

ES 1)

$$7. \{p, q\} = \left\{ \frac{1}{2} \tilde{p}^\alpha \cos \tilde{q}, \beta \tilde{p}^\alpha \sin \tilde{q} \right\} =$$

$$\{p, p\} = 0$$

$$\{p, q\} = 0 \text{ un definite al. p.p.}$$

$$= -\sin \tilde{q} \frac{\tilde{p}^\alpha}{2} \alpha \beta \tilde{p}^{\alpha-1} \sin \tilde{q} - \frac{\alpha}{2} \tilde{p}^{\alpha-1} \cos \tilde{q} \beta \tilde{p}^\alpha \cos \tilde{q} =$$

$$= - \underbrace{(\sin^2 \tilde{q} + \cos^2 \tilde{q})}_{=1} \frac{\alpha \beta}{2} \tilde{p}^{2\alpha-1}$$

→ q to deviazione cost effluvi traf corrente
 $\Rightarrow \alpha = 1/2$

$$\{q, p\} = \frac{\beta}{4} \quad \rightsquigarrow \quad \frac{1}{c} = \beta/4 \quad (\text{e } \beta=4 \text{ traf. e univ.})$$

$$8. K(\tilde{p}, \tilde{q}) = c H(p(\tilde{p}, \tilde{q}), q(\tilde{p}, \tilde{q}))$$

$$H = \frac{p^2}{2} + \frac{q^2}{2}$$

$$p = \frac{\sqrt{\beta}}{2} \cos \tilde{q} \quad q = \beta \sqrt{\beta} \sin \tilde{q}$$

$$\Rightarrow K = \frac{4}{\beta} \left(\frac{\tilde{p}}{8} \cos^2 \tilde{q} + \tilde{p} \frac{\beta}{2} \sin^2 \tilde{q} \right)$$

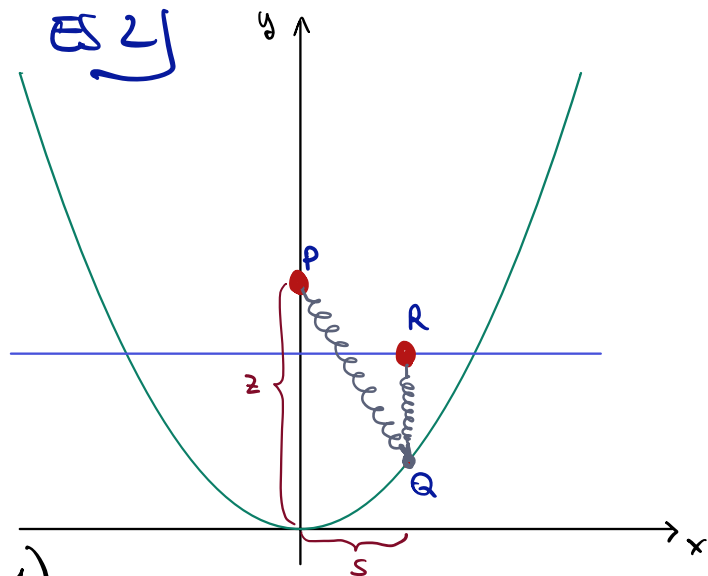
diff'abile e meno di scegliere $\beta = 1/4$

$$\Rightarrow K = \frac{1}{2} 2 \tilde{p} \Rightarrow \begin{cases} \tilde{p} = 0 \\ \dot{\tilde{q}} = 2 \end{cases}$$

$$\Rightarrow \begin{cases} \tilde{p}(t) = A^2 \\ \tilde{q}(t) = 2t + \varphi \end{cases} \quad \leftarrow \text{cost.}$$

$$p(t) = \frac{A}{2} \cos(2t + \varphi)$$

$$q(t) = \frac{A}{4} \sin(2t + \varphi) \quad (\text{consist. con } p = \dot{q})$$



$$x_P = 0$$

$$y_P = z$$

$$x_R = s$$

$$y_R = 0$$

$$x_Q = s$$

$$y_Q = \frac{s^2}{a}$$

$$T = \frac{m}{2} \dot{z}^2 + \frac{m}{2} \dot{s}^2$$

1)

$$V = mgy_P + \frac{k}{2} (d_{PQ}^2 + d_{RQ}^2) =$$

$$= mgz + \frac{k}{2} \left(s^2 + \left(\frac{s^2}{a} - z \right)^2 + \left(\frac{s^2}{a} - a \right)^2 \right)$$

$$= mgz + \frac{k}{a^2} s^4 + \frac{k}{2} s^2 (1 - 2 - 2\frac{z}{a}) + \frac{k}{2} z^2 + \cancel{\frac{ka^2}{2}} \text{transcendentes mehr const.}$$

$$= mgz + \frac{k}{2} z^2 - \frac{k}{a} z s^2 - \frac{k}{2} s^2 + \frac{k}{a^2} s^4$$

$$L = \frac{m}{2} \dot{z}^2 + \frac{m}{2} \dot{s}^2 - mgz - \frac{k}{2} z^2 + \frac{k}{a} z s^2 + \frac{k}{2} s^2 - \frac{k}{a^2} s^4$$

$$2) \frac{d}{dt} \frac{\partial L}{\partial \dot{z}} - \frac{\partial L}{\partial z} = \left[m \ddot{z} + mg + kz - \frac{k}{a} s^2 = 0 \right]$$

