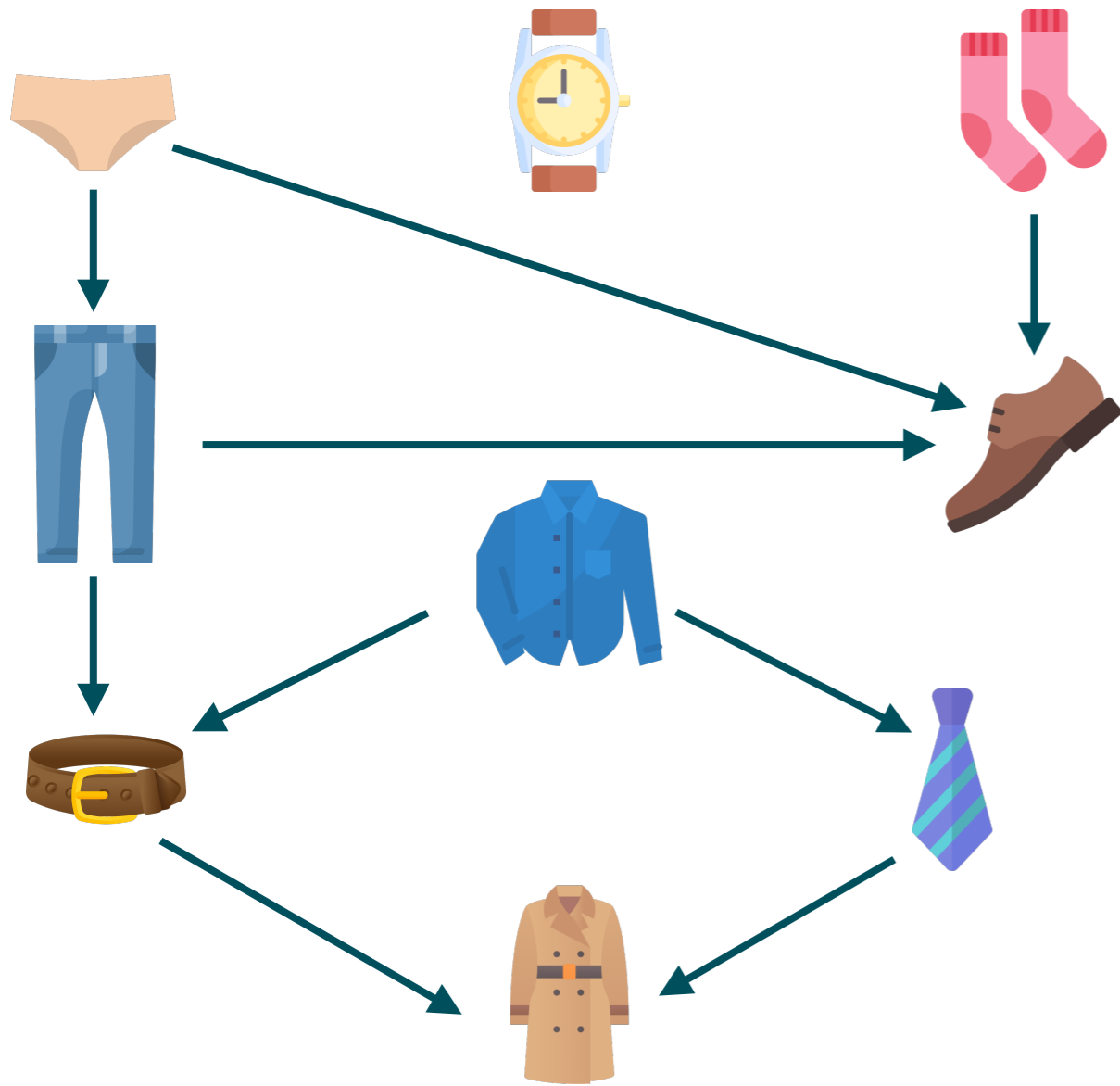
DFS produces a depth-first (DF) forest (a different tree for each source). Even for the same sources, this forest is **not unique**: it depends from the order in which the edges outgoing from each node are traversed. All the results are essentially equivalent.

The red edges are **tree edges**; the light blue edges are **back edges**, linking a node with one of its ancestors in the DF forest.

You can verify yourself that the result below is another possible outcome of DFS with the same two sources.

