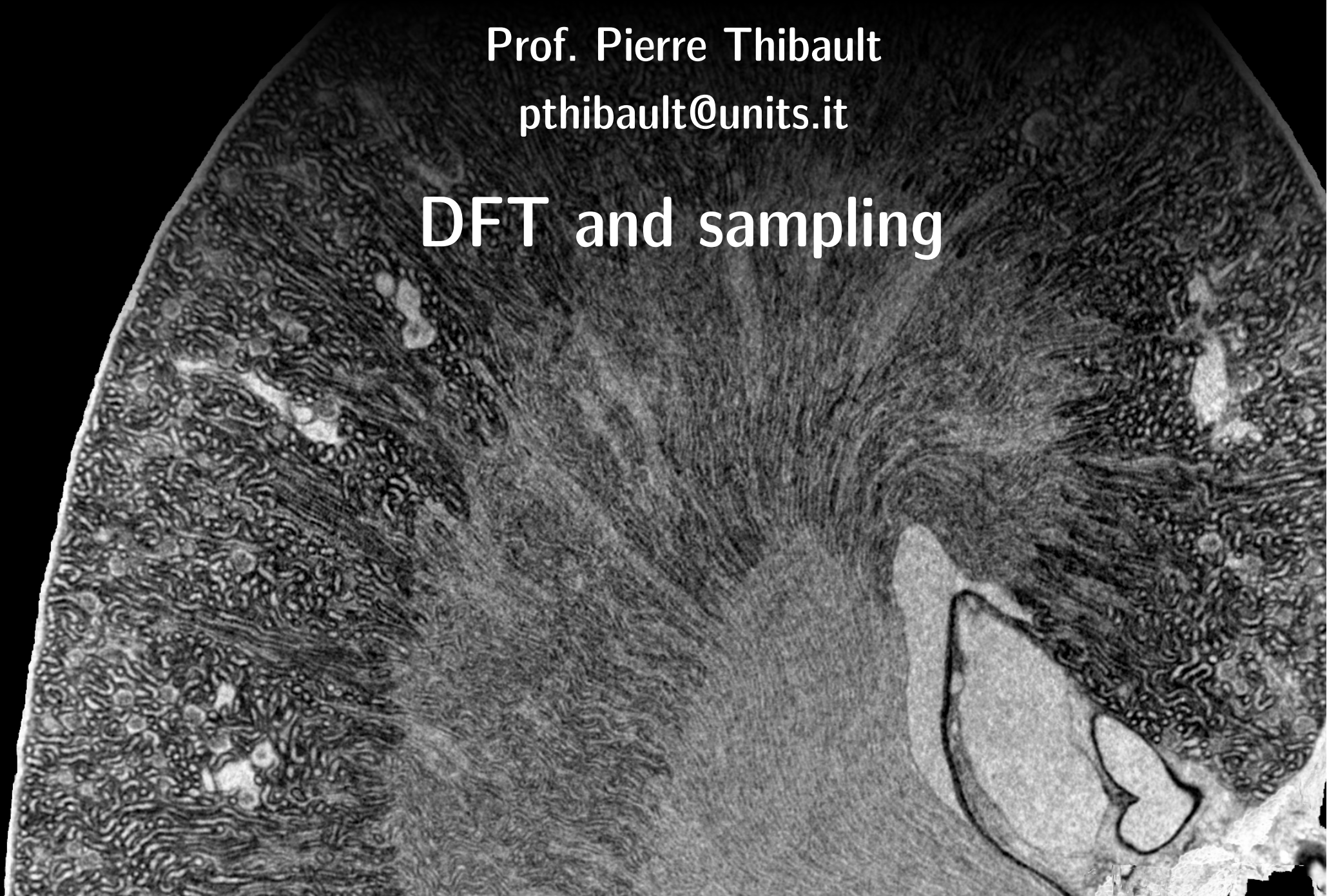


# Image Processing for Physicists

Prof. Pierre Thibault

[pthibault@units.it](mailto:pthibault@units.it)

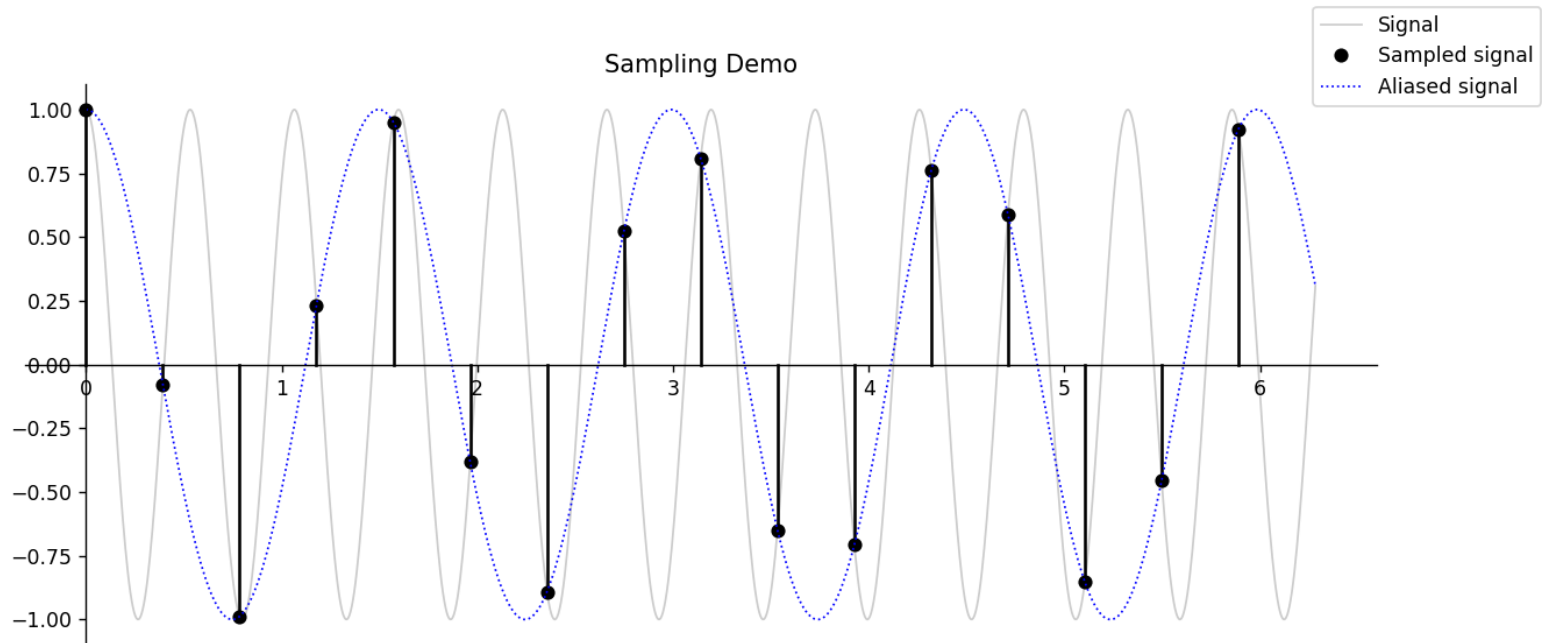
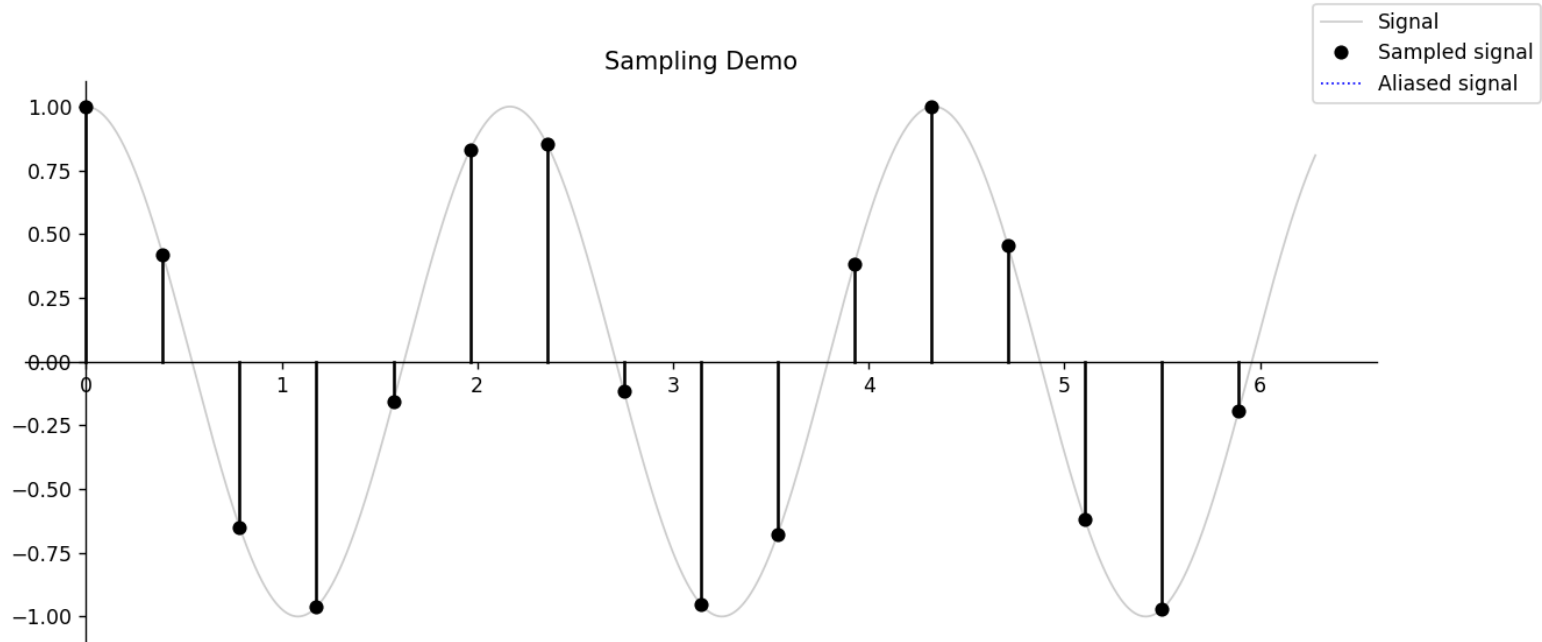
## DFT and sampling



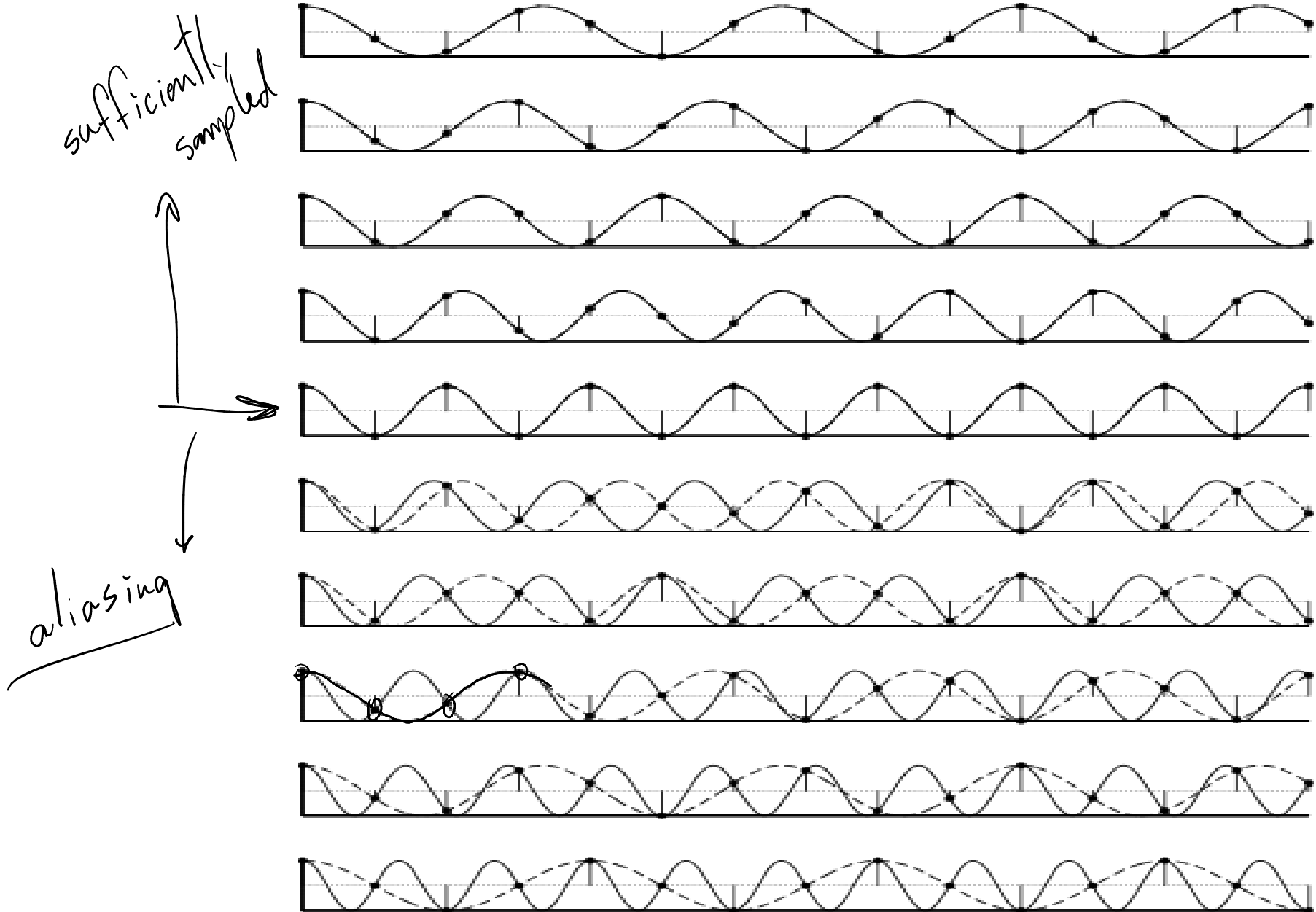
# Overview

- Sampling
  - Nyquist theorem
- Discrete Fourier transform
  - Undersampling and Aliasing
- Interpolation (resampling)

# Sampling



# Undersampling and aliasing



# The Nyquist-Shannon sampling theorem

“The largest frequency that can be represented in a signal sampled at intervals  $s$  is  $1/2s$ ”

sampling frequency }  
sampling rate }  $f = \frac{1}{s}$

$$\text{maximum frequency} = \frac{f}{2}$$

# Periodic signals

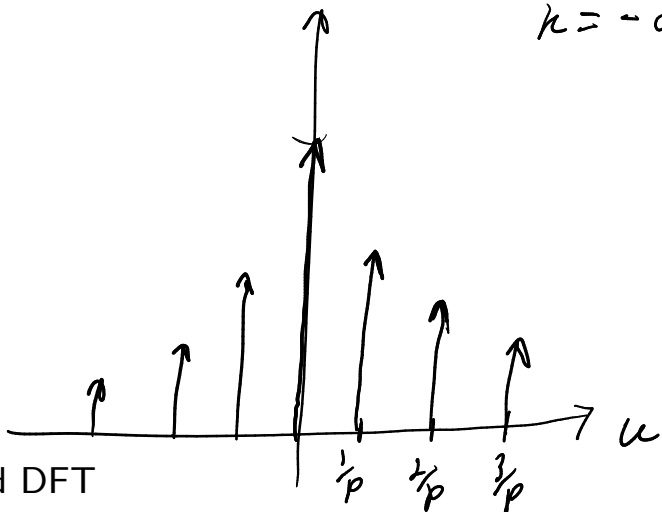
$f(x)$ : periodic with period  $p$

$$f(x) = \sum_{k=-\infty}^{\infty} C_k e^{2\pi i x \frac{k}{p}} \quad \leftarrow \text{Fourier series}$$

