

993SM - Laboratory of Computational Physics III week October 7, 2024

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numerical integration (now only deterministic methods: equispaced points & others)



Divide the integration interval into "small" intervals:

$$\Delta x = \frac{b-a}{n},$$

$$x_n = x_0 + n\,\Delta x.$$

(Note: *n* intervals \Leftrightarrow *n*+1 points)

Deterministic methods: rectangular rule



: The rectangular approximation for $f(x) = \cos x$ for $0 \le x \le \pi/2$.

Deterministic methods: rectangular rule - error



Rectangular approximations of the integral of $\cos x$ from x = 0 to $x = \pi/2$ as a function of n, the number of intervals. The error Δ_n is the difference between the rectangular approximation and the exact result of unity. Note that the error Δ_n decreases approximately as n^{-1} , that is, if n is increased by a factor of 2, Δ_n decreases by a factor 2.

Deterministic methods: generalities

- sum values of $f(x_i)$ with $x_i \in [a, b]$ we want to have $F = \int_a^b f(x) dx$ as accurate as possible a but with the minimum number of calculations of $f(x_i)$

OK simple algorithms, but if the number of calculations is too high, improve the algorithm!

Deterministic methods: trapezoidal rule

In one interval:

with error:

$$\int_{x_i}^{x_{i+1}} f(x)dx = h\left[\frac{1}{2}f_i + \frac{1}{2}f_{i+1}\right] \qquad \mathcal{O}(h^3 f'''), \propto 1/n^3$$

Applied iteratively over consecutive intervals:



Deterministic methods: Simpson's rule



Iteratively applied to the whole interval of integration (odd number of points!):

$$\int_{x_0}^{x_n} f(x)dx = h\left[\frac{1}{3}f_0 + \frac{4}{3}f_1 + \frac{2}{3}f_2 + \frac{4}{3}f_3 + \dots + \frac{2}{3}f_{n-2} + \frac{4}{3}f_{n-1} + \frac{1}{3}f_n\right] + \mathcal{O}(h^4 f^{IV}) (error \propto 1/n^4)$$

Errors in deterministic methods

Error estimate for numerical integration with deterministic methods

$$\int f(x)dx = F_n + error$$

How to evaluate the error? Consider the Taylor expansion of the integrand function and then integrate:

$$f(x) = f(x_i) + f'(x_i)(x - x_i) + \frac{1}{2}f''(x_i)(x - x_i)^2 + \dots, (*)$$

$$\int_{x_i}^{x_{i+1}} f(x) \, dx = f(x_i) \Delta x + \frac{1}{2} f'(x_i) (\Delta x)^2 + \frac{1}{6} f''(x_i) (\Delta x)^3 + \dots (**)$$
$$\Delta x \equiv x_{i+1} - x_i$$

Error estimate for numerical integration: Rectangular approximation

$$\int_{x_i}^{x_{i+1}} f(x) dx \approx f(x_i) \Delta x$$

Compare with (**):

$$\int_{x_i}^{x_{i+1}} f(x) \, dx = f(x_i) \Delta x + \frac{1}{2} \frac{f'(x_i) (\Delta x)^2}{6} + \frac{1}{6} f''(x_i) (\Delta x)^3 + \dots$$

(leading order in Δx)

For n intervals $(\Delta x = (b-a)/n)$: error is $n(\Delta x)^2 \sim 1/n$

Error estimate for numerical integration: Trapezoidal approximation

Compare with (**): $\int_{x_i}^{x_{i+1}} f(x) \, dx = f(x_i) \Delta x + \frac{1}{2} f'(x_i) (\Delta x)^2 + \frac{1}{6} \frac{f''(x_i) (\Delta x)^3}{\text{error}} + \dots$ error (leading order in Δx)

For n intervals: error is $n(\Delta x)^3 \sim 1/n^2$

Compare with (**): $\int_{x_{i}}^{x_{i+2}} f(x)dx = f(x_{i})\Delta x + \frac{1}{2!}f'(x_{i})(\Delta x)^{2} + \frac{1}{3!}f''(x_{i})(\Delta x)^{3} + \frac{1}{4!}f'''(x_{i})(\Delta x)^{4} + \frac{1}{5!}f''''(x_{i})(\Delta x)^{5} + \dots$ error (leading order in Δx)

For n intervals: error is $n(\Delta x)^5 \sim 1/n^4$

Numerical integration - deterministic methods: comparison of errors in ID



Deterministic methods - I

We use a piecewise polynomial interpolation:



NOT CONVENIENT! Warning: using higher degrees does not always improve accuracy!