3) $x \rightarrow -x$ $y \rightarrow y$ $m \rightarrow m$ $s \rightarrow -s$ $z \rightarrow z$ sim. dynam. , was sie apply können

$$4) \partial_z V = mg + kz - \frac{k}{a} s^2 = 0 \rightarrow z = \frac{s^2}{a} - \frac{mg}{k}$$

$$\partial_s V = -2\frac{k}{a} z s - ks + \frac{4k}{a^2} s^3 = 0$$

$$\hookrightarrow -2\frac{k}{a} s \left(\frac{s^2}{a} - \frac{mg}{k} \right) - ks + \frac{4k}{a^2} s^3 = 0$$

$$ks \left[-\frac{2s^2}{a^2} + 2\frac{mg}{ka} - 1 + \frac{4s^2}{a^2} \right] = 0$$

$$2Ks \left[\frac{s^2}{a^2} - \frac{1}{2} + \frac{mg}{ka} \right]$$

$$\rightarrow s=0$$

$$s = \pm s_* \quad \text{con} \quad s_*^2 = \frac{a^2}{2} \left(1 - \frac{2mg}{ka} \right) \leftarrow \exists \text{ solo per } \frac{mg}{ka} \leq \frac{1}{2}$$

$$s_* = a \sqrt{\frac{1}{2} - \frac{mg}{ka}}$$

$$\frac{mg}{ka} \leq \frac{1}{2}$$

$$(z, 0) \rightarrow \left(-\frac{mg}{k}, 0 \right)$$

$$\rightarrow \left(\underbrace{\frac{s_*^2}{a} - \frac{mg}{k}}_{\equiv z_*}, \pm s_* \right) \quad \text{con} \quad z_* = a \left(\frac{1}{2} - \frac{2mg}{ka} \right)$$

$$\partial^2 V = \begin{pmatrix} k & -\frac{2Ks}{a} \\ -\frac{2Ks}{a} & -\frac{2Kz}{a} - k + \frac{12K}{a^2} s^2 \end{pmatrix}$$

$$\partial^2 V_{\left(-\frac{mg}{k}, 0\right)} = \begin{pmatrix} k & 0 \\ 0 & \frac{2mg}{a} - k \end{pmatrix}$$

STAB.

$$s_* = a \sqrt{\frac{1}{2} - \frac{mg}{ka}}$$

≥ 0 quando $\frac{mg}{ka} \geq \frac{1}{2}$

(instab. altrimenti.)

$$\partial^2 V_{(z_*, \pm s_*)} = \begin{pmatrix} k & \mp 2K \sqrt{\frac{1}{2} - \frac{mg}{ka}} \\ \mp 2K \sqrt{\frac{1}{2} - \frac{mg}{ka}} & -2K \left(\frac{1}{2} - \frac{2mg}{ka} \right) - 2K \frac{1}{2} + 12K \left(\frac{1}{2} - \frac{mg}{ka} \right) \end{pmatrix}$$

$$= \begin{pmatrix} k & \mp 2k \sqrt{\frac{1}{2} - \frac{u_g}{k\alpha}} \\ \mp 2k \sqrt{\frac{1}{2} - \frac{u_g}{k\alpha}} & \left(\frac{1}{2} - \frac{u_g}{k\alpha}\right) (\underbrace{12k - 4k}_{8k}) \end{pmatrix}$$

$$\text{Tr} = k + 8k \left(\frac{1}{2} - \frac{u_g}{k\alpha} \right)$$

$$\det = 8k^2 \left(\frac{1}{2} - \frac{u_g}{k\alpha} \right) - 4k^2 \left(\frac{1}{2} - \frac{u_g}{k\alpha} \right) =$$

$$= 4k^2 \left(\frac{1}{2} - \frac{u_g}{k\alpha} \right) \geq 0 \quad \text{in} \quad u_g \leq 1/2$$

$\uparrow$
 in pto cas eucler $\text{tr} > 0$
 $\rightarrow$ stab.

Quindi:

• Per $\frac{u_g}{k\alpha} > \frac{1}{2}$: c'è un solo pt di equil.
 $\left(-\frac{u_g}{\alpha}, 0\right)$ ed è STABILE

• Per $\frac{u_g}{k\alpha} < \frac{1}{2}$: ci sono tre pt di equil.

