

# Green's function

**Green's function** is a basic solution to a linear differential equation, a building block that can be used to construct many useful solutions.

If one considers a linear differential equation written as:

$$L(x)u(x)=f(x)$$

where  $L(x)$  is a linear, self-adjoint differential operator,  $u(x)$  is the unknown function, and  $f(x)$  is a known non-homogeneous term, the GF is a solution of:

$$L(x)u(x,s)=\delta(x-s)$$

$G(x,s)$

# Why GF is important?

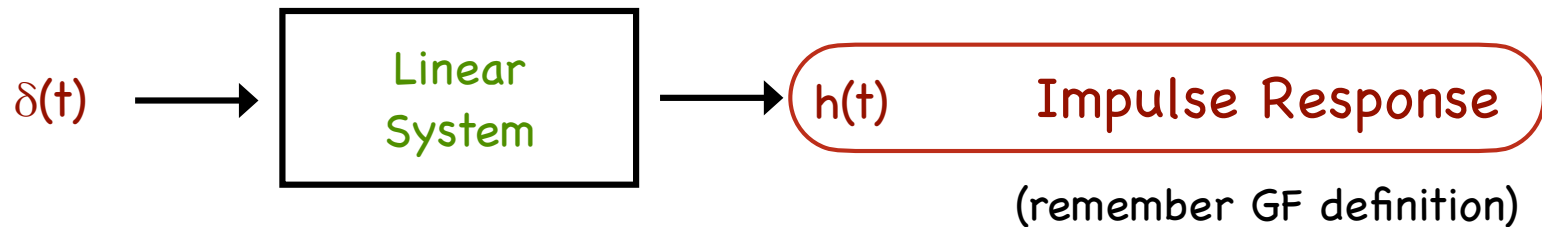
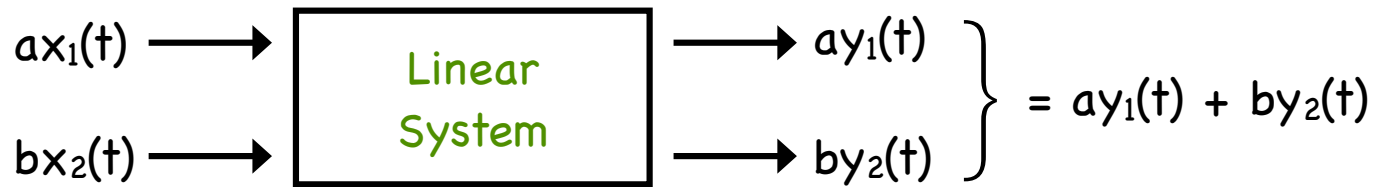
If such a function  $G$  can be found for the operator  $L$ , then if we multiply the second equation for the Green's function by  $f(s)$ , and then perform an integration in the  $s$  variable, we obtain:

$$\int L(x)G(x, s)f(s)ds = \int \delta(x - s)f(s)ds = f(x) = Lu(x)$$
$$L \int G(x, s)f(s)ds = Lu(x)$$

$$u(x) = \int G(x, s)f(s)ds$$

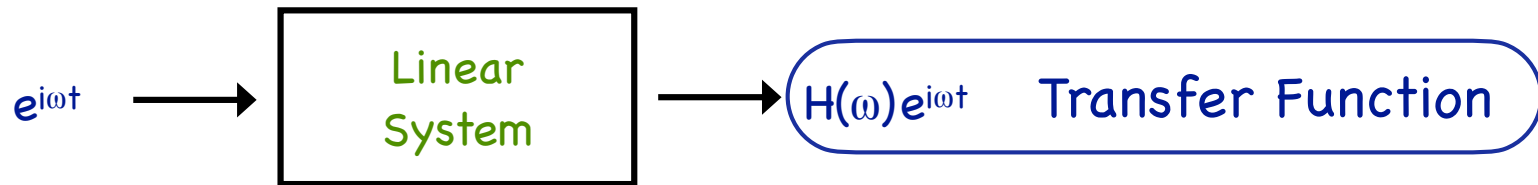
Thus, we can obtain the function  $u(x)$  through the knowledge of the **Green's function and the source term**. This process has resulted from the linearity of the operator  $L$ . See Linear System Theory (i.e. impulse response)

# Linear Systems



Since any input  $x(t)$  can be written as:

$$x(t) = \int x(\tau)\delta(t - \tau) d\tau \quad \longrightarrow \quad \int x(\tau)h(t - \tau) d\tau \quad \text{= } x * h$$



$$\int e^{i\omega\tau}h(t - \tau) d\tau = \int e^{i\omega(t-\tau)}h(\tau) d\tau = e^{i\omega t} \int e^{-i\omega\tau}h(\tau) d\tau$$

$$X(\omega) = \int x(t)e^{i\omega t} dt \quad \longrightarrow \quad X(\omega) \cdot H(\omega)$$

# Convolution

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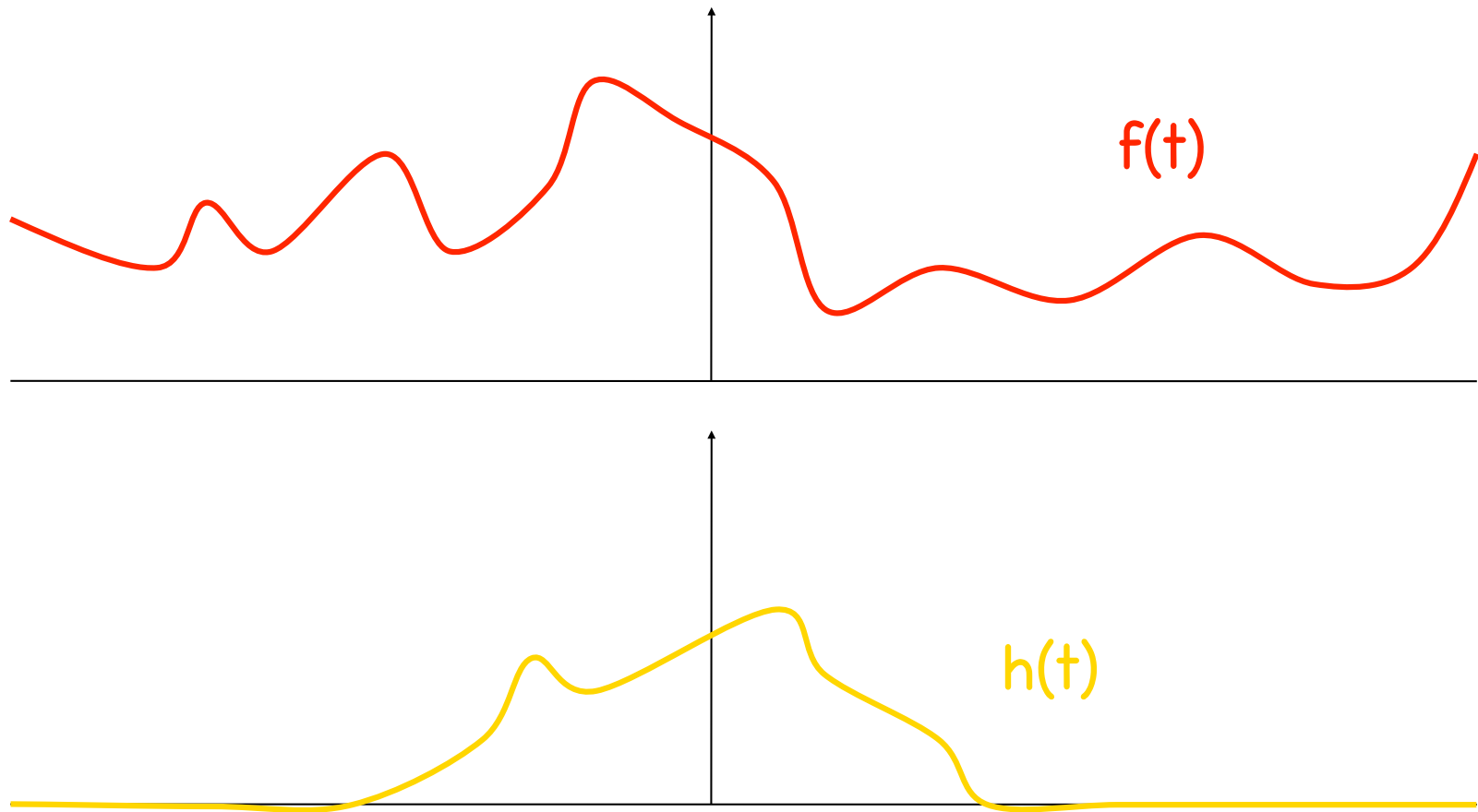
● Definition:

$$f(t) * h(t) = \int_{-\infty}^{\infty} f(\tau)h(t - \tau) d\tau$$

# Convolution

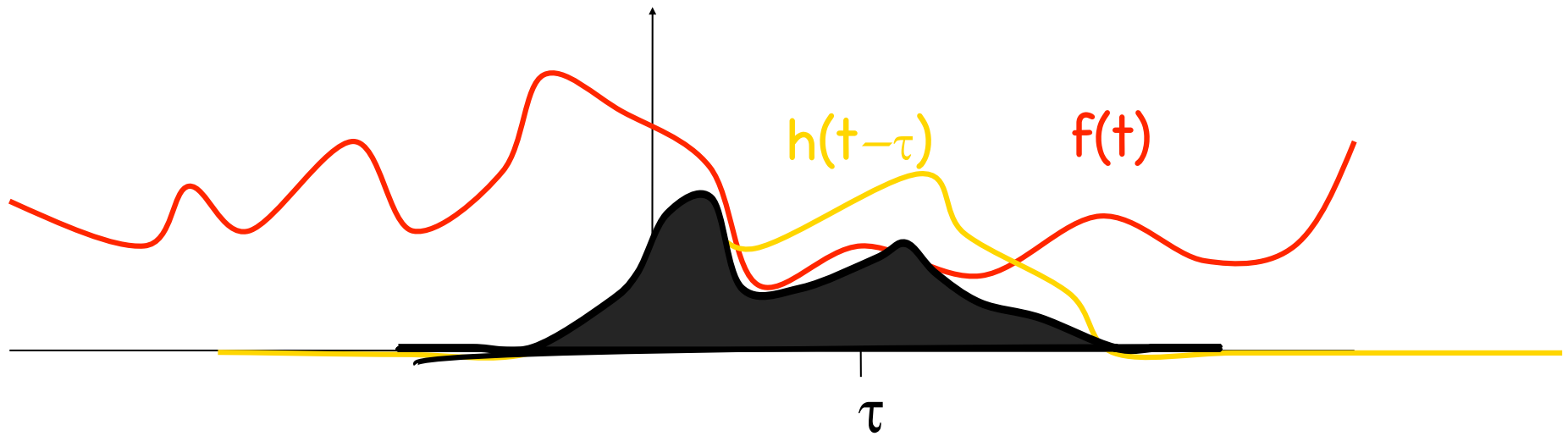
● Definition:  $f(t) * h(t) = \int_{-\infty}^{\infty} f(\tau)h(t - \tau) d\tau$

● Pictorially



# Convolution

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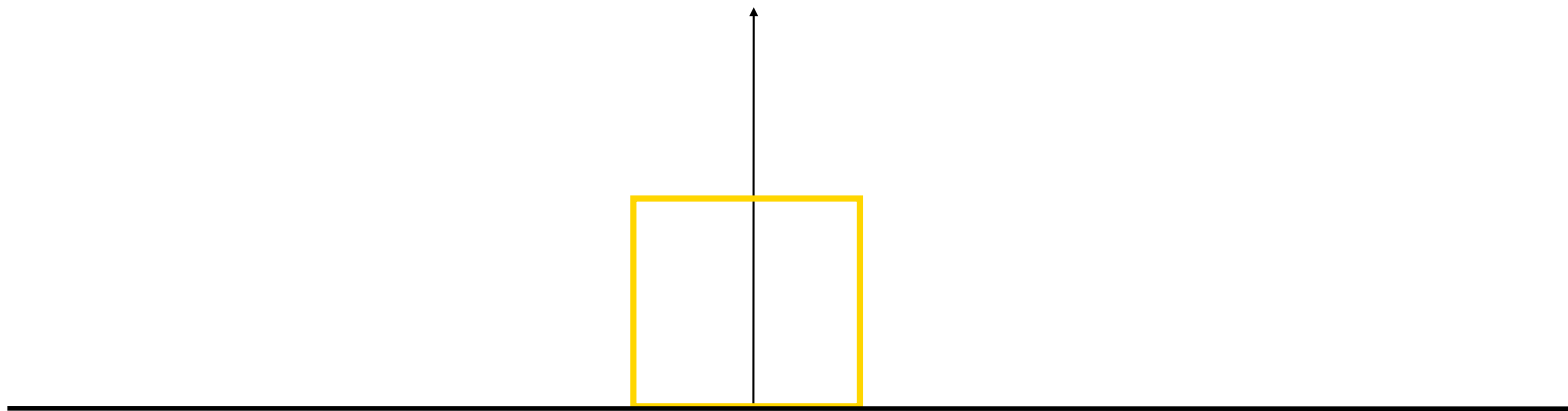


# Convolution

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- Consider the boxcar function (box filter):