What is the continuous Fourier transform of  $f$ ?

$$F(u) = \int_{-\infty}^{\infty} f(x) e^{-2\pi i u x} dx = \int_{-\infty}^{\infty} \sum_{k=-\infty}^{\infty} C_k e^{2\pi i x \frac{k}{p} - 2\pi i u x} dx$$

$$= \sum_{k=-\infty}^{\infty} C_k \int_{-\infty}^{\infty} e^{2\pi i x (\frac{k}{p} - u)} dx = \sum_{k=-\infty}^{\infty} C_k \delta(u - \frac{k}{p})$$

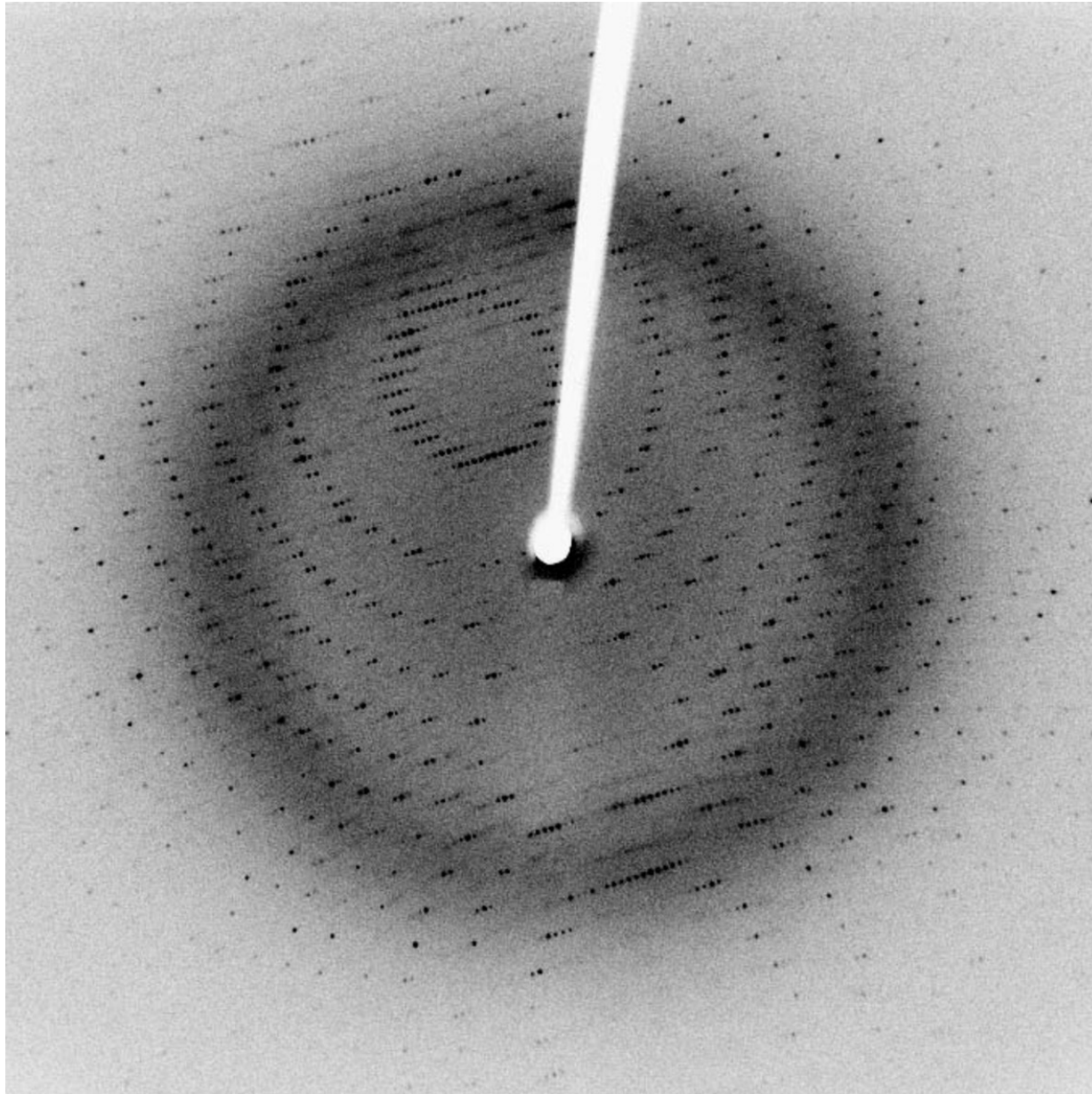


Sampling and DFT

F.T. of a periodic signal has non-zero amplitudes at discrete values of  $u$  located at multiples of  $\frac{1}{p}$

# Periodic signals

## X-ray diffraction by a crystal

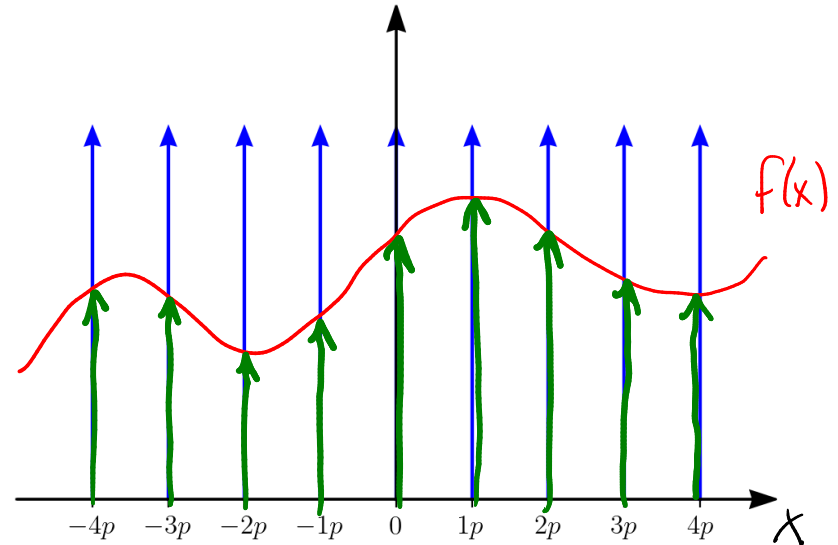


Bragg peaks  
↙

# Sampling with the Dirac comb

A periodic function made of Dirac functions

$$\Delta_p(x) = \sum_{n=-\infty}^{\infty} \delta(x - np)$$



$\Delta_p(x)$  can be used to represent the sampling process. For a function  $f(x)$

$$f(x) \Delta_p(x) = \sum_{n=-\infty}^{\infty} f(x) \delta(x - np) = \sum_{n=-\infty}^{\infty} f(np) \delta(x - np)$$



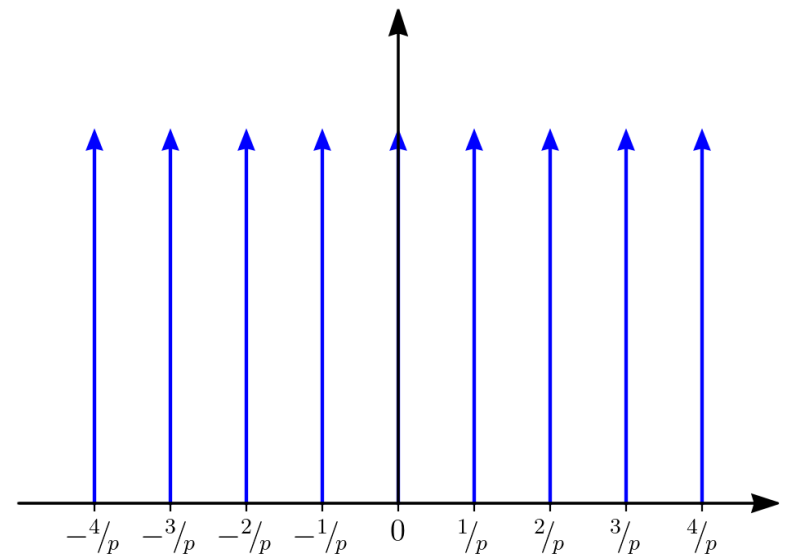
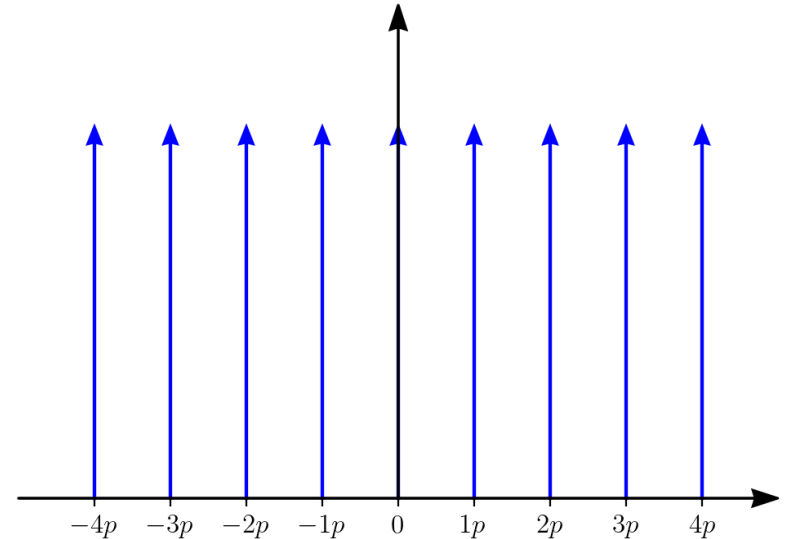
# Fourier transform of a Dirac comb

Fourier series of  $\Delta_p(x)$

$$c_k = \int_{-p/2}^{p/2} \Delta_p(x) e^{-2\pi i k x/p} dx$$
$$= 1$$

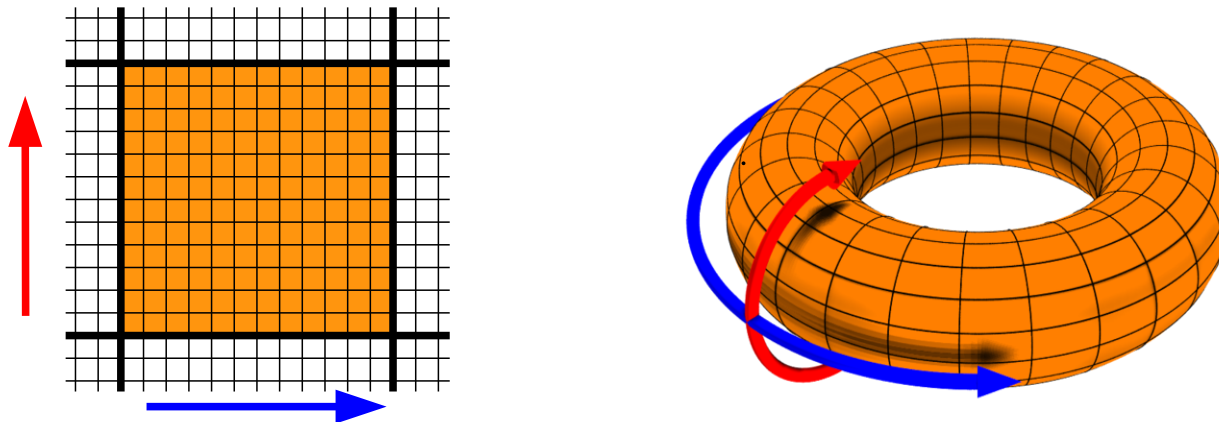
$$\Rightarrow \mathcal{F}\{\Delta_p(x)\} = \Delta_{\frac{1}{p}}(u)$$

Fourier transform of a Dirac comb is another Dirac comb



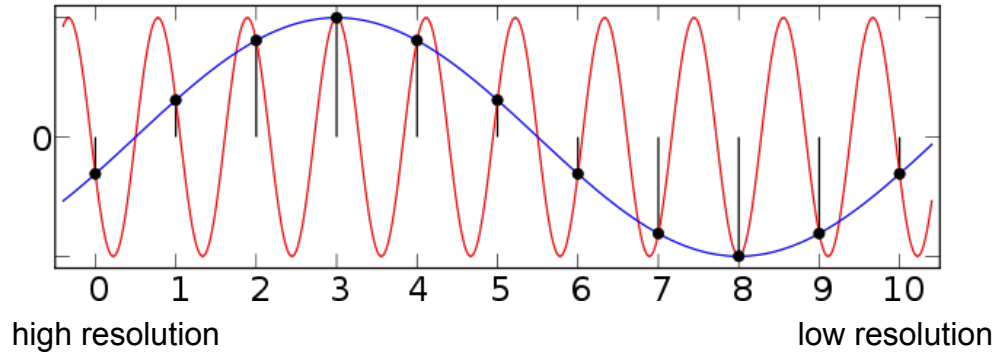
# Discrete Fourier Transform

- A **periodic** function has a **discrete** spectrum in the Fourier domain;
  - A function with **discrete** values in the spatial domain is **periodic** in the Fourier domain;
- ⇒ A periodic and discrete function has a periodic and discrete Fourier transform.



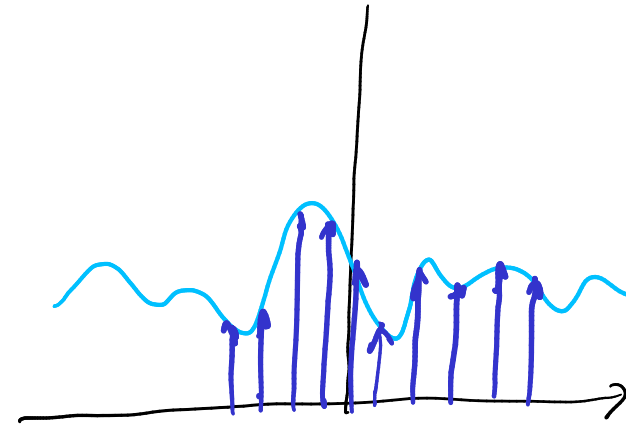
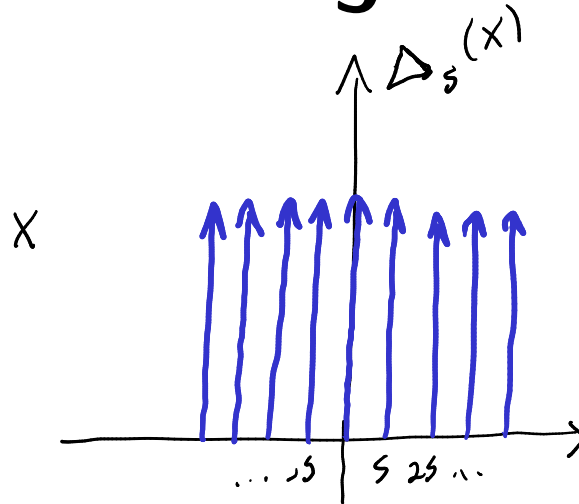
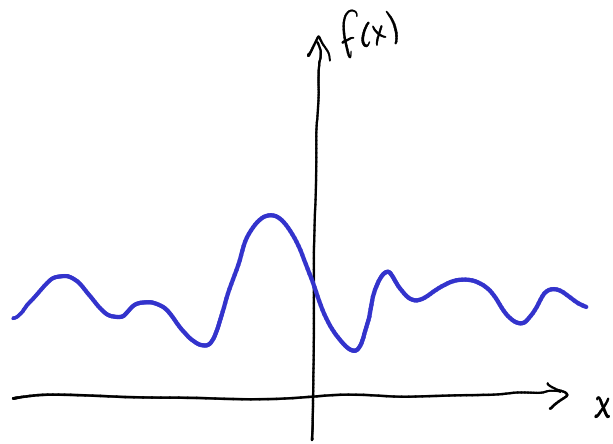
# Aliasing

Moiré: after resampling, high spatial frequencies appear as low spatial frequencies