(see also: Runge phenomenon (polynomial interpolation, oscillation at the edges of an interval), Gibbs phenomenon ...)

Deterministic methods - II



Other deterministic methods

Numerical integration; other deterministic methods:

• in the simplest equally-spaced-point methods, we choose weights to calculate the average of the function:

$$\int_{a}^{b} f(x)dx \approx F_{N} = \sum_{i=1}^{N} v_{i}f(x_{i})$$
rectangular rule: $x_{i} = a + \frac{b-a}{N}i$, $v_{i} = \frac{b-a}{N} \quad \forall i = 1, \dots N-1$
trapezoidal rule: $x_{i} = a + \frac{b-a}{N}i$, $v_{i} = \frac{b-a}{N} \quad \forall i \neq 1, N; \quad v_{1} = v_{N} = \frac{b-a}{2N}$
...

(at variance with these methods, in MC methods such as the 'importance sampling', we choose only points, not weights)

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Numerical integration; other deterministic methods:

 in the simplest equally-spaced-point methods, we choose weights to calculate the average of the function:

$$\int_{a}^{b} f(x)dx \approx F_{N} = \sum_{i=1}^{N} v_{i}f(x_{i})$$

idea: choose not only weights but also points: more degrees of freedom!

$$x_i =?, v_i =?$$

Another deterministic method: Gaussian quadrature - I Consider $\int_{a}^{b} f(x) dx$ and a function W(x) defined on [a, b]We can always formally write:

$$\int f(x)dx = \int W(x)F(x)dx \approx \sum_{j=1}^{N} w_j F(x_j) = \sum_{j=1}^{N} w_j \frac{f(x_j)}{W(x_j)} = \sum_{j=1}^{N} v_j f(x_j)$$

with $v_j = w_j/W(x_j)$

to be determined, depending on W(x) (*)

(This will be convenient in particular if the resulting F(x) is smooth, but not necessarily)

(*) in general: $w_j \neq W(x_j)$

Another deterministic method: Gaussian quadrature - II Consider $\int_{a}^{b} f(x) dx$ and a function W(x) defined on [a, b]We can always formally write:

$$\int f(x)dx = \int W(x)F(x)dx \approx \sum_{j=1}^{N} w_j F(x_j) = \sum_{j=1}^{N} w_j \frac{f(x_j)}{W(x_j)} = \sum_{j=1}^{N} v_j f(x_j)$$

For a given W(x), the N points and weights $\{x_j\}, \{w_j\}$ can be chosen to make the approximate relationship (*) an exact equality if F(x) is a 2N-1 degree polynomial.

Another deterministic method: Gaussian quadrature - III

Consider
$$\int_{x_1}^{x_2} W(x)F(x)dx = \sum_{j=1}^N w_jF(x_j)$$

F(x) a 2N - I degree polynomial. Which are the N $\{x_j\}, \{w_j\}$?

If there is a set of polynomials $\{p_N(x)\}$ which are orthogonal in the same interval and for the same weight function W(x):

 $\langle p_N | p_{N'} \rangle_W = \delta_{N,N'}$, *i.e.*, $\int_{x_1}^{x_2} W(x) p_N(x) p_{N'}(x) dx = \delta_{N,N'}$ the points $\{x_i\}$ are exactly the roots of the $p_N(x)$ polynomials. The weights $\{w_j\}$ are related to them, but in general $w_j \neq W(x_j)$.

Gauss-Legendre quadrature

Consider
$$\int_{x_1}^{x_2} W(x)F(x)dx = \sum_{j=1}^N w_jF(x_j)$$

with $F(x)$ a 2N - I degree polynomial.