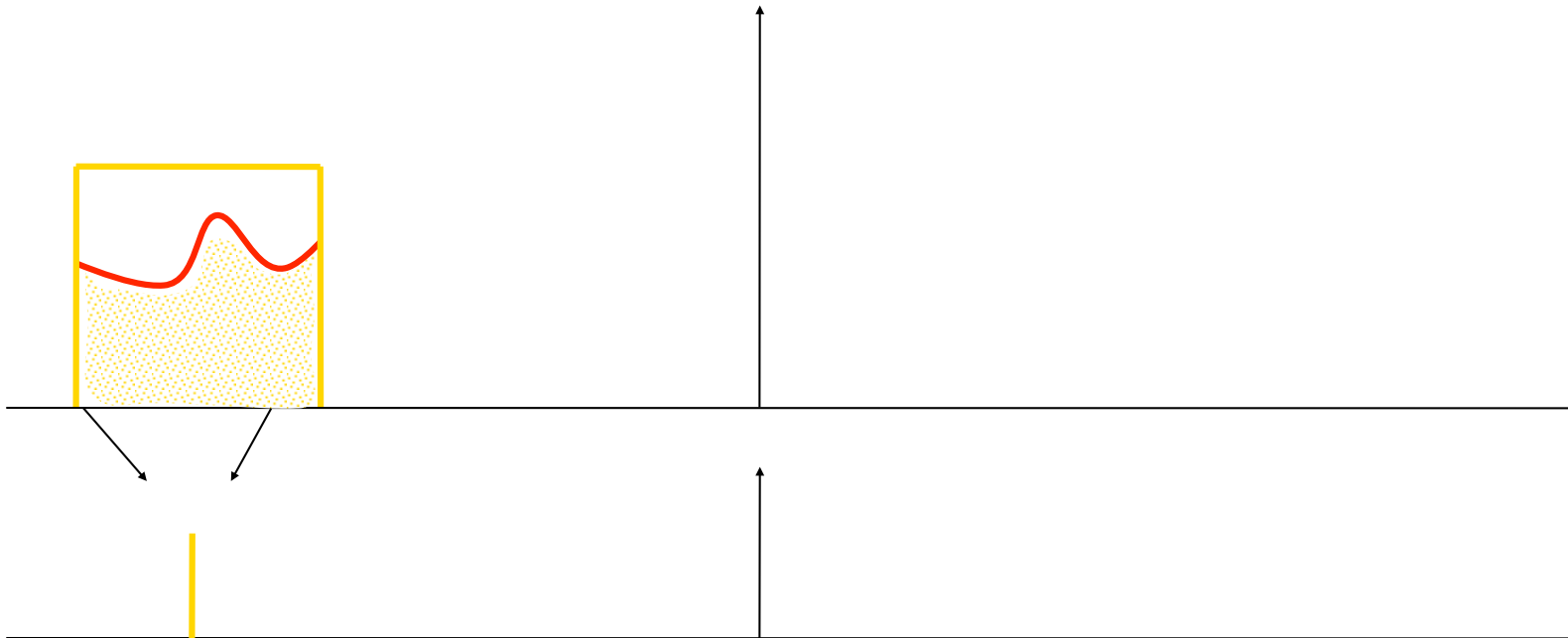
$$h(t) = \begin{cases} 0 & t < -\frac{1}{2} \\ 1 & -\frac{1}{2} \leq t \leq \frac{1}{2} \\ 0 & t > \frac{1}{2} \end{cases}$$



# Convolution

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- This function windows our function  $f(t)$

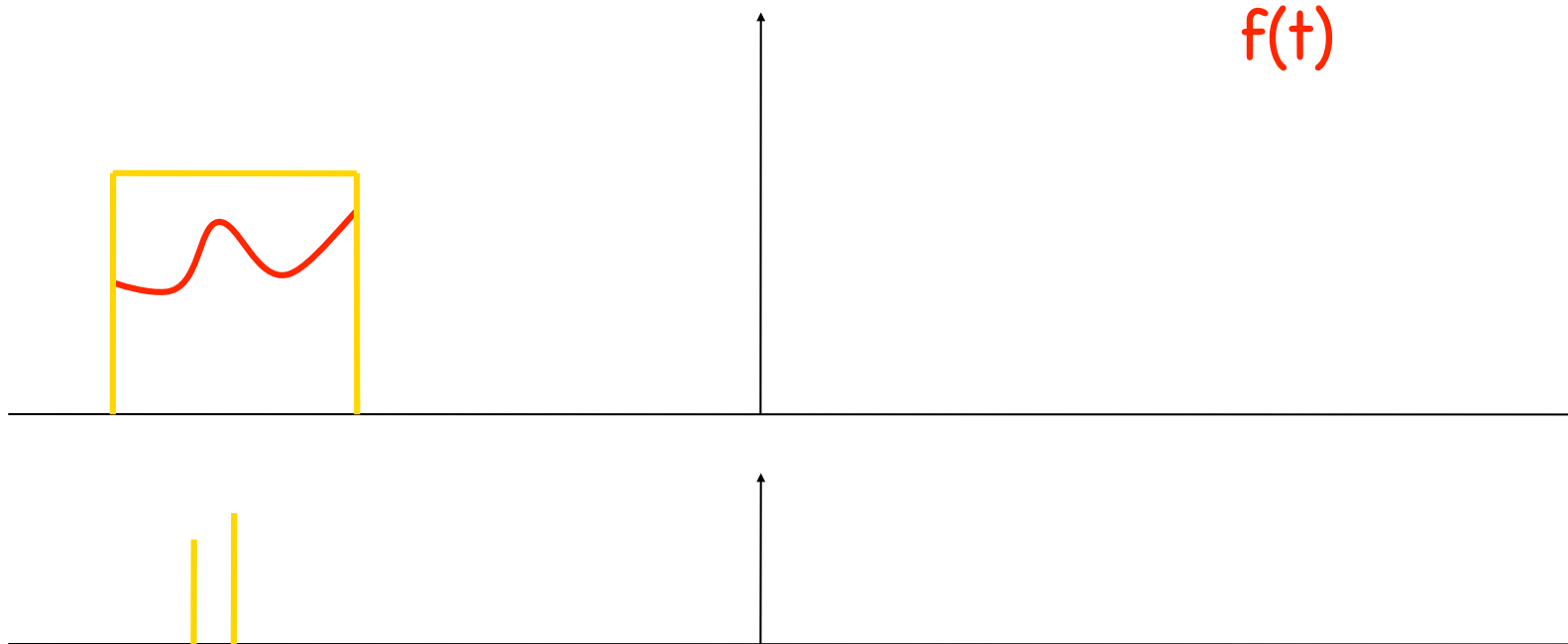




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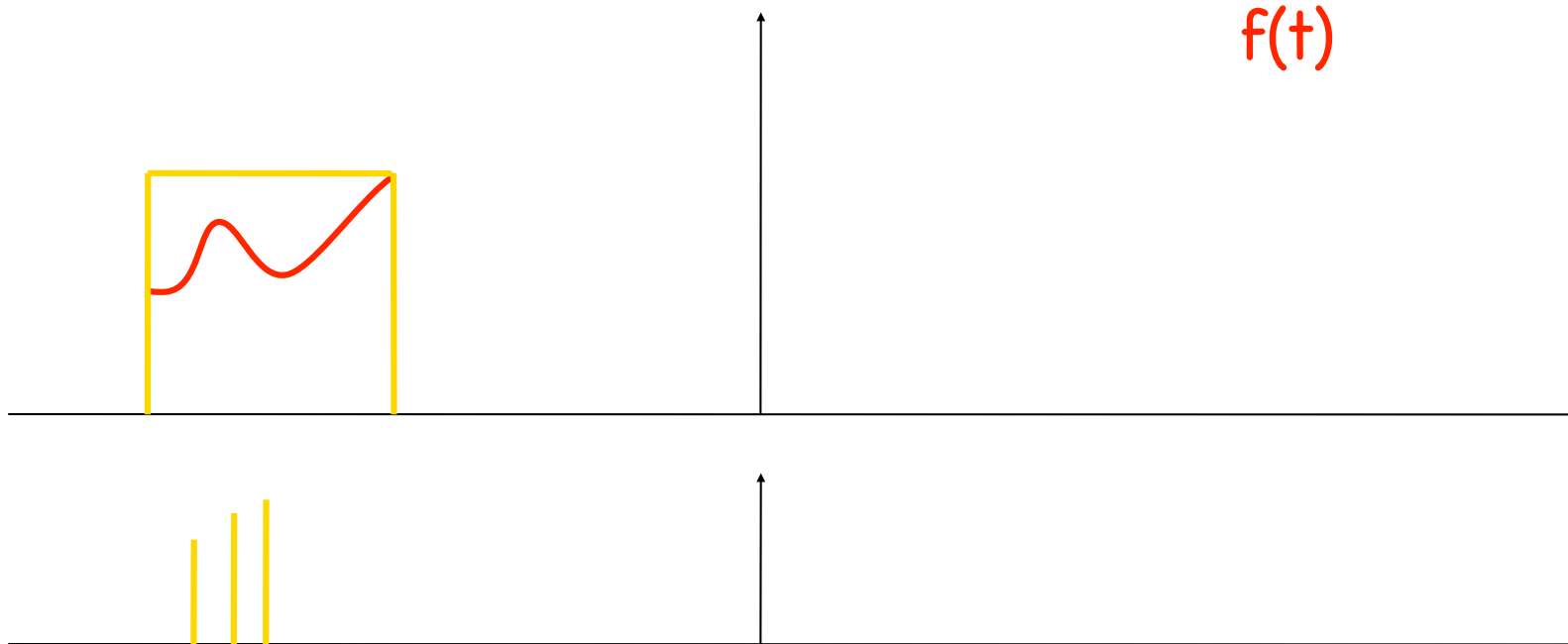
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# Convolution

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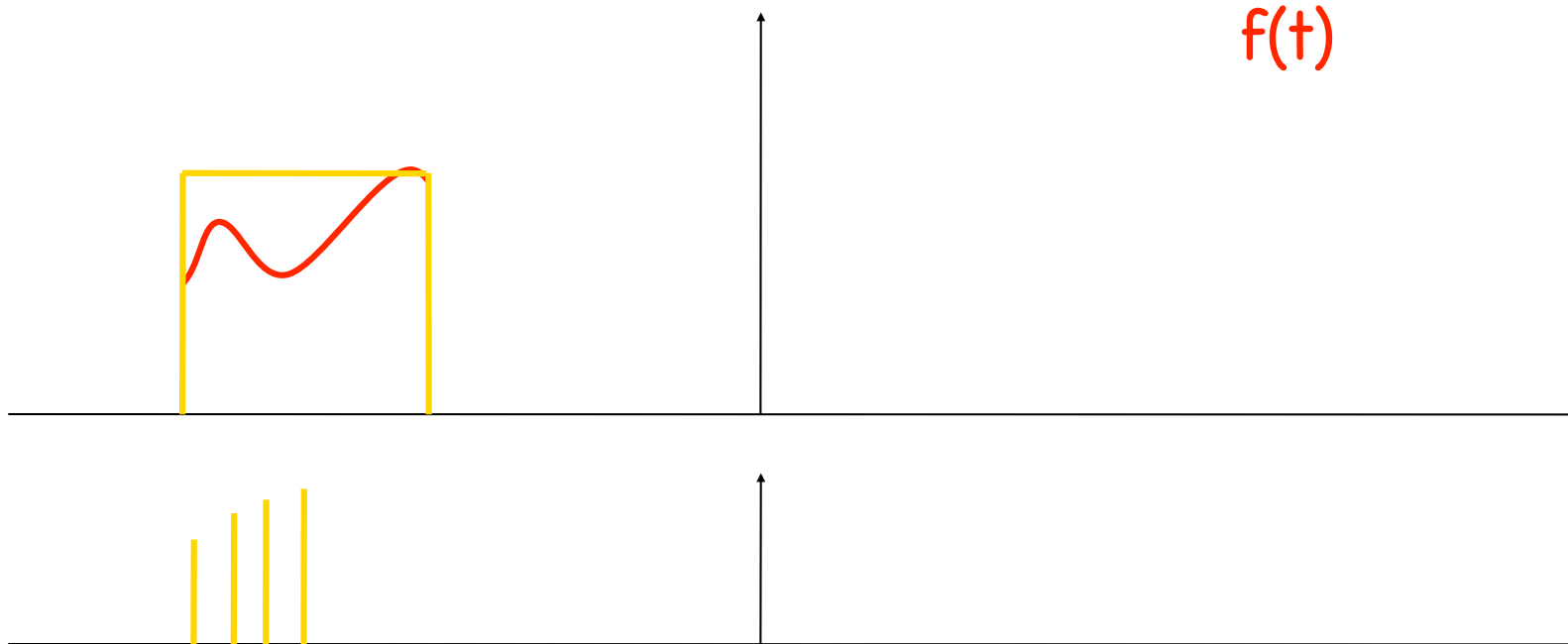
- This function windows our function  $f(t)$ .