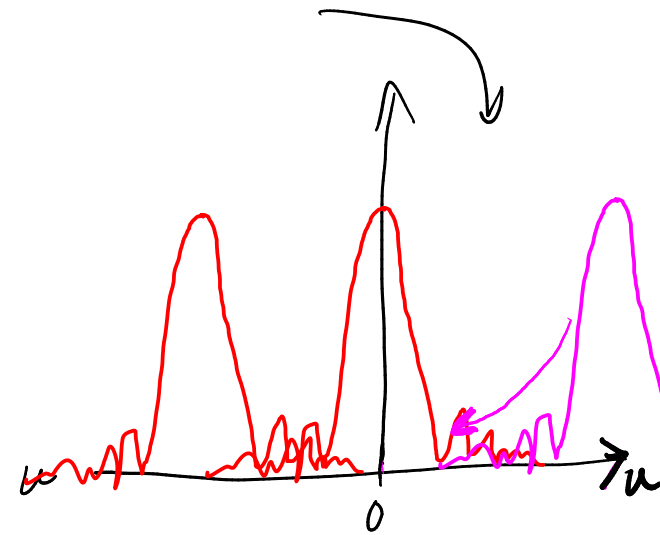
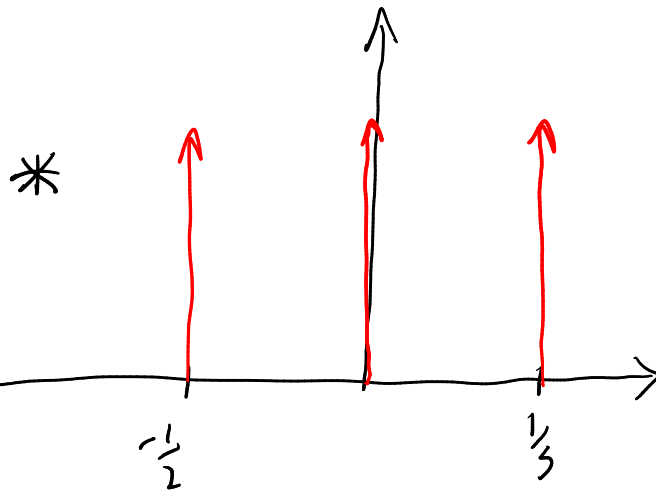
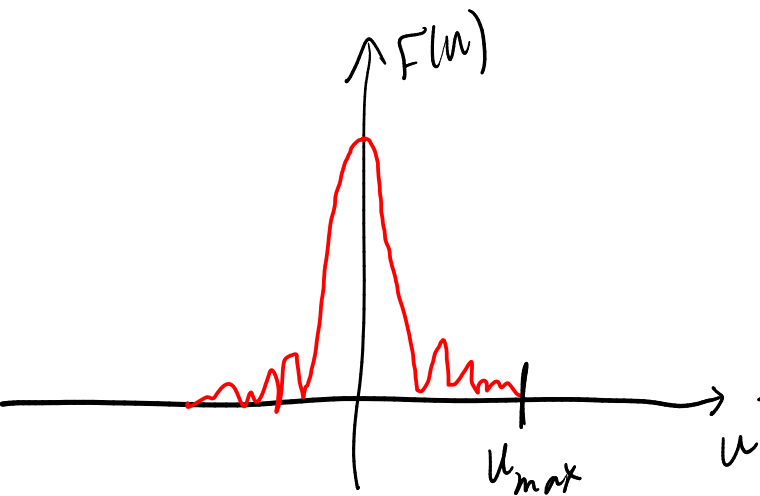
source: <http://wikipedia.org>

# Aliasing



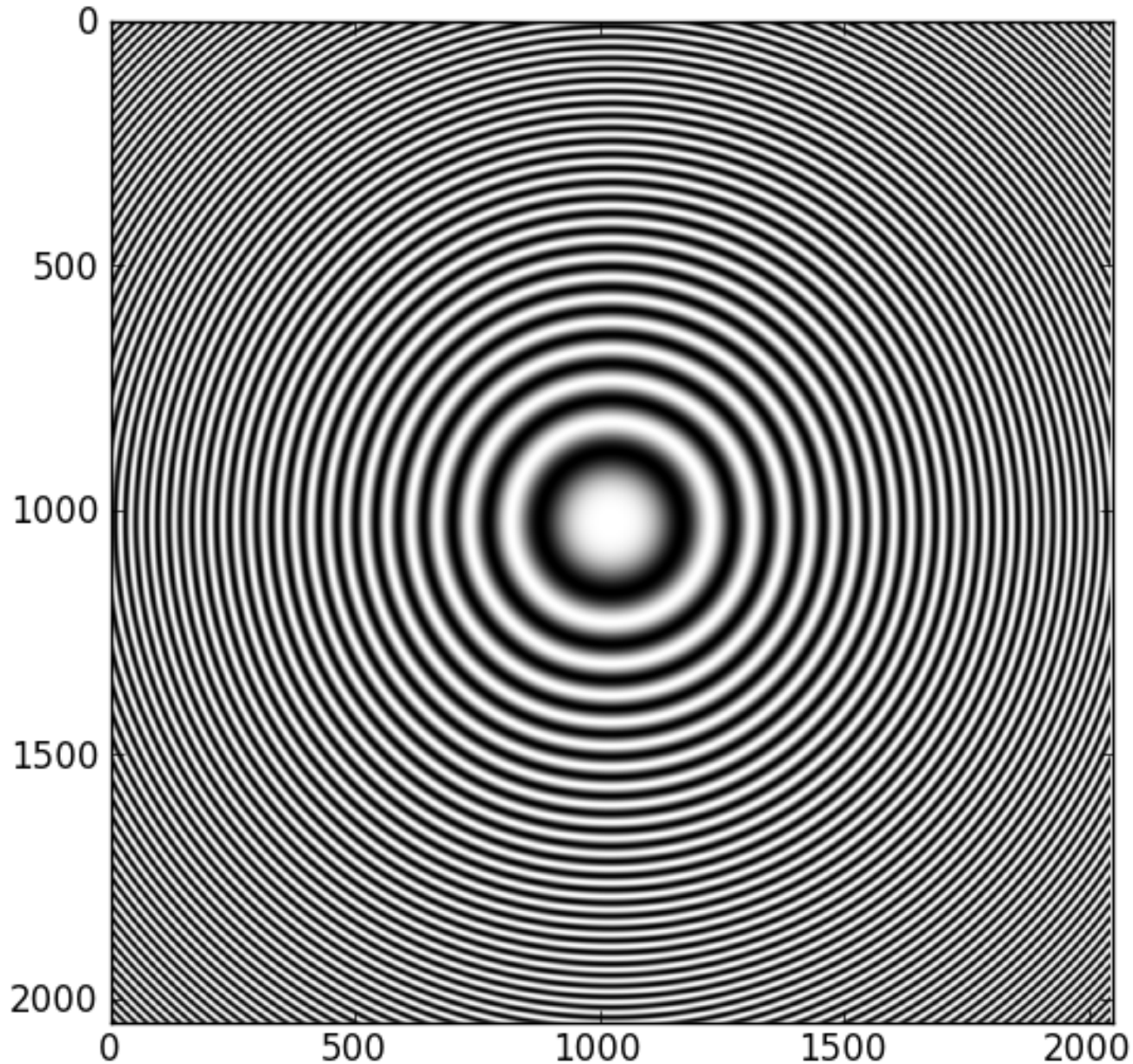
to avoid overlap:  $\omega_{max} < \frac{1}{2s}$

$\downarrow \mathcal{F}$



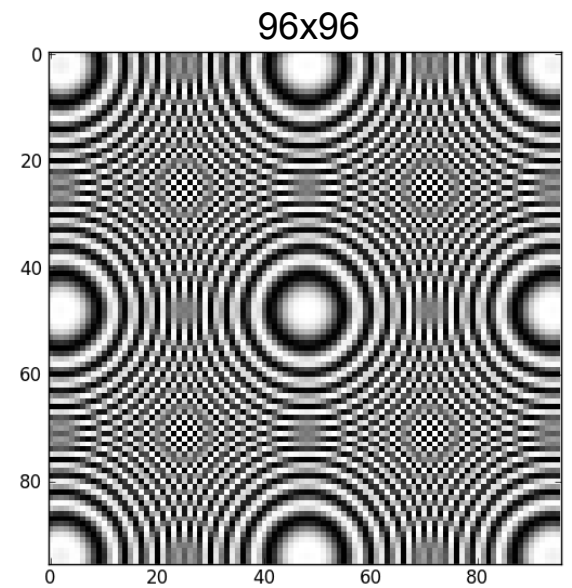
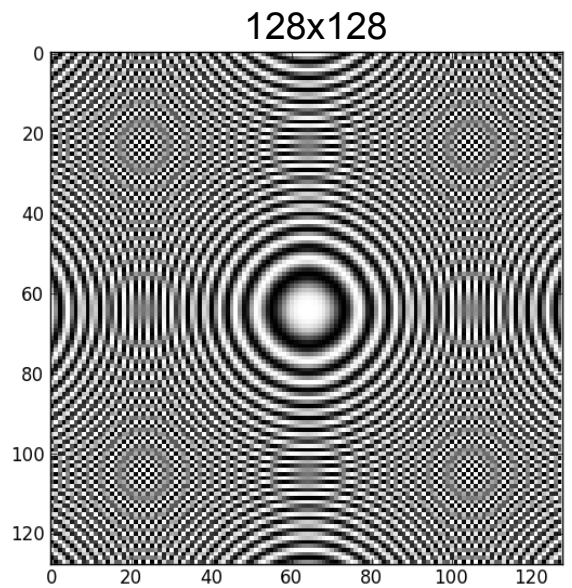
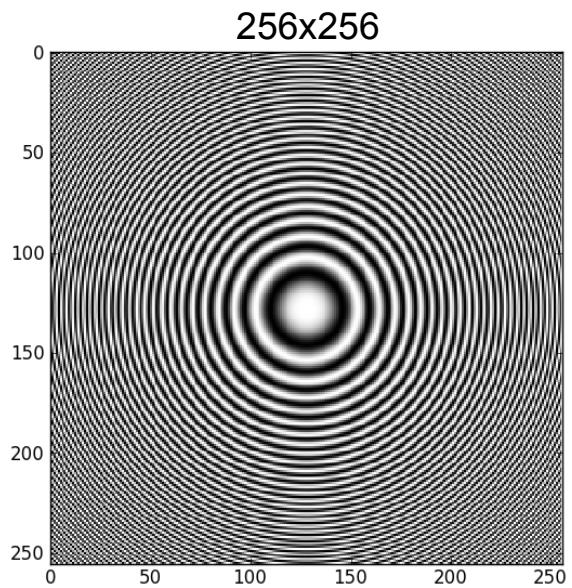
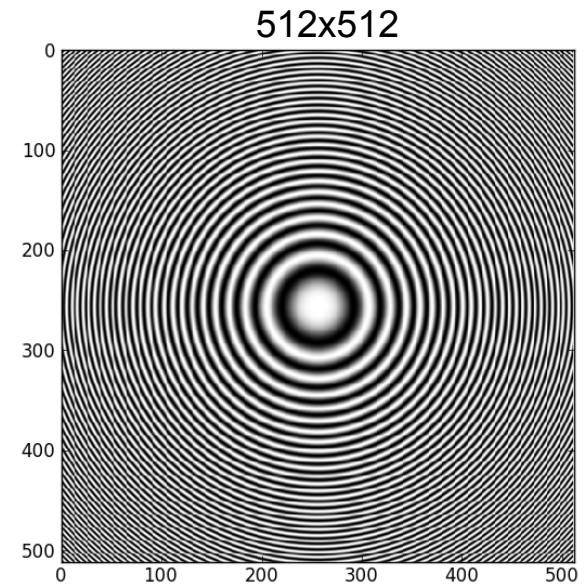
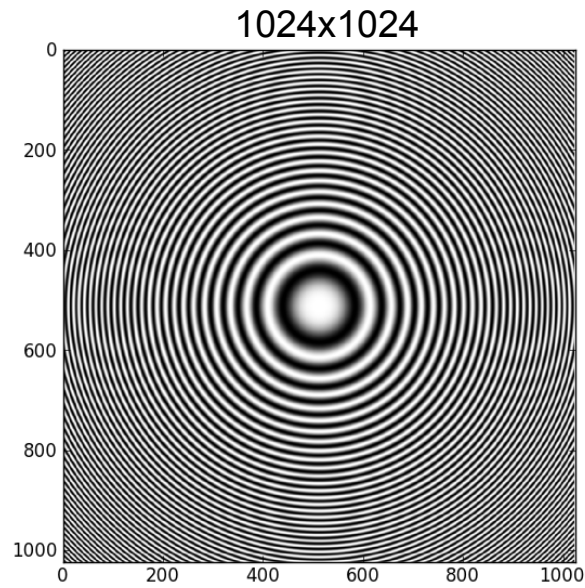
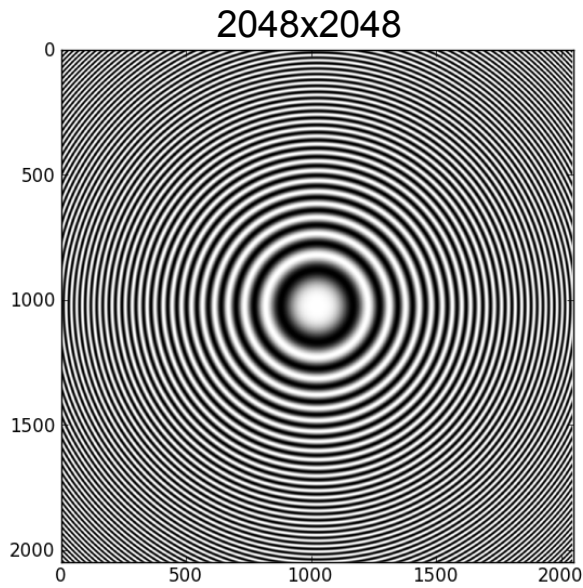
# Undersampling

“Fresnel zone” test pattern: radial linear increase in spatial frequency



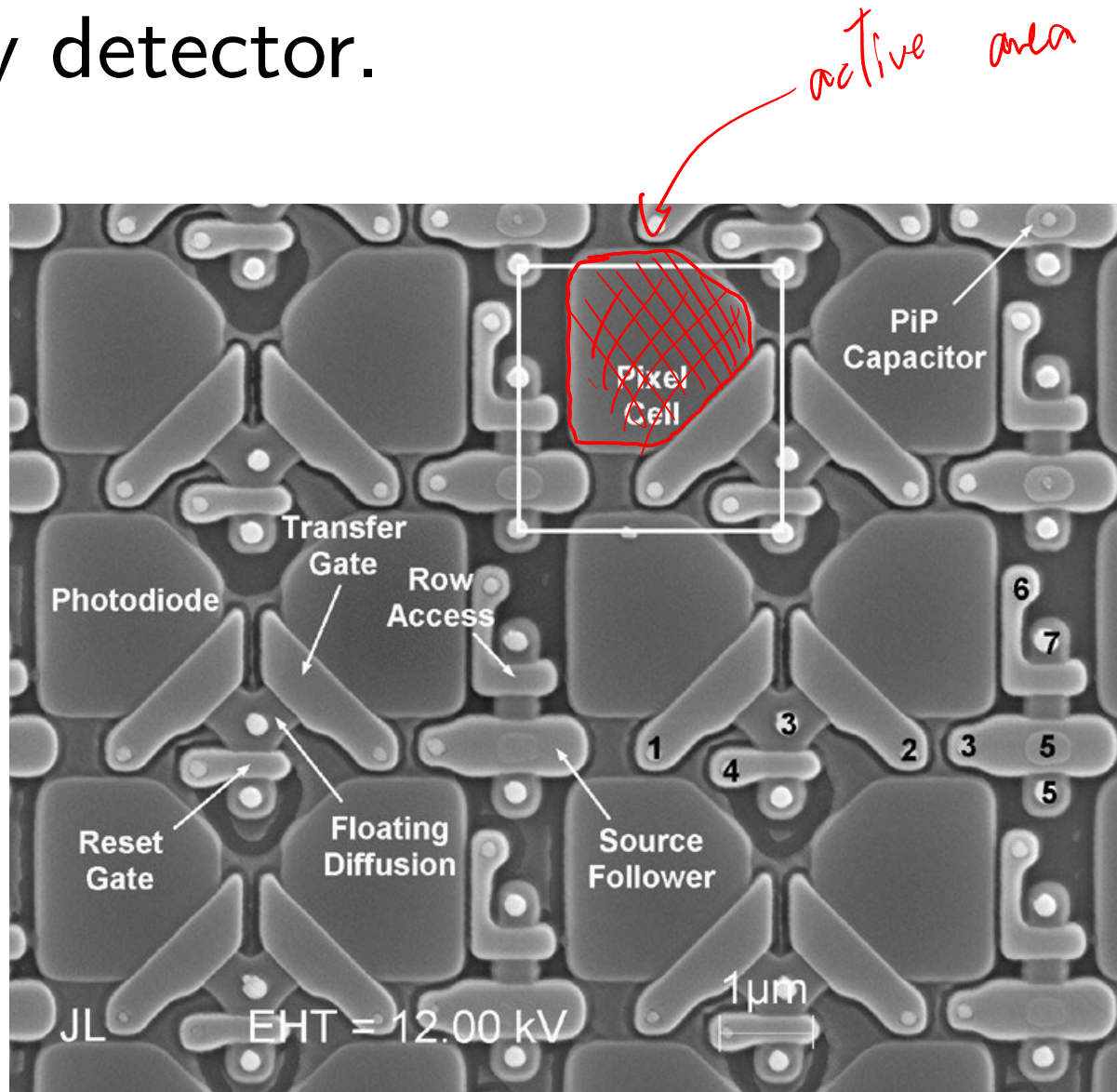
*“radial  
chirp”*

# Undersampling & aliasing



# Sampling with a pixel-array detector

- A 2D light field is sampled with a 2D pixel-array detector.