$\left(-\frac{u_g}{\alpha}, 0\right)$ INSTABILE

$(z_*, \pm s_*)$ STABILI

$$5) a = \frac{3mg}{k} \quad \left(\frac{mg}{ka} = \frac{1}{3} < \frac{1}{2} \right)$$

$$\left(-\frac{a}{2}, -s_+ \right) \quad s_+ = a \sqrt{\frac{1}{2} - \frac{mg}{ka}} = a \sqrt{\frac{1}{2} - \frac{1}{3}} = \frac{a}{\sqrt{6}}$$

$$A = Q|_{\min} = \begin{pmatrix} m & 0 \\ 0 & m \end{pmatrix}$$

$$B = \begin{pmatrix} k & -2k \sqrt{\frac{1}{2} - \frac{mg}{ka}} \\ -2k \sqrt{\frac{1}{2} - \frac{mg}{ka}} & 8k \left(\frac{1}{2} - \frac{mg}{ka} \right) \end{pmatrix} \Big|_{\frac{mg}{ka} = \frac{1}{3}}$$

$$= \begin{pmatrix} k & 2k/\sqrt{6} \\ 2k/\sqrt{6} & 8k/6 \end{pmatrix} = \begin{pmatrix} k & \sqrt{\frac{2}{3}} k \\ \sqrt{\frac{2}{3}} k & \frac{4}{3} k \end{pmatrix}$$

$$\det(B - \lambda A) = \det \begin{pmatrix} k - m\lambda & \sqrt{\frac{2}{3}} k \\ \sqrt{\frac{2}{3}} k & \frac{4}{3} k - m\lambda \end{pmatrix} =$$

$$= m^2 \left\{ \left(\frac{k}{m} - \lambda \right) \left(\frac{4k}{3m} - \lambda \right) - \frac{2}{3} \left(\frac{k}{m} \right)^2 \right\} = 0$$

$$3\lambda^2 - 7\frac{k}{m}\lambda + 2\left(\frac{k}{m}\right)^2 = 0$$

$$\Delta = 49 - 4 \cdot 3 \cdot 2 = 25$$

$$\lambda_{1,2} = \left(\frac{7}{6} \pm \frac{5}{6} \right) \frac{k}{m} \begin{cases} \frac{1}{3} \frac{k}{m} = \frac{g}{a} \\ 2 \frac{k}{m} = 6 \frac{g}{a} \end{cases}$$

$$\begin{aligned}
 L &= \frac{1}{2} (\delta \dot{z}, \delta \dot{s}) A \begin{pmatrix} \delta \dot{z} \\ \delta \dot{s} \end{pmatrix} - \frac{1}{2} (\delta z, \delta s) B \begin{pmatrix} \delta z \\ \delta s \end{pmatrix} = \\
 &= \frac{1}{2} m \delta \dot{z}^2 + \frac{1}{2} m \delta \dot{s}^2 - \frac{1}{2} (\delta z, \delta s) \begin{pmatrix} k & \frac{\sqrt{2}}{3} k \\ \frac{\sqrt{2}}{3} k & \frac{4}{3} k \end{pmatrix} \begin{pmatrix} \delta z \\ \delta s \end{pmatrix} = \\
 &= \frac{m \delta \dot{z}^2}{2} + \frac{m \delta \dot{s}^2}{2} - \frac{k}{2} \delta z^2 - \frac{2}{3} k \delta s^2 - \frac{\sqrt{2}}{3} k \delta z \delta s
 \end{aligned}$$

Dann $z = z_x + \delta z$ e $s = -s_x + \delta s$

$$\begin{aligned}
 6) \quad \lambda_1 &= \frac{1}{3} \frac{k}{m} \\
 B - \lambda_1 A &= \begin{pmatrix} \frac{2}{3} k & \frac{\sqrt{2}}{3} k \\ \frac{\sqrt{2}}{3} k & k \end{pmatrix} \rightsquigarrow \text{Ker} = \left\langle \begin{pmatrix} 1 \\ -\frac{\sqrt{2}}{3} \end{pmatrix} \right\rangle \\
 &\quad \parallel \\
 &\quad u_1
 \end{aligned}$$

$$\lambda_2 = \frac{2k}{m}$$

$$B - \lambda_2 A = \begin{pmatrix} -k & \frac{\sqrt{2}}{3} k \\ \frac{\sqrt{2}}{3} k & -\frac{2}{3} k \end{pmatrix} \rightsquigarrow \text{Ker} = \left\langle \begin{pmatrix} \frac{\sqrt{2}}{3} \\ 1 \end{pmatrix} \right\rangle \\
 \parallel \\
 u_2$$

$$\begin{pmatrix} z(t) \\ s(t) \end{pmatrix} = \begin{pmatrix} z_x \\ -s_x \end{pmatrix} + A_1 u_1 \cos \left(\sqrt{\frac{k}{3m}} t + \varphi_1 \right) + A_2 u_2 \cos \left(\sqrt{\frac{2k}{m}} t + \varphi_2 \right)$$

$$7) \quad \delta V = -Fs$$

$$L_{\text{new}} = L_{\text{old}} + Fs$$

$$s^2 = a^2$$

$$\partial_z V_{\text{new}} = mg + kz - \frac{k}{a} s^2 = 0 \quad z = -\frac{mg}{k} + \frac{3mg}{k} = \frac{2mg}{k}$$

$$\partial_s V_{\text{new}} = -2\frac{k}{a}zs - ks + \frac{4k}{a^2}s^3 - F$$

$$-2\frac{k}{a} \frac{2mg}{k} a - k \frac{3mg}{k} + 4k \frac{3mg}{k} - F$$

$$\Rightarrow F = mg(-4 - 3 + 12) = 5mg$$