# Convolution

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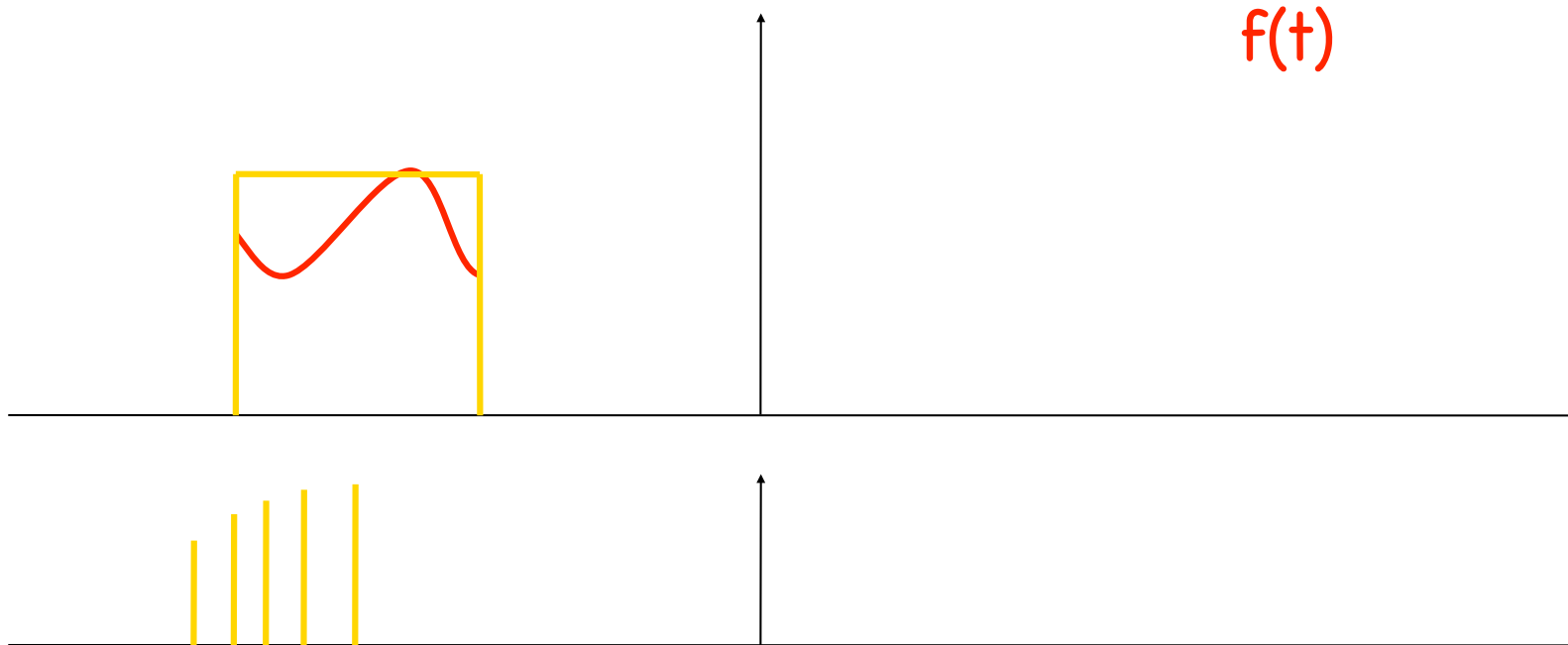
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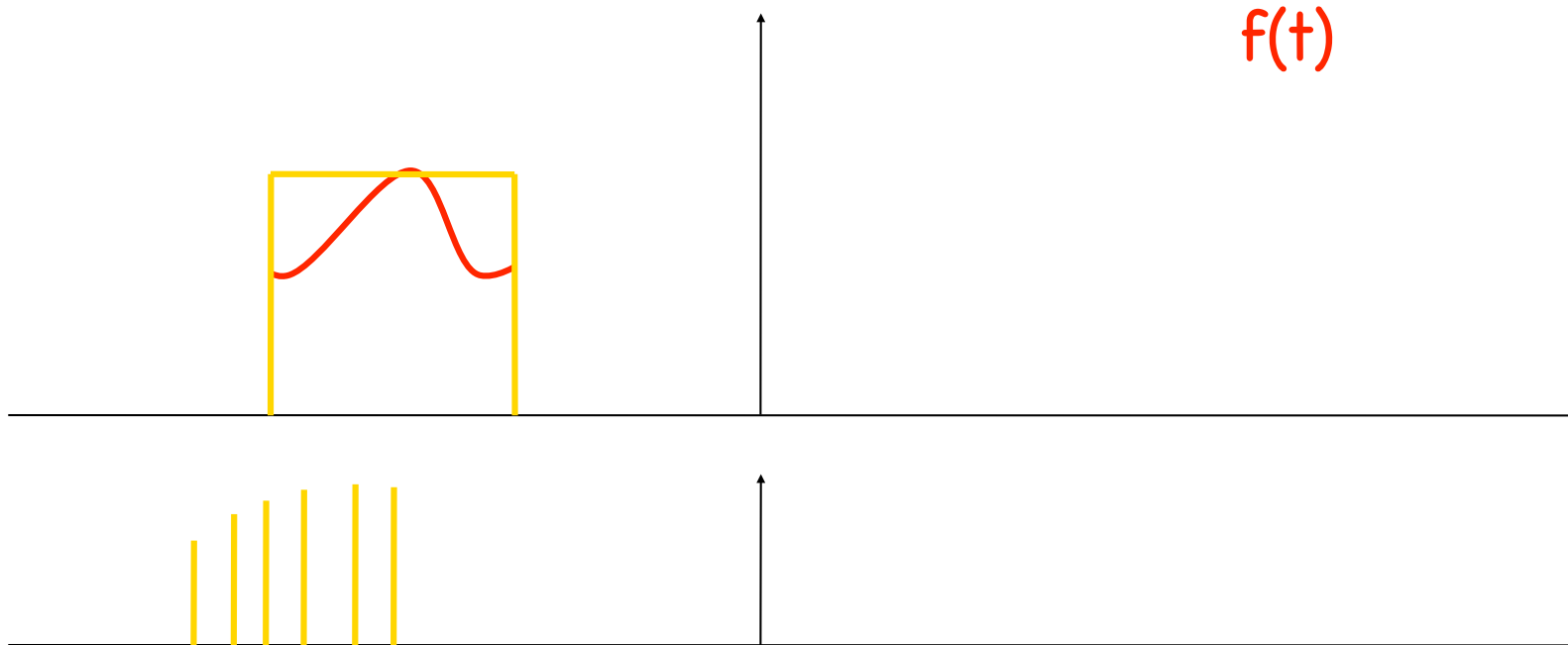
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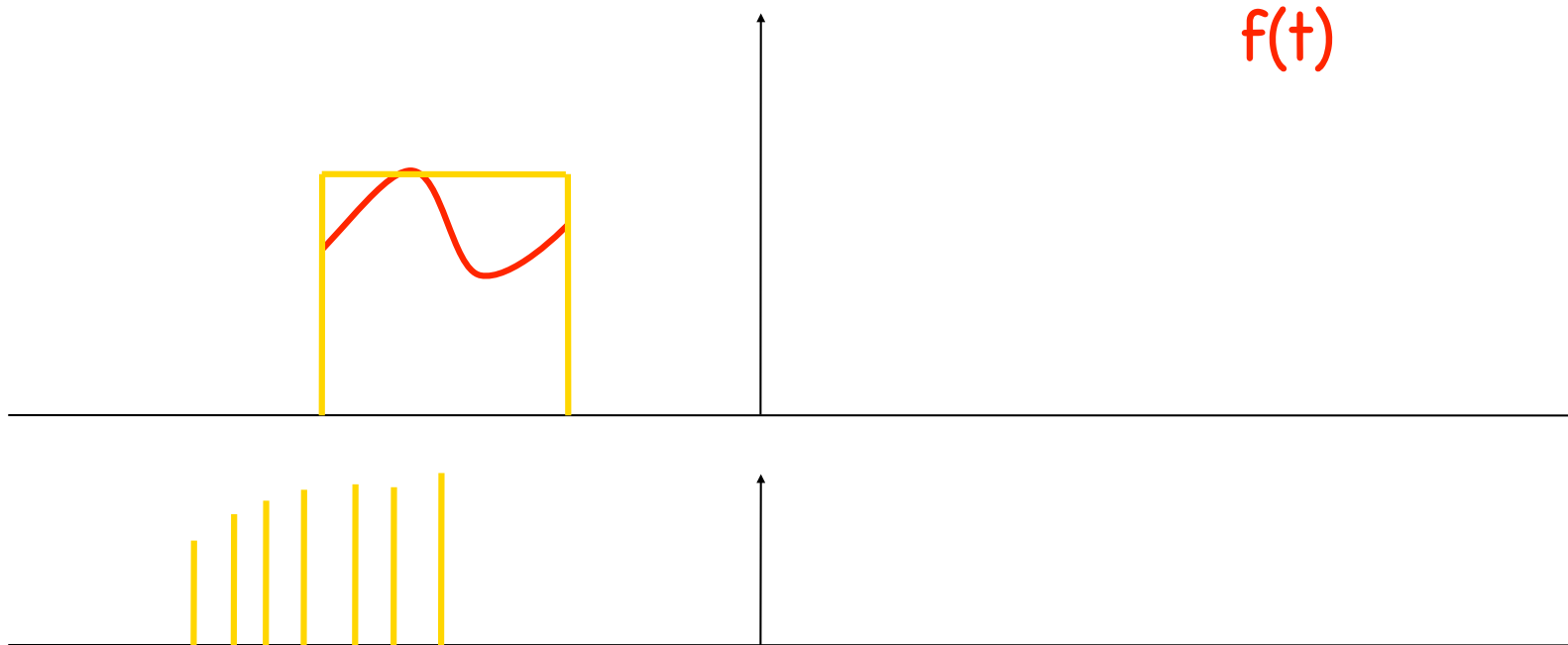
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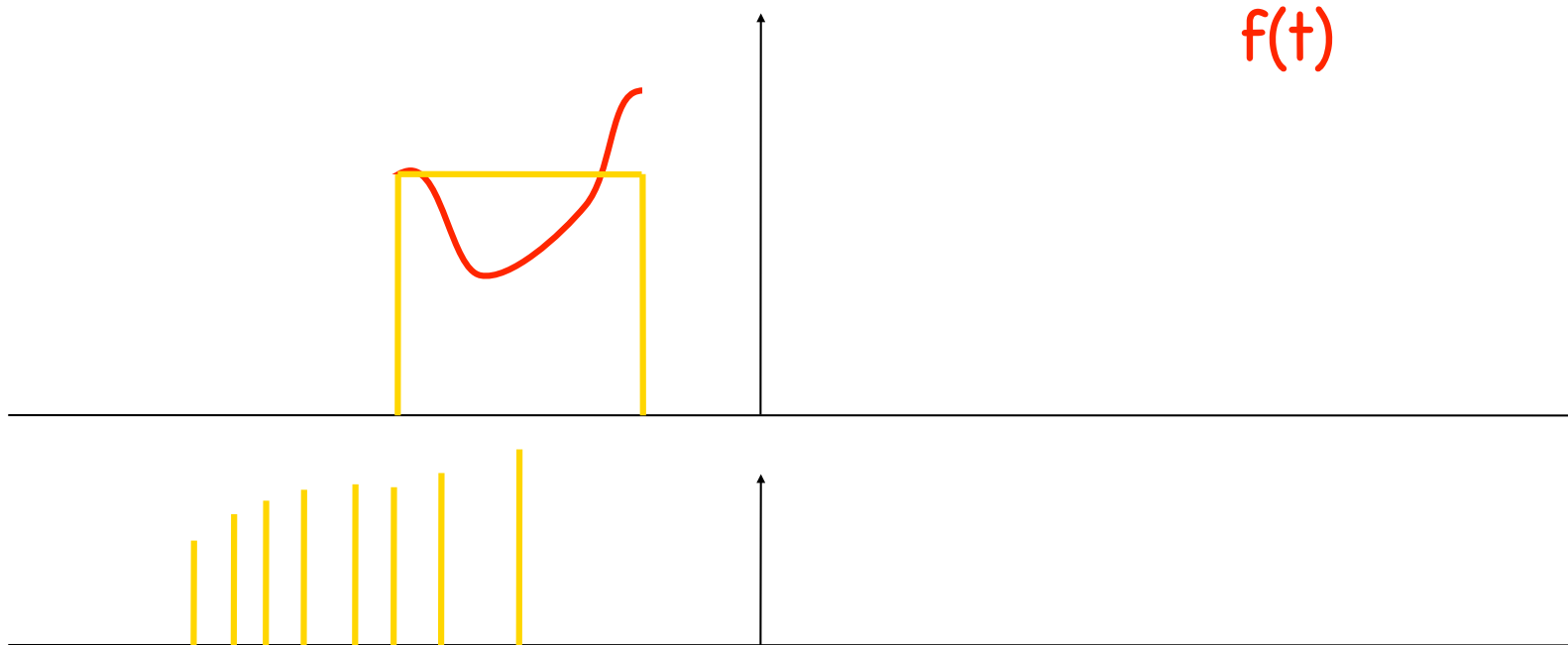
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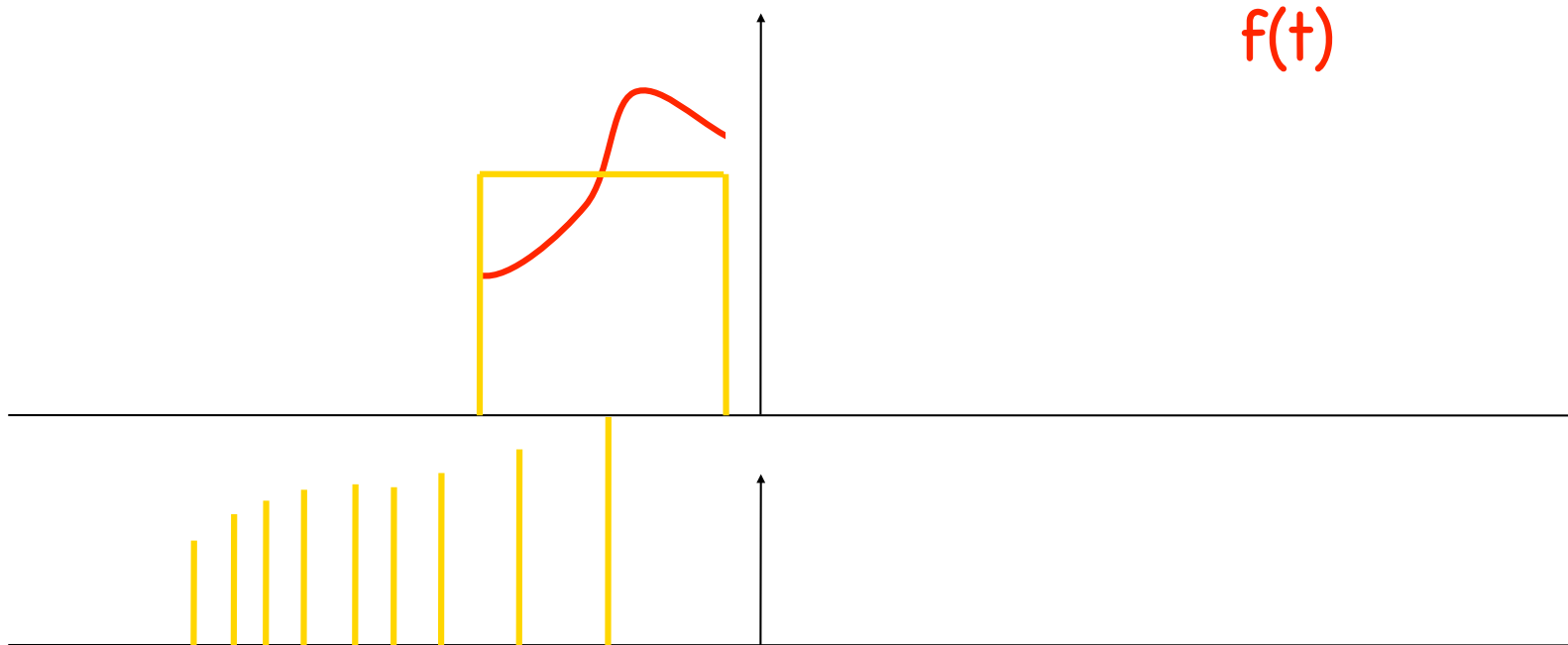
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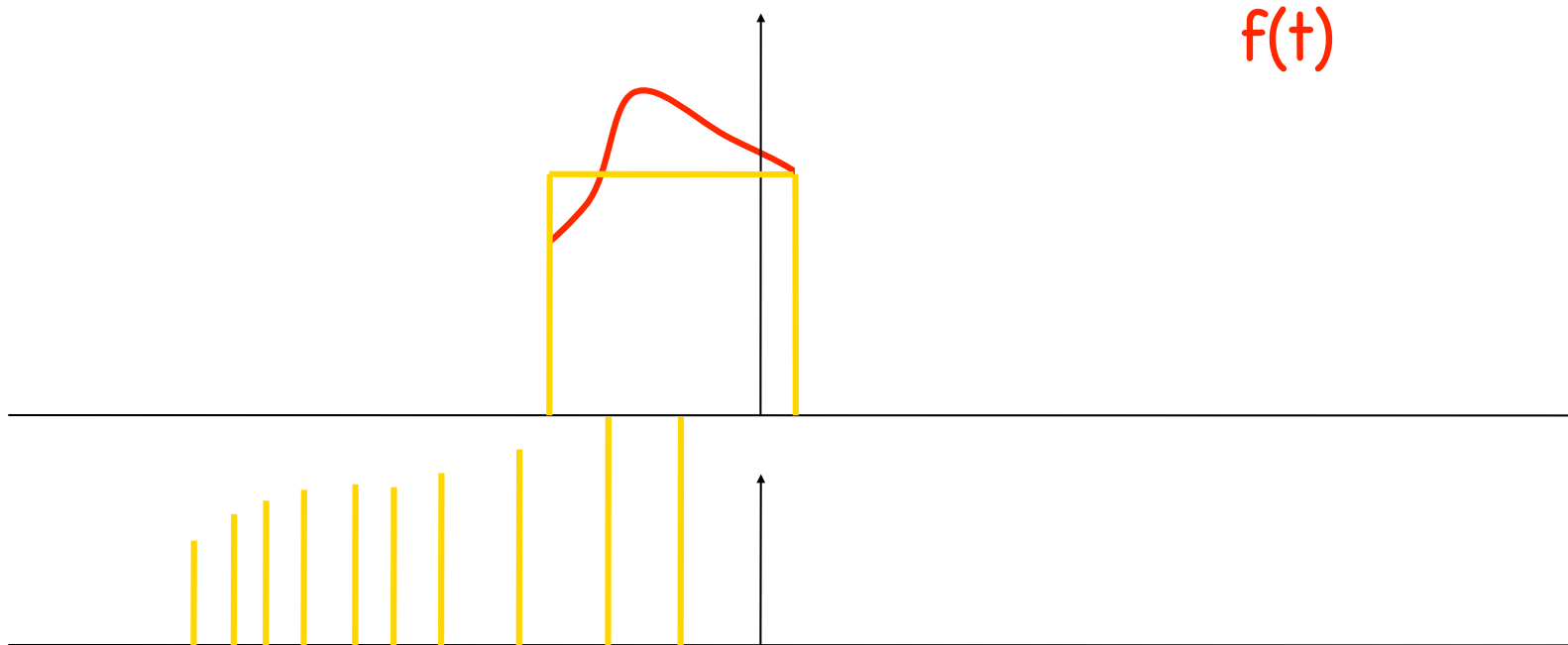