# Discrete Fourier Transform

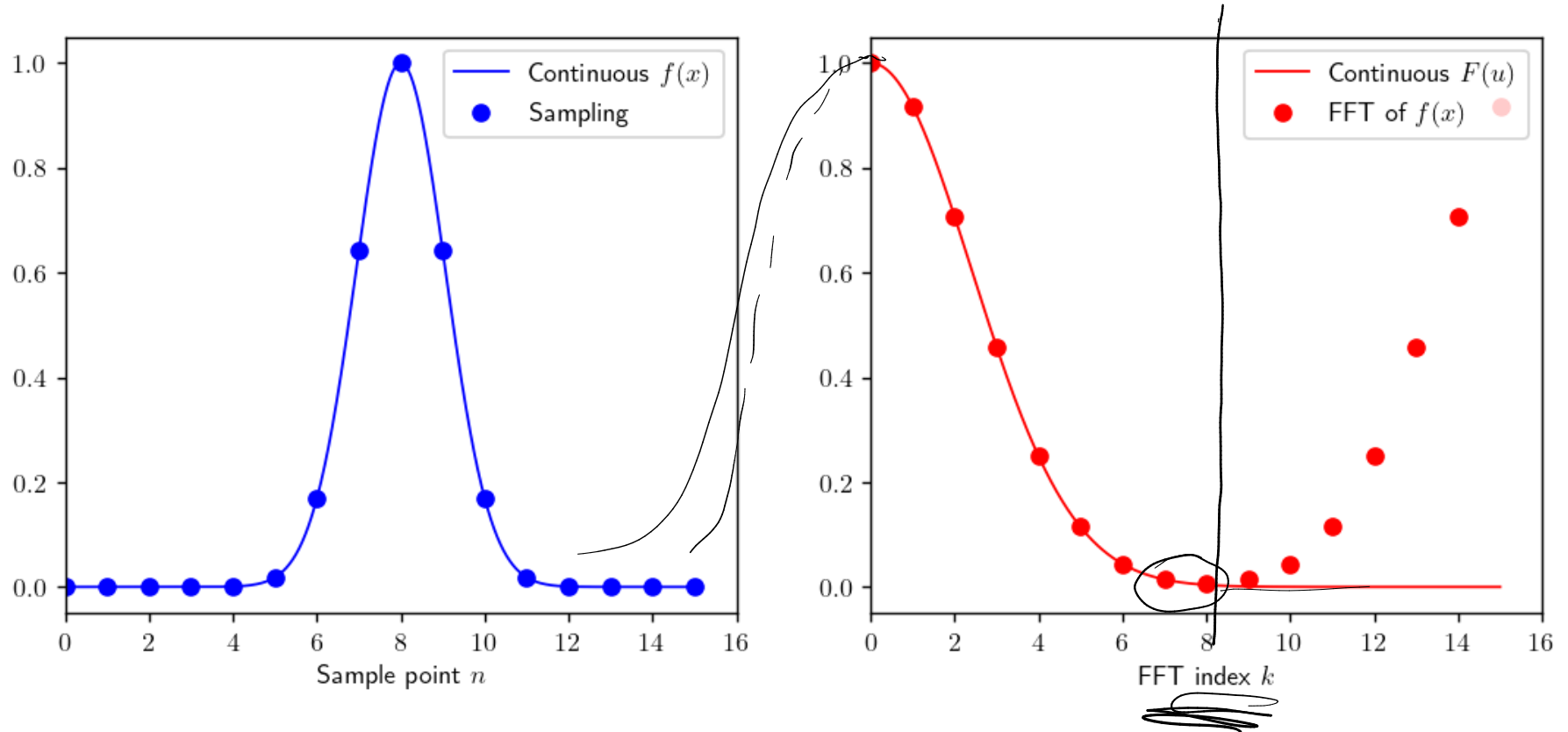
$$F_k = \sum_{n=0}^{N-1} f_n e^{-2\pi i k n / N}$$

- On computers, the signal is both sampled and of finite extent  $\rightarrow$  using DFT on this signal means that it is assumed to be periodic.
- If the signal is sufficiently sampled, then the DFT can be interpreted as a sampled version of the continuous Fourier Transform.



# DFT example

- Example: relation between space, sampling and frequency



zero frequency component is in the top left corner output array.

# FT to DFT conversion

\* Look at the  $\exp()$  argument.

$$\left. \begin{array}{l} \text{continuous: } e^{2\pi i u x} \\ \text{discrete: } e^{2\pi i n k / N} \end{array} \right\} \underbrace{u x = \frac{nk}{N}}$$

\* function sampling  $f(x) \rightarrow f_n$

step size  $s$  :  $\underline{x = ns}$

$L$ : "physical size" of signal

$$u x = u n s = \frac{nk}{N} \Rightarrow u = \frac{k}{Ns} = \frac{k}{L}$$

Observation:  $F_{k+N} = \sum_{n=0}^{N-1} f_n e^{-2\pi i n (k+N) / N}$

$$= \sum_{n=0}^{N-1} f_n e^{-2\pi i n (\frac{k}{N} + 1)} = F_k$$

$F_k$  is periodic

# Fourier space translation

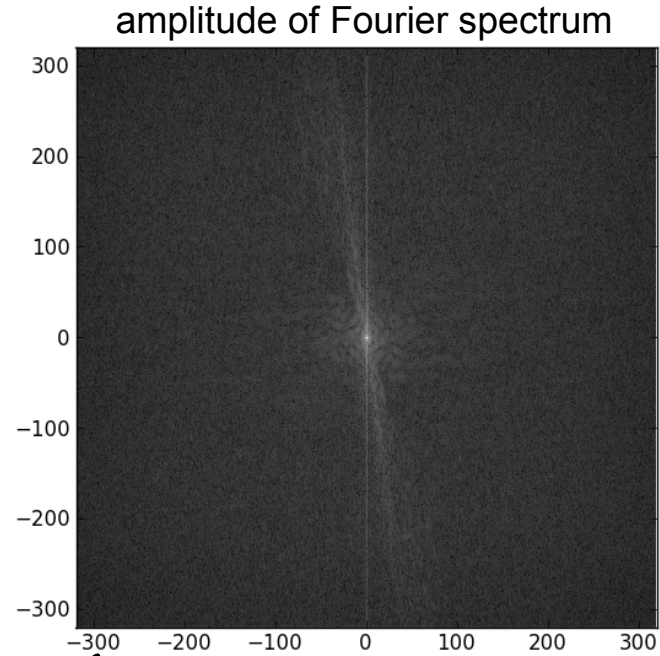
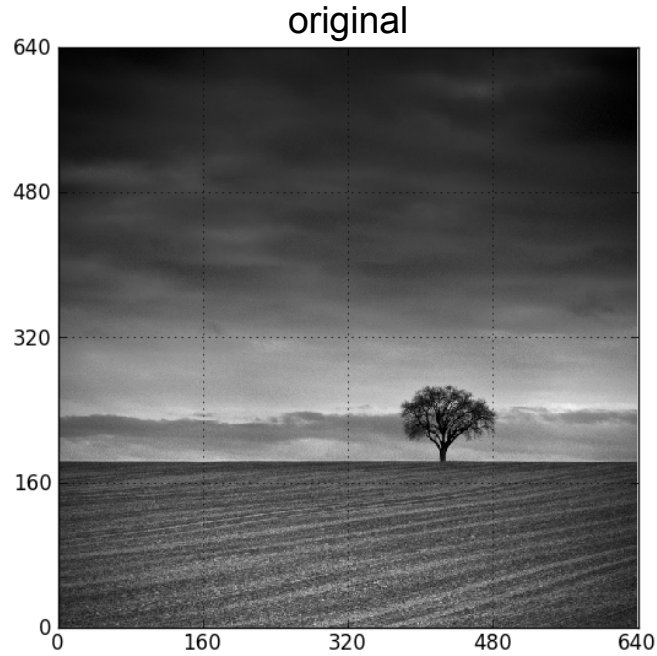
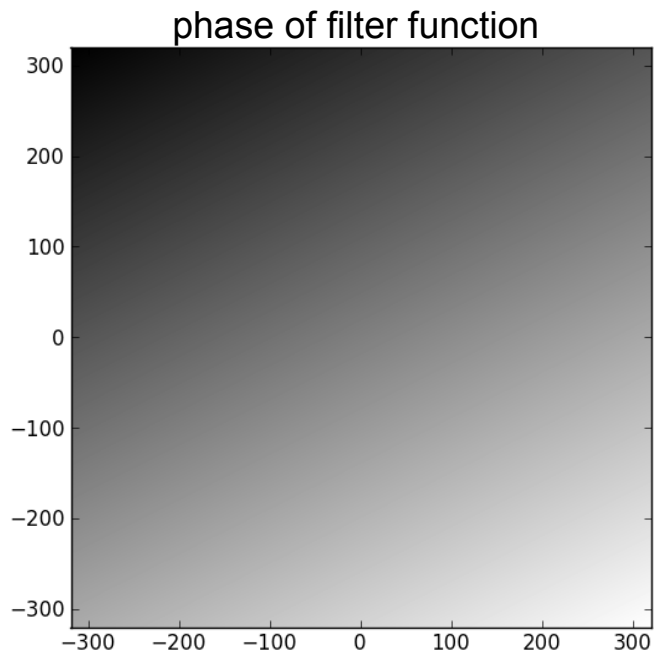


Image shifting using shifting property of FT



$$e^{2\pi i \vec{\omega} \vec{r}_0}$$

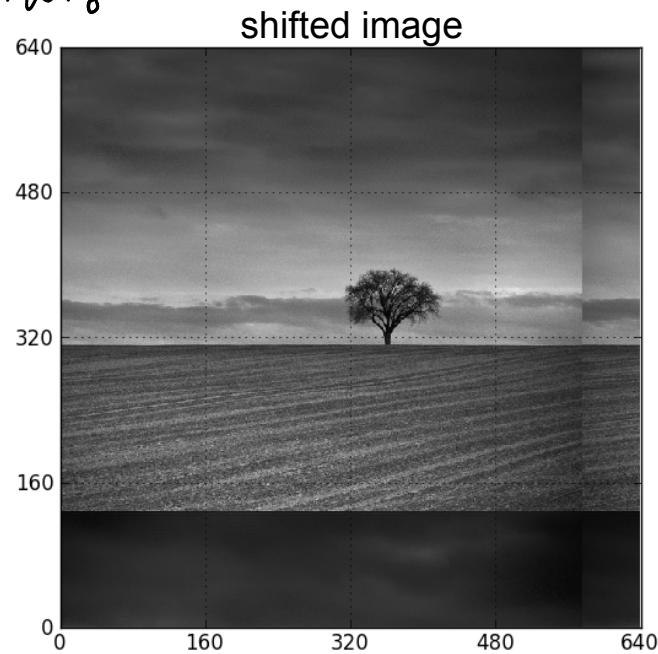
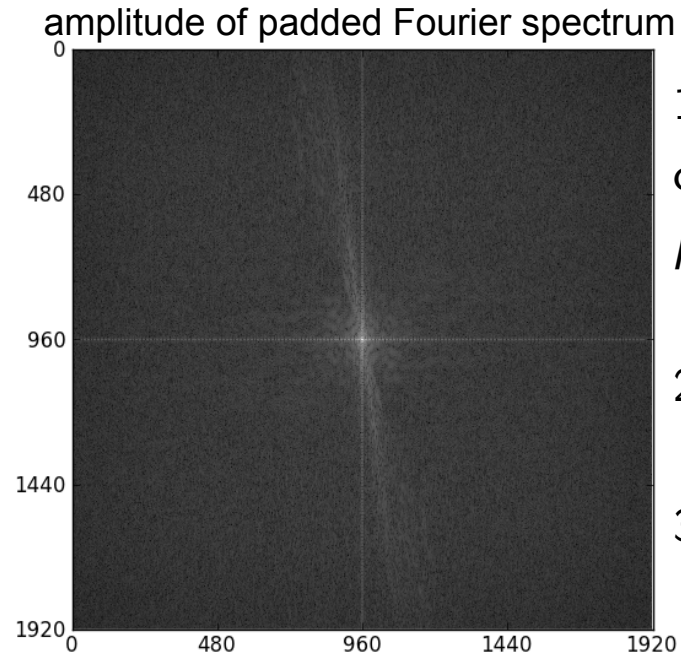
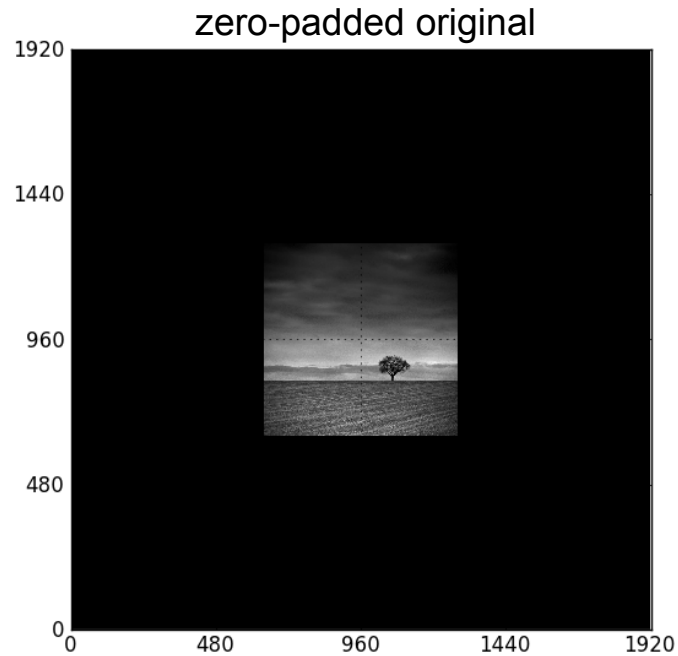


