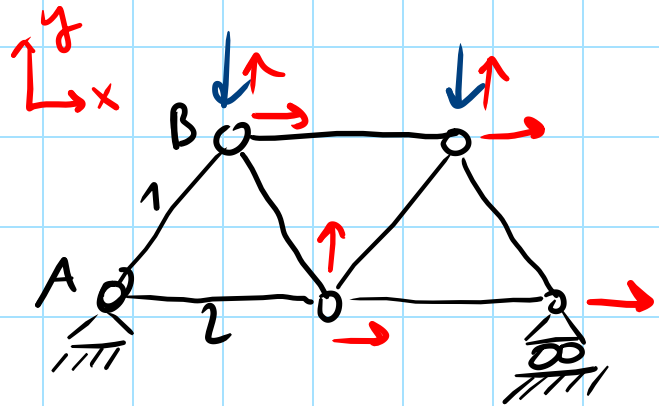


TRUSS STRUCTURES: SOLUTION BASED ON "METHOD OF DISPLACEMENTS"

25/03/25



NODAL DISPLACEMENTS ARE NOW THE UNKNOWNNS

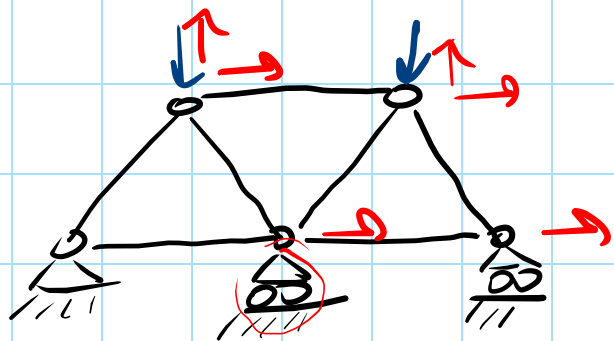
(7 IN OUR EXERCISE). IN ORDER TO SOLVE THE PROBLEM, WE

CAN WRITE A SYSTEM OF THE 7 EQUIL. EQS ASSOCIATED WITH THE DIRECTIONS OF THE UNKNOWNNS. TO ELIMINATE FORCES OF BODS WE INTRODUCE THE ELASTIC CONSTITUTIVE LAW ($N_i = f(u_j)$)

⇒ SYSTEM AS A FUNCTION OF THE 7 DISPLACEMENTS.

THERE ARE STILL 3 EQUIL EQS THAT ALLOW THE CALCULATION OF THE 3 EXTERNAL REACTIONS.

THE ADVANTAGE OF THE METHOD IS THAT IT CAN BE APPLIED IN THE SAME WAY FOR A REDUNDANT STRUCTURE:

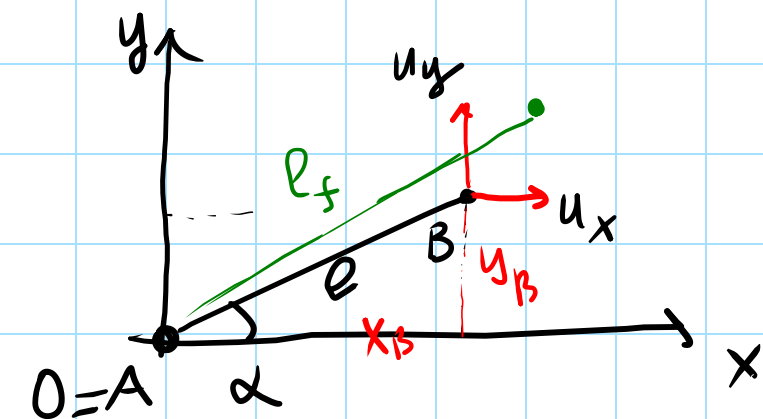


6 UNKNOWNNS ⇒ 6 EQUIL-EQS + CONSTITUTIVE LAW

LATER

4 EXTERNAL REACTIONS WITH THE REMAINING 4 EQUIL. EQS

INTRODUCTION OF DISPLACEMENT METHODS FOR TRUSS STRUCTURES



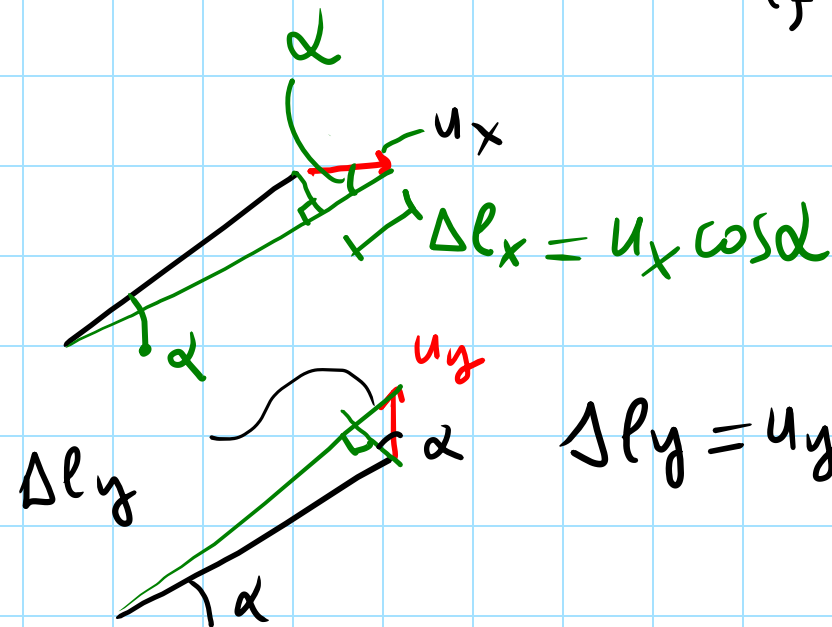
$$l = \sqrt{x_B^2 + y_B^2} ; l_f = \sqrt{(x_B + u_x)^2 + (y_B + u_y)^2} = l_f(u_x, u_y)$$

EXPAND l_f TO THE FIRST ORDER IN u_x AND u_y

$$l_f = l_f(0,0) + \frac{\partial l_f}{\partial u_x} \bigg|_{(0,0)} u_x + \frac{\partial l_f}{\partial u_y} \bigg|_{(0,0)} u_y + O(\sqrt{u_x^2 + u_y^2})$$

$$\Delta l = l_f - l = \Delta l_x + \Delta l_y$$

$$l_f \approx l + \left[\frac{1}{2\sqrt{}} \frac{\partial (x_B + u_x)}{\partial u_x} \right]_{(0,0)} u_x + \left[\frac{1}{2\sqrt{}} \frac{\partial (y_B + u_y)}{\partial u_y} \right]_{(0,0)} u_y = l + \underbrace{\frac{x_B}{l}}_{\Delta l_x} u_x + \underbrace{\frac{y_B}{l}}_{\Delta l_y} u_y$$

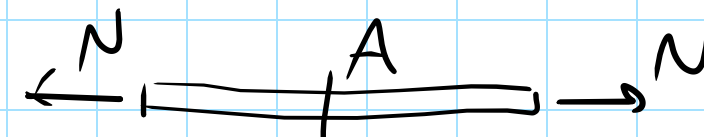


$$\Delta l_y = u_y \sin \alpha$$

$$\begin{aligned} \sigma &= E \epsilon \\ \frac{N}{A} &= E \frac{\Delta l}{l} \end{aligned}$$