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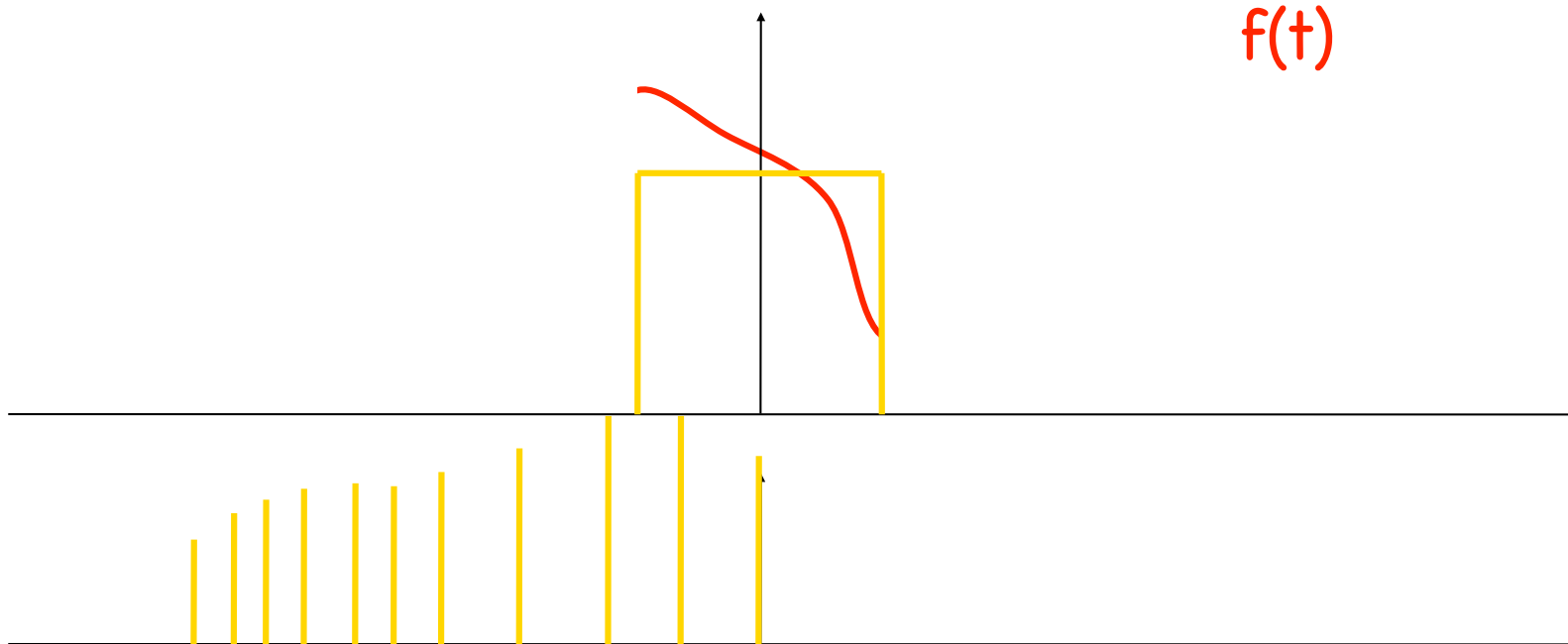
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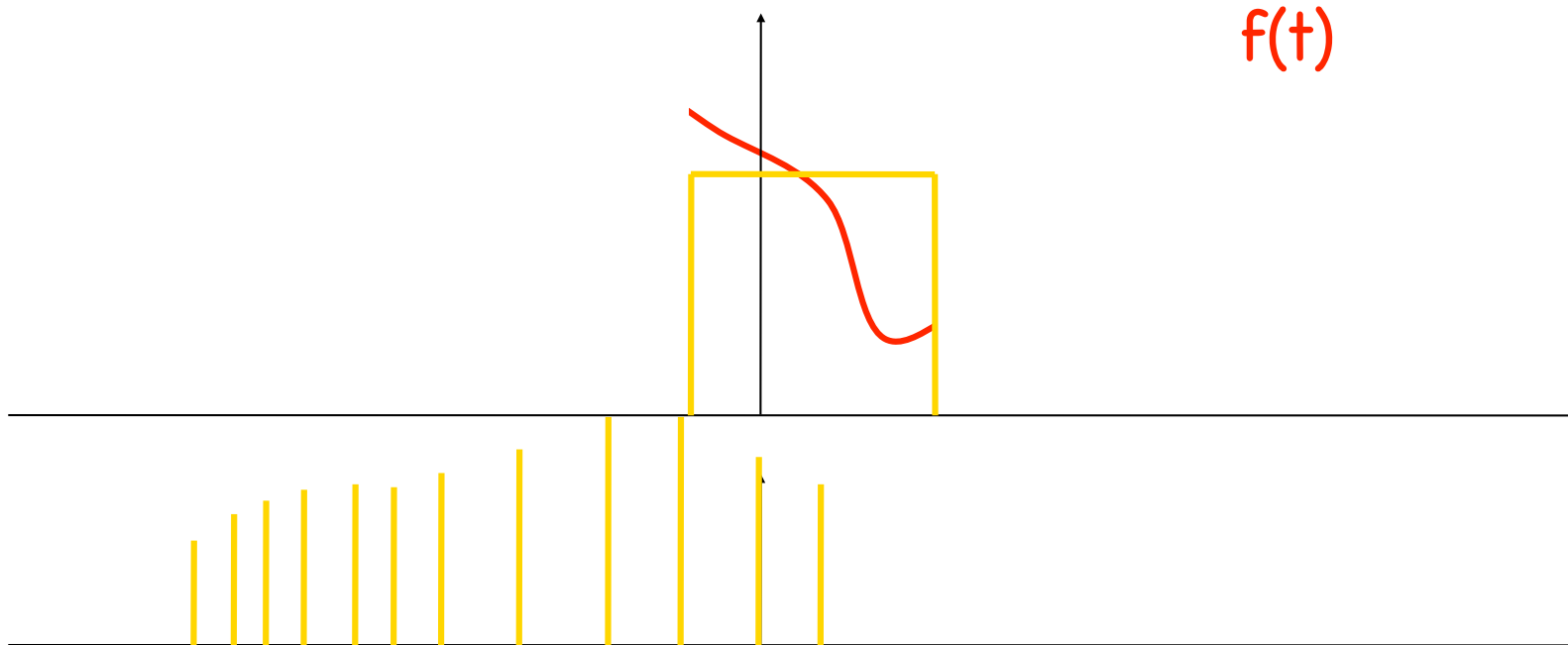
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# Convolution

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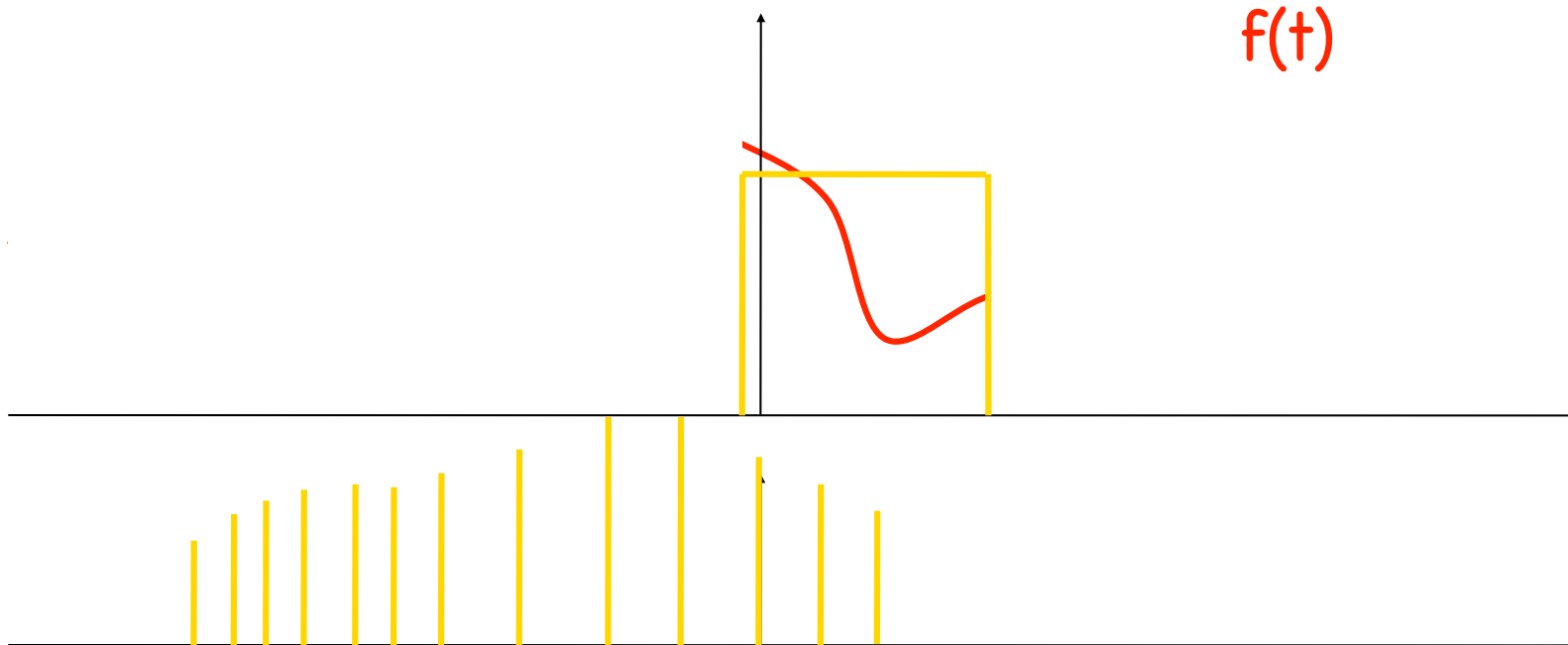
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# Convolution