Image gets wrapped around

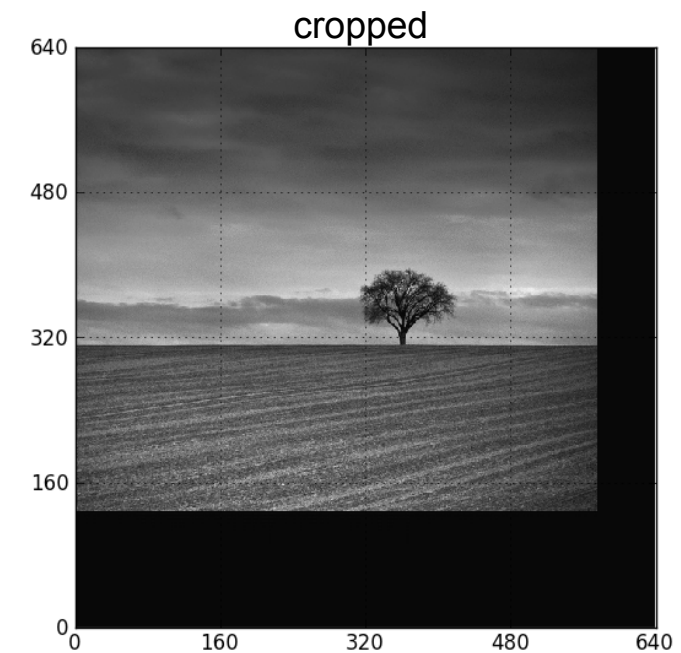
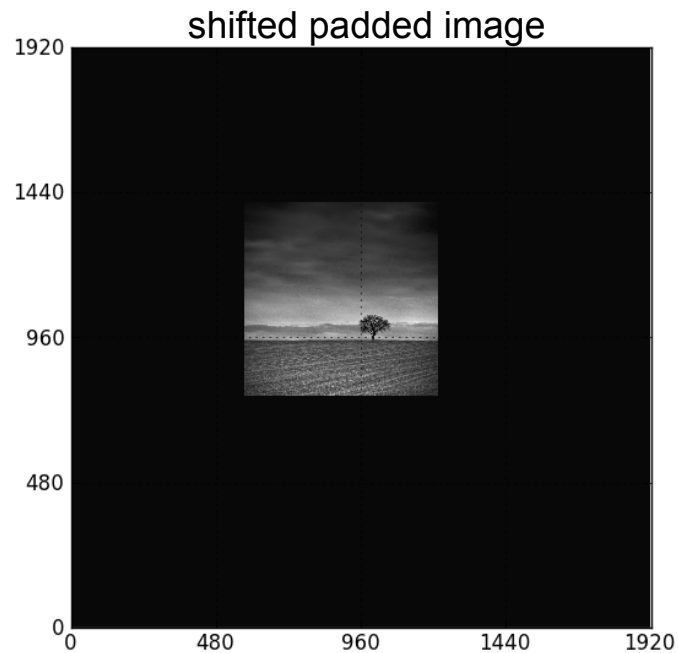
# Zero-padding



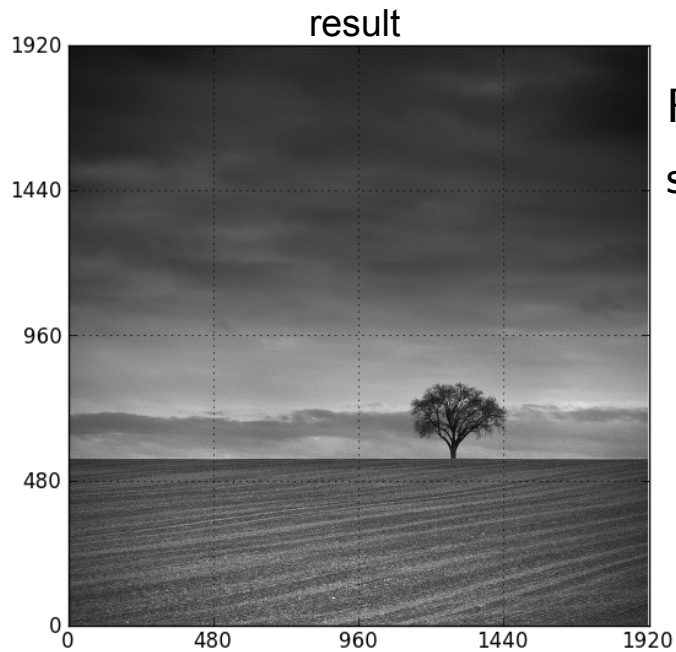
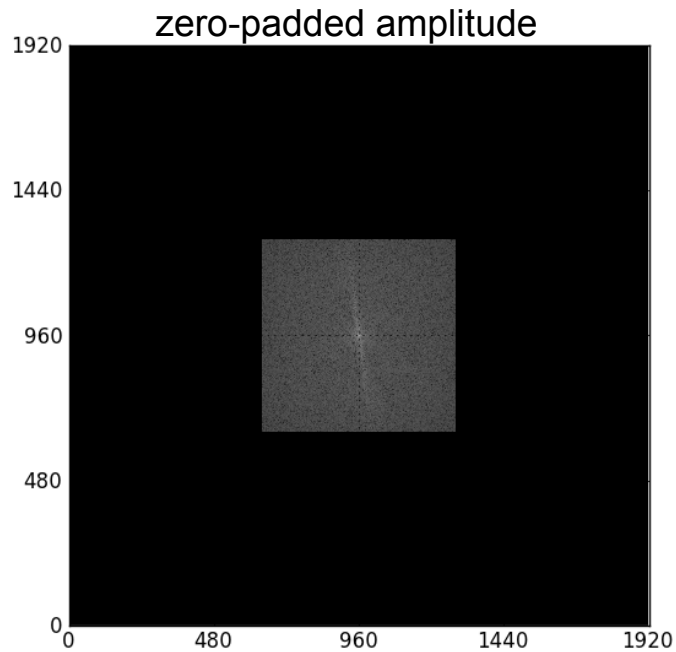
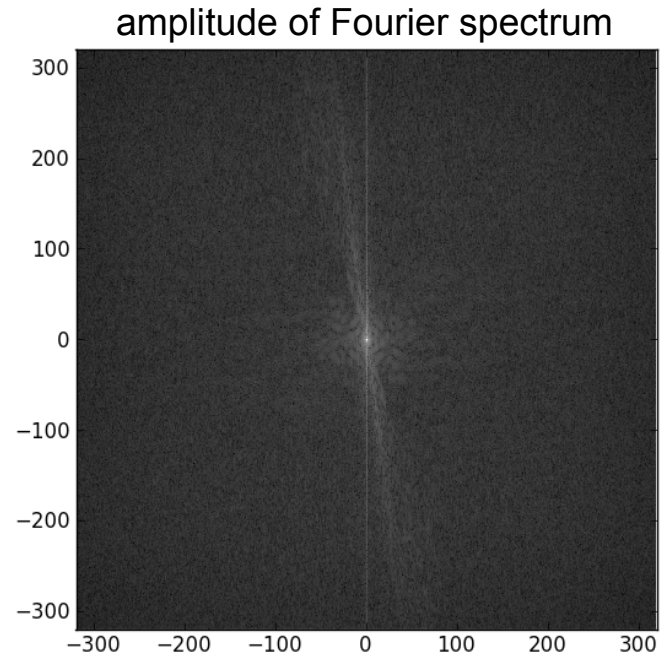
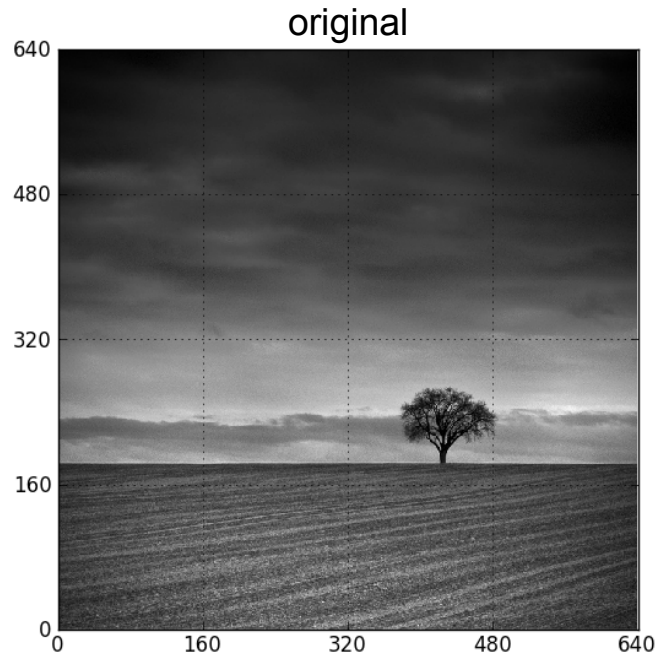
1. Add zeros around original image (*zero-padding*)

2. Shift using FT

3. Crop result



# Zero-padding in Fourier space

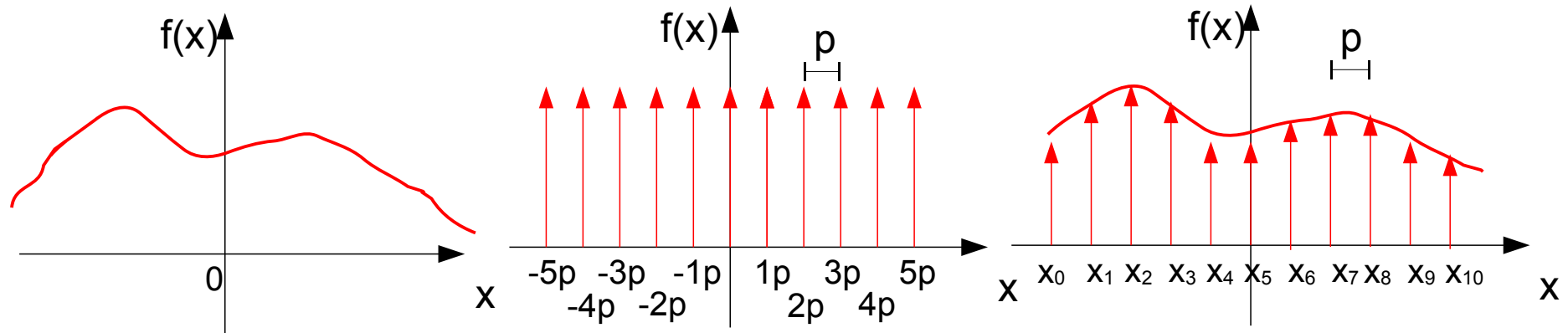


Result: increased sampling!

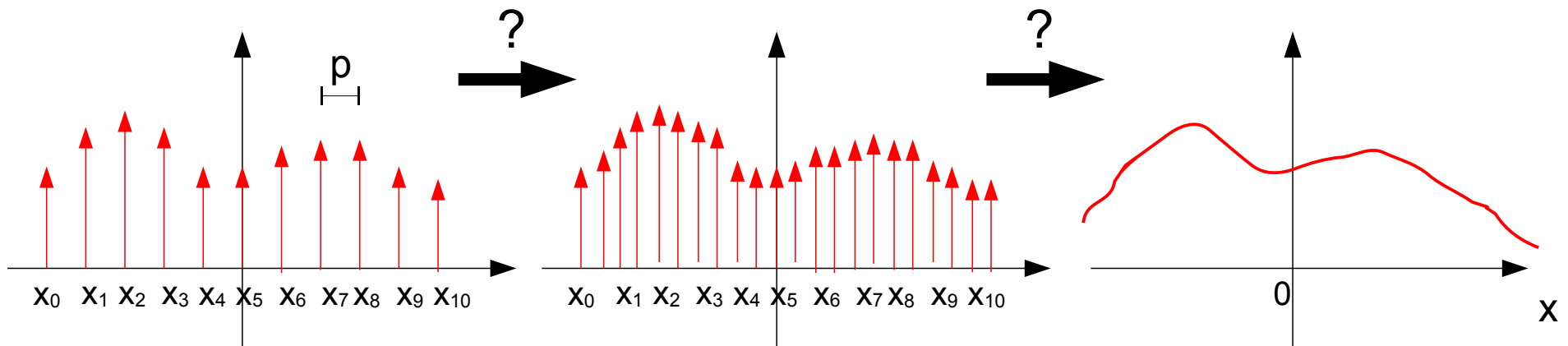
↓  
interpolation  
"upsampling"  
"upsampling"

# Interpolation

- Discrete sampling of a continuous function



- Reconstruct original function from sampled data?