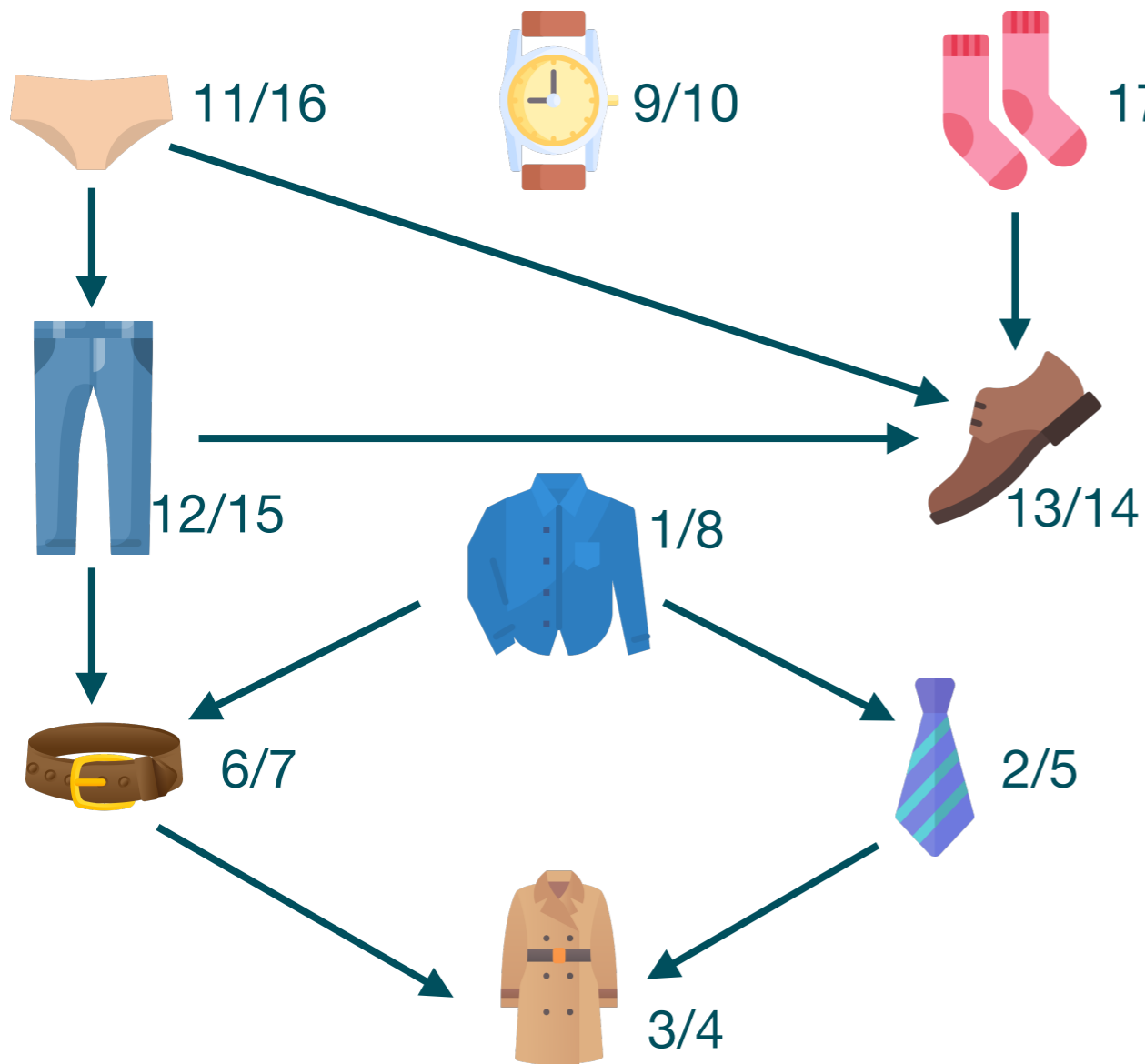


An application: Topological Sort



An edge (u,v) indicates that item u must be worn before item v .