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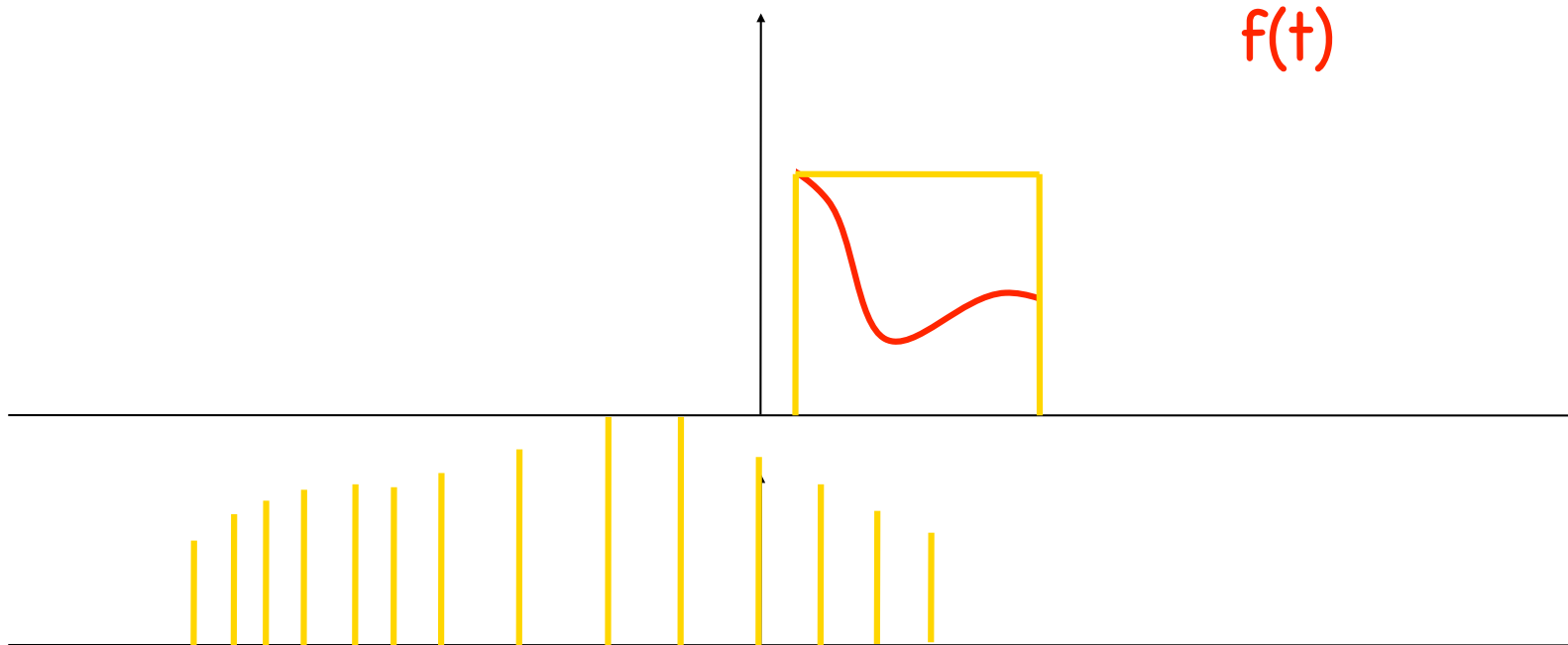
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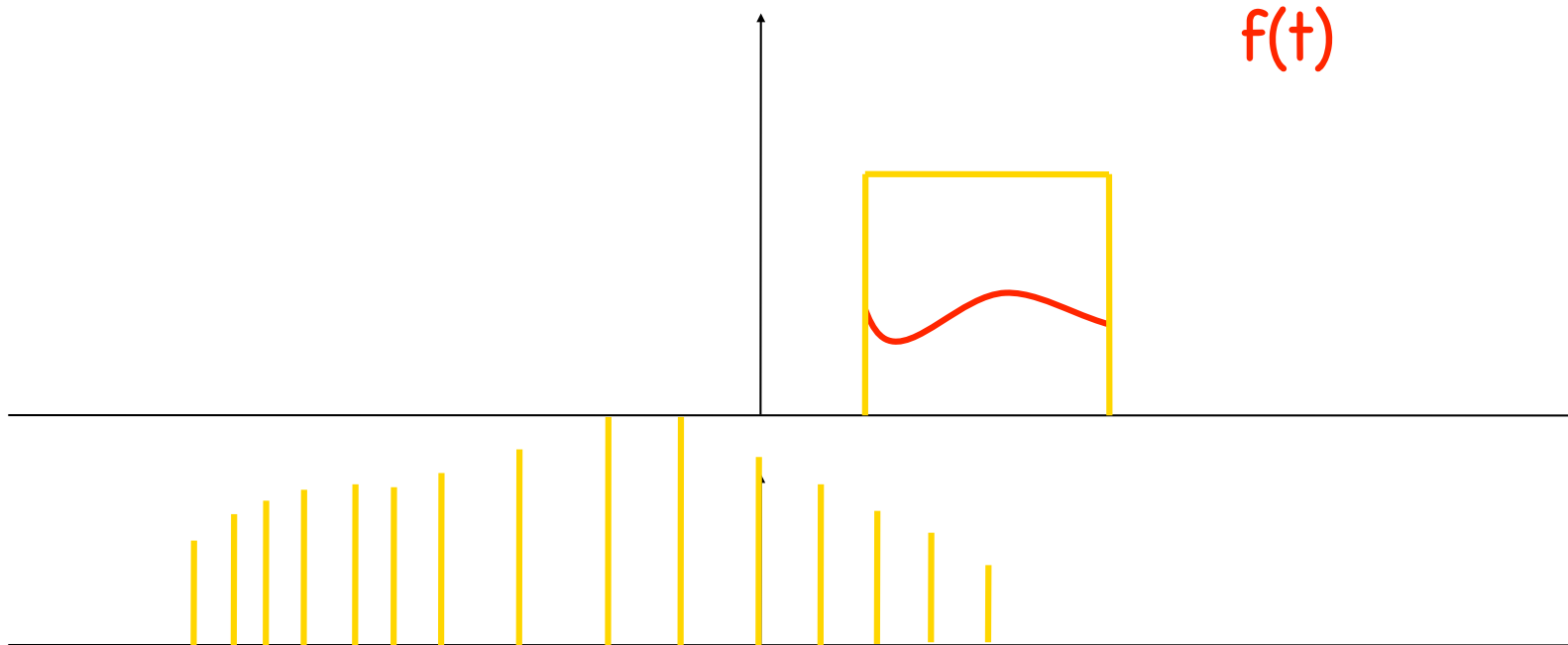
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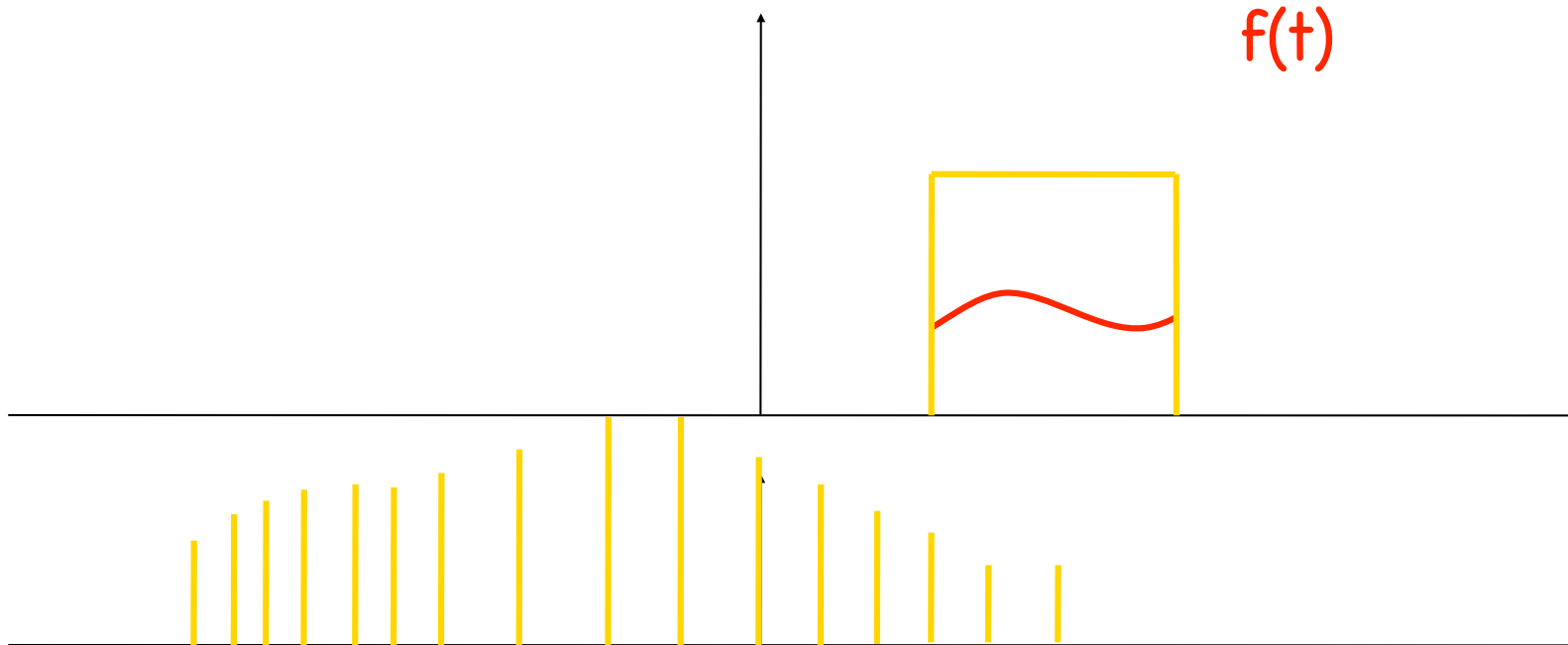
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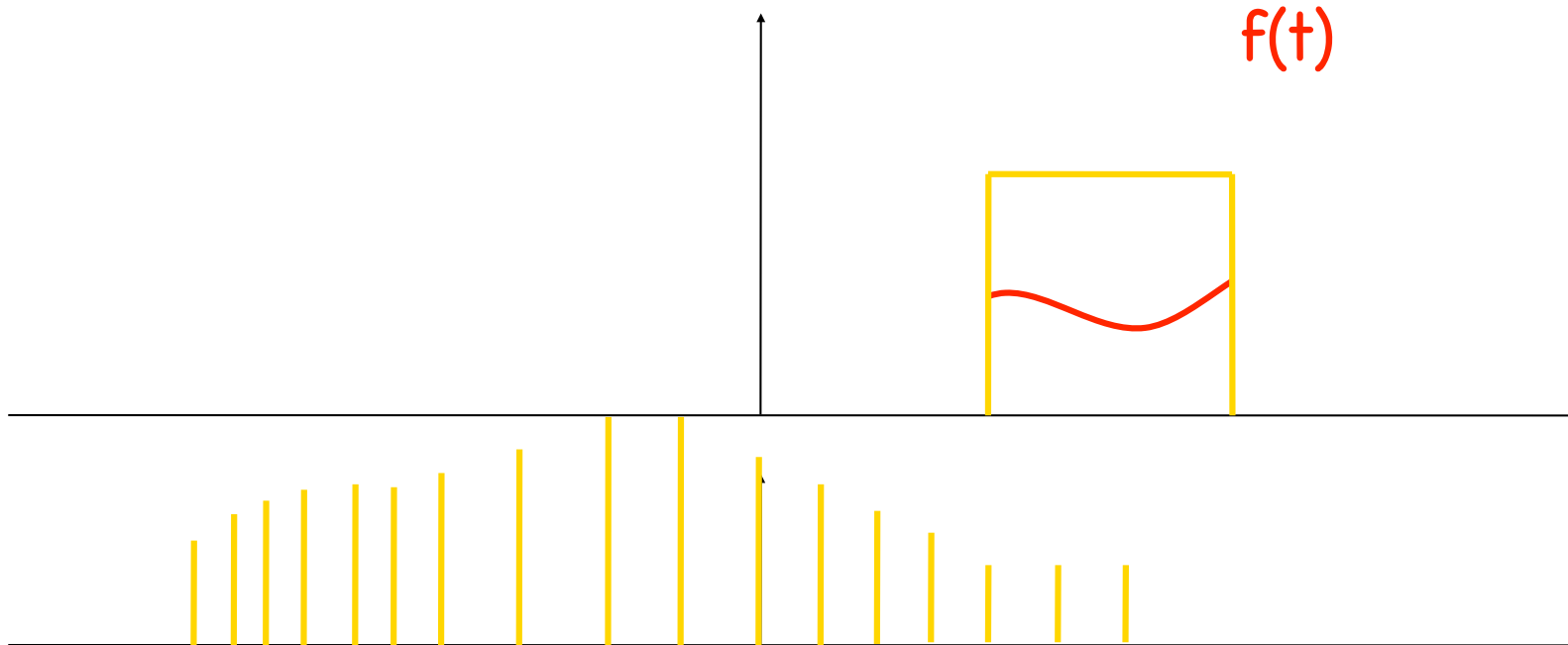
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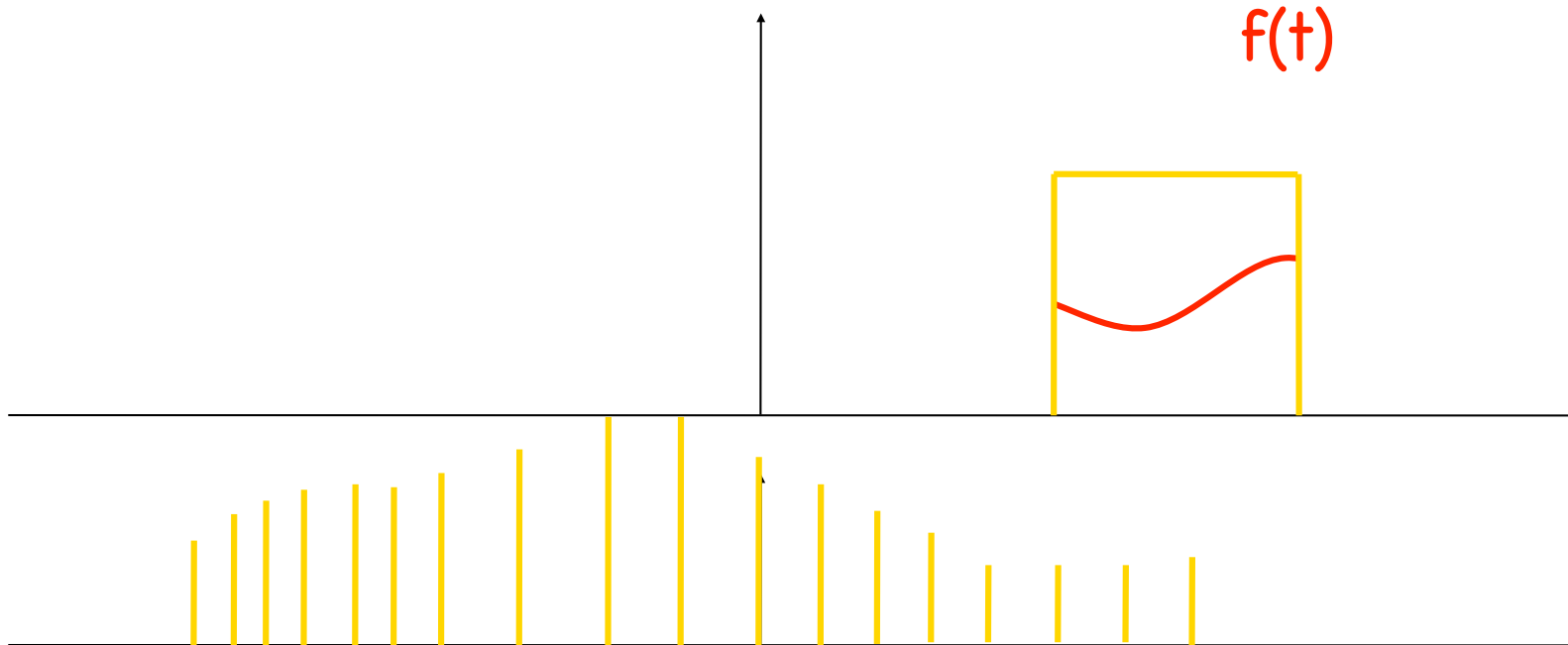