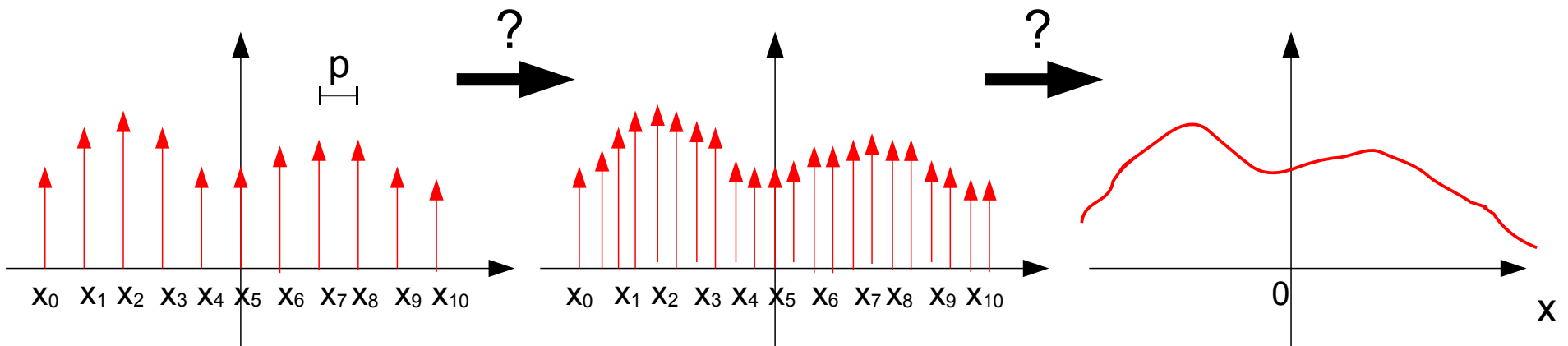


# Interpolation

Finding unknown points between known ones

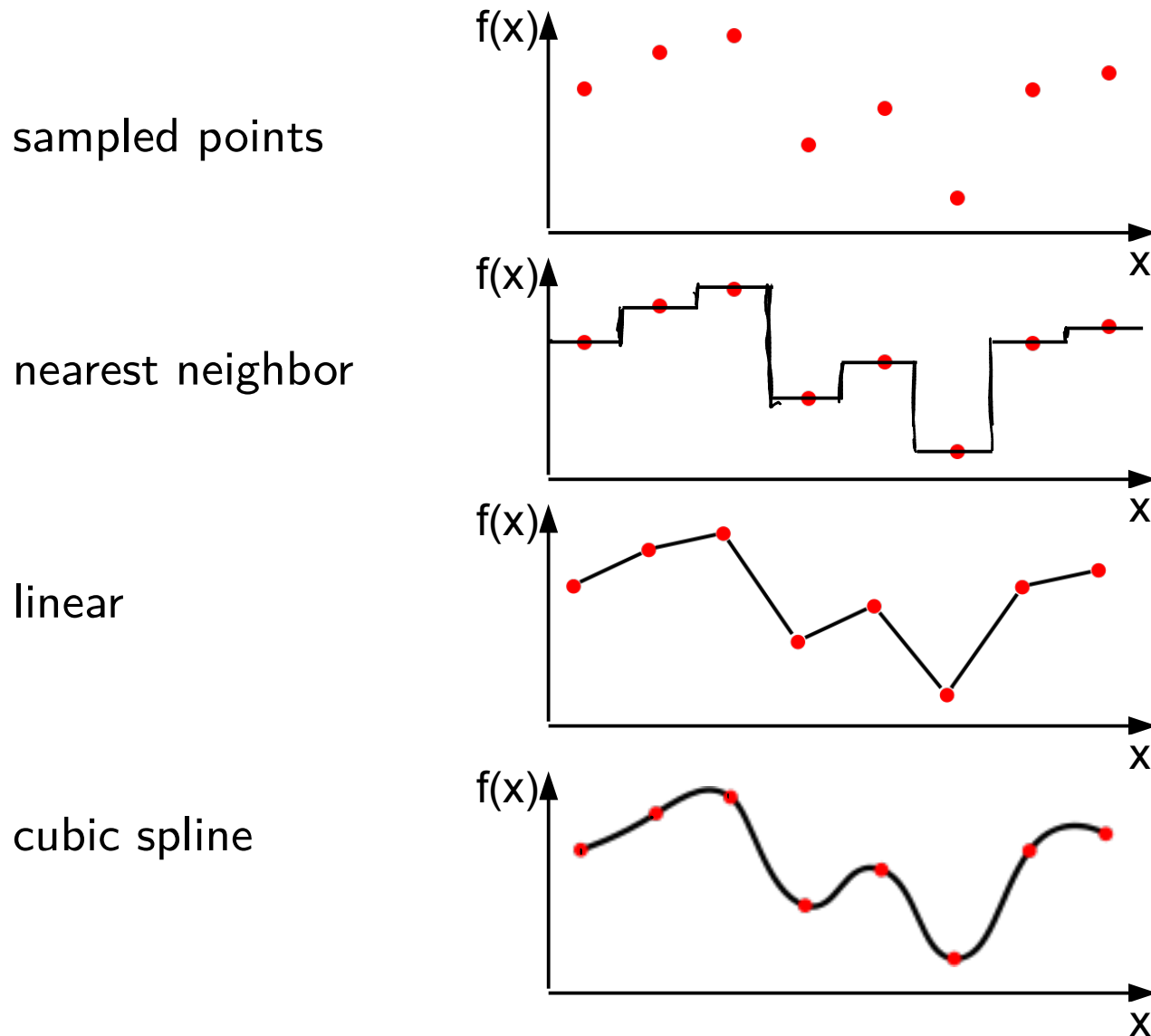
- wide field, many different approaches
- closely related to approximation theory and curve fitting

*difference: interpolated curve has to pass through all known samples*



# Interpolation

Various “classical” interpolation methods available

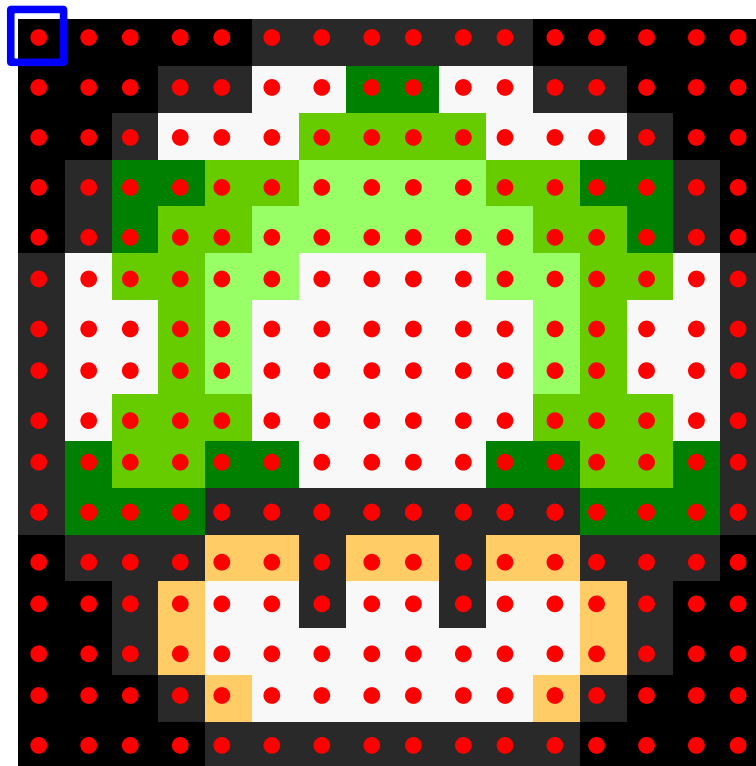




# Image pixels

Images are discrete samples of a continuous function

- ...with coordinates
- ...and values (voltage at coordinate, integral over pixel area, ...)
- ...represented by pixel basis functions on a sampling grid



# Linear interpolation

- Interpolation as an operator

$$f(x) = \mathcal{L} \{ f_n \}$$

- Linear interpolation

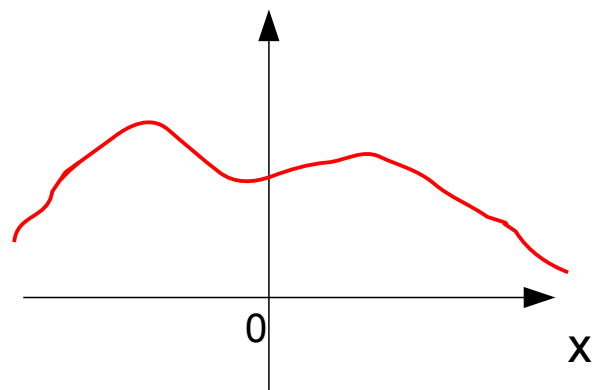
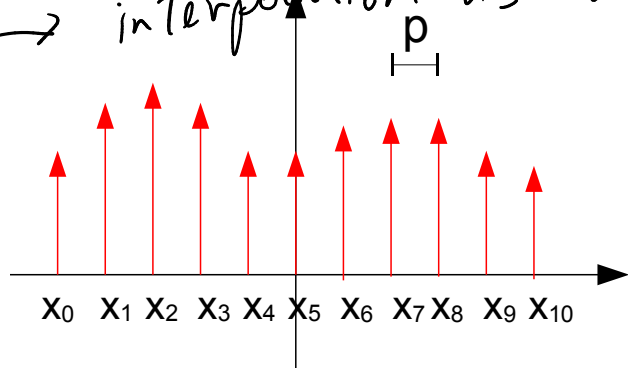
$$\mathcal{L} \{ f_n + g_n \} = \mathcal{L} \{ f_n \} + \mathcal{L} \{ g_n \}$$

- Shift invariance

$$\mathcal{L} \{ f_{n+n_0} \} = f(x + ns_0)$$

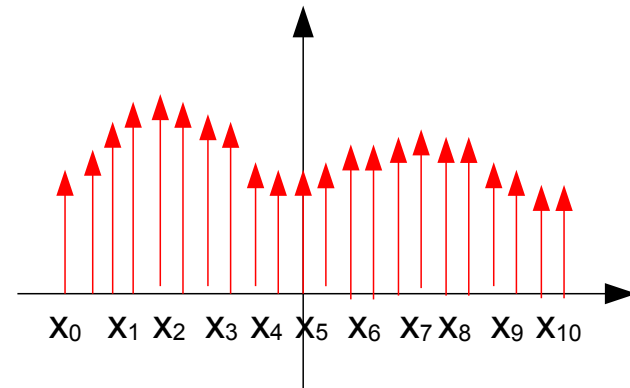
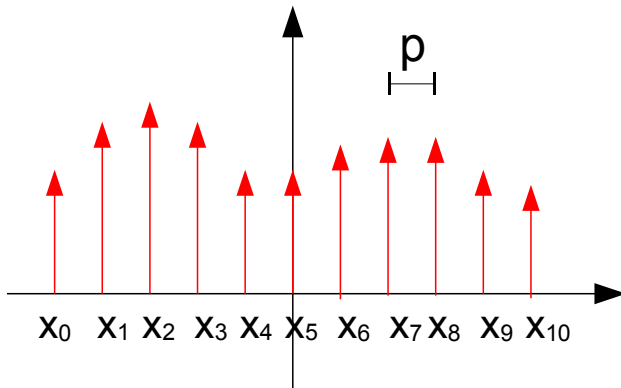
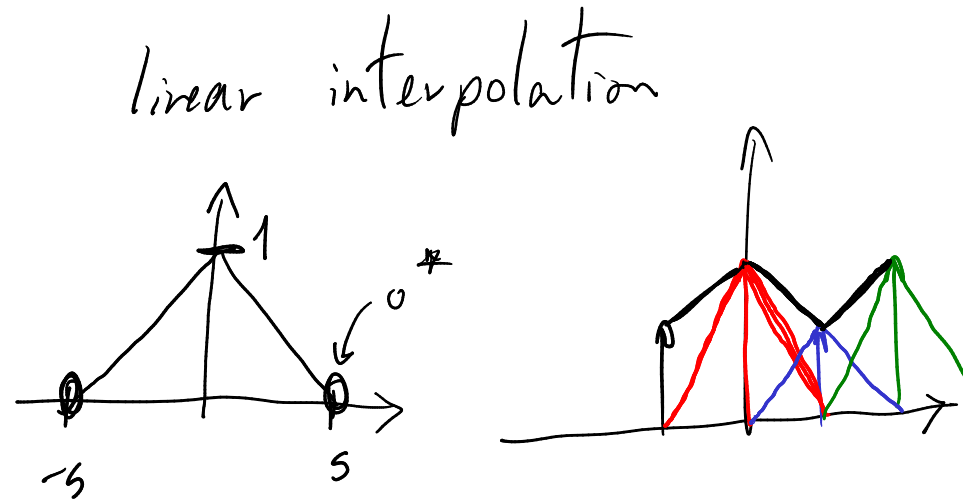
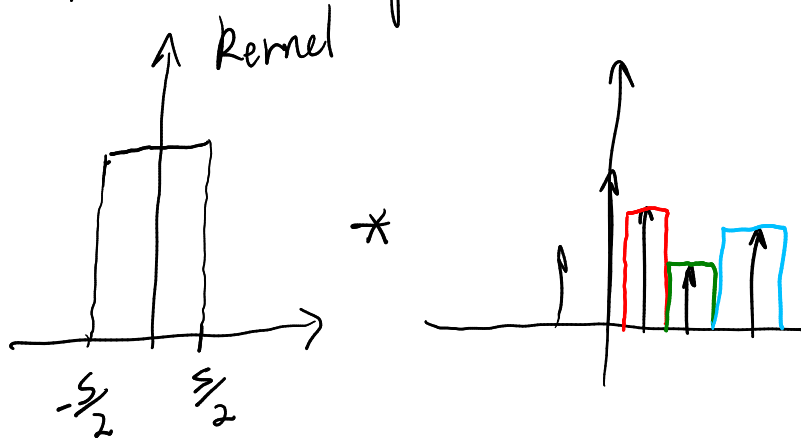
- Kernel

$\hookrightarrow$  interpolation as a convolution



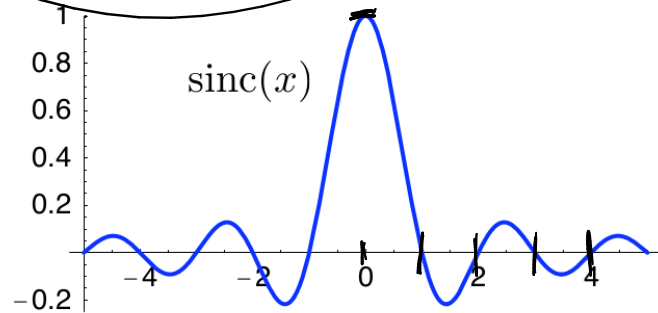
# Linear interpolation

- Linear interpolation can be written as a convolution with a kernel (e.g. a basis function)

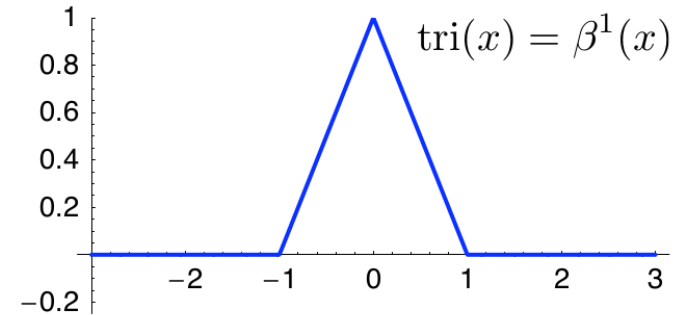


# Linear interpolation

## ■ Bandlimited



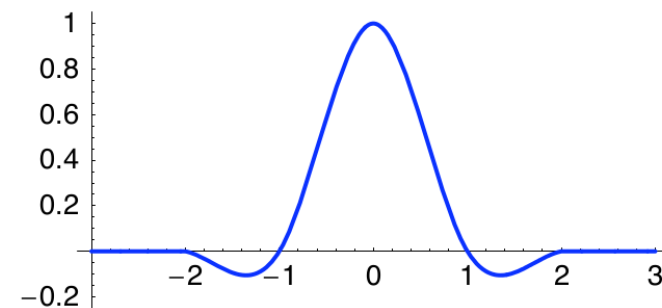
## ■ Piecewise linear



Interpolation condition:

$$\varphi_{\text{int}}(k) = \delta_k = \begin{cases} 1, & k = 0 \\ 0, & \text{otherwise} \end{cases}$$

## ■ Cubic convolution



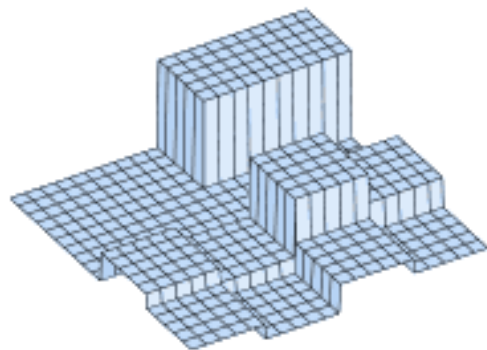
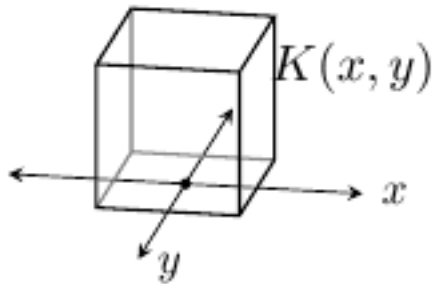
[Keys, 1981; Karup-King 1899]

source: [http://bigwww.epfl.ch/tutorials/unser\\_isbi\\_06\\_part1](http://bigwww.epfl.ch/tutorials/unser_isbi_06_part1)

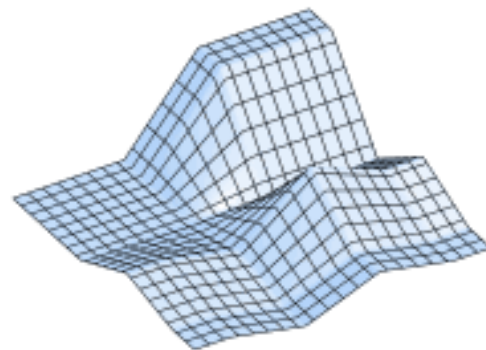
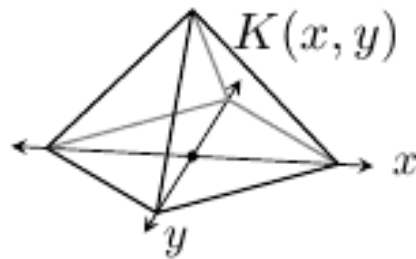
# 2D interpolation