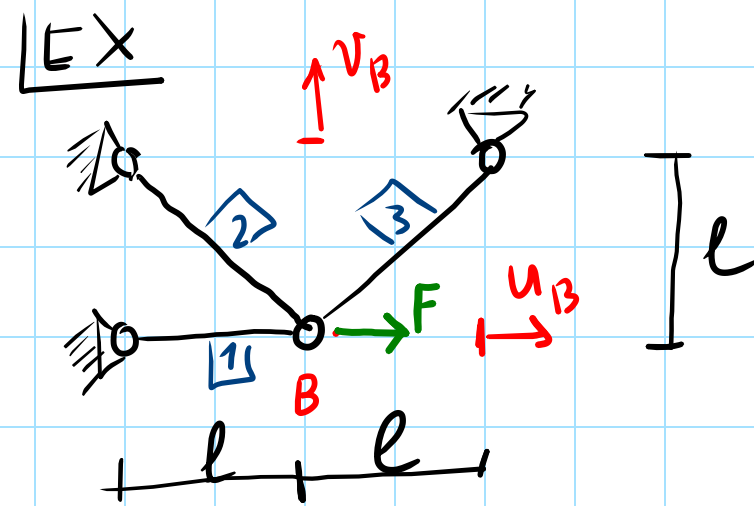
$$N = \frac{EA}{l} \Delta l$$

K : EQUIV. SPRING STIFFNESS

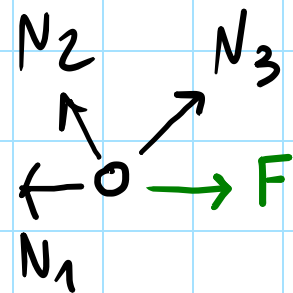


RECALL THAT THE CONSTITUTIVE EQUATION FOR A BAR IS

$$N = \frac{EA}{l} \Delta l$$



$E: \text{CONST}$
 $A_1 = A; A_2 = A_3 = \sqrt{2}A$
 $l_1 = l; l_2 = l_3 = \sqrt{2}l$



2 EQUIL. EQS

$$\left. \begin{aligned}
 +\rightarrow: -N_1 - N_2 \frac{1}{\sqrt{2}} + N_3 \frac{1}{\sqrt{2}} + F &= 0 \\
 +\uparrow: N_2 \frac{1}{\sqrt{2}} + N_3 \frac{1}{\sqrt{2}} &= 0
 \end{aligned} \right\} \begin{aligned}
 -K u_B - \frac{K}{\sqrt{2}\sqrt{2}} (u_B - v_B) + \frac{K}{\sqrt{2}\sqrt{2}} (-u_B - v_B) + F &= 0 \\
 \frac{K}{2} (u_B - v_B) + \frac{K}{2} (-u_B - v_B) &= 0
 \end{aligned}$$

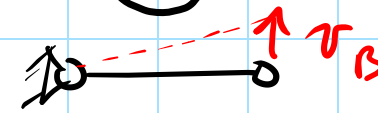
$u_B, v_B: \text{UNKNOWN}$

CONSTITUTIVE EQS: $N_i = N_i(u_B, v_B)$

$K = EA/l$

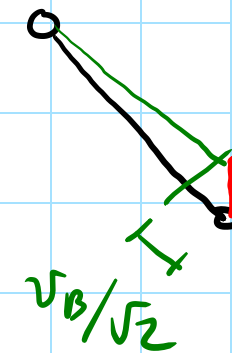
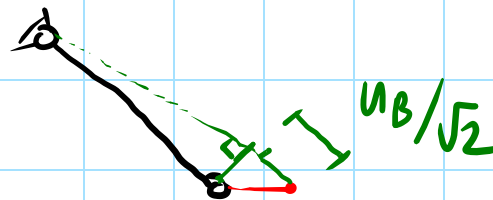
$N_1 = \frac{EA}{l} \Delta l_1; N_2 = \frac{E\sqrt{2}A}{\sqrt{2}l} \Delta l_2; N_3 = \frac{E\sqrt{2}A}{\sqrt{2}l} \Delta l_3$

$\Delta l_1)$



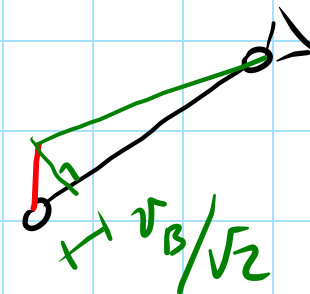
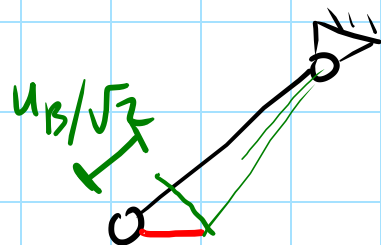
$\Delta l_1 = +u_B$