# Convolution

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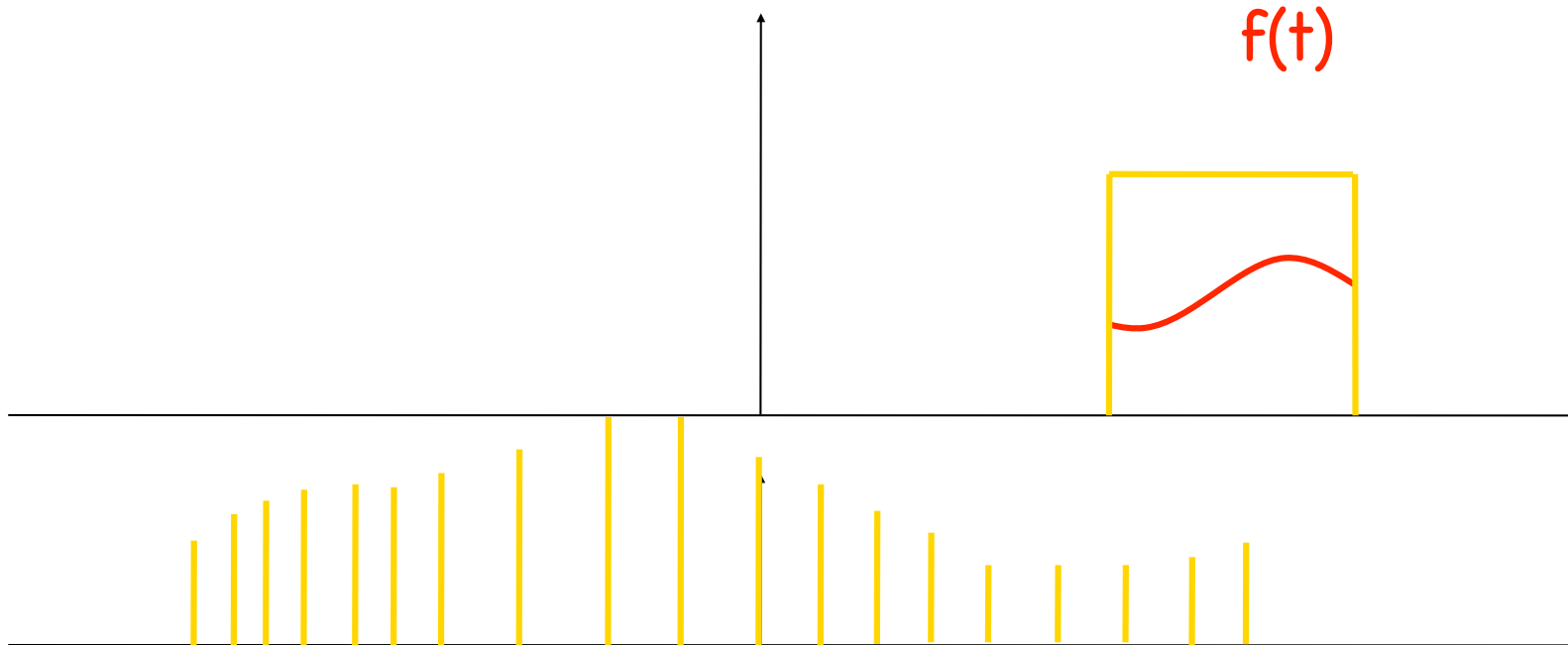
- This function windows our function  $f(t)$



# Convolution

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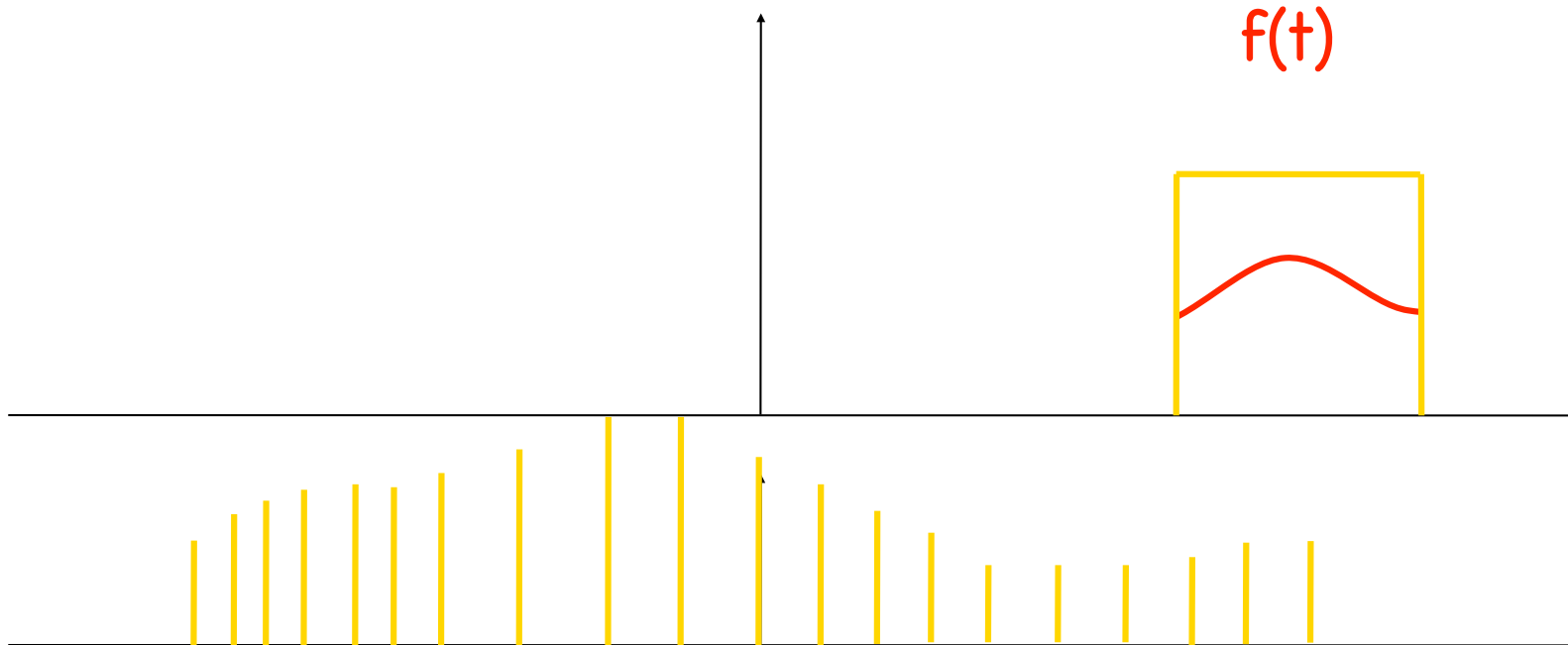
- This function windows our function  $f(t)$



# Convolution

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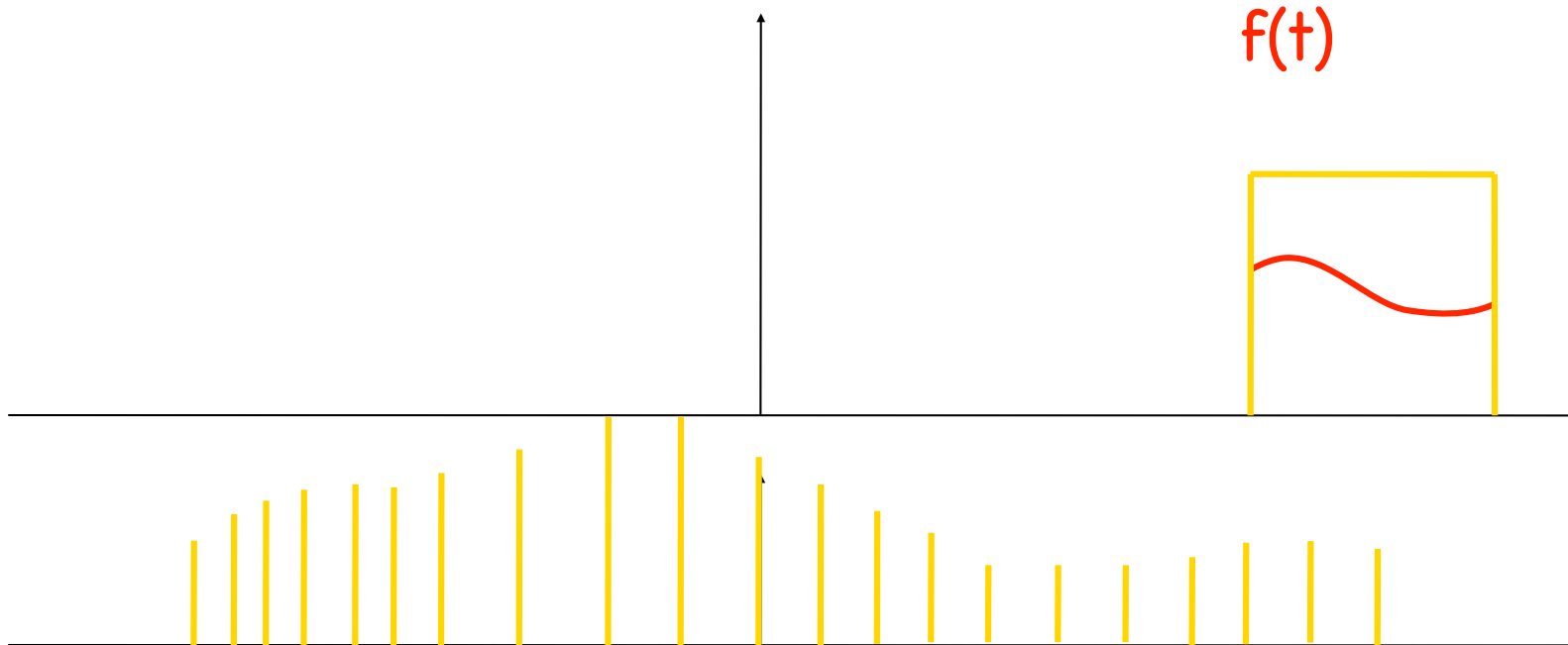
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# Convolution