- Make 2D interpolation linear in each variable

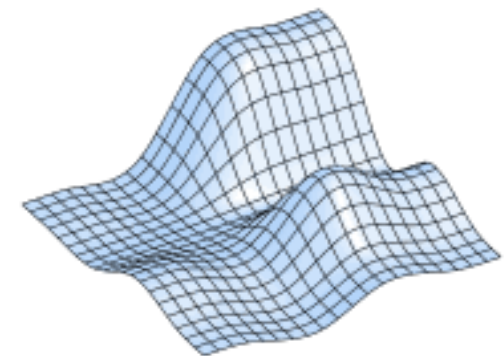
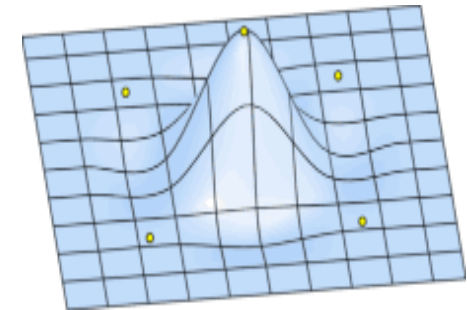
nearest neighbor



bilinear



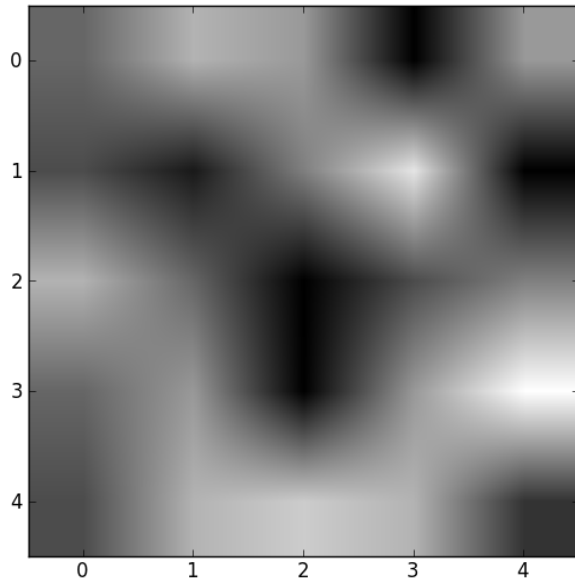
bicubic



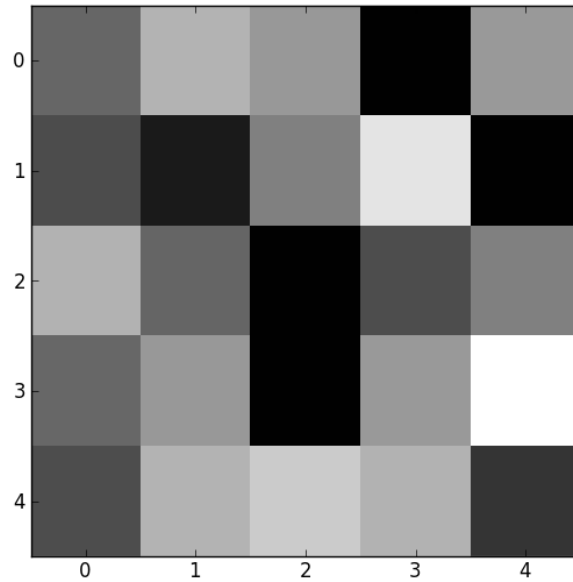
source: [http://www.ipol.im/pub/art/2011/g\\_lmii/](http://www.ipol.im/pub/art/2011/g_lmii/)

# Python plotting

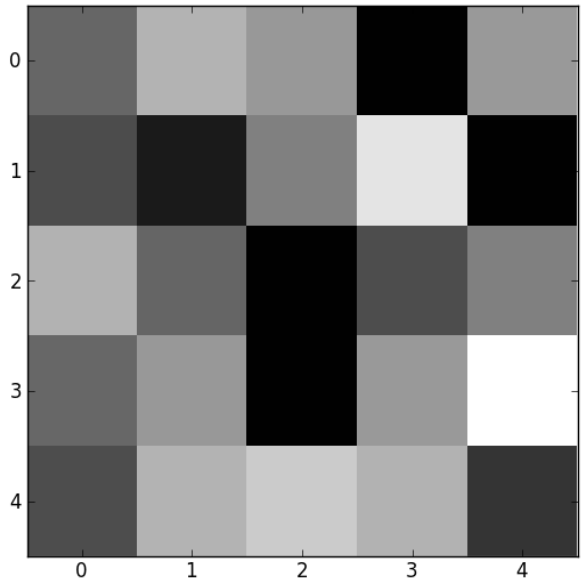
`plt.imshow(im)`



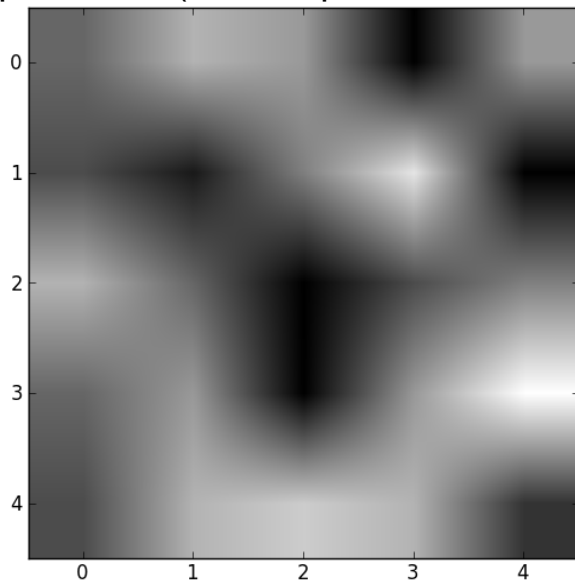
`plt.imshow(im, interpolation='none')`



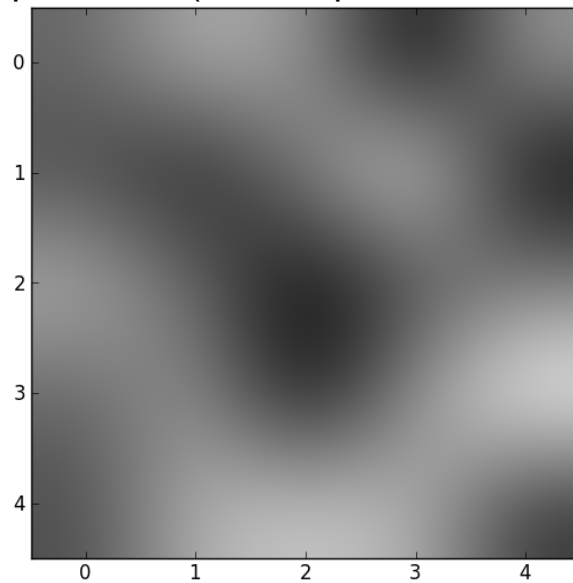
`plt.imshow(im, interpolation='nearest')`



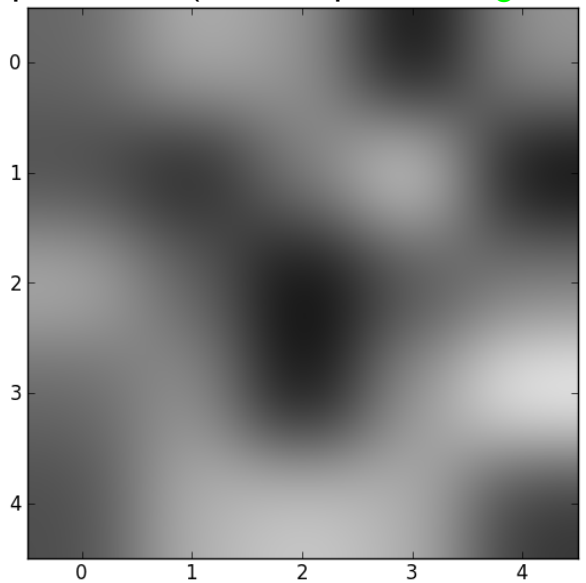
`plt.imshow(im, interpolation='bilinear')`



`plt.imshow(im, interpolation='bicubic')`

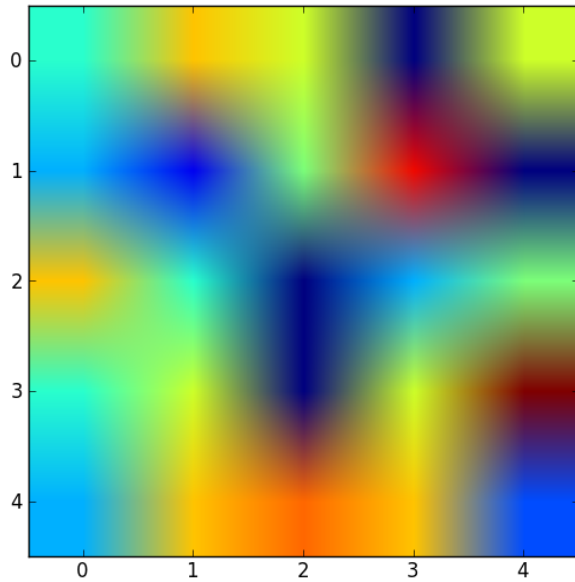


`plt.imshow(im, interpolation='gaussian')`

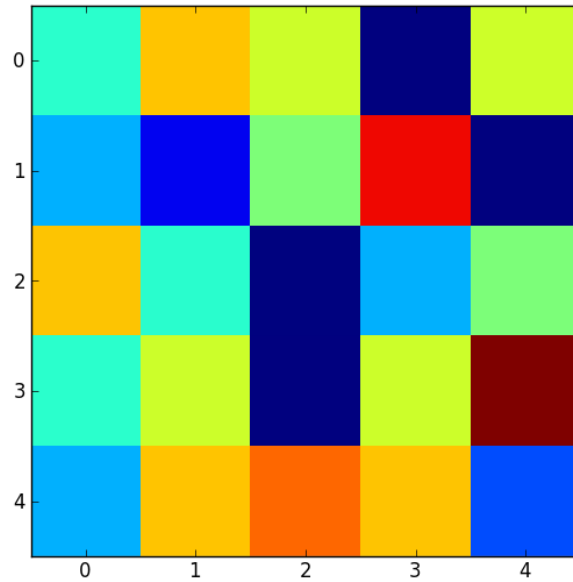


# Python plotting

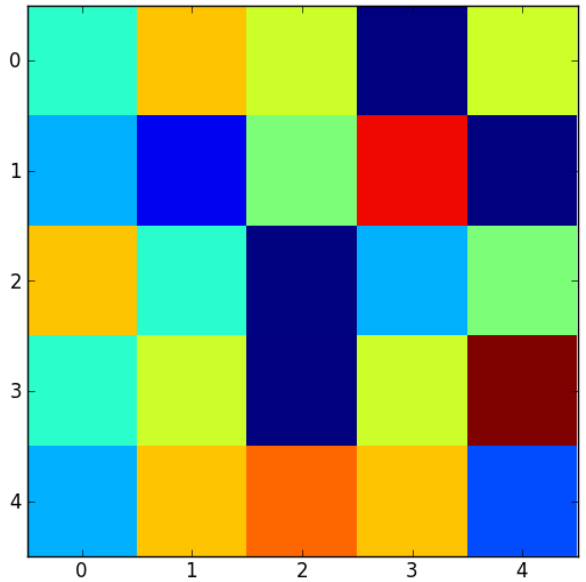
`plt.imshow(im)`



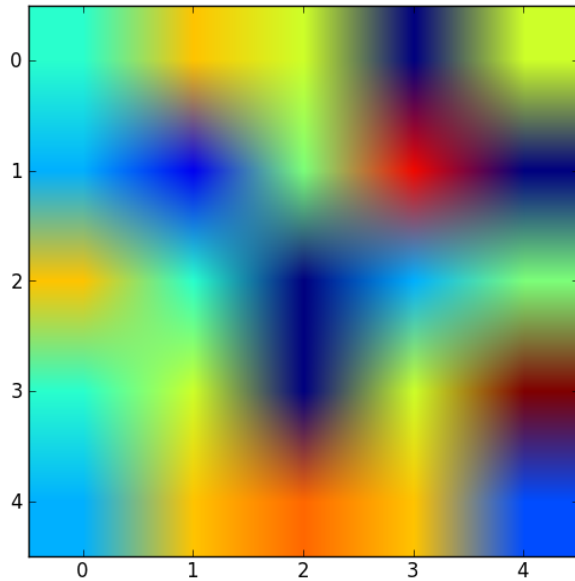
`plt.imshow(im, interpolation='none')`



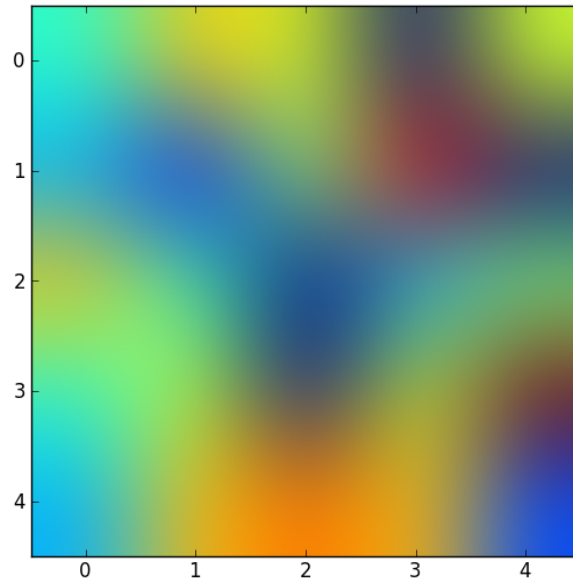
`plt.imshow(im, interpolation='nearest')`



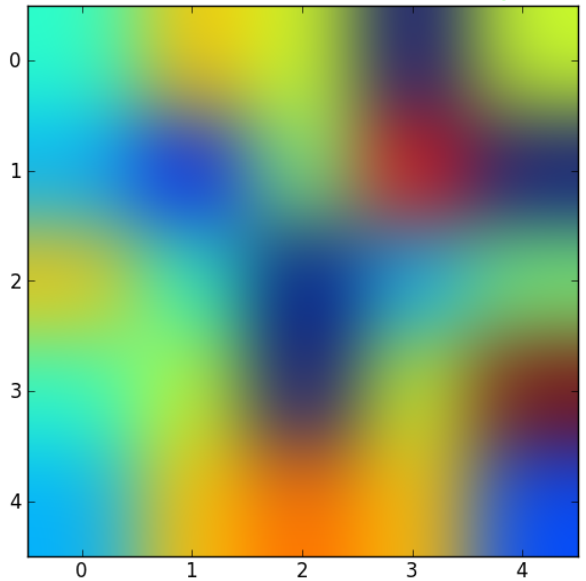
`plt.imshow(im, interpolation='bilinear')`