$\Delta l_2)$



$\Delta l_2 = +\frac{u_B}{\sqrt{2}} - \frac{v_B}{\sqrt{2}}$

$\Delta l_3)$



$\Delta l_3 = -\frac{u_B}{\sqrt{2}} - \frac{v_B}{\sqrt{2}}$

$$\ominus K u_B + \frac{K}{2} (u_B - v_B) + \frac{K}{2} (u_B + v_B) = \ominus F ; \quad \begin{bmatrix} -2K & 0 \\ 0 & -K \end{bmatrix} \begin{bmatrix} u_B \\ v_B \end{bmatrix} = \begin{bmatrix} -F \\ 0 \end{bmatrix} ; \quad \begin{matrix} u_B = \frac{F}{2K} \\ v_B = 0 \end{matrix}$$

$$\frac{K}{2} (u_B - v_B) - \frac{K}{2} (u_B + v_B) = 0$$

$$N_1 = K u_B = F/2$$

$$N_2 = \frac{K}{\sqrt{2}} (u_B - v_B) = \frac{F}{2\sqrt{2}}$$

$$N_3 = -\frac{K}{\sqrt{2}} (u_B + v_B) = -\frac{F}{2\sqrt{2}}$$

$$\Downarrow$$

$$\begin{bmatrix} 2K & 0 \\ 0 & K \end{bmatrix} \begin{bmatrix} u_B \\ v_B \end{bmatrix} = \begin{bmatrix} +F \\ 0 \end{bmatrix}$$

STIFFNESS MATRIX (SYMMETRIC AND POSITIVE DEFINITE)
[K]

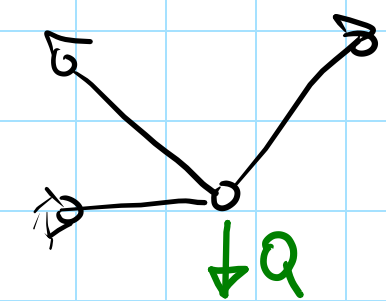
② MEANING OF K_{11}

first line of the system: $K_{11} u_B + K_{12} v_B = F$

TAKE $u_B = 1$ AND $v_B = 0 \Rightarrow K_{11} = F$

TAKE $u_B = 0$ AND $v_B = 1 \Rightarrow K_{12} = F$

COMMENT: ①



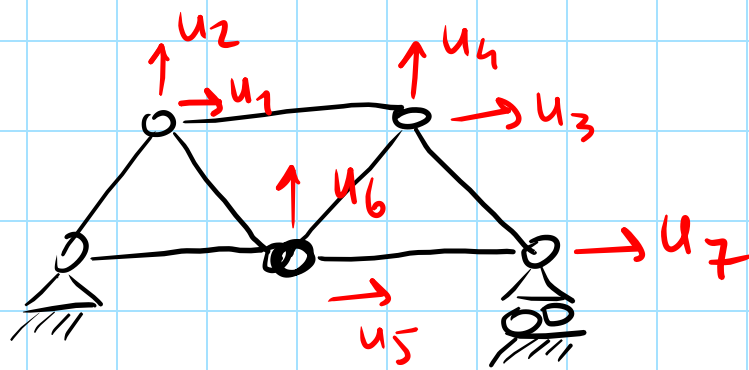
SYSTEM

$$\begin{bmatrix} 2K & 0 \\ 0 & K \end{bmatrix} \begin{bmatrix} u_B \\ v_B \end{bmatrix} = \begin{bmatrix} 0 \\ -Q \end{bmatrix}$$