If: W(x) = 1 and $x_1 = -1, x_2 = 1$, the Legendre polynomials $\{P_N(x)\}$ defined by: $(j+1)P_{j+1} = (2j+1)xP_j - jP_{j-1}$

are orthogonal in [-1,1] with W(x)=1; $\{x_i\}, \{w_i\}$ are such that $P_N(x_i) = 0$ and 2 $w_i = \frac{1}{(1 - x_i^2)[P'_N(x_i)]^2}$

The first few Legendre polynomials are:

polynomials are odd or even in $x \implies$ roots are even

Legendre polynomials in Physics: examples of applications

I) For a polynomial expansion of a gravitational or coulombic potential:

$$rac{1}{|{f x}-{f x}'|} = rac{1}{\sqrt{r^2+r'^2-2rr'\cos\gamma}} = \sum_{\ell=0}^\infty rac{r'^\ell}{r^{\ell+1}} P_\ell(\cos\gamma)$$

where r and r' are the lengths of the vectors x and x' respectively and γ is the angle between those two vectors.

2) solution of Laplace's equation of the static potential, $\nabla^2 \Phi(\mathbf{x}) = 0$, in a charge-free region of space, if the boundary conditions have axial symmetry :

 θ is the angle between the position of the observer and the \hat{z} axis (the zenith angle);

the solution for the potential will be

$$\Phi(r, heta) = \sum_{\ell=0}^\infty \left[A_\ell r^\ell + B_\ell r^{-(\ell+1)}
ight] P_\ell(\cos heta)$$

solving Schrödinger equation in three dimensions for a central force :

the **associated Legendre polynomials** are derivatives of ordinary Legendre polynomials ($m \ge 0$)

$$P_\ell^m(x) = (-1)^m (1-x^2)^{m/2} rac{d^m}{dx^m} \left(P_\ell(x)
ight)_{\ell}$$

The Legendre polynomials are closely related to the spherical harmonics

$$Y_{\ell,m}(heta,\phi) = \sqrt{rac{(2\ell+1)(\ell-m)!}{4\pi(\ell+m)!}} \ P_\ell^m(\cos heta) \ e^{im\phi} \qquad -\ell \leq m \leq \ell.$$

Gaussian quadrature

In practice, we choose W(x) and N and use the set of N points and weights $\{x_j\}, \{w_j\}$ for the approximate integration:

$$\int f(x)dx = \int W(x)F(x)dx \approx \sum_{j=1}^{N} w_j F(x_j) = \sum_{j=1}^{N} w_j \frac{f(x_j)}{W(x_j)} = \sum_{j=1}^{N} v_j f(x_j)$$

Gauss-Legendre quadrature

Gauss-Legendre quadrature

In case of classical, well known, orthogonal polynomials, ready-to-use subroutines exist for the computation of Abscissas and Weights $\{x_j\}, \{w_j\}$

e.g. GAULEG(x_1, x_2, x, w, n) of Numerical Recipes which, given x_1, x_2, n , provides as output the arrays x(n), w(n)

Some programs:

on https://moodle2.units.it/

int.f90 (trapeziodal and Simpson integration)
gauleg-llorder.f90
gauleg-others.f90 (generation of points up to 15 points
in [-1,1] using GAULEG adapted from "Numerical Recipes" (selfcontained) and some tests for easy-to-integrate functions)

In the subdirectory: gauss-nr90/ find the original routine from "Numerical Recipes" and related external routines/modules/interfaces and a main program for test (see following slide)

Gauss-Legendre from Numerical Recipes

Use of GAULEG:

In order to use the routines of Numerical Recipes, you have to compile and link the main program with:

- the subroutine **gauleg.f90** which gives points and abscissas
- **nrtype.f90** containing type declarations;
- **nrutil.f90** containing **moduli** and utilities;
- **nr.f90** containing (through the interfaces) the conventions to call the subroutines with the main program

i) You must first compile these files with the option "-c":

this produces .mod and .o (the objects).

ii) In a second step compile the main program.

iii) Finally you link all the files *.o and produce the executable:

gfortran -c nrtype.f90 nrutil.f90 nr.f90 gauleg.f90 gfortran -c gauleg_nr_test.f90 gfortran -o a.out gauleg_nr_test.o nrtype.o nrutil.o nr.o gauleg.o

```
SUBROUTINE gauleg(x1,x2,x,w)
```

```
USE nrtype; USE nrutil, ONLY : arth,assert_eq,nrerror IMPLICIT NONE
```

```
REAL(SP), INTENT(IN) :: x1,x2
 REAL(SP), DIMENSION(:), INTENT(OUT) :: x,w
 REAL(DP), PARAMETER :: EPS=3.0e-14_dp
 INTEGER(I4B) :: its,j,m,n
  INTEGER(I4B), PARAMETER :: MAXIT=10
 REAL(DP) :: x1,xm
 REAL(DP), DIMENSION((size(x)+1)/2) :: p1,p2,p3,pp,z,z1
 LOGICAL(LGT), DIMENSION((size(x)+1)/2) :: unfinished
 n=assert_eq(size(x),size(w),'gauleg')
 m = (n+1)/2
 xm=0.5_dp*(x2+x1)
 xl=0.5_dp*(x2-x1)
 z=cos(PI_D*(arth(1,1,m)-0.25_dp)/(n+0.5_dp))
    ...
    ...
    ...
  x(1:m)=xm-xl*z
  x(n:n-m+1:-1)=xm+xl*z
  w(1:m)=2.0_dp*x1/((1.0_dp-z**2)*pp**2)
  w(n:n-m+1:-1) = w(1:m)
END SUBROUTINE gauleg
```

```
MODULE nrtype
  INTEGER, PARAMETER :: I4B = SELECTED_INT_KIND(9)
  INTEGER, PARAMETER :: I2B = SELECTED_INT_KIND(4)
  INTEGER, PARAMETER :: I1B = SELECTED_INT_KIND(2)
  INTEGER, PARAMETER :: SP = KIND(1.0)
  INTEGER, PARAMETER :: DP = KIND(1.0D0)
  INTEGER, PARAMETER :: SPC = KIND((1.0, 1.0))
  INTEGER, PARAMETER :: DPC = KIND((1.0D0,1.0D0))
  INTEGER, PARAMETER :: LGT = KIND(.true.)
  REAL(SP), PARAMETER :: PI=3.141592653589793238462643383279502884197_sp
  REAL(SP), PARAMETER :: PI02=1.57079632679489661923132169163975144209858_sp
  REAL(SP), PARAMETER :: TWOPI=6.283185307179586476925286766559005768394_sp
  REAL(SP), PARAMETER :: SQRT2=1.41421356237309504880168872420969807856967_sp
  REAL(SP), PARAMETER :: EULER=0.5772156649015328606065120900824024310422_sp
  REAL(DP), PARAMETER :: PI_D=3.141592653589793238462643383279502884197_dp
  REAL(DP), PARAMETER :: PI02_D=1.57079632679489661923132169163975144209858_dp
  REAL(DP), PARAMETER :: TWOPI_D=6.283185307179586476925286766559005768394_dp
  TYPE sprs2_sp
     INTEGER(I4B) :: n,len
     REAL(SP), DIMENSION(:), POINTER :: val
     INTEGER(I4B), DIMENSION(:), POINTER :: irow
     INTEGER(I4B), DIMENSION(:), POINTER :: jcol
  END TYPE sprs2_sp
  TYPE sprs2_dp
     INTEGER(I4B) :: n,len
     REAL(DP), DIMENSION(:), POINTER :: val
     INTEGER(I4B), DIMENSION(:), POINTER :: irow
     INTEGER(I4B), DIMENSION(:), POINTER :: jcol
  END TYPE sprs2_dp
END MODULE nrtype
```

nr.f90 from Numerical Recipes

MODULE nr INTERFACE SUBROUTINE gauleg(x1,x2,x,w) USE nrtype REAL(SP), INTENT(IN) :: x1,x2 REAL(SP), DIMENSION(:), INTENT(OUT) :: x,w END SUBROUTINE gauleg END INTERFACE ! ... the original file contains several other INTERFACES ...

END MODULE nr

nrutil.f90 (Here only for: array_copy, arth, assert_eq, nrerror)

MODULE nrutil USE nrtype IMPLICIT NONE INTEGER(I4B), PARAMETER :: NPAR_ARTH=16,NPAR2_ARTH=8

•••

INTERFACE array_copy

MODULE PROCEDURE array_copy_r, array_copy_d, array_copy_i END INTERFACE

•••

! ... l'originale contiene ancora molte altre INTERFACEs.... CONTAINS

```
SUBROUTINE array_copy_r(src,dest,n_copied,n_not_copied)
    REAL(SP), DIMENSION(:), INTENT(IN) :: src
```

•••

! and many other FUNCTIONs and SUBROUTINEs END MODULE nrutil

Numerical integration, deterministic methods: comparison of errors in ID

(double precision needed to appreciate the convergence of Gauss-Legendre numerical estimate)