`plt.imshow(im, interpolation='bicubic')`

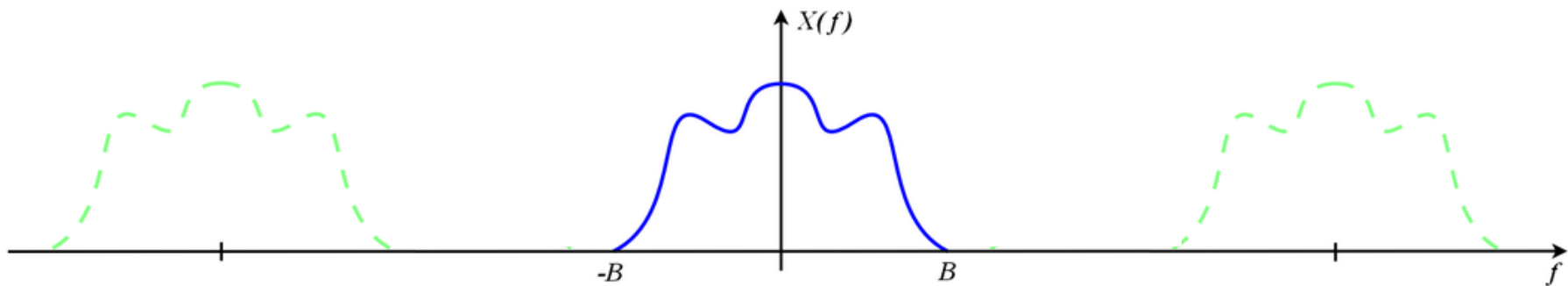
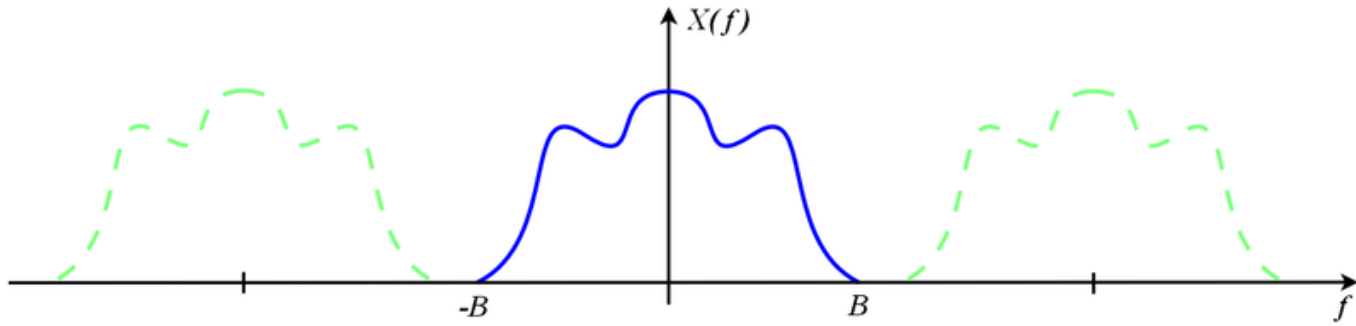
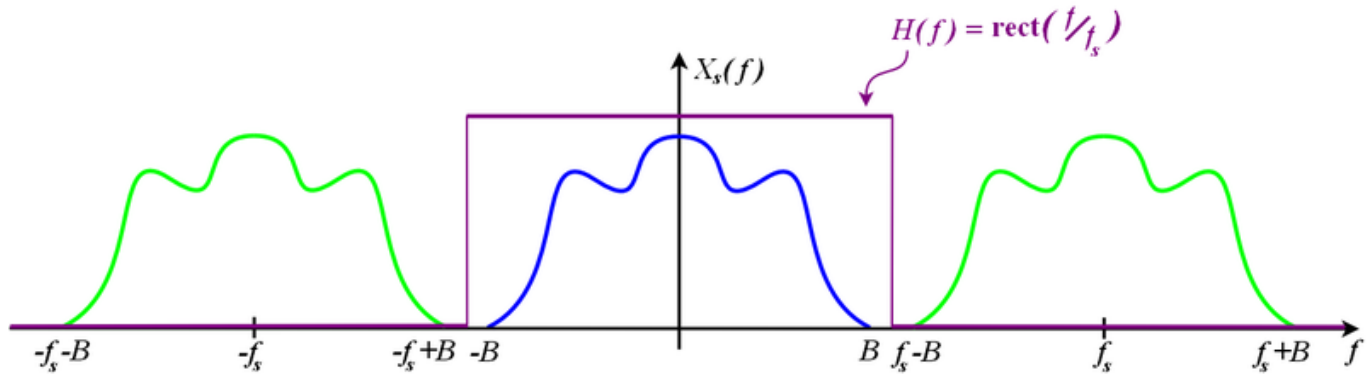


`plt.imshow(im, interpolation='gaussian')`



# Sinc interpolation and zero-padding

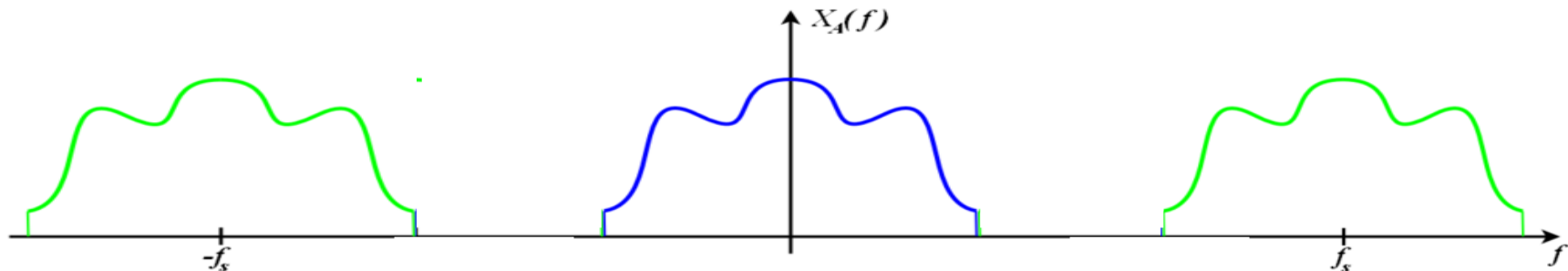
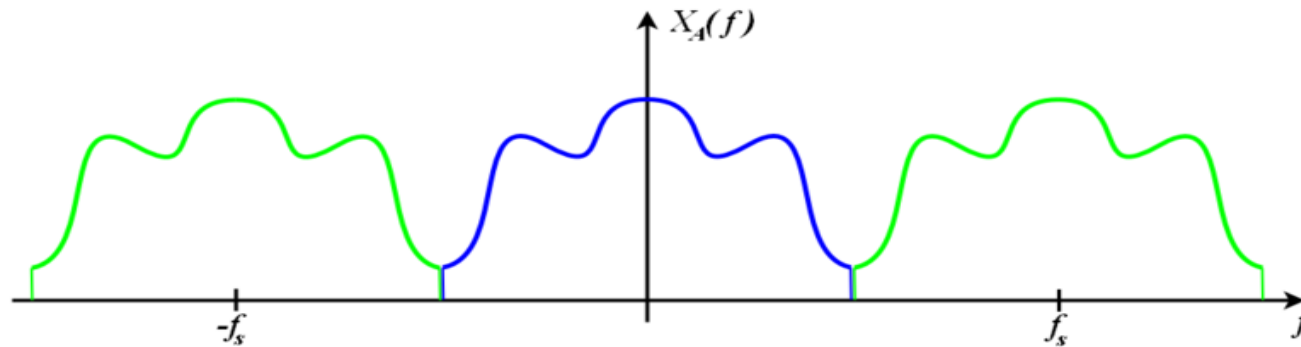
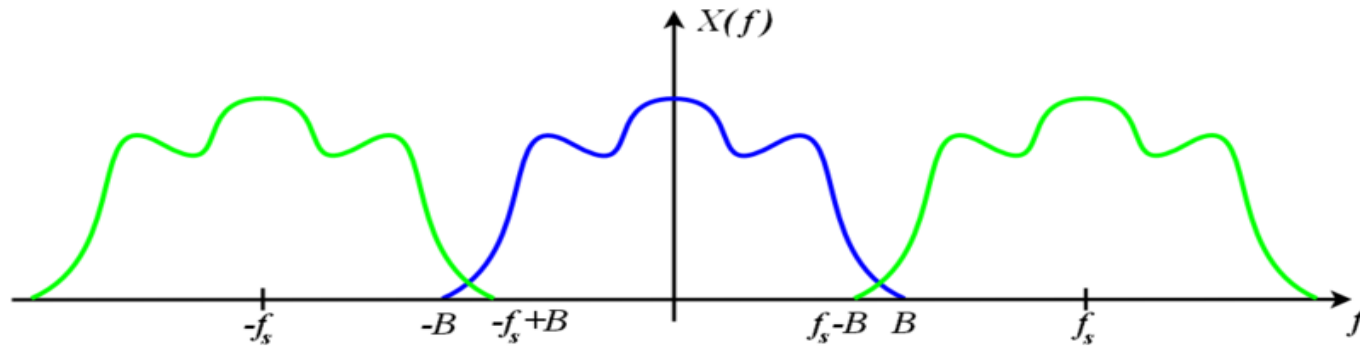
Also known as “Whittaker–Shannon interpolation”





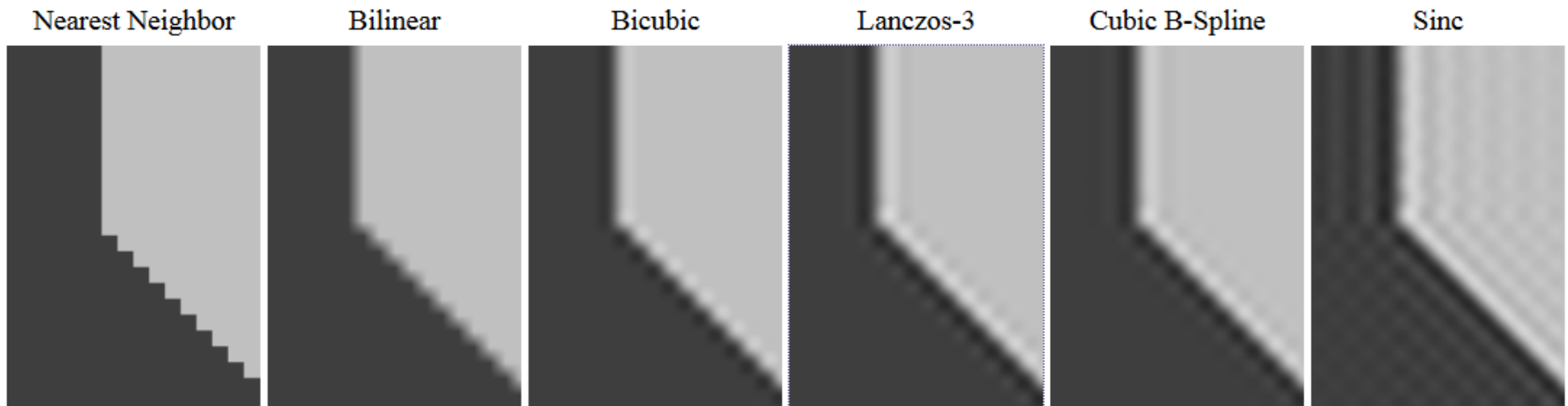
# Sinc interpolation and zero-padding

Also known as “Whittaker–Shannon interpolation”



# Reconstruction from samples

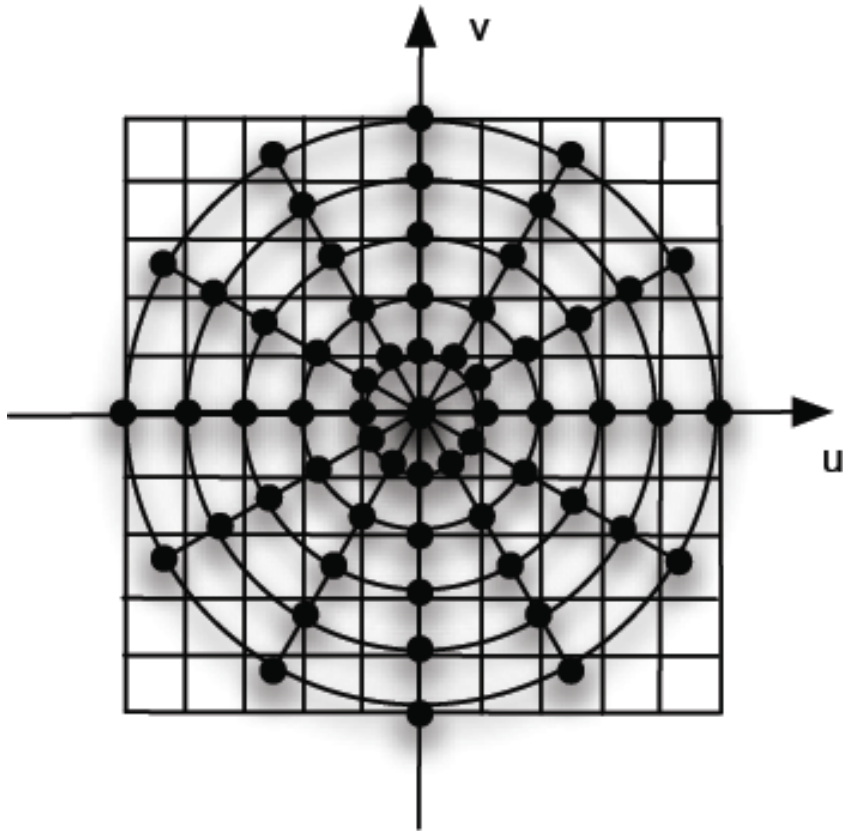
- Sinc interpolation can perfectly reconstruct a function from its samples if
  - sampled at a rate higher than Nyquist rate
  - bandlimited up to Nyquist frequency
  - no aliasing
- Sinc interpolation introduces ringing otherwise, due to leakage of aliased frequencies



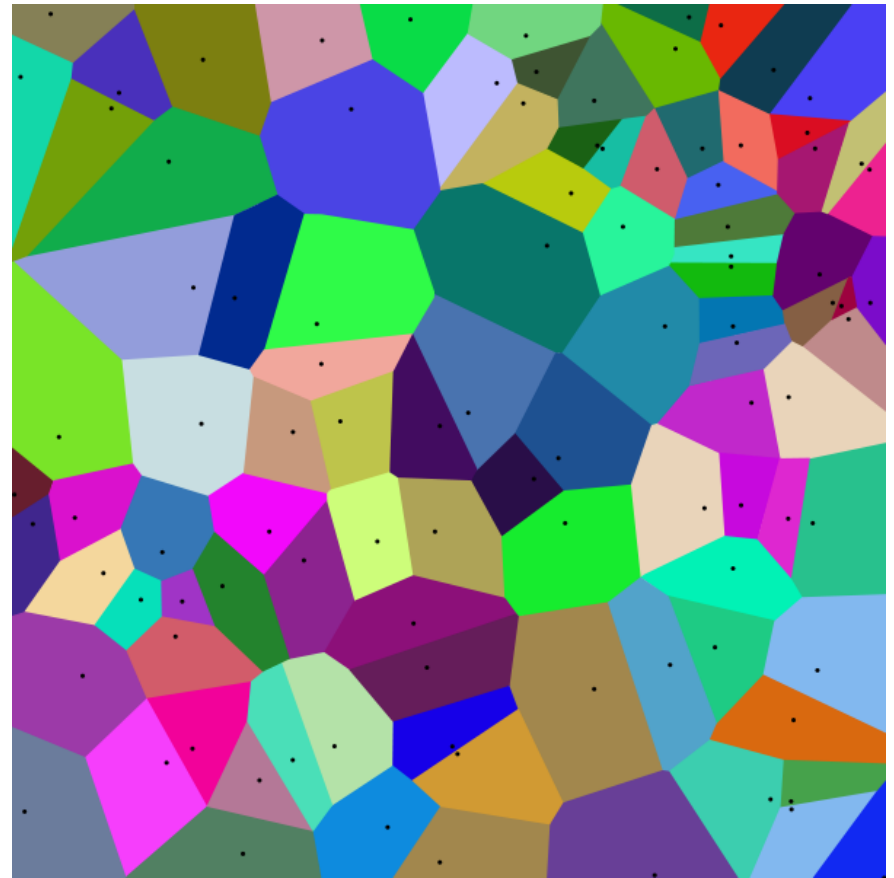
*Linear interpolation of a step edge: a balance between staircase artifacts and ripples.*

# Other Interpolation

- Change from polar to cartesian grid
- Linear, but not translation invariant



polar vs. cartesian sampling



irregular sampling

# Summary

- Images can be represented as a sampling grid and pixel basis functions
- Need for interpolation arises when changing the grid
- Linear and translation invariant interpolation can be written as a convolution with an interpolation kernel function
- Typical interpolation kernels include nearest neighbor, linear, cubic and higher B-spline interpolation
- Zero-padding in one domain equals sinc interpolation in the other
- “ideal” sinc interpolation may lead to ringing artifacts