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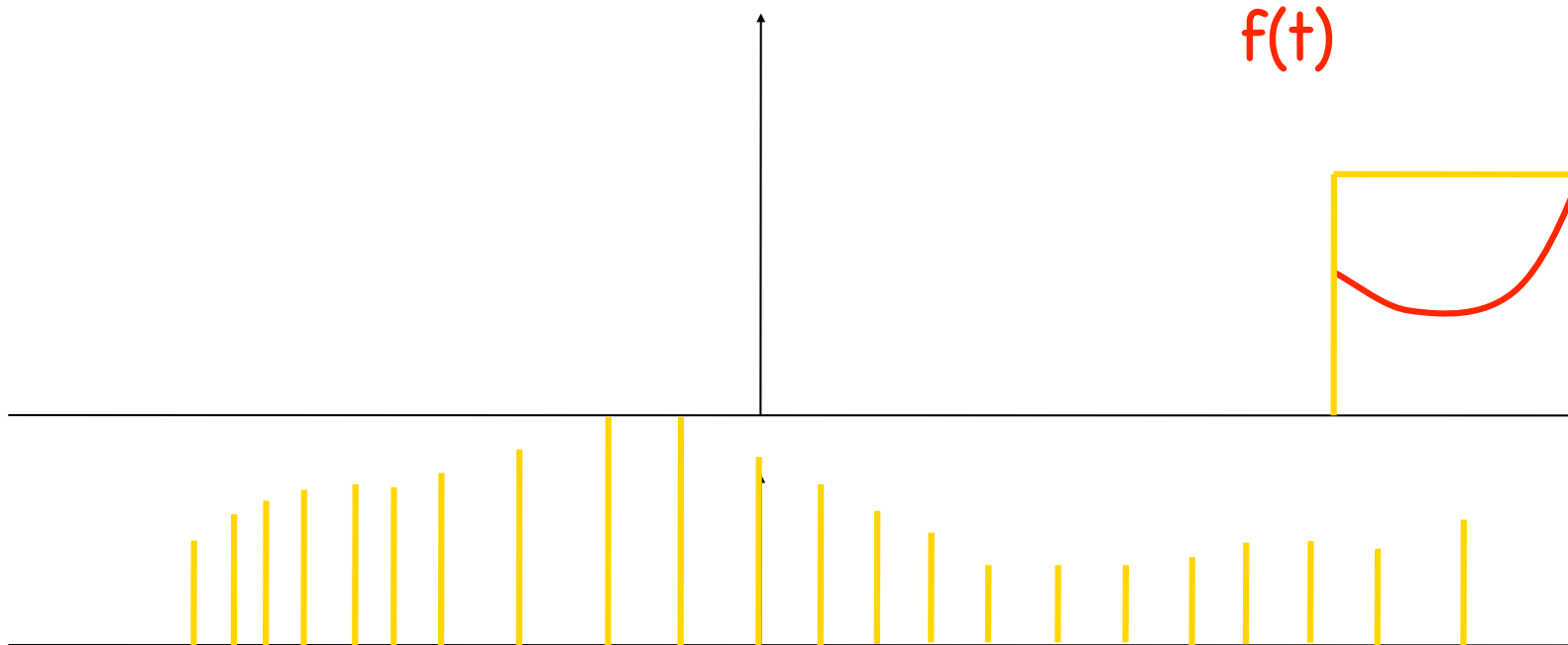
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# Convolution

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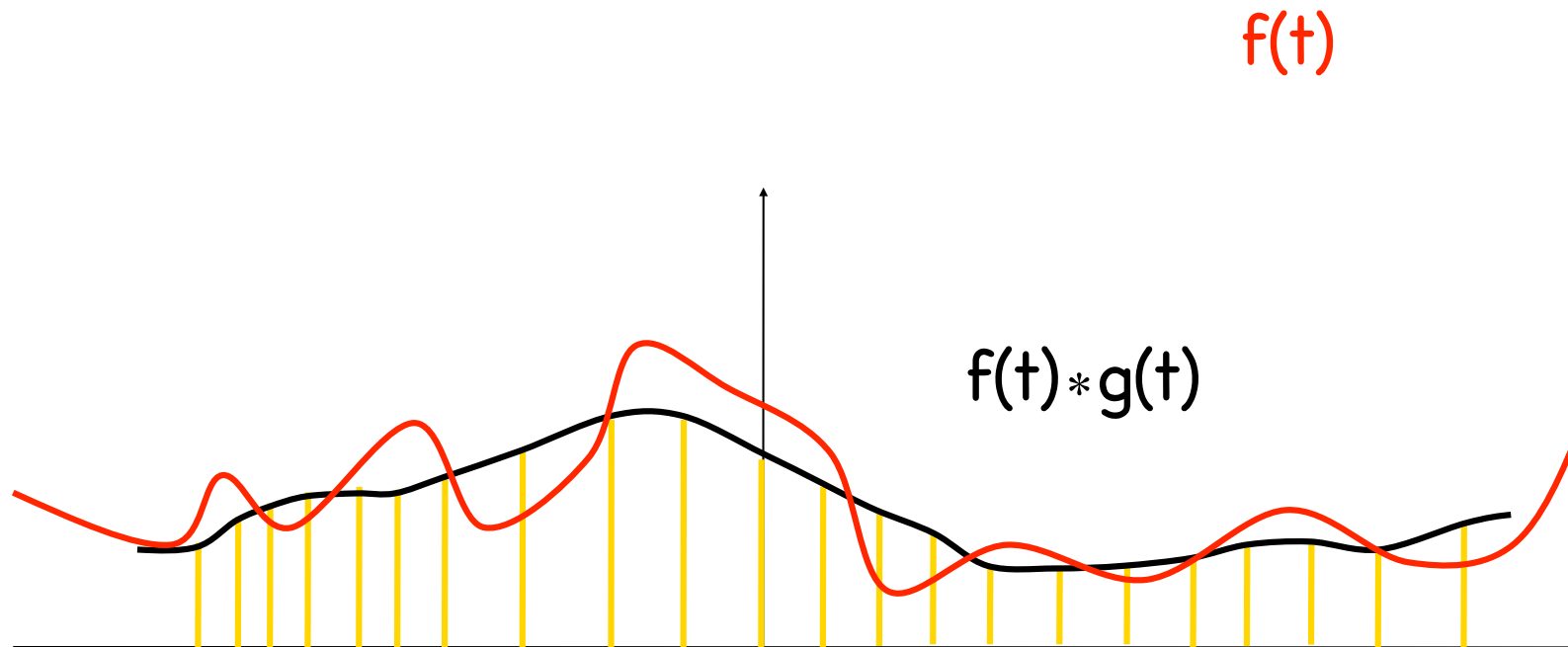
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# Convolution

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- This particular convolution smooths out some of the high frequencies in  $f(t)$ .



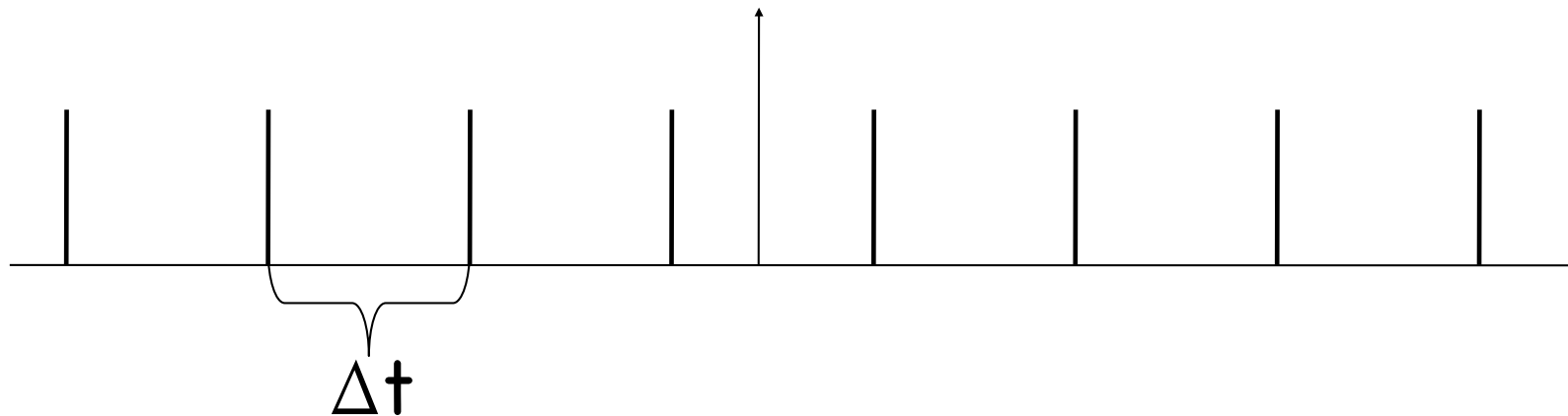
# Sampling Function

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- A Sampling Function or Impulse Train is defined by:

$$S_T(t) = \sum_{k=-\infty}^{\infty} \delta(t - k\Delta t)$$

where  $\Delta t$  is the sample spacing.



# Sampling Function

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- The Fourier Transform of the Sampling Function is itself a sampling function.
- The sample spacing is the inverse.

$$S_{\Delta t}(t) \Leftrightarrow S_{\frac{1}{\Delta t}}(\omega)$$



# Convolution Theorem

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- The convolution theorem states that convolution in the temporal domain is equivalent to multiplication in the frequency domain, and viceversa.

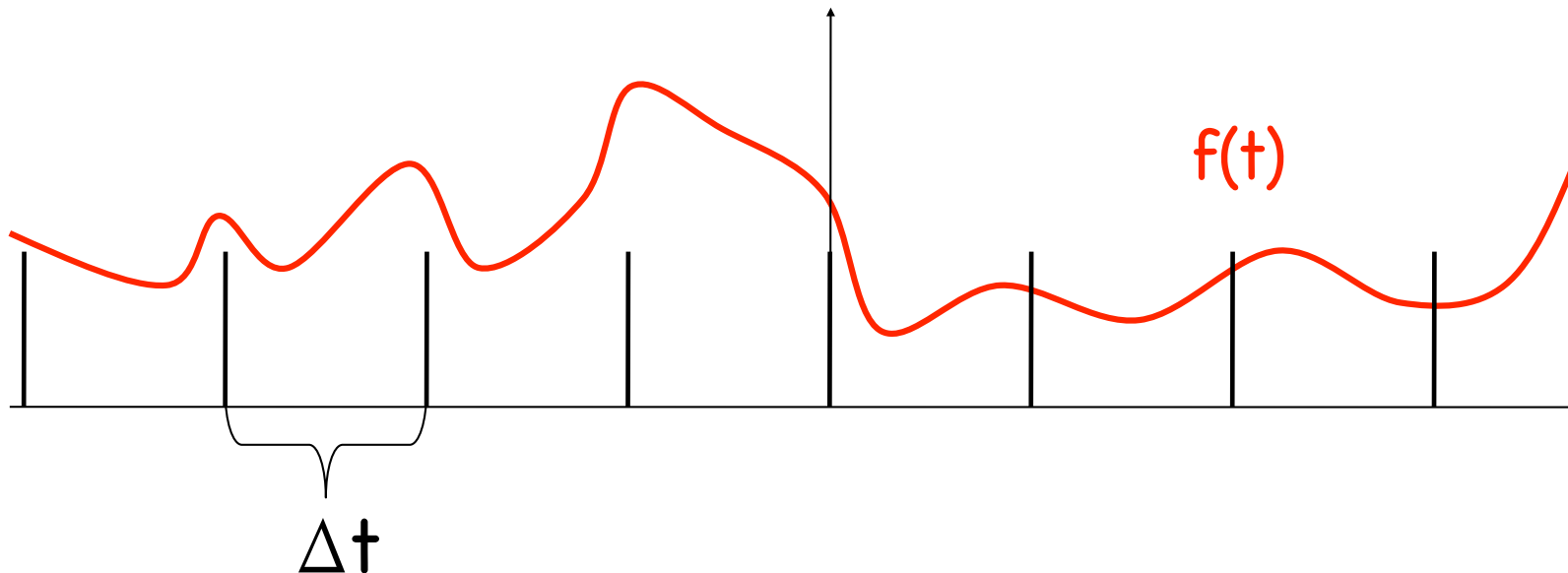
$$f(t) * g(t) \Leftrightarrow F(\omega) \cdot G(\omega)$$