An application: Topological Sort

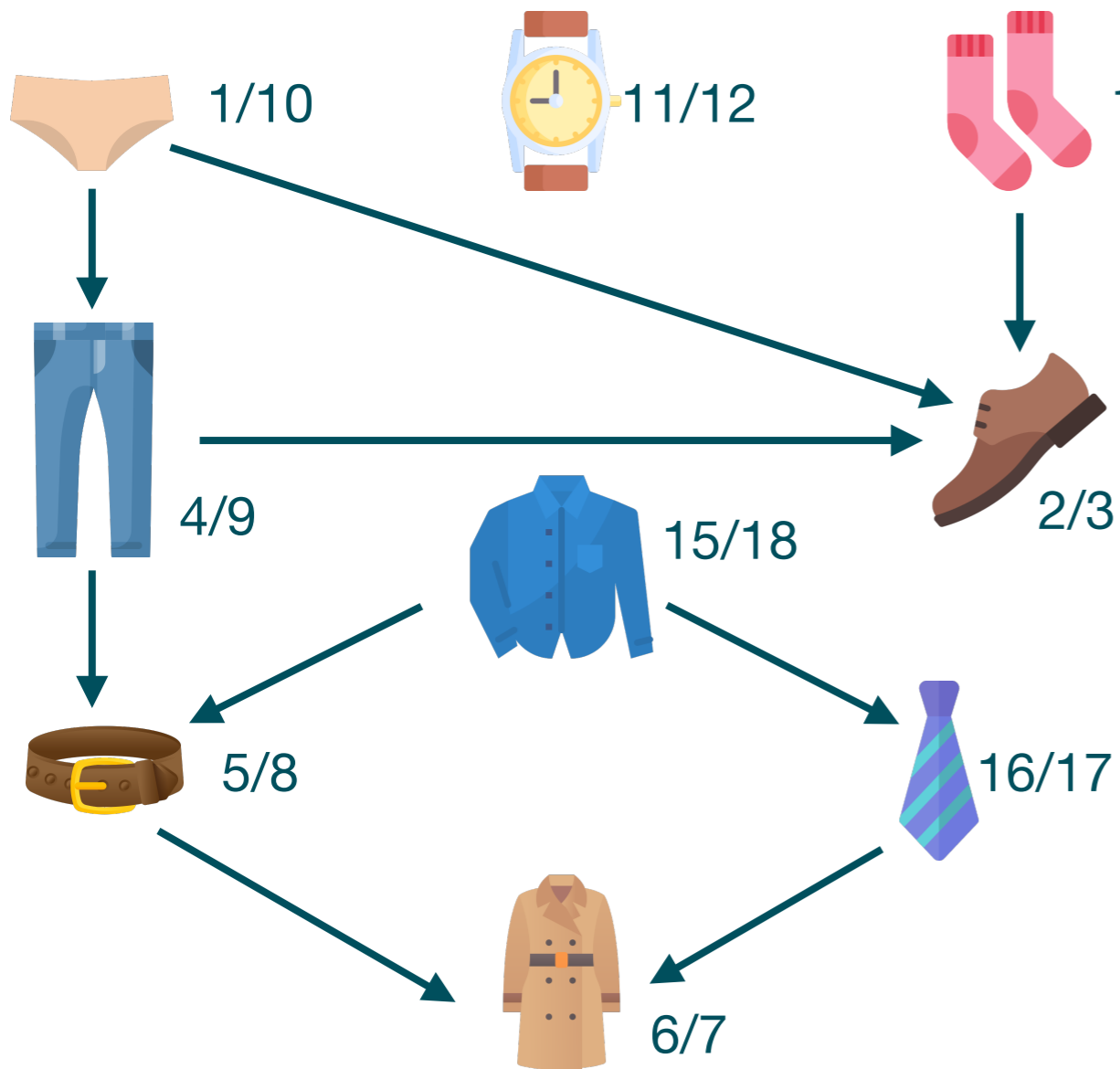


```
TopologicalSort(G)
DFS(G);
 $\tilde{V}[1, \dots, |V|] \leftarrow V$  sorted w.r.t finishing time
TopOrder  $\leftarrow$  empty_stack;
for  $i = 1 \dots |V|$ 
    TopOrder.push( $\tilde{V}[i]$ );
return TopOrder;
```

An edge (u, v) indicates that item u must be worn before item v .

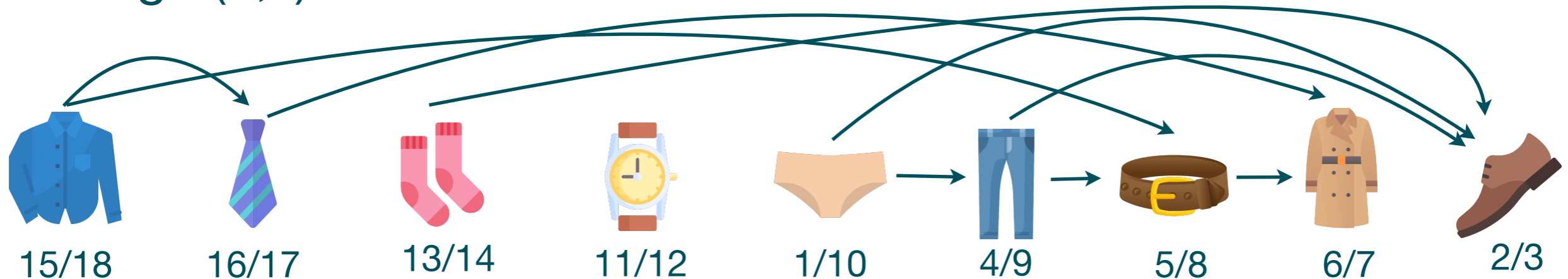


An application: Topological Sort



```
TopologicalSort(G)
DFS(G);
 $\tilde{V}[1, \dots, |V|] \leftarrow V$  sorted w.r.t finishing time
TopOrder  $\leftarrow$  empty_stack;
for  $i = 1 \dots |V|$ 
    TopOrder.push( $\tilde{V}[i]$ );
return TopOrder;
```

An edge (u, v) indicates that item u must be worn before item v .



Exercises

EX (Cormen 17.1-1): If the set of stack operations included a MULTIPUSH operation, which pushes k items onto the stack, would the $O(1)$ bound on the amortized cost of stack operations continue to hold?

Exercises

EX1: Given a connected, undirected graph, design an algorithm that assigns one of two colors (say blue or green) to each vertex in such a way that no edge links two vertices of the same color; or return FAIL if no such coloring is possible.

Exercises

EX2: Give an $O(|V|)$ -time algorithm that determines whether or not a given undirected graph contains a cycle. (*Hint: Think of the maximum number of edges that an acyclic undirected graph may have; use DFS and terminate it early when appropriate*).