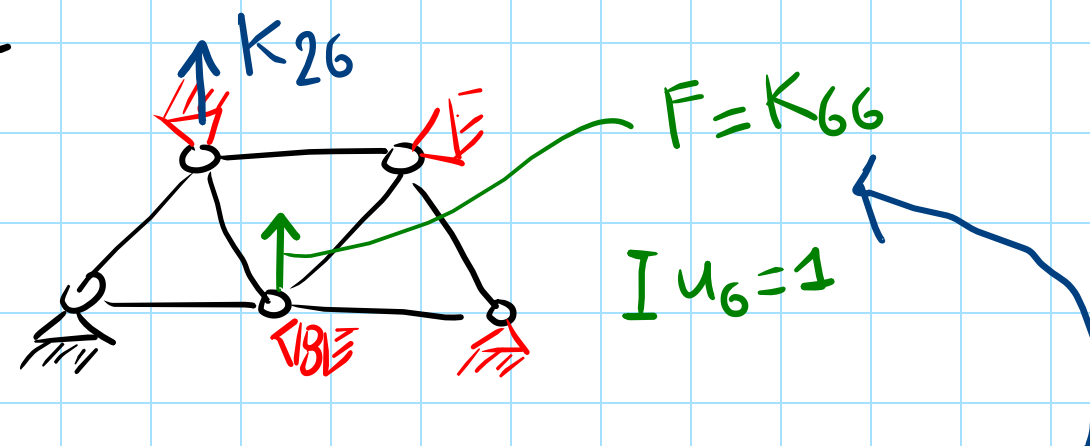
SOLUTION

$$\begin{matrix} u_B = 0 \\ v_B = -\frac{Q}{K} \end{matrix} \quad \left(\begin{matrix} N_1 = 0 \\ \vdots \end{matrix} \right)$$

K_{ij} IS THE "FORCE" ASSOCIATED WITH DOF i WHEN DOF $j=1$ AND THE REMAINING DOFS ARE ALL NULL.

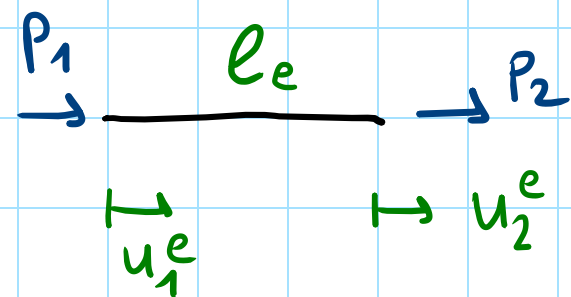


K_{66} ? $u_6 = 1$
 $u_i (i \neq 6) = 0$



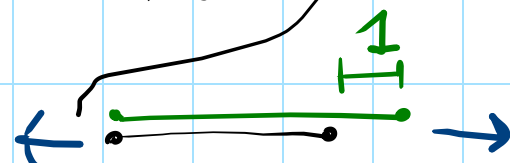
K_{26} : REACTION ALONG DIRECTION 2 OF THE LOADED SYSTEM

LOCAL STIFFNESS MATRIX OF A BAR



$$u_2^e = 1$$

$$u_1^e = 0$$



$$K_{12} = -\frac{EA}{l_e} \cdot 1$$

$$K_{22} = \frac{EA}{l_e} \cdot 1$$

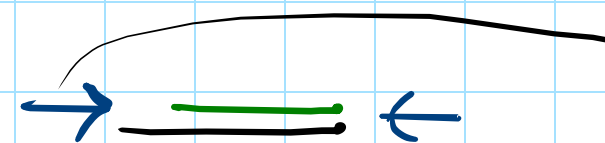
$$\begin{bmatrix} P_1 \\ P_2 \end{bmatrix} = \begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{bmatrix} \begin{bmatrix} u_1^e \\ u_2^e \end{bmatrix}$$

$$= \frac{EA}{l_e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

LOCAL STIFFNESS
MATRIX $\underline{\underline{K}}_e$

$$u_1^e = 1$$

$$u_2^e = 0$$



$$K_{11} = \frac{EA}{l_e} \cdot 1$$

$$K_{21} = -\frac{EA}{l_e} \cdot 1$$