$$f(t) \cdot g(t) \Leftrightarrow F(\omega) * G(\omega)$$

# Convolution Theorem

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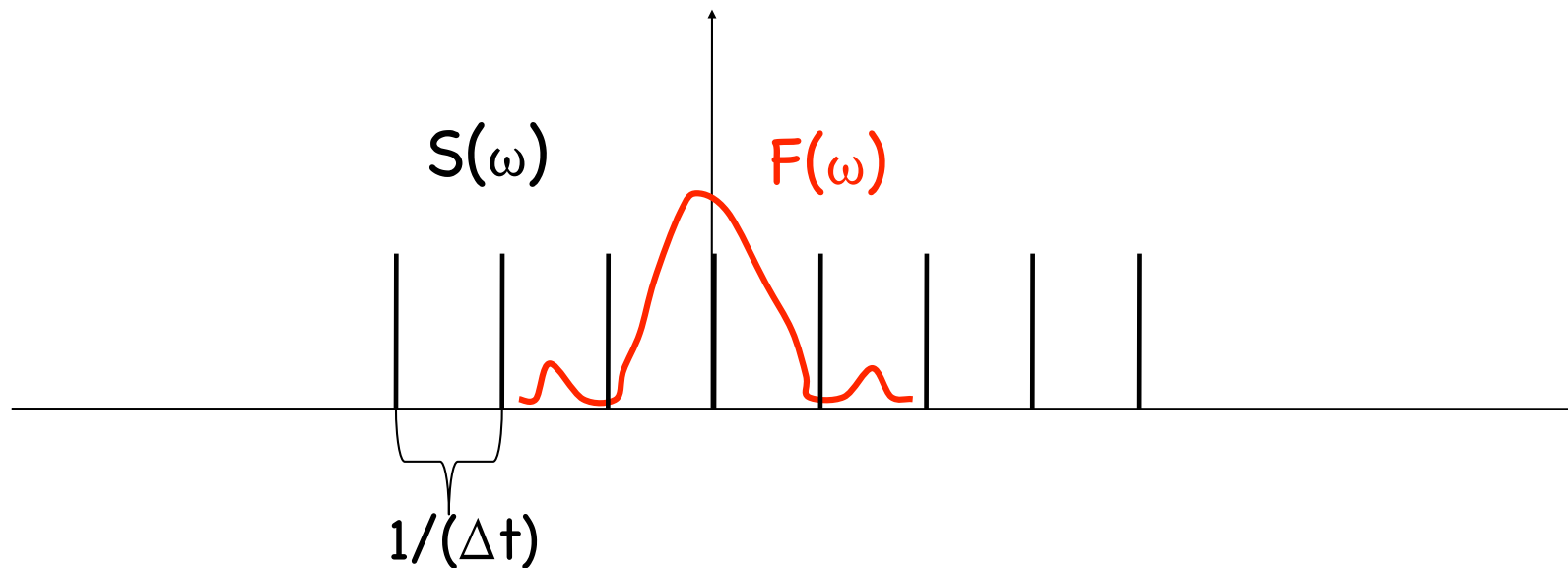
- This powerful theorem can illustrate the problems with our point sampling and provide guidance on avoiding aliasing.
- Consider:  $f(t) \cdot S_{\Delta t}(t)$



# Convolution Theorem

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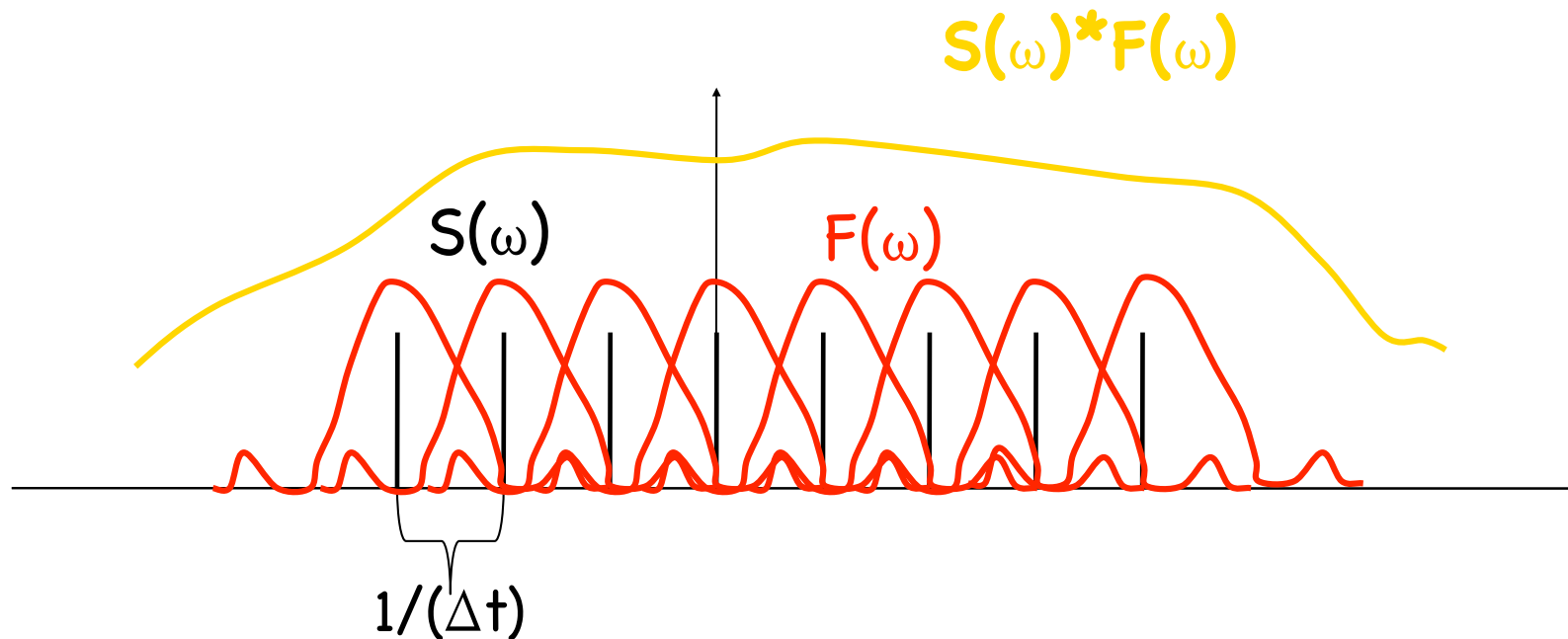
- What does this look like in the Fourier domain?



# Convolution Theorem

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- In Fourier domain we would convolve



# Aliasing

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- What this says, is that any frequencies greater than a certain amount will appear intermixed with other frequencies.
- In particular, the higher frequencies for the copy at  $1/\Delta t$  intermix with the low frequencies centered at the origin.

# Aliasing and Sampling

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- Note, that the sampling process introduces frequencies out to infinity.
- We have also lost the function  $f(t)$ , and now have only the discrete samples.
- This brings us to our next powerful theory.

# Sampling Theorem

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## ● The Shannon Sampling Theorem:

A band-limited signal  $f(t)$ , with a cutoff frequency of  $\lambda$ , that is sampled with a sampling spacing of  $\Delta t$  may be perfectly reconstructed from the discrete values  $f[n\Delta t]$  by convolution with the sinc(t) function, provided the Nyquist limit:  $\lambda < 1/(2\Delta t)$

## ● Why is this?

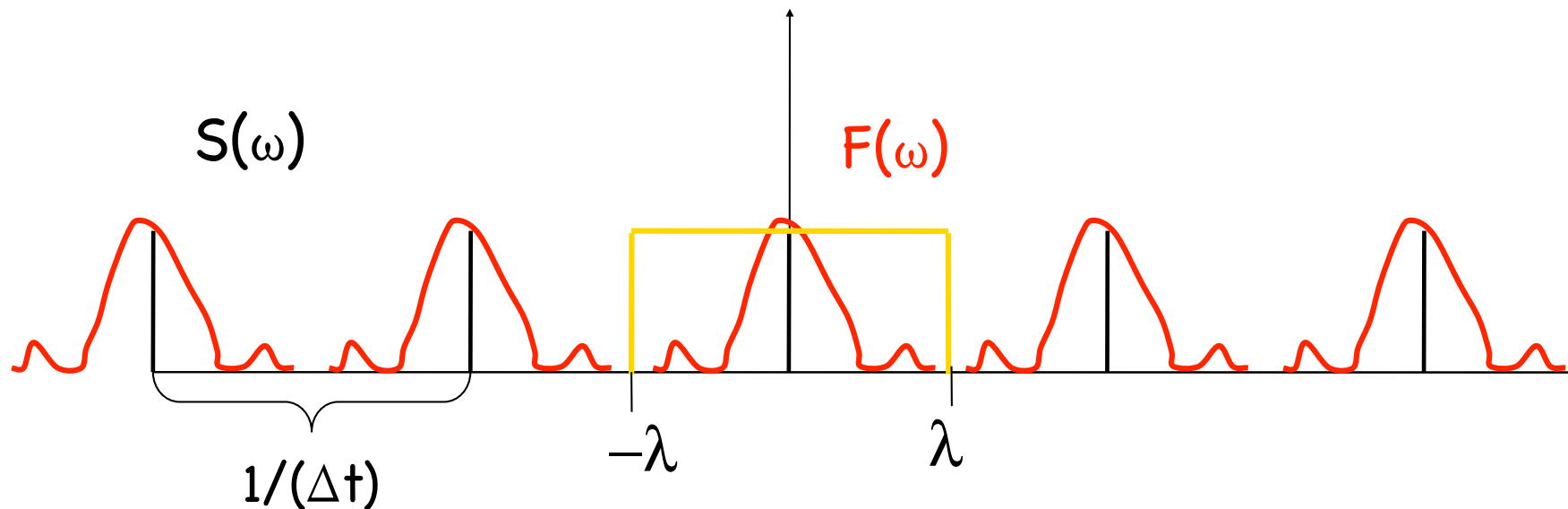
The Nyquist limit will ensure that the copies of  $F(\omega)$  do not overlap in the frequency domain.

We can completely reconstruct or determine  $f(t)$  from  $F(\omega)$  using the Inverse Fourier Transform.

# Sampling Theory

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- In order to do this, we need to remove all of the shifted copies of  $F(\omega)$  first.
- This is done by simply multiplying  $F(\omega)$  by a box function of width  $2\lambda$ .

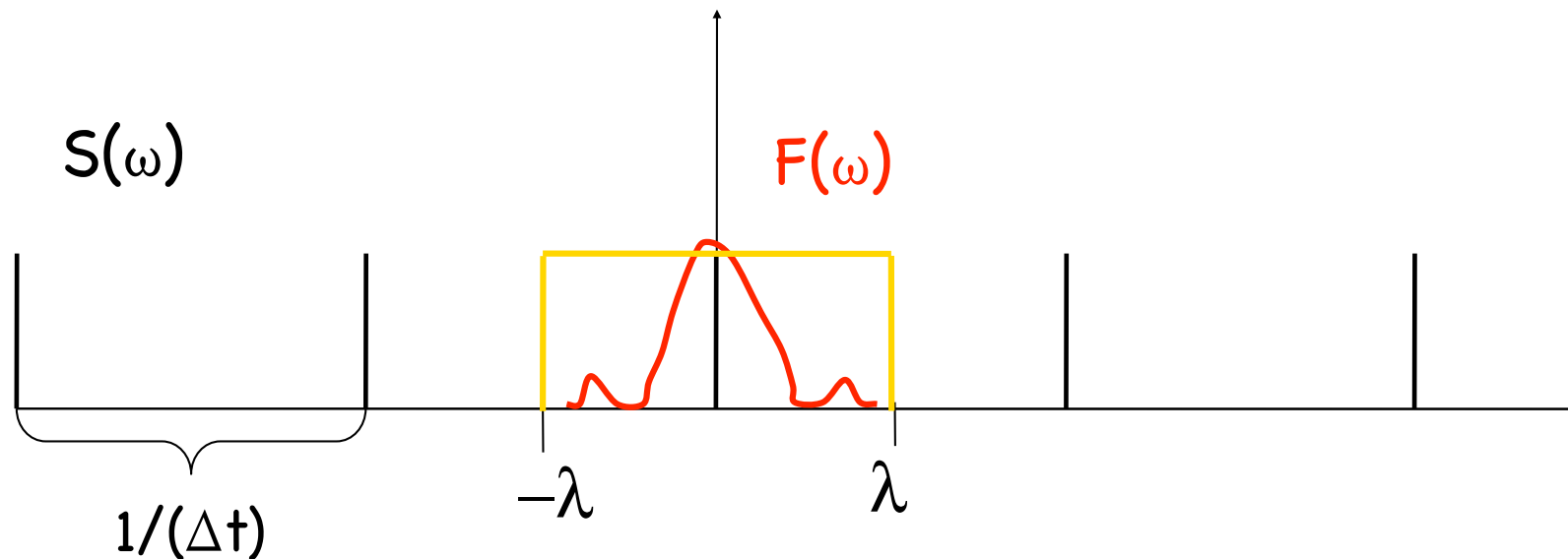




# Sampling Theory

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# Sampling Theory

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- So, given  $f[n\Delta t]$  and an assumption that  $f(t)$  does not have frequencies greater than  $1/(2\Delta t)$ , we can write the formula:

$$f[nT] = f(t) \cdot S_{\Delta t}(t) \Leftrightarrow F(\omega) * S_{\Delta t}(\omega)$$

$$F(\omega) = (F(\omega) * S_{\Delta t}(\omega)) \cdot \text{Box}_{1/(2\Delta t)}(\omega)$$

therefore,

$$f(t) = f[n\Delta t] * \text{sinc}(t)$$

<http://www.thefouriertransform.com/pairs/box.php>

[http://195.134.76.37/applets/AppletNyquist/Appl\\_Nyquist2.html](http://195.134.76.37/applets/AppletNyquist/Appl_Nyquist2.html)